

Pedantic description of the svGPFA theory

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Abstract

Here we provide a pedantic description of the sparse variational Gaussian process factor analysis (svGPFA) theory, expanding on Duncker and Sahani (2018b,a).

1 GPFA model

$$\begin{aligned} p(\{x_{kr}(\cdot)\}_{k=1, r=1}^{K, R}) &= \prod_{r=1}^R \prod_{k=1}^K p(x_{kr}(\cdot)) \\ x_{kr}(\cdot) &\sim \mathcal{GP}(\mu_k(\cdot), \kappa_k(\cdot, \cdot)) \quad \text{for } k = 1, \dots, K \text{ and } r = 1, \dots, R \\ h_{nr}(\cdot) &= \sum_{k=1}^K c_{nk} x_{kr}(\cdot) + d_n \quad \text{for } n = 1, \dots, N \text{ and } r = 1, \dots, R \\ p(\{\mathbf{y}_{nr}\}_{n=1, r=1}^{N, R} | \{h_{nr}(\cdot)\}_{n=1, r=1}^{N, R}) &= \prod_{r=1}^R \prod_{n=1}^N p(\mathbf{y}_{nr} | h_{nr}(\cdot)) \end{aligned} \tag{1}$$

where $x_{kr}(\cdot)$ is the latent process k in trial r , $h_{nr}(\cdot)$ is the embedding process for neuron n and trial r and \mathbf{y}_{nr} is the activity of neuron n in trial r .

Notes:

- the first equation shows that the latent processes are independent,
- the second equation shows that the latent processes share mean and covariance functions across trials. That is, for any k , the mean and covariance functions of latents processes of different trials, $x_{kr}(\cdot)$, $r = 1, \dots, R$, are the same ($\mu_k(\cdot)$ and $\kappa_k(\cdot, \cdot)$),
- the fourth equation shows that, given the embedding processes, the responses of different neurons are independent.

2 svGPFA prior

To use the sparse variational framework for Gaussian processes Duncker and Sahani (2018b) augmented the GPFA model by introducing inducing points \mathbf{u}_{kr} for each latent process k and trial r . The inducing points \mathbf{u}_{kr} represent evaluations of the latent process $x_{kr}(\cdot)$ at the M_{kr} locations \mathbf{z}_{kr} . A joint prior over the latent process $x_{kr}(\cdot)$ and its inducing points \mathbf{u}_{kr} is given in Eq. 2.

$$\begin{aligned}
p(\{x_{kr}(\cdot)\}_{k=1,r=1}^{K,R}, \{\mathbf{u}_{kr}\}_{k=1,r=1}^{K,R}) &= p(\{x_{kr}(\cdot)\}_{k=1,r=1}^{K,R} | \{\mathbf{u}_{kr}\}_{k=1,r=1}^{K,R}) p(\{\mathbf{u}_{kr}\}_{k=1,r=1}^{K,R}) \\
p(\{x_{kr}(\cdot)\}_{k=1,r=1}^{K,R} | \{\mathbf{u}_{kr}\}_{k=1,r=1}^{K,R}) &= \prod_{k=1}^k \prod_{r=1}^R p(x_{kr}(\cdot) | \mathbf{u}_{kr}) \\
p(\{\mathbf{u}_{kr}\}_{k=1,r=1}^{K,R}) &= \prod_{k=1}^k \prod_{r=1}^R p(\mathbf{u}_{kr}) \\
p(\mathbf{u}_{kr}) &= \mathcal{N}(\mathbf{0}, K_{zz}^{kr})
\end{aligned} \tag{2}$$

where $K_{zz}^{(kr)}[i, j] = \kappa_k(\mathbf{z}_{kr}[i], \mathbf{z}_{kr}[j])$.

We next derive the functional form of $p(x_{kr}(\cdot) | \mathbf{u}_{kr})$.

Define the random vector \mathbf{x}_{kr} as the random process $x_{kr}(\cdot)$ evaluated at times $\mathbf{t}^{(r)} := \{t_1^{(r)}, \dots, t_M^{(r)}\}$ (i.e., $\mathbf{x}_{kr} := [x_{kr}(t_1^{(r)}), \dots, x_{kr}(t_M^{(r)})]^\top$). Then, because the inducing points \mathbf{u}_{kr} are evaluations of the latent process $x_{kr}(\cdot)$ at \mathbf{z}_{kr} , \mathbf{x}_{kr} and \mathbf{u}_{kr} are jointly Gaussian:

$$p\left(\begin{bmatrix} \mathbf{u}_{kr} \\ \mathbf{x}_{kr} \end{bmatrix}\right) = \mathcal{N}\left(\begin{bmatrix} \mathbf{u}_{kr} \\ \mathbf{x}_{kr} \end{bmatrix} \middle| \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} K_{zz}^{(kr)} & K_{zt}^{(kr)} \\ K_{tz}^{(kr)} & K_{tt}^{(r)} \end{bmatrix}\right) \tag{3}$$

where $K_{tz}^{(kr)}[i, j] = \kappa_k(t_i^{(r)}, \mathbf{z}_{kr}[j])$, $K_{zt}^{(kr)}[i, j] = \kappa_k(\mathbf{z}_{kr}[i], t_j^{(r)})$ and $K_{tt}^{(r)}[i, j] = \kappa_k(t_i^{(r)}, t_j^{(r)})$.

Now, applying the formula for the conditional pdf of jointly Normal random vectors (Bishop, 2016, Eq. 2.116) to Eq. 3, we obtain

$$p(\mathbf{x}_{kr} | \mathbf{u}_{kr}) = \mathcal{N}\left(\mathbf{x}_{kr} \middle| K_{tz}^{(kr)} \left(K_{zz}^{(kr)}\right)^{-1} \mathbf{u}_{kr}, K_{tt}^{(r)} - K_{tz}^{(kr)} \left(K_{zz}^{(kr)}\right)^{-1} K_{zt}^{(kr)}\right) \tag{4}$$

Because Eq. 4 is valid for any $\mathbf{t}^{(r)}$, it follows that

$$p(x_{kr}(\cdot) | \mathbf{u}_{kr}) = \mathcal{GP}(\tilde{\mu}_{kr}(\cdot), \tilde{\kappa}_{kr}(\cdot, \cdot))$$

with

$$\begin{aligned}
\tilde{\mu}_{kr}(t) &= \kappa_k(t, \mathbf{z}_{kr}) \left(K_{zz}^{(kr)}\right)^{-1} \mathbf{u}_{kr}, \\
\tilde{\kappa}_{kr}(t, t') &= \kappa_k(t, t') - \kappa_k(t, \mathbf{z}_{kr}) \left(K_{zz}^{(kr)}\right)^{-1} \kappa_k(\mathbf{z}_{kr}, t')
\end{aligned}$$

which is Eq. 3 in Duncker and Sahani (2018b).

3 Derivation of the svGPFA variational lower bound

To derive the sparse variational lower bound we have the freedom of using $\{x_{kr}(\cdot)\}_{k=1,r=1}^{K,R}$ or $\{h_{nr}(\cdot)\}_{n=1,r=1}^{N,R}$ as latent processes in the complete-data likelihood¹. In Duncker and Sahani (2018a) the authors used the former, which requires the non-trivial proof of Eq. 5.

¹To simplify notation below we write $\{x_{kr}(\cdot)\}_{k=1,r=1}^{K,R}$ as $\{x_{kr}(\cdot)\}$ and similarly for $\{\mathbf{u}_{kr}\}_{k=1,r=1}^{K,R}$ and $\{h_{nr}(\cdot)\}_{n=1,r=1}^{N,R}$

$$\mathbb{E}_{q(\{x_{kr}(\cdot)\})} \log p(\{\mathbf{y}_{nr}\}|\{x_{kr}(\cdot)\}) = \mathbb{E}_{q(\{h_{nr}(\cdot)\})} \log p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\}) \quad (5)$$

Here we use the latter, which avoids the need of Eq. 5. Then the complete data likelihood is given in Eq. 6 and a variational lower bound in Eq. 7.

$$p(\{\mathbf{y}_{nr}\}, \{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) = p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\})p(\{h_{nr}(\cdot)\}|\{\mathbf{u}_{kr}\})p(\{\mathbf{u}_{kr}\}) \quad (6)$$

$$\log p(\{\mathbf{y}_{nr}\}) \geq \mathbb{E}_{q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})} \log (p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) - KL \{q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})||p(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})\} \quad (7)$$

As in Duncker and Sahani (2018a), we choose the approximating variational distribution in Eq. 8.

$$\begin{aligned} q(\{x_{kr}(\cdot)\}, \{\mathbf{u}_{kr}\}) &= q(\{x_{kr}(\cdot)\}|\{\mathbf{u}_{kr}\})q(\{\mathbf{u}_{kr}\}) \\ q(\{x_{kr}(\cdot)\}|\{\mathbf{u}_{kr}\}) &= p(\{x_{kr}(\cdot)\}|\{\mathbf{u}_{kr}\}) \\ q(\{\mathbf{u}_{kr}\}) &= \prod_{r=1}^R \prod_{k=1}^K q(\mathbf{u}_{kr}) \\ q(\mathbf{u}_{kr}) &= \mathcal{N}(\mathbf{u}_{kr}|\mathbf{m}_{kr}, S_{kr}) \end{aligned} \quad (8)$$

Because $h_{nr}(\cdot)$ is a function of $\{x_{kr}(\cdot)\}$ only (Eq. 1), and because $q(\{x_{kr}(\cdot)\}|\{\mathbf{u}_{kr}\}) = p(\{x_{kr}(\cdot)\}|\{\mathbf{u}_{kr}\})$ (Eq. 8), then

$$q(\{h_{nr}(\cdot)\}|\{\mathbf{u}_{kr}\}) = p(\{h_{nr}(\cdot)\}|\{\mathbf{u}_{kr}\}) \quad (9)$$

The first term in Eq. 7 can be rewritten as

$$\begin{aligned}
& E_{q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})} \log(p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})) = \\
& \int \int q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) \log(p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})) d\{\mathbf{u}_{kr}\} d\{h_{nr}(\cdot)\} = \\
& \int \int q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) \log(p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\})) d\{\mathbf{u}_{kr}\} d\{h_{nr}(\cdot)\} = \\
& \int \left(\int q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) d\{\mathbf{u}_{kr}\} \right) \log(p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\})) d\{h_{nr}(\cdot)\} = \\
& \int q(\{h_{nr}(\cdot)\}) \log(p(\{\mathbf{y}_{nr}\}|\{h_{nr}(\cdot)\})) d\{h_{nr}(\cdot)\} = \\
& \int q(\{h_{nr}(\cdot)\}) \log \left(\prod_{r=1}^R \prod_{n=1}^N p(\mathbf{y}_{nr}|h_{nr}(\cdot)) \right) d\{h_{nr}(\cdot)\} = \\
& \sum_{r=1}^R \sum_{n=1}^N \int q(\{h_{nr}(\cdot)\}) \log(p(\mathbf{y}_{nr}|h_{nr}(\cdot))) d\{h_{nr}(\cdot)\} = \\
& \sum_{r=1}^R \sum_{n=1}^N \int \int q(\{h_{n'r'}(\cdot)\}_{n' \neq n, r' \neq r} | h_{nr}(\cdot)) q(h_{nr}(\cdot)) \log(p(\mathbf{y}_{nr}|h_{nr}(\cdot))) d\{h_{n'r'}(\cdot)\}_{n' \neq n, r' \neq r} dh_{nr}(\cdot) = \\
& \sum_{r=1}^R \sum_{n=1}^N \int \left(\int q(\{h_{n'r'}(\cdot)\}_{n' \neq n, r' \neq r} | h_{nr}(\cdot)) d\{h_{n'r'}(\cdot)\}_{n' \neq n, r' \neq r} \right) q(h_{nr}(\cdot)) \log(p(\mathbf{y}_{nr}|h_{nr}(\cdot))) dh_{nr}(\cdot) = \\
& \sum_{r=1}^R \sum_{n=1}^N \int q(h_{nr}(\cdot)) \log(p(\mathbf{y}_{nr}|h_{nr}(\cdot))) dh_{nr}(\cdot) = \\
& \sum_{r=1}^R \sum_{n=1}^N E_{q(h_{nr}(\cdot))} \log(p(\mathbf{y}_{nr}|h_{nr}(\cdot)))
\end{aligned} \tag{10}$$

Notes:

- the second line follows from the previous one because, given the embedding process, activities of neurons are independent of inducing points (Eq. 6),
- the fifth line follows from the previous one because, given embedding processes, responses of neurons are independent of each other (last line in Eq. 1),

The second term in Eq. 7 can be rewritten as

$$\begin{aligned}
KL\{q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) || p(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})\} &= \int \int q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) \log \frac{q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})}{p(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\})} d\{h_{nr}(\cdot)\} d\{\mathbf{u}_{kr}\} \\
&= \int \int q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) \log \frac{q(\{h_{nr}(\cdot)\} | \{\mathbf{u}_{kr}\}) q(\{\mathbf{u}_{kr}\})}{p(\{h_{nr}(\cdot)\} | \{\mathbf{u}_{kr}\}) p(\{\mathbf{u}_{kr}\})} d\{h_{nr}(\cdot)\} d\{\mathbf{u}_{kr}\} \\
&= \int \int q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) \log \frac{q(\{\mathbf{u}_{kr}\})}{p(\{\mathbf{u}_{kr}\})} d\{h_{nr}(\cdot)\} d\{\mathbf{u}_{kr}\} \\
&= \int \int q(\{h_{nr}(\cdot)\}, \{\mathbf{u}_{kr}\}) d\{h_{nr}(\cdot)\} \log \frac{q(\{\mathbf{u}_{kr}\})}{p(\{\mathbf{u}_{kr}\})} d\{\mathbf{u}_{kr}\} \\
&= \int q(\{\mathbf{u}_{kr}\}) \log \frac{q(\{\mathbf{u}_{kr}\})}{p(\{\mathbf{u}_{kr}\})} d\{\mathbf{u}_{kr}\} \\
&= \int q(\{\mathbf{u}_{kr}\}) \log \frac{\prod_{r=1}^R \prod_{k=1}^K q(\mathbf{u}_{kr})}{\prod_{r=1}^R \prod_{k=1}^K p(\mathbf{u}_{kr})} d\{\mathbf{u}_{kr}\} \\
&= \int q(\{\mathbf{u}_{kr}\}) \sum_{r=1}^R \sum_{k=1}^K \log \frac{q(\mathbf{u}_{kr})}{p(\mathbf{u}_{kr})} d\{\mathbf{u}_{kr}\} \\
&= \sum_{r=1}^R \sum_{k=1}^K \int q(\{\mathbf{u}_{kr}\}) \log \frac{q(\mathbf{u}_{kr})}{p(\mathbf{u}_{kr})} d\{\mathbf{u}_{kr}\} \\
&= \sum_{r=1}^R \sum_{k=1}^K \int \prod_{k'=1}^K \prod_{r'=1}^R q(\mathbf{u}_{k'r'}) \log \frac{q(\mathbf{u}_{kr})}{p(\mathbf{u}_{kr})} d\{\mathbf{u}_{kr}\} \\
&= \sum_{r=1}^R \sum_{k=1}^K \int q(\mathbf{u}_{kr}) \log \frac{q(\mathbf{u}_{kr})}{p(\mathbf{u}_{kr})} d\mathbf{u}_{kr} \\
&= \sum_{r=1}^R \sum_{k=1}^K KL(q(\mathbf{u}_{kr}) || p(\mathbf{u}_{kr}))
\end{aligned} \tag{11}$$

Notes:

- the third line follows from the previous one by Eq. 9,
- the tenth line follows from the previous because, for $k' \neq k$ or $r' \neq r$, the factors $q(\mathbf{u}_{k'r'})$ integrate out to one.

Replacing Eq. 10 and Eq. 11 into Eq. 7 we obtain

$$\log p(\{\mathbf{y}_{nr}\}) \geq \sum_{r=1}^R \sum_{n=1}^N E_{q(h_{nr}(\cdot))} \log(p(\mathbf{y}_{nr} | h_{nr}(\cdot))) - \sum_{r=1}^R \sum_{k=1}^K KL(q(\mathbf{u}_{kr}) || p(\mathbf{u}_{kr})) \tag{12}$$

which is Eq. 4 in Duncker and Sahani (2018b).

4 Variational distribution of $h_{nr}(\cdot)$

For the calculation of the lower bound in the right-hand side of Eq. 12, below we derive the distribution $q(h_{nr}(\cdot))$.

We first deduce the distribution $q(x_{kr}(\cdot))$. Note, from Eq. 2, that for any $P \in \mathbb{N}$ and for any $\mathbf{t} = (t_1, \dots, t_P) \in \mathbb{R}^P$ the approximate variational posterior of the random vectors $\mathbf{x}_{kr} = (x_{kr}(t_1), \dots, x_{kr}(t_P))$ and \mathbf{u}_{kr} is jointly Gaussian

$$\begin{aligned} q(\mathbf{x}_{kr}, \mathbf{u}_{kr}) &= p(\mathbf{x}_{kr} | \mathbf{u}_{kr}) q(\mathbf{u}_{kr}) \\ &= \mathcal{N}\left(\mathbf{x}_{kr} | K_{tz}^{kr} (K_{zz}^{kr})^{-1} \mathbf{u}_{kr}, K_{tt}^k - K_{tz}^{kr} (K_{zz}^{kr})^{-1} K_{zt}^{kr}\right) \mathcal{N}(\mathbf{u}_{kr} | \mathbf{m}_{kr}, S_{kr}) \end{aligned} \quad (13)$$

where K_{tt}, K_{tz}, K_{zt} , and K_{zz} are covariance matrices obtained by evaluating of $\kappa_k(t, t'), \kappa_k(t, z), \kappa_k(z, t)$, and $\kappa_k(z, z')$, respectively, at $t, t' \in \{t_1, \dots, t_P\}$ and $z, z' \in \{\mathbf{z}_{kr}[1], \dots, \mathbf{z}_{kr}[M_{kr}]\}$. Next, using the expression for the marginal of a joint Gaussian distribution (e.g., Eq. 2.115 in Bishop (2016)) we obtain

$$q(\mathbf{x}_{kr}) = \mathcal{N}\left(\mathbf{x}_{kr} | K_{tz}^{kr} (K_{zz}^{kr})^{-1} \mathbf{m}_{kr}, K_{tt}^k + K_{tz}^{kr} \left((K_{zz}^{kr})^{-1} S_{kr} (K_{zz}^{kr})^{-1} - (K_{zz}^{kr})^{-1} \right) K_{zt}^{kr}\right) \quad (14)$$

Because Eq. 14 holds for any $P \in \mathbb{N}$ and for any $(t_1, \dots, t_P) \in \mathbb{R}^P$ then

$$\begin{aligned} q(x_{kr}(\cdot)) &= \mathcal{GP}(\check{\mu}_{kr}(\cdot), \check{\kappa}_{kr}(\cdot, \cdot)) \\ \check{\mu}_{kr}(t) &= \kappa_k(t, z_{kr}) (K_{zz}^{kr})^{-1} \mathbf{m}_{kr}, \\ \check{\kappa}_{kr}(t, t') &= \kappa_k(t, t') + \kappa_k(t, z_{kr}) \left((K_{zz}^{kr})^{-1} S_{kr} (K_{zz}^{kr})^{-1} - (K_{zz}^{kr})^{-1} \right) \kappa_k(z_{kr}, t') \end{aligned} \quad (15)$$

Finally, because affine transformations of Gaussians are Gaussians, $h_{nr}(\cdot)$ is an affine transformation of $\{x_{kr}(\cdot)\}$ (which are Gaussians, Eq. 15), then the approximate posterior of $h_{nr}(\cdot)$ is the Gaussian process in Eq. 16.

$$\begin{aligned} q(h_{nr}(\cdot)) &= \mathcal{GP}(\tilde{\mu}_{nr}(\cdot), \tilde{\kappa}_{nr}(\cdot, \cdot)) \\ \tilde{\mu}_{nr}(t) &= \sum_{k=1}^K c_{nk} \check{\mu}_{kr}(t) \\ \tilde{\kappa}_{nr}(t, t') &= \sum_{k=1}^K c_{nk}^2 \check{\kappa}_{kr}(t, t') \end{aligned} \quad (16)$$

which is Eq. 5 in Duncker and Sahani (2018b).

References

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