

Modelos de Deep Learning

Derivadas

Universidad ORT Uruguay

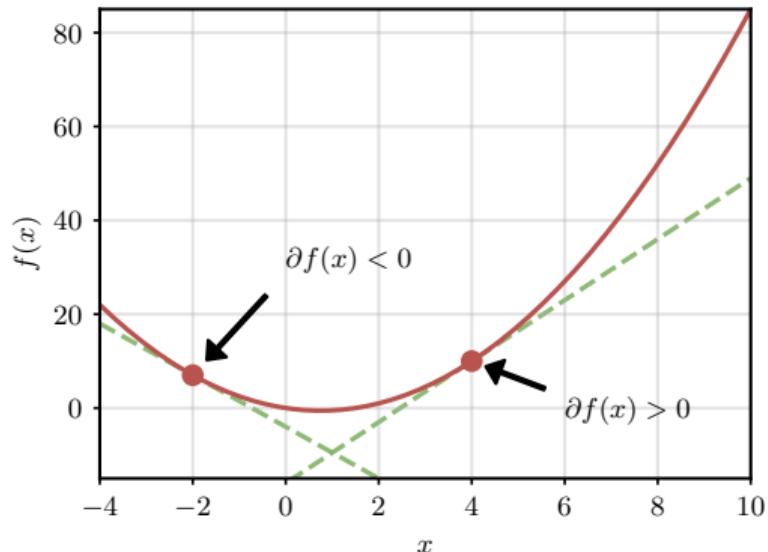
18 de Agosto, 2025

Reaso: definición de derivada

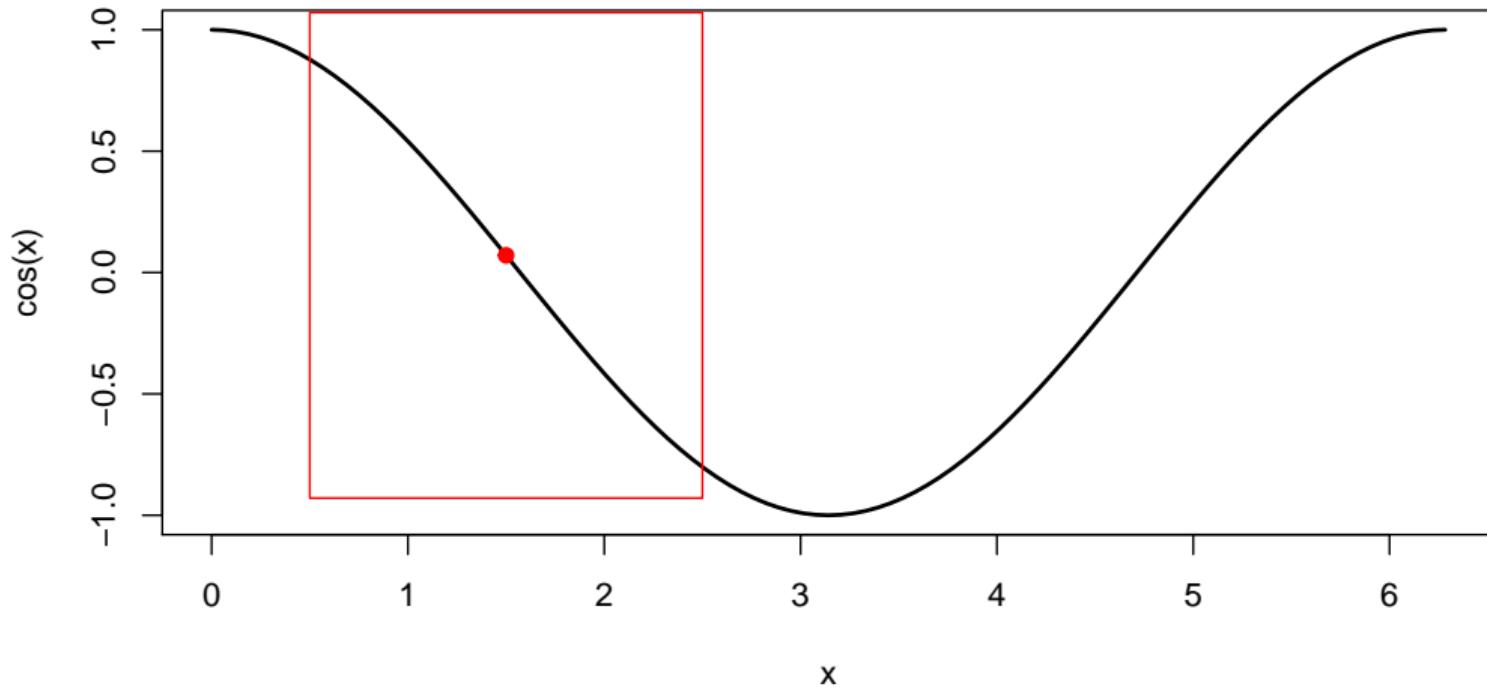
Para una función $y = f(x)$ con **entrada escalar y salida escalar**, su derivada es

$$f'(x) = \lim_{\Delta x \rightarrow 0} \frac{\Delta f}{\Delta x}$$

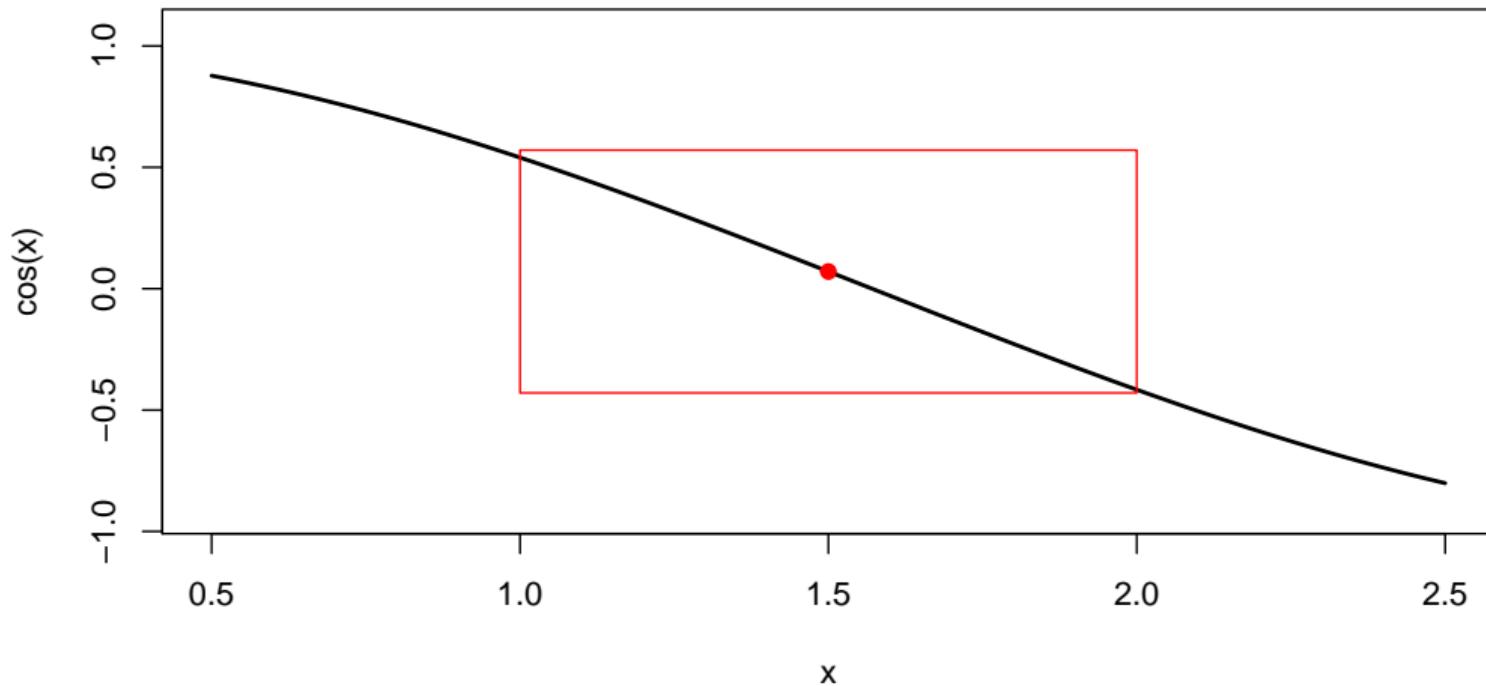
Otra notación: $\partial f(x)$



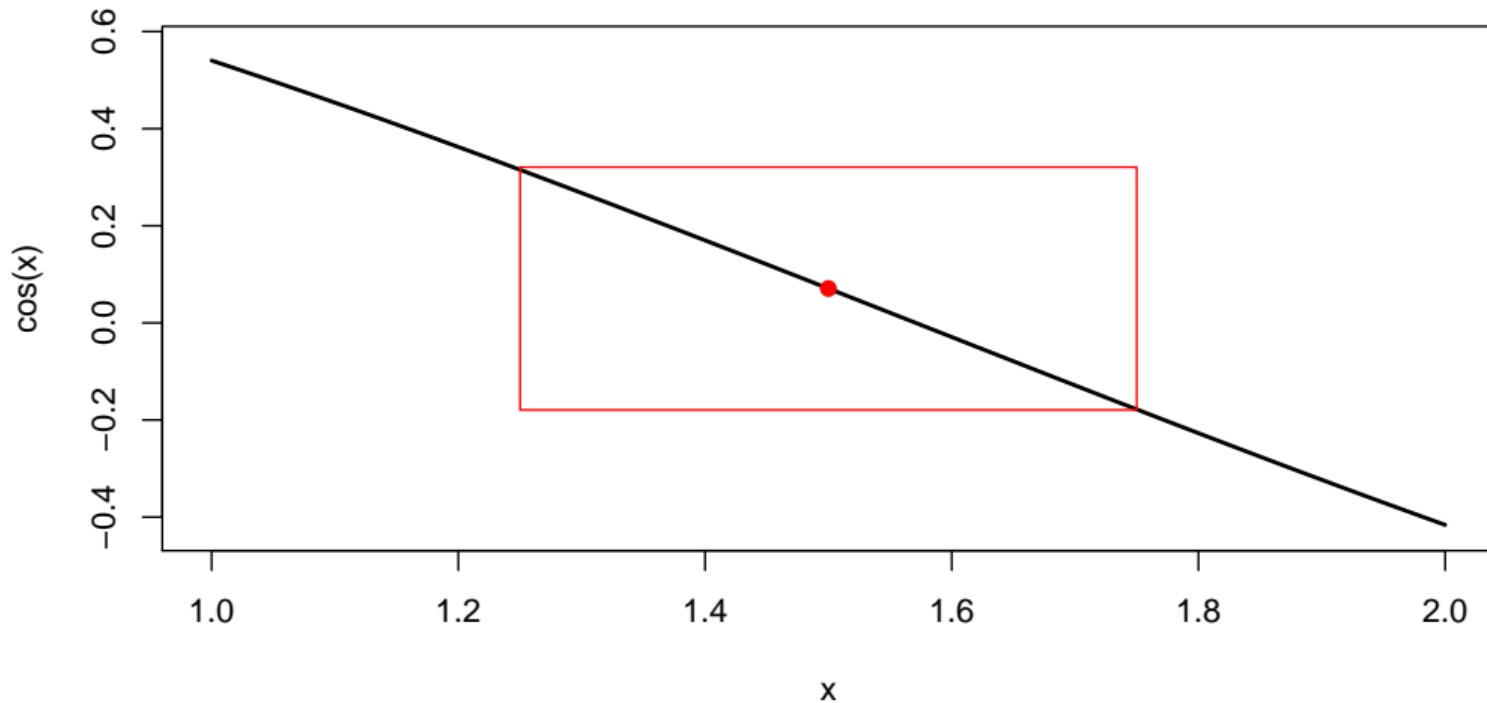
Haciendo zoom



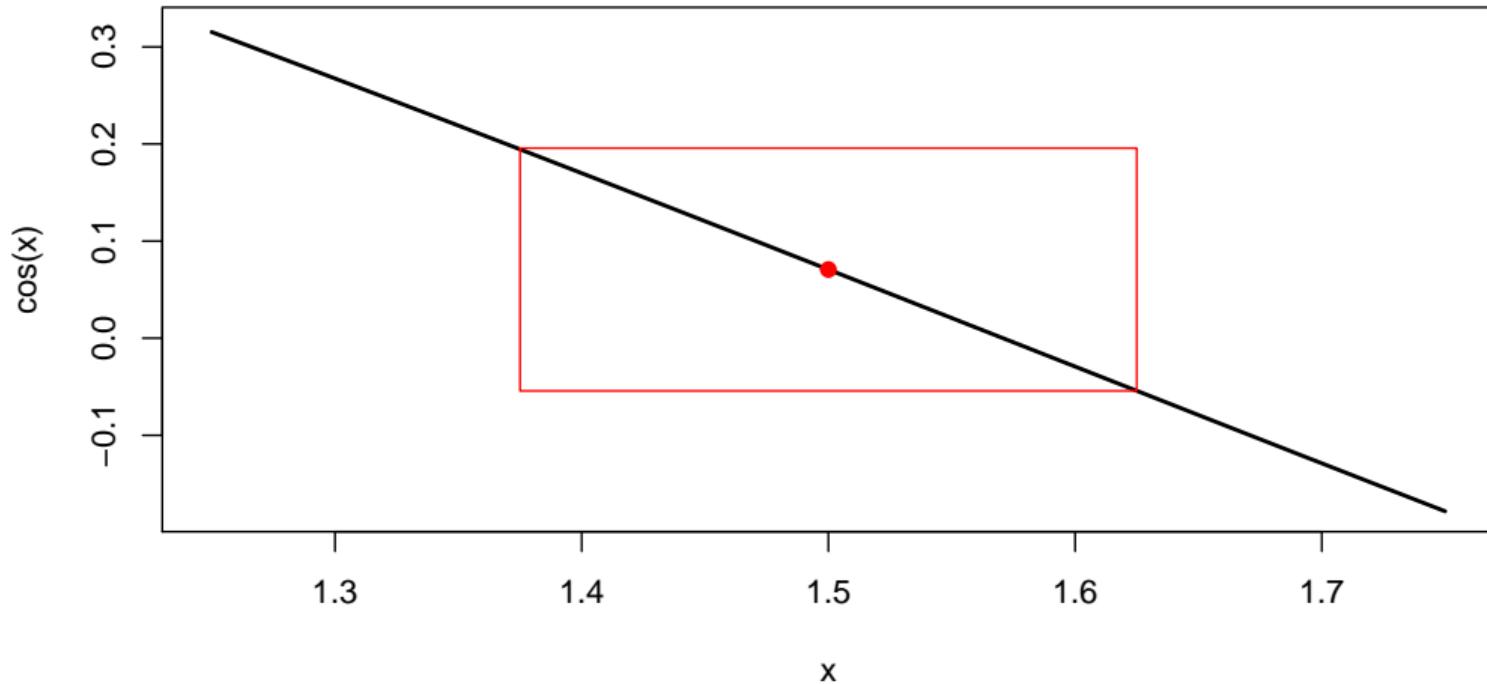
Haciendo zoom



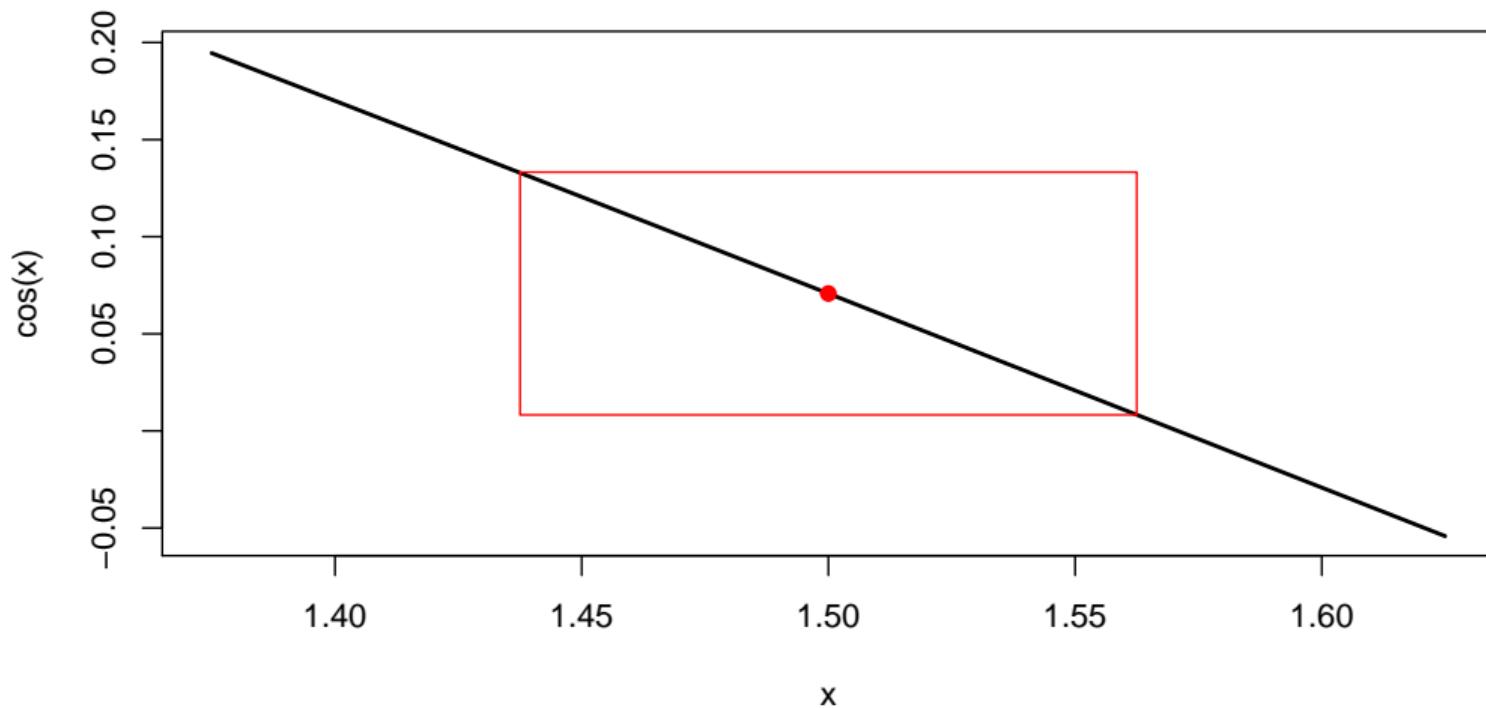
Haciendo zoom



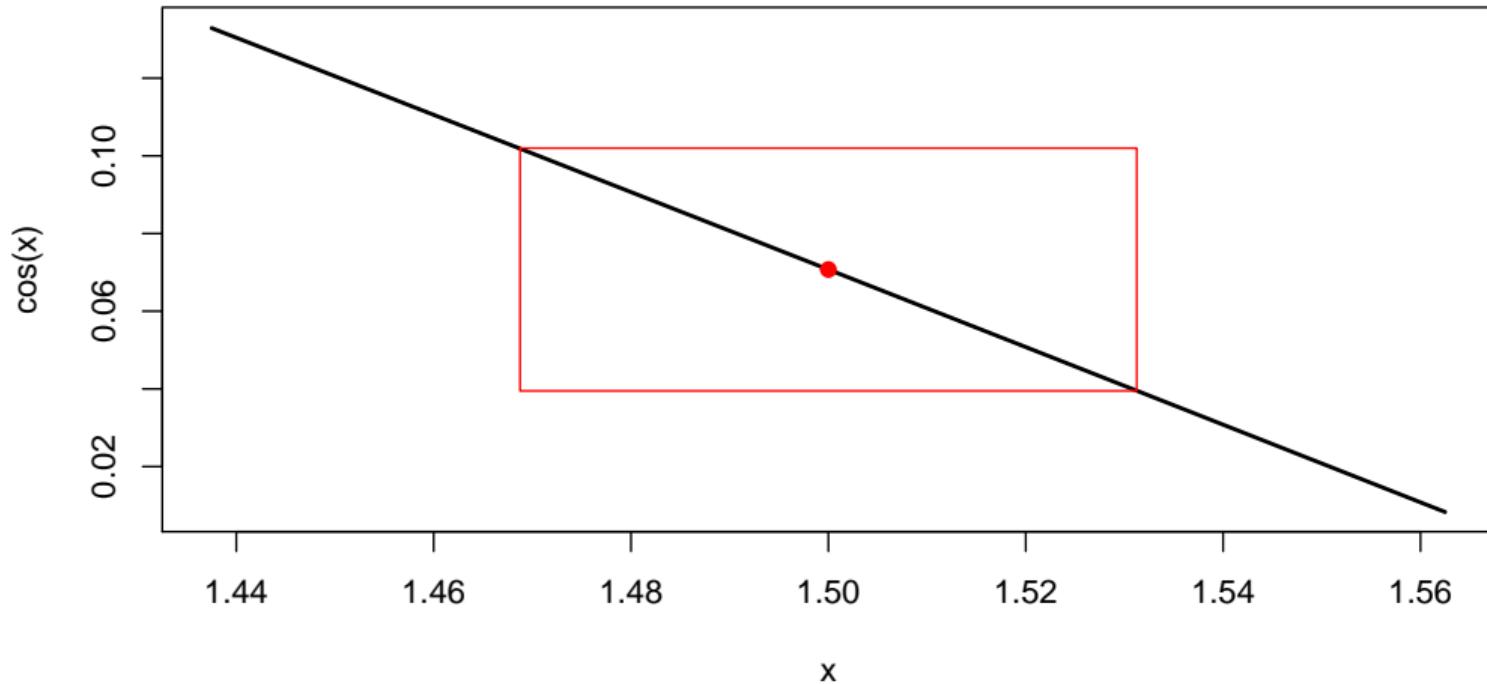
Haciendo zoom



Haciendo zoom



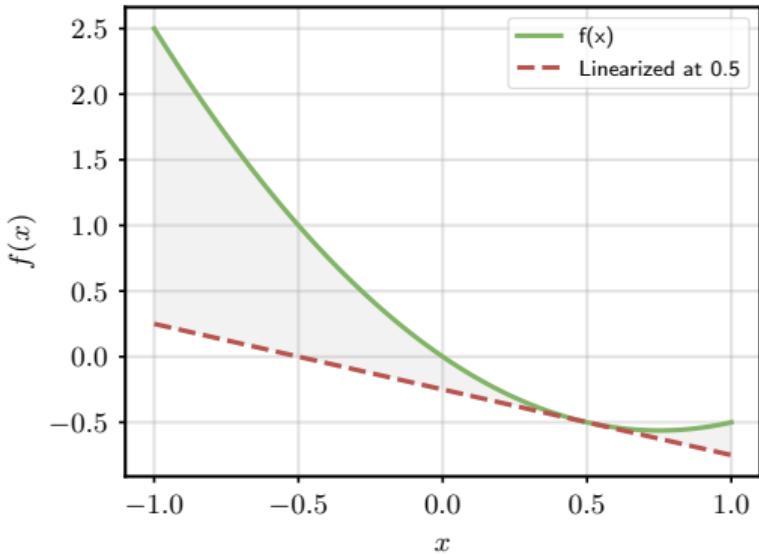
Haciendo zoom



Aproximación lineal

Para $x \approx x_0$:

$$f(x) \approx f(x_0) + \partial f(x_0) \cdot (x - x_0)$$



Propiedades básicas

- **Linealidad:** si a y b son constantes, entonces

$$\partial[a f(x) + b g(x)] = a \partial f(x) + b \partial g(x)$$

- **Regla del producto:**

$$\partial[f(x)g(x)] = \partial f(x) \cdot g(x) + f(x) \cdot \partial g(x)$$

- **Regla de la cadena:**

$$\partial[f(g(x))] = \partial f(g(x)) \cdot \partial g(x)$$

Derivadas parciales y gradiente

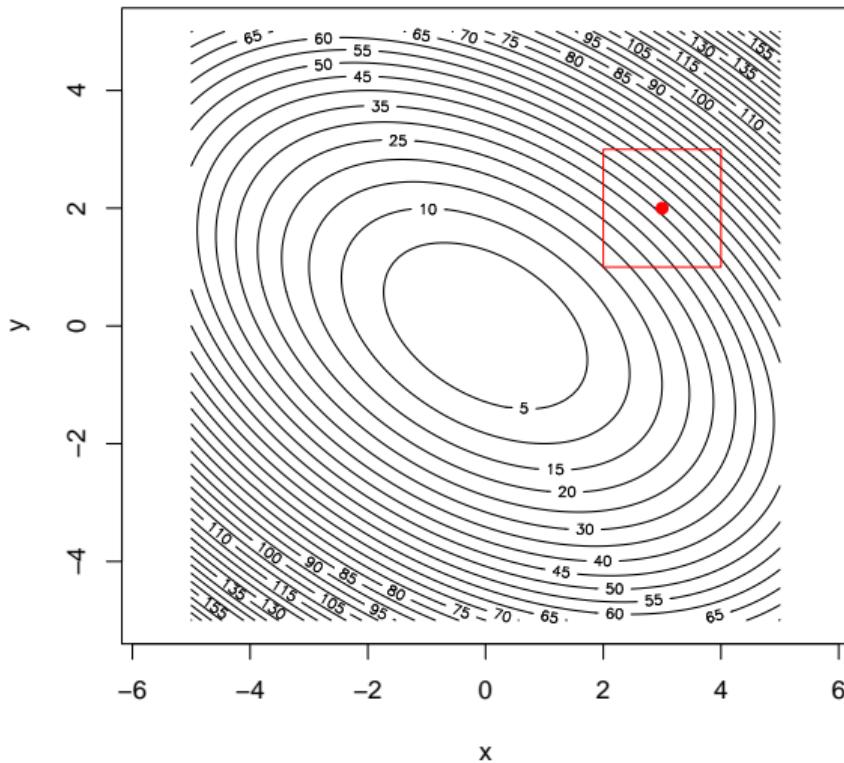
- Sea $y = f(\mathbf{x})$ una función con **entrada $\mathbf{x} \sim (d)$** y **salida escalar**.
- Su **derivada parcial** respecto a x_i es

$$\partial_i f(\mathbf{x}) = \lim_{\Delta x_i \rightarrow 0} \frac{\Delta f}{\Delta x_i} \quad (\text{dejando las } x_j, j \neq i \text{ constantes})$$

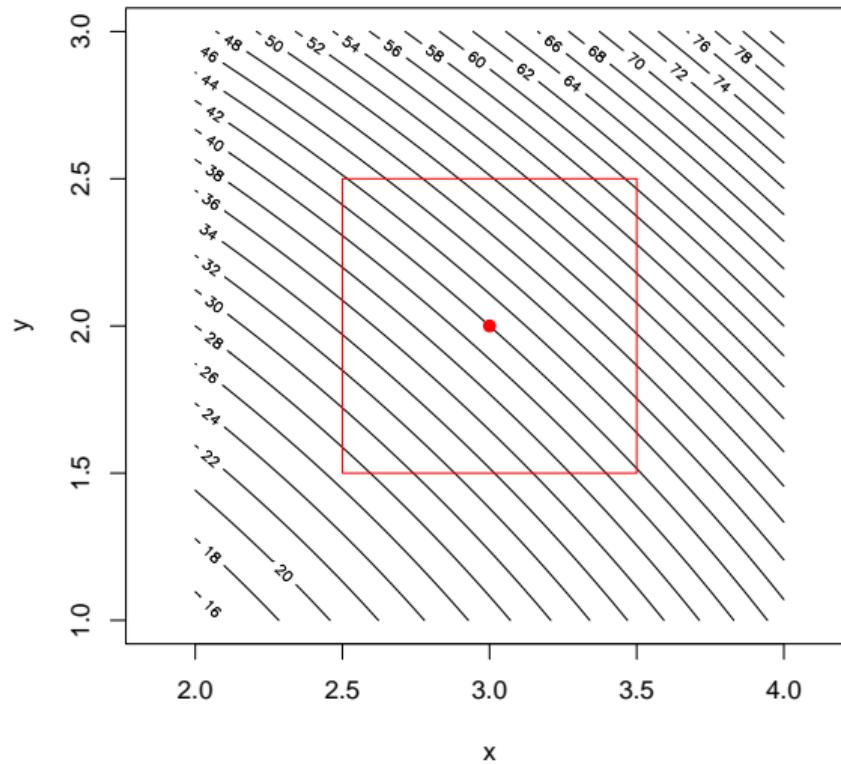
- El **gradiente** de $y = f(\mathbf{x})$ es

$$\nabla f(\mathbf{x}) = \begin{bmatrix} \partial_1 f(\mathbf{x}) \\ \vdots \\ \partial_d f(\mathbf{x}) \end{bmatrix}$$

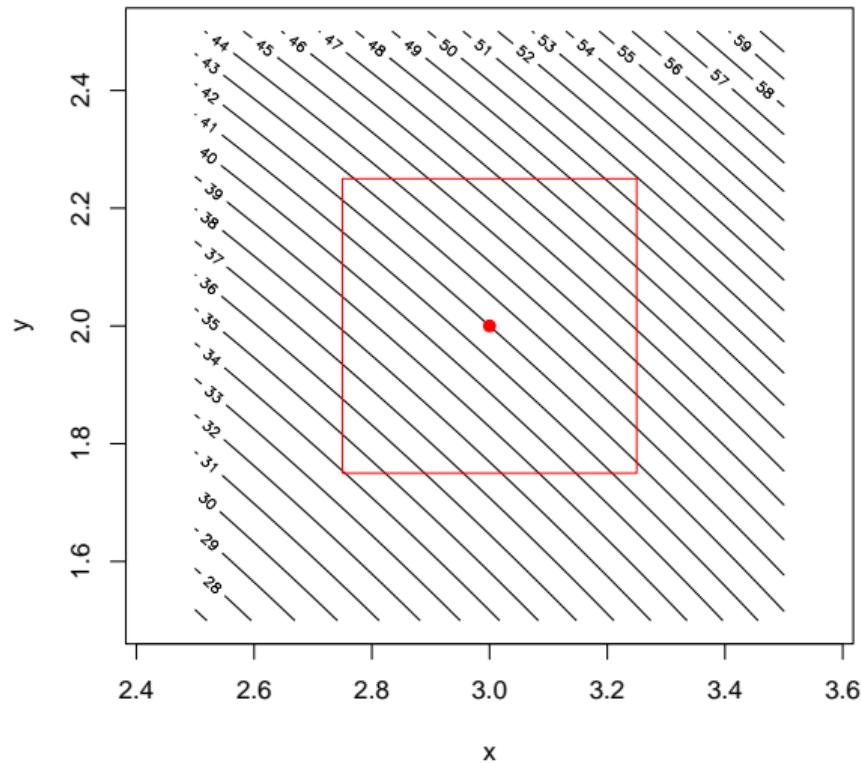
Curvas de nivel de $f=2x^2+2xy+y^2$



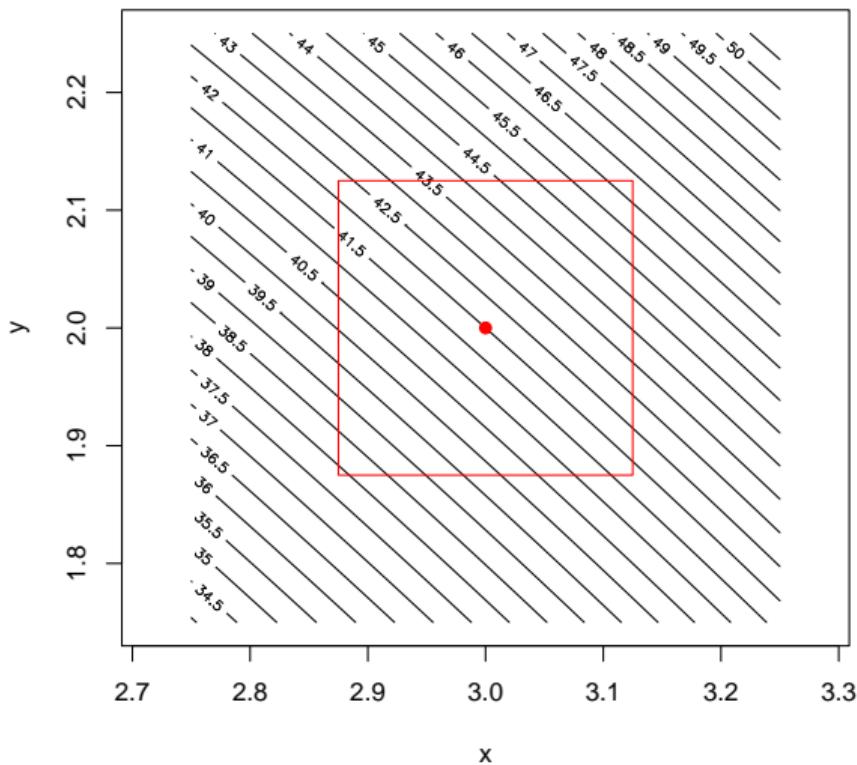
Zoom en (3,2)



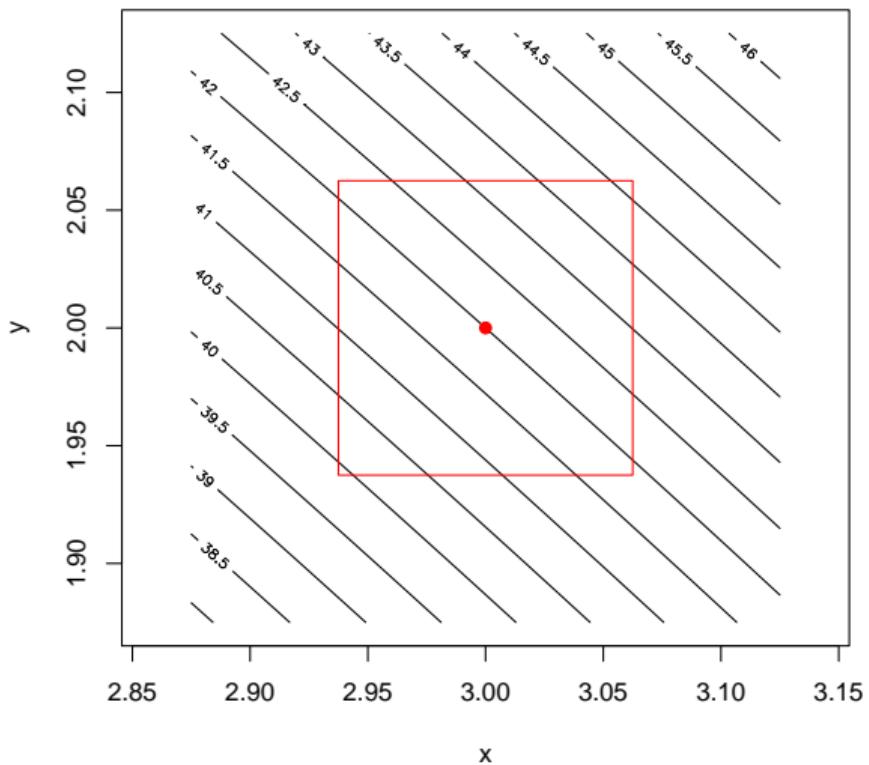
Zoom en (3,2)



Zoom en (3,2)



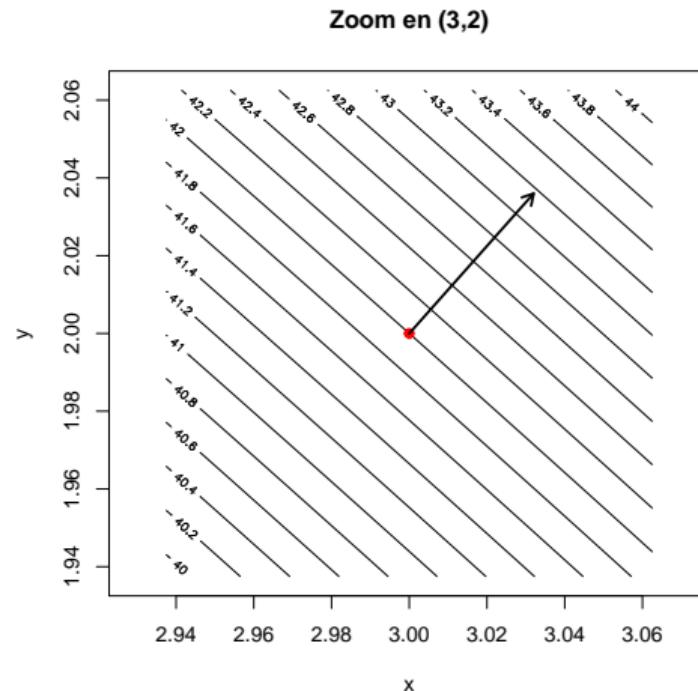
Zoom en (3,2)



Aproximación lineal

Para $\mathbf{x} \approx \mathbf{x}_0$:

$$f(\mathbf{x}) \approx f(\mathbf{x}_0) + \langle \nabla f(\mathbf{x}_0), \mathbf{x} - \mathbf{x}_0 \rangle$$



El Jacobiano

- Sea $\mathbf{y} = f(\mathbf{x})$ una función con **entrada** $\mathbf{x} \sim (d)$ y **salida** $\mathbf{y} \sim (k)$.
- Su **Jacobiano** se define como

$$\partial f(\mathbf{x}) = \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \cdots & \frac{\partial y_1}{\partial x_d} \\ \vdots & \ddots & \vdots \\ \frac{\partial y_k}{\partial x_1} & \cdots & \frac{\partial y_k}{\partial x_d} \end{pmatrix} = \begin{pmatrix} \nabla f_1^\top \\ \vdots \\ \nabla f_k^\top \end{pmatrix} \sim (k, d)$$

Siendo $f = (f_1, \dots, f_k)$.

- **Regla de la cadena:**

$$\partial [f(g(\mathbf{x}))] = \partial f(g(\mathbf{x})) \partial g(\mathbf{x}) \quad (\text{multiplicación de matrices})$$

Ejemplo

- Consideremos la función lineal $\mathbf{y} = \mathbf{Wx}$
- Vista como función de \mathbf{x} , su Jacobiano es la matriz (k, d) :

$$\partial_{\mathbf{x}} [\mathbf{Wx}] = \mathbf{W}$$

- Vista como función de \mathbf{W} , su Jacobiano es la matriz (k, kd) :

$$y_i = \sum_j W_{ij} x_j \Rightarrow \frac{\partial y_i}{\partial W_{r\ell}} = \begin{cases} x_\ell & \text{si } r = i \\ 0 & \text{si } r \neq i \end{cases} \Rightarrow \partial_{\mathbf{W}} \mathbf{Wx} = \begin{pmatrix} \mathbf{x}^\top & \mathbf{0} & \cdots & \mathbf{0} \\ \mathbf{0} & \mathbf{x}^\top & \cdots & \mathbf{0} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0} & \vdots & \mathbf{0} & \mathbf{x}^\top \end{pmatrix}$$