

#### ■ The Parking Support Brake function (rear-crossing vehicles) will operate when

The function will operate when the PKSB OFF indicator is not illuminated (→P. 361, 365) and all of the following conditions are met:

##### ● Engine output restriction control

- The Parking Support Brake is enabled.
- The vehicle speed is approximately 9 mph (15 km/h) or less.
- Vehicles which are approaching from the right or left at the rear of the vehicle at a traveling speed of approximately 5 mph (8 km/h) or more.
- The shift lever is in R.
- The system determines that a stronger than normal brake operation is necessary to avoid a collision with an approaching vehicle.

##### ● Brake control

- Engine output restriction control is operating.
- The system determines that an emergency brake operation is necessary to avoid a collision with an approaching vehicle.

#### ■ The Parking Support Brake function (rear-crossing vehicles) will stop operating when

The function will stop operating if any of the following conditions are met:

##### ● Engine output restriction control

- The Parking Support Brake is disabled.
- The collision becomes avoidable with normal brake operation.
- A vehicle is no longer approaching from the right or left at the rear of the vehicle.

##### ● Brake control

- The Parking Support Brake is disabled.
- Approximately 2 seconds elapse after the vehicle is stopped by brake control.
- The brake pedal is depressed after the vehicle is stopped by brake control.
- A vehicle is no longer approaching from the right or left at the rear of the vehicle.

#### ■ Detection area of the Parking Support Brake function (rear-crossing vehicles)

The detection area of the Parking Support Brake function (rear-crossing vehicles) differs from the detection area of the RCTA function (→P. 345).

Therefore, even if the RCTA function detects a vehicle and provides an alert, the Parking Support Brake function (rear-crossing vehicles) may not start operating.

#### ■ Situations in which the system may not operate properly

→P. 351

#### ■ Situations in which the system may operate even if there is no possibility of a collision

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