

Artificial and Biological Neural Systems

Theory Notes

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These notes are for the course “Artificial and Biological Neural Systems” held by professor Uri Hasson.

I have included all the topics seen during the lectures and tried my best to avoid mistakes. I have also included some digressions (i.e. non-mandatory topics), marking them as such and with a yellow background. That being said, a very broad range of topics was to be covered, hence I do not take responsibility for any mistake or imperfection that might be present; still, it would be much appreciated if you reported any of those, so that I can fix the notes accordingly. In the GitHub repository¹ you can find the LaTex source code; feel free to create issues and pull requests to include topics and corrections.

I hope that this document will help in the study of this beautiful and exciting subject.

If you consider this material valuable for you in order to be prepared for the exam, consider offering me a coffee :)

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XOXO - jo

¹<https://github.com/jo-valer/ABNS-Hasson>

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Chapter 1

Introduction to brain physiology and research methods

1.1 Basic facts about the human brain

The human brain is partitioned in many structures. The first one is the **cortex**, and in the following we provide the *traditional function specializations* ▲:

- **Temporal lobe:** **Auditory processing** (hearing and language)
- **Parietal lobe:** **Attention**, touch, saccade planning
- **Frontal lobe:** Planning, execution, **higher level cognition**, high level language processing and language production
- **Occipital lobe:** **Vision:** perception of visual features, categories and location



▲ Here we have the traditional function specializations, even though nowadays we know that all areas of the brain take part in more functions: a function is computed by the whole network. The auditory processing is a sort of exception: audio is processed only in the temporal lobe; however, it is still part of the network, as its functions can be *modified on demand*.

We then have the **subcortical structures**:

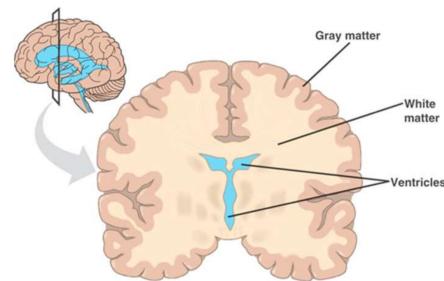
- **Cerebellum:** Fine motor control, implicated in emotional responses
- **Thalamus:** Major gateway for sensory processing. One of the final stops before sensory information arrives at the cortex

- **Hippocampus:** implicated in construction of memories; these are later transferred to other cortical regions
- **Corpus Callosum:** A main “highway” of white matter tracks that connects the two hemispheres

1.1.1 Gray matter

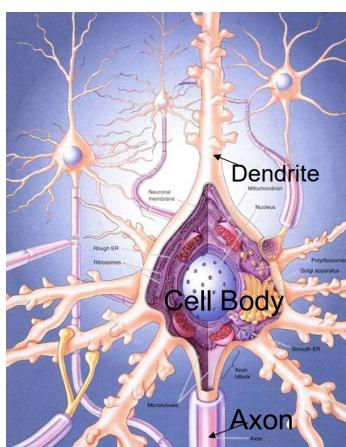
Gray matter (GM), which gets its name from its color, is the brain part that **performs computation**. The gray matter includes not only the cerebral cortex but also the cerebellum, basal ganglia, thalamus, and several other regions. Techniques for measuring brain activity often reflect the function of gray matter regions, which are responsible for the majority of cognitive processing. As a result, understanding the role and function of gray matter in the brain is essential for gaining insight into various neurological and psychiatric conditions.

The gray matter is on the perimeter of the brain, and its folded structure (with *gyri* and *sulci*, determined by the DNA) allows for higher surface. This also causes parts that are located close to each other, in physical space, to be far away in cortical space.



1.1.2 White matter

White matter consists mainly of **long-range axon pathways**, or *tracts*, that **connect different regions of the brain**. Unlike gray matter, there is **no direct information processing** within white matter itself. The structure of white matter can change with learning because it reflects the long-range neural pathways that carry nerve impulses and facilitate the communication between different regions of the brain.



Damage to white matter, such as the loss of myelin in conditions like multiple sclerosis, can have significant impacts on communication between different regions of the brain, leading to various neurological and psychiatric symptoms. Therefore, understanding the role and function of white matter is critical for studying brain function and identifying potential targets for interventions in various neurological and psychiatric disorders.

1.1.3 The neuron

A neuron consists of **dendrites**, a **cell body** (aka **soma**) and an **axon**. Connections between neurons are called **synapses**, and typically occur on a neuron's dendrite (but in some cases also on soma), which receives synaptic signals. Synapses are **chemical, not electrical**. A neuron will *fire* (generate an action potential) depending on the number of signals it receives on its dendrites and their strength, which are *summed* in the neuron's body.

Digression: Synaptic communication

Synaptic communication is the process by which neurons communicate with each other through the release and reception of chemical signals called neurotransmitters. The postsynaptic neuron receives the signal, which is either excitatory (the neuron is depolarized and fires an action potential), or inhibitory (causing the neuron to hyperpolarize and become less likely to fire an action potential). Depolarization produces an *all-or-nothing* signal: **no partial firing**.

1.1.4 Neuroplasticity

Neuroplasticity refers to *network changes* over time, to adapt to the environment. Synapses can be **strengthened** or **pruned**.

Connections between neurons are consistently removed (or created) depending on use. A large percentage of neurons that develop die. A *hub* neuron, which receives inputs from many neurons is more likely to survive. When many neurons connect to a target neuron, this decreases their survival rate. This calibration is thought to be associated with generating an optimal degree of synaptic connection. Brain volume triples between birth and adulthood; this is mostly not due to addition of neurons, but to an increased number of connections (synapses), myelination of existing axons and greater dendritic branching.



Synaptic density and total synapses in visual cortex as a function of age.

1.2 Studying the human brain: tools and basics of experimentation

The human brain can be studied at different levels of organization, from systems and pathways to synapses and membranes.

- Systems and pathways: large-scale neural networks responsible for specific functions, such as sensory perception, motor control, and cognition. These may be topographically distributed.
- Circuits and neurons: networks of interconnected neurons that underlie information processing within the brain.
- Synapses and membranes: molecular and cellular mechanisms that govern the transmission of signals between neurons, such as the release of neurotransmitters and activation of ion channels.

Studying the brain at different scales provides insights into organization of function from the macroscopic to the microscopic level.

1.2.1 Basics of experimentation

There are several **non-invasive tools** available for studying brain activity and structure, including electroencephalography (EEG), structural imaging, functional magnetic resonance imaging (fMRI), and diffusion-weighted imaging. These tools provide insights into different aspects of brain function and structure: electrical activity of neurons, structural connectivity of brain regions, and metabolic activity (i.e. energy consumption) associated with specific tasks or behaviors.



Figure 1.1: **Temporal and spatial resolution** of common tools. An additional dimension is **coverage**: how much of the brain is simultaneously observable by the tool.

Experimental procedures are used to analyze the data collected by these tools; they typically consist in conducting studies that involve manipulating variables of interest and collecting and analyzing data from participants. In neuroscience, an **experiment** or study is a systematic **investigation of a research hypothesis** that involves **manipulating variables and measuring their effects on some outcome of interest**. Conclusions from experiments are drawn by analyzing the data collected from participants and testing whether there are statistically significant differences between groups or conditions, typically using statistical methods to quantify the strength and direction of effects and assessing the probability that the observed effects are due to chance.

In the following sections we will discuss the most important tools (namely EEG, structural imaging, fMRI), however there are many others:

- TMS (Transcranial Magnetic Stimulation): induces a virtual lesion of a part of the brain (this might be dangerous).
- MEG (Magnetoencephalography): directly measures the magnetic fields generated by neural activity.
- Patch clamp: records the current from ion channels in the cell membrane

1.2.2 Electroencephalography (EEG)

EEG is a non-invasive method used to study patterns of brain activity with high temporal resolution. The principle behind EEG is that it is sensitive to very subtle changes in electric potentials below the sensors, which are propagated to the scalp. These changes reflect alterations in the electrical environment of thousands of neurons that fire in synchrony. Each EEG sensor gives one time series. It is difficult to pinpoint the brain regions causing the fluctuations, since the electromagnetic waves are dispersed by the scalp. However, the **timing of the signals is very precise**.

From EEG time series to ERP

Tasks can generate **stereotyped evoked potentials** that can be averaged (over all epochs ▲) to obtain an **Event-Related Potential** (aka **Evoked-Response-Potential**). An ERP analysis quantifies electrical brain responses to events/stimuli based on time-locked EEG portions. This analysis can be used as the basis for more sophisticated analysis such as source localization.

- ▲ An epoch consists in the timespan [0ms, 500ms] after the stimulus presentation.

Neural activity is not the only activity causing electrical fluctuations. Muscles are also one of the main causes of fluctuations (e.g. every time we blink or move our eyes there are oscillations collected by EEG sensors). All these **noise** artifacts have to be independently measured and then removed from the data. The sensors placed near the eyes are indeed used to measure such noise. Moreover, since the interesting brain **signal is low**, while the **noise is high**, **many repetitions** of each condition are needed (the impact of noise on computing ERPs scales down as a function of the square root of the number of observations). This noise reduction applies to each timepoint measured. The need for many repetitions can be challenging and time-consuming, but it is necessary for obtaining reliable and statistically significant results. In addition to repetition, other techniques such as filtering and artifact rejection can also help to reduce noise in EEG recordings.

EEG also contains important information in form of frequency characteristics (cycling rate). The frequency differentiates sleep stages from awake, and drowsy from alert. Power plots can show the relative strength of each frequency, helping in *frequency band interpretation*. For instance, the alpha band in EEG, which has a frequency range of 8-12 Hz, is commonly observed during eyes-closed recordings and relaxed states. Alpha oscillations are associated with reduced communication between the cortex and thalamus. During externally oriented attention and stimulus processing, the alpha activity is suppressed.



A waveform showing several ERP components. Notice the plot has negative voltages upward.

ERP in practice

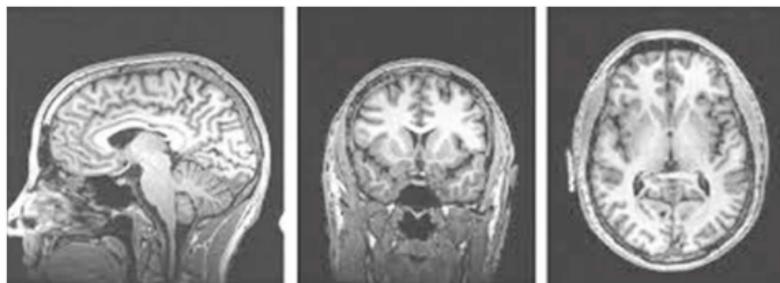
This experiment tries to understand when children develop the ability to predict language. It consists in presenting congruous (e.g. *pizza was too hot to eat*, in blue) or incongruous (e.g. *pizza was too hot to sit*, in red) sentences.



Here we see the ERPs from a single sensor (the PZ one). We can notice the time point where the two functions diverge is when the word is processed by the brain (so we can understand how much it takes for a word to be processed).

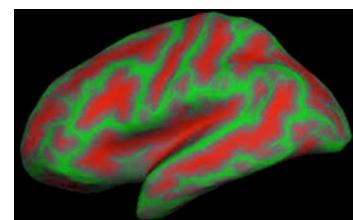
1.2.3 Structural imaging

Structural imaging involves collecting 3D images of the brain, similar to the images obtained in a medical setting.



This type of imaging can provide information about various aspects of brain structure, such as:

- Gray matter volume (i.e. the overall size of the gray matter in the brain)
- The density of gray matter in specific regions, which can approximate the concentration of neurons
- Cortical thickness at a resolution of a few millimeters
- Surface area of particular brain regions



Example of cortical thickness map.

Calculation of cortical thickness is usually done by converting the brain's 3D representation to a 2D sheet representation. We can look for correlation (covariance across different people) of structural cortical thickness between different areas of the brain.

1.2.4 Functional magnetic resonance imaging (fMRI)

Functional MRI is the method that helped most in understanding how the brain works. It consists in observing which parts of the brain are involved in **metabolic activity** when we do things like thinking or perceiving ▲.

fMRI uses a big magnet to affect protons in the brain and then measures how they behave as they return to their original state (areas that are involved in oxygen consumption have a different relaxation profile). By analyzing the patterns of proton behavior, we can identify which brain areas are more active during certain tasks. This method gives us very detailed information about where activity is happening in the brain and can help us understand how different regions contribute to complex processes like thinking and perception. With fMRI we get a time series for each **voxel** (typically a $3 \times 3 \times 3$ mm brain region).

- ▲ In neurology, metabolic activity is often used as a proxy for neural activity: active neurons require more energy to function and can increase their metabolic rate.

In our brain there are 60 to 70 thousands voxels. By chance (statistics) we will surely get some false positives. For this reason we undertake many experiments.

fMRI in an experimental context

The **signal** is defined as the measurable response to a stimulus.

In statistical detection theory we:

- understand relationship between stimulus and signal;
- describe noise properties statistically;
- devise methods to distinguish noise-only measurements from signal+noise measurements, and assess the methods' reliability.

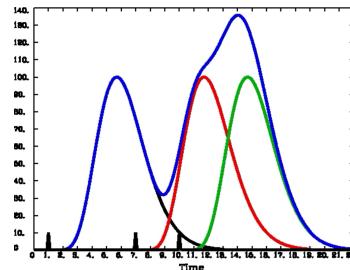
Stimulus-signal connection and *noise statistics* are complex and poorly characterized. We devise, a priori, a **mathematical model connecting stimulus** (or “activation”) **to signal** (typically a regression model). We make an estimation of the **statistical model for the noise**, taking into account whether it is random, structured, oscillatory, etc. These two models are then combined to produce an **equation for measurements given signal+noise** (also often a regression model). The final result is an equation with few **free parameters that can be fitted to the data**.

fMRI analysis often fits a (convolved) activation model to **each voxel's time series separately** (*massively univariate analysis*). Pre-processing techniques are applied to reduce noise, including spatial smoothing across nearby voxels. The outcome of model fitting is a collection of parameters estimated from each voxel's data. The Activation Amplitude (Beta) is the most critical parameter, and it is related to the correlation between the model and activity. At the group level, the **voxel-level estimates are pooled together to reach a group-level conclusion per voxel**.

fMRI measures changes in neural activity, there are no absolute magnitudes. The baseline signal level in a voxel does not provide information about neural activity. An experiment using fMRI requires at least two conditions to detect changes in neural activity. Minimally, experiments use a “task” and “rest” condition. In such a two-task experiment intermixed with rest, a Beta value is estimated per task, and their values are contrasted to determine the difference between the two tasks.

Hemodynamic response function (HRF)

The response measured by fMRI (called “Hemodynamic” because it is related to blood) is delayed since the blood requires time to flow. Notice this is not a simply shifted impulse response, as it is a smooth function. For this reason, fMRI tells us **where** the process takes place, but not **when**. Combining fMRI and EEG can be a solution.



1.2.5 Diffusion weighted imaging (DTI)

Diffusion weighted imaging (also known as **Diffusion MRI** or **Diffusion tensor imaging**), is used to examine the structure of **white matter fibers**. For each voxel, the preferred **direction** of diffusion and the **strength** of diffusion are estimated to determine white matter tracts. These connections are considered *hardwired* connections. They can be cross-referenced against functional connectivity.

Chapter 2

Overview of ML approaches to modeling cognitive neuroscience data

In this Chapter we have two papers on the topic of **cognitive neuroscience models**.

2.1 *Analyzing biological and artificial neural networks: challenges with opportunities for synergy?* Barrett et al. (2019)

Deep neural networks brought a revolution in the area of ML, with millions of parameters, no engineered features, and very high performance. We can see an **analogy with neuroscience**, as both fields need to:

- understand how neural networks, consisting of large numbers of interconnected elements, transform representations of stimuli across multiple processing stages to implement a wide range of complex computations and behaviours;
- describe and analyze very high dimensional data.

The analogies appear in four areas: Receptive fields, Ablation, Dimensionality reduction, and Representational geometries.

2.1.1 Receptive fields

Neurons in the human visual cortex are **specialized to process stimuli in specific spatial areas** (see ◇ Retinotopy map) **or certain types of features**. The neurons in the **initial processing** regions of the visual cortex have **small receptive fields**; sensitive to stimuli in small areas of visual space. As information is transmitted to **higher level** areas of visual processing, **receptive fields become larger**, enabling sensitivity to larger areas of space. These regions also encode more complex features, and there is evidence of “abstract” coding with invariance to small transformations. There are “**concept cells**” **sensitive to identity** of objects but **not to appearance**. For example, simple “repetition priming ▲” effect repeated exactly with same face but different orientation.

▲ Repetition priming refers to the change in responding to a word or an object as a result of a previous encounter with that same item, either in the same task or in a different task.

(Some) AI researchers also think that **DNN neurons may code for specific information**, which can be studied via receptive field analysis.

Some experiments investigate which types of images maximally activate a neuron. Other studies examine how receptive fields change in deeper layers (as we go deeper in the network, each element in the feature map is occupying more space in the visual field, through pooling, but *in what way are larger receptive fields more complex?*).

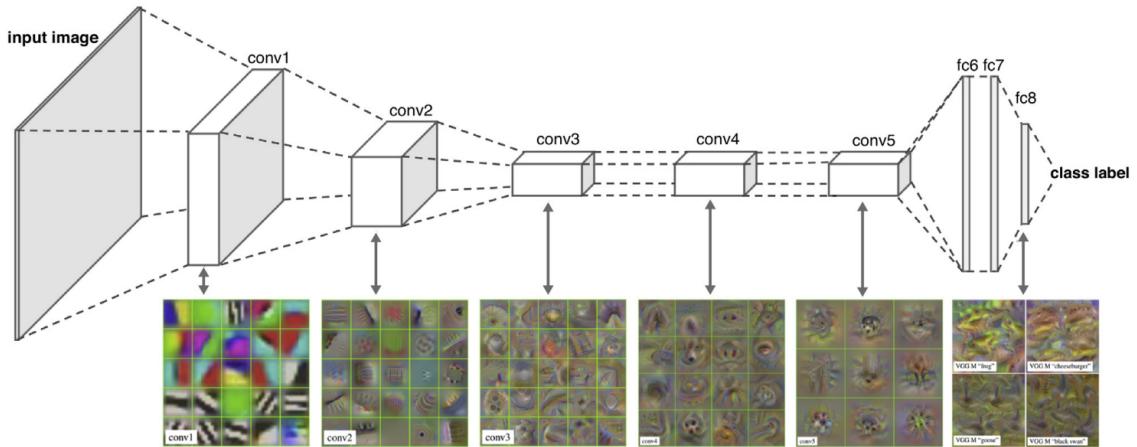
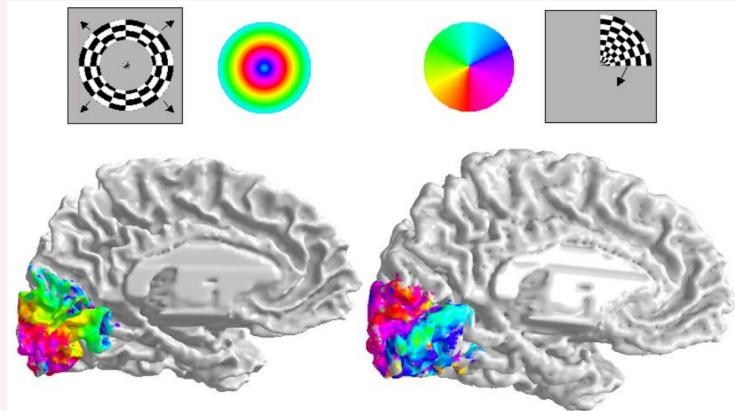


Figure 2.1: Top: how an input image is progressively processed by a CNN. Bottom: receptive fields for each layer are calculated using activation maximization (i.e. take an already trained CNN and create stimuli that produce the maximal activation in a given feature mapping in the network). For each layer, a single square corresponds to a feature map. We can notice conv1 (the first layer) encodes large scale information; some shapes (e.g. circles) start appearing as early as conv2.

◆ Retinotopy map

The **occipital cortex (visual cortex)** is devoted to image processing. They found out that the coding in the brain is along two dimensions: **eccentricity** and **radial degree**. It is possible to get a map of such coding by applying fMRI to a relatively simple experiment:



Focus first on the experiment on the left. The person is looking at the center of the shape. While looking, the shape changes according to a defined temporal pattern (shrinking and expanding with a certain period). If there are neurons caring for a certain distance from the center, then they should fire at determinate time points. This is indeed the case, and we can track which neurons code for a certain eccentricity (we use colors to represent eccentricity). The experiment on the right is quite similar: while the person is looking at the center, the shape rotates around it.

Different people have almost all the same coding, and it is interesting to note how there are no “jumps” in the coding.

A similar thing can be done with the **primary auditory cortex**, in the **temporal lobe**, to get a **tonotopy map**.

2.1.2 Ablation

Brain lesions (ablations) offer much information about potential function of brain areas. By mapping lesions to symptoms, we can understand which brain areas are important for given tasks.

Pruning and ablation causes performance deficits. However, thanks to neuroplasticity, the human brain can achieve again the same performance.

Speaking of artificial neural networks, the debate in the last years has seen three thesis on how DNNs encode information:

- distributed information (meaning we can remove some parts without hardly impacting a single task),
 - local encoding (meaning some neurons are super specialized and don't share encoding information),
 - Modularity theory: not each single neuron is necessary, but some modules (groups of neurons) are necessary for specific tasks.

We ask ourselves, how do artificial neural networks change after ablation? The ablation (lesioning) analysis is applicable to DNNs. We can *silence* neurons and observe how this impacts the network output. Silencing of neurons is done via **structural pruning** (entirely removing a neuron with all its outgoing weights). Networks trained for generalization (out of sample prediction) are more robust to ablation than those trained on memorizing labels. Pruning and fine-tuning are active areas of research.

2.1.3 Dimensionality reduction

The brain codes information in a distributed manner, necessitating multivariate analysis:

- Multiple units encode information in the brain, leading to **redundancy** where two neurons may fire almost identically; or
 - Information is coded in a **distributed** manner among multiple units (e.g. coding for 4 classes among 2 neurons, each coding {0, 1}); or
 - **Correlation** among units could indicate that the **activity can be described in a lower dimensional space**.

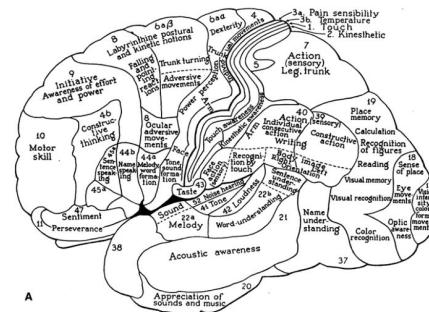
It has been shown that, in DNNs, an object-by-feature matrix from fully connected layer can be **compressed by more than 80%** (e.g. from 4096 dimensions to 512) while maintaining almost all variance. This means few dimensions are enough to explain differences between images.

2.1.4 Representational geometries

To **understand representations**, we study how they are represented in different layers, how they change over time, and how different embedding spaces are related to each other.

Matrix factorization measures: they are a good starting point to compare matrices and understand if there is some sort of covariance between the two. We compare representations across networks by comparing **object-by-feature matrices**. *Canonical Correlation Analysis* and *PLS correlation* are two different factorization measures, they identify lower-level factors that capture and maximize the correlations/covariance between the datasets (note: these methods can be seen as “supervised” as they re-weight columns in both tables to maximize similarity).

Representational Similarity Analysis: it involves **comparing two similarity matrices**, often constructed from object-by-feature matrices. This yields an object-by-object similarity matrix. Representational Similarity Analysis does not factorize matrices. The principle is: describe how the objects cluster together (in the representational space) according to the matrix. To code for distances between objects, we need a distance matrix; and to get this a distance function is needed (e.g. Euclidean, Mahalanobis, etc.), indeed each row in the object-by-feature matrix is a vector. So we can **turn the object-by-feature matrix into an object-by-object distance matrix** (pairwise distance between objects). For human data (how human represent things), we usually don't get an object-by-feature matrices (we are directly provided an object-by-object matrix), so with RSA we can study the **relationship between human representation and machine representation**.



Kleist's functional brain map. This map is old and partially incorrect, but still interesting.

Linear regression: The machine representation in the neural network (*DNN embeddings*) can be used to predict brain activity (*neurobiological activation vectors*) using linear regression.

2.2 What does the mind learn? A comparison of human and machine learning representations Spicer and Sanborn (2019)

This paper reviews the modern machine learning techniques and their use in models of human mental representations, detailing three notable branches: spatial methods, logical methods and artificial neural networks.

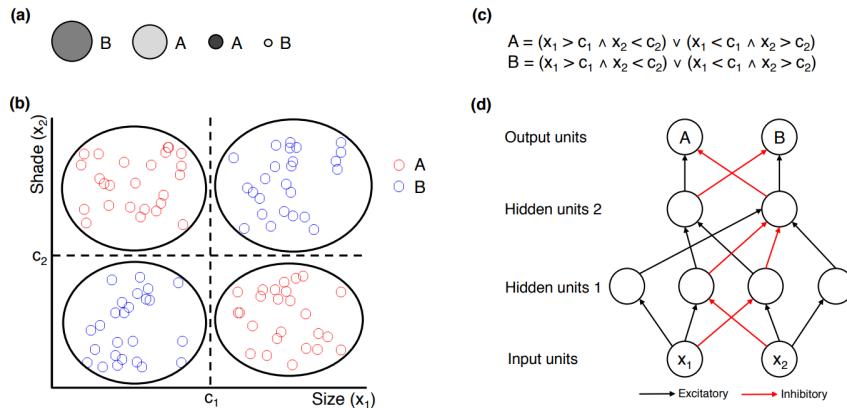


Figure 2.2: Illustration of the XOR classification task using size and shade: examples of stimuli in (a). This problem can be solved by a spatial clustering method (b), a logical Boolean method (c), and an artificial neural network (d).

2.2.1 Spatial methods

Spatial methods involve placing items in a **multidimensional space** and using their location to draw conclusions about **categorization**. Classification based on spatial methods can be determined by an item's location relative to a hyperplane or its similarity to different prototypes (means) or exemplars (centroids):

- **Prototype approaches** assume that learning is based on similarity to the center of a category (mean), which is stored after training (i.e. all examples are forgotten, the prototype only is stored).
- **Exemplar approaches** calculate similarity as a ratio between the similarity of an item to all items within a class (...n) and the similarity of that item to all other items. This provides a fit per class and requires storing item-level information (i.e. all examples are kept).
- **Clustering** organizes items into groups (cohorts), with quality often quantified by the distance between items within and between clusters. Clustering can be either hard (each item belongs to only one cluster) or soft (items can have multiple memberships, potentially fuzzy).

Example of spatial method: Generalized Context Model (GCM)

According to the GCM, the probability that stimulus i is classified into category C_J is found by summing the similarity of i to all training exemplars of C_J and then dividing by the summed similarity of i to all training exemplars of all categories:

$$P(C_J|i) = \frac{\left(\sum_{j \in J} s_{ij}\right)^\gamma}{\sum_K \left(\sum_{k \in K} s_{ik}\right)^\gamma}$$

2.2.2 Logical methods and Artificial neural networks (ANNs)

Logical methods: concepts are based on a definition that is applied to the features of the object. One viable solution is searching for rules that maximize discrimination between stimuli; the rules can be probabilistic (i.e., the rules, if not given, can be automatically computed/learned).

ANNs: do not make assumptions about the representations involved, but offer an implementation method.

2.2.3 Thoughts

Asking which model is the most accurate might be misleading: the answer depends on what area of science you work in. Therefore it is better to focus on whether a model offers “useful explorations of the ways in which human learning operates”. The value depends not just on match to human behavior, but whether there is a need to understand the underlying representations. We have to consider **not just accuracy**, but **also confusion**. Today, very large emphasis is put on **explainability**: we want to explain the model behaviors (for naturally explainable models). And if it is not naturally explainable, we need to address this issue.

Chapter 3

Psychology of concepts and categories

In this Chapter we discuss about categories in sensation/perception (non-semantic categories, Section 3.1) and conceptual structure (words and concepts, Section 3.2).

3.1 Categories and categorical perception

Categorical perception is the phenomenon in which people perceive stimuli from different categories as more different from each other than stimuli from within the same category. This is useful as it introduces invariance in response with respect to a functionally defined category, allowing for rapid prediction, efficient memory, and compression.

How we know categorical representation exists

A demonstrating experiment consists in:

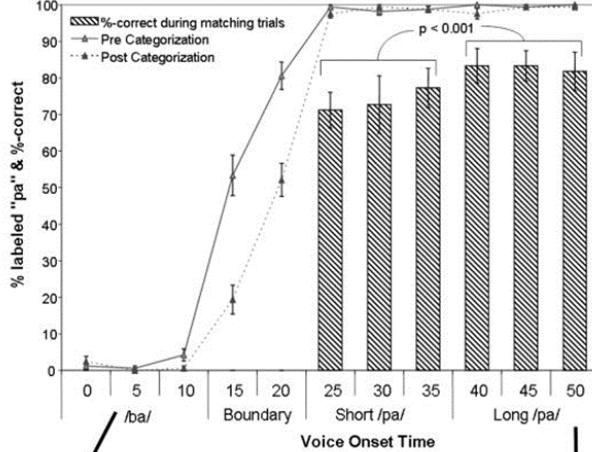
- selecting a set of stimuli that uniformly covers a certain physical domain (e.g. sound freq 100Hz-8000Hz),
- select an objective distance measure so that the space is partitioned in intervals; e.g. distance in frequency space (applicable to both sounds and colors),
- select a method for operationalizing human similarity (e.g. similarity judgments, generalization, confusion [same/different]),
- in one procedure, assign all stimuli to categories (e.g. assign all stimuli to color names); in a second, obtain similarity judgments for within-category vs. between-category pairs, or ask for categorization, and evaluate if the boundary is fuzzy or not (e.g. how much objects are considered similar when belonging to the same category, and when to different categories)

3.1.1 Categorical perception in audition

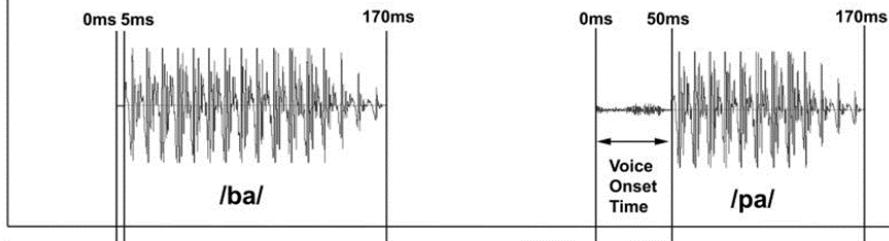
In auditory stimuli, there is discrimination between speech sounds. People have a sharper discrimination boundary between sounds that are perceived as belonging to different phonetic categories than between sounds that are perceived as belonging to the same category. For experimenting, we use as objective dimension the **Voice Onset Time** (VOT) of consonants (i.e. the timespan between the start of the consonant and the start of sound emitted by vocal cords). The discrimination performance is simply a “same/different” judgment. We present consonants such as /b/ and /p/. A fixed-size physical difference in VOT, that is easily discriminated when it straddles the boundary between two categories (labeled as /b/ or /p/), produces *chance* discrimination performance when both tokens come from the same category (either both /b/ or both /p/); results are in Figure 3.1.

Within phonetic category, two different stimuli sound the same (see ◊ Eimas et al. (1971)).

(A) Psychophysical Properties of the /ba/ to /pa/ Syllable Voice Onset Time Continuum



(B) Auditory Waveforms



(C) Spectrograms

Figure 3.1: For the experiment, they created a range of stimuli with VOT between 5ms and 50ms (which are the standard values for respectively /ba/ and /pa/). In **(A)** are the results, with the percentage of responders hearing a /pa/ sound. We see the shift is between 10ms and 25ms

Prior categories aid online processing via categorical perception, in a sort of *experience-dependent learning*; related phenomena are:

- *Change deafness*, Vitevitch (2003): participants repeat words presented by a speaker. Halfway through study, the speaker changed. Only 40% of participants noticed the change.
- *Sine-wave speech*: phonetic categories/expectations can be considered *priors* on sounds, impacting whether a stimulus is perceived as speech (e.g. if you previously listen to a voice and then hear a sound which is not speech, but has some correlation to the previous voice, you can “hear” the words¹).
- *McGurk Effect*: the categorization of sounds is not only an auditory task, since our brain combines multimodal inputs (e.g. also from vision²).

¹<https://users.sussex.ac.uk/~cjd/SWS/>

²<https://www.youtube.com/watch?v=PWGeUztTkRA&t=49s>

◆ Eimas et al. (1971)

They observed 4-month old sucking rate on pacifier (notice that a higher rate is interpreted as more surprise/interest). They examined the rate as function of relation between current and previously heard stimuli, in particular they presented two stimuli with VOT differing by 20ms. In one condition (labeled “D”) the difference straddled (on two sides of) the border of a phonetic boundary (stimuli perceived as “b” and “p” by adults). In another condition “S” they belonged to the same phonetic category.

See Figure 3.2 for more details.

Brain areas coding for **low-level** representations are **not influenced** by such categorization, while those coding for high-level representations are.

3.1.2 Categorical perception in vision

In categorical perception for color, discrimination of items that cross category boundaries is better (faster, more accurate) than when the items are within the same color category. Notice that color category is **linguistic** ▲. For example, it is easier to distinguish between a green stimulus and a blue stimulus than between two stimuli within the same category (two shades of green), who are **spaced at the same distance**.

▲ Practical note: color differences in terms of discriminability can be equated across between-category and within-category comparisons by using the *Commission Internationale de L'Eclairage* (CIE) values.

Color categories are not universal, and thus **categorical perception depends on language** (see ◇ Robertson et al. (2000)).

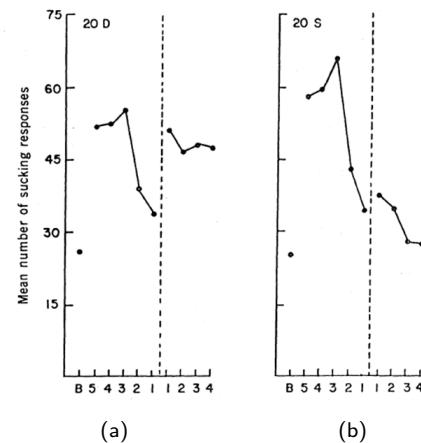


Figure 3.2: 5 min of habituation precede a 20ms VOT change, either within the same (a) or across (b) phonetic category; habituation consists in hearing the /ba/ sound. This proves how 4-month-old children already have the auditory **categorization** enabling them to distinguish between /b/ and /p/ sounds.

◆ Robertson et al. (2000)

The stone-age tribe Berinmo uses “*nol*” as the color name that in English falls under both green and blue, so they have no categorical perception at the boundary between green and blue (no boundary in their language). On the contrary, they have a category boundary between “*nol*” and “*wor*” that does not exist in English as both sides are green. Berinmo people exhibit better discrimination of 32 cross-category items than 32 within-category items at the boundary between *nol* and *wor*. English speakers do not show categorical perception at this boundary.

3.2 Conceptual structure

3.2.1 Theory on words and concepts

The typical approach is to assume that words are associated with concepts or a network of conceptual representations. We need to first have a good theory of what the conceptual structure is like, and then we can see how this structure is used to represent meaning when referred to by words. Ultimately, a word is a sound or written pattern, and it is generally assumed that a single word corresponds to a single concept (this assumption would help with word-embedding models), but there are complications.

There is evidence proving that *form-to-meaning mapping* is not 1-to-1. We encounter **Polysemy**: a phenomenon where a single word can have multiple meanings depending on the context in which it is used, such as “cinema” which can refer to different things in different contexts (e.g. *American cinema is naïve* vs *This cinema is ugly*).

According to Murphy, it is impossible for a single concept to fully capture the meaning of a polysemous word; the process of **meaning extension** is not a result of *natural change* (chaining) but a matter of **online derivation**. Online derivation does not prevent information from also being stored somewhere, at least for a short time, in order to understand the nearby context more effectively. Indeed, Klein and Murphy (2001) found evidence suggesting that the different senses of polysemous words can be stored, as they observed priming effects when a word was used twice in the same sense, and interference effects when the sense was switched.

Another possibility is that a word specifies a set of potentials that is then refined by context to determine which sense is intended.

To put it in a nutshell: **words are not concepts**. Such distinction between *meaning* and *lexical form* is also proven by *anomia*, which is a type of *aphasia* that results in the inability to retrieve the lexical form of a concept for production, even though the ability to recognize or define the term is maintained.

3.2.2 Focusing on conceptual structure

Understanding word meaning requires understanding the organization of conceptual structure in the mind-brain. Concepts represent our knowledge of things in the world and enable us to identify things, infer features, or know how to interact with them. Access to conceptual structure can be achieved through various means, including words, pictures, or music ▲. The study of conceptual structure or “semantic memory” should be independent of what governs word meaning or how word meanings are accessed through language. Much of this psychology work focuses on how people represent categories, with classical experiments focused on artificial, non-linguistic categories to see how people “summarize” those. We will not get into that, but be aware of the link. In much of the literature, concepts are studied by using words, assuming that words map onto conceptual knowledge and are a reasonable “proxy” for studying relations between concepts.

- ▲ Access to conceptual structure is more rapid when people are presented an image, than when presented a word (for the same concept). There are studies showing that music also influences the time of access to conceptual structures.

The classic view of word meaning

In the classic view *word* and *concept* are the same, and the word’s meaning is a **definition**. Definitions are sets of necessary conditions that are jointly sufficient: every object is **either within a category or not** (e.g. *Bachelor = Man, unmarried*). This classical view of *concept structure* (word meaning) implies that there are no different levels of category membership (all members are equivalent to others). It has the advantage of supporting hierarchical structure and inheritance.

3.2.3 Representing the meaning of concepts in the brain

We first introduce **propositional networks**. A concept has a definition (e.g. *Dog: a member of the canine species, that is domesticated*), it can inherit the default features of the parent class (*canine*) and add a few exceptions if non-default. Then the parent classes in the taxonomy are defined (*canine*, then *mammal*, *vertebrate*, *animal*, *organism*, etc.). At the end, some reference to visual features is added.

An example of representation in memory is provided in Figure 3.3, while Figure 3.4 shows a propositional network.

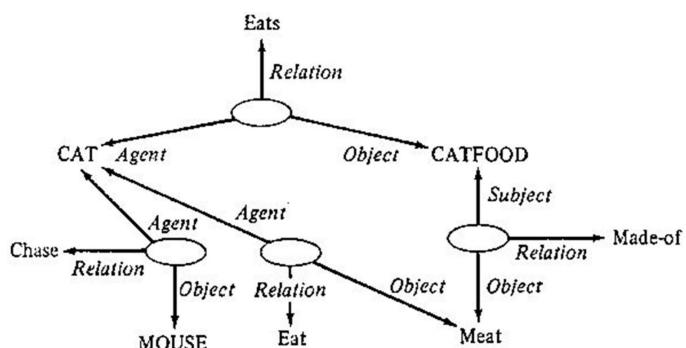


Figure 3.3: A partial representation of “cat” in memory.



Figure 3.4: Propositional network used by Collins and Quillian (1969).

Sentence	Latency
Robins eat worms	1310 ms
Robins have feathers	1380 ms
Robins have skin	1470 ms

Table 3.1: Verification time of affirmative responses. Even though the difference in timing seems to be small, it actually is massive (there are brain processes taking only 5 ms, so 70 ms is a lot). To measure the latency, EEG was used.

Propositional networks as psych model

Collins and Quillian (1969) study of conceptual structure involved **measuring response latencies for statements** such as “Robins eat worms/have feathers/have skin”. The study proposed that **some features of a concept are directly stored while others are inferred through inheritance**. For example, the feature “have skin” can be inferred after traversing three links in the ISA hierarchy: “is bird”, “is animal”, “animals have skin”. On the other hand, “have feathers” can be inferred from a lower level in the hierarchy. The latencies of affirmative responses were expected to reflect this distinction (see the results in Table 3.1). One **question** that the study raises is whether these hierarchies are **pre-represented in memory** or whether they are **formed on the fly** when people are asked questions.

Propositional networks, however, present some problems:

- **Verification time is not solely determined by hierarchical relations**, but is also influenced by the frequency of encountered statements. For instance, “apples are eaten” is verified faster than “apples have dark seeds.”
- The propositional network approach suggests that verification times should increase as the number of ISA links traveled increases. However, people are **faster to verify “dogs are animals” than “dogs are mammals”**.
- The approach expects **clear logical inferences**, such as “if A is a B and B is a C, then A is a C.” But this **assumption has been challenged**. For example, while a car seat is a seat and people agree that seats are furniture, car seats are not considered furniture.

Prototypes

Rosch (1973) proposed an alternative to propositional networks. He argued against the idea of “sets of necessary and sufficient features”, taking the example of “game” (there is no set of necessary and sufficient conditions that is in common to all games. Team? Yes/no. Physical skill? Yes/no etc). Instead, what makes all games “games” is their **family-resemblance** to each other. The **prototypical members are highly similar to other members within the category but less similar to members of other categories** (in a sort of natural clustering, see ◇ Rosch and Mervis (1975)).

Rosch's refutation of "classic view" in psychology has empirical support, as **typicality effects** (i.e. typical reactions of people to stimuli) are evident in:

- **verification times** (e.g. *Robins are birds* faster to verify than *Chicken are birds*);
- **ratings** (people are very systematic in rating whether a certain member is a typical member of a category);
- **generation tasks** when listing members (e.g. for "birds" many more people list *robins* than *chicken*, and for "sports" many more list *soccer* than *weightlifting*).

In conclusions **categories have central and peripheral members**.

◆ Rosch and Mervis (1975)

Family resemblances: Studies in the internal structure of categories

The underlying idea of their study: a prototype of a category is a (hypothetical) member of a category for which all the values are the default or most popular. They first collected feature listing for various items (in different categories), then asked people to rate *how typical* items were of categories, and counted how many category members tended to share features listed. Finally, they analysed **correlation**, finding items that had more features in common with other items in the category were, independently, rated as more typical of the category (they cross-referenced the typicality ratings against the number of shared features). The results are in Table 3.2.

Category	Most typical members	Least typical members
Furniture	13	2
Vehicle	36	2
Fruit	16	0
Weapon	9	0
Vegetable	3	0
Clothing	21	0

Table 3.2: Number of attributes in common to five most and five least prototypical members of six categories.

Fuzziness and levels of abstraction

Propositions also have another problem: **fuzzy category boundaries**. Natural **categories do not necessarily have fixed boundaries**. Mcloskey and Glucksberg (1978) showed that people's judgments about category membership differ with typicality (e.g. all agree that *cancer* is a disease and *happiness* is not, opinions differ on *stroke*). Category membership is related to typicality. Edge cases exist, and **people disagree**. Moreover, **people are unsure** (e.g. when asked the same question after one month, 11/30 reverse on "stroke is a disease").

These observations raise a question: Why do we end up with the words we have? We introduce the concept of **levels of abstraction and informativeness**.

When presented an image of a cat and asked what they see, some people will answer *a cat*, some other *a Siamese cat*, or even *an animal*. People likely represent the world at different levels of granularity:

- **Superordinate level (*animal*)**
- **Basic level (*cat*)**
- **Subordinate level (*Siamese cat*)**

People will use the level of abstraction corresponding to the level of discrimination they need. **Informativeness** (i.e. the amount of facts linked to the category) and **distinctiveness** (the extent to which a category differs from other categories at the level) is what makes them useful. The superordinate level lacks informativeness but is distinctive, the opposite of the subordinate level. The basic level has both informativeness and distinctiveness. We do not create a subordinate concept for each item due to reasons of cognitive economy: they maximize information, but without offering much distinction.

Chapter 4

Modeling conceptual organization

4.1 Modeling typicality

Deep Neural Networks Predict Category Typicality Ratings for

Images

Lake et al. (2015)

They evaluate deep convolutional networks trained for classification on their ability to **predict category typicality** (human typicality ratings), and try to understand whether deep learning systems can serve as potential cognitive models.

4.1.1 Background

The motivation is that, for any task that requires relating an item to its category, **typicality will influence performance**, whether it is the speed of categorization, ease of production, ease of learning, usefulness for inductive inference, or word order in language.

CNNs learn categorization, but **perhaps they categorize by learning prototypes**, i.e., they produce representations that track categorical structure with typicality structure.

4.1.2 Methods

They asked people to rate a collection of images for category typicality (images drawn from 8 image categories), and tested different CNN architectures on their ability to predict these ratings.

Behavioral experiment

Each participant rates “how well does this picture fit your idea or image of the category”. Mean typicality per image is computed across all splits. Human reliability ratings have good split-half correlation: the average reliability of human ratings across random splits is $\rho = 0.92$. This confirms that two groups of people produce similar rankings ▲.

- ▲ This is required to know if we can trust human ratings (i.e. *is human behaviour reliable enough to predict itself?*). If we could not trust human data, there would be no point in aligning the model output to human ratings.

Computational experiment

They use 3 CNN architectures (but for the sake of simplicity *OverFeat* only is described). After the convolutions, the next two layers have 3072 and 4096 fully-connected units, respectively. Finally, a 1000-way softmax layer produces a probability distribution over the $j = 1, \dots, 1000$ classes. They get a top-five error rate of 14.2% ▲.

- ▲ Top-five error: the correct label did not appear in the top five guesses.

4.1.3 Estimating image-typicality

They assume that (human) **typicality is related to the strength of the model’s classification response** to the category of interest. The **classification strength** can be estimated in two ways:

- **Raw typicality:** This is a raw category score. There is a theoretical vector (input of last layer) which **maximizes the activation** of a particular category. Images with representation very close to this theoretical vector are expected to be more typical. So we can maximize y_j to get the particular abstract representation for each category j :

$$y_j = \sum_{i=1}^{4096} w_{ij} x_i$$

- **Contrast typicality:** It measures to what extent the correct category is more active than the others. It benefits images that load on the correct category much more than on other ones. The most typical image produces y_j that is most differentiated from other categories' response to this image. This is independent from the raw value:

$$z_j = \frac{e^{y_j}}{\sum_{j=1}^{1000} e^{y_j}}$$

The values computed for each j are averaged, then they check for correlation with human ratings.

4.1.4 Results

They found that raw and contrast scores do similarly well, and that some models have significant human-machine typicality correlation. This suggests that deep CNNs learn **graded categories that can predict human typicality ratings**, at least for some types of everyday categories.

However, when dealing with hidden layers, one cannot have categories' activations, so they needed to redefine typicality. They used 1300 images (of the same category) as input for the network and averaged the activation of the given layer over all images to get the **category prototype** (typical activation vector). Typicality was modeled as the cosine distance between the activation vector for a new image and the stored prototype. They found better prediction in deeper convolutional layers (see Figure 4.1), i.e., by going deeper (closer to the output layer) the layer representations predict increasingly better human typicality.

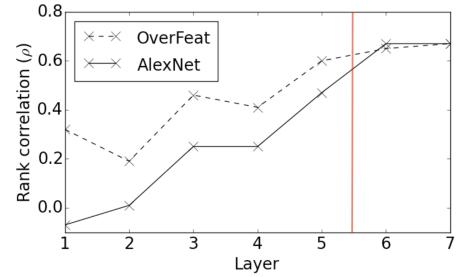


Figure 4.1: Correlation between human and convnet typicality ratings as a function of network depth. The red line indicates a transition from convolutional (1-5) to standard layers (6-7).

4.2 Words-as-features as models of cognition

Predicting Human Brain Activity Associated with the Meanings of Nouns
Mitchell et al. (2008)

They try to answer this question: Can feature models explain behavioral and brain responses? The underlying idea is to understand how/where word meaning is stored in the brain, under the assumption that our brain represents words as features. Notice: this assumption is not necessarily true, there might be also other possibilities (not tackled in this paper).

4.2.1 Background

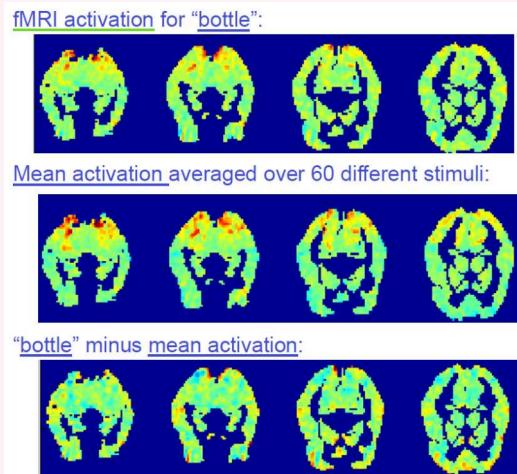
Core questions for neuroscience are:

- Are there systematic differences in neural activity as people think about different concepts?
- Is the neural representation of concepts localized in specific brain areas or is it distributed across the entire cortex?
- How meaningful are individual differences, or is the *representation of meaning* similar across people?

We ask ourselves if fMRI and neuroscience allow us to *test* or *understand* what are the **basis functions** (the **semantic feature** space) that underlie the representation of words. This can help in designing more cognitive real computational models.

Historical approach

We present multiple words sampled from several categories (e.g. tools, buildings), and then train a classifier that predicts the class (tool/building) from the brain images of the words. Brain images are taken with fMRI: see the figure, which shows activation maps from fMRI data (each of the 4 images in a row represent a slice of the brain). A classifier can be trained using a single voxel. The results of the classifier can be used as a tool for studying the semantics in the brain. For instance, we can understand which brain area contains information about particular classes. This is a pure *decoder*; there is no domain-based knowledge that is applied to predict the brain response from more basic principles.



Classifiers capture some meaning, as they show **cross-domain generalization** (train on words, guess class of image). They collected brain activity while people watched an image (instead of the word), and while Portuguese (instead of English) people watched the same words. They then took the classifier trained to discriminate categories based on brain responses to words presented in English and tested on brain activity from those other domains. Both *testing on pictures* and *testing on other language* produce above chance accuracy: **semantics generalize beyond modality used**.

The historical (decoding) approach works, but has a problem: **data is highly dimensional** (over 20 thousand features/voxels per word). At the same time, however, **data is also sparse** (only few examples of brain activity per category). This is difficult from a regression perspective and solutions to this (regularization) are mathematically valid but may lose information about the brain. These considerations sparked Mitchell et al. (2008) to propose an alternative.

4.2.2 Generative encoding model

Their proposal is to **come up with a theory of word meaning and see whether the theory predicts brain activity (activation)**. They capture “word meaning” from corpus statistics (from mutual constraints appearing in corpora). The challenge is basically to find a “mapping function” from word meaning to brain activity.

The model works in two steps. The first step encodes the stimulus word. The second step predicts the neural fMRI activation at every voxel location in the brain, as a weighted sum of neural activations contributed by each of the intermediate semantic features. A schematic explanation can be seen in Figure 4.3.

Define word meaning

We mentioned that they captured word meanings via corpora exploitation. They use 60 **nouns**. Each noun j is described using 25 **features**.

Semantic feature values: "celery"
0.8368, eat
0.3461, taste
0.3153, fill
0.2430, see
0.1145, clean
0.0600, open
0.0586, smell
0.0286, touch
...
...
0.0000, drive
0.0000, wear
0.0000, lift
0.0000, break
0.0000, ride

Figure 4.2: Example of feature vector.

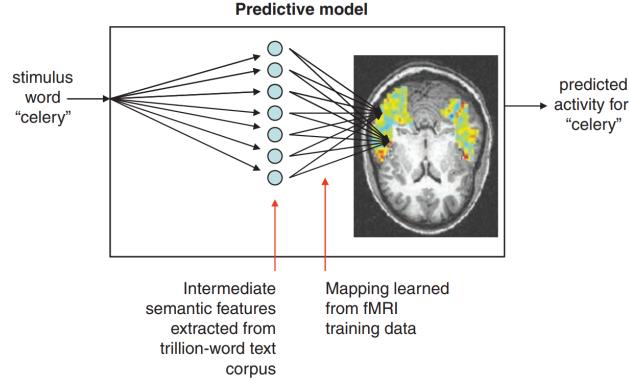


Figure 4.3: The predictive encoding model. Each word gets a vector of n features (in this simplified schema just 7); the value of n has to be chosen as it is a hyper-parameter. Note: there is no single step prediction for the whole brain. The prediction is done for a single pixel, i.e., we get a weight vector for each voxel. Then all pixels are put together to get the whole map.

Feature i is defined as the **co-occurrence frequency of the stimulus noun with the verb i** . They chose verbs which are either: *sensory*, *motor*, or *abstract* verbs. An example of the resulting semantic features is provided in Figure 4.2.

Single-voxel analysis

They perform a single-voxel analysis. For each voxel in the brain they learn the relation between voxel activity values for the 60 nouns, and the semantic features of the 60 nouns ▲.

Such analysis can tell, **for each voxel, what is the relative importance of each of the 25 features** when it comes to predicting brain activation. To show generalization, they train the model with 58 words and test on the remaining 2.

In matrix notation the multiple regression model is $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$, where:

$$\mathbf{Y} = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix}, \quad \boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}, \quad \boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & X_{11} & \dots & X_{1k} \\ 1 & X_{21} & \dots & X_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & X_{n1} & \dots & X_{nk} \end{bmatrix}$$

\mathbf{Y} is the activity for the 58 nouns in the voxel; $\boldsymbol{\varepsilon}$ is the bias; $\boldsymbol{\beta}$ are the 25 weights to be fit; \mathbf{X} is the set of 25 feature-value per noun ($n = 25, k = 58$).

- ▲ To be precise, they present stimuli of noun+image together (but for the sake of simplicity we refer to them just as “nouns”).

Predicting word activity in each voxel just means multiplying its semantic feature values by learned weights (Figure 4.4).



Figure 4.4: Predicting fMRI image for given word.

4.2.3 Results

They tested the model by predicting activity for word A, and checking if it is more similar to true activity of word A than it is to the other word B (where A and B are the two left over words, not used for training). They got an average accuracy of 0.79, suggesting that word meanings are indeed **represented as features in the brain**.

They also examined, for each of the 25 features (verbs), the importance across the brain, to obtain a map of which brain areas are the most important for a given verb (and therefore for a given activity, see Figure 4.5a).

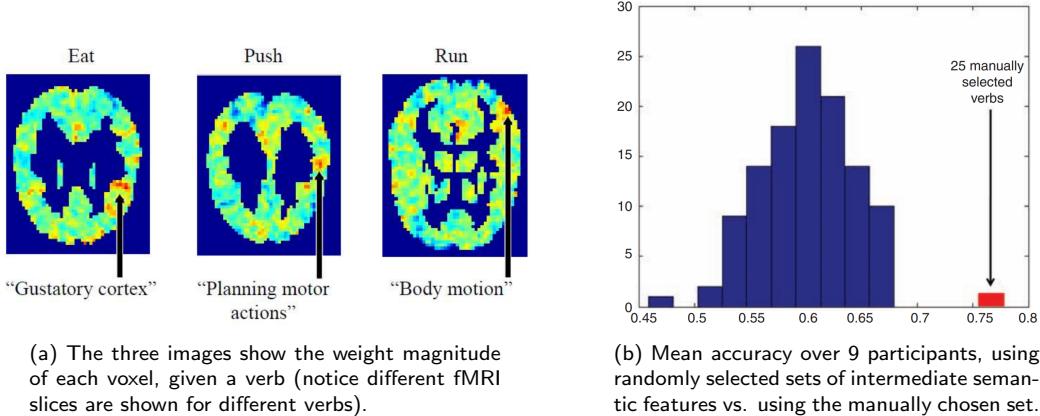


Figure 4.5: Results.

Furthermore, they performed a *by participant* analysis that allowed them to account for inter-individual differences. They split the brain into areas and swept through a very large number of words (10 thousands) to see **which word maximally activates that region** (or the entire brain). They found there are indeed words that are most activating for specific brain areas.

In the end, they experimented with **random 25-feature-basis** sets, instead of a manually chosen set. They tried with 115 randomly selected sets (composed not only by verbs), finding that the results are much worse, yet with **significant accuracy** (> 0.61 , see Figure 4.5b).

4.3 Studying representations via similarity spaces

Matching categorical object representations in inferior temporal cortex of man and monkey
Kriegeskorte et al. (2008)

In this section we see how they model similarity spaces expressed in human behavior and brain responses.

4.3.1 The principles of Representational Similarity Analysis (RSA)

To compare if two clustering representations are similar, a possibility is to pick single elements, and check if the neighbors that are part of the same cluster in a representation, are part of the same cluster also in the other representation. This idea coming from statistics is exploited in RSA. RSA relates modalities of human behavior (or brain activity measurement) and information processing models by **comparing activity-pattern dissimilarity matrices**. A single similarity-matrix captures *first-order* similarity between stimuli (either similarity in brain response, or similarity as computed by a model). **RSA is a 2nd order similarity** because it quantifies how alike two similarity-matrices are. RSA:

- is modality independent: it allows to compare completely different modalities, provided we can measure similarity or distance between pairs of stimuli;
- can relate whatever modality of brain or behavioral measurement to information processing models;
- is based on the notion of similarity, or distance, between stimuli.

4.3.2 Applied contexts for RSA

A **Representational Dissimilarity Matrix (RDM)** of **human behavior** is shown in Figure 4.6a. We can see how objects in the same category are judged to be similar (as expected). Such matrix can be populated either by directly asking pairwise similarity to people, or via item sorting task: given randomly placed objects, people are required to sort objects in an array with similar objects close one to each other.

An RDM can also be constructed on **brain data**. Figure 4.6b shows how it is populated: we consider how much each group of voxels is related to input stimuli. We can then compare the similarity matrices as in Figure 4.7.

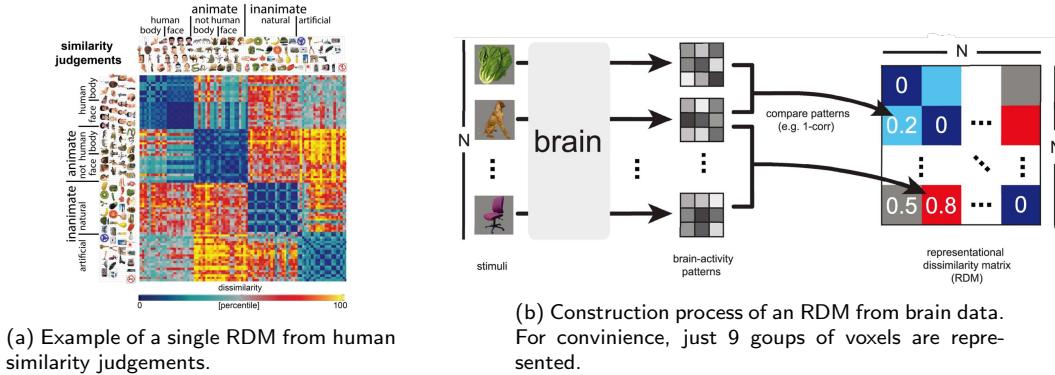


Figure 4.6: Examples of RDMs.

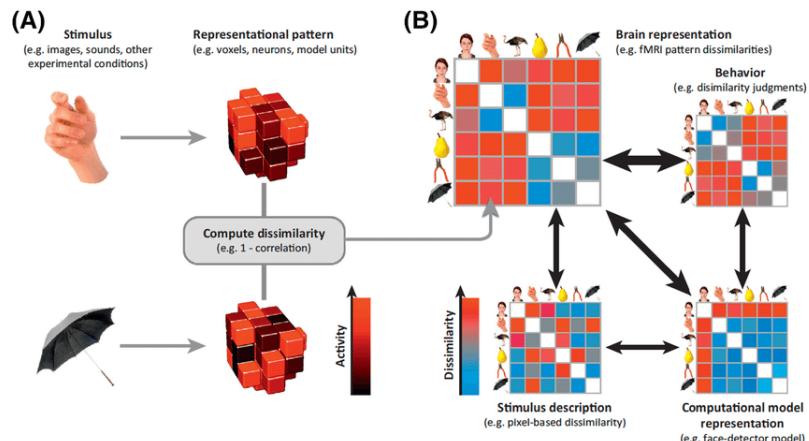


Figure 4.7: Example of comparing RDMs, with 2 stimuli and brain response. (A) First-order RSA: differences between patterns of activity in a chunk of tissue responding to two objects, here a hand and an umbrella, populate one cell of an RDM in (B). (B) A complete RDM can now be compared using second-order RSA with other RDMs constructed from behavior, input measures, or other models.

Another possibility (Figure 4.8) is to understand what information is coded over time, so that we can check if there is similarity between representations in the brain and in a neural network at the same depth (e.g. comparing shallow layers of the brain with shallow layers of a CNN). MEG data can be split along the time domain into intervals. For each interval, a similarity matrix is computed correlating the activity between images (note that the matrices are not the same, as representation in the brain changes over time). With fMRI data we can do another thing: relate different modalities (different brain areas), discovering that Extrastriate and Inferior temporal fit with the NN.

Moreover, probing for 2nd order similarity across brain regions (not against a model) allows to relate brain and behavior, find areas that code similarly for different stimuli across participants or even species. It also allows to code a single set of stimulus across multiple dimensions and code RDMs at each feature level.



Figure 4.8: Example of comparing similarity matrices. The Noise ceiling is the maximal (ceiling) value expected given the noise in the data. Oftentimes the noise ceiling is estimated as the correlation between the estimates of the responses in two independent repetitions of the same experimental procedure. The idea is that the ability of X to predict Y cannot exceed the noise ceiling, defined as the correlation between Ys (Y_1 and Y_2) obtained for the same stimuli on 2 different test data.

4.3.3 RSA and loss of dimensions

When using Human Similarity Judgments, we create an RDM directly from those judgments (we do not have the features). When using NeuroBio data to produce RDMs we use an $S \times V$ (stimuli/observation \times voxels/sensors/regions) matrix. When using Computational Models to produce RDMs we use an $S \times F$ (stimuli/observation \times features) matrix. When relating NeuroBio and Computational models the $[S \times V]$ and $[S \times F]$ matrices are first converted to RDMs. Consider you can get the exact same RDM from different $S \times F$ matrices that differ massively on the number of F . This means that when we convert to RDMs **we do not have specific information on dimensions that produce the alignment**. **This is the main drawback of RSA**. For instance, in the case of Mitchell et al. (2008), we get an RDM with shape $[60 \times 60]$, so we lose the dimension of the 25 verbs used to compute word representations. However, the main problems of methods that keep information of the features are that they are unstable and very complicated to understand or to implement.

When dealing with 2 domains (brain, model) represented as observation \times feature matrices, and when the two matrices reflect the same feature, we could evaluate the fit directly at the matrix level. There are many different techniques that probe for strength of common dimensions between two matrices.

Digression

The following techniques all probe for strength of common dimensions between two matrices:

- Procrustes rotation: it takes N objects in D features, and tries to find a transformation to map one into the other, see image;
- Principal component regression (i.e., supervised PCA);
- Partial least squares correlation: similar to PCA, but it tries to maximize the correlation on both tables;
- Canonical correlation analysis.

4.3.4 Univariate and multivariate approaches

In the following we consider already seen topics, but from a different perspective.

Information contained in multiple voxels

The typical approach of fMRI is massively multivariate, since it considers one voxel at a time. The problem is that information contained in multiple voxels is lost.

For this reason they studied brain responses during narrative comprehension: some participants were required to focus on space, others on time, others on actions, hearing the same story. They considered each IFG sub-region as a “voxel”. With an univariate approach, regional activity in *pars opercularis* (see Figure 4.9) was higher for some conditions, while *pars triangularis* responded always with the same level of activation for the different dimensions. In a multivariate approach, they considered the entire set of values in each region, and quantified how similar those activity patterns were for the three conditions. Instead of considering the whole area (*pars triangularis*) by averaging, they kept voxels separated and found very different activations when focusing on different dimensions.

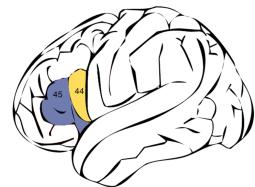


Figure 4.9: Pars opercularis (yellow) and pars triangularis (blue).

Decoding category (binary case) from brain

A multi voxel pattern analysis (MVPA) can be carried out. Two conditions are presented, which produce different distributions of activity across trials. In Case 1, each condition produces different activity levels, in both Voxel 1 and Voxel 2. Clearly, the region discriminates the classes. In Case 2, each condition produces highly similar mean activity levels in both Voxel 1 and Voxel 2. So one might conclude that the region does not discriminate, if aggregating across univariate analysis. But the multivariate analysis leads to a completely different result, allowing us to better understand: the region containing voxels 1 and 2 **contains information about conditions in the joint distribution** of Voxel 1 and Voxel 2.

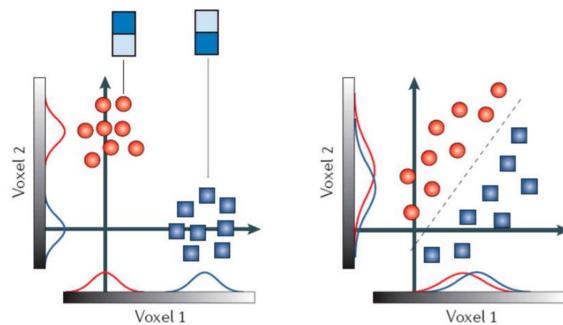


Figure 4.10: Case 1 on the left, Case 2 on the right. Each trial is represented as a circle or a square (depending on its category).

Chapter 5

Modeling human representational geometry

From a historical point of view, the success of RSA brought to many studies on ablation, plasticity, etc. Many researchers used it, but they started questioning whether it is a good model of human knowledge. In the following we are discussing different assumptions, in respect to artificial DNN.

5.0.1 Background

We have already seen in Chapter 3 the most accepted representation of concepts, as categories, in psychology: semantic domains or categories (e.g. mammals, animals, dogs) are organized via features or dimensions that carry the relevant variance for the category (Classical view, Rosch and Mervis (1975), Lake et al. (2015)). We have also seen how we can have typicality effects in AI: entities (e.g. images, words) are described by feature values from which representational category effects emerge.

We can use AI systems as models of semantics (Section 4.3): AI systems trained for image categorization or word embedding produce representations that reasonably approximate those of humans. Similarity between categories, as operationalized from human data, is well predicted by distances between objects in the AI model, where human similarity is quantified using brain/behavior and model similarity is quantified via Euclidean distances, inverse cosine, etc. For prediction of human similarity judgments on images, they found 20 to 60% of the judgments is modeled by the NN. While in MVPA the results are more complicated: these can predict activation in brain areas, but the correlation is just barely above the significance threshold.

5.0.2 AI modeling of human representations

Modeling human representations with AI is useful for many fields:

- Psychology: AI models achieve human-like competence on different tasks. Because of their competence, they offer a **model of potential knowledge organization**. They can also offer **interpretability of human behaviour**: if we have an AI model that behaves as humans, we can study it to come up with valid hypotheses.
- Engineering: better prediction of human behavior, and improved AI-human alignment. For instance, to evaluate how good generated images are, similarity metrics are used. However this does not take into account the subjectivity of human brain.
- Computer science: understanding representations in neural networks.

There are three approaches:

- **Default: use all DNN features** (all in the whole network, or all in a particular layer) as object-representation for modeling human data. This implicitly assumes that all features are relevant and equally important, for the alignment, for all concepts.
- **Reweighting: keep all features, but adjust the weights by finetuning**. It addresses mis-calibrated, human-relevant features by applying concept-specific adjustment of feature saliency for modeling human representations. This assumes that AI learns human-relevant features, but these are mis-calibrated.

- **Pruning:** keep the weights unchanged but remove some features, investigating modular structures in AI models. This assumes that the network develops a modular structure where information about different categories is represented in different subspaces (subsets of latent dimensions) within the model, i.e., knowledge about particular categories or concepts is stored in particular areas (“modules”) in the AI model.

Default approach

Assuming two objects, U and V , each with 3 features, **human similarity** can be defined using the **inner product** (or a related quantity), and approximated as follows:

$$\text{Similarity}(V, U) = V \cdot U = V_1 \cdot U_1 + V_2 \cdot U_2 + V_3 \cdot U_3$$

Note this is just an evaluation (no learning involved).

Reweighting approach, Peterson et al. (2018)

The similarity is defined as the **weighted inner product** (or related measure), where the weights ($W_{1,2,3}$) are learned via regression and evaluated on out-of-sample data.

$$\text{Similarity}(V, U) = W_1 \cdot V_1 \cdot U_1 + W_2 \cdot V_2 \cdot U_2 + W_3 \cdot V_3 \cdot U_3$$

This **involves learning** (via linear regression or other techniques). Learning the weights is far from easy, since the number of free parameters is extremely huge (regularization is needed), as weight solutions are category-specific.

Peterson et al. (2018) proved that this approach generalizes well, outperforming the baseline (default approach), despite this being already high.

Pruning

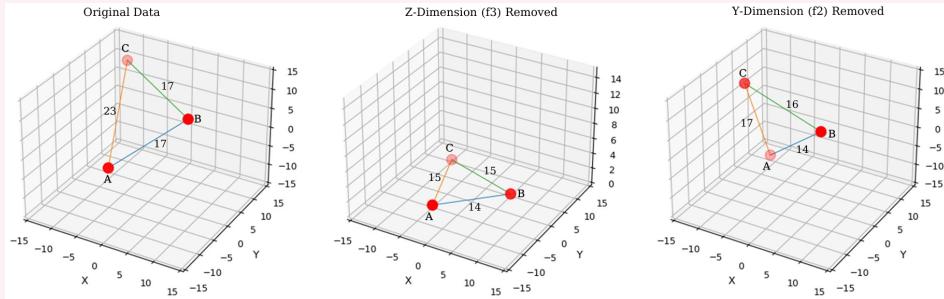
It aims at identifying a **subset of features, per category**, improving prediction of human representations, e.g.:

$$\text{Similarity}(V, U) = V_2 \cdot U_2 + V_3 \cdot U_3$$

Pruning aims to find a subset of features that produces object-to-object distances that best match those produced from human behavior. By iterating over features and using *Sequential Feature Selection* algorithms, supervised pruning learns a subset of features that **better predicts human judgments and generalizes to out-of-sample data**. It is supervised pruning since we are using human similarity judgments to choose which features to prune.

Pruning at work: a toy example

Humans find Tigers more similar to Lions than to Pumas. The model representation is disaligned from human representation (as Tiger-Lion and Tiger-Puma distances are the same in the embedding space of the model). We see that removing Y-Dimension brings the embedding space closer to human representation:



To summarize, pruning:

- improves out-of-sample prediction accuracy for human similarity judgments of images, (higher RSA isomorphism);
- produces a more psychologically valid representational space;
- improves prediction of out-of-sample MVPA data (Brain RDMs).

Moreover, the feature-sets retained by pruning vary depending on the category guiding the pruning process, and these sets identify different subspaces (latent factors) in the feature space. Pruning improves out of sample prediction of human similarity judgments for words and allows an interpretation of latent dimensions underlying word similarity judgments.

◆ Tarigopula et al. (2023)

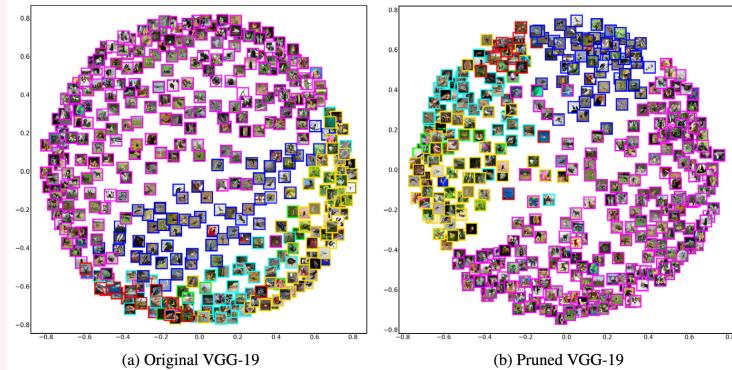
Improved prediction of behavioral and neural similarity spaces using pruned DNNs

They prune a model that learns to predict human similarity judgments within 6 categories, each consisting of 120 images. In particular, they prune the penultimate layer of VGG19, which has 4096 nodes (features), and show that pruning outperforms other methods, including reweighting:

	Animals	Automobiles	Fruits	Furniture	Various	Vegetables
Baseline	0.61 (0.07)	0.51 (0.07)	0.33 (0.08)	0.29 (0.05)	0.43 (0.10)	0.32 (0.07)
PAG18	0.71 (0.09)	0.50 (0.05)	0.25 (0.15)	0.34 (0.08)	0.50 (0.13)	0.27 (0.07)
LASSO	0.64 (0.12)	0.51 (0.08)	0.38 (0.13)	0.37 (0.11)	0.47 (0.12)	0.31 (0.08)
Sim-DR	0.64	0.57	0.30	0.33	0.50	0.30
Pruned	0.75 (0.05)	0.55 (0.08)	0.39 (0.08)	0.38 (0.07)	0.56 (0.1)	0.41 (0.05)
# nodes	807 (63)	647 (45)	563 (76)	557 (101)	830 (44)	605 (190)

The number of nodes refers to how many nodes are retained by the pruning algorithm (e.g. for Animals 807 out of the original 4096).

They then proceed showing how pruning improves representational space for **out-of-sample image embeddings**. They first use a **different dataset** of Animal images and apply MDS (MultiDimensional Scaling); then they repeat but using only feature indices retained from pruning against the original experimental Animals dataset. In this second case, the animal types are better separated in the MDS representation (better clustering).



Pruning also improves representational space for **out-of-sample brain data**. They use a dataset with two independent sets of 144 images. They produce RDMs from brain activity, per regions, then use RDMs to supervise pruning, and test on out-of-sample data, finding the prediction of brain-derived RDMs is improved.

◆ Bavaresco et al. (unpublished)
Continuation of Tarigopula et al. (2023)

They try to understand whether the different feature sets retained by pruning, for each class, are similar; and whether they code for different information. To measure the overlap between the (indices of the) features retained from the different category they use the Dice-Sørensen coefficient:

$$DSC = 2 \cdot \frac{\text{intersection}}{\text{union}}$$

They find the lowest value for $\langle Fruits, Automobiles \rangle$ (0.13) and the highest for $\langle Fruits, Vegetables \rangle$ (0.28). It is not surprising that the highest DSC value is between fruits and vegetables, which are indeed similar. However, in general, the overlap is quite low. They find that just 1 out of 4096 feature is always selected for all 6 categories, meaning that there is not a “core” set of features that is always retained.

To know if the selected features identify different information, they use a different dataset of 50k images. **Images are represented using only activations on the retained features** (6 different versions: 50k×807; 50k×647, etc.). For each of these derived embeddings they **identified the top-5 images that maximize activation on that set of features** (i.e., highest sum by row (in the matrix with inputs in rows and features in columns)). They find that pruning-retained features, per category, are **maximized by images that exemplify the category**. This is consistent with the prototype theory.

To have a more quantitative analysis, they apply PCA to each version (of the 6) and obtain the scores for the 50k images on the first Principal Component (this is needed since the matrices are too large). Then the 50k PC1 scores are correlated across solutions (they get a score for each image). They conclude that **different retained sets select for different latent dimensions** (i.e., PC1 of similar categories encode for similar information).

◆ Manrique et al. (2023)
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Chapter 6

Developing common representations in AI and Humans

In this Chapter we study how human representation and AI representation can be combined, and how brain data can be infused into neural networks.

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