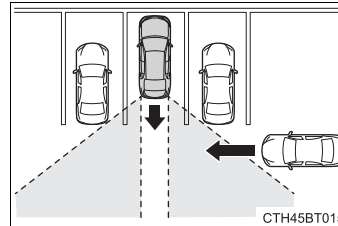


■ Conditions under which the system will not detect a vehicle

The RCTA function is not designed to detect the following types of vehicles and/or objects:

- Vehicles approaching from directly behind
- Vehicles backing up in the parking space next to your vehicle*
- Vehicles that the sensors cannot detect due to obstructions



- Guardrails, walls, signs, parked vehicles and similar stationary objects*
- Small motorcycles, bicycles, pedestrians, etc.*
- Vehicles moving away from your vehicle
- Vehicles approaching from the parking spaces next to your vehicle*
- The distance between the sensor and approaching vehicle gets too close

*: Depending on the conditions, detection of a vehicle and/or object may occur.