OPERATIONS DOCUMENT 405

STANDARD OPERATING PROCEDURES FOR AUTONOMOUS MOBILE ROBOT

DEPLOYMENT AND MAINTENANCE

Effective Date: January 1, 2024

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1. PURPOSE AND SCOPE

1. This Operations Document 405 ("Document") establishes the binding operational procedures and

protocols for the deployment, maintenance, and decommissioning of Polar Dynamics Robotics, Inc.

("Company") autonomous mobile robots ("AMRs") in temperature-controlled environments.

2. This Document applies to all Company employees, contractors, and authorized third-party service

providers involved in the deployment, operation, or maintenance of Company AMRs.

2. DEFINITIONS

1. "IceNav System" means the Company's proprietary cold-environment navigation and operation

platform.

2. "Critical Operating Temperature" means any ambient temperature below -30 C (-22 F).

3. "Deployment Zone" means any customer facility or operating environment where Company

AMRs are installed and operational.

4. "Maintenance Protocol" means the prescribed series of inspection, service, and repair procedures

detailed in Section 4.

3. DEPLOYMENT PROCEDURES

1. Pre-Deployment Assessment

a) Environmental survey of Deployment Zone

b) Temperature mapping and variation analysis

c) Floor surface evaluation and friction testing

d) Network infrastructure verification

- e) Safety system compatibility check
- 2. IceNav System Configuration
- a) Zone-specific thermal calibration
- b) Navigation mesh generation and validation
- c) Emergency stop system verification
- d) Fail-safe protocol programming
- e) Customer-specific operating parameters setup
- 3. Initial Operation Protocol
- a) Minimum 48-hour system observation period
- b) Progressive load testing sequence
- c) Navigation accuracy verification
- d) Collision avoidance validation
- e) Emergency response timing confirmation

4. MAINTENANCE PROTOCOLS

- 1. Scheduled Maintenance Requirements
- a) Weekly visual inspections
- b) Monthly actuator performance testing
- c) Quarterly thermal management system evaluation
- d) Semi-annual software system updates
- e) Annual full-system certification
- 2. Critical Component Monitoring
- a) Thermal protection systems
- b) Navigation sensors
- c) Drive train assemblies
- d) Battery management systems
- e) Emergency stop mechanisms
- 3. Performance Monitoring Requirements
- a) Daily operational metrics collection

- b) Weekly performance analysis
- c) Monthly trend evaluation
- d) Quarterly efficiency assessment
- e) Annual performance review

5. SAFETY AND COMPLIANCE

- 1. Safety Standards
- a) Compliance with ISO 10218-1:2011
- b) Adherence to ANSI/RIA R15.06-2012
- c) Conformance to CE Machinery Directive 2006/42/EC
- d) Implementation of ISO 13849-1:2015 requirements
- 2. Emergency Procedures
- a) Immediate response protocols
- b) System shutdown procedures
- c) Emergency maintenance guidelines
- d) Incident reporting requirements
- e) Recovery protocols

6. DOCUMENTATION AND REPORTING

- 1. Required Documentation
- a) Deployment checklist completion
- b) Maintenance log updates
- c) Performance metric recording
- d) Incident documentation
- e) Compliance certification maintenance
- 2. Reporting Schedule
- a) Daily operational summaries
- b) Weekly performance reports
- c) Monthly maintenance records
- d) Quarterly compliance reviews

e) Annual system audits

7. PROPRIETARY INFORMATION

1. All technical specifications, procedures, and protocols contained within this Document are

considered confidential and proprietary information of Polar Dynamics Robotics, Inc.

2. Distribution of this Document is restricted to authorized personnel only and subject to applicable

non-disclosure agreements.

8. AMENDMENTS AND UPDATES

1. This Document may be amended or updated by the Company at any time, with notice provided to

all relevant parties.

2. All amendments must be approved by the Chief Technology Officer and Chief Operations Officer.

9. EXECUTION

IN WITNESS WHEREOF, the undersigned hereby acknowledges and agrees to comply with all

procedures and protocols set forth in this Operations Document 405.

POLAR DYNAMICS ROBOTICS, INC.

By:

Name: Sarah Nordstrom

Title: Chief Operations Officer

Date: _

By:

Name: Marcus Chen

Title: Chief Technology Officer

Date: _