

USB Core for Altera DE-Series Boards

For Quartus II 14.0

1 Core Overview

The USB chip on Altera DE2/DE2-115 board is intended for connecting any USB device or for connecting the board to a computer. The USB Core provides a connection to the on-board USB controllers and presents an easy-to-use communication interface to the USB device.

The on-board USB chip contains the Host Controller (HC), the Device Controller (DC), and the On-The-Go (OTG) controller. The HC and DC share the same data bus, but use different I/O locations. There are two ports and a 4KB built-in buffer on the USB chip.

2 Functional Description

The USB Core's hardware provides a basic connection to the Host Controller and Device Controller ports of the on-board USB Controller. The USB Core's main function is to provide a set of useful software functions for communicating with the on-board USB Controller. These software functions can be easily included into a software program using the Altera Monitor Program or the Nios II IDE.

3 Instantiating the Core in Qsys

Designers can instantiate a USB Core by using the Qsys tool in Quartus II software. There is no need to configure the core.

4 Software Programming Model

4.1 Register Map

Device drivers control and communicate with the USB Core through four 32-bit registers. These registers are directly mapped to the four ports of the on-board USB Controller. Table 1 shows the details for the registers.

4.2 Device Driver for the Nios II Processor

The USB Core is packaged with C-language functions accessible through the hardware abstraction layer (HAL) as listed below. These functions implement common operations that users need for the USB Core.

To use the functions, the C code must include the statements:

Table 1. USB Core register map					
Offset	Register	R/W	Bit description		
in bytes	Name	IX/ VV	310		
0	HcAddr	R	Host Controller Address		
4	HcData	R/W	Host Controller Data		
8	DcAddr	R	Device Controller Address		
12	DcData	R/W	Device Controller Data		

```
#include "altera_up_avalon_usb.h"
#include "altera_up_avalon_usb_ptd.h"
#include "altera_up_avalon_usb_regs.h"
#include "altera_up_avalon_usb_low_level_driver.h"
#include "altera_up_avalon_usb_high_level_driver.h"
```

In addition, some sample functions for specific communication with the mouse are also provided. They serve as a good starting point if the user wishes to develop more features with the USB. To use the mouse communication functions, the corresponding header file, altera_up_avalon_usb_mouse_driver.h, has to be included. These functions are described in Sections 4.7 - 4.11.

4.3 Writing programs using USB device driver functions

General steps for writing a program to communicate with the USB controller are:

- 1. Set up the corresponding controllers and buffers for USB operations.
- 2. Query the USB device and assign addresses to the connected devices.
- 3. Choose a configuration for the device.
- 4. Start transmitting data packets.

Step 1 configures the operational mode of the USB controller. Steps 2 and 3 establish the connection between the HC and the device. Step 4 is the actual data transfer process. All the steps will be further clarified with the example functions shown in following sections.

4.4 Example Program: USB Mouse

A complete example of C code that uses the HAL device drivers is shown in Figure 1. The program displays the x and y locations of the mouse on the red LEDs and green LEDs respectively. It also shows the button status on the HEX displays. A '0' will appear on HEX0 if the right button is clicked, a '0' will appear on HEX1 if the center button is clicked, and a '0' will appear on HEX2 if the left button is clicked.

As shown in the Figure 1, the program first opens the USB device by calling the function <code>alt_up_usb_open_dev</code> (...) in line 4. The argument to be passed to the function should be the USB component name in the Qsys tool prefixed with the string <code>/dev/</code>. In our example, the name of the USB component in the Qsys tool is <code>USB</code>, so the string

included in the function is /dev/USB.

After the device pointer is returned, the program iteratively calls the function alt_up_usb_setup (...) in line 17 to set up a connection between the host and the device. Details about the setup function are given in the Section 4.5. The way we set up the USB controller here may not be optimal, it is a simple demonstration of the USB controller setup process.

Once the program confirms that the connected device is a mouse, it will choose a configuration on the device by calling the function alt_up_usb_set_config (...) in line 22.

Then it calls the function <code>alt_up_usb_play_mouse(...)</code> in line 25 to set up the mouse, and receives the mouse-movement packets. The function is explained in detail in Section 4.6.

```
1 int main(void) {
2
    // 1.Open the USB device
3
      alt_up_usb_dev * usb_device;
4
      usb_device = alt_up_usb_open_dev("/dev/USB");
5
      if (usb_device != NULL) {
6
           printf("usb_device->base %08x, please check if this matches the USB's base
              address in Qsys\n", usb_device->base);
7
           unsigned int mycode;
8
           int port = -1;
9
           int addr = -1;
10
           int config = -1;
11
           int HID = -1; //Human Interface Device Descriptor number.
12
           while (1) {
13
               port = -1;
14
               addr = -1;
15
16
               // 2. Set up the USB and get the connected port number and its address
17
               HID = alt up usb setup(usb device, &addr, &port);
18
19
               if (port !=-1 \&\& HID == 0x0209) {
20
                   // 3. After confirming that the device is connected is a mouse, the
                       host must choose a configuration on the device
21
                   config = 1;
22
                   mycode = alt_up_usb_set_config(usb_device, addr, port, config);
23
                   if (mycode == 0) {
24
                        // 4. Set up and play mouse
25
                       alt_up_usb_play_mouse(usb_device, addr, port);
26
                   }
27
               }
28
29
      }else {
30
           printf("Error: could not open USB device\n");
31
32
    return 0;
33 }
```

Figure 1. Example C code for the USB mouse demo.

4.5 Example Setup Function: alt_up_usb_setup

The function in Figure 2 shows a simple way to set up the USB controllers. It performs the following operations:

- 1. Reset and configure the controller by calling the functions in lines 16 and 17. The function alt_up_usb_hc_initialize_defaults (...) in line 17 configures the buffer sizes, disables all interrupts, and stops processing of all buffers.
- 2. Set the HC to the operational state by calling the function alt_up_usb_hc_set_operational (...) in line 20.
- 3. Enable the port if a connection has been detected using the function alt_up_usb_enable_ports (...) in line 21.
- 4. Assign new addresses to the ports by calling the function alt_up_usb_assign_address (...) in line 32; in our example, address 1 is assigned to port 1, address 2 is assigned to port 2.
- 5. Get the required descriptors by calling the function alt_up_usb_get_control (...) in lines 50 and 56.
- 6. Return the Human Interface Device (HID) number upon successful setup. The newly assigned port number and address will also be returned by pointers.

The function could be modified to fit specific requirements; more information can be found to ISP1362 USB datasheet online.

```
1 unsigned int alt up usb setup(alt up usb dev * usb device, int * addr ptr, int *
      port_ptr) {
2
      unsigned int rbuf[128];
3
      unsigned int mycode;
4
      unsigned int iManufacturer, iProduct;
5
      unsigned int status;
6
      unsigned int new_port1_addr, new_port2_addr, print_port_info;
7
      unsigned int extra, HID;
8
9
      // 1 means port1 is connected; 2 means port2 is connected;
10
      *port_ptr = -1;
11
      HID = -1;
12
13
      while (1) {
14
15
           // Configure and Set up the controls of the ATL buffer
16
          alt_up_usb_reset(usb_device);
17
           alt up usb hc initialize defaults (usb device);
18
19
           // Change the HC to operational state and Enable the port
20
          alt_up_usb_hc_set_operational(usb_device);
21
          alt_up_usb_enable_ports(usb_device);
22
23
          // Suspend the host controller, if the system doesn't need it
24
          alt_up_usb_hc_req_write_16(usb_device, ALT_UP_USB_HcControl, 0x6c0);
```

```
25
           alt_up_usb_hc_reg_write_16(usb_device, ALT_UP_USB_HcuPInterrupt, 0x1a9);
26
27
           // Assign new addresses for port 1 and port 2, maximum addr number is 7
28
           new_port1_addr = 1;
29
           new_port2_addr = 2;
30
           print_port_info = 0;
31
32
           status = alt up usb assign address(usb device, new port1 addr,
              new_port2_addr, print_port_info);
33
           // Enable ALT_IRQ and HC suspended
34
35
           alt_up_usb_hc_reg_write_16(usb_device, ALT_UP_USB_HcuPInterruptEnable,
              0x120);
36
37
           *port_ptr = -1;
38
           extra = 0;
39
40
           if ((status & 0x0001) != 0) {//port 2 active
41
               *port_ptr = 2;
42
               *addr_ptr = new_port2_addr;
43
           } else if ((status & 0x0100) != 0) {//port 1 active
44
               *port_ptr = 1;
45
               *addr_ptr = new_port1_addr;
46
           }
47
48
           if (*port_ptr != -1) {
49
               // Check port for device
50
               mycode = alt_up_usb_get_control(usb_device, rbuf, *addr_ptr, 'D',
                  extra, *port_ptr);
51
               if (mycode == 0x0300) {
                   iManufacturer = rbuf[7]&0xFF;
52
53
                   iProduct = (rbuf[7] \& 0xFF00) >> 8;
54
                   alt_up_usb_addr_info(*addr_ptr, 'W', 'O', iManufacturer);
55
                   alt_up_usb_addr_info(*addr_ptr, 'W', 'P', iProduct);
56
                   mycode = alt_up_usb_get_control(usb_device, rbuf, *addr_ptr, 'H',
                       alt_up_usb_addr_info(*addr_ptr, 'R', 'P', 0), *port_ptr);
57
58
                   HID = \star (rbuf + 1);
59
                   if (HID == 0x0209) { //it must be 0x0209, if connected device is a
60
                       printf("\nMouse Detected...\n");
61
                   } else if (HID == 0 \times 0609) { //it must be 0 \times 0609, if connected
                       device is a keyboard
62
                       printf("\nKeyboard Detected...\n");
63
64
                       printf("\nUSB Device with HID 0x%04x Detected...\n", HID);
65
66
                   return HID;
67
68
               }
69
           }
```

Figure 2. Example HAL function for USB setup: alt up usb setup.

4.6 Example Function for mouse communication: alt_up_usb_play_mouse

The function alt_up_usb_play_mouse (...) shown in Figure 3 demonstrates how to set up and retrieve mouse packets using polling. It keeps calling the function alt_up_usb_retrieve_mouse_packet (...) in line 57 to acquire the data from the mouse device.

```
1 unsigned int alt_up_usb_play_mouse(alt_up_usb_dev * usb_device, int addr, int port)
2
3
      printf("ISP1362 USB Mouse Demo....\n");
4
      alt_up_usb_mouse_setup(usb_device, addr, port);
5
6
      alt_up_usb_mouse_packet usb_mouse_packet;
7
8
      usb_mouse_packet.x_movement = 0;
9
      usb_mouse_packet.y_movement = 0;
10
      usb mouse packet.buttons = 0;
11
12
      unsigned int pX = 320, pY = 240;
13
14
      do {
15
           pX = pX + usb mouse packet.x movement;
16
          pY = pY + usb_mouse_packet.y_movement;
17
18
           if (pX > 639) {
19
               pX = 639;
20
21
           if (pX < 0) {
22
               pX = 0;
23
24
           if (pY > 479) {
25
               pY = 479;
26
27
           if (pY < 0) {
28
               pY = 0;
29
           }
30
31
           alt_up_parallel_port_dev * Green_LEDs_dev;
32
           alt up parallel port dev * Red LEDs dev;
33
           alt_up_parallel_port_dev * HEX3_HEX0_dev;
34
```

```
35
          Green_LEDs_dev = alt_up_parallel_port_open_dev("/dev/Green_LEDs");
36
          Red_LEDs_dev = alt_up_parallel_port_open_dev("/dev/Red_LEDs");
37
          HEX3_HEX0_dev = alt_up_parallel_port_open_dev("/dev/HEX3_HEX0");
38
39
          alt_up_parallel_port_write_data(Red_LEDs_dev, pX);
40
          alt_up_parallel_port_write_data(Green_LEDs_dev, pY);
41
42
          if ((usb mouse packet.buttons & 0x1) == 1) { //left button
43
              alt_up_parallel_port_write_data(HEX3_HEX0_dev, 0x3f0000);
44
45
          if (((usb_mouse_packet.buttons & 0x2) >> 1) == 1) { //right button}
46
              alt_up_parallel_port_write_data(HEX3_HEX0_dev, 0x3f);
47
48
          if (((usb_mouse_packet.buttons & 0x4) >> 2) == 1) { //center button
49
              alt_up_parallel_port_write_data(HEX3_HEX0_dev, 0x3f00);
50
          }
51
52
          usb_mouse_packet.x_movement = 0;
53
          usb_mouse_packet.y_movement = 0;
          usb_mouse_packet.buttons = 0;
54
55
56
      // Polling and get the data from the mouse
57
      } while (alt_up_usb_retrieve_mouse_packet(usb_device, &usb_mouse_packet) !=
          ALT_UP_USB_MOUSE_NOT_CONNECTED);
58
      printf("Mouse Not Detected\n");
59
      return 0;
60 }
```

Figure 3. Example HAL function for USB data transfer: alt_up_usb_play_mouse

4.7 USB Device Driver Details

4.7.1 alt_up_usb_dev

Prototype:

```
typedef struct alt_up_usb_dev {
    alt_dev dev;
    unsigned int base;
    unsigned int irq_base;
    unsigned int irq_id;
} alt_up_usb_dev;
```

Include: <altera_up_avalon_usb.h>

Fields: dev – the device structure

base - the base address of the device's data port

irq_base - the base address of the device's interrupt port

irq_id - the interrupt ID of the device

Description: Define the device structure. Each instance of the driver uses one of these structures to hold its

associated state.

4.7.2 usb_open_dev

Prototype: alt_up_usb_dev* alt_up_usb_open_dev(const char* name)

Include: <altera_up_avalon_usb.h>

Parameters: name – the specified name of the device in Qsys prefixed with the string /dev/.

Returns: the pointer to the USB device structure

Description: Open a USB device structure with name in Qsys.

4.7.3 struct ptd_struct

Prototype:

```
struct ptd_struct {
    alt_u16 actualBytes;
   alt_u8 completionCode;
   alt_u8 active;
   alt_u8 toggle;
    alt u16 maxPacketSize;
    alt_u8 endpointNumber;
    alt u8 last; // For isochronous(ISO) transfer only
    alt_u8 speed;
    alt_u16 totalBytes;
    alt_u8 paired;
    alt u8 pingPong;
    alt_u8 dirToken;
    alt_u8 functionAddress;
    alt_u8 pollingRate; // For Interrupt transfer only
   alt_u8 startingFrame;
} ;
```

Include: Fields:

<altera_up_avalon_usb_ptd.h>

actualBytes - the actual amount of data transferred at the moment

completionCode – the completion code that reports success or errors in transaction. Details can be referred to Table3 in the appendix.

active – This is set to logic 1 by firmware to enable the execution of transactions by the HC. The Host Controller(HC) sets this bit to logic 0 when the transaction associated with this descriptor is completed to indicate that a transaction for this element should not be executed when it is next encountered in the schedule.

toggle – This bit is used to generate or compare the data Packet ID value (DATA0 or DATA1) for IN and OUT transactions. It is updated after each successful transmission or reception of a data packet.

maxPacketSize - the maximum amount of data per packet

endpointNumber - the USB address of the target endpoint within the function

last – This is 1 if this PTD is the last PTD. last is used only for ISO transfers. The last PTD is indicated by the HcINTLLastPTD and HcATLLastPTD registers.

speed – the speed of the port. 0 indicates low-speed, 1 indicates high-speed.

totalBytes - the total amount of data to be transferred

paired – This bit determines whether this PTD is a normal bulk PTD or a paired-PTD.

pingPong – the identification of the paired buffer. 0 indicates this is the ping buffer; 1 indicates this is the pong buffer. pingPong is used only when paired is set to 1.

dirToken - the token type to specify IN, OUT or setup token

functionAddress - the address of target device

pollingRate - the polling rate

startingFrame - the start frame number

Description: Define the Philips Transfer Descriptor(PTD). PTD is an 8-byte data structure to provide communi-

cation between the processor and USB Host Controller, it gives order to the Host Controller(HC)

and reflects the status of USB transaction.

4.7.4 usb_init_ptd

Prototype: void alt_up_usb_init_ptd(struct ptd_struct * ptd, unsigned int

dirToken, alt_u8 endpointNumber, alt_u16 packetSize, alt_u8

toggle, alt_u8 functionAddress, alt_u8 portNumber)

Include: <altera_up_avalon_usb_ptd.h>

Parameters: portNumber - the port number

functionAddress - the address assigned to the USB port

toggle - This bit is used to generate or compare the data Packet ID value (DATA0 or DATA1)

for IN and OUT transactions. It could be 1 or 0.

packet Size - the size of the packet which specifies the maximum amount of data per packet

endpointNumber - the target endpoint number

dirToken - the direction token, which can be ALT_UP_USB_DIR_TOKEN_SETUP,

ALT_UP_USB_DIR_TOKEN_OUT or ALT_UP_USB_DIR_TOKEN_IN.

ptd – the pointer to the Philips Transfer Descriptor(PTD) structure

Returns: nothing

Description: Initialize the parameters in the PTD structure.

4.7.5 usb_convert_ptd_to_array

Prototype: void alt_up_usb_convert_ptd_to_array(unsigned int * ptd_array,

struct ptd_struct * ptd)

Include: <altera_up_avalon_usb_ptd.h>

Parameters: ptd – the pointer to the Philips Transfer Descriptor(PTD) structure

ptd array - the pointer to the array to store the PTD data

Returns: nothing

Description: Convert the data stored in the ptd_struct into an array.

4.8 Addresses of Registers in the USB Device Driver

Register Name	Address				
Control and Status Registers					
ALT_UP_USB_HcRevision	0x00				
ALT_UP_USB_HcControl	0x01				
ALT_UP_USB_HcCommandStatus	0x02				
ALT_UP_USB_HcInterruptStatus	0x03				
ALT_UP_USB_HcInterruptEnable	0x04				
ALT_UP_USB_HcInterruptDisable	0x05				
Frame Counter Registers	·				
ALT_UP_USB_HcFmInterval	0x0D				
ALT_UP_USB_HcFmRemaining	0x0E				
ALT_UP_USB_HcFmNumber	0x0F				
ALT_UP_USB_HcLSThreshold	0x11				
Root Hub Registers					
ALT_UP_USB_HcRhDescriptorA	0x12				
ALT_UP_USB_HcRhDescriptorB	0x13				
ALT_UP_USB_HcRhStatus	0x14				
ALT_UP_USB_HcRhPortStatus1	0x15				
ALT_UP_USB_HcRhPortStatus2	0x16				
DMA and Interrupt Control Registers					
ALT_UP_USB_HcHardwareConfiguration	0x20				
ALT_UP_USB_HcDMAConfiguration	0x21				
ALT_UP_USB_HcTransferCounter	0x22				
ALT_UP_USB_HcuPInterrupt	0x24				
ALT_UP_USB_HcuPInterruptEnable	0x25				
Miscellaneous Registers					
ALT_UP_USB_HcChipID	0x27				
ALT_UP_USB_HcScratch	0x28				
ALT_UP_USB_HcSoftwareReset	0x29				
Buffer RAM Control Registers					
ALT_UP_USB_HcBufferStatus	0x2C				
ALT_UP_USB_HcDirectAddressLength	0x32				

Continued on next page

Table 2 – continued from previous page

Register Name	Address			
ALT_UP_USB_HcDirectAddressData	0x45			
ISO Transfer Registers				
ALT_UP_USB_HcISTLBufferSize	0x30			
ALT_UP_USB_HcISTL0BufferPort	0x40			
ALT_UP_USB_HcISTL1BufferPort	0x42			
ALT_UP_USB_HcISTLToggleRate	0x47			
Interrupt Transfer Registers	'			
ALT_UP_USB_HcINTLBufferSize	0x33			
ALT_UP_USB_HcINTLBufferPort	0x43			
ALT_UP_USB_HcINTLBlkSize	0x53			
ALT_UP_USB_HcINTLPTDDoneMap	0x17			
ALT_UP_USB_HcINTLPTDSkipMap	0x18			
ALT_UP_USB_HcINTLLastPTD	0x19			
ALT_UP_USB_HcINTLCurrentActivePTD	0x1A			
Aperiodic Transfer Registers				
ALT_UP_USB_HcATLBufferSize	0x34			
ALT_UP_USB_HcATLBufferPort	0x44			
ALT_UP_USB_HcATLBlkSize	0x54			
ALT_UP_USB_HcATLPTDDoneMap	0x1B			
ALT_UP_USB_HcATLPTDSkipMap	0x1C			
ALT_UP_USB_HcATLLastPTD	0x1D			
ALT_UP_USB_HcATLCurrentActivePTD	0x1E			
ALT_UP_USB_HcATLPTDDoneThresholdCount	0x51			
ALT_UP_USB_HcATLPTDDoneThresholdTimeOut	0x52			
OTG Control Registers				
ALT_UP_USB_OTGControl	0x62			
ALT_UP_USB_OTGStatus	0x67			
ALT_UP_USB_OTGInterrupt	0x68			
ALT_UP_USB_OTGInterruptEnable	0x69			
ALT_UP_USB_OTGTimer	0x6A			
ALT_UP_USB_OTGAltTimer	0x6C			

Section 4.8 shows the names of the USB Host Control Data Registers and their corresponding addresses. Details about the functionality of each register can be found in the ISP1362 USB datasheet online.

4.9 USB_low_level_driver Details

4.9.1 usb_hc_reg_write_16

Prototype: void alt_up_usb_hc_reg_write_16(alt_up_usb_dev * usb_device,

unsigned char reg, unsigned int value)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: value – the 16-bit value to be written to the Host Controller(HC) register

req – the address of the HC register. The register addresses can be found in Section 4.8.

usb_device - the USB device structure

Returns: nothing

Description: Write a 16-bit value to the HC register.

4.9.2 usb_hc_reg_write_32

Prototype: void alt_up_usb_hc_reg_write_32(alt_up_usb_dev * usb_device,

unsigned char reg, unsigned long value)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: value – the 32-bit value to be written to the Host Controller(HC) register.

req – the address of the HC register. The register addresses can be found in Section 4.8.

usb_device - the USB device structure

Returns: nothing

Description: Write a 32-bit value to the HC register

4.9.3 usb_hc_reg_read_16

Prototype: unsigned int alt_up_usb_hc_reg_read_16(alt_up_usb_dev *

usb_device, unsigned char reg)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: reg - the address of the Host Controller(HC) register. The register addresses can be found in

Section 4.8.

usb device - the USB device structure

Returns: the 16-bit value stored in the HC register **Description:** Read a 16-bit value from the HC register

4.9.4 usb_hc_req_read_32

Prototype: unsigned long alt_up_usb_hc_reg_read_32(alt_up_usb_dev *

usb_device, unsigned char reg)

Include: <altera_up_avalon_usb_low_level_driver.h>

reg - the address of the Host Controller(HC) register. The register addresses can be found in **Parameters:**

Section 4.8.

usb_device - the USB device structure

Returns: the 32-bit value stored in the HC register **Description:** Read a 32-bit value from the HC register

4.9.5 usb_hc_write_atl

Prototype: void alt_up_usb_hc_write_atl(alt_up_usb_dev * usb_device,

unsigned int * a_ptr, unsigned int data_size)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: data_size - the number of 16-bit words to be written

a_ptr - the pointer that points to the memory array that holds data to be written to the ATL buffer

usb device - the USB device structure

Returns: nothing

Description: Write data to the ATL buffer.

4.9.6 usb_hc_read_atl

void alt_up_usb_hc_read_atl(alt_up_usb_dev * usb_device, **Prototype:**

unsigned int * a_ptr, unsigned int data_size)

<altera up avalon usb low level driver.h> Include:

Parameters: data_size - the number of 16-bit words to be read

a ptr – the pointer that points to the memory array to hold data from the ATL buffer

usb device - the USB device structure

Returns: nothing

Description: Read data from the ATL buffer.

4.9.7 usb_hc_write_int

Prototype: void alt_up_usb_hc_write_int(alt_up_usb_dev * usb_device,

unsigned int * a_ptr, unsigned int data_size)

Include: <altera up avalon usb low level driver.h> **Parameters:**

data size - the number of 16-bit words to be written

a ptr – the pointer that points to the memory array that holds data to be written to the INTL

buffer

usb device - the USB device structure

Returns: nothing

Description: Write data to the INTL buffer.

4.9.8 usb_hc_read_int

Prototype: void alt_up_usb_hc_read_int(alt_up_usb_dev * usb_device,

unsigned int * a_ptr, unsigned int data_size)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: data size – the number of 16-bit words to be read

a_ptr - the pointer that points to the memory array to hold data from the INTL buffer

usb_device - the USB device structure

Returns: nothing

Description: Read data from the INTL buffer.

4.9.9 usb_hc_direct_address_write

Prototype: void alt_up_usb_hc_direct_address_write(alt_up_usb_dev *

usb_device, unsigned int *a_ptr, unsigned int start_addr,

unsigned int data_size)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: data_size – the number of 16-bit words to be written

start_addr - the starting byte address of the data to be written in the Host Controller(HC)

buffer

a_ptr - the pointer that points to the memory array that holds data to be written directly to the

address specified

usb_device - the USB device structure

Returns: nothing

Description: Write data to the Host Controller(HC) buffer using direct addressing. This addressing method

views the entire buffer as a single linear array of 4096 bytes instead of 4 sperate buffer areas(ATL

buffer, INTL buffer, ISTLO buffer, and ISTL1 buffer).

4.9.10 usb hc direct address read

Prototype: void alt_up_usb_hc_direct_address_read(alt_up_usb_dev *

usb_device, unsigned int *a_ptr, unsigned int start_addr,

unsigned int data_size)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: data size – the number of 16-bit words to be read

 $start_addr$ - the starting byte address of the data to be read in the Host Controller(HC) buffer a_ptr - the pointer that points to the memory array to hold the data read from the address

specified

usb_device - the USB device structure

Returns: nothing

Description: Read data from the Host Controller(HC) buffer using direct addressing. This addressing method

views the entire buffer as a single linear array of 4096 bytes instead of 4 sperate buffer areas(ATL

buffer, INTL buffer, ISTLO buffer, and ISTL1 buffer).

4.9.11 usb_dc_reg_write_16

Prototype: void alt_up_usb_dc_reg_write_16(alt_up_usb_dev * usb_device,

unsigned char reg, unsigned int value)

Include: <altera_up_avalon_usb_low_level_driver.h>

Parameters: value – the 16-bit value to be written to the Device Controller(DC) register

reg – the address of the DC register.
usb device – the USB device structure

Returns: nothing

Description: Write a 16-bit value to the DC register.

4.9.12 usb_dc_reg_write_32

Prototype: void alt_up_usb_dc_reg_write_32(alt_up_usb_dev * usb_device,

unsigned char reg, unsigned long value)

Include: <altera up avalon usb low level driver.h>

Parameters: value – the 32-bit value to be written to the Device Controller(DC) register

reg – the address of the DC register.
usb_device – the USB device structure

Returns: nothing

Description: Write a 32-bit value to the DC register.

4.9.13 usb_dc_reg_read_16

Prototype: unsigned int alt_up_usb_dc_reg_read_16(alt_up_usb_dev *

usb_device, unsigned char reg)

usb_device - the USB device structure

Returns: the 16-bit value stored in the DC register **Description:** Read a 16-bit value from the DC register

4.9.14 usb_dc_reg_read_32

Prototype: unsigned long alt_up_usb_dc_reg_read_32(alt_up_usb_dev *

usb_device, unsigned char reg)

usb device - the USB device structure

Returns: the 32-bit value stored in the DC register **Description:** Read a 32-bit value from the DC register

4.10 USB_high_level_driver Details

4.10.1 usb_setup

Prototype: unsigned int alt_up_usb_setup(alt_up_usb_dev * usb_device, int *

addr_ptr, int * port_ptr)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: port_ptr - the pointer to the port number

addr_ptr - the pointer to the address
usb_device - the USB device structure

Returns: the Human Interface Device(HID) number. It must be 0x0209, if connected device is a mouse.

Description: Set up the USB, get the connected port number and its address. It is an simple example function

of how to set up the USB. The USB can be set up in different modes to fit your own need.

4.10.2 usb_reset

Prototype: int alt_up_usb_reset(alt_up_usb_dev * usb_device)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: usb_device - the USB device structure

Returns: 0 on success

Description: Reset the USB operation.

4.10.3 usb_enable_ports

Prototype: int alt_up_usb_enable_ports(alt_up_usb_dev * usb_device)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: usb device - the USB device structure

Returns: 0 on success

Description: Enable a port if a USB device is found to be connected to it and update the USB port status.

Notes: Port 2 is always used as a host port.

4.10.4 usb_hc_set_operational

Prototype: int alt_up_usb_hc_set_operational(alt_up_usb_dev * usb_device)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: usb device - the USB device structure

Returns: 0 on success

Description: Set the Host Controller to the operational mode. In the operational mode, the bits in the HcBuffer-

Status register can request the Host Controller to start processing the data in buffers.

4.10.5 usb_hc_setup_atl_buffer

Prototype: int alt_up_usb_hc_setup_atl_buffer(alt_up_usb_dev * usb_device)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: usb device - the USB device structure

Returns: 0 on success

Description: Set up the controls of the ATL buffer.

4.10.6 usb_hc_initialize_defaults

Prototype: int alt_up_usb_hc_initialize_defaults(alt_up_usb_dev *

usb_device)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: usb_device - the USB device structure

Returns: 0 on success

Description: Initialize the host controller. It sets the ATL, INTL, ISTL buffer size to 1536, 1024 and 512 respec-

tively, disables all the interrupts, sets up the controls of the ATL buffer and disables processing of

all buffers.

4.10.7 usb_hc_disable_all_interrupts

Prototype: void alt_up_usb_hc_disable_all_interrupts(alt_up_usb_dev *

usb_device)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: usb device - the USB device structure

Returns: 0 on success

Description: Disable all interrupts.

4.10.8 usb_hc_set_istl_buffer_size

Prototype: void alt_up_usb_hc_set_istl_buffer_size(alt_up_usb_dev *

usb_device, unsigned int buffer_size)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: buffer_size - the size of ISTL buffer in bytes

usb_device - the USB device structure

Returns: nothing

Description: Configure the ISTL buffer size.

4.10.9 usb_hc_set_intl_buffer_size

Prototype: void alt_up_usb_hc_set_intl_buffer_size(alt_up_usb_dev *

usb_device, unsigned int buffer_size)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: buffer_size - the size of INTL buffer in bytes

usb_device - the USB device structure

Returns: nothing

Description: Configure the INTL buffer size.

4.10.10 usb_hc_set_atl_buffer_size

Prototype: void alt_up_usb_hc_set_atl_buffer_size(alt_up_usb_dev *

usb_device, unsigned int buffer_size)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: buffer_size - the size of ATL buffer in bytes

usb_device - the USB device structure

Returns: nothing

Description: Configure the ATL buffer size.

4.10.11 usb_get_connection_status

Prototype: int alt_up_usb_get_connection_status(alt_u8 portNumber)

Include: <altera up avalon usb high level driver.h>

Parameters: portNumber – the port number **Returns:** 1 if the port is connected, 0 otherwise.

Description: Get the connection status of the port specified.

4.10.12 usb_get_port_speed

Prototype: int alt_up_usb_get_port_speed(alt_u8 portNumber)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: portNumber - the port number

Returns: 1 for low-speed device, or 0 for high-speed device

Description: Get the speed of the port specified.

4.10.13 usb_send_control

Prototype: unsigned int alt_up_usb_send_control(alt_up_usb_dev *

usb_device, unsigned int * control_packet, unsigned int *

return_packet)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: return_packet - the pointer to the location that stores the data to be returned from the ATL

buffer to the host

control_packet - the pointer to the location that stores the data to be sent from the host to

the ATL buffer

usb device - the USB device structure

Returns: a number. It should be greater than 0, otherwise it indicates a time out in the polling loop.

Description: Copy the PTD and payload (if any) into the ATL buffer and activate the buffer. Once the transaction

is completed, the routine terminates and returns a number greater than zero together with the

processed PTD in the return packet to the calling function.

4.10.14 usb set address

Prototype: unsigned int alt_up_usb_set_address(alt_up_usb_dev * usb_device,

int port, int old_addr, int new_addr)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: new addr – the new address of the port

old addr - the old address of the port. The initialized address for port is 0 by default.

port – the port number

usb device - the USB device structure

Returns: 0 on success

Description: Allocate an available address to the newly connected USB device.

Notes: The routine has only two stages: Setup and Status. If an error is encountered in the Setup stage, it

will not proceed to the Status stage to send out the data IN packet.

4.10.15 usb_set_config

Prototype: unsigned int alt_up_usb_set_config(alt_up_usb_dev * usb_device,

int addr, int port, int config)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: config – the configuration to be set on the device

port – the port number

addr – the address assigned to the USB port usb_device – the USB device structure

Returns: 0 on success

Description: Choose a configuration on the device after confirming the device identity.

4.10.16 usb_send_int_packet

Prototype: unsigned int alt_up_usb_send_int_packet(alt_up_usb_dev *

usb_device, unsigned int * control_packet, unsigned int *

return_packet)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: return_packet - the pointer to the location that stores the data to be returned from the INTL

buffer to the host

control_packet - the pointer to the location that stores the data to be sent from the host to

the INTL buffer

usb device - the USB device structure

Returns: a number. It should be greater than 0, otherwise it indicates a time out.

Description: Send packet to the INTL buffer and activate the buffer. Once the transaction is completed, the

routine terminates and returns a number greater than zero together with the return packet

containing device information to the calling function.

4.10.17 usb_get_control

Prototype: unsigned int alt_up_usb_get_control(alt_up_usb_dev * usb_device,

unsigned int * return_packet, unsigned int addr, char

control_type, unsigned int extra, int port)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: port – the port number

extra - the extra information for string processing. It is ORed with the 5th element in

alt control packet.

control_type - the type of descriptor you want to get from the USB device.

Input 'D' for Device Descriptor, 'C' for Configuration Descriptor, 'S' for String Descriptor,

'E' for Endpoint Descriptor, or 'H' for Human Interface Device (HID) Descriptor.

addr – the address assigned to the USB port

return_packet - the pointer to the location that stores the data to be returned from the device

to the host

usb_device - the USB device structure

Returns: the completion code. Bit 0-3 indicates the error code, bit 8-11 indicates at which stage the error

was encountered, bit 12-15 is 0xF if time runs out, else 0.

Description: Get a descriptor from the device.

4.10.18 usb_addr_info

Prototype: unsigned int alt_up_usb_addr_info(int addr, int mode, int dtype,

int para)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: para – the input parameter for the Write mode

dtype - the data type. Input 'S' for speed, 'M' for maximum packet size, 'O' for manufac-

turer, or 'P' for product.

mode – the mode of the operation. Input 'D' for displaying data, 'W' for writing data, or 'R'

for reading data.

addr - the address assigned to the USB port

Returns: the acquired data in read mode, 0 in other modes

Description: Perform display, write, or read operation on the USB data bank.

4.10.19 usb_assign_address

Prototype: unsigned int alt_up_usb_assign_address(alt_up_usb_dev *

usb_device, unsigned int new_port1_addr, unsigned int

new_port2_addr, unsigned int print_port_info)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: print port info – the parameter to enable printing the port information. Input 1 to enable

the feature, 0 to disable it.

new_port2_addr - the new address for port 2
new_port1_addr - the new address for port 1

usb device - the USB device structure

Returns: the status. The status &0x0100 becomes TRUE if port 1 has a device attached and an address

has been successfully assigned to it. The status &0x0001 becomes TRUE if port 2 has a device

attached and an address has been successfully assigned to it.

Description: Assign address to the connected port and return the status. It calls the usb_set_address

function.

4.10.20 usb hc buffer size info

Prototype: unsigned int alt_up_usb_hc_buffer_size_info(alt_up_usb_dev *

usb_device)

Include: <altera_up_avalon_usb_high_level_driver.h>

Parameters: usb_device - the USB device structure

Returns: 0 on success

Description: Print out the buffer size information.

4.11 USB_mouse_driver Details

4.11.1 alt_up_usb_mouse_packet

Prototype:

```
typedef struct alt_up_usb_mouse_packet {
    signed char x_movement;
    signed char y_movement;
    signed char buttons;
} alt_up_usb_mouse_packet;
```

buttons - the button status. Bit 0 indicates the left button is clicked, bit 1 indicates the right

button is clicked, and bit 2 indicates the center button is clicked.

Description: Define the mouse packet structure.

4.11.2 usb_mouse_setup

Prototype: int alt_up_usb_mouse_setup(alt_up_usb_dev * usb_device, int

addr, int port)

Include: <altera up avalon usb mouse driver.h>

Parameters: port – the port number

addr – the address assigned to the USB port usb_device – the USB device structure

Returns: 0 on success

Description: Set up the INTL buffer for the mouse packet transaction. This function should be called after

confirming that the port is connected to a mouse device and an address has been assigned to the

port.

4.11.3 usb_retrieve_mouse_packet

Prototype: int alt_up_usb_retrieve_mouse_packet(alt_up_usb_dev *

usb_device, struct alt_up_usb_mouse_packet * mouse_packet)

Include: <altera_up_avalon_usb_mouse_driver.h>

Parameters: mouse_packet - the pointer to the mouse packet structure to be retrieved

usb device - the USB device structure

Returns: 0 on success, 1 if no packet is retrieved, or 2 if the mouse is not connected

Description: Retrieve mouse packet.

4.11.4 usb_play_mouse

Prototype: unsigned int alt_up_usb_play_mouse(alt_up_usb_dev * usb_device,

int addr, int port)

Include: <altera_up_avalon_usb_mouse_driver.h>

Parameters: port – the port number

addr – the address assigned to the USB port usb_device – the USB device structure

Returns: 0 on success

Description: Retrieves mouse packet and displays the mouse information.

4.11.5 usb_mouse_example

Prototype: void alt_up_usb_mouse_example(alt_up_usb_dev * usb_device)

Include: <altera_up_avalon_usb_mouse_driver.h>

Parameters: usb_device - the USB device structure

Returns: nothing

Description: Demonstrate how the USB mouse works. By calling this function, it sets up the USB host con-

troller, configures the mouse device, retrieves mouse packet and displays the mouse information on the FPGA boards (DE2 and DE2-115) by calling the usb_setup, usb_set_config, and usb_play_mouse functions. The LEDRs on board display the X location of the mouse, the LEDGs display the Y location of the mouse, and the HEX0-HEX2 display the status of the mouse

buttons.

A Appendix

Table 3. Transaction Completion Codes

Completion codes		
ALT_UP_USB_PTD_CC_NoError	0x0	
ALT_UP_USB_PTD_CC_CRC	0x1	
ALT_UP_USB_PTD_CC_BitStuffing	0x2	
ALT_UP_USB_PTD_CC_DataToggleMismatch	0x3	
ALT_UP_USB_PTD_CC_Stall	0x4	
ALT_UP_USB_PTD_CC_DeviceNotResponding	0x5	
ALT_UP_USB_PTD_CC_PIDCheckFailure	0x6	
ALT_UP_USB_PTD_CC_UnexpectedPID	0x7	
ALT_UP_USB_PTD_CC_DataOverrun	0x8	
ALT_UP_USB_PTD_CC_DataUnderrun	0x9	
ALT_UP_USB_PTD_CC_BufferOverrun	0xC	
ALT_UP_USB_PTD_CC_BufferUnderrun	0xD	
ALT_UP_USB_PTD_CC_Initial	0xF	