

# 1 Summary

Word limit: 550

In plain English, provide a summary we can use to identify the most suitable experts to assess your application.

We usually make this summary publicly available on external-facing websites, therefore do not include any confidential or sensitive information. Make it suitable for a variety of readers, for example:

- opinion-formers
- policymakers
- the public
- the wider research community

**Guidance for writing a summary** Clearly describe your proposed work in terms of:

- context
- the challenge the project addresses
- aims and objectives
- potential applications and benefits
- its relevance to the BBSRC long-term research and innovation priorities and, if applicable Responsive Mode Spotlight areas

## 20 **2 Core team**

21 List the key members of your team and assign them roles from the following:

- 22 • project lead (PL)
- 23 • project co-lead (UK) (PcL)
- 24 • specialist
- 25 • professional enabling staff
- 26 • research and innovation associate
- 27 • technician
- 28 • researcher co-lead (RcL)

29 Only list one individual as project lead.

30 UKRI has introduced a new addition to the ‘specialist’ role type. Public  
31 contributors such as people with lived experience can now be added to an  
32 application.

33 Find out more about [UKRI’s core team roles in funding applications and](#)  
34 [our eligibility guidance](#).

## 3 Application questions

### 3.1 BBSRC schemes

Word limit: 1

Indicate the scheme through which you are applying.

In the text box, copy the number corresponding to the scheme you are applying through. These are:

1. standard (no scheme)
2. Industrial Partnership Award (IPA)
3. LINK
4. Brazil (FAPESP)
5. Luxembourg (FNR)
6. NSF-Bio

Additional guidance

This is for administrative purposes to help the initial application processing.

Please follow the scheme specific guidance below and upload the additional documents listed as a single PDF no larger than 8MB:

IPA or LINK:

- a letter from your institution's technology transfer office outlining the management of outputs from the proposed research

FAPESP:

- FAPESP proposal form
- FAPESP consolidated budget form
- FAPESP letter of eligibility

FNR:

60      • CVs of international collaborators

61      • FNR ‘INTER’ budget form

62      • FNR ‘INTER’ cost justification

63      NSF-Bio:

64      • US biosketches

65      • US budget forms

## 66 **3.2 BBSRC remit classification**

67 Word limit: 1

68 Your application will be considered by one of our four research committees  
69 made up of independent experts. Indicate which you feel would be best placed  
70 to assess your application.

71 In the text box, write only the letter (in uppercase) corresponding to the  
72 committee you feel would be best placed to assess your application. These  
73 are:

74 **A** animal disease, health and welfare

75 **B** plants, microbes, food and sustainability

76 **C** genes, development, and science, technology, engineering and maths (STEM)  
77 approaches to biology

78 **D** molecules, cells and industrial biotechnology

79 Additional guidance:

80 This is for administrative purposes to help the initial application pro-  
81 cessing. We will check your choice and make a final decision as to which  
82 committee will assess your application.

### 83 3.3 Vision

84 Word limit: 550

85 What are you hoping to achieve with your proposed work?

86 What the assessors are looking for in your response

87 Explain how your proposed work:

- 88 1. is of excellent quality and importance within or beyond the field(s) or  
89 area(s)
- 90 2. has the potential to advance current understanding, or generate new  
91 knowledge, thinking or discovery within or beyond the field or area
- 92 3. is timely given current trends, context, and needs
- 93 4. impacts world-leading research, society, the economy, or the environ-  
94 ment

95 You may demonstrate elements of your responses in visual form if rele-  
96 vant. Further details are provided in the Funding Service. References may  
97 be included within this section.

#### 98 3.3.1 Context

99 Conventional systems neuroscience experiments are typically short in dura-  
100 tion and often place significant constraints on subjects behaviours to simplify  
101 data analysis. However, these restrictions may limit our ability to observe  
102 critical aspects of brain function and behaviour that only manifest in more  
103 naturalistic and extended conditions.

104 At the Sainsbury Wellcome Centre (SWC) and Gatsby Computational  
105 Neuroscience Unit (GCNU) we are pioneering **Naturalistic, Long-Duration,**  
106 **and Continual (NaLoDuCo) experiments** in mice that span weeks to  
107 months. During these experiments, we collect high-resolution behavioural  
108 and neural recordings in naturalistic settings (Figure 1).

109 To support this endeavor, we are developing the **AEON platform**, an  
110 innovative set of hardware and software tools for NaLoDuCo experimen-  
111 tal control, data store and access. We are using this platform to investi-  
112 gate the neural basis of foraging behavior in mice over prolonged periods of  
113 time (Campagner et al., 2024).

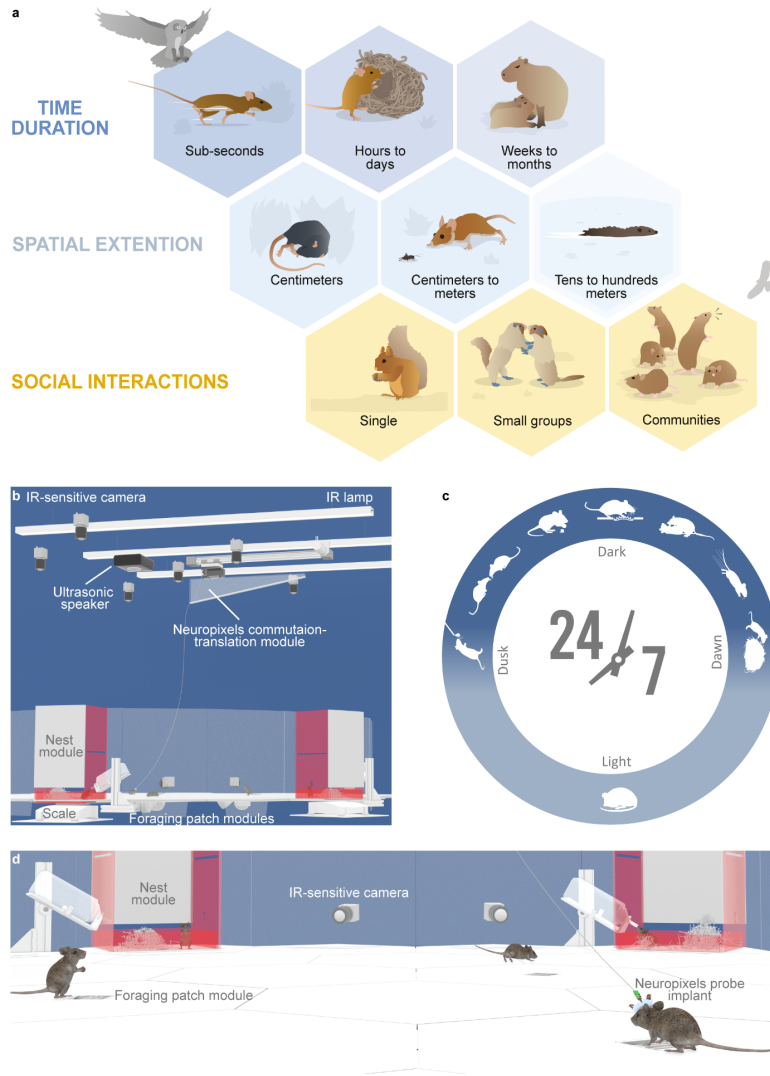


Figure 1: **a**: Example of natural behaviours in rodents that take place over different timescale, spatial extensions and involving different numbers of individuals.

**b-d**: Close-up views of one possible configuration of the Aeon environment in which naïve mice and mice chronically implanted with Neuropixels probe can live while expressing a variety of natural behaviours including exploring, drinking, escaping, foraging, nesting, sleeping, eating and interacting socially.

114 Our US partner, the **Allen Institute for Neural Dynamics (AIND)**  
115 is also performing NaLoDuCo experimentation, using the AEON platform,  
116 studying naturalistic olfactory learning over weeks to month outside conven-  
117 tional task structures (Fink et al., 2024).

118 **NeuroGEARS Ltd**, our industrial partner, is a UK-based company sup-  
119 porting academic institutions implementing innovative technology for scien-  
120 tific investigation. It is the main developer of the **Bonsai** software ecosystem  
121 for experimental control (Lopes et al., 2015), used by thousands of scientists  
122 around the world, and powering the AEON platform. NeuroGEARS has  
123 played a central role in the development of the AEON platform, and pro-  
124 vides services to both the SWC and the AIND.

125 NaLoDuCo experimentation will enable researchers to explore neural mech-  
126 anisms underlying ethological behaviours in naturalistic environments over  
127 months, for the first time. The experiments will shed new light on a wide  
128 range of poorly understood neural mechanisms, including how the brain  
129 structures complex behavioural sequences as a function of the animal needs,  
130 learning, adaptation, sleep-dependent memory consolidation and social dy-  
131 namics. **The data generated from NaLoDuCo experiments represent**  
132 **an entirely new resource in neuroscience**, with the potential to drive  
133 breakthroughs and discoveries that are beyond the reach of traditional ex-  
134 periments.

135 While **naturalistic, long-duration, or continuous** neuroscience ex-  
136 periments have been conducted in the past (Nagy et al., 2023; Ho et al.,  
137 2023; Ray et al., 2025; Weissbrod et al., 2013; Dhawale et al., 2017; Newman  
138 et al., 2024), to the best of our knowledge, **we are the first ones to inte-**  
139 **grate all three of these features in a single experimental paradigm.**

140 This emerging paradigm of long-duration experimentation is poised to  
141 become mainstream in the coming years. However, experiments spanning  
142 weeks to months generate massive datasets—often reaching hundreds of ter-  
143 abytes—posing significant challenges in data acquisition, management, distri-  
144 bution, visualization, and analysis. To address these challenges, we (GCNU,  
145 SWC, AIND, and NeuroGEARS Ltd) will collaboratively extend the AEON  
146 platform with functionality to **visualise and statistically analyze pre-**  
147 **viously collected NaLoDuCo experimental data on the cloud**, and  
148 **to perform real-time machine to enable the intelligent control of**  
149 **NaLoDuCo experiments.**



### 3.3.2 Specific aims

Data generated by NaLoDuCo experiments will be of general interest to the neuroscience community. **We want to share our NaLoDuCo foraging and odor learning recordings and allow other groups collecting this type of data to share their own.** However, this dissemination is not trivial, as datasets are of the order of hundreds of terabytes, and it will take users several days to download them over standard Internet connections.

Instead of bringing data to users, we will bring users to data, by storing datasets in the cloud (or in institutional clusters), and providing **cloud software to allow users to visually explore and statistically analyse behavioural and neural NaLoDuCo datasets where they live** (1 and 2 in Figure 2).

Our statistical analysis of neural time series will require knowledge of the spiking activity of single units; i.e., spike sorting. In long-duration experiments with freely moving animals spike sorting is a challenging problem, because movements of recording probes change the shape of spike waveforms over time and complicate the assignment of spikes to units based on their waveforms. We will address this problem by developing **spike sorting methods for long-duration, continual and high-channel-count recordings** (3 in Figure 2).

Funded by a BBSRC award we are adding machine learning functionality to Bonsai in order to enable a new type of experimentation controlled by advanced machine learning inference on behavioral and neural recordings (Bonsai.ML, [Guilbeault et al., 2025](#)). We have developed this functionality for conventional short duration experiments. We will **add to Bonsai.ML real-time machine learning functionality tailored to nonstationary data**, such as that generated in NaLoDuCo experiments.

Most of the neural data analysis methods that we will add to AEON require sorted spikes. We will **adapt the offline spike sorting methods mentioned above to operate under the strict time constraints of real-time experiments** (5 in Figure 2).

## References

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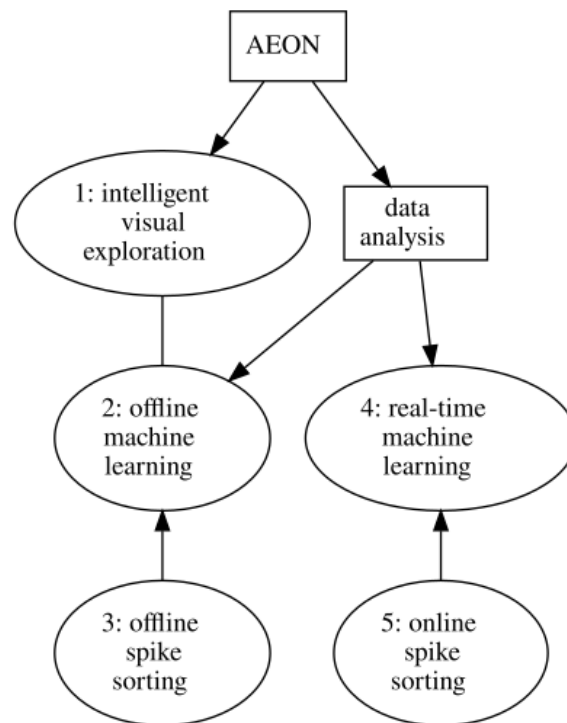


Figure 2: Specific aims

184 Pouget, A., Rapela, J., Ryan, T., Reggiani, J., and Group, S. S.  
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186 neural basis of ethological behaviours over naturalistic timescales.  
187 [https://www.sfn.org/-/media/SfN/Documents/NEW-SfN/Meetings/](https://www.sfn.org/-/media/SfN/Documents/NEW-SfN/Meetings/Neuroscience-2024/Abstracts-and-Sessions/Abstract-PDFs/SFN24_Abstracts-PDF-Posters_SAT_PM.pdf)  
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## 223 3.4 Approach

224 Word limit: 3,300

225 How are you going to deliver your proposed work?

226 What the assessors are looking for in your response

227 Explain how you have designed your approach so that it:

- 228 1. is effective and appropriate to achieve your objectives
- 229 2. is feasible, and comprehensively identifies any risks to delivery and how  
230 they will be managed
- 231 3. uses a clearly written and transparent methodology (if applicable)
- 232 4. summarises the previous work and describes how this will be built upon  
233 and progressed (if applicable)
- 234 5. will maximise translation of outputs into outcomes and impacts
- 235 6. describes how your, and if applicable your team's, research environment  
236 (in terms of the place and relevance to the project) will contribute to  
237 the success of the work

238 You may demonstrate elements of your responses in visual form if rele-  
239 vant.

240 Please make sure to check sizing and readability of the image using 'read  
241 view' prior to submission. Further details are provided in the Funding Ser-  
242 vice.

243 References may be included within this section.

244 Within the 'Approach' section we also expect you to:

- 245 • provide a detailed and comprehensive project plan including milestones  
246 and timelines in the form of an embedded Gantt chart or similar (please  
247 make sure to check sizing and readability of the image using 'read view'  
248 prior to submission)

249 BBSRC's [action plan for EDI](#) outlines our commitment to removing bar-  
250 riers to participation in our programmes, ensuring investments do not inad-  
251 vertently prevent access or usage by individuals from minority groups, for  
252 example disabled researchers.

253 To this end, applications should identify how accessibility and inclusive-  
254 ness in the widest sense have been incorporated into the design of the project.  
255 For example, you may wish to reference relevant institutional strategies and  
256 policies which support equality, diversity, and inclusion as they relate to ac-  
257 cess to equipment and facilities and indicate how the proposed project has  
258 been designed and will be delivered with broad access in mind.

259 We have collected unprecedented NaLoDuCo datasets at the SWC and  
260 AIND. However, these very large datasets are of not much help without  
261 methods to visually explore and analyse them. We will **disseminate a**  
262 **library of methods for visualisation and data analysis of NaLoDuCo**  
263 **experimental data**. Sections 3.4.1 and 3.4.2 present offline and online  
264 data analysis methods, Section 3.4.3 discusses visualization methods, and  
265 Sections 3.4.4 and 3.4.5 elaborate on offline and online spike sorting methods.

### 266 3.4.1 Offline Analysis Methods

267 Modern neuroscience lacks robust methods to characterize *long-duration and*  
268 *continual time series*, especially in settings where the statistical properties  
269 of the data evolve over time. Furthermore, few approaches are currently ca-  
270 pable of performing accurate *long-horizon forecasting*—over hours, days, or  
271 weeks—on behavioral or neural data. These limitations present a method-  
272 ological gap that must be addressed in order to unlock the scientific potential  
273 of NaLoDuCo experiments.

274 To bridge this gap, we will develop and disseminate software libraries  
275 that implement offline analysis methods specifically tailored to: (1) operate  
276 effectively under **non-stationary conditions**, and (2) scale to **very long**  
277 **time series**. When existing methods prove inadequate, we will create new  
278 algorithms. All implementations will be optimized for high-throughput, dis-  
279 tributed computation on large datasets.

### 280 Initial List of Methods to Include in the Library

281 We will initially populate this library with the methods already in use at  
282 GCNU, SWC, and AIND to analyze neural and behavioral data in NaLo-  
283 DuCo foraging and olfactory learning experiments in mice. These meth-  
284 ods span multiple domains—kinematics, neural dynamics, behavioral state  
285 segmentation, forecasting, and joint modeling—and are grouped below by  
286 function.

287 **Behavioral Analysis:** The first step in behavioral analysis involves multi-  
288 body-part tracking. For this, we will use **deep learning-based pose esti-**  
289 **mation** methods such as **SLEAP**, which allow tracking of multiple unmarked  
290 mice across long durations.

291 Next, we will infer continuous kinematic variables from these pose esti-  
292 mates using **linear dynamical systems (LDS)**, including variants based  
293 on particle filters (see **LDS**). These features will be used to infer discrete be-  
294 havioral states with **Hidden Markov Models (HMMs)**, as implemented  
295 in tools such as **MoSeq**.

296 We will relate behavioral kinematics and inferred states to foraging-related  
297 outcomes (e.g., patch-leaving decisions) using both **generalized linear mod-**  
298 **els (GLMs)** and **deep neural networks**. For long-horizon prediction  
299 of behavioral trajectories, we will implement **recurrent neural networks**  
300 **(RNNs)** and **transformer architectures**. To infer behavioral policies, we  
301 will apply **inverse reinforcement learning** methods such as **HIQL**.

302 **Neural Data Analysis:** Analysis of high-density electrophysiology will be-  
303 gin with **latent variable modeling** to reduce the dimensionality of multi-  
304 electrode recordings. We will use both linear and nonlinear approaches, in-  
305 cluding **svGPFA** (a Gaussian Process latent dynamical model) and **LFADS**  
306 (a deep generative model based on RNNs).

307 The latent trajectories will be used as inputs to infer discrete neural states  
308 via **HMMs**, using libraries such as **SSM**. For long-duration forecasting of  
309 neural activity, we will again employ **RNNs** and **transformers**.

310 We will also perform spatial decoding from hippocampal spikes using  
311 **point-process decoders**, enabling the study of long-term replay during  
312 naturalistic foraging, as implemented in **replay\_trajectory\_classification**.

313 **Joint Neural-Behavioral Modeling:** To better understand the relation-  
314 ships between neural and behavioral processes, we will develop models that  
315 extract **shared latent variables** from both domains. This includes **Recognition-**  
316 **Parametrized Models (RPM)**, a method developed at the GCNU for joint in-  
317 ference from multiple modalities, and **CEBRA**, a recent contrastive learning  
318 approach for multimodal representation learning.

## 319 Non-stationarity

320 Many conventional methods for analyzing neural and behavioral time series  
321 assume that the underlying data-generating processes are stationary—that  
322 is, their statistical properties remain constant over time. While this assump-  
323 tion may be acceptable in short-duration experiments, it breaks down in  
324 long-duration and continual recordings. In such settings, animals learn and  
325 adapt, their internal states and motivations fluctuate, and their behavior and  
326 physiology are influenced by biological rhythms such as circadian, ultradian,  
327 and infradian cycles. These changes induce non-stationarity in the data,  
328 making models that assume stationarity progressively less reliable or even  
329 obsolete.

330 To address this challenge, we will adapt and develop methods that are  
331 explicitly designed to operate in non-stationary environments. Our approach  
332 draws on techniques from multiple domains, including adaptive signal pro-  
333 cessing, machine learning, and Bayesian inference.

334 **Adaptive Signal Processing.** The field of adaptive signal processing has  
335 produced robust methods for modeling linear systems with time-varying dy-  
336 namics (Haykin, 2002). The recursive least-squares (RLS) algorithm, for  
337 example, is a well-known adaptation of the ordinary least squares algorithm  
338 that continuously updates model parameters to perform linear regression  
339 under non-stationary conditions. We will use generalized versions of RLS to  
340 study time-varying relations between behavioral states, as inferred by hidden  
341 Markov models, and mice decisions, like when to leave a foraging patch.

342 **Neural Networks and Continual Learning.** For nonlinear models such  
343 as artificial neural networks, a wide range of strategies have been proposed  
344 to handle non-stationarity. The subfield of *continual learning* has intro-  
345 duced techniques such as Elastic Weight Consolidation (EWC) and Learning  
346 Without Forgetting (LwF), which preserve performance on previously learned  
347 tasks while adapting to new data. Experience Replay (ER), another tech-  
348 nique from this domain, maintains a buffer of historical data that is replayed  
349 during training to avoid catastrophic forgetting. Ensemble methods further  
350 enhance robustness by combining models with different adaptability profiles,  
351 for example, models trained on different time windows or with varied learning  
352 rates.



353 **Adaptive State-Space Models.** In state-space modeling, the Kalman  
354 filter provides a principled way to handle non-stationary Gaussian processes  
355 with drifting mean and covariance. More flexible approaches are needed when  
356 data exhibit abrupt regime shifts or complex latent dynamics. Switching  
357 state-space models, such as Switching Linear Dynamical Systems (SLDS)  
358 and Switching Hidden Markov Models (sHMMs), model discrete changes in  
359 underlying system dynamics. For nonlinear, non-Gaussian signals, particle  
360 filters approximate the posterior distribution through sequential sampling.  
361 Bayesian online learning techniques offer a general framework for continually  
362 updating model parameters as new data arrive.

363 **Concept Drift in Machine Learning.** In the machine learning litera-  
364 ture, non-stationarity is often studied under the framework of *concept drift* (?),  
365 which refers to shifts in the joint distribution of inputs and outputs over time.  
366 Unlike adaptive signal processing, many concept drift techniques are model-  
367 agnostic and can be layered on top of various learning architectures. Drift  
368 may be sudden, gradual, or cyclical (e.g., re-emergence of behavioral patterns  
369 linked to circadian modulation). Effective strategies involve drift detection  
370 followed by targeted model updates or retraining. Ensemble approaches can  
371 also be used to mitigate drift by weighting component models according to  
372 recent predictive accuracy.

373 Although many concept drift methods have been developed for supervised  
374 learning, unsupervised extensions exist, including drift detection via cluster-  
375 ing evolution, density monitoring, or changes in autoencoder reconstruction  
376 loss. These tools are particularly relevant in our setting, where labeled data  
377 may be sparse or unavailable.

378 In summary, robust modeling of NaLoDuCo datasets demands tools that  
379 adapt continuously to changing data distributions. Our offline analysis frame-  
380 work will incorporate both well-established adaptive algorithms and cutting-  
381 edge methods from continual learning and concept drift research to address  
382 this fundamental challenge.

### 383 **Computational efficiency**

384 Neural and behavioral data analysis is most effective when computations  
385 are performed quickly, ideally in real time. Slow computations discourage  
386 data exploration and hinder scientific discovery. The large dataset sizes gen-  
387 erated by NaLoDuCo experimentation pose a significant challenge for fast

388 data analysis.

389 To overcome this limitation, we will combine distributed and GPU com-  
390 puting. Distributed computing is a paradigm in which tasks and data are  
391 divided across multiple computers. Instead of relying on a single powerful  
392 machine, distributed computing accelerates processing by executing multiple  
393 parts of a computation in parallel. GPU computing is a parallel computing  
394 approach that uses Graphics Processing Units (GPUs) to accelerate compu-  
395 tational tasks. Unlike traditional Central Processing Units (CPUs), which  
396 execute a few complex operations sequentially, GPUs consist of thousands of  
397 smaller cores optimized for executing many operations simultaneously.

398 Distributed and GPU computing address different bottlenecks in large-  
399 scale computation. GPUs are highly efficient at parallelizing operations  
400 within a single machine. They excel at matrix operations and batch process-  
401 ing. However, GPUs are limited by memory and cannot scale indefinitely  
402 when dealing with huge datasets that exceed the GPU memory. Distributed  
403 computing allows to split workload across multiple machines, overcoming  
404 memory and computational limitations. It is particularly useful for scaling  
405 to massive datasets (e.g., long-term time series recordings).

406 We will develop accelerated implementations of all methods in the library  
407 of methods to process NaLoDuCo experimental data (Section 3.4.1). These  
408 implementations will use JAX<sup>1</sup> for model learning, inference, and numerical  
409 computation, Apache Spark<sup>2</sup> or Dask<sup>3</sup> to distribute pre-processing and fea-  
410 ture extraction, and Ray<sup>4</sup> to distribute machine learning and deep learning  
411 functionality.

412 Thunder is a library developed in 2014 to accelerate the analysis of  
413 large scale neural data. It was pioneering by introducing the use of dis-  
414 tributed computing in neural data analysis. Our library is different from  
415 Thunder in that, besides analyzing large scale neural data, it processes con-  
416 tinual recordings, and needs to overcome non-stationarity problems. In ad-  
417 dition, it includes methods to characterize behavior, while Thunder focuses  
418 on neural activity. Finally, Thunder implements simpler methods assuming  
419 independent and identically distributed data, while our library contains more  
420 sophisticated time series ones.

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<sup>1</sup><https://docs.jax.dev/>

<sup>2</sup><https://spark.apache.org/>

<sup>3</sup><https://www.dask.org/>

<sup>4</sup><https://docs.ray.io/>

## 421 **3.4.2 Online Machine Learning**

### 422 **3.4.2.1 Outputs**

- 423 1. Bonsai packages implementing real-time ML functionality for experimental  
424 control
- 425 2. Documentation of these packages

## 426 **3.4.3 Visual Exploration**

### 427 **3.4.3.1 Outputs**

- 428 1. visualisations for continuous behavioural and neural recording
- 429 2. visualisations for epoched behavioural and neural recording
- 430 3. visualisations for model outputs
- 431 4. indexing system to support intelligent visualisations
- 432 5. deployment of the above items to allow users to visualise NaLoDuCo  
433 DANDI datasets on the cloud

## 434 **3.4.4 Offline spike Sorting**

### 435 **3.4.4.1 Outputs**

- 436 1. Repository with implementations and benchmarking of offline spike  
437 sorting algorithms for long-duration recordings

## 438 **3.4.5 Online spike Sorting**

### 439 **3.4.5.1 Outputs**

- 440 1. Repository with implementations and benchmarking of online spike  
441 sorting algorithms

## 442 **References**

- 443 Haykin, S. S. (2002). *Adaptive filter theory*. Pearson Education India.

### 444 3.5 Applicant and team capability to deliver

445 Word limit: 1,650

446 Why are you the right individual or team to successfully deliver the pro-  
447 posed work?

448 What the assessors are looking for in your response

449 Please ensure the current job titles of the core team members are included  
450 here to ensure eligibility can be established for the core team roles assigned.  
451 Find out more about [UKRI's core team roles in funding applications](#) and our  
452 [eligibility guidance](#).

453 Evidence of how you, and if relevant your team, have:

- 454 • the relevant experience (appropriate to career stage) to deliver the pro-  
455 posed work
- 456 • the right balance of skills and expertise to cover the proposed work
- 457 • the appropriate leadership and management skills to deliver the work  
458 and your approach to develop others
- 459 • contributed to developing a positive research environment and wider  
460 community

461 You may demonstrate elements of your responses in visual form if rele-  
462 vant.

463 Further details are provided in the Funding Service.

464 The word limit for this section is 1,650 words: 1,150 words to be used for  
465 R4RI modules (including references) and, if necessary, a further 500 words  
466 for Additions.

467 Use the Résumé for Research and Innovation (R4RI) format to showcase  
468 the range of relevant skills you and, if relevant, your team (project and project  
469 co-leads, researchers, technicians, specialists, partners and so on) have and  
470 how this will help deliver the proposed work. You can include individuals'  
471 specific achievements but only choose past contributions that best evidence  
472 their ability to deliver this work.

473 Complete this section using the R4RI module headings listed. Use each  
474 heading once and include a response for the whole team, see the UKRI guid-  
475 ance on R4RI. You should consider how to balance your answer, and empha-  
476 sise where appropriate the key skills each team member brings:

- 477     • contributions to the generation of new ideas, tools, methodologies, or  
478       knowledge
- 479     • the development of others and maintenance of effective working rela-  
480       tionships
- 481     • contributions to the wider research and innovation community
- 482     • contributions to broader research or innovation users and audiences  
483       and towards wider societal benefit

#### 484     Additions

485     Provide any further details relevant to your application. This section is  
486     optional and can be up to 500 words. You should not use it to describe  
487     additional skills, experiences, or outputs, but you can use it to describe any  
488     factors that provide context for the rest of your R4RI (for example, details  
489     of career breaks if you wish to disclose them).

490     Complete this as a narrative. Do not format it like a CV.

491     References may be included within this section.

492     The roles in funding applications policy has descriptions of the different  
493     project roles.

## 494 **3.6 Project partners**

495 Add details about any project partners' contributions. If there are no project  
496 partners, you can indicate this on the Funding Service.

497 A project partner is a collaborating organisation who will have an integral  
498 role in the proposed research. This may include direct (cash) or indirect (in-  
499 kind) contributions such as expertise, staff time or use of facilities. Project  
500 partners may be in industry, academia, third sector or government organisa-  
501 tions in the UK or overseas, including partners based in the EU.

502 If you are applying via the IPA or LINK scheme, please include details  
503 of industry partners here.

504 If applying under the BBSRC-NSF lead agency scheme, please include  
505 details of your US partner here.

506 Add the following project partner details:

- 507 • the organisation name and address (searchable via a drop-down list or  
508 enter the organisation's details manually, as applicable)
- 509 • the project partner contact name and email address
- 510 • the type of contribution (direct or in-direct) and its monetary value

511 If a detail is entered incorrectly and you have saved the entry, remove the  
512 specific project partner record and re-add it with the correct information.

513 For audit purposes, UKRI requires formal collaboration agreements to be  
514 put in place if an award is made.

### 515 **3.7 Project partners: statement of support**

516 Word limit: 3,000

517 Only complete a statement of support if you have named project partners  
518 in the project partner section above. A statement is required to be provided  
519 from each partner you named in the ‘Project partners’ section.

520 If you are applying via the IPA or LINK scheme, please include details  
521 of industry partner support here.

522 What the assessors are looking for in your response

523 A project partner is a collaborating organisation who will have an integral  
524 role in the proposed research. This may include direct (cash) or indirect (in-  
525 kind) contributions such as expertise, staff time or use of facilities.

526 Each statement should:

- 527 • confirm the partner’s commitment to the project
- 528 • clearly explain the value, relevance, and possible benefits of the work  
529 to them
- 530 • describe any additional value that they bring to the project

531 Ensure you have prior agreement from project partners so that, if you are  
532 offered funding, they will support your project as indicated in the ‘Project  
533 partners’ section.

534 For audit purposes, UKRI requires formal collaboration agreements to be  
535 put in place if an award is made.

536 Do not provide a statement of support from host and project co-leads’  
537 research organisations.

538 Do not provide a statement of support from collaborators. Contributions  
539 from collaborators not listed as project partners can be outlined in ‘Applicant  
540 and team capability to deliver’.