Babylonian Square Roots

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THE ALGORITHM

- Divide-and-Average algorithm
- Very accurate after a few iterations
- Large numbers (~ I I digits) can be calculated within accuracy using less than 25 iterations

 - The COBOL program has a timeout of 1000 iterations, which is somewhat extreme.

WHAT IS IT?

- In order to take N's square root, we first make an initial guess, R_0 , on what it is. In the COBOL program, it takes the original number N and divides it by 2, which—when generalized to all numbers—is actually a pretty good guess.
- In order to cycle through a single iteration, we take the initial guess— R_0 —and average it with N/R_0 —which is the original number divided by this initial guess.

•
$$R_1 = \frac{R_0 + \frac{N}{R_0}}{2} =$$

•
$$Guess = \frac{PreviousGuess + \frac{OriginalNumber}{PreviousGuess}}{2}$$

WHAT IS IT?

• As stated earlier, this algorithm's family is divide-and-average—as such—it is nearly logarithmic. One could create a naïve-but-easy implementation of this algorithm (using 100 as the radicand) as follows:

```
OriginalNumber \leftarrow 100
Guess \leftarrow OriginalNumber / 2

for i \leftarrow 0 to 1000 do
Guess \leftarrow (Guess + (OriginalNumber / Guess)) / 2
```

WHAT IS IT?

• This algorithm's naïveté comes from the knowledge that large numbers rarely need more than 25 iterations, so we can forego verifying precision by just iterating 1000 times. That being said—1000 iterations is still fast—and the TAs probably wouldn't notice.

```
OriginalNumber \leftarrow 100
Guess \leftarrow OriginalNumber / 2

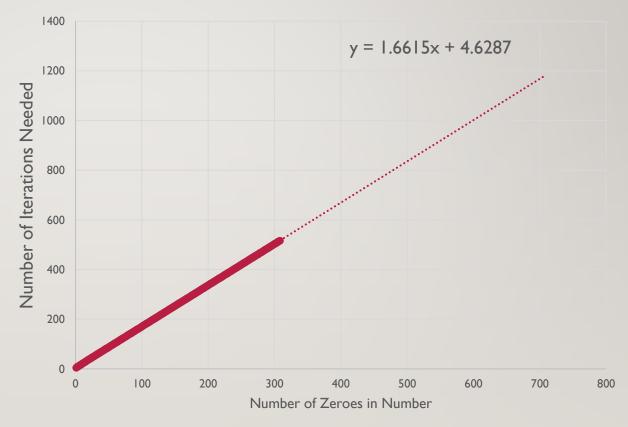
for i \leftarrow 0 to 1000 do
Guess \leftarrow (Guess + (OriginalNumber / Guess)) / 2
```

OWO *NOTICES ITERATION COUNT*

You would need a 600-digit number in order to require 1000 iterations (assuming a 0.000001 epsilon value on absolute error $(|R_0 - R_1|)$).

Data based on C program

Number Size vs. Number of Babylon Iterations Needed



LOOKING BACK

• Notice in our pseudocode, we don't use PreviousGuess as shown in the equation:

$$Guess = \frac{PreviousGuess + \frac{OriginalNumber}{PreviousGuess}}{2}$$

• We don't actually need PreviousNumber for the core of the algorithm to work—it is useful for if you want to look back a guess though. Up next is the implementation in C, but a non-naïve approach that does use the two variables. You'll see why it's needed.

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
    do {
        previous guess = guess;
        guess = (previous guess + (N / previous guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return quess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
    return 0;
```

This is our precision constant.

Every time a new guess is made, it is subtracted from the old guess and compared with the epsilon to check for "doneness". If it exceeds this, we do it again. This continues until the difference between guesses is smaller than it.

That was absolute precision. An alternative—relative precision—is where you check for the same constant, but with the *ratio* of the numbers—not the difference.

```
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#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
    do {
        previous guess = guess;
        guess = (previous_guess + (N / previous_guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return guess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
    return 0;
```

This is our Babylon function.

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
    do {
        previous guess = guess;
        guess = (previous_guess + (N / previous_guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return quess;
int main(void)
                                                                              It is called here.
    printf("%f\n", babylon(9458151235.0));
    return 0;
```

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
   do {
        previous guess = guess;
        guess = (previous_guess + (N / previous_guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return guess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
   return 0;
```

Let us dance...?

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
    do {
        previous guess = guess;
        guess = (previous guess + (N / previous guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return quess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
   return 0;
```

Like earlier, we have two variables.

- guess is our latest guess. As
 of this point in the code, it is
 simply half the original number.
- previous_guess is the previous guess, but it doesn't exist yet, so it's uninitialized.

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
    do {
        previous guess = guess;
        guess = (previous guess + (N / previous guess)) / 2.0;
     while (fabs(guess - previous guess) > precision);
    return quess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
    return 0;
```

I was going to make a while loop, but the comparison check between guess and previous_guess is only possible after the latter is set.

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
    do
        previous guess = guess;
        guess = (previous guess + (N / previous guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return quess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
    return 0;
```

First, we set the previous_guess to be the current guess. It isn't logical I know, but give me a sec!

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon (double N)
    double guess = N / 2.0;
    double previous guess;
   do {
        previous guess = guess;
        guess = (previous guess + (N / previous guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return quess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
   return 0;
```

Then we do the calculation. Now. our naïve example where we used only guess still holds here previous guess is always going to be equal to guess in this step. This is actually a disguised guess = (guess + (N /quess)) / 2.0. It's just that after this step, we now have a record of our new guess, while having a record of our old guess. After quess is set, previous guess still holds the before value.

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon (double N)
    double guess = N / 2.0;
    double previous guess;
   do {
        previous guess = guess;
        guess = (previous_guess + (N / previous_guess))/ 2,
     while (fabs(guess - previous guess) > precision);
    return quess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
   return 0;
```

We do this to compare the guesses. Now instead of doing it naively 1000 times, we are now checking the absolute error (difference) to see if we need to re-enter the loop or not. The math.h library is used for absolute value, and we are comparing it with precision from earlier.

```
#include <stdio.h>
#include <math.h>
#define precision 0.000001
double babylon(double N)
    double guess = N / 2.0;
    double previous guess;
    do {
        previous guess = guess;
        guess = (previous_guess + (N / previous_guess)) / 2.0;
    } while (fabs(guess - previous guess) > precision);
    return guess;
int main(void)
    printf("%f\n", babylon(9458151235.0));
    return 0;
```

Because guess is the most recent iteration's value, we return it.

