

# **Cruise Control**

# **Software Development Document**

## **V.0.5**

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“I pledge my honor that I have abided by the Stevens Honor System.”

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# 1. Executive Summary

This project is to develop a cruise control that is used to automatically maintain a car's speed without the user having their foot on the gas pedal. Cruise control is a feature offered in the majority of modern cars to provide user convenience specifically for long drives on highways. Some major features that are needed to make the cruise control work include turning the program on and off, a dashboard display of the speed of the car, buttons to increase and decrease the speed as necessary, and so on. Our goal is to successfully implement these major features with no chance of failure in order to increase the reliability of our cruise control software and enhance the overall performance of the cruise control system.

## 2. Introduction

### **High-Level Customer Need**

Cruise control is a highly sought after feature in vehicles that electronically interacts with the engine's management system to maintain its speed. Originally invented to save gas by reducing gas-wasting surges on the accelerator, cruise control provides an opportunity for the driver to rest their foot and safely adjust their positioning, while also helping to prevent speeding tickets on long roads and highways.

### **Major Features**

Our implementation of cruise control needs a number of standard features in order to work properly. The first major feature we need is to take input that will turn cruise control on and off. In addition, cruise control needs to be able to shut off when the user presses the brake and, when the car turns off, the entire program should stop running. We need another input that sets the speed that the cruise control will maintain. To see the speed that we are maintaining we will need a dashboard display of a speedometer that shows the current speed. Input to increase and decrease the set speed of the cruise control will also be implemented so the driver does not have to turn off cruise control and try to get the desired speed by pressing the gas. There will be a logging system that writes data to an excel spreadsheet as soon as cruise control is turned on. It will track any changes in the program such as when it turns on, being set, the current speed, and when it is turned off or deactivates. This will provide a better understanding of how the cruise control program is running and if there is a problem, it will be easier to understand where and why it occurred.

### **High-Level Reliability**

As the reliability of our implementation of cruise control is directly related to the safety of the passengers, it is crucial to develop highly reliable software to give the passengers a sense of security. Ultimately, our goal will be for our implementation to have a success rate of 99.99% for hardware and 99.999% for software of the cruise control. To achieve this goal, we have to make sure that all of the major features mentioned above, such as turning the cruise control on and off, and setting the speed the passenger wants to maintain the vehicle at, should work 99.99% of the time. With our agile development process, we will successfully implement all the features with a low probability of failure and test the reliability of our implementations via series of tests and experiments, to make sure that we have reached our goals.

## **High-Level Performance**

The cruise control system will have to have optimal performance while the car is in motion. Optimal performance means that the vehicle will reach the cruise control speed that is set by the driver as soon as possible. The cruise control will also have to maintain the speed that the driver decided to set by the cruise control button until the driver turns off the engine or turns off the cruise control option. It is important that once the cruise control is turned on, and the speed has been set, that the vehicle does not dip above nor below the speed. A fluctuation of the speed of the car is an indicator of a low-level performance, which should be avoided and be accounted for when implementing the cruise control system in the vehicle.

### 3. Requirements

#### **Functional Requirements**

##### Input (Requires user input to activate)

1. On an activate input, cruise control shall turn on and display that cruise control has been turned on.
2. On a cancel input, cruise control shall turn off completely and the cruise control display icon will turn off.
3. On a set speed input, cruise control shall maintain the speed of the car at the current speed shown on the speedometer.
4. On an increase speed input, cruise control shall increase the set speed by 1 mph.
5. On a decrease speed input, cruise control shall decrease the set speed by 1 mph.
6. On a brake input, cruise control shall turn off the set speed but the cruise control system is still activated.
7. When the car turns off, cruise control shall turn off completely.

##### Output (Functions that output without user)

1. Logging of car data shall begin within 1 second of the car turning on
2. When the vehicle shuts down, cruise control hardware shall perform a graceful automatic shutdown after 1 minute, as to not consume the car's battery electricity

#### **System Requirements**

1. The cruise control system shall have a sensor to detect the speed of the car.
2. The cruise control system shall log all changes of speed and operations during usage.
3. The cruise control shall perform an automatic shutdown after one minute to preserve battery if cruise control has been turned on, but a speed has not been set.

#### **Non-Functional Requirements**

##### Performance

1. The cruise control system shall activate within 100ms of an activation input.
2. The cruise control system shall turn off within 100ms of a cancel input.

3. The cruise control system shall turn off the set speed within 100ms of a brake input.

## Reliability

1. The cruise control system shall be able to activate 99.99% of the time.

## Availability

1. The cruise control system shall be ready to use without delay 99.99% of the time.
2. The cruise control system shall be ready for activation within 2 seconds after the car is turned on and the engine starts running.
3. The cruise control system shall only be activated when the car is driving at a minimum speed of 25 mph.

## Maintainability

1. The cruise control shall be able to maintain itself until the car becomes unable to move. If maintenance is needed, the cruise control unit shall be able to signal to the primary actor/driver whenever the system is unavailable.
2. The technician shall be able to view the logged data when necessary.

## Security

1. The cruise control unit shall not be connected to the internet, so it will not be vulnerable to cyber attacks. The only vulnerability it has is if there is a physical harm against the unit. If the cruise control system were to fall to an physical attack that caused any controls or sensors to malfunction outside optimal operation, the cruise control system would alert the driver and deny usage.

## Usage Scenarios

*Use case 1:* Usage of Cruise Control on a highway

*Primary actor:* The driver

*Goal in context:* Use cruise control to drive on a highway

*Precondition:* The car is in good condition, and the driver is trying to use cruise control  
in

an appropriate condition (on a highway, with a speed of over 25 mph)

*Trigger:* Driver decides to use cruise control on a highway

1. While on the highway, the driver powers on cruise control through the user interface.
2. Cruise control gives visual feedback to show that it has been activated.
3. The driver sets it to the speed that he wants, and visual feedback shows the current speed.
4. Cruise control requests values from sensors. Sensors provide approval to set cruise control at current speed, and cruise control requests the engine management system to set the speed at current position for desired speed.
5. The Engine Management System is set to the indicated speed, and is visually shown to the driver. The driver can adjust according to changes of surrounding environment, and the sensors shall provide feedback, resulting in changes of the speed of EMS too.
6. The driver increases and decreases set speed and the change is shown on the speedometer.
7. The driver is done using cruise control and hits cancel which turns the cruise control system off completely.

*Use case 2:* Usage of brake with cruise control engaged

*Primary actor:* The driver.

*Goal in context:* Cruise control shall disengage when brake is applied.

*Precondition:* The car is in good condition, and the driver has activated and engaged cruise control in an appropriate condition (on straight road, with a speed of over 25 mph)

*Trigger:* Driver must brake to avoid potential collision.

1. While using cruise control, the driver sets foot on the brake pedal.
2. Cruise control disengages to a neutral state of activation, no longer controlling the vehicles throttle.
3. Cruise control gives visual feedback to show that it has been disengaged.
4. The driver accelerates again to their desired speed and sets the cruise control speed. Cruise control requests values from sensors that provide approval to set cruise control at the current speed. Cruise control requests



the engine management system to set the speed at current position for desired speed and then displays visual feedback of the current speed.