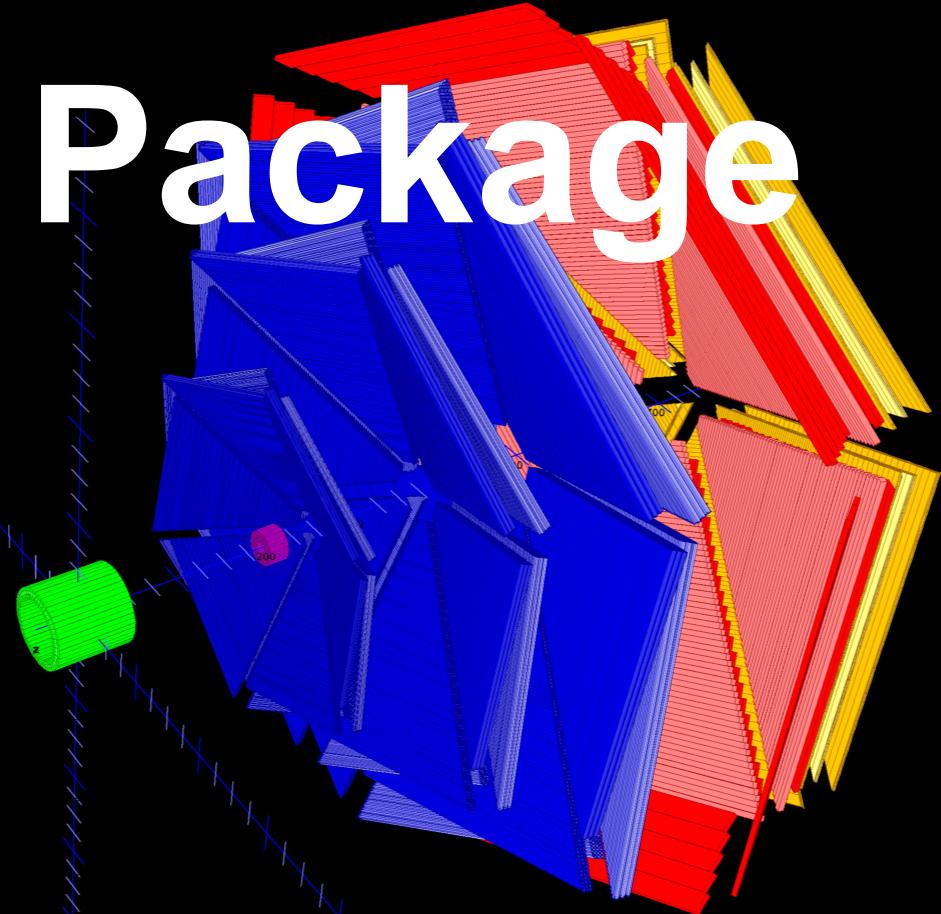


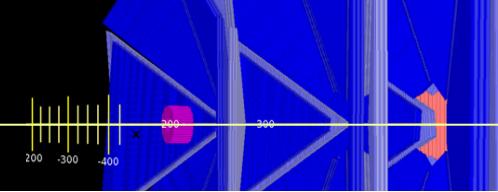
Geometry Package

Jeremiah Hankins

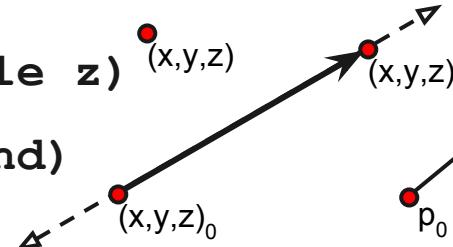
California State University Dominguez Hills



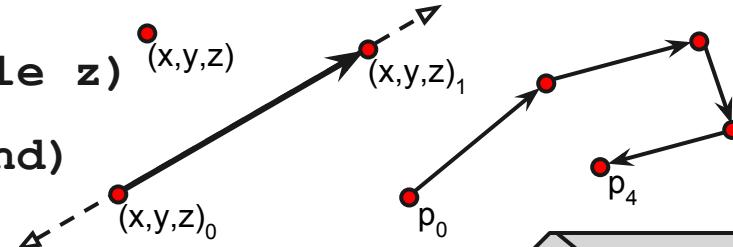
Primitives: Basic Types



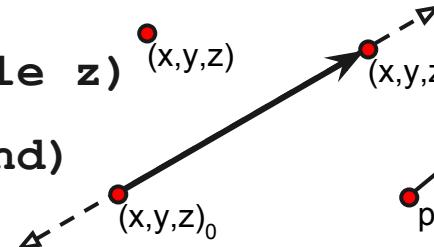
`Point3D(double x, double y, double z)`



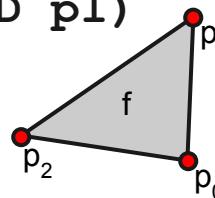
`Line3D(Point3D origin, Point3D end)`



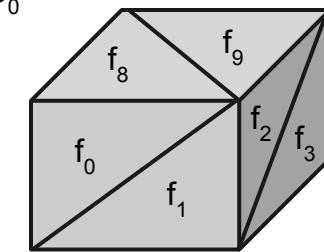
`Path3D(Point3D... points)`



`Face3D(Point3D p0, Point3D p1, Point3D p1)`

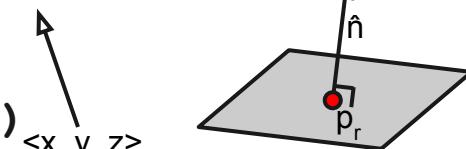


`Shape3D(Face3D... faces)`

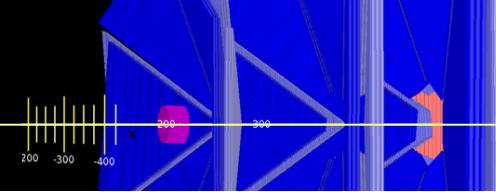


`Vector3D(double x, double y, double z)`

`Plane3D(Point3D reference, Vector3D normal)`



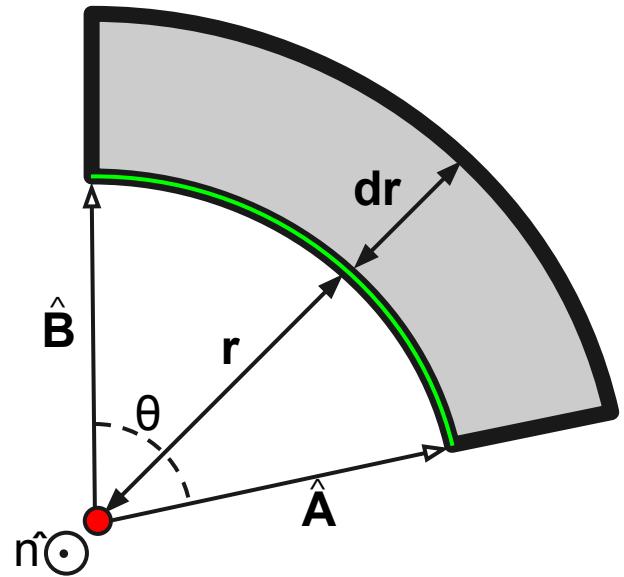
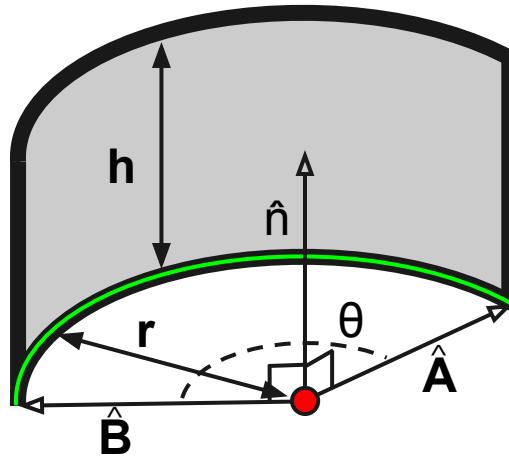
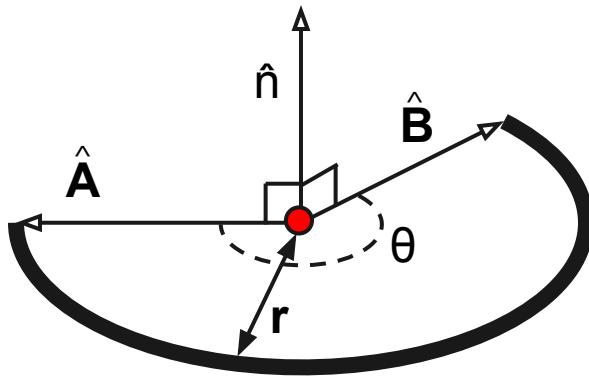
Primitives: Arcs



`Arc3D (Point3D center, Vector3D A, Vector3D B, double r)`

`Cylindrical3D (Arc3D base, double h)`

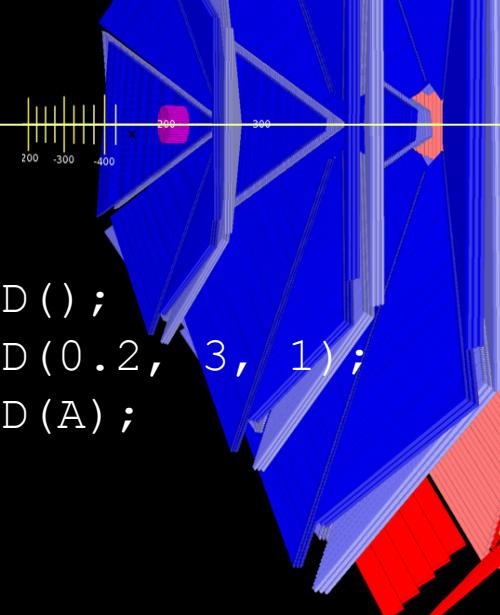
`Sector3D (Arc3D innerArc, double dr)`



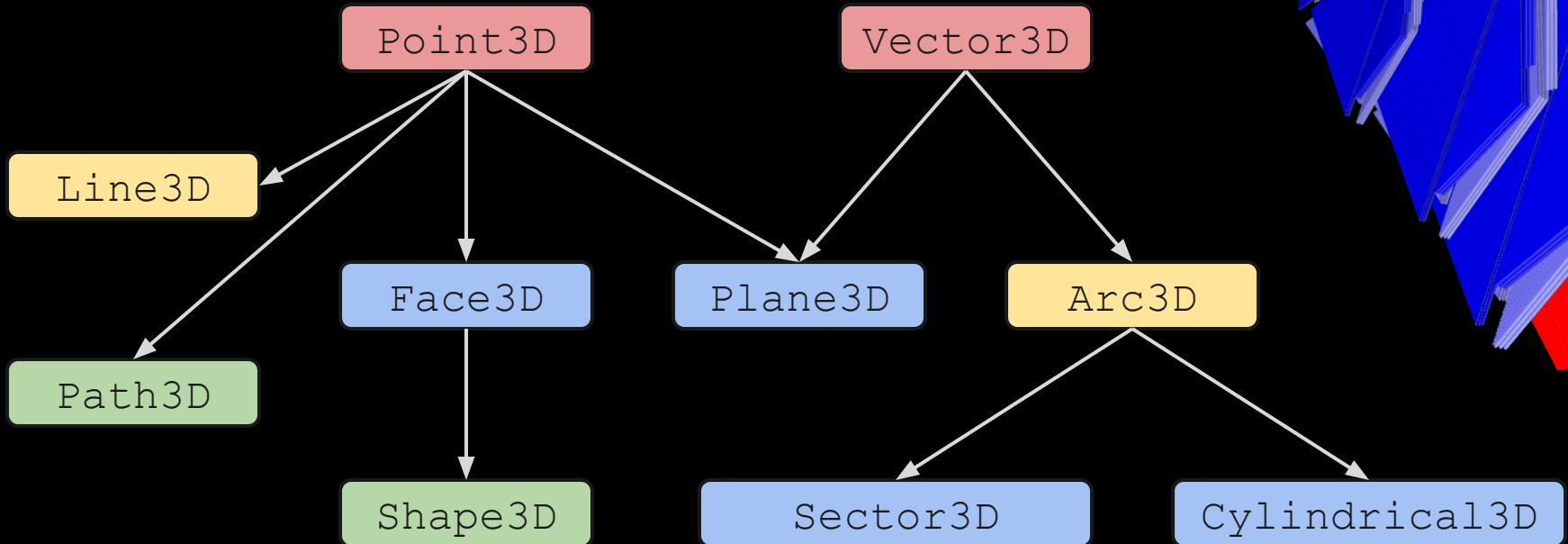
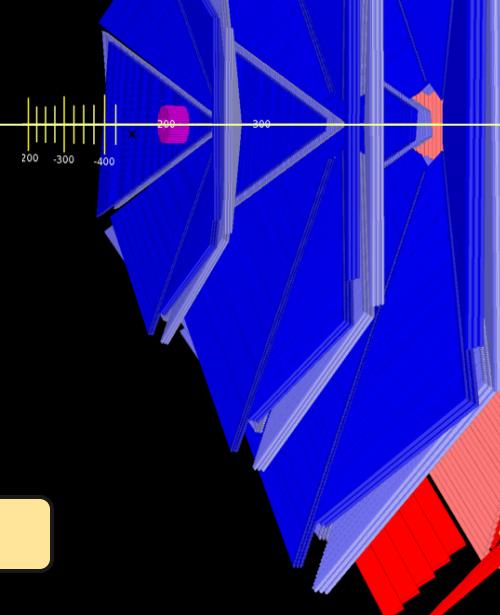
Primitives: Basic Types

All Primitives Have:

- Empty Constructors
 - Explicit Constructors
 - Copy Constructors
 - Copy Methods
 - Setters
 - Copies Arguments
 - Getters
 - Returns Original
 - Translations
 - Rotations (clockwise)
 - Show & `toString()`
- ```
Point3D A = new Point3D();
Point3D B = new Point3D(0.2, 3, 1);
Point3D C = new Point3D(A);
A.copy(B);

Line3D line = new Line3D();
line.setEnd(A);
A.set(0, 0, 0); // line isn't modified
B = line.end();
B.set(0, 0, 0); // line is modified
C.translateXYZ(0.1, 3, -100);
C.rotateX(Math.toRadians(15));
C.show(); System.out.println(C);
```
- 

# Primitives: Hierarchy



Fundamental

Derived

Surface

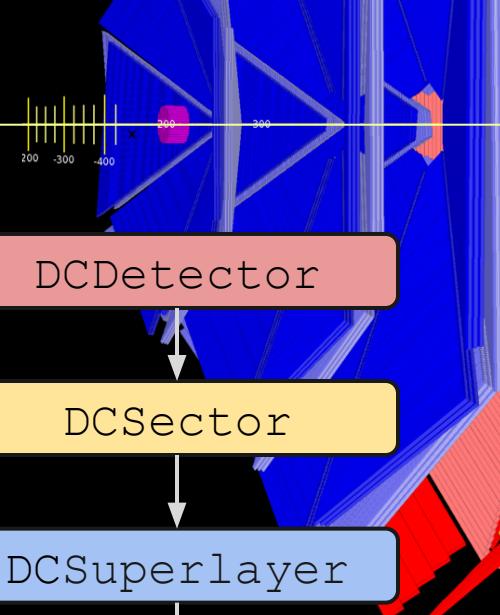
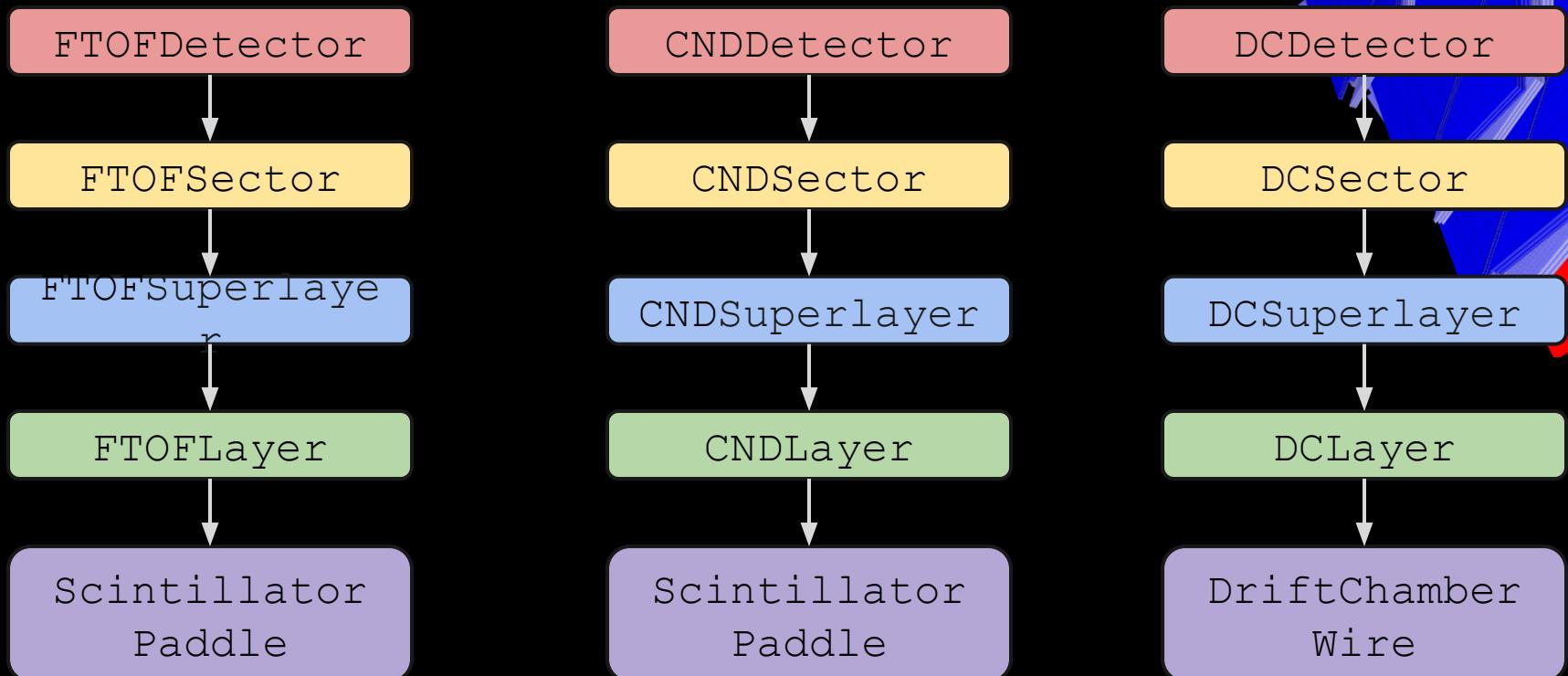
Container

# Detector: Hierarchy

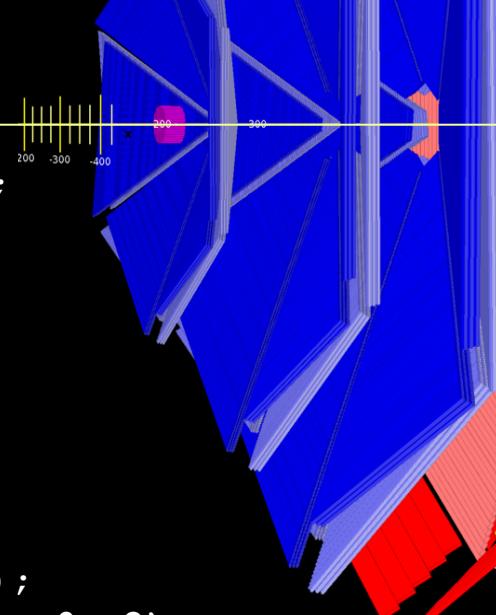


|            |                                                               |                                                                                                           |
|------------|---------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------|
| Detector   | DetectorId getDetectorId()<br>String getType()<br>void show() | int getNumSectors()<br>Sector getSector(int sectorId)<br>List<Sector> getAllSectors()                     |
| Sector     | int getSectorId()<br>String getType()<br>void show()          | int getNumSuperlayers()<br>Superlayer getSuperlayer(int superlayerId)<br>List<Superlayer> getAllSectors() |
| Superlayer | int getSuperlayerId()<br>String getType()<br>void show()      | int getNumLayers()<br>Sector getLayer(int layerId)<br>List<Layer> getAllLayers()                          |
| Layer      | int getLayerId()<br>String getType()<br>void show()           | int getNumComponents()<br>Component getSector(int componentId)<br>List<Component> getAllComponents()      |
| Component  | int getComponentId()<br>String getType()<br>void show()       | Point3D getMidpoint()<br>double getLength()                                                               |

# Detector: Hierarchy



# Detector: Factories



```
ConstantProvider constants = DataBaseLoader.getConstantsEC();

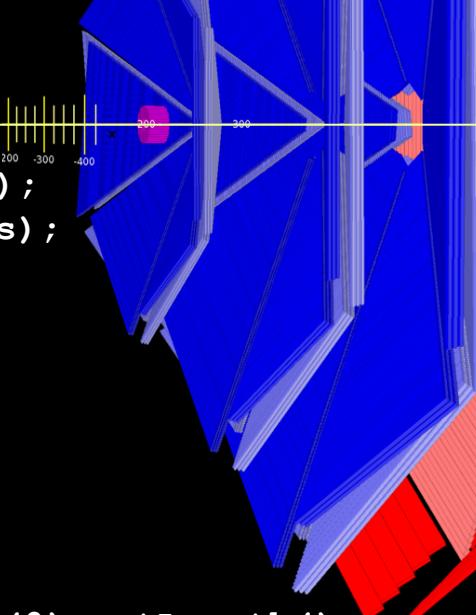
ECDetector detector;
detector = new ECFactory().createDetectorCLAS(constants);
detector = new ECFactory().createDetectorSector(constants);
detector = new ECFactory().createDetectorTilted(constants);
detector = new ECFactory().createDetectorLocal(constants);

// Constructed in "local" coordinates (varies by detector)
ECSector firstSector = factory.createSector(constants, 0);
ECSuperlayer outerEC = factory.createSuperlayer(constants, 0, 2);
ECLayer wLayer = factory.createLayer(constants, 0, 2, 2);

// Factories have no member variables or initialization procedure.
// It is acceptable to instantiate a new factory every time one is needed.

// However some detectors DO have non-negligible initialization procedures.
// For example, the BST has 33,792(!) wires, the end points of which are
// calculated using 67,584 line-plane intersections. This takes ~0.5 seconds.
```

# Detector: Example Usage



```
ConstantProvider dcConstants = DataBaseLoader.getConstantsDC();
DCDetector dc = new DCFactory().createDetectorCLAS(dcConstants);

DCSector sector = dc.getSector(0);
DCSuperlayer superlayer = sector.getSuperlayer(5);
DCLayer layer = superlayer.getLayer(5);
DriftChamberWire wire = layer.getComponent(12);
Point3D wireStart = wire.getLine().origin();

double length =
 dc.getSector(0).getSuperlayer(0).getLayer(0).getComponent(0).getLength();

int numSectors = dc.getNumSectors();

List<Point3D> midPoints = new ArrayList();
for (DCSector sector : dc.getAllSectors())
 for (DCSuperlayer superlayer : sector.getAllSuperlayers())
 for (DCLayer layer : sup.getAllLayers())
 for (DriftChamberWire wire : layer.getAllComponents())
 midPoints.add(wire.getMidpoint());
```

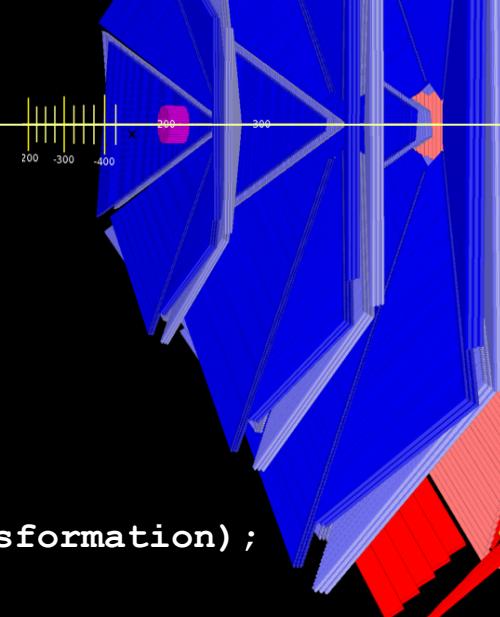
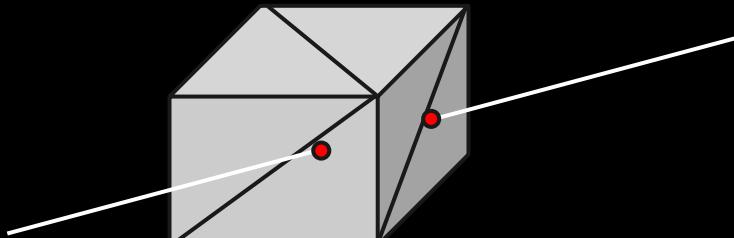
# Detector: Components

```
public interface Component extends Transformable {
 int getComponentId();

 int getNumVolumePoints();
 Point3D getVolumePoint(int p);
 int getNumVolumeEdges();
 Line3D getVolumeEdge(int e);
 Shape3D getVolumeShape();
 List<Line3D> getVolumeCrossSection(Transformation3D transformation);
 boolean getVolumeIntersection(Line3D line,
 Point3D intersect1,
 Point3D intersect2);

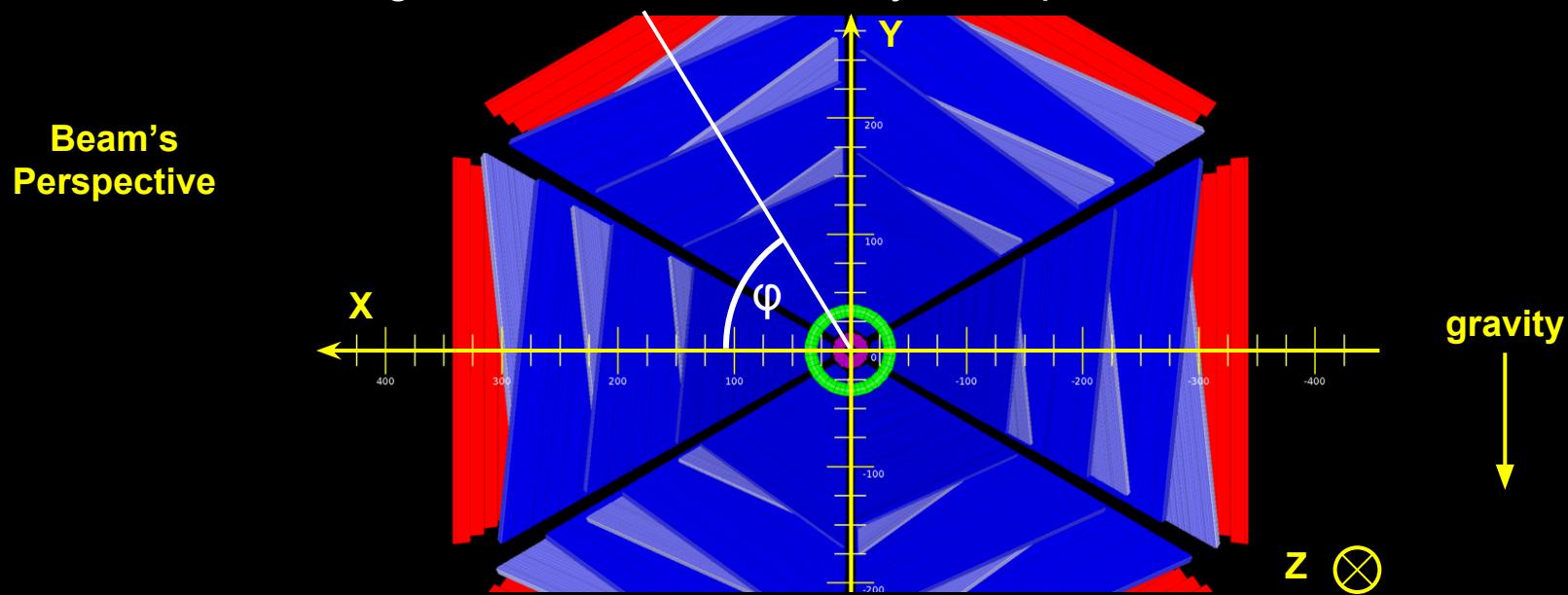
 Point3D getMidpoint();
 double getLength();

 String getType();
 void show();
}
```



# Coordinates: CLAS

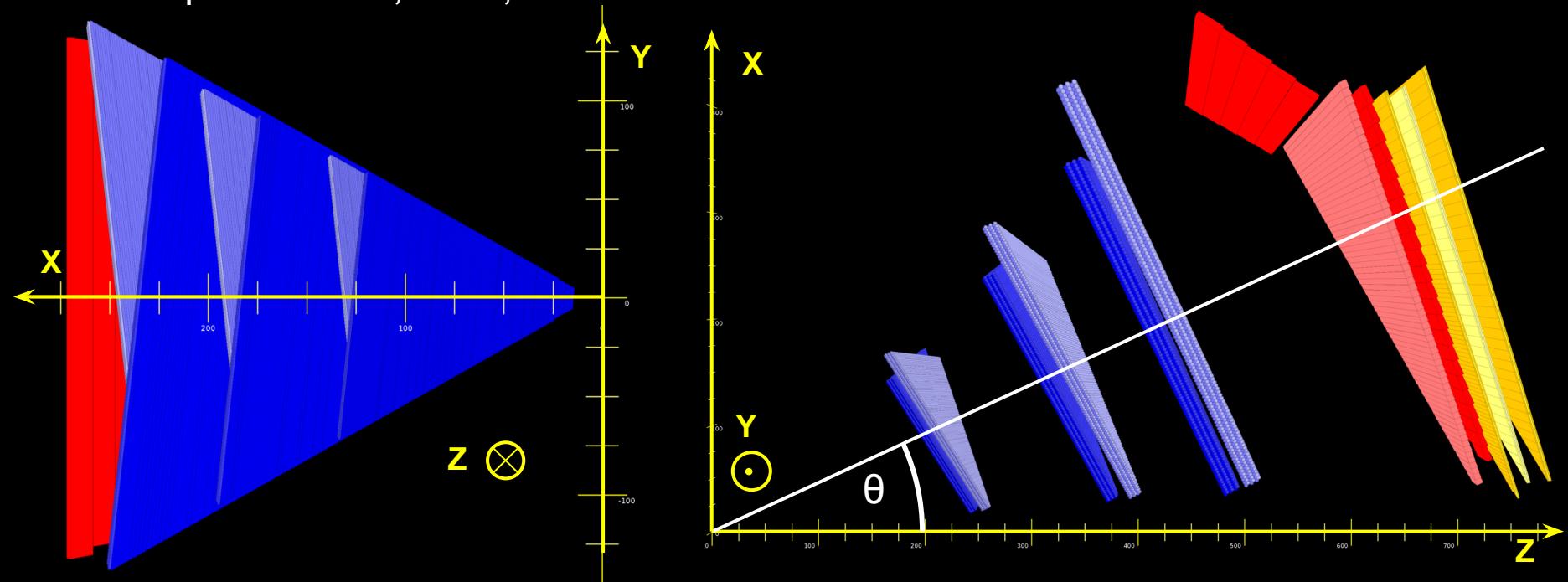
- Detectors created in CLAS coordinates are in their final nominal positions
- z-axis: parallel to the beam, positive direction is down beam
- y-axis: anti-parallel to gravity, positive direction is “up”
- x-axis: forms a right-handed coordinate system, positive is left



To Sector:    Rotate each sector CCW around the z-axis by  $\text{sectorId} \cdot 60^\circ$  to  $\varphi = 0$

# Coordinates: Sector

- All sectors from the same detector coincide at  $\varphi = 0$ .
- Exceptions: BST, CND, FTCAL

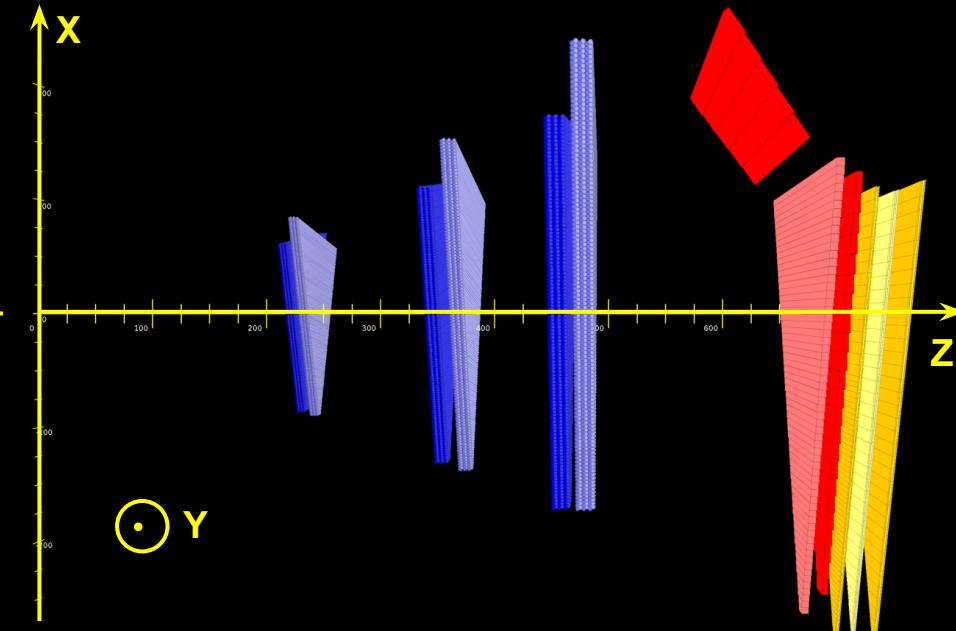
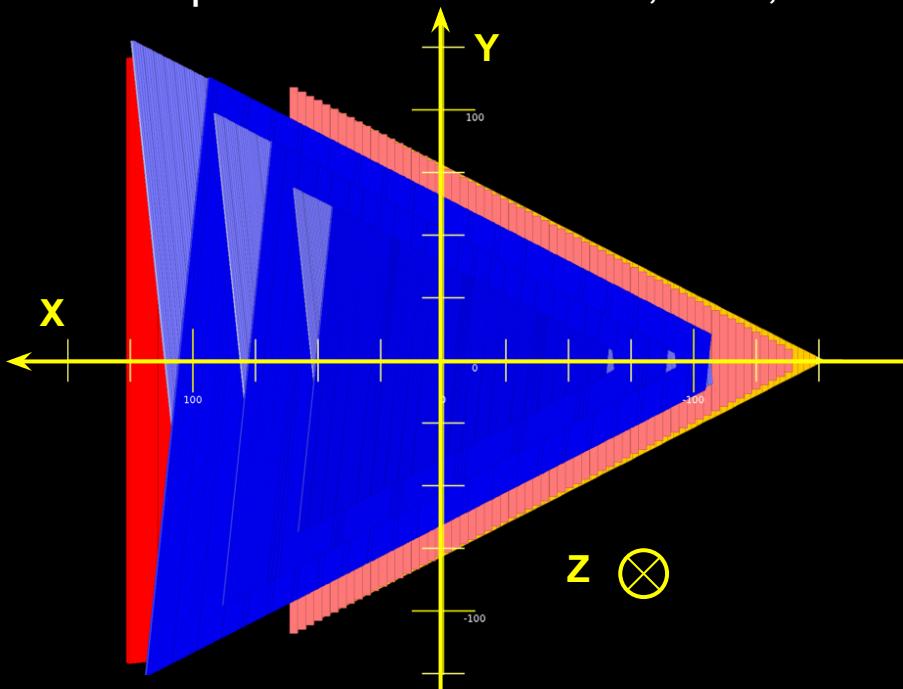


To CLAS:      Rotate each sector CW around z-axis by  $\varphi = \text{sectorId} \cdot 60^\circ$

To Tilted:      Rotate each sector CCW around the y-axis by  $25^\circ$  to  $\theta = 0$

# Coordinates: Tilted

- The normal of the up-beam surface of each detector is parallel to the z-axis
- Exceptions: FTOF Panel 2, BST, CND

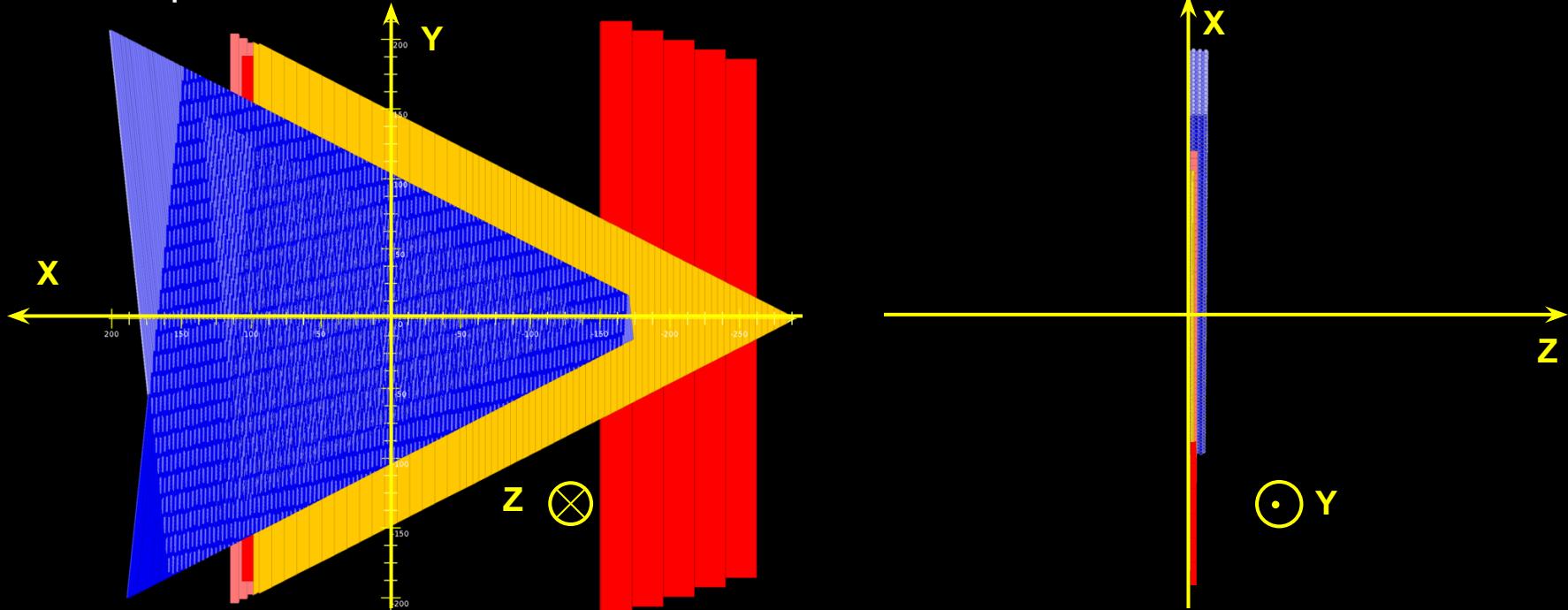


To Sector:      Rotate each sector CW around the y-axis by 25°

To Local:        Translate each superlayer's up-beam surface to  $z = 0$

# Coordinates: Local

- The up-beam surface of each superlayer is at  $z = 0$ .
- Exceptions: BST, CND

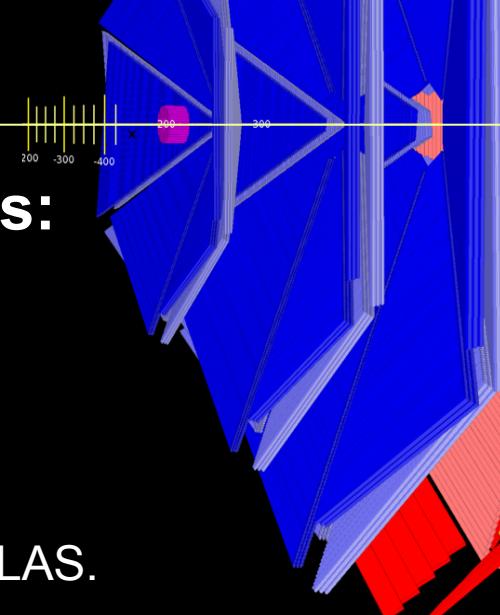


To Tilted: Translate each superlayer's up-beam surface along the z-axis.

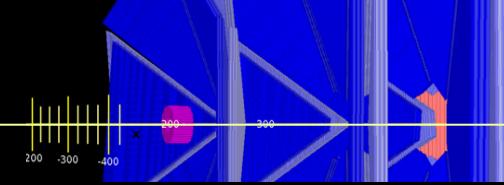
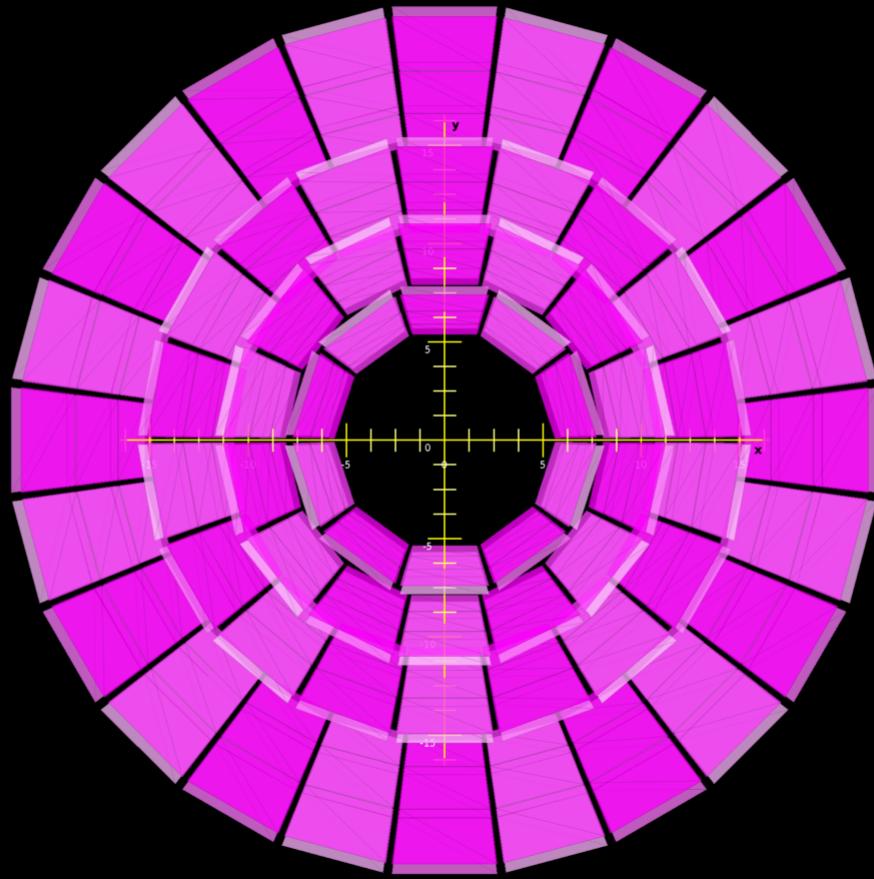
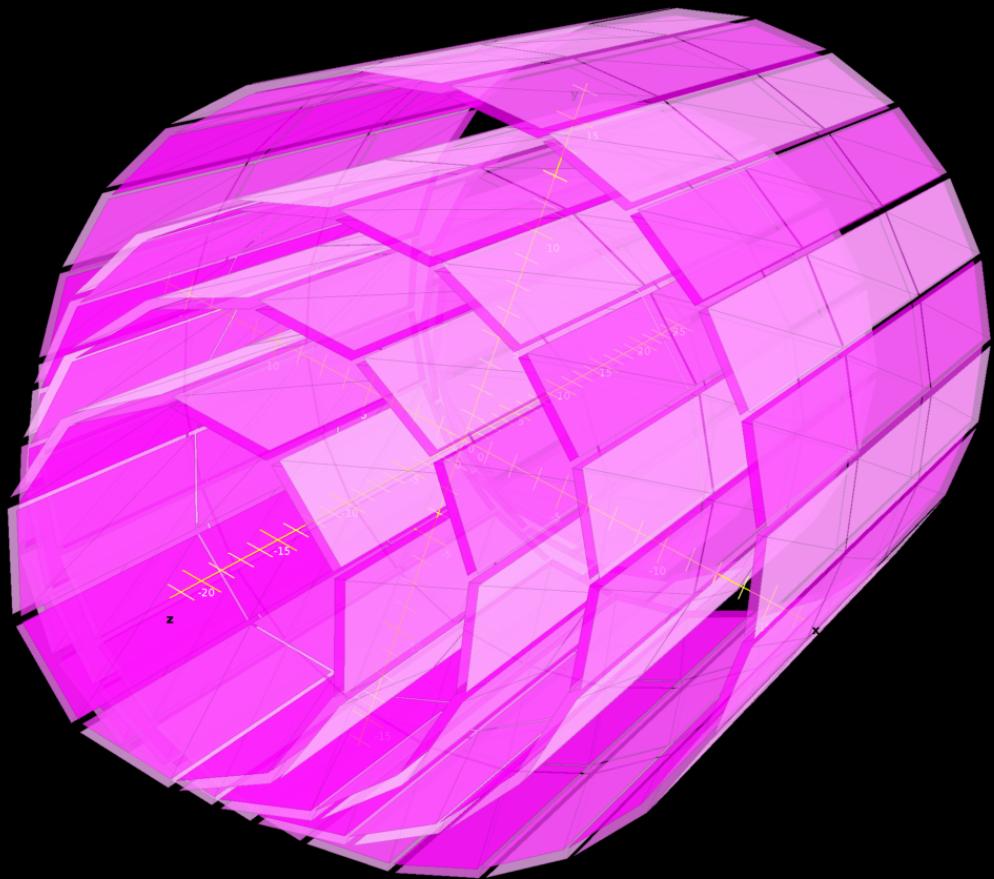
# Coordinates: Local

**Current working definition of local coordinates:**

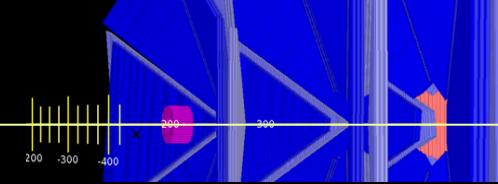
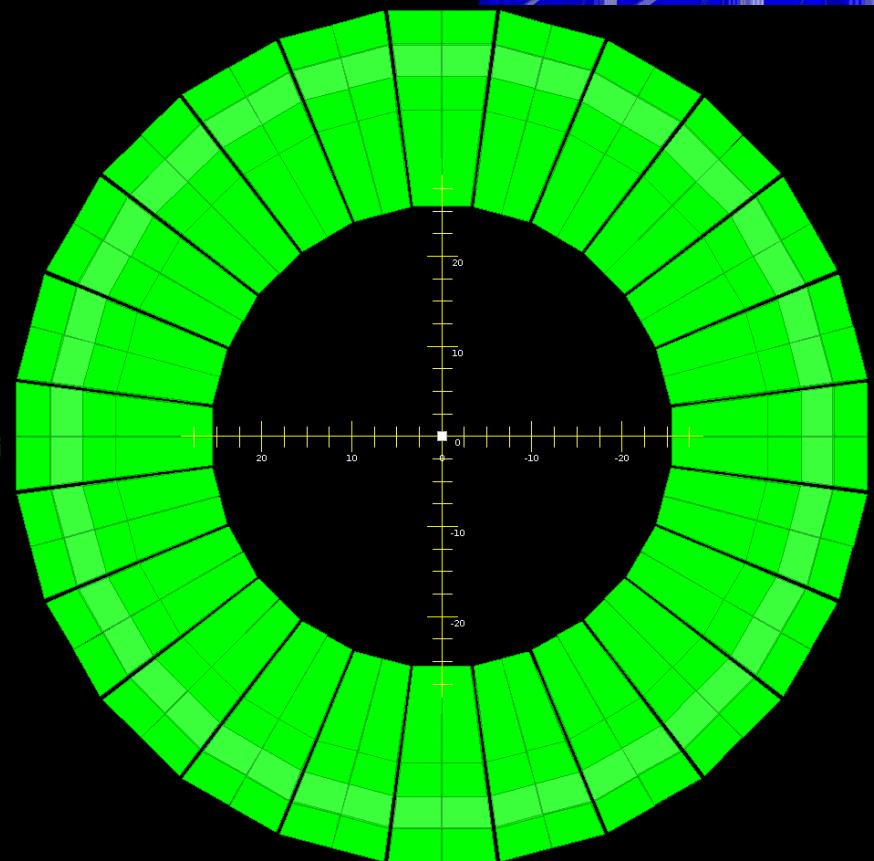
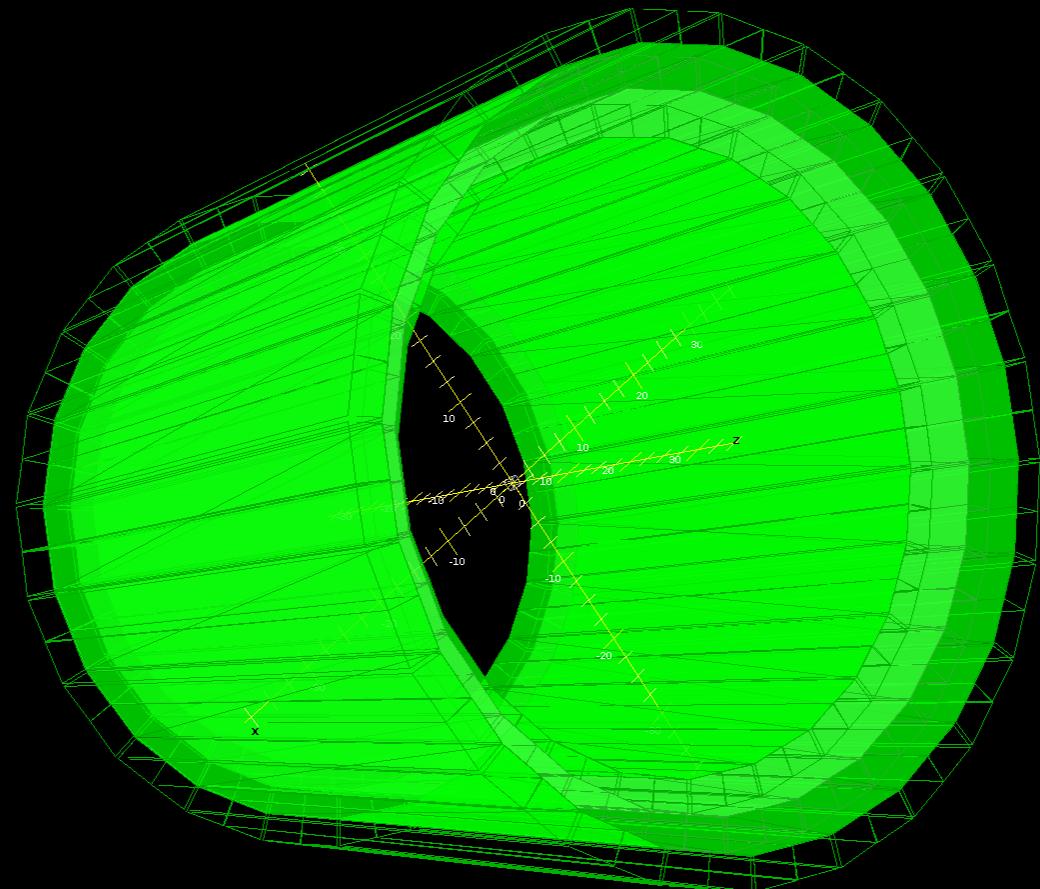
1. All sectors belonging to the same detector coincide.
2. No rotations around the x-axis are required to get to CLAS.
3. No translations along the x- or y-axis are required to get to CLAS.
4. No rotations around the z-axis are required to get the first sector to CLAS.
5. The upstream surface of each superlayer is at  $z=0$  and in the xy-plane.
6. Layers are in place relative to their respective superlayers and do not require further translations or rotations independently of their superlayer.



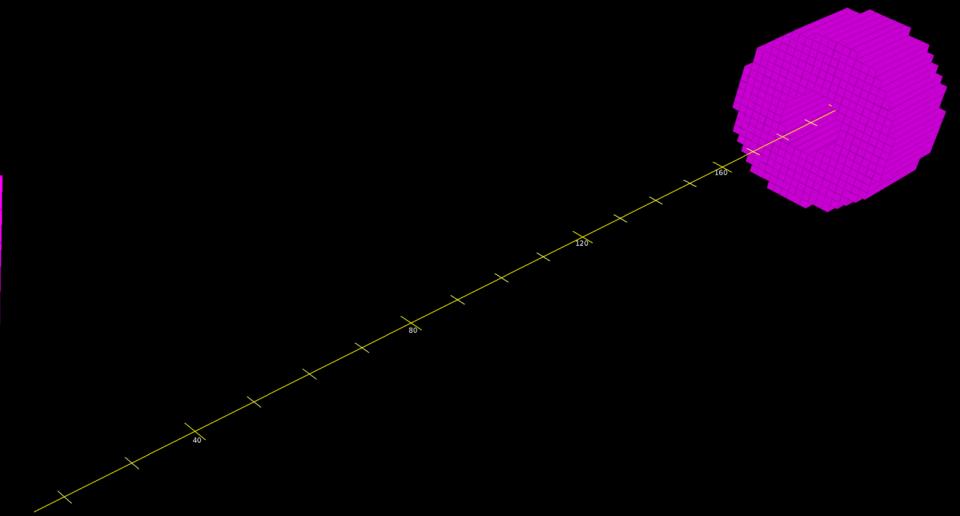
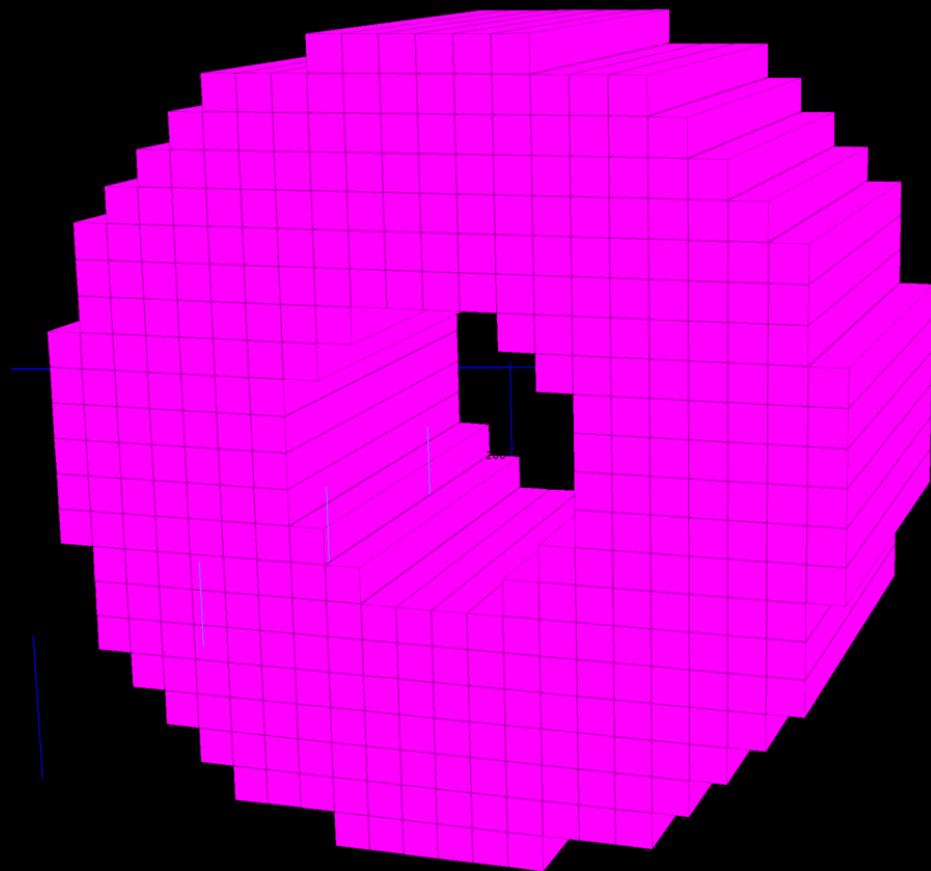
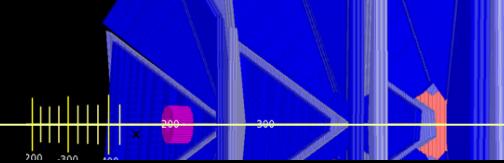
# Special Cases: BST



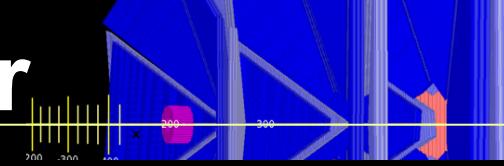
# Special Cases: CND



# Special Cases: FTCAL



# Visualizer: clas-visualizer



**CLAS Geometry Viewer**

File Inspector Method Window Help

Clear AA Trans- Trans+ Wire Surf Plane Line Dir

missing license, cannot find = /home/jphankin/lab/clas-visualizer/javaview-lic.lic  
register at www.javaview.de

Control Panel - JavaView

File Inspector Method Window Help

Camera: Main Display Show 4 Displays

Perspective Top (X-Y)  
Front (X-Z) Right (Y-Z)

Position Show Camera

View Direction 1 0.0 0.6  
Interest 0.0 0.0 600

Distance 1000.0

Roll 90

Perspectivity 0.5

Transform Model Coordinate System

Ambient Space R3 Euclidean  
Projection Parallel

Clipping Scene Camera

Near Clip 1.00000000  
Far Clip -10.0

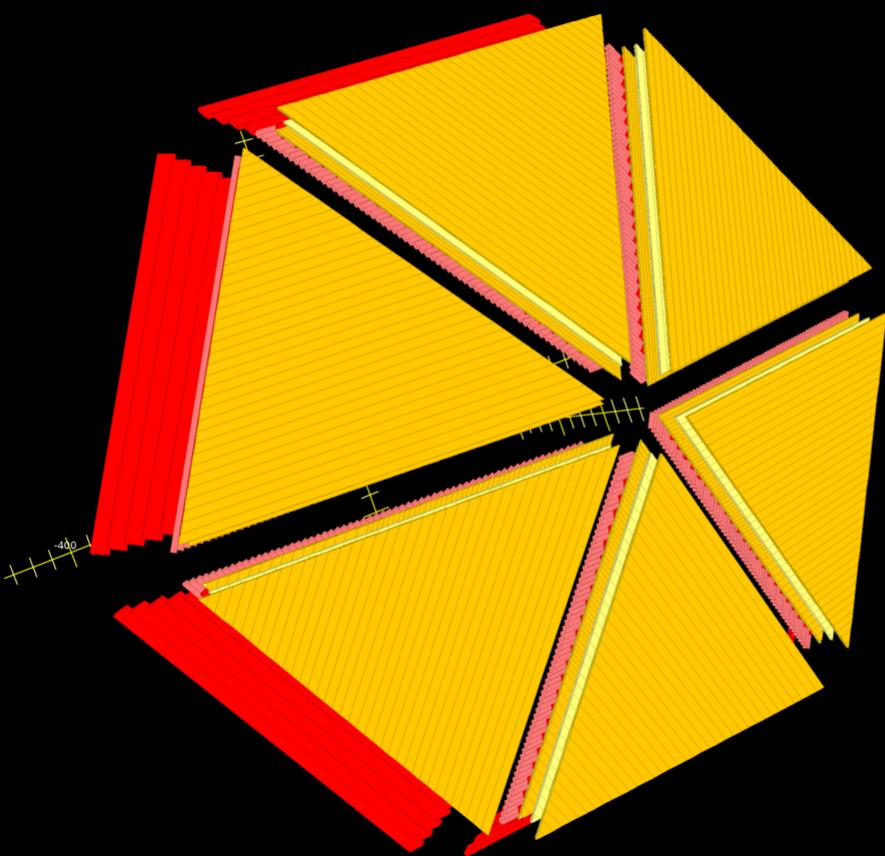
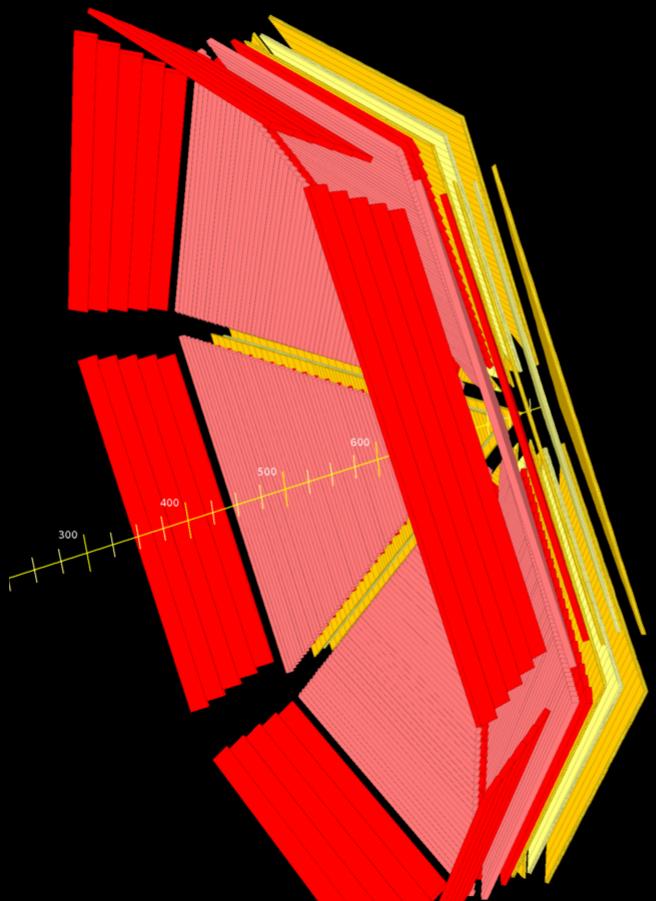
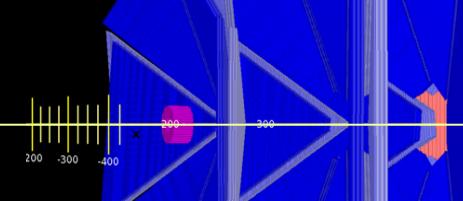
Box Ratio Enable Aspect

Ratios 1.0 1.0 1.0

Center Fit  
Save Reset Reset All

The main window displays a 3D geometric model of a particle detector. The model consists of various colored surfaces (blue, red, yellow, green) representing different detector components. A coordinate system is visible on the left side of the model. The right side of the image shows the "Control Panel - JavaView" window, which contains various controls for camera settings, transformation, clipping, and box ratios.

# Details: FTOF & EC



# Details: DC

