# **EXTREME CONDITION STRESS TESTING MANUAL**

# **EXTREME CONDITION STRESS TESTING MA**

**Document ID: PDR-OPS-024** 

Version: 3.2

Effective Date: January 15, 2024

**Classification: CONFIDENTIAL** 

## 1. PURPOSE AND SCOPE

1. This Extreme Condition Stress Testing Manual ("Manual") establish

2. This Manual applies to all BlueCore(TM)-enabled robots and associate
2. DEFINITIONS
"Test Unit" means any PDR robot or component system undergoin
2. "Testing Environment" means PDR's ISO/IEC 17025-certified Envir
3. "Critical Systems" include, but are not limited to:
a) BlueCore(TM) navigation modules
b) Power distribution systems
c) Motor control units
d) Sensor arrays
e) Emergency shutdown mechanisms

# 3. TESTING REQUIREMENTS

1. Temperature Cycling Protocol	
1.1. Each Test Unit shall undergo minimum 72-hour continuous opera	
1.2. Temperature cycles shall follow the prescribed pattern:	
-	
4 hours at -40 C	
-	
2 hours transition to -20 C	
-	
4 hours at -20 C	
-	
2 hours transition to 0 C	

#### Repeat sycle 6 times

- 2. Load Testing Requirements
- 2.1. Test Units must maintain rated payload capacity throughout testing
- 2.2. Dynamic load variations shall be introduced at 2-hour intervals.
- 2.3. Emergency stop functionality must be verified at temperature exti

# 4. PERFORMANCE METRICS

- 1. Navigation Accuracy
- 1.1. Maximum allowable deviation: 15mm at -40 C
- 1.2. Sensor calibration drift: <2% from baseline
- 1.3. Path-finding latency: <50ms
- 2. Power Systems

- 2.1. Battery discharge rate variation: <15% from room temperature ba
- 2.2. Charging efficiency: >85% at all test temperatures
- 2.3. Voltage stability: 0.5V maximum variation

## **5. SAFETY PROTOCOLS**

- 1. Testing Personnel Requirements
- 1.1. Minimum two certified technicians present during testing
- 1.2. Valid PDR Environmental Safety certification required
- 1.3. Personal protective equipment mandatory per Schedule A
- 2. Emergency Procedures
- 2.1. Immediate testing suspension if:

-

Fire detection system activation

-

Unauthorized chamber access

-

Test Unit thermal runaway

-

Control system failure

## 6. DATA COLLECTION AND REPORTING

- 1. Required Measurements
- 1.1. Core system temperatures at 5-minute intervals
- 1.2. Power consumption metrics
- 1.3. Navigation accuracy measurements

- 1.4. System response times
- 1.5. Error logs and fault conditions
- 2. Documentation Requirements
- 2.1. Complete test logs maintained in PDR's secure testing database
- 2.2. Video recording of all test sequences
- 2.3. Calibration certificates for all measurement equipment

#### 7. COMPLIANCE AND CERTIFICATION

- 1. Each Test Unit must meet or exceed all performance metrics define
- 2. Testing certification is valid for:
- 2.1. 12 months for new robot models
- 2.2. 24 months for previously certified models with no modifications

3. Non-qampliance requires immediate retesting and engineering revi
8. PROPRIETARY INFORMATION
All testing procedures, results, and documentation contained herein
2. Disclosure to third parties prohibited without written authorization fr
9. DOCUMENT CONTROL
Approved by:
_
Dr. James Barrett
Chief Robotics Officer

Date: -8
Sarah Nordstrom
Chief Operating Officer

Date:

...

Document History:

Version 3.2: January 15, 2024

Version 3.1: July 12, 2023

Version 3.0: January 30, 2023

