

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% MATLAB Brush Up Course: Session 3 %%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%% by JOAN MARGALEF %%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
```

## % SYMBOLIC EXPRESSIONS, ANONYMOUS FUNCTIONS & LOCAL FUNCTIONS

```
% This session explores symbolic mathematics, anonymous functions and local
% functions. It covers symbolic expressions for computations in calculus
% and algebra, and anonymous functions for optimization. The concept
% of local functions is addressed for organizing complex scripts.
```

### %% 0. Understanding Symbolic Expressions, Anonymous Funct., and Local Funct

#### % Symbolic Expressions:

```
% - Symbolic expressions involve symbolic math, where the values of
%   variables are not numerical but symbolic.
% - They are useful for exact mathematical calculations like
%   differentiation, integration, and solving equations symbolically.
```

```
% - Pros: Allow for precise manipulation of mathematical formulas.
% - Cons: Slower for numerical computations.
% - Purpose: Algebra
```

#### % Example:

```
syms x
symExpr = x^2 - 4*x + 4;
```

#### % Anonymous Functions:

```
% - Anonymous functions are quick, one-line functions.
% - They are ideal for simple operations.
```

```
% - Pros: Easy to write and use for simple tasks.
% - Cons: Less versatile for complex tasks.
% - Purpose: Function evaluation
```

#### % Example:

```
anonFunc = @(x) x^2 - 4*x + 4;
```

#### % Local Functions:

```
% - Help in organizing code and reusing functionality.
```

```
% - Pros: Useful for breaking down complex tasks within a script.
% - Cons: Not accessible outside the parent script or function.
% - Purpose: Reduce code
```

```
% This is an example, but will not work (see later why)
% Local function defined within a script or function file:
% function y = localFunc(x)
%     y = x^2 - 4*x + 4;
% end
```

## %% 1.1 Symbolic Expressions: Basics

% Initialize symbolic variables

syms x

% Basic Symbolic Operations

expr = x - x^2 ;

expr

% Now we can do things with the equations like

% - Differentiate w.r.t. x

diffExpr = diff(expr, x);

disp(diffExpr)

% Integrate the expression with respect to x

intExpr = int(expr, x);

intExpr

% Combine with other expressions

syms y z

expr2= y + z

expr3= expr + expr2

% And evaluate them:

evaluatedDiffExpr = subs(expr3, {x, y}, {1, 2})

%% Practice 1.1.

% 1. Define a symbolic expression  $f(x) = \cos(x) - x^3$ .

% Differentiate  $f(x)$  with respect to  $x$ , and then evaluate this

% derivative at  $x = \pi/4$ . Display the result.

% 2. Define a symbolic cost function  $C(x) = 50x + 300$

% The revenue function  $R(x)$  is defined as  $R(x) = 75x$ ,

% Find the profit function  $P(x)$  and compute the profit for producing

% 10 units.

## %% 1.1 Symbolic Expressions: Solving Equations

```
clc;clear
```

```
syms x y z
```

```
% Define an equation
```

```
equation = x^2 - 4 == 0;
```

```
disp('Equation:');
```

```
disp(equation);
```

```
% Solve the equation
```

```
solution = solve(equation, x);
```

```
disp('Solution to the Equation:');
```

```
disp(solution);
```

```
% System of Equations
```

```
% Define a system of equations
```

```
eq1= x + y + z == 6
```

```
eq2= x - y + 2*z == 7
```

```
eq3= 2*x + y + z == 10
```

```
% Solve the system of equations as System
```

```
solutionsSystem = solve([eq1, eq2, eq3 ], [x, y, z]);
```

```
disp([solutionsSystem.x, solutionsSystem.y, solutionsSystem.z]);
```

```
% Solve the system of equations as individual sim vars
```

```
[xstar, ystar, zstar] = solve([eq1, eq2, eq3 ], [x, y, z]);
```

```
%% Practice 1.2.
```

```
% 1. Define and solve the equation  $x^3 - 3x^2 + 2 = 0$  symbolically.
```

```
% Display the solutions.
```

```
% 2. Define and solve the following system of equations symbolically:
```

```
%  $2x + 3y - z = 1$ 
```

```
%  $-x + y + z = 3$ 
```

```
%  $x - 2y + 3z = -1$ 
```

```
% Display the solutions for x, y, and z.
```

## %% 2.1. Anonymous Functions: Unconstrained Optimization

% Define an anonymous function for a quadratic equation

```
quadFunc = @(x) x - x^2 ;
```

% Easy to Evaluate

```
quadFunc(2)
```

% The advantage of being functions is MATLAB's set of built-in functions

% An important area where this is beneficial is in OPTIMIZATION.

% Optimization processes in MATLAB focus on finding LOCAL MINIMA!

% Local Minima are not Maximums! And also not necessarily Global minima!

% We will find ways to find them from searching local minima.

% As MATLAB performs numerical optimization, the results often depend on

% the chosen starting points, influencing the outcome of the minimization.

% There are several commands:

% - 'fminunc()' - Function Minimization Unconstrained (WE FOCUS ON THIS)

% Finds a local minimum of a scalar function of one or more variables.

% It is best suited for problems where the objective function is

% differentiable and when gradient information is available or can be

% approximated.

%

% - 'fminsearch()' - Unconstrained Multivariable Function Minimization

% Uses the Nelder-Mead simplex algorithm to find a minimum of a function

% of several variables. It does not require the function to be

% differentiable, and is a good choice when gradient information is not

% available.

```
quadFunc = @(x) x - x^2 ;
```

% This function has an inverse U-shape, implying it has two minima at

% negative and positive infinity. Depending on the starting point,

% the optimization process may converge to one of these minima.

% Use fminunc to find the minimum of the objective function

```
x0= 0 ; % this is a guess, since optimize it numerically
```

```
fminunc(quadFunc2 , x0) % gives optimum
```

% If we also want the function evaluated at the optimum

```
[optimum, optimalValue] = fminunc(quadFunc , x0)
```

% With fminunc we can find also a maximum (add '-' to the function)

```
quadFunc2 = @(x) -(x - x^2) ;
```

```
[optimum, optimalValue] = fminunc(quadFunc2 , x0)
```

```
maxValue = -optimalValue % Negate back to get the maximum utility
```

% Example objective function with two variables, x and y

```
% f(x, y) = (x-1)^2 + (y-2)^2
```

% You define them as a vector now and call its separate elements

```
objectiveFunc = @(xy) (xy(1) - 1)^2 + (xy(2) - 2)^2;
```

% Define the initial guess for the optimization

% Initial guess for x and y

```
x0 = [0, 0];
```

% Use fminunc to find the minimum of the objective function

```
[optimalXY, optimalValue] = fminunc(objectiveFunc, x0)
```

%% Practice 2.1.

% 1. Define an utility function  $U(c) = 10c - c^2$

% Evaluate it at  $x=10$

% Use fminunc to find this maximum, starting from an initial guess  $-10$ .

% 2. Define a welfare maximization problem for a social planner who aims

% to maximize the sum of utilities of 2 guys:

%  $U_1(x_1) = -(x_1 - c_1)^2$  and  $U_2(x_2) = -(x_2 - c_2)^2$

% Assume  $c_1 = 3$  and  $c_2 = 5$ .

% Use fminunc to find the optimal points  $x_1$  and  $x_2$ , starting from an

% initial guess of  $x_1 = 0$  and  $x_2 = 0$ .

## %% 2.2. Anonymous Functions: Constrained Optimization

```
%Imagine we want to maximize  $f(x) = x^2 - 4x$   
% s.t.  $x \leq 1.5$ 
```

```
% We define the objective function as before  
objectiveFunc = @(x) x^2 - 4*x; % Example quadratic function
```

```
% First Matlab needs to differentiate between Inequality and Equality Const  
% And they have to be in Matrix Form:
```

```
% Inequality Constraints  $A*x \leq b$   $x$ :vector variables ;  $b$ :vector scalars
```

```
A = 1;  
b = 1.5;
```

```
% If the inequality constraints are  $\geq$  ( $x \geq 1.5$ ), we negate it to have the  
% equivalent:
```

```
% A= -1  
% b = - 1.5;  
%  $-x \leq -1.5$  which is equivalent to  $x \geq 1.5$ 
```

```
% Define the equality constraints  $Aeq*x = beq$  (if any [])
```

```
Aeq = [];  
beq = [];
```

```
% Define the bounds of the variable  $lb \leq x \leq ub$  (if any [])
```

```
lb = [];  
ub = [];
```

```
% Define the initial guess
```

```
x0 = 0;
```

```
% Use fmincon to find the minimum of the obj. function under constraints  
[optimum, optimalValue]= fmincon(objectiveFunc, x0, A, b, Aeq, beq, lb, ub)
```

```
% In this example, the inequality is equivalent to a lower bound
```

```
% We define the objective function as before
```

```
objectiveFunc = @(x) x^2 - 4*x; % Example quadratic function
```

```
% Inequality Constraints
```

```
A = [];  
b = [];  
Aeq = [];  
beq = [];  
lb = [];  
ub = 1.5;
```

```
x0 = 0;
```

```
[optimum, optimalValue]= fmincon(objectiveFunc, x0, A, b, Aeq, beq, lb, ub)
```

## % Complex Constrained Optimization Example

```
% f(x, y, z) = x^2 + y^2 - z    s.t.
% x + y <= 5
% y + z <= 6
% x + z = 3
% 0 <= x <= 4,
% 1 <= y <= 5,
```

```
% We'll negate the function as fmincon minimizes the function, and we want
% to maximize it
objectiveFunc = @(xyz) -(xyz(1)^2 + xyz(2)^2 - xyz(3));
```

```
% Initial guess for x, y, and z
x0 = [0, 0, 0];
```

```
% Inequality constraints (A*xyz <= b)
% Let's say we have the constraints
A = [1, 1, 0; 0, 1, 1];
b = [5; 6];
```

```
% Equality constraints (Aeq*xyz = beq)
% Suppose we also have the constraint
Aeq = [1, 0, 1];
beq = 3;
```

```
% Bounds on the variables (lb <= xyz <= ub)
% Let's set bounds on the variables:
lb = [0, 1, -Inf];
ub = [4, 5, Inf];
```

```
% Use fmincon to find the maximum of the obj. function under constraints
[optimalXYZ, optimalValue]=fmincon(objectiveFunc, x0, A, b, Aeq, beq,lb,ub)
optimalValue = -optimalValue % Negate back to get the maximum value
```

## %% Practice 2.2.

```
% Assume an individual seeks to maximize their utility, which depends on
% two goods x and y, and labor l. The utility function is
```

```
%          
$$U(x, y, l) = \log(x) + \log(y) + \log(1-l)$$

```

```
% The individual's budget constraint is:
```

```
%          
$$p_1x + p_2y \leq w \cdot l$$

```

```
% where p1 and p2 are the prices of goods x and y, and w is the wage rate.
% The individual earns income by supplying labor, giving up leisure l.
```

```
% Find the combination of x, y, and l that maximizes utility subject to
% the budget constraint.
```

```
% Assume p1 = 2, p2 = 3, and w = 10. Also, the individual can work between
% 0 and 1.
```

### %% 2.3. Anonymous Functions: Global Optimization

% The algorithms in matlab to find a global maximum, are based on  
% finding a local maximum from a grid of initial points.

### %% 3. Local Functions

% Local Functions can be used in two places:

% 1- Put it END OF FILE

multiplicationtable(1)

% 2- In another Script (name must match, same WD)

```
mu=5;  
sigma=1;  
x=normrnd(mu,sigma,1,100)
```

mainstats(x)

% NOTE You can make it print the results, but if you want to store  
% the values, you need to declare output

[n, m, av, std] = mainstatsout(x)

% It might be required to introduce multiple inputs  
% n: elements of the set (number of letters)  
% k: how many combinations of 3 letters we can have  
calculateCombinations(4,2)

### %% Practice 3.

% 1. Write at the end of script a function called 'displayFibonacci'  
% It take an integer 'n' as input and print the first 'n' numbers  
% After writing the script, call displayFibonacci(10);

% 2. Write a function in a separate script 'circleProperties.m'.  
% This function should take the radius of a circle as input and return  
% the area and the perimeter of the circle.



```
%% END. Local Functions
```

```
function multiplicationtable(number)

    disp(['Multiplication Table for ', num2str(number), ':']);
    for i = 1:10
        result = number * i;
        disp([num2str(number), ' x ', num2str(i), ' = ', num2str(result)]);
    end
end
```