

TERRAIN CLASSIFICATION ALGORITHM DOCUMENTATION

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NaviFloor Robotics, Inc.

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Classification: CONFIDENTIAL

1. PROPRIETARY NOTICE AND LEGAL DISCLAIM

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2. ALGORITHM OVERVIEW

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1. The NaviFloor Terrain Classification Algorithm ("NTCA") comprises a pr

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2. Primary Components:

- a) LiDAR-based depth sensing module
- b) Multi-surface texture analysis engine
- c) Dynamic coefficient of friction calculator
- d) Terrain feature extraction system
- e) Machine learning classification framework

3. TECHNICAL SPECIFICATIONS

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1. Core Algorithm Parameters:

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Sampling Rate: 1000Hz

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Resolution: 0.5mm vertical, 1mm horizontal

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Processing Latency: <5ms

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Classification Accuracy: 99.7% under standard conditions

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2. Input Requirements:

- - 3 -

Minimum point cloud density: 100 points/cm²

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Sensor data format: NaviFloor Standard Format (NSF) v2.1

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Environmental lighting: 5-10,000 lux

4. INTELLECTUAL PROPERTY PROTECTION

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1. Patent Coverage:

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US Patent No. 11,234,567: "Method for Real-time Surface Classification in a

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US Patent No. 11,345,678: "Multi-modal Terrain Analysis System"

- - 4 -

PCT Application No. PCT/US2023/012345 (pending)

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2. Trade Secret Protection:

The following components are maintained as trade secrets:

- a) Surface texture correlation matrices
- b) Dynamic coefficient calculation methods
- c) Machine learning model architecture
- d) Training data preprocessing techniques

5. IMPLEMENTATION REQUIREMENTS

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1. Hardware Dependencies:

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NaviFloor Series 3000 LiDAR Array

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Minimum computing specifications:

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Processing: 4.0 GHz quad-core

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Memory: 16GB RAM

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Storage: 256GB SSD

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2. Software Dependencies:

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NaviFloor Runtime Environment v4.2 or higher

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CUDA 11.0+

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ROS2 Humble

6. PERFORMANCE METRICS AND VALIDATION

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1. Certified Performance Levels:

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Classification Speed: <10ms per frame

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False Positive Rate: <0.1%

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Surface Type Recognition: 32 distinct categories

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Operating Temperature: -10°C to 45°C

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2. Validation Protocol:

Testing and validation conducted in accordance with ISO 13849-1:2015 and 61508.

7. USAGE RESTRICTIONS

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1. The NTCA may only be implemented in:

- a) NaviFloor-manufactured devices
- b) Licensed third-party systems with written authorization
- c) Approved testing environments

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2. Prohibited Applications:

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Military or defense systems

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Non-industrial consumer applications

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Unauthorized reverse engineering

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Integration with non-certified hardware

8. MAINTENANCE AND UPDATES

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1. Algorithm updates are provided through:

- - 9 -

Quarterly maintenance releases

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Critical security patches

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Performance optimization updates

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2. Version Control:

All implementations must maintain strict version control in accordance with NaviFloor's Change Management Protocol (CMP-2023-V2).

9. COMPLIANCE AND CERTIFICATION

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1. Regulatory Compliance:

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ISO/IEC 27001:2013

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CE Marking (EU)

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UL 1740 (Safety Standard for Robots)

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ANSI/RIA R15.06-2012

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2. Industry Certifications:

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TÜV SÜD Functional Safety Certification

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IECEEx certification for hazardous environments

10. LEGAL GOVERNANCE

This documentation is governed by the laws of the State of Delaware, United States, without regard to conflicts of law principles. Any dispute arising from or relating to this documentation shall be subject to the exclusive jurisdiction of the courts of Delaware.

11. DOCUMENT CONTROL

Document Owner: Chief Technology Office

Technical Review: Dr. Elena Kovacs, Chief Research Officer

Legal Review: James Wilson, General Counsel

Security Classification: Confidential - Level 2

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APPROVED AND AUTHORIZED:

Marcus Depth

Chief Technology Officer

NaviFloor Robotics, Inc.

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