

# Solution for the worksheet **temporal time series analysis**

Joaquin Rapela

February 10, 2025

1. The random process in Eq. 1 of the **worksheet** is an autoregressive model of order one, AR(1).

When  $|\phi| < 1$ , as show in the **lecture** slide **Mean function** containing **Example (Mean function of the autoregressive model of order 1)**, the mean of this AR(1) model is zero.

When  $|\phi| < 1$ , as show in the **lecture** slide **Autovariance function** containing **Example (Autocovariance function of AR(1))**, the covariance of an AR(1) random process is  $\gamma(t+h, t) = \phi^h \sigma_w^2 \frac{1}{1-\phi^2}$ . Therefore, the variance of this AR(1) random process is  $\sigma^2 = \sigma_w^2 \frac{1}{1-\phi^2}$ .

When  $|\phi| < 1$ , because (1) its mean is constant, (2) its variance is also constant and (3) its covariance does not depend on  $t$ , the AR(1) random process is wide-sense stationary (WSS).

When  $|\phi| \geq 1$ , assume  $\{x_t\}$  is WSS, then, because the variance of the sum of independent random variables is the sum of their variances, and because  $x_{t-1}$  and  $w_t$  are uncorrelated Gaussian random variables, and therefore independent random variables,  $\sigma_x^2 = \text{var}\{x_t\} = \phi^2 \text{var}\{x_{t-1}\} + \text{var}\{w_t\} = \phi^2 \sigma_x^2 + \sigma_w^2$  or  $\sigma_x^2 = \frac{\sigma_w^2}{1-\phi^2}$ . The last equality states that  $\sigma_x^2 < 0$ , because  $|\phi| \geq 1$ , which cannot be. This wrong result arose from our assumption that, when  $|\phi| \geq 1$ ,  $\{x_t\}$  was WSS. Therefore, when  $|\phi| \geq 1$ ,  $\{x_t\}$  cannot be WSS.

2. The code to generate the figures in the **lecture** slide titled **Analytical and estimated autocovariance function for AR(1)** and the generated figures are available **here**.
3. For the random walk with drift model:

- (a) The covariance function  $\gamma(s, t)$  is

$$\begin{aligned}\gamma(t, s) &= E\{(x_t - \mu_t)(x_s - \mu_s)\} = E\left\{\left(\left(\delta t + \sum_{i=0}^t w_i\right) - \delta t\right)\left(\left(\delta s + \sum_{j=0}^s w_j\right) - \delta s\right)\right\} \\ &= E\left\{\left(\sum_{i=0}^t w_i\right)\left(\sum_{j=0}^s w_j\right)\right\} = E\left\{\sum_{i=0}^t \sum_{j=0}^s w_i w_j\right\} \\ &= \sum_{i=0}^t \sum_{j=0}^s E\{w_i w_j\} = \sum_{k=0}^{\min(t,s)} E\{w_k^2\} = \sum_{k=0}^{\min(t,s)} \sigma_w^2 = \min(t, s) \sigma_w^2\end{aligned}$$

Then the variance function  $\text{var}(t)$  is

$$\text{var}(t) = \gamma(t, t) = t \sigma_w^2$$

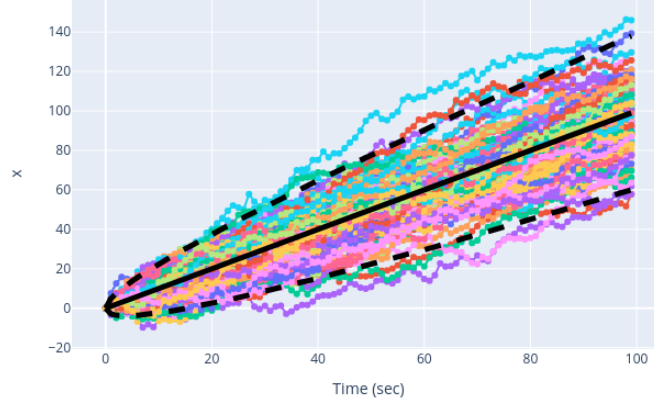


Figure 1: One hundred samples of a random walk with drift process (colour traces). The solid line is the mean of the random process and the dotted lines mark the 95% confidence interval. At any time point 95% of the samples (i.e., 5 samples) should lie above or below the dotted lines. Click on the figure to see its interactive version.

- (b) Figure 1 plots 100 samples of a random walk with drift model, its mean function and its 95% confidence bounds. That approximately 5 samples escape the confidence bounds at any time point suggest that the calculated variance function is correct.
- (c) The random walk with drift process is not wide-sense stationary because (1) when  $\delta \neq 0$  the mean is not constant, (2) the variance is neither constant, and (3) the autocovariance function does not depend only on the time separation of its arguments.