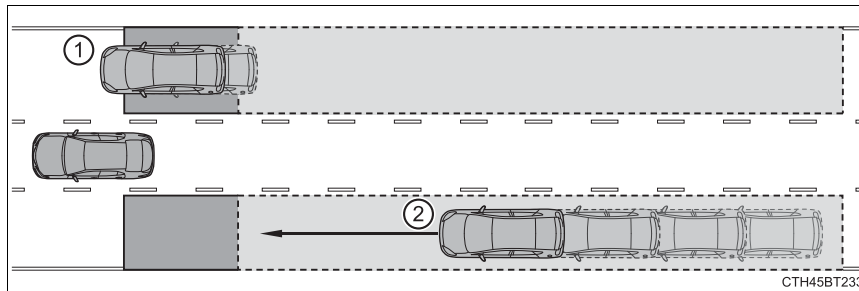


BSM function

The BSM function uses radar sensors to detect the following vehicles traveling in an adjacent lane in the area that is usually not reflected in the outside rear view mirror (the blind spot), and advises the driver of the presence of such vehicles via the indicators on the outside rear view mirrors.



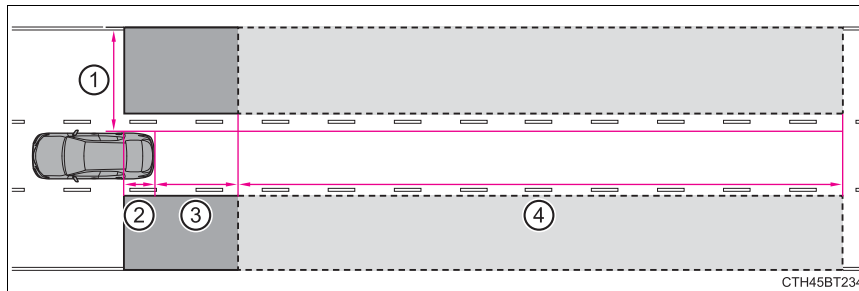
- ① Vehicles that are traveling in areas that are not visible using the outside rear view mirrors (the blind spots)
- ② Vehicles that are approaching rapidly from behind in areas that are not visible using the outside rear view mirrors (the blind spots)

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Driving

BSM function detection areas

The areas that vehicles can be detected in are outlined below.



The range of the detection area extends to:

- ① Approximately 1.6 ft. (0.5 m) to 11.5 ft. (3.5 m) from either side of the vehicle
The area between the side of the vehicle and 1.6 ft. (0.5 m) from the side of the vehicle cannot be detected
- ② Approximately 3.3 ft. (1 m) forward of the rear bumper
- ③ Approximately 9.8 ft. (3 m) from the rear bumper