

By Definition

## Dynamics

$$\underbrace{\begin{bmatrix} \mathbf{H} & -\mathbf{J}_c^\top \\ -\mathbf{J}_c & 0 \end{bmatrix}}_{\mathbf{K}} \underbrace{\begin{bmatrix} \ddot{\mathbf{q}} \\ \lambda \end{bmatrix}}_{\boldsymbol{\nu}} = \underbrace{\begin{bmatrix} \mathbf{S}^\top \boldsymbol{\tau} - \mathbf{h} \\ \mathbf{J}_c \dot{\mathbf{q}} \end{bmatrix}}_{\boldsymbol{\Psi}}$$

$$\boldsymbol{\nu} = \mathbf{K}^{-1} \boldsymbol{\Psi}$$

$$\begin{aligned} \mathbf{H} \ddot{\mathbf{q}} + \mathbf{h}(\mathbf{q}, \dot{\mathbf{q}}) - \mathbf{J}_c^\top \lambda &= \mathbf{S}^\top \boldsymbol{\tau} \\ \mathbf{J}_c \ddot{\mathbf{q}} + \dot{\mathbf{J}}_c \dot{\mathbf{q}} &= 0 \end{aligned}$$

## EMRNEA ( $\mathbf{q}, \dot{\mathbf{q}}, \ddot{\mathbf{q}}, \mathbf{a}_g, \mu, \lambda$ )

$$\begin{bmatrix} \mu^\top \boldsymbol{\tau} \\ \mathbf{v} \\ \mathbf{a} \end{bmatrix} = \begin{bmatrix} \mu^\top [\mathbf{H}(\mathbf{q}) \ddot{\mathbf{q}} + \mathbf{h}(\mathbf{q}, \dot{\mathbf{q}}) - \mathbf{J}_c^\top \lambda] \\ \mathbf{J}_c \dot{\mathbf{q}} \\ \dot{\mathbf{J}}_c \dot{\mathbf{q}} + \mathbf{J}_c \ddot{\mathbf{q}} \end{bmatrix}$$

where  $\mu$  is any vector

## Conventional iLQR

AD tools once:  $\frac{\partial \nu}{\partial \mathbf{q}} \quad \mathcal{O}(n^2)$

## Conventional DDP

AD tools twice:  $\frac{\partial^2 \nu}{\partial^2 \mathbf{q}} \quad \mathcal{O}(n^3)$   
 $\xi^\top \frac{\partial^2 \nu}{\partial^2 \mathbf{q}} \quad \mathcal{O}(n^3)$

## EMRNEA DDP

With  $\xi^\top = \gamma^\top \mathbf{K}^{-1}$

$$[\mathbf{T}_1 \ \mathbf{V}_1 \ \mathbf{A}_1]^\top = \text{EMRNEA}(\mathbf{q}, \dot{\mathbf{q}}, \ddot{\mathbf{q}}, \mathbf{a}_g, \xi_1, \lambda) \quad \mathcal{O}(n)$$

$$[\mathbf{T}_2 \ \mathbf{V}_2 \ \mathbf{A}_2]^\top = \text{EMRNEA}\left(\mathbf{q} * 0, \dot{\mathbf{q}} * 0, \frac{\partial \dot{\mathbf{q}}}{\partial \mathbf{q}}, \mathbf{a}_g * 0, \xi_1, \frac{\partial \lambda}{\partial \mathbf{q}}\right) \quad \mathcal{O}(n)$$

$$[\mathbf{T}_3 \ \mathbf{V}_3 \ \mathbf{A}_3]^\top = \text{EMRNEA}(\mathbf{q}, \dot{\mathbf{q}}, \ddot{\mathbf{q}}, \mathbf{a}_g, \xi_2, \lambda) \quad \mathcal{O}(n)$$

$$[\mathbf{T}_4 \ \mathbf{V}_4 \ \mathbf{A}_4]^\top = \text{EMRNEA}\left(\mathbf{q} * 0, \dot{\mathbf{q}} * 0, \frac{\partial \dot{\mathbf{q}}}{\partial \mathbf{q}}, \mathbf{a}_g * 0, \xi_2, \frac{\partial \lambda}{\partial \mathbf{q}}\right) \quad \mathcal{O}(n)$$

$$\begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix}^\top \frac{\partial^2 \nu}{\partial^2 \mathbf{q}} = \begin{bmatrix} \gamma_1^\top \\ \gamma_2^\top \end{bmatrix} \frac{\partial^2 \ddot{\mathbf{q}}}{\partial \mathbf{q} \partial \mathbf{q}} = \frac{\partial^2 \mathbf{T}_1}{\partial^2 \mathbf{q}} - \frac{\partial^2 \mathbf{T}_2}{\partial^2 \mathbf{q}} \quad \mathcal{O}(n^2)$$

$$\begin{bmatrix} \xi_1 \\ \xi_2 \end{bmatrix}^\top \frac{\partial^2 \nu}{\partial^2 \mathbf{q}} = \begin{bmatrix} \gamma_1^\top \\ \gamma_2^\top \end{bmatrix} \frac{\partial^2 \lambda}{\partial \mathbf{q} \partial \mathbf{q}} = \frac{\partial^2 \mathbf{A}_3}{\partial^2 \mathbf{q}} + \frac{\partial \mathbf{A}_4}{\partial \mathbf{q}} \quad \mathcal{O}(n^2)$$