# Theory

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# Random variables

## Conditional expectation

**Proposition.** \*(Bjork, B.37.) Let  $(\Omega, \mathcal{F}, P)$  be a given probability space, let  $\mathcal{G}$  be a sub-sigma-algebra of  $\mathcal{F}$ , and let X be a square integrable random variable. Consider the problem of minimizing

$$E\left[(X-Z)^2\right]$$

where Z is allowed to vary over the class of all square integrable  $\mathcal{G}$  measurable random variables. The optimal solution  $\hat{Z}$  is then given by.

$$\hat{Z} = E[X|\mathcal{G}].$$

#### Proof.

Let  $X \in L^2(\Omega, \mathcal{F}, P)$  be a random variable. Now consider an arbitrary  $Z \in L^2(\Omega, \mathcal{G}, P)$ . Recall that  $\mathcal{G} \subset \mathcal{F}$  and so X is also in  $Z \in L^2(\Omega, \mathcal{G}, P)$ , as it is bothe square integrable and  $\mathcal{G}$ -measurable. Then

$$E[Z \cdot (X - E[X|\mathcal{G}])] = E[Z \cdot X] - E[Z \cdot E[X|\mathcal{G}]].$$

Then by using the law of total expectation and secondly that Z is  $\mathcal{G}$ -measurable we have that

$$E[Z \cdot X] = E[E[Z \cdot X|\mathcal{G}]] = E[Z \cdot E[X|\mathcal{G}]].$$

Combining the two equations gives the desired result. Obviously, we have that

$$X - Z = X - Z + E[X|\mathcal{G}] - E[X|\mathcal{G}] = (X - E[X|\mathcal{G}]) + (E[X|\mathcal{G}] - Z).$$

Then squaring the terms gives

$$(X - Z)^{2} = (X - E[X|\mathcal{G}])^{2} + (E[X|\mathcal{G}] - Z)^{2} + 2(X - E[X|\mathcal{G}])(E[X|\mathcal{G}] - Z)^{2}$$

Taking expectation on each side and using linearity of the expectation we have that

$$E[(X - Z)^{2}] = E[(X - E[X|\mathcal{G}])^{2}] + E[(E[X|\mathcal{G}] - Z)^{2}] + 2E[(X - E[X|\mathcal{G}])(E[X|\mathcal{G}] - Z)].$$

We can now use that  $E[X|\mathcal{G}] - Z$  is  $\mathcal{G}$ -measurable with the above result on the last term.

$$E[(X - Z)^2] = E[(X - E[X|\mathcal{G}])^2] + E[(E[X|\mathcal{G}] - Z)^2].$$

Now since X is given the term  $E[(X - E[X|\mathcal{G}])^2]$  is simply a constant not depending on the choice og Z. The optimal choice of Z is then  $E[X|\mathcal{G}]$  since this minimizes the second term. The statement is then proved.

#### Moment generating function

Let X be a random variable with distribution function  $F(x) = P(X \le x)$  and Y be a random variable with distribution function  $G(y) = P(Y \le y)$ .

**Definition.** The moment generating function or Laplace transform of X is

$$\psi_X(\lambda) = E\left[e^{\lambda X}\right] = \int_{-\infty}^{\infty} e^{\lambda x} dF(x)$$

provided the expectation is finite for  $|\lambda| < h$  for some h > 0.

The MGF uniquely determine the distribution of a random variable, due to the following result.

**Theorem.** (Uniqueness) If  $\psi_X(\lambda) = \psi_Y(\lambda)$  when  $|\lambda| < h$  for some h > 0, then X and Y has the same distribution, that is, F = G.

There is also the following result of independence for Moment generating functions.

**Theorem.** (Independence) If

$$E\left[e^{\lambda_1 X + \lambda_2 Y}\right] = \psi_X(\lambda_1)\psi_Y(\lambda_2)$$

for  $|\lambda_i| < h$  for i = 1, 2 for some h > 0, then X and Y are independent random variables.

### Stochastic processes

### **Brownian Motion**

**Definition.** (Bjork, def. 4.1) A stochastic process W is called a **Brownian motion** or **Wiener process** if the following conditions hold

- 1.  $W_0 = 0$ .
- 2. The process W has independent increments, i.e. if  $r < s \le t < u$  then  $W_u W_t$  and  $W_s W_r$  are independent random variables.
- 3. For s < t the random variable  $W_t W_s$  has the Gaussian distribution  $\mathcal{N}(0, t s)$ .
- 4. W has continuous trajectories i.e.  $s \mapsto W(s; \omega)$  i continuous for all  $\omega \in \Omega$ .

```
#Example of trajectory for BM
set.seed(1)
t <- 0:1000
N <- rnorm(
   n = length(t)-1, #initial value = 0
   mean = 0, #incements mean = 0
   sd = sqrt(t[2:length(t)] - t[1:(length(t)-1)]) #increment sd = sqrt(t-s)
)
W <- c(0,cumsum(N))</pre>
```

# Martingale

**Definition.** Let  $M_t$  be a stochastic process defined on a background space  $(\Omega, \mathcal{F}, P)$ . Let  $(\mathcal{F}_t)_{t \geq 0}$  be a filtration. If  $M_t$  is adapted to the filtration  $\mathcal{F}_t$ ,  $E|M_t| < \infty$  and

$$E[M_t|\mathcal{F}_s] = M_s$$

holds for any t > s we say that  $M_t$  is a martingale.

