# **QUALITY CONTROL SAMPLING PROCEDURES**

# **QUALITY CONTROL SAMPLING PROCEDUI**

NaviFloor Robotics, Inc.

Effective Date: January 1, 2024

Document ID: QC-2024-001

Version: 2.0

version. 2.0

#### 1. PURPOSE AND SCOPE

1. This Quality Control Sampling Procedures document ("Procedures") established

<ul><li>- 1 -</li><li>2. These Procedures apply to all production units, software releases, and sys</li></ul>
2. DEFINITIONS
- 1. "Critical Components" means the LiDAR sensors, terrain-mapping modul
- 2. "Production Batch" means any group of AMR units manufactured within
-
3. "Testing Environment" means Company-approved facilities equipped with
3. SAMPLING REQUIREMENTS

2-
1. Production Batch Sampling
-
Minimum sampling rate of 15% of units per Production Batch
-
100% testing of Critical Components prior to assembly
-
Additional sampling required for batches exceeding 50 units
2. Software Validation
-
Full system testing on minimum 3 production units per software release
-
Regression testing on all previously validated navigation scenarios

- - 3 -

Minimum 72-hour continuous operation testing per sampled unit

#### 4. TESTING PROTOCOLS

- 1. Hardware Validation
- a) Surface Navigation Testing

-

Minimum 1,000 meters traversed on each approved surface type

-

Variable load testing at 25%, 75%, and 100% of rated capacity

-

Obstacle avoidance verification using standardized test objects

D)	Sensor Calibration
-	
Li	iDAR accuracy verification within ±2mm at 10m range
-	
D	epth-sensing calibration across minimum 20 reference poi
-	
C	ross-validation with redundant sensor arrays
-	
2.	Software Validation
a)	Navigation Algorithm Testing
-	
M	fulti-floor mapping accuracy verification
_	
D	ynamic obstacle response timing measurement

- - 5 -

Path optimization efficiency scoring

b) Fleet Management Integration

\_

Multi-unit coordination scenarios

-

Network latency measurement

\_

Failsafe protocol verification

#### 5. ACCEPTANCE CRITERIA

\_

1. Hardware Performance

- 6 100% pass rate on safety system functionality

Maximum deviation of ±0.1% on movement precision

Zero critical failures during continuous operation testing

2. Software Performance

Maximum latency of 50ms for navigation decisions

99.9% accuracy in obstacle detection

100% completion rate for standardized test courses

### 6. DOCUMENTATION AND REPORTING

- 1. Required Records
- Test results for each sampled unit
- Calibration certificates for testing equipment
- Environmental condition logs during testing
- Video documentation of critical test scenarios
- 2. Retention Requirements

- 8 -

All test records maintained for minimum 5 years

\_

Digital backups stored in redundant locations

-

Chain of custody documentation for all test units

#### 7. NON-CONFORMANCE PROCEDURES

-

- 1. Upon detection of any non-conformance:
- a) Immediate quarantine of affected Production Batch
- b) Root cause analysis within 24 hours
- c) Corrective action plan development
- d) Expanded sampling of adjacent Production Batches

9 -
2. Return to Production Requirements
-
Implementation of corrective actions
-
Verification testing on minimum 3 units
-
Quality Control Manager approval
-
Updated test documentation
8. REVISION AND CONTROL

1. These Procedures shall be reviewed annually and updated as necessary to

- 10 -
Changes in production methods
-
New technology implementations
-
Regulatory requirements
-
Customer specifications
-
2. All revisions require approval from:
-
Chief Technology Officer
-
Quality Control Manager

- - 11 -

Chief Research Officer

#### 9. LEGAL COMPLIANCE

-

1. These Procedures comply with:

\_

ISO 9001:2015 Quality Management Systems

-

ANSI/RIA R15.06-2012 Safety Requirements

\_

Applicable OSHA regulations

-

Company's Quality Management System

### **AUTHORIZATION**

APPROVED AND ADOPTED by NaviFloor Robotics, Inc.
By:
Dr. Elena Kovacs
Chief Research Officer
Date:
By:
Richard Torres
Chief Operating Officer
Date:

