

OPERATIONS DOCUMENT 404

STANDARD OPERATING PROCEDURES FOR AUTONOMOUS MOBILE ROBOT DEPLOYMENT AND MAINTENANCE

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1. PURPOSE AND SCOPE

1. This Operations Document 404 ("Document") establishes the binding operational procedures and protocols for the deployment, maintenance, and decommissioning of Polar Dynamics Robotics, Inc. ("Company") autonomous mobile robots ("AMRs") in temperature-controlled environments.
2. This Document applies to all Company personnel involved in AMR operations, including but not limited to field technicians, deployment specialists, maintenance engineers, and operational supervisors.

2. DEFINITIONS

1. "IceNav System" means the Company's proprietary cold-environment navigation and operation platform.
2. "Critical Operating Temperature" means any ambient temperature below -30 C (-22 F).
3. "Deployment Zone" means any customer facility where Company AMRs are installed and operational.
4. "Maintenance Protocol" means the prescribed series of inspection, service, and repair procedures detailed in Section 4.

3. DEPLOYMENT PROCEDURES

1. Pre-Deployment Assessment
 - a) Conduct comprehensive site survey of Deployment Zone
 - b) Document temperature mapping of operational areas
 - c) Verify IceNav System compatibility with facility layout

- d) Assess RF interference patterns and signal strength
- e) Validate emergency stop system placement

2. Installation Requirements

- a) AMR charging stations must be installed in temperature-controlled areas
- b) Navigation beacons shall be mounted at 3-meter intervals
- c) Thermal sensors must be calibrated to 0.5 C accuracy
- d) Emergency shutdown protocols must be integrated with facility systems

4. MAINTENANCE PROTOCOLS

1. Scheduled Maintenance

- a) Weekly inspection of thermal management systems
- b) Bi-weekly calibration of navigation sensors
- c) Monthly actuator performance assessment
- d) Quarterly full system diagnostics
- e) Semi-annual firmware updates

2. Critical Component Monitoring

- a) Battery thermal protection systems
- b) Cold-resistant actuator assemblies
- c) IceNav sensor arrays
- d) Emergency stop circuits
- e) Thermal management subsystems

5. SAFETY AND COMPLIANCE

1. The Company shall maintain compliance with:

- a) ANSI/RIA R15.06-2012 Safety Requirements
- b) ISO 10218-1:2011 Robot Safety Standards
- c) UL 3300 Robot Safety Certification
- d) CE Marking requirements for European operations

2. Safety Protocols

- a) Mandatory safety training for all operational personnel
- b) Monthly safety audits of Deployment Zones
- c) Quarterly emergency response drills
- d) Documentation of all safety incidents

6. QUALITY CONTROL

1. Performance Metrics

- a) Navigation accuracy within 5mm at Critical Operating Temperature
- b) System uptime minimum of 98.5%
- c) Mean time between failures (MTBF) > 5000 hours
- d) Battery lifecycle > 1000 charge cycles

2. Quality Assurance

- a) Daily performance logs
- b) Weekly system health reports
- c) Monthly performance analytics
- d) Quarterly quality review meetings

7. DOCUMENTATION AND REPORTING

1. Required Documentation

- a) Deployment checklists
- b) Maintenance records
- c) Incident reports
- d) Performance metrics
- e) Safety audit results

2. Reporting Schedule

- a) Daily operational status reports
- b) Weekly performance summaries
- c) Monthly maintenance reviews
- d) Quarterly compliance reports

8. PROPRIETARY INFORMATION

1. All technical specifications, procedures, and protocols contained within this Document are confidential and proprietary to Polar Dynamics Robotics, Inc.
2. This Document may not be reproduced, distributed, or shared without written authorization from the Company's Chief Technology Officer or Chief Operating Officer.

9. AMENDMENTS AND UPDATES

1. This Document shall be reviewed and updated annually or as required by operational changes.
2. All amendments must be approved by the Chief Robotics Officer and documented in the version control log.

AUTHORIZATION

APPROVED AND ADOPTED by the undersigned authorized officers of Polar Dynamics Robotics, Inc.

Date: January 1, 2024

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