

# **PATENT SPECIFICATION**

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### **BLUECORE(TM) EMERGENCY SHUTDOWN PROTOCOL**

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## **ABSTRACT**

A system and method for emergency shutdown of autonomous mobile devices in extreme cold environments, comprising a multi-layered safety protocol.

ensures graceful degradation of robotic systems while preserving critical operational data and preventing damage to temperature-sensitive components.

## BACKGROUND

[001] This invention relates to safety systems for autonomous mobile robots operating in sub-zero environments, specifically addressing the challenges of emergency shutdown procedures in temperature-controlled facilities where standard shutdown protocols may be insufficient or potentially damaging to robotic components.

[002] Conventional emergency shutdown systems for autonomous mobile robots typically assume ambient operating temperatures above 0 C (32 F). When deployed in extreme cold environments, standard shutdown procedures can lead to mechanical failure, sensor damage, and loss of critical operational data.

## **DETAILED DESCRIPTION**

### **1. System Overview**

[010] The BlueCore(TM) Emergency Shutdown Protocol comprises:

- a) A primary control unit with redundant temperature-hardened processes
- b) Multiple distributed thermal sensors
- c) Proprietary shutdown sequence algorithms
- d) Emergency power reserve system
- e) Data preservation module

### **2. Components and Architecture**

[020] The primary control unit includes:

1. Dual-redundant processing cores rated for operation at -40 C
2. Solid-state memory arrays with cold-temperature optimization
3. Thermal management subsystem with active heating elements
4. Emergency power cells with cold-resistant chemistry

[021] Distributed sensor network comprising:

5. Temperature sensors with 0.1 C accuracy at sub-zero temperatures
6. Motion detection systems with ice/frost compensation
7. Power monitoring circuits with thermal calibration

### **3. Shutdown Sequence**

[030] The emergency shutdown protocol executes in the following sequence:

1. Initiation Triggers:

- a) Detection of critical system failure
- b) Temperature excursion beyond operational parameters
- c) Power system anomaly
- d) Manual emergency stop activation
- e) Network connectivity loss exceeding predetermined threshold

## 2. Primary Sequence:

- a) Immediate cessation of all motion systems
- b) Activation of emergency brake mechanisms
- c) System state preservation to protected memory
- d) Initiation of thermal protection protocols
- e) Emergency beacon activation

## 3. Data Protection:

- a) Real-time operational data compression
- b) Secure storage in temperature-hardened memory
- c) Transmission of critical data to facility control system
- d) Creation of encrypted backup in redundant storage

#### **4. Safety Features**

[040] The protocol incorporates multiple safety mechanisms:

##### **1. Mechanical Safety:**

- a) Fail-safe brake engagement
- b) Component protection through controlled power reduction
- c) Thermal protection of critical systems

##### **2. Data Safety:**

- a) Multiple redundant storage systems
- b) Encrypted data transmission
- c) Black box recording system

## **5. Recovery Procedures**

[050] The system includes automated recovery procedures:

### **1. System Verification:**

- a) Component integrity checking
- b) Sensor calibration verification
- c) Power system assessment
- d) Data integrity verification

### **2. Restart Sequence:**

- a) Gradual power restoration
- b) Systematic component activation
- c) Operational parameter verification
- d) Return to service protocols

## **CLAIMS**

A method for emergency shutdown of autonomous mobile robots in s

- a) Detecting emergency conditions through distributed thermal sensors
- b) Executing a temperature-optimized shutdown sequence
- c) Preserving operational data in cold-resistant storage
- d) Maintaining critical system integrity during shutdown

The method of claim 1, wherein the shutdown sequence includes:



- a) Immediate motion cessation
- b) Thermal protection activation
- c) Data preservation procedures
- d) Emergency signal transmission

[Additional claims 3-20 omitted for brevity]

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## **ASSIGNMENT**

All rights, title, and interest in this patent are assigned to Polar Dynamics Robotics, Inc., a Delaware corporation.

## **CERTIFICATION**

I hereby certify that I am the original inventor of the technology described herein.

/s/ Dr. Elena Frost

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