

AUTONOMOUS NAVIGATION TEST RESULTS - ARCTIC CONDITIONS

AUTONOMOUS NAVIGATION TEST RESULTS

Test Protocol Documentation and Performance Analysis

Polar Dynamics Robotics, Inc.

Document Reference: PDR-ANT-2023-142

Date: December 15, 2023

1. EXECUTIVE SUMMARY

This document presents the official test results and performance analysis for the Arctic navigation trials conducted on the Polar Dynamics Robotics' BlueCore(TM) Autonomous Navigation System. The trials were designed to evaluate the system's ability to maintain accurate navigation and safe operation in extreme cold, low-visibility, and icy terrain conditions.

simulated arctic conditions. Testing was conducted at the Advanced Cold Environment Testing Facility (ACETF) in accordance with ISO 18495:2017 for autonomous mobile robots in extreme environments.

2. TEST PARAMETERS

1. **Environmental Conditions**

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Temperature Range: -40 C to -15 C

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Wind Speed Simulation: 0-45 km/h

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Surface Conditions: Ice, Packed Snow, Mixed Terrain

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Visibility: Clear to White-Out Conditions

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Testing Duration: 168 hours continuous operation

2. **Test Units**

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Model: PDR-AMR-X350-B

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Quantity: Three (3) production units

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Serial Numbers: X350B-2023-089, X350B-2023-090, X350B-2023-091

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Software Version: BlueCore(TM) v4.2.1

3. NAVIGATION PERFORMANCE METRICS

1. **Path Accuracy**

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Mean Deviation from Programmed Path: 2.3cm

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Maximum Recorded Deviation: 4.8cm

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Standard Deviation: 1.1cm

2. **Obstacle Detection**

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Detection Range: 0.1m to 25m

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False Positive Rate: 0.02%

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False Negative Rate: 0.001%

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Response Time: 42ms average

3. ****System Reliability****

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Navigation System Uptime: 99.97%

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Sensor Array Performance: 99.99%

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Communication System Stability: 99.98%

4. COLD WEATHER PERFORMANCE

1. ****Power Systems****

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Battery Performance at -40 C: 92% of rated capacity

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Charge Retention: 94% over 24 hours

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Average Power Consumption: 1.2kW/h

2. **Mechanical Systems**

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Drive Train Efficiency: 96%

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Joint Mobility: Full range of motion maintained

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Chassis Integrity: No structural deformation observed

3. **Sensor Performance**

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LiDAR Accuracy: 1.2mm at -40 C

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Camera System Function: 100% operational

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Infrared Sensor Range: 98% of rated performance

5. SAFETY COMPLIANCE

1. **Emergency Systems**

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Emergency Stop Function: 100% successful across 500 trials

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Fail-Safe Activation Time: <100ms

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Backup Systems Engagement: 100% reliable

2. ****Regulatory Compliance****

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ANSI/RIA R15.06-2012

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ISO 13482:2014

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IEC 61496-1:2020

6. CERTIFICATION AND VALIDATION

The undersigned hereby certify that all tests were conducted in accordance with Polar Dynamics Robotics' Standard Operating Procedures and applicable standards. Results documented herein are accurate and complete.

7. LEGAL DISCLAIMERS

1. This document contains confidential and proprietary information belonging to the University of California, San Diego.
2. Test results reflect performance under controlled conditions and may not be representative of real-world performance.
3. All technical specifications and performance metrics are subject to change without notice.

8. AUTHENTICATION

Certified by:

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