OPERATIONS DOCUMENT 373

STANDARD OPERATING PROCEDURES FOR AUTONOMOUS MOBILE ROBOT

DEPLOYMENT AND MAINTENANCE

Effective Date: January 1, 2024

Document Version: 3.2

Last Updated: December 15, 2023

1. PURPOSE AND SCOPE

1. This Operations Document ("Document") establishes binding operational procedures and protocols

for the deployment, maintenance, and decommissioning of Polar Dynamics Robotics, Inc.

("Company") autonomous mobile robots ("AMRs") in temperature-controlled environments.

2. This Document applies to all Company personnel involved in AMR operations, including but not

limited to field technicians, deployment specialists, maintenance engineers, and operational

supervisors.

2. DEFINITIONS

1. "IceNav System" means the Company's proprietary cold-environment navigation and operation

platform.

2. "Critical Operating Temperature" means any ambient temperature below -30 C (-22 F).

3. "Deployment Zone" means any customer facility where Company AMRs are installed and

operational.

4. "Thermal Management Protocol" or "TMP" means the Company's standardized procedures for

maintaining optimal AMR operating temperatures.

3. DEPLOYMENT PROCEDURES

1. Pre-Deployment Assessment

a) Conduct comprehensive site survey including thermal mapping

b) Verify facility compliance with Company's Technical Specification 276-B

c) Document all thermal transition zones and temperature gradients

- d) Validate IceNav System compatibility with facility layout
- 2. Installation Requirements
- a) Follow Company Standard Installation Protocol 455
- b) Calibrate thermal sensors per Technical Bulletin 2023-07
- c) Install redundant emergency stop systems at prescribed intervals
- d) Verify charging station thermal management systems

4. MAINTENANCE PROTOCOLS

- 1. Scheduled Maintenance
- a) Perform weekly diagnostic scans of IceNav System
- b) Conduct monthly actuator stress tests
- c) Calibrate thermal management systems quarterly
- d) Replace cold-environment seals per maintenance schedule
- 2. Emergency Procedures
- a) Implement rapid shutdown protocol if thermal anomalies detected
- b) Follow Emergency Response Plan 92-C for system failures
- c) Document all incidents in Company's secure incident management system

5. SAFETY AND COMPLIANCE

- 1. The Company shall maintain compliance with:
- a) ISO 10218-1:2011 for robotic safety standards
- b) ANSI/RIA R15.06-2012 for industrial robot safety
- c) Company's proprietary Cold Environment Safety Protocol (CESP-2023)
- 2. Safety Documentation
- a) Maintain digital logs of all safety incidents
- b) Update safety protocols quarterly based on operational data
- c) Conduct monthly safety audits of all deployed systems

6. QUALITY CONTROL

1. Performance Metrics

a) Monitor and record AMR uptime in sub-zero environments

b) Track navigation accuracy in varying temperature conditions

c) Measure thermal management system efficiency

2. Quality Assurance

a) Conduct weekly performance reviews

b) Implement corrective actions within 24 hours of identified issues

c) Maintain quality control documentation for 7 years

7. PROPRIETARY INFORMATION

1. All technical specifications, procedures, and protocols contained herein constitute confidential and

proprietary information of the Company.

2. Disclosure of any portion of this Document to third parties is strictly prohibited without prior

written authorization from the Company's Legal Department.

8. AMENDMENTS AND UPDATES

1. This Document may be amended or updated by the Company at any time, with notice to relevant

personnel.

2. All amendments must be approved by the Chief Operations Officer and Chief Robotics Officer.

9. EXECUTION AND APPROVAL

IN WITNESS WHEREOF, this Operations Document has been executed by the duly authorized

representatives of the Company:

APPROVED BY:

Sarah Nordstrom

Chief Operations Officer

Date: December 15, 2023

Dr. James Barrett

Chief Robotics Officer

Date: December 15, 2023

Katherine Wells

Chief Financial Officer

Date: December 15, 2023

10. DOCUMENT CONTROL

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