

$$\Phi = -\frac{GM}{\sqrt{R^2+z^2}} \Rightarrow \frac{\partial \Phi}{\partial R} = \frac{GM}{(R^2+z^2)^{3/2}} R, \quad \frac{\partial \Phi}{\partial z} = \frac{GM}{(R^2+z^2)^{3/2}} z$$

Consider small displacements in $R \rightarrow R_0 + \delta R$ & $z \rightarrow \delta z$, at constant specific angular momentum h , about a circular orbit

$$z \text{ eqn } \frac{\partial \Phi}{\partial z} \approx \frac{GM}{R_0^3} \delta z = \Omega^2 \delta z \quad \text{so we get } \underline{\underline{\ddot{\delta z} = -\Omega^2 \delta z}}$$

$$R \text{ eqn } \frac{\partial \Phi}{\partial R} \approx \frac{GM}{[(R_0 + \delta R)^2 + z^2]^{3/2}} (R_0 + \delta R) = \frac{GM}{(R_0 + \delta R)^2} \approx \frac{GM}{R_0^2} \left(1 - 2\frac{\delta R}{R_0}\right)$$

$$R \dot{\phi}^2 = \frac{h^2}{R_0^3} \Rightarrow \frac{h^2}{(R_0 + \delta R)^3} \approx \frac{h^2}{R_0^3} \left(1 - 3\frac{\delta R}{R_0}\right), \quad \ddot{R} \rightarrow \ddot{\delta R} \text{ since } \ddot{R}_0 = 0.$$

$$\ddot{\delta R} = \frac{h^2}{R_0^3} - \frac{GM}{R_0^2} + \left[-\frac{3h^2}{R_0^4} + \frac{2GM}{R_0^3} \right] \delta R, \quad \text{since } h = \sqrt{GM R_0} \text{ for circular orbit.}$$

$$= \left[-\frac{3GM R_0}{R_0^4} + \frac{2GM}{R_0^3} \right] \delta R = -\frac{GM}{R_0^3} \delta R = -\Omega^2 \delta R$$

$\Rightarrow \ddot{\delta R} = -\Omega^2 \delta R, \quad \ddot{\delta z} = -\Omega^2 \delta z \leftarrow \text{SHM motion with frequency } \Omega \rightarrow \text{natural oscillation time} \rightarrow \underline{\underline{\Omega^{-1}}}$