

PREDICTIVE MAINTENANCE ALGORITHM FOR ROBOT COMPONENTS

PREDICTIVE MAINTENANCE ALGORITHM FOR

PROPRIETARY & CONFIDENTIAL DOCUMENTATION

NaviFloor Robotics, Inc.

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1. OVERVIEW AND SCOPE

1. This document describes the proprietary predictive maintenance algorithm for robot components.

2. The Algorithm constitutes protected intellectual property of the Company

2. ALGORITHM SPECIFICATIONS

1. Core Components

- a) Real-time sensor data collection system
- b) Machine learning model based on gradient-boosted decision trees
- c) Component wear prediction engine
- d) Maintenance scheduling optimization module
- e) Integration with NaviFloor Fleet Management Platform v4.2

2. Data Collection Parameters

- a) Vibration frequency analysis (0.1-1000 Hz range)
- b) Temperature variations (0.1 C precision)

- c) Motor current draw patterns
- d) Wheel torque measurements
- e) LiDAR system performance metrics
- f) Battery charge/discharge cycles

3. PROPRIETARY METHODOLOGIES

1. The Algorithm employs the following proprietary methodologies:
 - a) Multi-modal sensor fusion using Company's patented NaviSense(TM)
 - b) Adaptive threshold determination based on operational environment
 - c) Component-specific wear pattern recognition
 - d) Environmental factor compensation algorithms
 - e) Fleet-wide learning distribution system

2. Protected Elements

- a) Sensor calibration coefficients
- b) Neural network architecture
- c) Training datasets and parameters
- d) Failure prediction models
- e) Maintenance optimization algorithms

4. IMPLEMENTATION REQUIREMENTS

1. Hardware Requirements

- a) NaviFloor Sensor Package v3.0 or higher
- b) Minimum processor specifications: ARM Cortex-A72 or equivalent
- c) Dedicated FPGA for real-time processing
- d) Minimum 8GB RAM for local processing

2. Software Requirements

- a) NaviFloor Core Operating System v4.5+
- b) Real-time monitoring module v2.3
- c) Secure data transmission protocol implementation
- d) Local edge processing capabilities

5. CONFIDENTIALITY AND SECURITY

- 1. All aspects of the Algorithm, including but not limited to its architecture

2. Access Requirements

- a) Minimum security clearance level: L3
- b) Signed confidentiality agreement
- c) Need-to-know basis authorization

d) Continuous access monitoring

6. INTELLECTUAL PROPERTY PROTECTION

1. Patent Protection

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U.S. Patent No. 11,234,567

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PCT Application No. PCT/US2023/012345

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European Patent Application No. EP21234567

2. Copyright Registration

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US Copyright Registration No. TX-9-876-543

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Source code protection under DMCA

7. USAGE RESTRICTIONS

1. The Algorithm may only be implemented in Company-authorized hardware.
2. Any modification, reverse engineering, or unauthorized access to the Algorithm is prohibited.
3. Usage monitoring and audit trails are automatically maintained.

8. MAINTENANCE AND UPDATES

1. Algorithm updates are pushed quarterly through secure channels.
2. Version control and change management procedures must follow Company standards.

9. LEGAL NOTICES

1. PROPRIETARY INFORMATION: This document contains proprietary information of NaviFloor Robotics, Inc. All rights reserved.
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10. DOCUMENT CONTROL

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