



Code CONstructor User Tool

supported by

- Canadian Foundation for Innovation
- Ontario Innovation Trust (?!)
- Apple Canada
- McMaster University



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Coconut

Christopher Anand

3 years Medical Electronics Industry

4 patents + 2 pending
real-time, parallel MRI,
rack of PPC604/750s

best result: 1000X performance
mathematical transformation
efficient implementation

W60



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HOPS

term-graph-based
program transformation
code generation
derivation of correct programs
functional programming
relation-algebraic methods



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- targeting numerical code
 - signal processing
 - image processing
 - math libraries
- goals
 - more reliable
 - faster



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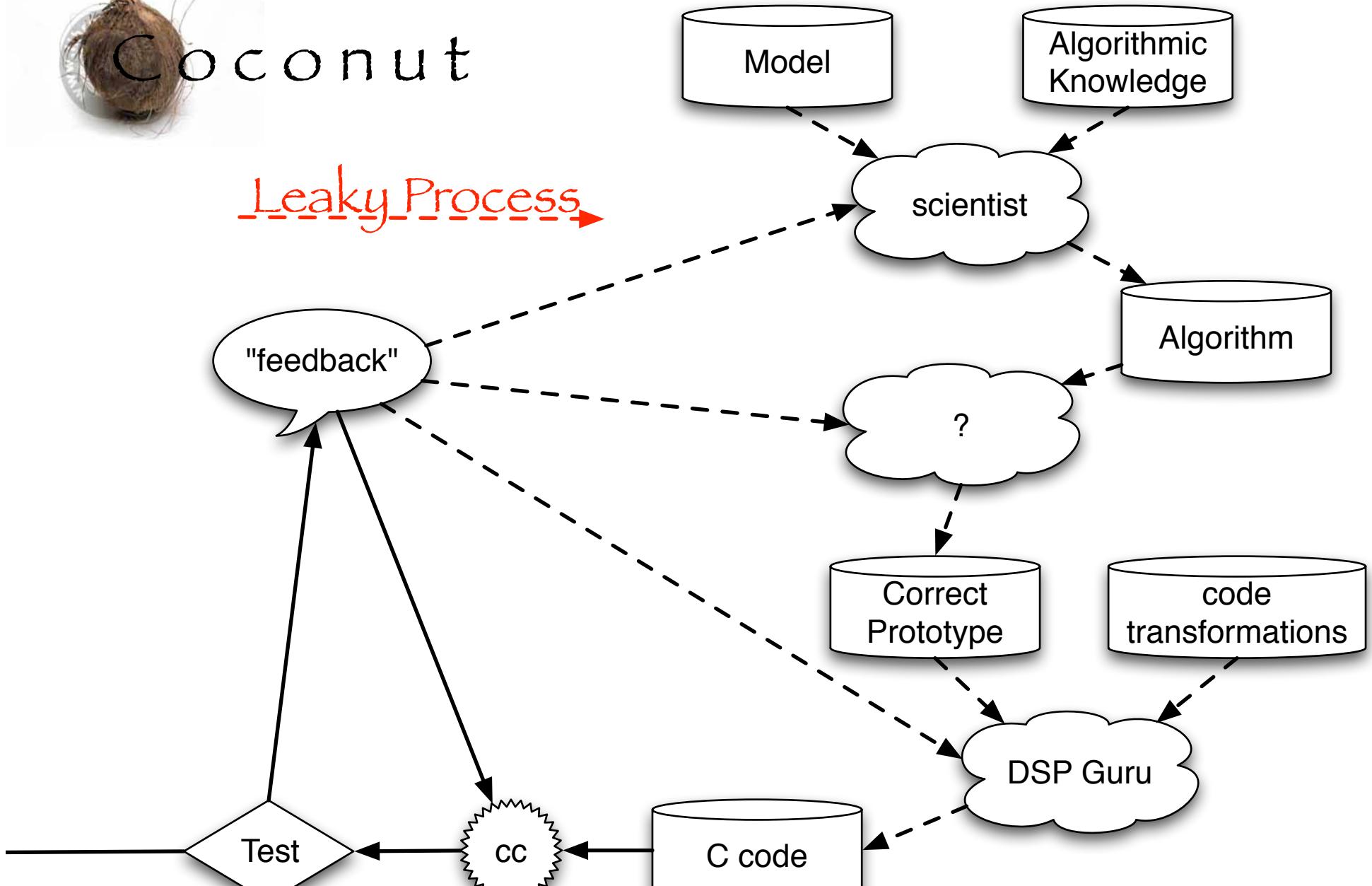
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Leaky_Process



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Plug leaks!



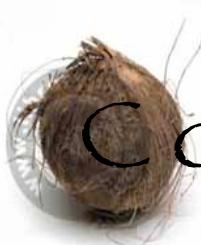
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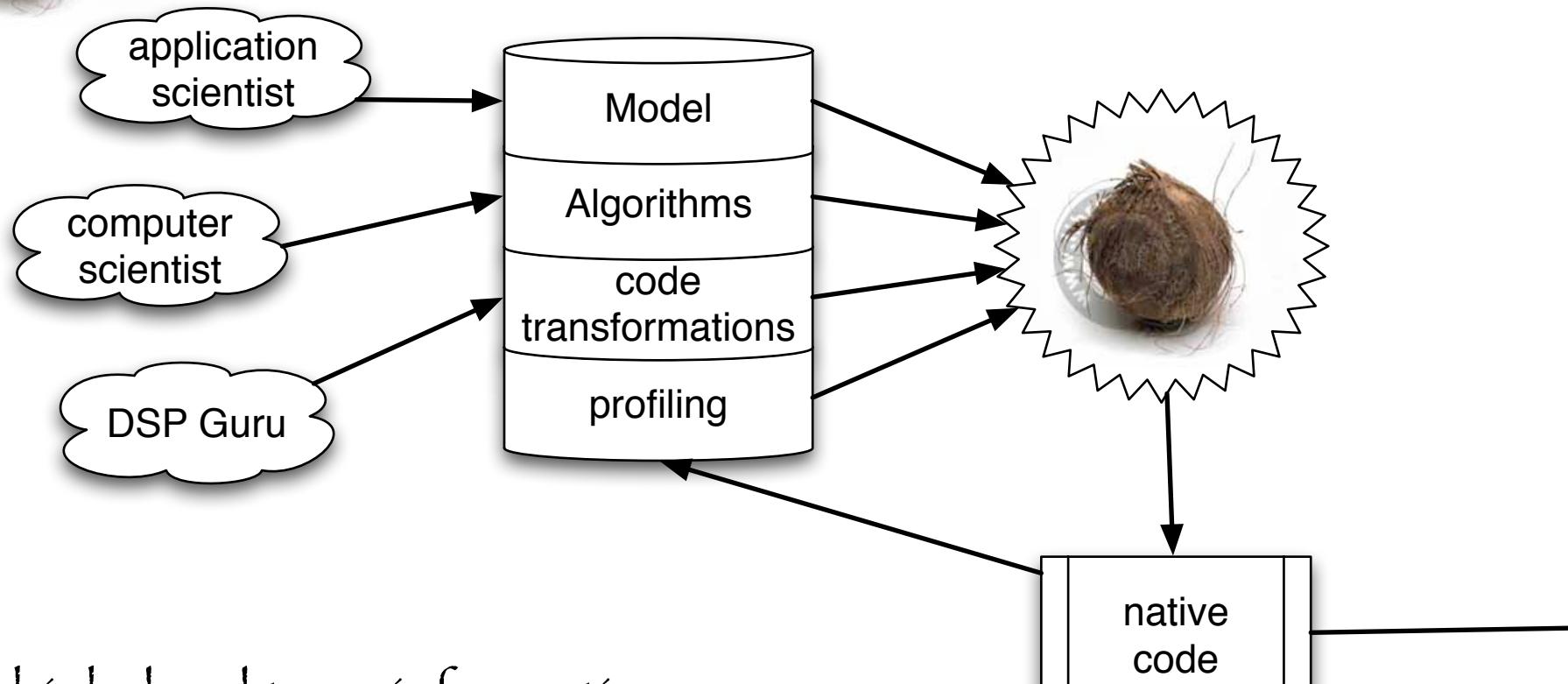
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no pipes \Rightarrow no leaks



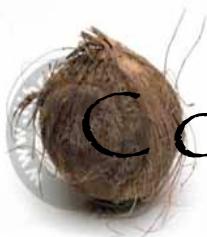
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- faster via
 - global data transformations
 - arrays of structs of arrays
 - alignment
 - virtual objects
 - leverage
 - SIMD (VMX)
 - cache hierarchy



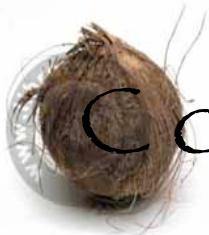
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- fast via
 - high-level code transformations
 - generic BLAS++
 - pipelining without cleanup
 - reason about precision
 - custom virtual machines
 - tricks !



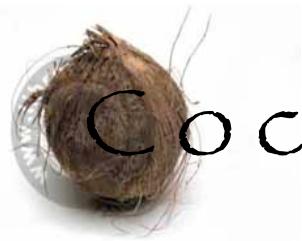
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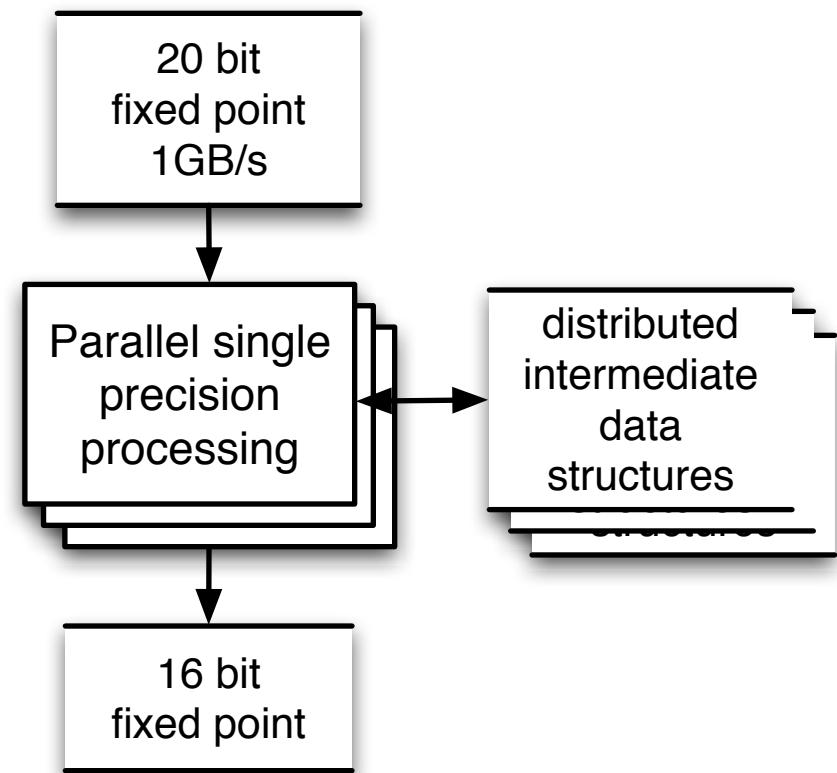
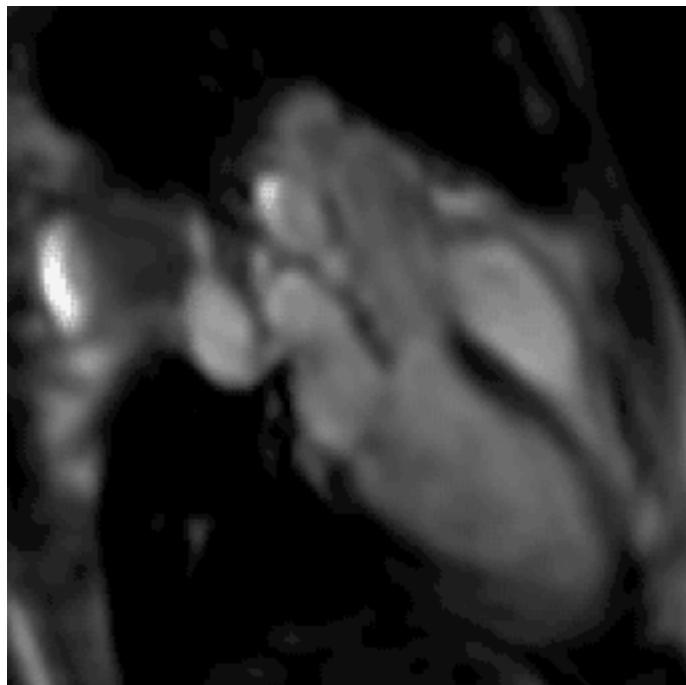
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Magnetic Resonance Imaging



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fast imaging \Rightarrow nonuniform Fourier Transform \Rightarrow

```
void vexpif(    float *thetas, int quarterSize, float *sines, float *cosines) {
    int index;
    for (index = 0; index < 4*quarterSize; index++) {
        sines[index] = sin(theta[index]);
        cosines[index] = cos(theta[index]);
    }
}
```

want to

- inline
 - eliminate storage for thetas
 - use VMX/Altivec
 - prefetch data
- } 12X acceleration



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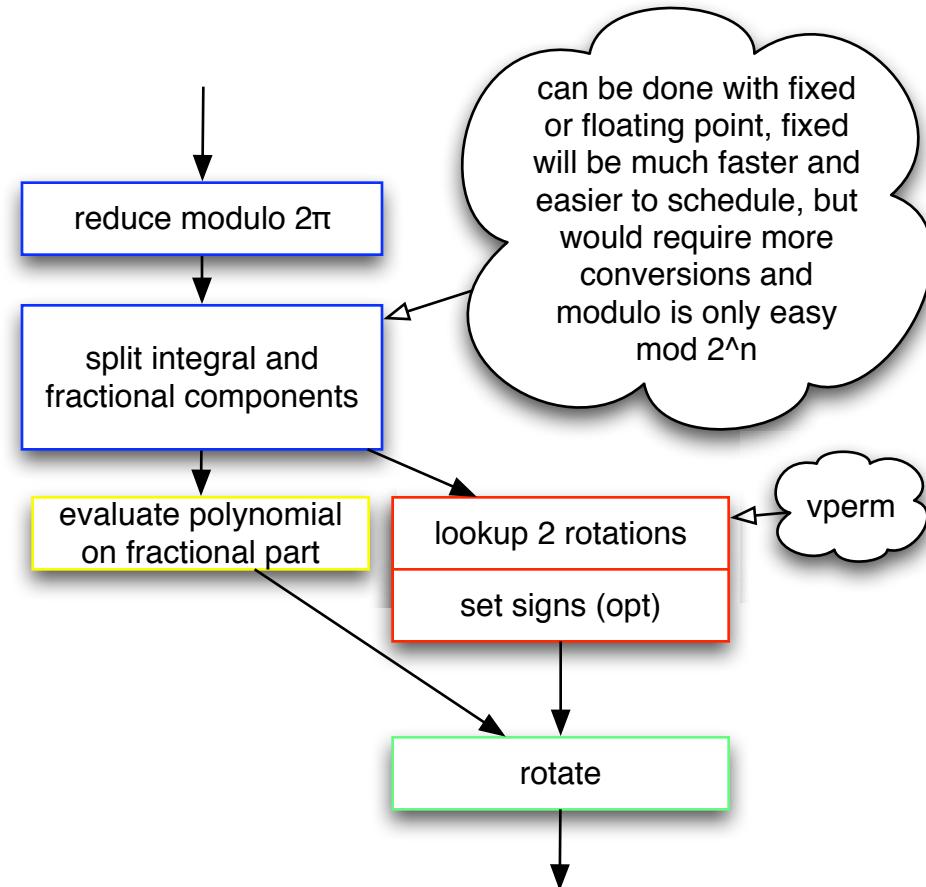
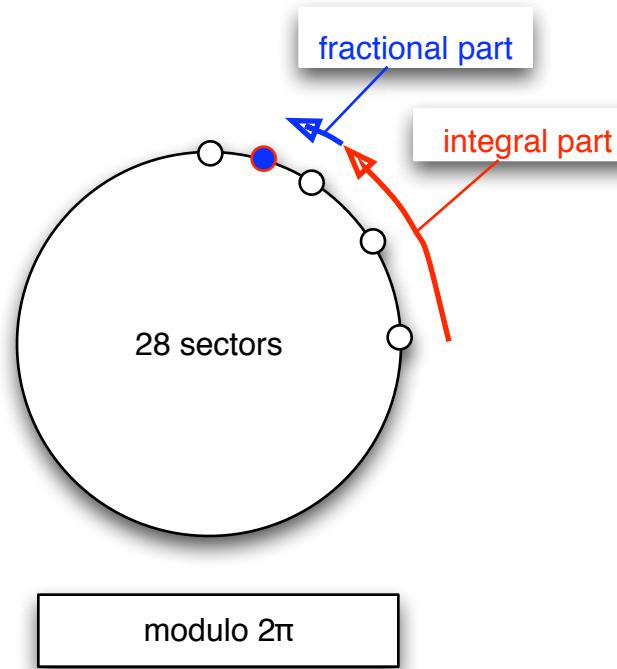
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```
static unsigned char staticcsinLookupLookup[] = {
    0*4,1*4,2*4,3*4,4*4,5*4,6*4,7*4,6*4,5*4,4*4,3*4,2*4,1*4, // positive lookups
    0*4,1*4+1,2*4+1,3*4+1,4*4+1,5*4+1,6*4+1,7*4+1,6*4+1,5*4+1,4*4+1,3*4+1,2*4+1,1*4+1, // negative lookups
    0,0,0,0 //unused
};

static unsigned char staticcosLookupLookup[] = {
    7*4,6*4,5*4,4*4,3*4,2*4,1*4,0*4,1*4+1,2*4+1,3*4+1,4*4+1,5*4+1,6*4+1,
    7*4+1,6*4+1,5*4+1,4*4+1,3*4+1,2*4+1,1*4+1,0*4,1*4,2*4,3*4,4*4,5*4,6*4,
    0,0,0,0 //unused
};

static unsigned char staticpartialSplat[] = {
    3,3,3,3,7,7,7,11,11,11,15,15,15
};

static unsigned int staticotherConstants[] = {
    0x3E22F983,//.1591549431, // oneOverTwoPi
    0x3C924925,//.1785714286e-1, // oneOver56
    0x40C90FDB,//6.283185308, // twoPi
    0x3E65C8F0,//.2243993266, // sin1

    0xBAF6999E,//-.1881409241e-2, // sin3
    0x3F800000//0.9999999996880272, // cos0
    0xBCCE4126,//-.2517754893e-1, // cos2
    0x38DD614C,//.1055622430e-3 // cos4

    0x41E00000,//28.
    0x00010203,//0..3
    0x0000001C,//28
    0x3E65C8FA,//2PiOver28
};
```



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```

for (count = quarterSize / refreshSize; count--;) {
    vec_dst(pInput,GetPrefetchConstant(8, 2 * refreshSize * 2 / (8), 8*16),0);
    for (subCount = refreshSize; subCount--;) {
        theta = vec_ld(0,pInput);
        vfp(theta);
        vOneOver56 = vec_splat(vOtherConstants1,1);
        vOneOver2Pi = vec_splat(vOtherConstants1,0);
        pInput++;
        theta = vec_madd(theta,vOneOver2Pi,vOneOver56);
        intPart = vec_floor(theta);
        v28f = vec_splat(vOtherConstants3,0);
        theta = vec_sub(theta,intPart); // got (theta/2Pi + 1/2/28) mod 1, offset by 1/2 a segment length
        theta = vec_madd(theta,v28f,vZero);
        intPart = vec_floor(theta);
        theta = vec_sub(theta,intPart);
        (vector unsigned int)temp = vec_splat_u32(1); // make .5f
        temp = vec_cif((vector unsigned int)temp,1);
        theta = vec_sub(theta,temp);
        (vector unsigned int)intPart = vec_ctu(intPart,0);
        v28 = vec_splat((vector unsigned int)vOtherConstants3,2);
        vOneToFour = vec_splat((vector unsigned int)vOtherConstants3_1);

asm("dcbz %0, %1" : : "0" (0), "b" (pCosines));
asm("dcbz %0, %1" : : "0" (0), "b" (pSines));

sinSign = vec_perm(vSinLookupLookup1,vSinLookupLookup2,(vector unsigned char)intPart); // now we have 0x000000PosSign
sinMap = vec_and(sinSign,(vector unsigned char)v28);
sinMap = vec_perm(sinMap,sinMap,vPartialSplat);
sinRot = vec_perm(lookup1,lookup2,sinMap);
vOne = vec_splat_u32(31);
(vector unsigned int)sinSign = vec_sl((vector unsigned int)sinSign,vOne);
sinRot = vec_or((vector float)sinSign,sinRot);

(cosigned char)cosSign = vec_perm(vCosLookupLookup1,vCosLookupLookup2,(vector unsigned char)intPart); // now we have 0x000000PosSign
cosMap = vec_and(cosSign,(vector unsigned char)v28);
cosMap = vec_perm(cosMap,cosMap,vPartialSplat);
cosMap = vec_add(cosMap,vOneToFour);
cosRot = vec_perm(lookup1,lookup2,cosMap);
(vector unsigned int)cosSign = vec_sl((vector unsigned int)cosSign,vOne);
cosRot = vec_or((vector float)cosSign,cosRot);

cos4 = vec_splat(vOtherConstants2,3);
cos2 = vec_splat(vOtherConstants2,2);
square = vec_madd(theta,theta,vZero);
cos = vec_madd(square,cos4,cos2);
cos0 = vec_splat(vOtherConstants2,1);
cos = vec_madd(square,cos,cos0);
sin1 = vec_splat(vOtherConstants1,3);
sin3 = vec_splat(vOtherConstants2,0);
sin = vec_madd(square,sin3,sin1);
sin = vec_madd(sin,theta,vZero);
cosOut = vec_madd(cos,cosRot,vZero);
sinOut = vec_madd(cos,sinRot,vZero);
cosOut = vec_nmadd(sin,sinRot,cosOut);
sinOut = vec_nmadd(sin,cosRot,sinOut);
vec_stl(cosOut,0,pCosines);
vec_stl(sinOut,0,pSines);
pCosines++;
pSines++;

}
}

```

now

- inline
- pipeline / unroll
- tune prefetch



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Design Patterns for Signal Processing

"in functional languages Design Patterns are executable"

- less programmer intervention = fewer errors
- type checking = almost as good as model checking
- provably correct implementations
- inheritance replaced by Haskell type classes



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Coconut Haskell

- functional: functions as first-class citizens
- pure: no side-effects
- non-strict: unneeded arguments may be undefined
 - implemented usually via lazy evaluation
 - enables separation of concerns, e.g., generate/prune
- strongly typed
- safe overloading (type classes)
- accessible for correctness proofs and program derivation
- compiled mostly by transformation
- large, active community; open definition and compilers



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Haskell

static typing
no side-effects } \Rightarrow verifiably correct code
by construction



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Domain-Specific Languages (DSLs) in Haskell

- Embedded DSLs
 - built from primitives and combinators defined in Haskell
 - compiled by Haskell compiler
- Wrapping DSLs
 - wrap other libraries via the foreign-function interface (FFI)
 - from immediate wrappers to high-level abstractions
- Arbitrary DSLs
 - represented by Haskell data structures
 - the compiler will be a special Haskell program
 - Haskell is an excellent language for writing compilers



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Domain Specific Language

inside Haskell \Rightarrow open, extensible



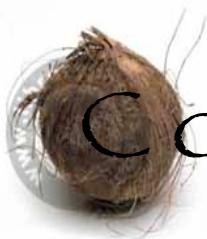
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High Level DSL
mathematical specification of
algorithms

Low Level DSL
high-performance, parallel vector,
target-specific implementation



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High level DSL

- containers (matrices, structures)
- precision
- approximation
- derivatives
- special functions
- polynomials
- linear programming
- Newton's method

80% grammar
Oct 2003



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Low level DSL

- includes High Level DSL
- cache hierarchy
- cache hinting
- instruction scheduling
- storage classes
- page sizes
- inter-processor messaging
- SIMD



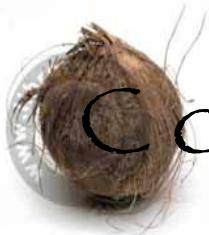
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Example: Interior Point Method for LP

key step: $A^* \text{diag}(x) \text{diag}(s)^{-1} A$

sparsity \notin BLAS

BLAS custom

$n \times m \times m \times m \times n$

$n \times m \times n$

cache s^{-1}



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