

## 7. Hashing

Reading suggestion: Chapter 11 of the textbook

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CIS2520

Hashing

### TABLE ADT

Hash Tables

Collision Resolution

Algorithms

Hash and Probe Functions

Conclusion

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*SIN:* 522-145-678  
*Last name:* Smith  
*First name:* John  
*Title:* Associate Professor  
.....

*SIN:* **501-997-403**  
*Last name:* Roe  
*First name:* Jane  
*Title:* Professor  
.....

*SIN:* 593-021-844  
*Last name:* **Major**  
*First name:* **Mary**  
*Title:* **Assistant Professor**  
.....

**Insert**  
**Update**  
**Remove**  
**Search**  
**Retrieve**

*SIN:* 570-133-981  
*Last name:* Smith  
*First name:* John  
*Title:* **Professor**  
.....

*SIN:* 537-702-556  
*Last name:* Miles  
*First name:* Richard  
*Title:* Assistant Professor  
.....

Reading suggestion: Chapter 11 of the textbook

*Code:* PHL  
*Country:* Pennsylvania  
*City:* Philadelphia  
*Volume:* 31 million  
.....

*Code:* AKL  
*Country:* New Zealand  
*City:* Auckland  
*Volume:* 13 million  
.....

*Code:* FRA  
*Country:* Germany  
*City:* Frankfurt  
*Volume:* 53 million  
.....

**Insert**  
**Update**  
**Remove**  
**Search**  
**Retrieve**

*Code:* ORY  
*Country:* France  
*City:* Paris  
*Volume:* 25 million  
.....

*Code:* HKG  
*Country:* China  
*City:* Hong Kong  
*Volume:* 50 million  
.....

Reading suggestion: Chapter 11 of the textbook

- N**: The set of nonnegative integers  
**I**: A nonempty set  
**K**: A nonempty set  
 $\preceq$ : A total order relation on K

**Table** of **items** of type I and **keys** of type K:

A set  $\{(item_1, key_1), (item_2, key_2), \dots, (item_n, key_n)\}$  such that

◇  $\forall i \in 1..n, (item_i \in I \wedge key_i \in K)$

◇  $\forall i \in 1..n, \forall j \in 1..n, (key_i = key_j \rightarrow item_i = item_j)$

Each pair (item, key) is a table **entry**

**Table[I, K]:**

The set of all tables of items of type I and keys of type K

Reading suggestion: Chapter 11 of the textbook

**Create**:  $\emptyset \rightarrow \text{Table}[I, K]$

**Insert**:  $I \times K \times \text{Table}[I, K] \rightarrow \text{Table}[I, K]$

**Update**:  $I \times K \times \text{Table}[I, K] \rightarrow \text{Table}[I, K]$

**Remove**:  $K \times \text{Table}[I, K] \rightarrow \text{Table}[I, K]$

**Full**:  $\text{Table}[I, K] \rightarrow \text{Boolean}$

**Empty**:  $\text{Table}[I, K] \rightarrow \text{Boolean}$

**Size**:  $\text{Table}[I, K] \rightarrow \mathbb{N}$

**Entry**:  $K \times \text{Table}[I, K] \rightarrow \text{Boolean}$

**Retrieve**:  $K \times \text{Table}[I, K] \rightarrow I$

} **constructor**

} **mutators**

} **accessors**

$\{\neg \text{Full}(t) \wedge \neg \text{Entry}(k, t)\} \text{Insert}(i, k, t)$

$\{\text{Entry}(k, t)\} \text{Update}(i, k, t)$

} **preconditions**

$\text{Remove}(k, t) \{\neg \text{Full}(t) \wedge \neg \text{Entry}(k, t)\}$

$\text{Insert}(i, k, t) \{\text{Retrieve}(k, t) = i\}$

} **postconditions**

Reading suggestion: Chapter 11 of the textbook

## TABLE ADT: Representations (1/2)

7.7

- ✧ A table entry (item,key) can be represented by a C struct.
- ✧ A table can be represented by an **array** of (pointers to) table entries stored in ascending order of their keys.

PHL  
ORY  
GCM  
HKG  
GLA  
AKL  
FRA  
LAX  
DCA

AKL	DCA	FRA	GCM	GLA	HKG	LAX	ORY	PHL		
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Traversal	Search	Insertion	Removal
$O(n)$	$O(\log n)$	$O(n)$	$O(n)$

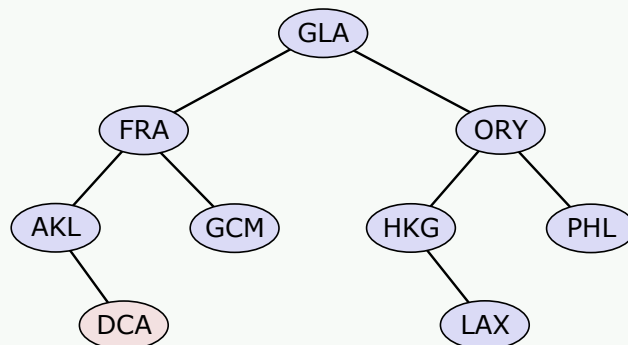
Reading suggestion: Chapter 11 of the textbook

## TABLE ADT: Representations (2/2)

7.8

- ✧ A table entry (item,key) can be represented by a C struct.
- ✧ A table can be represented by an **AVL tree**, where each tree node stores a (pointer to a) table entry and pointers to other tree nodes.

PHL  
ORY  
GCM  
HKG  
GLA  
AKL  
FRA  
LAX  
DCA

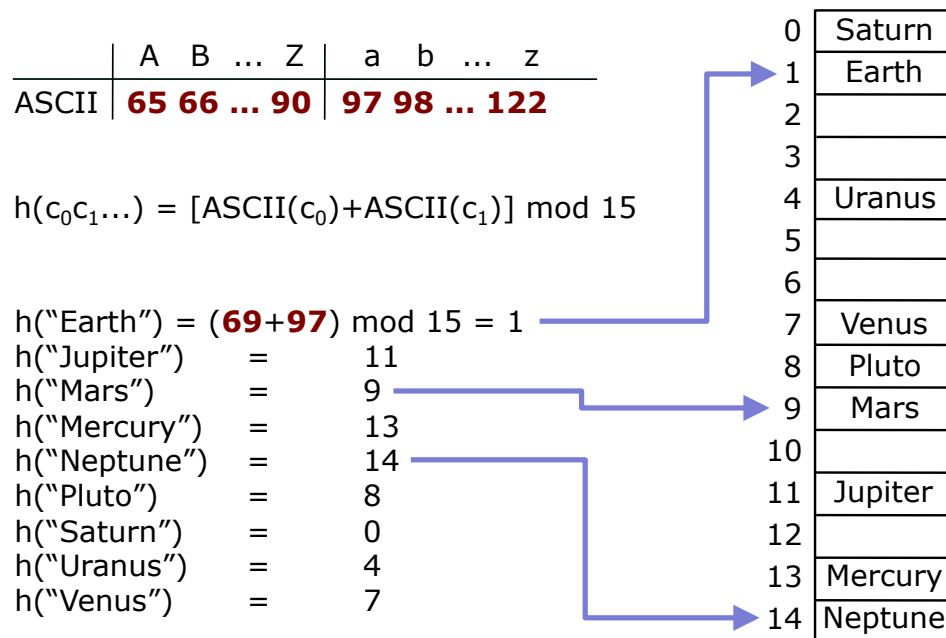


Traversal	Search	Insertion	Removal
$O(n)$	$O(\log n)$	$O(\log n)$	$O(\log n)$

Reading suggestion: Chapter 11 of the textbook

Table ADT  
HASH TABLES  
Collision Resolution  
Algorithms  
Hash and Probe Functions  
Conclusion

<i>Name:</i> Neptune <i>Diameter:</i> 50,000 km <i>Orbit:</i> 30 AU <i>Moons:</i> 13 .....	<i>Name:</i> Mars <i>Diameter:</i> 6,800 km <i>Orbit:</i> 1.5 AU <i>Moons:</i> 2 .....
<i>Name:</i> Mercury <i>Diameter:</i> 4,900 km <i>Orbit:</i> 0.4 AU <i>Moons:</i> 0 .....	<i>Name:</i> Earth <i>Diameter:</i> 12,800 km <i>Orbit:</i> 1 AU <i>Moons:</i> 1 .....
<i>Name:</i> Jupiter <i>Diameter:</i> 143,000 km <i>Orbit:</i> 5.2 AU <i>Moons:</i> 65 .....	



Reading suggestion: Chapter 11 of the textbook

**array:** able to store up to  $m$  (pointers to) table entries

**h:** total function from the set of keys to the integer interval  $0..m-1$ ;  
 ↓ an arithmetic calculation transforms each key into an array index

**perfect hash function**

**hash table**

To search for an item with key  $k$ , just look in slot  $h(k)$  of the array.

The  $h(k)$  values lie in a relatively small range.

The  $h(k)$  values are dispersed in that range.

The  $h(k)$  values are all different.

↓  
**hash address**

**Pros:** worst-case running time for search, insertion and removal is  $O(1)$ .

**Cons:** traversal is  $O(n \log n)$ , and lost space in array.

*Note that in the previous example,  
 the number of keys is equal to the number of entries.*

Reading suggestion: Chapter 11 of the textbook

**array:** able to store up to  $m$  (pointers to) table entries

**h:** total function from the set of keys to the integer interval  $0..m-1$ ;

↓ an arithmetic calculation transforms each key into an array index

**hash function**

**hash table**

To search for an item with key  $k$ , **look first** in slot  $h(k)$  of the array.

The  $h(k)$  values lie in a relatively small range.

The  $h(k)$  values are dispersed in that range.

**Most**  $h(k)$  values are different.

↓  
**hash address**

**Pros:** **expected** running time for search, insertion and removal is  $O(1)$ .

**Cons:** traversal is  $O(n \log n)$ , and lost space in array.

*Note that in the general case,  
the number of keys is much greater than the number of entries.*

Reading suggestion: Chapter 11 of the textbook

0	
1	
2	
3	
4	PHL
5	
6	GCM
7	
8	ORY
9	
10	

HKG

key	$h(\text{key})$
PHL	4
ORY	8
GCM	6
HKG	4
GLA	8
AKL	7
FRA	5
LAX	1
DCA	1

A B C ... Z

0 1 2 ... 25

$h(\text{PHL})$   
 $= (15 \times 26^2 + 7 \times 26^1 + 11) \bmod 11$   
 $= 10333 \bmod 11 = 4$

$h(\text{ORY})$   
 $= (14 \times 26^2 + 17 \times 26^1 + 24) \bmod 11$   
 $= 9930 \bmod 11 = 8$

**Collision** when  $h(k_1) = h(k_2)$  and  $k_1 \neq k_2$

Need for a **collision resolution policy**

Reading suggestion: Chapter 11 of the textbook

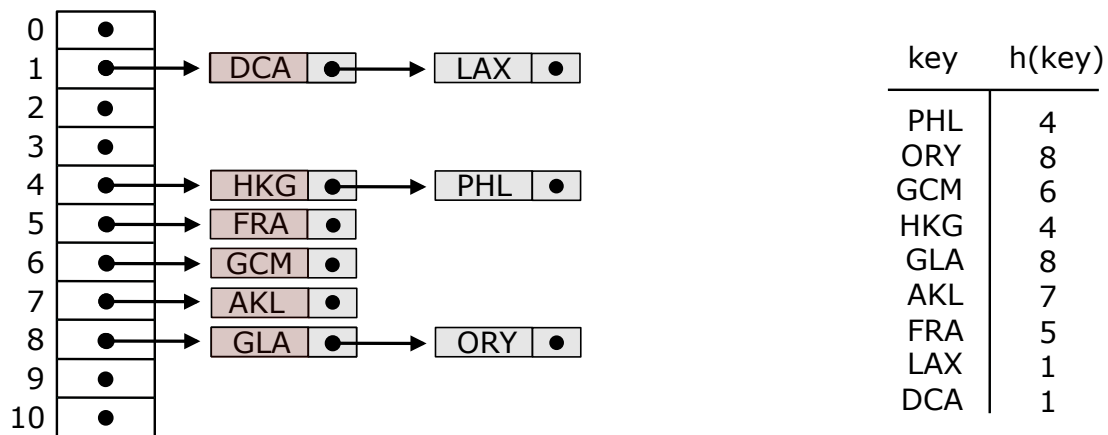
Table ADT  
Hash Tables  
**COLLISION RESOLUTION**  
Algorithms  
Hash and Probe Functions  
Conclusion

collisions are relatively frequent  
even in sparsely occupied hash tables

Consider hash table with  $m=365$  slots:

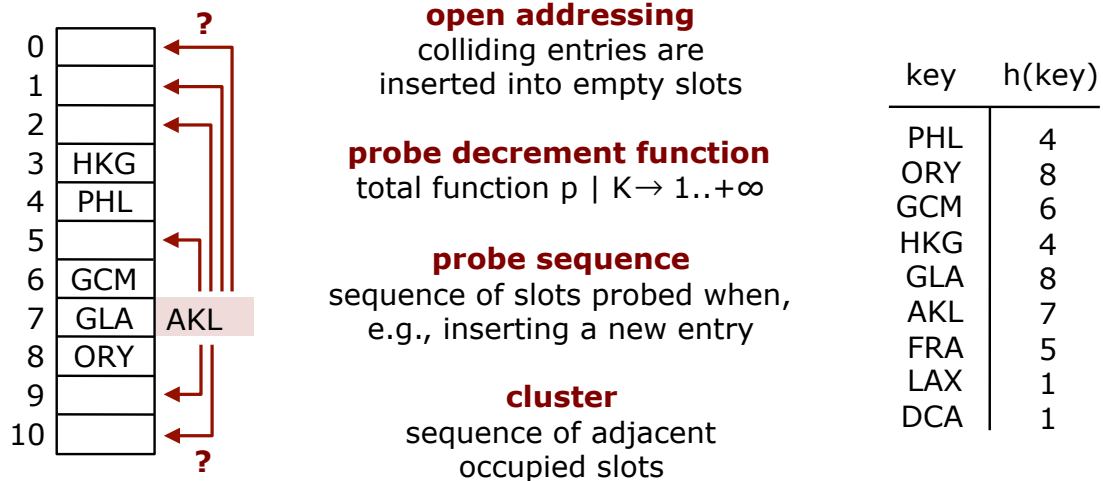
- ✧ if  $n=366$  entries inserted randomly  
probability of collision 100%
- ✧ if  $n=57$  entries inserted randomly  
probability of collision greater than 99%  
(and table 16% full)
- ✧ if  $n=23$  entries inserted randomly  
probability of collision greater than 50%  
(and table 6% full)



**chaining**

one linked list per slot; two colliding entries placed on the same linked list

Reading suggestion: Chapter 11 of the textbook

**open addressing**

colliding entries are  
inserted into empty slots

**probe decrement function**

total function  $p \mid K \rightarrow 1..+\infty$

**probe sequence**

sequence of slots probed when,  
e.g., inserting a new entry

**cluster**

sequence of adjacent  
occupied slots

Reading suggestion: Chapter 11 of the textbook

0	DCA
1	LAX
2	FRA
3	HKG
4	PHL
5	AKL
6	GCM
7	GLA
8	ORY
9	
10	

**linear probing**  
 if slot  $i$  is occupied try  $i - p(\text{key})$   
 (or  $m + i - p(\text{key})$  if  $i - p(\text{key}) < 0$ )  
 where  $p(\text{key}) = 1$  for any key

**primary clustering**  
 clusters tend to merge  
 and grow faster and faster

key	$h(\text{key})$
PHL	4
ORY	8
GCM	6
HKG	4
GLA	8
AKL	7
FRA	5
LAX	1
DCA	1

*5 collisions and  
up to 3 clusters*

Reading suggestion: Chapter 11 of the textbook

0	
1	HKG
2	DCA
3	
4	PHL
5	FRA
6	GCM
7	AKL
8	ORY
9	LAX
10	GLA

**double hashing**  
 if slot  $i$  is occupied try  $i - p(\text{key})$   
 (or  $m + i - p(\text{key})$  if  $i - p(\text{key}) < 0$ )  
 where  $p(\text{key})$  depends on key  
 very much like  $h(\text{key})$

double hashing  
 avoids primary  
 clustering

key	$h(\text{key})$	$p(\text{key})$
PHL	4	4
ORY	8	1
GCM	6	1
HKG	4	3
GLA	8	9
AKL	7	2
FRA	5	6
LAX	1	7
DCA	1	2

*4 collisions and  
up to 5 clusters*

Reading suggestion: Chapter 11 of the textbook

A	B	C	...	Z
0	1	2	...	25

$$h(\text{PHL}) = 15 \times 26^2 + 7 \times 26^1 + 11 = 10333 \bmod 11 = 4$$

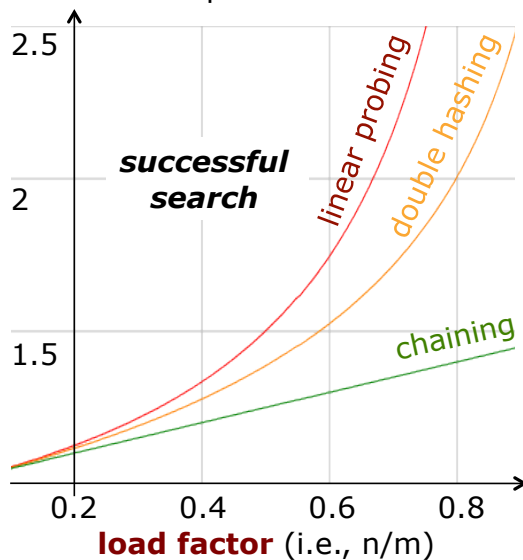
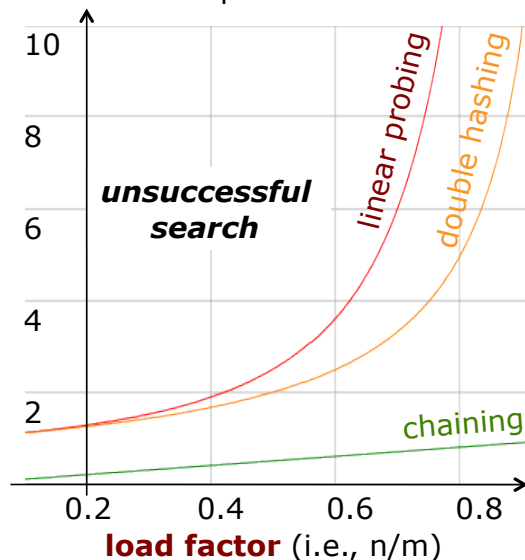
$$h(\text{ORY}) = 14 \times 26^2 + 17 \times 26^1 + 24 = 9930 \bmod 11 = 8$$

$$p(\text{PHL}) = \max \{ 1, (10333 \bmod 11) \} = 4$$

$$p(\text{ORY}) = \max \{ 1, (9930 \bmod 11) \} = 1$$

key	p(key)
PHL	4
ORY	1
GCM	1
HKG	3
GLA	9
AKL	2
FRA	6
LAX	7
DCA	2

Reading suggestion: Chapter 11 of the textbook

average number  
of addresses probedaverage number  
of addresses probed

Reading suggestion: Chapter 11 of the textbook

Table ADT  
Hash Tables  
Collision Resolution  
**ALGORITHMS**  
Hash and Probe Functions  
Conclusion

```
function Initialize (table)
    table.entries=0
    table.freeSlots=table.slots
    for i=0 to table.slots-1
        table[i]=nil

function Size (table)
    return table.entries
```

```
function Full (table)
    if table.freeSlots=1
    then return true
    else return false

function Empty (table)
    if table.entries=0
    then return true
    else return false
```

Reading suggestion: Chapter 11 of the textbook

```
function Remove (key, table)
    i=h(key)
    decrement=p(key)
    while table[i].key≠key
        i=i-decrement
        if i<0 then i=i+table.slots
    table[i].available=true
    table.entries=table.entries-1
```

Reading suggestion: Chapter 11 of the textbook

```
function Insert (item, key, table)
    i=h(key)
    decrement=p(key)
    while table[i]≠nil and table[i].available=false
        i=i-decrement
        if i<0 then i=i+table.slots
    if table[i]=nil
    then table.freeSlots=table.freeSlots-1
    table[i].key=key
    table[i].item=item
    table[i].available=false
    table.entries=table.entries+1
```

Reading suggestion: Chapter 11 of the textbook

```
function Search (key, table)
    i=h(key)
    decrement=p(key)
    while table[i]≠nil and table[i].key≠key
        i=i-decrement
        if i<0 then i=i+table.slots
    if table[i]=nil or table[i].available=true
    then return -1
    else return i
```

Reading suggestion: Chapter 11 of the textbook

```
function Update (item, i, table)
    table[i].item=item

function Retrieve (i, table)
    return table[i].item
```

Reading suggestion: Chapter 11 of the textbook

Table ADT  
Hash Tables  
Collision Resolution  
Algorithms

HASH AND PROBE FUNCTIONS

Conclusion

A good hash function maps keys uniformly and randomly onto the full range of possible table locations. Ideally:

$$\forall i, \forall j, |\{k \in K \mid h(k) = i\}| = |\{k \in K \mid h(k) = j\}|$$

Reading suggestion: Chapter 11 of the textbook

Assume keys are strings of symbols from some alphabet. The symbols are seen as base  $b$  digits.

Consider a key  $s_t s_{t-1} \dots s_1 s_0$ . It is seen as the base  $b$  expansion of

$$i = s_t b^t + s_{t-1} b^{t-1} + \dots + s_1 b + s_0$$

Let  $m$  be the number of slots in the hash table.

Choose  $m$  prime, but do not choose it too close to a small power of  $b$ .

$$h(s_t s_{t-1} \dots s_1 s_0) = i \bmod m$$

$$\begin{aligned} h(\text{PHL}) &= (\mathbf{15} \times 26^2 + \mathbf{7} \times 26^1 + \mathbf{11}) \bmod 11 \\ &= 10333 \bmod 11 = \mathbf{4} \end{aligned}$$

A	B	C	...	Z
0	1	2	...	25

Reading suggestion: Chapter 11 of the textbook



**folding**

divide sequence of digits into subsequences; combine them

$$k = 512-678-890$$

$$h(k) = 512 + 678 + 890 = 2080$$

**middle squaring**

take middle digits; square them; take middle digits again if necessary

$$k = 512-678-890$$

$$678^2 = 459684$$

$$h(k) = 5968$$

**truncation**

delete part of the key; use the remaining digits

$$k = 512-678-890$$

$$h(k) = 8890$$

Reading suggestion: Chapter 11 of the textbook

0	6
1	2
2	9
3	5
4	1
5	8
6	4
7	11
8	7
9	3
10	10

$h(k) = 4$   
 $p(k) = 3$

A slot should not appear twice in a probe sequence.  
At worst, a probe sequence should cover all slots.



$p(k)$  must be relatively prime to the number  $m$  of slots  
(e.g.,  $m$  prime and  $p(k)$  in  $1..m-1$ ,  
 $m$  power of 2 and  $p(k)$  odd).

**division method**

$$h(k) = i \bmod m$$

$$p(k) = \max \{ 1, (i \div m) \bmod m \}$$

Reading suggestion: Chapter 11 of the textbook

Table ADT  
Hash Tables  
Collision Resolution  
Algorithms  
Hash and Probe Functions  
**CONCLUSION**

Best representation for a table  
(e.g., sorted array, AVL tree, hash table)  
depends on the frequency of the operations to be performed.

**HASH TABLE**

In the worst case,  
searches, insertions and removals  
take  $O(n)$  time.

In practice,\*  
searches, insertions and removals  
are extremely fast and take  $O(1)$  time.

\* *for collision resolution with open addressing  
keep the load factor below some threshold;  
the lower the load factor the better*