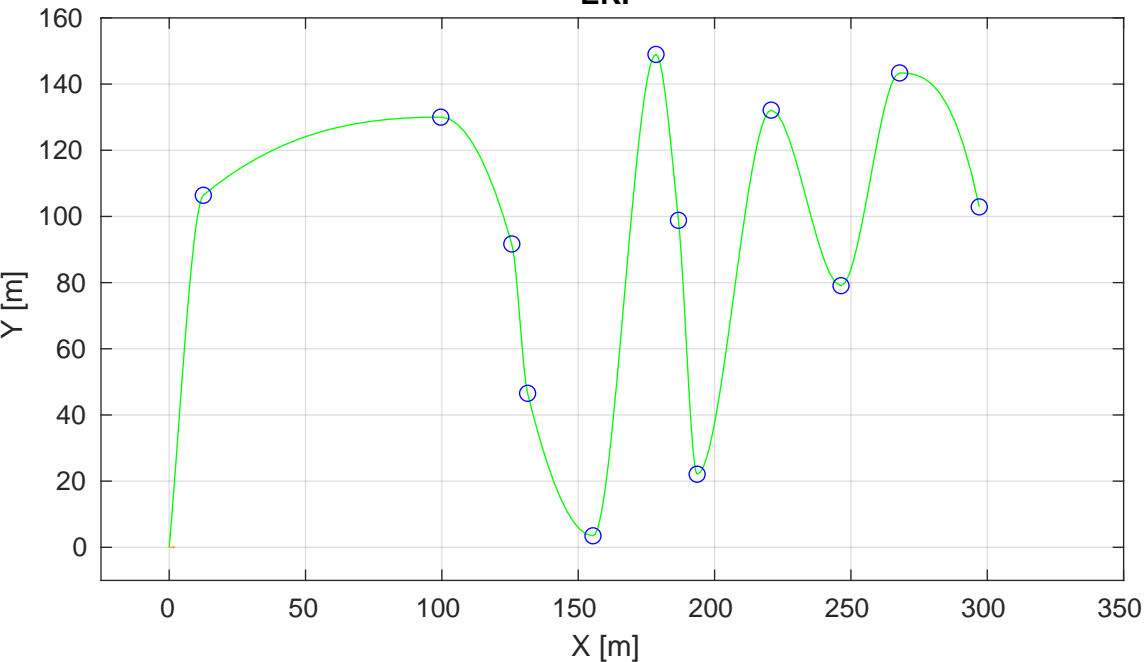


EKF



— Trajectória planeada ○ Faróis → Pose estimada