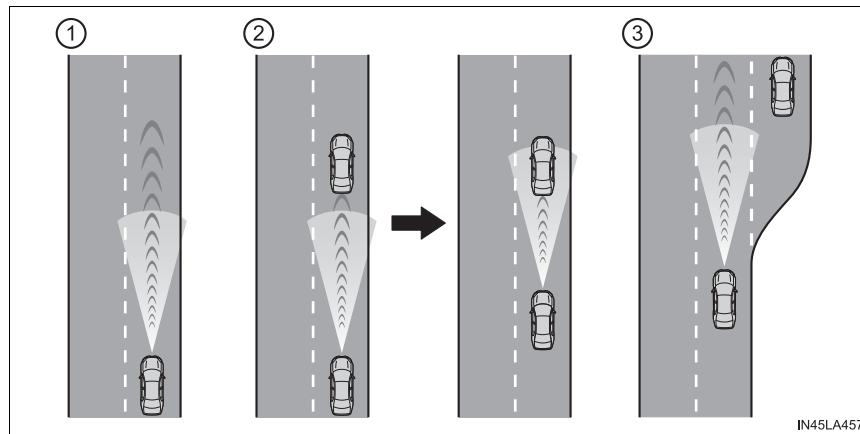


Driving in vehicle-to-vehicle distance control mode

This mode employs a radar to detect the presence of vehicles up to approximately 328 ft. (100 m) ahead, determines the current vehicle-to-vehicle following distance, and operates to maintain a suitable following distance from the vehicle ahead. The desired vehicle-to-vehicle distance can also be set by operating the vehicle-to-vehicle distance switch.

When driving on downhill slopes, the vehicle-to-vehicle distance may become shorter.



① Example of constant speed cruising

When there are no vehicles ahead

The vehicle travels at the speed set by the driver.