ROBOT BEHAVIOR LEARNING AND ADAPTATION SYSTEM

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TECHNICAL SPECIFICATION AND INTELLECTUAL

PROPRIETARY AND CONFIDENTIAL

NaviFloor Robotics, Inc.

Document Version: 3.2

Last Updated: January 11, 2024

1. SYSTEM OVERVIEW

1. This document describes the proprietary Robot Behavior Learning a

2. The System comprises proprietary algorithms, software architecture

2. TECHNICAL ARCHITECTURE

1. Core Components:

a) Neural Network-Based Decision Engine

b) Multi-Surface Terrain Classification System

c) Dynamic Path Planning Algorithm

d) Behavioral Learning Database

e) Real-time Adaptation Module

2. System Infrastructure:

a) Edge Computing Framework

b) Distributed Learning Network

c) Secure Data Storage Architecture

d) Fleet-wide Knowledge Sharing Protocol

3. PROPRIETARY TECHNOLOGIES

1. Protected Algorithms:

a) TerrainSense(TM) - Surface classification and response calibration

b) AdaptiveNav(TM) - Real-time navigation optimization

c) FleetLearn(TM) - Distributed learning across robot fleet

d) SafeMotion(TM) - Collision avoidance and safety protocols

2. Patent Status:

a) US Patent No. 11,XXX,XXX: "Method for Autonomous Robot Learn

Environments"

b) US Patent Application No. 17/XXX,XXX: "System for Multi-Surface and Adaptation"

c) PCT Application No. PCT/US2023/XXXXX: "Distributed Learning S Fleets"

4. DATA COLLECTION AND PROCESSING

1. The System collects and processes the following data types:

a) Environmental mapping data

b) Surface texture and composition metrics

c) Robot performance parameters

d) Operational efficiency metrics

e) Safety incident logs

2. Data Security Measures:

a) AES-256 encryption for data at rest

b) TLS 1.3 for data in transit

c) Secure boot verification

d) Hardware security module integration

5. LEARNING METHODOLOGY

1. The System employs a hybrid learning approach incorporating:

a) Supervised learning for initial behavior modeling

b) Reinforcement learning for optimization

c) Transfer learning across robot units

d) Federated learning for fleet-wide improvements

2. Learning Parameters:

a) Surface adaptation coefficients

b) Navigation confidence scores

c) Performance optimization metrics

d) Safety threshold values

6. INTELLECTUAL PROPERTY PROTECTION

1. The Company maintains exclusive ownership of:

a) All source code and compiled software

b) Training data and derived models

c) System architecture designs

d) Implementation methodologies

e) Documentation and technical specifications

2. Trade Secret Protection:

a) Core algorithms maintained as trade secrets

b) Proprietary training methodologies

c) System optimization parameters

d) Performance tuning protocols

7. COMPLIANCE AND CERTIFICATION

1. The System complies with:

a) ISO/TS 15066:2016 (Robots and robotic devices)

b) IEC 61508 (Functional Safety)

c) UL 3100 (Automated Mobile Platforms)

d) ANSI/RIA R15.06-2012 (Industrial Robots)

8. CONFIDENTIALITY

1. All information contained herein is strictly confidential and constitute

9. AUTHENTICATION

IN WITNESS WHEREOF, this document has been executed by the du

representatives of NaviFloor Robotics, Inc.

By:

Dr. Sarah Chen

CEO & Co-founder

NaviFloor Robotics, Inc.

By:

Marcus J. Depth

CTO & Co-founder

NaviFloor Robotics, Inc.

Date: January 11, 2024

Document Control Number: IP-RBLAS-2024-001

Classification: CONFIDENTIAL - Level 1

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