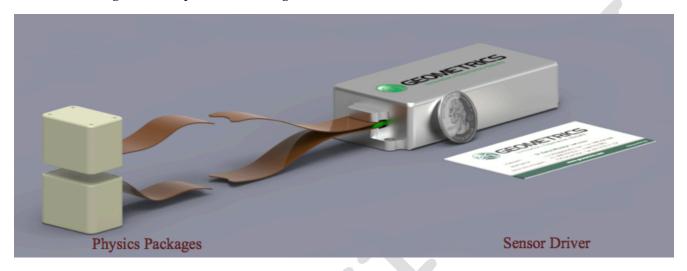
## LASER PUMPED CESIUM MAGNETOMETER

## LCS050G



The Geometrics LCS050G is a laser pumped cesium magnetometer module that measures the total magnetic field strength, with a digital interface for easy integration with modular sensing platforms. The module features two sensors that can be used independently or as an intrinsic gradiometer. The sensors can also be arranged to compensate heading error or eliminate dead zone.



## **Features**

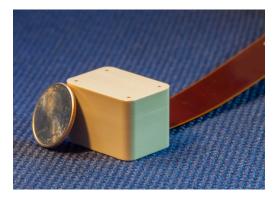
Reconfigurable dual-sensor module for:

- - Intrinsic heading error compensation
- Dead-zone free operation

• Small size:

Gradiometry

- o 15 cm<sup>3</sup> sensor
- o 200 cm<sup>3</sup> electronics volume
- High performance:
  - $\circ$  2pT/√Hz noise typical
  - o 1 kSps sample rate
- Low power operation:
  - o 5 W power consumption
- Dead Zone:
  - o Polar,  $\pm 25^{\circ}$
- Fully digital interface



## Applications:

- Autonomous Geophysical Surveys
- Non-destructive Evaluation
- Magnetocardiography
- Structural Health Monitoring

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## LCS050G



<b>Specifications</b>		•	
	Sn	1011	
	ישט	TOTES	•

Characteristic	Condition	Min	Тур	Max	Units
					<i>y</i>

# **Power Supply**

Supply Voltage	Vin referenced to GND	8	12	16	Volts
Average Current Draw	Vin = 12V, 25 °C ambient temperature Vin = 12V, -35 °C ambient temperature		0.4	0.6	A
Average Power Draw	25 °C ambient temperature -35 °C ambient temperature		5 8	7 10	W

### **Performance**

Field Range	Full scale	20		100	μΤ
Noise Floor	Magnetic field orthogonal to sensor optical axis		2	5	pT/√Hz
Dead Zone	Polar only, included angle		50	60	degree
Heading Error	Measured at 50µT field strength		25	60	nTp
Digital Resolution	32-bit magnetometer output		0.05		pT/LSb
Output Data Rate	Continuous measurement		1000		Hz

## **Environmental**

Operating Temperature	Ambient	-35	50	<sub>ō</sub> C
Storage Temperature	Ambient	-40	70	ōС
Operating Altitude			10000	Feet
Storage Altitude			45000	Feet



# **Mechanical Specifications:**

Dimensions in [mm] inches.

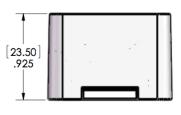
### Sensor

Weight: 30g each, 2 sensors per magnetometer module.

# **Top View** [27.43] 1.080 [3.20] [3.20] .126 [17.78] .700 4X ∅.089 (USE 4-40 SELF TAPPING) **Front View**

[24.18] .952

**Bottom View** 





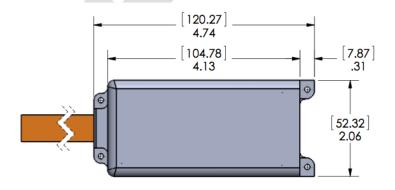
**Side View** 

[33.83] 1.332

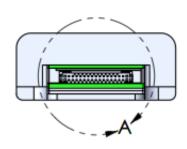
**Driver Unit** 

Weight: 200g each.

## **Top View**



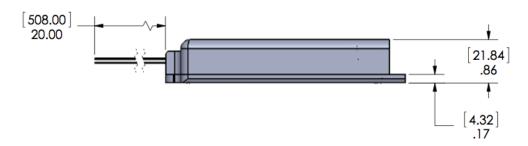
### **Connector Placement**



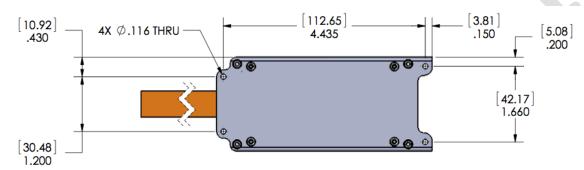
[508.00] 20.00



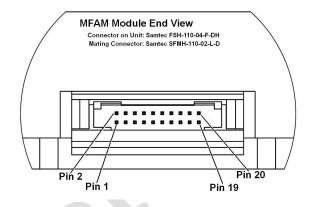
#### **Side View**



#### **Bottom View**



### **Connector Details**



#### **Connector on MFAM Module:**

Samtec FSH-110-04-F-DH

### **Mating connector:**

Samtec SFMH-110-02-L-D



# **Pin Configuration**

Pin	Signal	Description
1	CHASSIS	Chassis ground
2	GND	Power supply ground
3	Vin	Power supply (9.5V to 16V)
4	Vin	Power supply (9.5V to 16V)
5	GND	Power supply ground
6	GND	Power supply ground
7	MSPI_DOUT	Data output (TX), SPI protocol, unit is master
8	DNC	Do not connect, leave pin open.
9	MSPI_DIN	Data input (RX), SPI protocol unit is master
10	DNC	Do not connect, leave pin open.
11	MSPI_SCLK	Clock output, SPI protocol, unit is master
12	DNC	Do not connect, leave pin open.
13	MSPI_CSB	Chip select, active low signal, SPI protocol, unit is master
14	DNC	Do not connect, leave pin open.
15	CTS	Clear To Send handshake signal, INPUT to MFAM unit (not implemented)
16	REF10M	10 MHz reference clock input, OPTIONAL
17	RTS	Ready To Send handshake signal, OUTPUT from MFAM unit (not implemented)
18	1PPS	1 pulse per second input, positive edge triggered
19	GND	Power supply ground
20	GND	Power supply ground



## **Document Information**

Revision	Date	Description
0.1	8 July 2015	Document created.
0.2	1 Sep 2016	Updated specifications and formatting.
0.2a	21 Nov 2016	Updated to allow external sharing.
0.3	14 Mar 2017	Minor specification change.
0.4	03 May 2017	ITAR notice in footer.

## Disclaimer

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