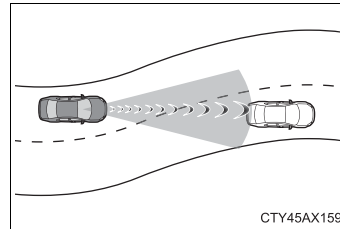


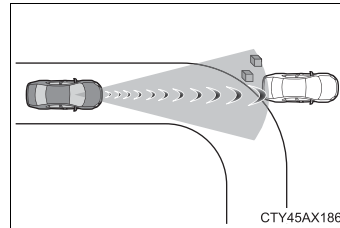
### ■ Conditions under which the system may operate even if there is no possibility of a collision

- In some situations such as the following, the system may determine that there is a possibility of a frontal collision and operate.

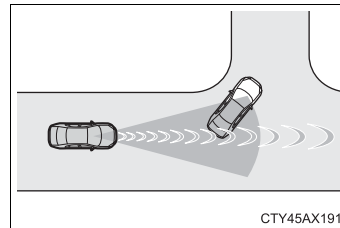
- When passing a detectable object, etc.
- When changing lanes while overtaking a detectable object, etc.
- When approaching a detectable object in an adjacent lane or on the roadside, such as when changing the course of travel or driving on a winding road



- When rapidly closing on a detectable object, etc.
- When approaching objects on the roadside, such as detectable objects, guardrails, utility poles, trees, or walls
- When there is a detectable object or other object by the roadside at the entrance of a curve



- When there are patterns or paint in front of your vehicle that may be mistaken for a detectable object
- When the front of your vehicle is hit by water, snow, dust, etc.
- When overtaking a detectable object that is changing lanes or making a right/left turn



- When passing a detectable object in an oncoming lane that is stopped to make a right/left turn

