AUTONOMOUS ROBOT SAFETY PROTOCOL MANUAL

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Version 3.1

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1. INTRODUCTION AND SCOPE

- 1. This Autonomous Robot Safety Protocol Manual ("Protocol") is issu
- 2. This Protocol applies to all PDR Series X-100, X-200, and X-300 at

2. DEFINITIONS

- 1. "AMR" means any autonomous mobile robot manufactured by PDF
- 2. "Operating Environment" means any controlled temperature facility
- 3. "Safety Zone" means the designated perimeter surrounding an AM
- 4. "Emergency Stop System" or "EMS" means PDR's proprietary eme

3. SAFETY CERTIFICATIONS AND COMPLIANCE

- 1. All AMRs must maintain current certification under:
- a) ISO 10218-1:2011 (Robots and robotic devices)
- b) ANSI/RIA R15.06-2012 (Industrial Robots and Robot Systems)

- c) IEC_61496-1:2020 (Safety of machinery Electro-sensitive protective equipment)
- 2. Operating Environment Requirements:
- a) Maximum floor grade variation: 1.5%
- b) Minimum aisle width: 2.8 meters
- c) Emergency exit clearance: 3.5 meters
- d) Floor surface friction coefficient: 0.4 minimum

4. OPERATIONAL SAFETY PROTOCOLS

- 1. Pre-Operation Verification
- a) System diagnostic check
- b) Sensor calibration verification

- c) Emergency Stop System test
- d) BlueCore(TM) temperature adaptation cycle
- e) Navigation system alignment
- 2. Operating Parameters
- a) Maximum velocity: 1.8 meters/second
- b) Minimum separation distance: 3.0 meters
- c) Load capacity: As specified per model
- d) Operating temperature range: -40 C to 0 C
- 3. Safety Zone Monitoring
- a) Continuous LiDAR scanning
- b) Infrared proximity detection
- c) Machine vision system monitoring

d) Audiq-visual warning system activation

5. EMERGENCY PROCEDURES

- 1. Automatic Shutdown Triggers:
- a) Human presence within 1.0 meter
- b) Mechanical obstruction detection
- c) System temperature exceeding specifications
- d) Navigation system failure
- e) Power system anomaly
- 2. Manual Emergency Procedures:
- a) Emergency Stop Button activation
- b) Remote shutdown protocol

- c) Facility-wide system halt
- d) Emergency evacuation procedure

6. MAINTENANCE AND INSPECTION

- 1. Required Maintenance Schedule:
- a) Daily system diagnostics
- b) Weekly sensor calibration
- c) Monthly mechanical inspection
- d) Quarterly software updates
- e) Annual certification renewal
- 2. Documentation Requirements:
- a) Maintenance logs

- b) Incident reports
- c) Certification records
- d) Training records
- e) Software update history

7. TRAINING REQUIREMENTS

- 1. Required Personnel Training:
- a) Basic AMR operation
- b) Emergency response procedures
- c) Maintenance protocols
- d) Safety system operation
- e) Regulatory compliance

- 2. Certification Requirements:
- a) Initial operator certification
- b) Annual recertification
- c) Safety officer designation
- d) Maintenance technician qualification

8. LIABILITY AND INDEMNIFICATION

- 1. Operation of AMRs in violation of this Protocol voids all warranties
- 2. Operator assumes all liability for damages resulting from non-comp

9. PROTOCOL UPDATES AND REVISIONS

1. PDR reserves the right to update this Protocol as required by:

a)	Regų	atory c	hanges
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- b) Technology updates
- c) Safety requirements
- d) Operating environment modifications
- 2. Operators must implement Protocol updates within 30 days of issua

AUTHORIZATION

This Protocol is authorized and approved by:

Dr. Elena Frost

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Dr. James Barrett

Chief Robotics Officer

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Date: January 15, 2024

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