10. Information theory

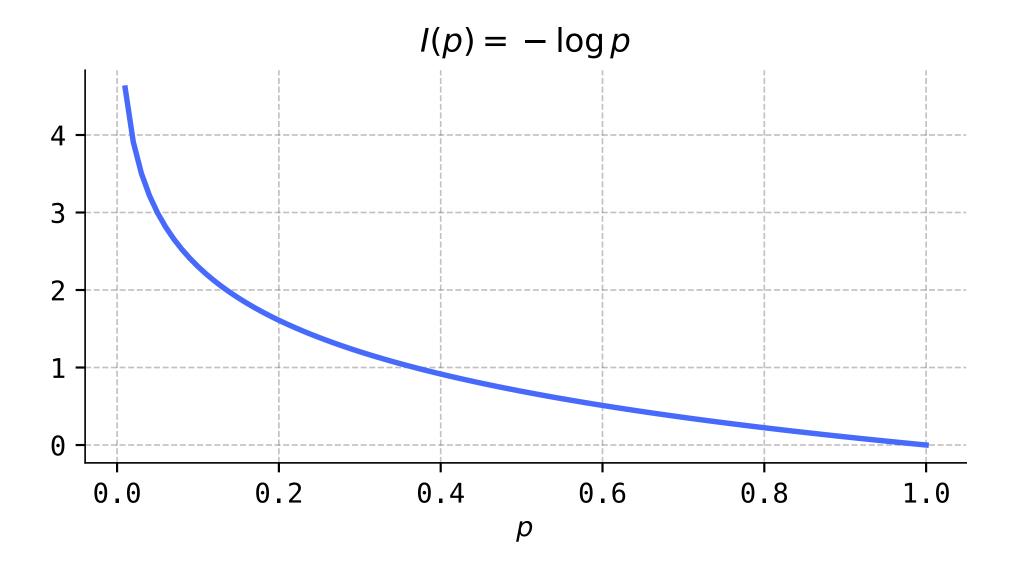
10.1. Shannon information and entropy

Let P be a probability measure on a finite sample space S with mass function p(s). The (Shannon) information content of the sample point $s \in S$, denoted $I_P(s)$, is defined to be

$$I_P(s) \stackrel{ ext{def}}{=} -\log(p(s)).$$

The information content is also called the *surprisal*.

If the probability measure P is clear from context, we will write I(s) in place of $I_P(s)$. If \mathbf{X} is a random vector with finite range and probability measure $P_{\mathbf{X}}$, we will write $I_{\mathbf{X}}(\mathbf{x})$ in place of $I_{P_{\mathbf{X}}}(\mathbf{x})$.

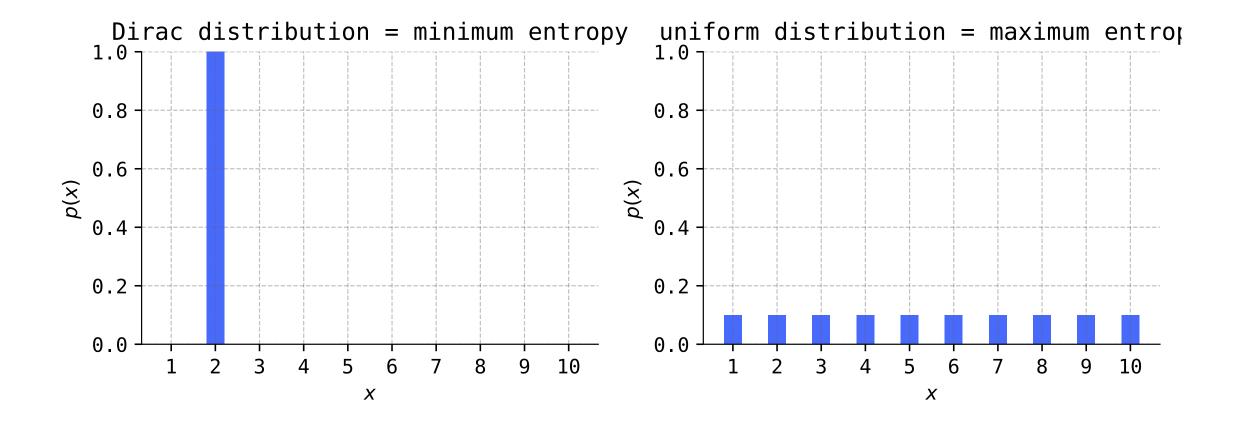


Let P be a probability measure on a finite sample space S with mass function p(s). The (Shannon) entropy of P, denoted H(P), is defined to be

$$H(P) \stackrel{\mathrm{def}}{=} \sum_{s \in S} p(s) I_P(s).$$

The entropy is also called the *uncertainty*.

If ${\bf X}$ is a random vector with finite range and probability measure $P_{\bf X}$, we will write $H({\bf X})$ in place of $H(P_{\bf X})$. If we write the vector in terms of its component random variables ${\bf X}=(X_1,\ldots,X_m)$, then we shall also write $H(X_1,\ldots,X_m)$ in place of $H(P_{\bf X})$ and call this the *joint entropy* of the random variables X_1,\ldots,X_m .





Do problems 1 and 2 on the worksheet.

Let P and Q be two probability measures on a finite sample space S with mass functions p(s) and q(s). Suppose they satisfy the following condition:

• Absolute continuity. For all $s \in S$, if q(s) = 0, then p(s) = 0. Or equivalently, the support of q(s) contains the support of p(s).

Then the *cross entropy* from P to Q, denoted $H_P(Q)$, is defined by

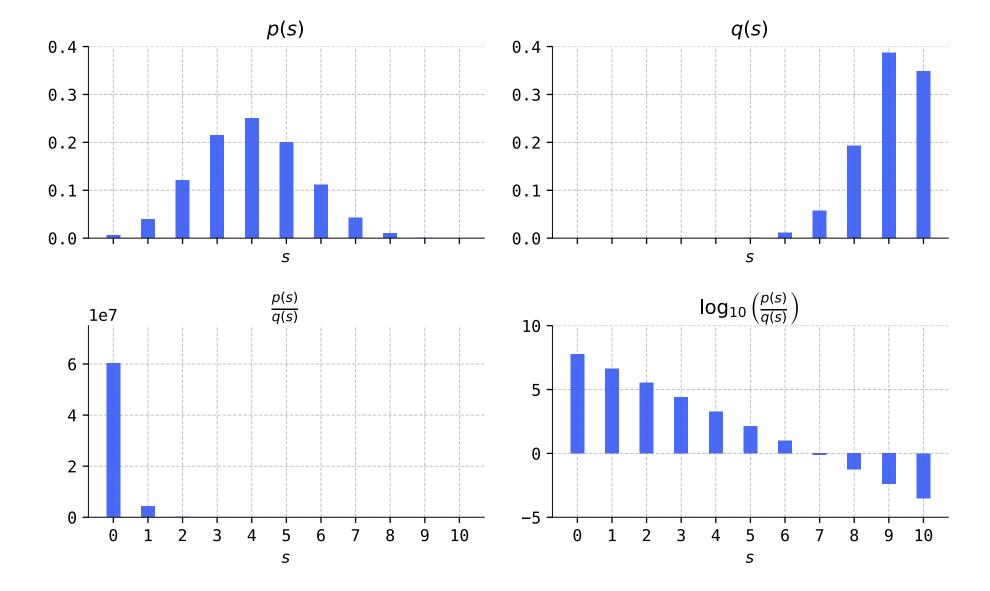
$$H_P(Q) \stackrel{ ext{def}}{=} E_{s \sim p(s)} \left[I_Q(s)
ight] = - \sum_{s \in S} p(s) \log(q(s)).$$

As usual, if $P_{\mathbf{X}}$ and $P_{\mathbf{Y}}$ are the probability measures of two random vectors \mathbf{X} and \mathbf{Y} with finite ranges, we will write $H_{\mathbf{Y}}(\mathbf{X})$ in place of $H_{P_{\mathbf{Y}}}(P_{\mathbf{X}})$.



Do problem 3 on the worksheet.

10.2. Kullback Leibler divergence



Let P and Q be two probability measures on a finite sample space S with mass functions p(s) and q(s). Suppose they satisfy the following condition:

• Absolute continuity. For all $s \in S$, if q(s) = 0, then p(s) = 0. Or equivalently, the support of q(s) contains the support of p(s).

Then the *Kullback-Leibler divergence* (or just *KL divergence*) from P to Q, denoted $D(P \parallel Q)$, is the mean order of relative magnitude of P to Q. Precisely, it is given by

$$D(P \parallel Q) \stackrel{ ext{def}}{=} E_{s \sim p(s)} \left[\log \left(rac{p(s)}{q(s)}
ight)
ight] = \sum_{s \in S} p(s) \log \left(rac{p(s)}{q(s)}
ight).$$

The KL divergence is also called the *relative entropy*.

As always, if $P_{\mathbf{X}}$ and $P_{\mathbf{Y}}$ are the probability measures of two random vectors \mathbf{X} and \mathbf{Y} with finite ranges, we will write $D(\mathbf{Y} \parallel \mathbf{X})$ in place of $D(P_{\mathbf{Y}} \parallel P_{\mathbf{X}})$.



To problem 4 on the worksheet.

Theorem 10.1 (KL divergence and entropy)

Let P and Q be two probability measures on a finite sample space S. Then

$$D(P \parallel Q) = H_P(Q) - H(P).$$

Theorem 10.3 (Gibbs' inequality)

Let P and Q be two probability measures on a finite probability space S satisfying the absolute continuity condition in <u>Definition 10.4</u>. Then

$$D(P \parallel Q) \geq 0$$
,

with equality if and only if P=Q.

Corollary 10.1 (Uniform distributions maximize entropy)

Let P be a probability measures on a finite sample space S. Then

$$H(P) \leq \log |S|,$$

with equality if and only if P is uniform.

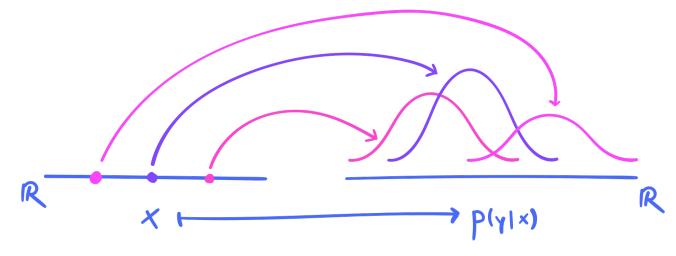


Do problem 5 on the worksheet.

10.3. Flow of information

R y = g(x)Peterministic link y = g(x)





A Markov kernel is a mapping

$$\kappa:\{1,2,\ldots,m\} o \mathbb{R}^n$$

such that each vector $\kappa(i)\in\mathbb{R}^n$ is a probability vector (i.e., a vector with nonnegative entries that sum to 1). The m imes n matrix

$$\mathbf{K} = egin{bmatrix} \leftarrow & \kappa(1)^\intercal &
ightarrow \ dots & dots & dots \ \leftarrow & \kappa(m)^\intercal &
ightarrow \end{bmatrix}$$

is called the transition matrix of the Markov kernel.



A communication channel is a Markov kernel.

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Theorem 10.4 (Conditional distributions determine communication channels)

Let X and Y be two random variables with finite ranges

$$\{x_1, \ldots, x_m\}$$
 and $\{y_1, \ldots, y_n\}$. (10.8)

Then the matrix

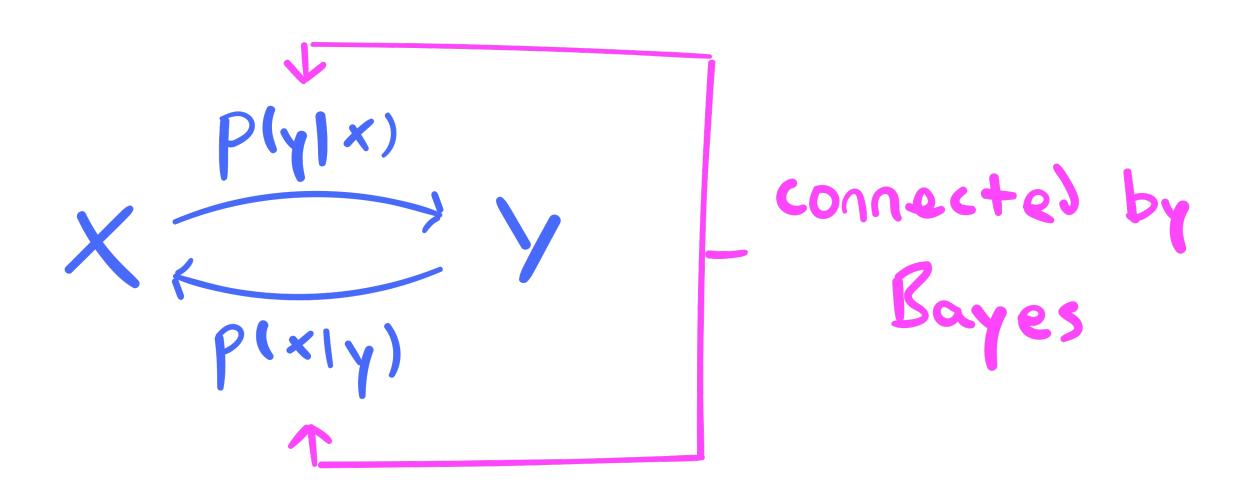
$$\mathbf{K} = [p(y_j|x_i)] = egin{bmatrix} p(y_1|x_1) & \cdots & p(y_n|x_1) \ dots & \ddots & dots \ p(y_1|x_m) & \cdots & p(y_n|x_m) \end{bmatrix}$$
 (10.9)

is the transition matrix of a Markov kernel.

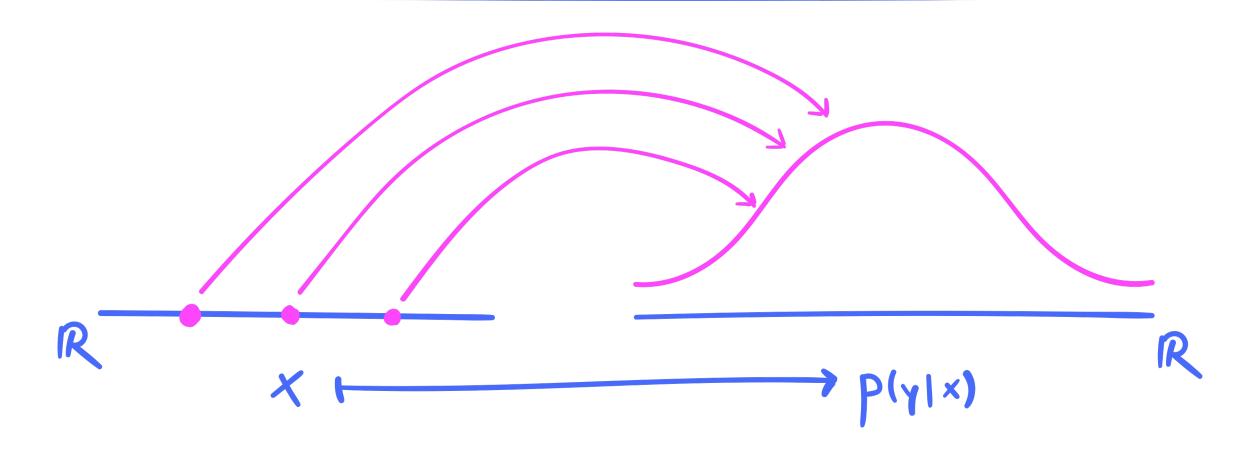


Do Problem 6 on the worksheet.

Flow of information



Constant communication channel = no information transfer



Theorem 10.5 (Independence = constant Markov kernels)

Let X and Y be two random variables with finite ranges

$$\{x_1,\ldots,x_m\}$$
 and $\{y_1,\ldots,y_n\}$.

Then the induced communication channel

$$\kappa:\{1,2,\ldots,m\} o \mathbb{R}^n, \quad \kappa(i)^\intercal=[p(y_1|x_i)\quad \cdots \quad p(y_n|x_i)],$$

is constant if and only if X and Y are independent. In this case, $\kappa(i)=m{\pi}(Y)$ for each $i=1,\dots,m$.

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Definition 10.7

Let X and Y be two random variables with finite ranges. The *mutual information* shared between X and Y, denoted I(X,Y), is the KL divergence

$$I(X,Y) \stackrel{ ext{def}}{=} D(P_{XY} \parallel P_X \otimes P_Y) = \sum_{(x,y) \in \mathbb{R}^2} p(x,y) \log igg(rac{p(x,y)}{p(x)p(y)}igg).$$



Do Problem 7 on the worksheet.

Theorem 10.6 (Independence = zero mutual information)

Let X and Y be two random variables with finite ranges

$$\{x_1,\ldots,x_m\}$$
 and $\{y_1,\ldots,y_n\}$.

Then the following statements are equivalent:

1. The induced communication channel

$$\kappa:\{1,2,\ldots,m\} o \mathbb{R}^n, \quad \kappa(i)^\intercal=[p(y_1|x_i)\quad \cdots \quad p(y_n|x_i)],$$

is constant.

- 2. The random variables X and Y are independent.
- 3. The mutual information I(X,Y)=0.

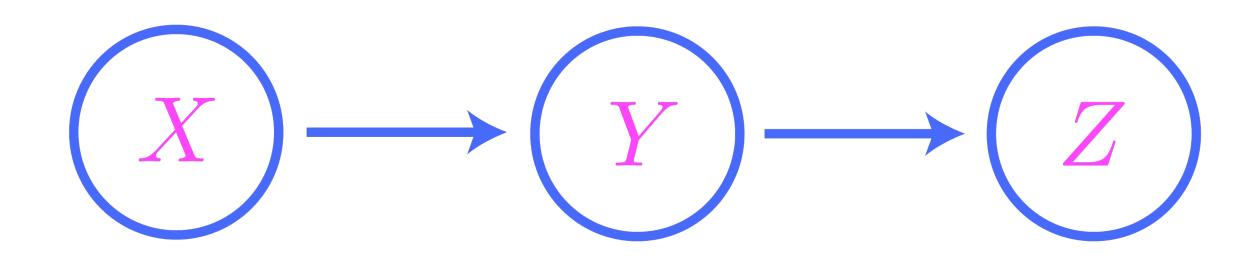
Theorem 10.7 (Mutual information and entropy)

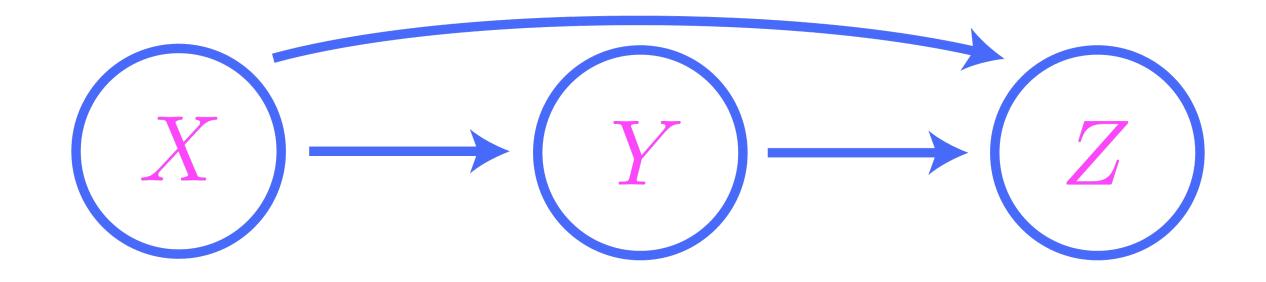
Let X and Y be two random variables with finite ranges. Then:

$$I(X,Y) = H(X) + H(Y) - H(X,Y).$$

Corollary 10.2 (Symmetry of mutual information)

Let X and Y be random variables with finite ranges. Then I(X,Y)=I(Y,X).





Let X, Y, and Z be three random variables.

1. If the variables are jointly discrete, then we shall say X and Z are conditionally independent given Y if

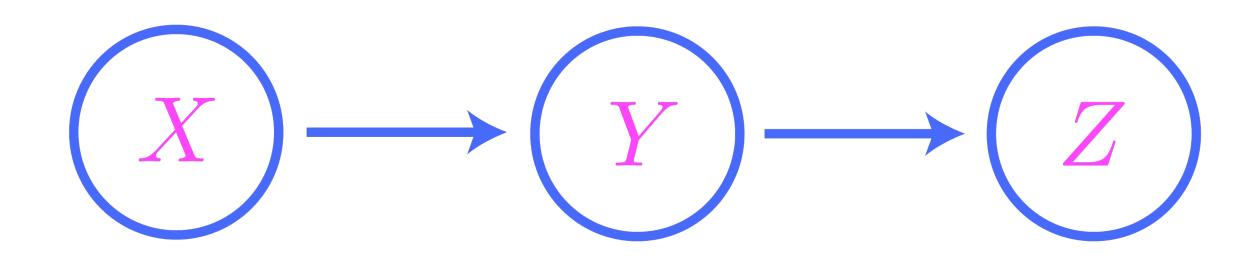
$$p(x,z|y) = p(x|y)p(z|y)$$

for all x, y, and z.

2. If the variables are jointly continuous, then we shall say X and Z are conditionally independent given Y if

$$f(x,z|y) = f(x|y)f(z|y)$$

for all x, y, and z.



Theorem 10.8 (Data Processing Inequality)

Suppose X,Y, and Z are three random variables with finite ranges, and suppose that X and Z are conditionally independent given Y. Then

$$I(X,Z) \le I(X,Y),\tag{10.11}$$

with equality if and only if X and Y are independent given Z.