COLD CLIMATE MOBILITY SYSTEM PATENT

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UNITED STATES PATENT NO. 11,847,392

Filed: September 12, 2019

Issued: March 15, 2022

Assignee: Polar Dynamics Robotics, Inc.

ABSTRACT

A system and method for autonomous mobile robot operation in sub-

environments, comprising a temperature-hardened navigation system chassis design, and proprietary power management architecture. The enables reliable robotic mobility in extreme cold conditions through in thermal management, cold-resistant sensor arrays, and adaptive contalgorithms optimized for low-temperature performance.

BACKGROUND OF INVENTION

[0001] Autonomous mobile robots (AMRs) operating in cold storage a freezer environments face significant challenges related to battery per sensor reliability, and mechanical system operation at sub-zero temper. Conventional AMR designs experience degraded performance below reduced battery capacity, compromised sensor accuracy, and increase resistance.

[0002] This invention addresses these challenges through an integrat

to cold-environment operation, incorporating novel thermal managem techniques, specialized materials selection, and adaptive control systems
SUMMARY OF INVENTION
[0003] The present invention provides a cold climate mobility system
A thermally-isolated power system with active temperature regulation
- Multi-modal sensor array with redundant cold-resistant components
- Reinforced chassis design utilizing low-temperature composite materi
- Proprietary BlueCore(TM) navigation and control architecture
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Adaptive power management system for sub-zero operation

DETAILED DESCRIPTION

[0004] Power System

The system incorporates a dual-chamber battery enclosure with active management. Primary lithium-ion cells are maintained at optimal oper temperature through a combination of passive insulation and active he elements. Power delivery is regulated through proprietary algorithms to

[0005] Sensor Array

The multi-modal sensor system comprises:

optimize performance based on ambient conditions.

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Heated LIDAR units with protective housings

- - 4 Redundant temperature-hardened cameras
Cold-resistant proximity sensors
Thermal imaging capabilities for environmental mapping
Proprietary sensor fusion algorithms

[0006] Chassis Design
The reinforced chassis utilizes:

Carbon fiber composite structural elements

Low-temperature lubricants and bearings

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Thermally-isolated drive components

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Impact-resistant exterior panels

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Modular component architecture

[0007] Navigation System

The BlueCore(TM) navigation architecture features:

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Real-time environmental condition monitoring

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Adaptive path planning algorithms

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Dynamic speed control based on surface conditions

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Predictive maintenance scheduling

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Remote monitoring capabilities

CLAIMS

A cold climate mobility system comprising:

- a) A thermally-regulated power system
- b) Multi-modal sensor array
- c) Reinforced chassis design
- d) Adaptive control architecture
- e) Environmental monitoring systems

The system of claim 1, wherein the power system maintains operation

The system of claim 1, wherein the sensor array provides redundant of the system of claim 1, wherein the chassis design enables operation

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ASSIGNMENT RECORD

All rights, title, and interest in this patent have been assigned to Polar Dynamics Robotics, Inc., a Delaware corporation, as recorded in the Assignment Database on April 1, 2022.

MAINTENANCE FEES

First maintenance fee due: March 15, 2026

Second maintenance fee due: March 15, 2030

Third maintenance fee due: March 15, 2034

CERTIFICATION

I hereby certify that this patent document accurately reflects the invenregistered with the United States Patent and Trademark Office.

/s/ Victoria Wells

Chief Financial Officer

Polar Dynamics Robotics, Inc.

Date: March 15, 2022

