

EQUIPMENT OPERATING INSTRUCTIONS - STATION 1-5

EQUIPMENT OPERATING INSTRUCTIONS -

NaviFloor Robotics, Inc.

Document No.: OPS-EQ-2023-105

Effective Date: January 15, 2024

Version: 2.1

1. PURPOSE AND SCOPE

-

1. This document establishes mandatory operating procedures for NaviFloor

- - 1 -

2. These instructions apply to all personnel authorized to operate or maintain

2. SAFETY REQUIREMENTS

-

1. All operators must complete NaviFloor's Advanced Equipment Safety Tra

-

2. Personal Protective Equipment (PPE) Requirements:

-

ESD-compliant footwear

-

Safety glasses with side shields

-

Level 2 cut-resistant gloves during component handling

-

Clean room suits when accessing the sensor calibration area

-

3. Emergency Protocols:

-

Red emergency stop buttons are located at each corner of the station

-

Yellow emergency phone at Station 3 connects directly to facility security

-

Fire suppression system activation points are marked in blue

3. PRE-OPERATION PROCEDURES

- - 3 -

1. System Verification:

- a) Verify green status indicators on all power distribution units
- b) Confirm calibration certificates are current for all testing equipment
- c) Check emergency stop system functionality
- d) Verify environmental controls are within specified parameters:

-

Temperature: 68-72°F (20-22°C)

-

Humidity: 45-55% RH

-

Particulate count: Class 1000 or better

-

2. Software Validation:

- a) Confirm NaviFloor Diagnostic Suite version 4.2.1 or higher is running
- b) Verify connection to central testing database
- c) Load appropriate test profiles for scheduled production batch

4. OPERATING PROCEDURES

-

1. Station 1 - Initial Assembly

- a) Load chassis according to specification NT750-AS-001
- b) Install primary navigation module using torque sequence NT750-TQ-103
- c) Connect main power harness following diagram EL-NT750-001
- d) Perform initial power-on test sequence

-

2. Station 2 - Sensor Integration

- a) Mount LiDAR array using calibrated mounting fixture MF-201
- b) Install depth sensors according to placement guide NT750-SN-002
- c) Connect sensor fusion processor
- d) Perform preliminary sensor alignment check

-

3. Station 3 - Software Loading

- a) Connect diagnostic interface cable to port P1
- b) Upload firmware package NT750-FW-421
- c) Initialize system configuration
- d) Perform basic movement test in safe mode

-

4. Station 4 - Calibration

- a) Place unit on calibration platform CP-301

- b) Execute full sensor calibration sequence
- c) Verify accuracy against golden sample
- d) Record calibration data in central database

-

5. Station 5 - Final Testing

- a) Execute comprehensive test suite TS-NT750-FINAL
- b) Verify all parameters meet specification SP-NT750-001
- c) Generate final test report
- d) Apply QC approval marking

5. QUALITY CONTROL REQUIREMENTS

-

1. All operations must be logged in the NaviFloor Manufacturing Execution

- - 7 -

2. Quality checkpoints require sign-off by authorized quality personnel at:

-

Component verification (Station 1)

-

Sensor alignment (Station 2)

-

Calibration completion (Station 4)

-

Final acceptance (Station 5)

-

3. Non-conformance handling:

a) Immediately stop operation

b) Tag unit with red hold tag

c) Create non-conformance report in MES

d) Notify shift supervisor

6. MAINTENANCE REQUIREMENTS

-

1. Daily Maintenance:

-

Clean all work surfaces

-

Verify calibration fixtures

-

Check diagnostic cable integrity

-

Empty ESD collection containers

- - 9 -

2. Weekly Maintenance:

-

Calibrate torque tools

-

Clean sensor alignment fixtures

-

Update software packages

-

Verify emergency systems

7. DOCUMENT CONTROL

-

1. This document is controlled by NaviFloor Robotics Quality Management

- - 10 -

2. Reviews required annually or upon significant process changes.

-

3. Distribution limited to authorized personnel only.

8. LEGAL NOTICES

-

1. This document contains proprietary and confidential information belonging

-

2. Compliance with these instructions is mandatory for maintaining product

[End of Document]

Approved by:

- 11 -

Richard Torres

Chief Operating Officer

NaviFloor Robotics, Inc.

Date: _

