Backward Difference Method

BDM_12_2_A(alpha,h,0.0005,t)

```
x w u e =
       0.1
             0.002342
                        0.0022224
                                   0.00011954
       0.2 0.0044547
                        0.0042273
                                   0.00022738
       0.3 0.0061313
                                   0.00031296
                        0.0058184
       0.4 0.0072078
                        0.0068399
                                   0.00036791
       0.5 0.0075787
                        0.0071919
                                   0.00038684
       0.6 0.0072078
                        0.0068399
                                   0.00036791
       0.7 0.0061313
                        0.0058184
                                   0.00031296
       0.8 0.0044547
                        0.0042273
                                   0.00022738
                        0.0022224
       0.9
            0.002342
                                   0.00011954
```

```
alpha = 1;
h = 0.1;
v = 0.01;
t = 0.5;
BDM_12_2_A(alpha,h,v,t)
```

```
x_w_u_e =
```

0.1	0.002898	0.0022224	0.0006756
0.2	0.0055124	0.0042273	0.0012851
0.3	0.0075871	0.0058184	0.0017688
0.4	0.0089192	0.0068399	0.0020793
0.5	0.0093782	0.0071919	0.0021863
0.6	0.0089192	0.0068399	0.0020793
0.7	0.0075871	0.0058184	0.0017688
0.8	0.0055124	0.0042273	0.0012851
0.9	0.002898	0.0022224	0.0006756

Source Code

```
clear;
clc;
close all;

format shortg

alpha = 1;
h = 0.1;
v = 0.01;
t = 0.5;

BDM_12_2_A(alpha,h,0.0005,t)
BDM_12_2_A(alpha,h,v,t)
```

```
function BDM_12_2_A(al,h,v,t)
    m = 1/h;
    iterations = t/v;
% s = a1^2*v/h^2;
    x = zeros(m-1,1);
    %go horizontal
    for i =1:m-1
        x(i) = i*h;
    end
    W = \sin(pi*x);
    wn = zeros(m-1,1);
    %go vertical
    [c,d,e] = compute_tridiag(wn, al, v, h);
    for j = 1:iterations
        wn = gaussian_diag(c,d,e, w);
        w = wn;
    end
    %compute true solution
    u = true_solution(x,t);
    e = abs(u-w);
    x_w_u = [x,w,u,e]
end
```

```
function [u] = true_solution(x,t)
    u = \exp(-pi^2*t)*\sin(pi*x);
end
function [c,d,e] = compute_tridiag(W, alpha, v,
h)
    n = length(W);
    c = zeros(n,1);
    d = zeros(n,1);
    e = zeros(n,1);
    lambda = alpha^2*(v/h^2);
    d(1) = (1 + (2*lambda));
    e(1) = -lambda;
    for i = 2:n-1
        c(i) = -lambda;
        d(i) = (1 + (2*lambda));
        e(i) = -lambda;
    end
    c(n) = -lambda;
    d(n) = (1 + (2*lambda));
end
```

```
function W = gaussian_diag(c,d,e,b)

n = length(d);

W = zeros(n,1);

for k = 2:n

    mult = -c(k)/d(k-1);
    d(k) = mult*e(k-1) + d(k);
    b(k) = mult*b(k-1) + b(k);

end

W(n) = b(n)/d(n);

for k = n-1:-1:1

    W(k) = (b(k)-e(k)*W(k+1))/d(k);

end

end
```