

# Emergency Stop System Technical Documentation

**Document ID:** PDR-TECH-2023-185

**Version:** 3.2

**Last Updated:** December 15, 2023

**Classification:** CONFIDENTIAL - Technical Documentation

## 1. Overview and Scope

This document details the Emergency Stop (E-Stop) system specifications and safety protocols implemented across Polar Dynamics Robotics, Inc.'s ("PDR") autonomous mobile robot ("AMR") product line, specifically designed for cold environment operations. This documentation complies with ISO 13850:2015 Safety of machinery - Emergency stop function and ANSI/RIA R15.06-2012 Industrial Robots and Robot Systems Safety Requirements.

## 2. System Architecture

### 2.1 Hardware Components

- Primary E-Stop Circuit: Redundant, dual-channel safety architecture
- Secondary Mechanical Override: Cold-resistant manual activation mechanism
- Monitoring System: Independent safety PLC with temperature-hardened components
- Actuator Interface: Proprietary IceNav(TM) emergency deceleration controls
- Visual Indicators: LED status array with -40 C operational rating

### 2.2 Safety Category Classification

The E-Stop system maintains Safety Category 4 performance level (PLe) per ISO 13849-1:2015, featuring:

- Redundant circuit monitoring
- Cross-checking of system states
- Fault detection capability
- Self-testing at system startup and during operation

## 3. Functional Requirements

### 3.1 Activation Methods

Manual activation via physical E-Stop buttons

Remote activation through wireless safety controls

Automated activation triggered by safety sensor array

Network-level emergency shutdown protocol

### **3.2 Response Parameters**

- Maximum response time: 100ms at -30 C
- Deceleration rate: 2.5 m/s (configurable per deployment environment)
- System state verification: <50ms
- Reset lockout period: 3 seconds minimum

## **4. Cold Environment Specifications**

### **4.1 Operating Parameters**

- Temperature range: -40 C to +50 C
- Humidity tolerance: 5% to 95% non-condensing
- Ice accumulation resistance: Up to 2mm
- Thermal cycling: Rated for 10,000 cycles

### **4.2 Material Specifications**

- Actuator housing: Cold-resistant polymer composite (Patent pending #US2023/0158749)
- Circuit boards: Conformal coated with proprietary PDR ColdShield(TM) technology
- Wiring: Arctic-grade insulation rated to -50 C
- Seals: Silicon-based with thermal expansion compensation

## **5. Integration Requirements**

### **5.1 Control System Interface**

The E-Stop system integrates with the IceNav(TM) platform through:

- Dedicated safety fieldbus connection
- Real-time status monitoring
- Automated system diagnostics
- Event logging and reporting

## **5.2 Installation Specifications**

Minimum button spacing: 500mm

Maximum cable run: 100m

Required redundant power supply

Mandatory shield grounding

## **6. Testing and Validation**

### **6.1 Required Testing Procedures**

- Daily functional check at start-up
- Weekly full system test
- Monthly environmental stress testing
- Quarterly third-party safety certification

### **6.2 Documentation Requirements**

All testing must be documented including:

- Test date and conditions
- System response metrics
- Environmental parameters
- Tester certification information

## **7. Maintenance and Inspection**

### **7.1 Scheduled Maintenance**

- Monthly: Physical inspection of all E-Stop buttons
- Quarterly: Full system diagnostic review
- Semi-annual: Calibration verification
- Annual: Complete system recertification

### **7.2 Component Replacement**

- E-Stop buttons: Every 2 years or 10,000 activations
- Control modules: Every 5 years
- Wiring harnesses: Inspect annually, replace as needed
- Sensor arrays: Calibrate quarterly, replace every 3 years

## **8. Legal Disclaimers**

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The E-Stop system must be installed, maintained, and operated in accordance with all applicable safety regulations and the specifications contained herein. PDR assumes no liability for any damages arising from improper installation, maintenance, or operation of the system.

## **9. Document Control**

### **Approved By:**

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**Date: December 15, 2023**

**Document Control Number: PDR-TECH-2023-185-v3.2**

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