

## Education

### Instituto Superior Técnico

PORTUGAL

#### MSc in Computer Science, Major in Intelligent Robotics

2018–2020

Final grade: 17/20

Thesis: "Domestic Robot Grasping using Visual Servoing and Deep Learning"

Installed a robotic arm in a domestic mobile robot. Developed an object grasping mechanism using visual servoing and deep learning for visual feedback. Implemented in ROS.

### Universidade Nova de Lisboa

PORTUGAL

#### BSc in Computer Science

2013–2016

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## Experience

### Ocado Technology

UNITED KINGDOM

#### Software engineer, Simulation, Advanced Technology

2021–present

- Developed Unity-based simulation of robotic picking, predominantly in C#
- Created and improved simulation tools for robotics, mainly in Python
- Set and prioritized tasks based on internal client needs

### Institute for Systems and Robotics - IST

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#### Research assistant

2019–2020

Under a research grant, implemented robotic benchmarks to use in [European Robotics League](#) competitions. Additionally, developed software for the european project [eu-robench](#), a benchmarking framework for bipedal robots.

### agap2 IT

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#### Software engineer

2016–2018

- Worked with shipping solutions company [Transsmart](#). Implemented connections to several courier APIs to book and track shipments.
  - Developed a macOS application for [DPD](#) clients.
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## Skills

- Proficient in written and spoken English
- Good teamwork and technical communication skills
- Solid foundations in computer architecture, algorithms, data structures, databases and distributed systems
- Strong software development skills — most comfortable with Python, Javascript, Java, C++
- Knowledge of several important topics in robotics: control, mapping, navigation, kinematics, manipulation
- Experienced in ROS development, using both C++ and Python — including MoveIt! manipulation, Gazebo simulation, and other common ROS packages

## Other Projects

### Smart Cities Robotics Challenge

MILTON KEYNES, UK

#### European Robotics League

2019

Helped to organize, referee, and manage the audience visualization system for the Smart Cities Challenge 2019, a robotics competition at the [centre:mk](#) shopping mall in Milton Keynes.

### Autonomous driving competition

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#### Robotics festival 2019

2019

Developed autonomous car systems, including traffic-sign recognition and obstacle detection and avoidance, to compete in the autonomous driving competition of the [Portuguese robotics festival](#).

### MIUP/SWERC 2015

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#### College programming contest

2015

Took part in MIUP 2015, a national college programming contest held at [Universidade do Porto](#). Our team qualified for and competed in the [Southwest Europe regional contest](#).

### FCT NOVA Hackathon

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#### Second place in college hackathon

2015

Participated in the 2015 edition of the college hackathon and placed second. Our team developed a multiplayer Android game, based on an existing traditional board game.