PDR-AMR-001 Base Platform Technical Specifications v2.1

CONFIDENTIAL AND PROPRIETARY

Polar Dynamics Robotics, Inc.

Effective Date: January 11, 2024

1. DOCUMENT CONTROL

- 1. This document supersedes and replaces version 2.0 dated October 15, 2023.
- 2. Distribution of this document is restricted to authorized personnel and subject to Non-Disclosure Agreement dated March 1, 2023.

2. BASE PLATFORM SPECIFICATIONS

- 1. Physical Specifications
- Dimensions: 1200mm (L) x 900mm (W) x 450mm (H)
- Unloaded Weight: 185 kg
- Maximum Payload Capacity: 750 kg
- Ground Clearance: 45mm
- Turning Radius: 0 (Zero-turn capability)
- 2. Operating Environment Parameters
- Temperature Range: -40 C to +45 C
- Humidity: 5% to 95% non-condensing
- IP Rating: IP65 (main chassis)
- Floor Condition Requirements: Smooth concrete, epoxy, or similar industrial surfaces
- Maximum Slope Operation: 5% grade

3. PROPULSION SYSTEM

- 1. Drive Configuration
- Quad-drive differential steering system
- Proprietary ColdTech(TM) actuators (Patent No. US 11,XXX,XXX)
- Thermal-managed brushless DC motors

- Regenerative braking capability

2. Performance Specifications

- Maximum Speed: 2.0 m/s

- Acceleration: 0.5 m/s

- Deceleration: 0.8 m/s

- Emergency Stop Distance: 300mm at full speed

4. POWER SYSTEM

1. Battery Specifications

- Type: Lithium Iron Phosphate (LiFePO4)

- Capacity: 48V, 200Ah

- Runtime: 12 hours (typical operation)

- Charging Time: 2.5 hours (10-90%)

- Cycle Life: >3,000 cycles

2. Charging System

- Input Voltage: 200-240VAC, 50/60Hz

- Maximum Charging Current: 40A

- Charging Protocol: CCS Type 2

- Auto-docking capability with IceNav(TM) guidance

5. NAVIGATION AND CONTROL

1. Sensor Suite

- 2x 3D LiDAR (270 FOV each)
- 8x Time-of-Flight sensors
- 4x RGB-D cameras
- IMU with temperature compensation
- Wheel encoders with anti-slip detection

2. IceNav(TM) Platform

- Localization Accuracy: 15mm

- Path Planning Update Rate: 10Hz
- Dynamic Obstacle Detection Range: 25m
- Cold-environment optimized SLAM algorithms
- Multi-robot coordination capability

6. SAFETY SYSTEMS

- 1. Emergency Systems
- 360 emergency stop buttons
- Remote emergency stop capability
- Automatic collision avoidance
- Load shift detection
- Thermal runaway protection
- 2. Compliance
- CE Marking (Machinery Directive 2006/42/EC)
- ISO 3691-4:2020
- ANSI/RIA R15.08-1-2020
- IEC 61496-1:2020
- EN 1525:1997

7. COMMUNICATION INTERFACES

- 1. Wireless Communications
- Wi-Fi 6 (IEEE 802.11ax)
- Bluetooth 5.2
- 4G LTE fallback
- Proprietary mesh networking
- 2. Integration Interfaces
- REST API
- WebSocket support
- OPC UA compatibility
- Custom protocol support via SDK

8. MAINTENANCE SPECIFICATIONS

1. Scheduled Maintenance Intervals

- Daily: Visual inspection

Weekly: Sensor cleaning

Monthly: Battery diagnostics

Quarterly: Full system calibration

- Annual: Major service

2. Mean Time Between Failures (MTBF)

- Drive System: 15,000 hours

- Battery System: 20,000 hours

- Electronics: 25,000 hours

- Sensors: 30,000 hours

9. PROPRIETARY NOTICE

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10. DOCUMENT APPROVAL

APPROVED BY:

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Date: January 11, 2024

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