using std::cpp 2016

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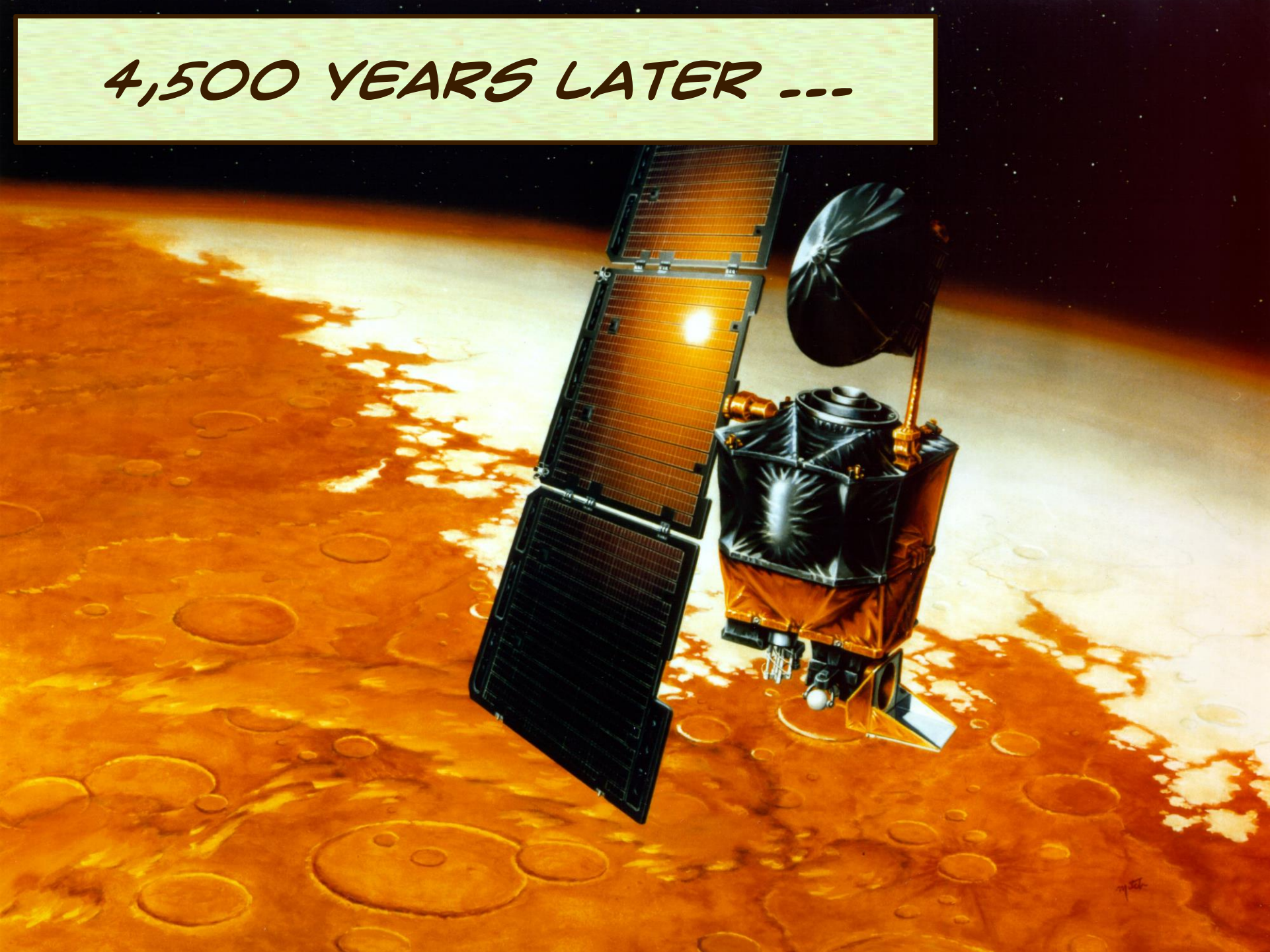
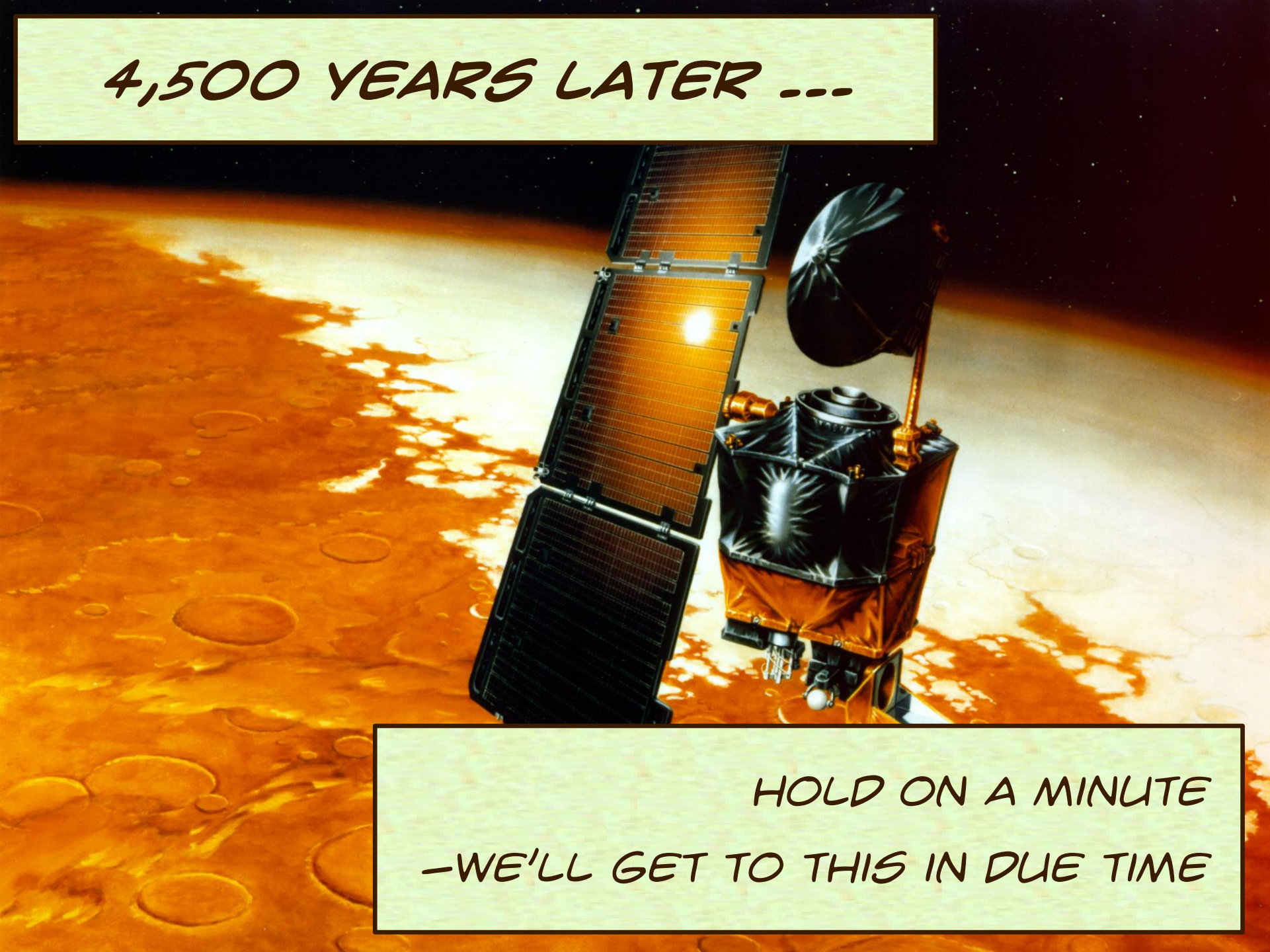

4,500 YEARS LATER ---

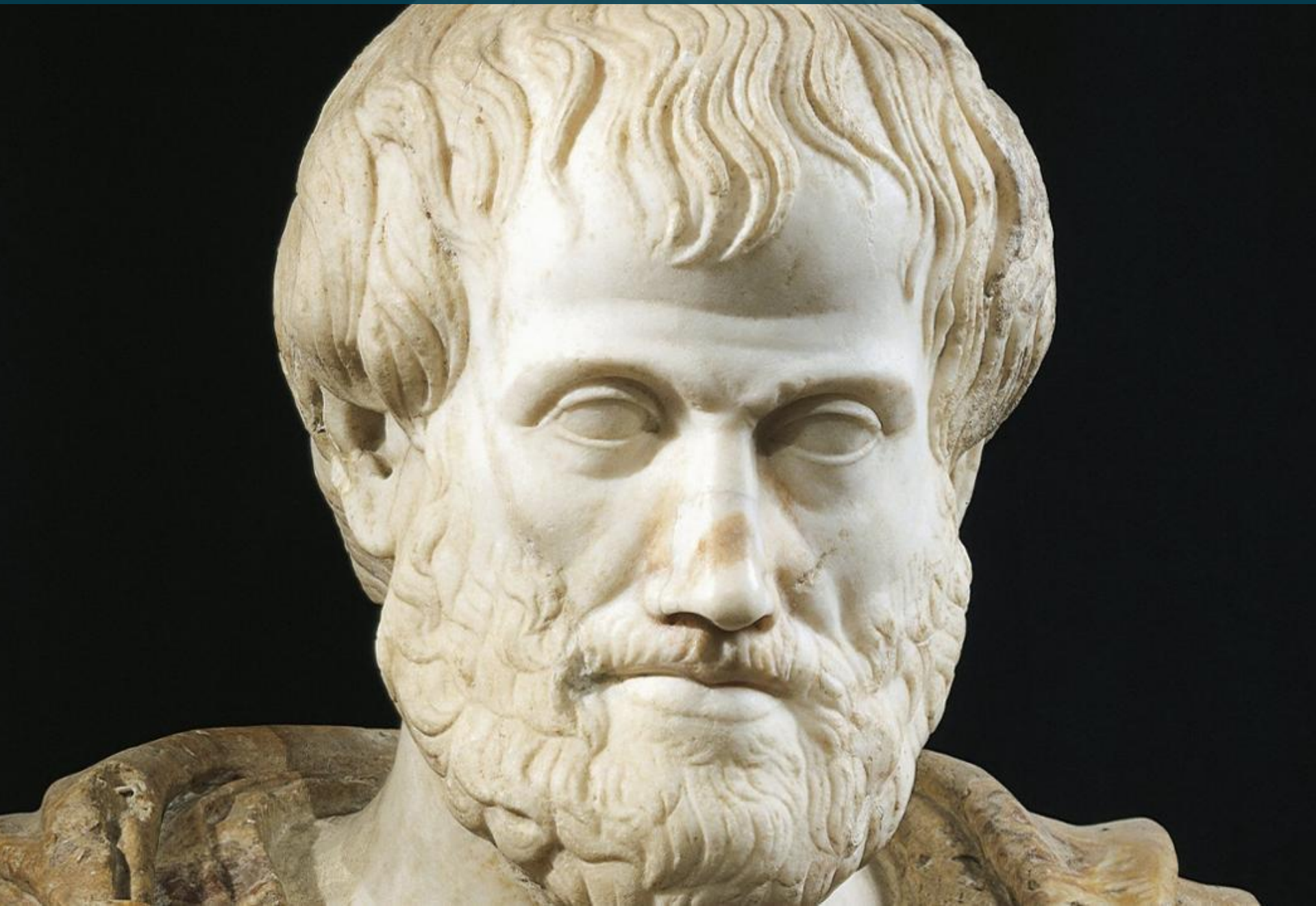
4,500 YEARS LATER ---



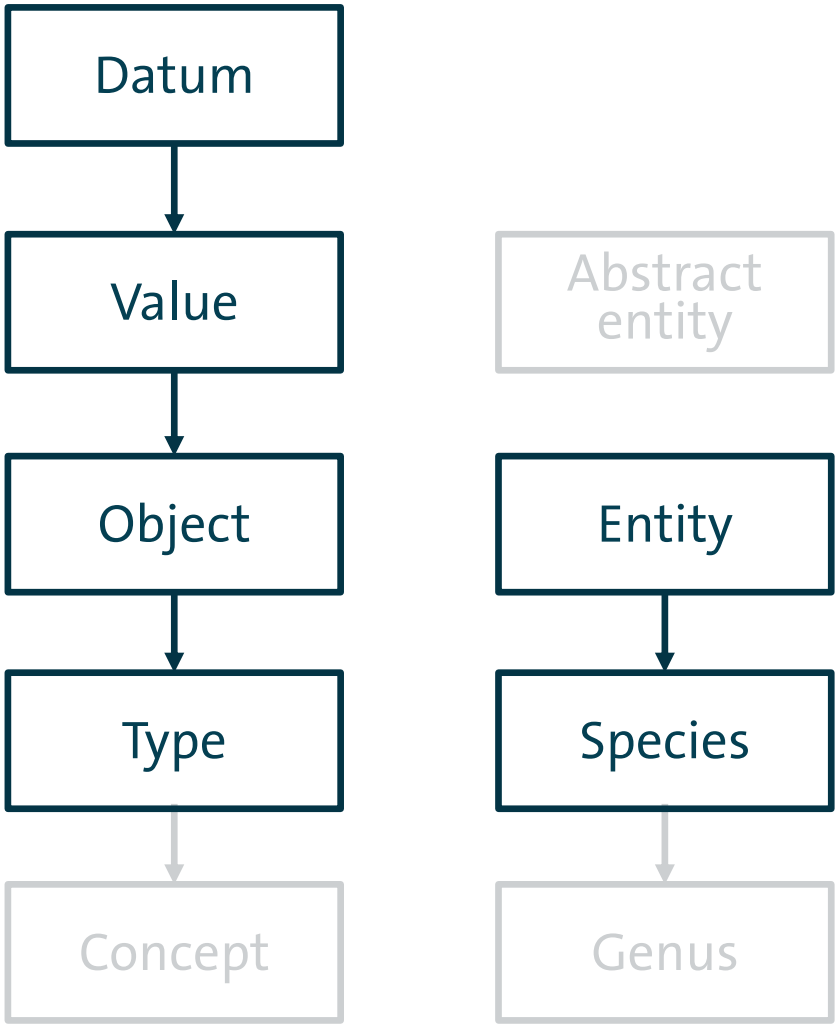
HOLD ON A MINUTE

–WE'LL GET TO THIS IN DUE TIME

What is a type, anyway?



What is a type, anyway?

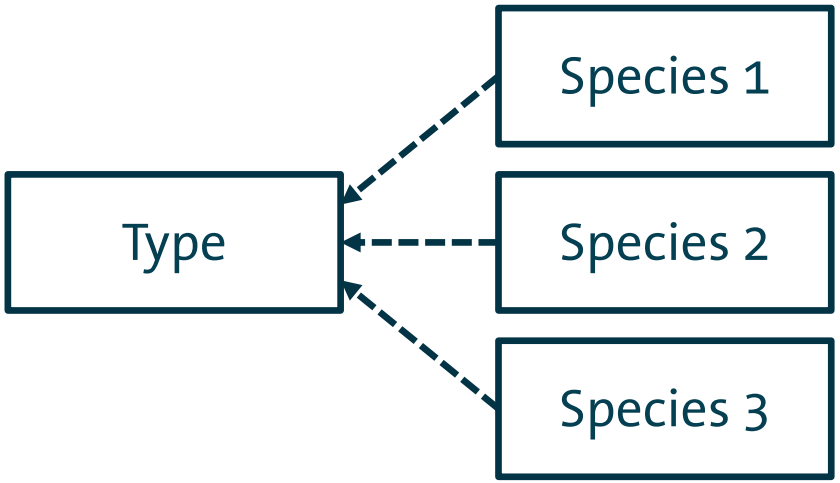


Alexander Stepanov
Paul McJones
Elements of programming
Addison-Wesley, 2009

What is a type, anyway?

- Programming is about modelling the real world
- Your types stand for real-world species, objects for entities
  - From math → app domain as we move higher up the hierarchy
- The state of an object is its value at a given (program) time
- Type invariants = permissible values
- Statically typed languages reduce permissible states of the world
  - The more info you give the compiler, the more bugs turn into compile-time errors

Bad practice #1: type overloading



Bad practice #1: type overloading

```
void set_date(int month,int day,int year)
{
  static const char* month_names[]=
  {"Jan","Feb","Mar","Apr","May","Jun","Jul","Aug","Sep","Oct","Dec"};

  std::cout<<month_names[month-1]<<" "<<day<<", "<<year<<"\n";
}

int main()
{
  // man lands on Moon
  set_date(20,7,1969); // oops
}
```

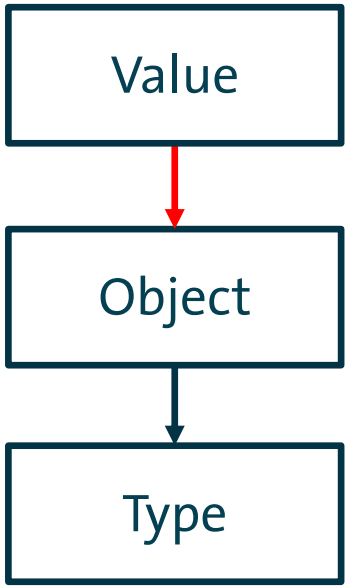
- A day (a month, a year) is **not** an `int`
- We are **representing** it with an `int`

Fighting type overloading

- At the very least, make types and representations different

```
struct month{int value;};
struct day{int value;};
struct year{int value;};

void set_date(month m,day d,year y)
{
  static const char* month_names[]=
  {"Jan","Feb","Mar","Apr","May","Jun","Jul","Aug","Sep","Oct","Dec"};

  std::cout<<month_names[m.value-1]<<" "<<d.value<<", "<<y.value<<"\n";
}

int main()
{
  // man lands on Moon
  set_date(day{20},month{7},year{1969}); // compile-time error
}
```

Bad practice #2: unchecked invariants



Bad practice #2: unchecked invariants

```
int main()
{
  // Apr 12, 1961: first spaceflight by Gagarin
  set_date(month{4},day{112},year{1961}); // oops
}
```

- Not all `int` values represent a valid day
- Except in the most trivial cases, object states are a **strict** subset of the representation type(s) values

Restricted representations

```
template<
  typename Int,
  Int min=std::numeric_limits<Int>::min(),
  Int max=std::numeric_limits<Int>::max()
>
class range{
  Int value;
  void check()const{assert(value>=min&&value<=max);}
public:
  range(Int value):value{value}{check();}
  range& operator=(Int value){this->value=value;check();return *this;}
  operator Int()const{return value;}
};
```

Restricted representations

```
struct month:range<int,1,12>{using range::range;};
struct day:range<int,1,31>{using range::range;};
struct year:range<int>{using range::range;};

void set_date(month m,day d,year y)
{
  static const char* month_names[]=
  {"Jan","Feb","Mar","Apr","May","Jun","Jul","Aug","Sep","Oct","Dec"};

  std::cout<<month_names[m]<<" "<<d<<", "<<y<<"\n";
}

int main()
{
  // Apr 12, 1961: first spaceflight by Gagarin
  set_date(month{4},day{112},year{1961}); // asserts
}
```

- Why not the following?

```
using month=range<int,1,12>;
```

Back to bad practice #1

```
int main()
{
  // March 31, 1966: Luna 10 probe is launched
  set_date(month{4},day{31},year{1966}); // oops
}
```

- Again, a problem with identifying objects and representations
- A date is **not** a tuple of (month, day, year)
- Keep iterating
- Rely on the experts…

Boost.Date_Time

```
#include <boost/date_time/gregorian/gregorian.hpp>

using namespace boost::gregorian;

void set_date(date d)
{
  std::cout<<d<<"\n";
}

int main()
{
  // March 31, 1966: Luna 10 probe is launched
  set_date({greg_year{1966},greg_month{4},greg_day{31}}); // throws
}
```

Levels of invariant checking

- Level 0: no checking
- Level 1: choose a stricter representation/interface
- Level 2: checking on construction/assignment
- Level 3: full check

- Go at least for level 1-2

Level 1: improve this

```
class child
{
  parent* p;
public:
  child(parent* p):p{p}{}
};

void print(const char* msg);

void set_thermostat(int temperature);

const record* locate_record(int id);

struct elevator
{
  bool door_closed;
  int  speed;
};
```

Ideas from:
fonathan::blog(): Type safe - Zero overhead utilities for more type safety
http://tinyurl.com/gp34bu2
Ben Deane: Using Types Effectively
http://tinyurl.com/hzpzcdk

Possible alternatives

```
class child
{
  parent* p;
public:
  child(parent& p):p{&p}{}
};

void print(const std::string& msg);

void set_thermostat(unsigned int temperature);

std::optional<std::reference_wrapper<record>> locate_record(int id);

struct elevator
{
  struct stopped{
    bool door_closed;
  };
  struct in_transit{
    int speed;
  };
  std::variant<stopped,in_transit> state;
};
```

Breaking the invariant barrier

```
template<typename T>
class sorted_vector{
  using implementation=std::vector<T>;
  implementation impl;
public:
  using iterator=typename implementation::iterator;
  iterator begin(){return impl.begin();}
  iterator end(){return impl.end();}
  void insert(const T& x){impl.push_back(x);std::sort(begin(),end());}
  void erase(iterator it){impl.erase(it);}
};

int main()
{
  sorted_vector<int> sv;
  for(int i=0;i<10;++i)sv.insert(i);
}
```

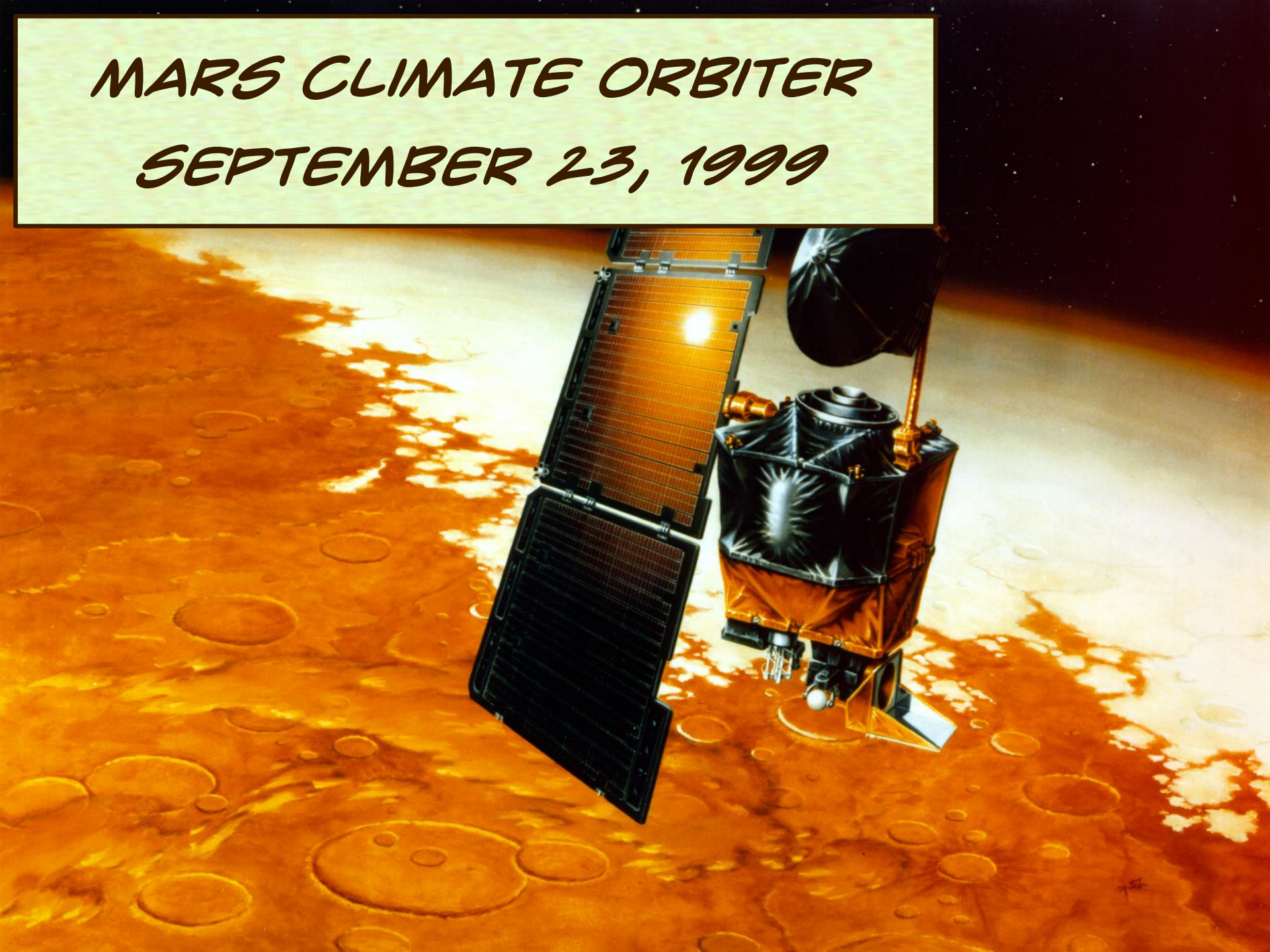
- Now duplicate each element in `sv`

Breaking the invariant barrier

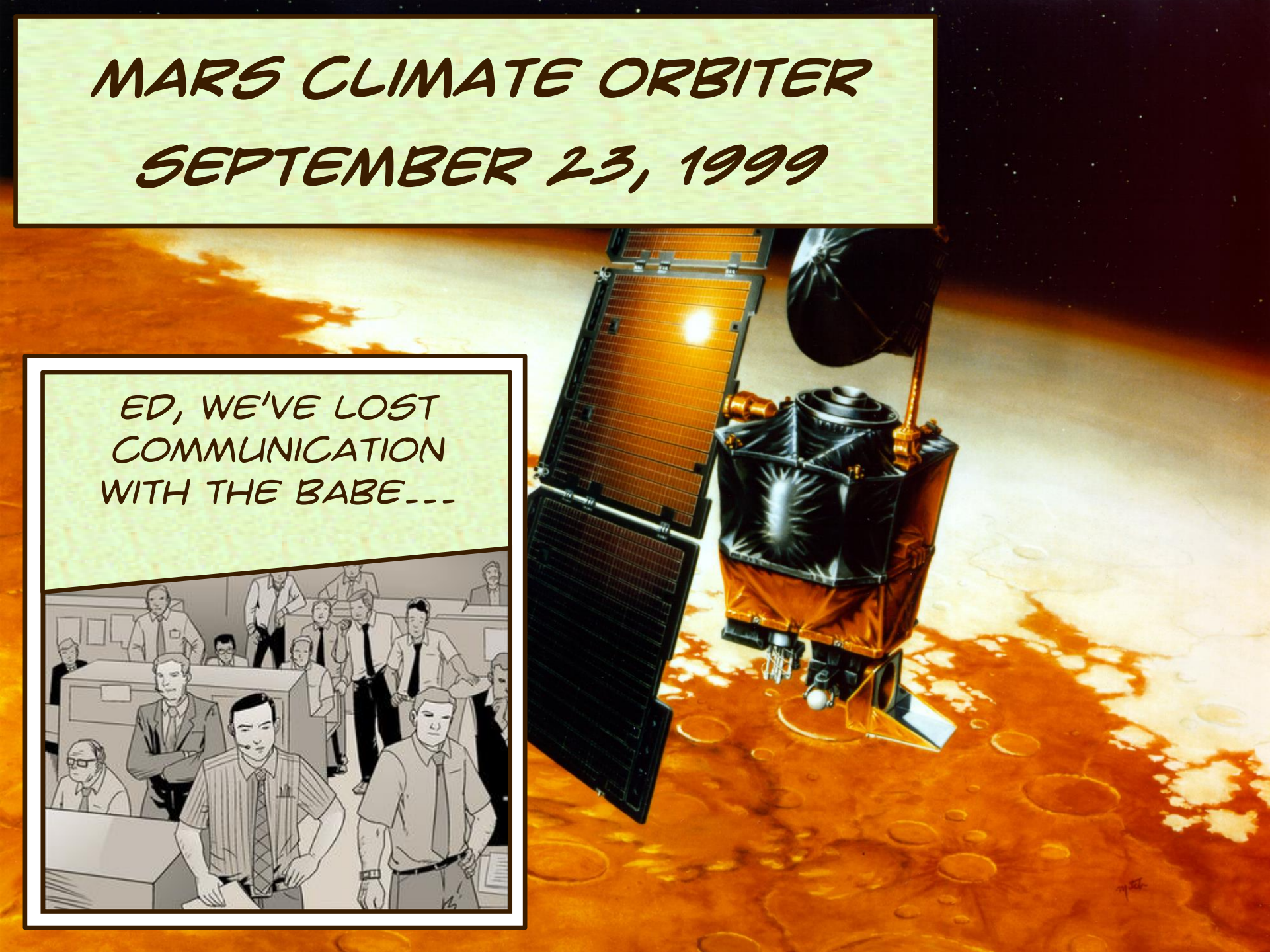
```
template<typename T>
class sorted_vector{
  using implementation=std::vector<T>;
  implementation impl;
public:
  ...
  implementation extract(){return std::move(impl);}
  void accept(implementation&& i){
    impl=std::move(i);std::sort(begin(),end());
  }
};

int main()
{
  sorted_vector<int> sv;
  for(int i=0;i<10;++i)sv.insert(i);
  auto impl=sv.extract();
  for(std::size_t n=0,m=impl.size();n<m;++n)impl.push_back(impl[n]);
  sv.accept(std::move(impl));
}
```

MARS CLIMATE ORBITER

SEPTEMBER 23, 1999



MARS CLIMATE ORBITER
SEPTEMBER 23, 1999



MARS CLIMATE ORBITER
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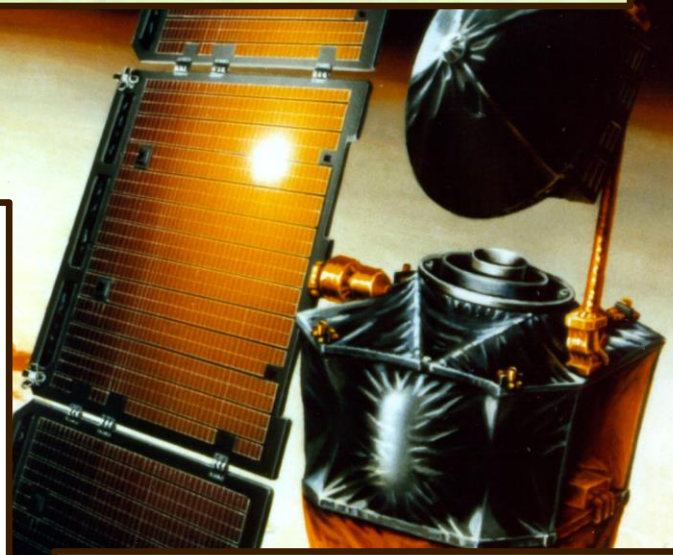
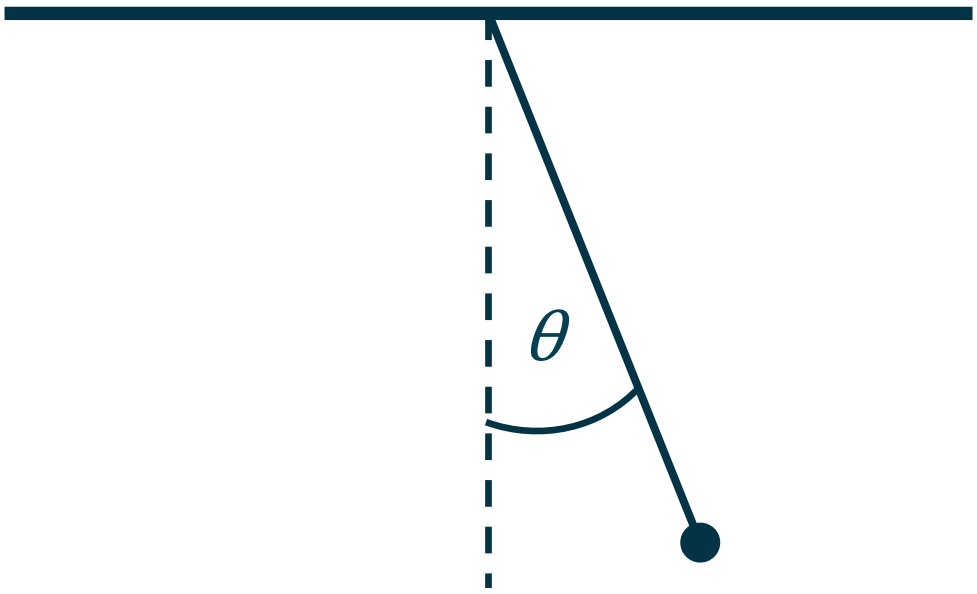


ED, WE'VE LOST COMMUNICATION WITH THE BABE...

A SOFTWARE PROBLEM WITH WRONG METRIC UNITS COST NASA $327 MILLION –NOT A GOOD DAY AT CAPE CANAVERAL

Pendulum equation



$$\frac{d^2\theta}{dt^2} = -\frac{g}{l}\sin\theta$$

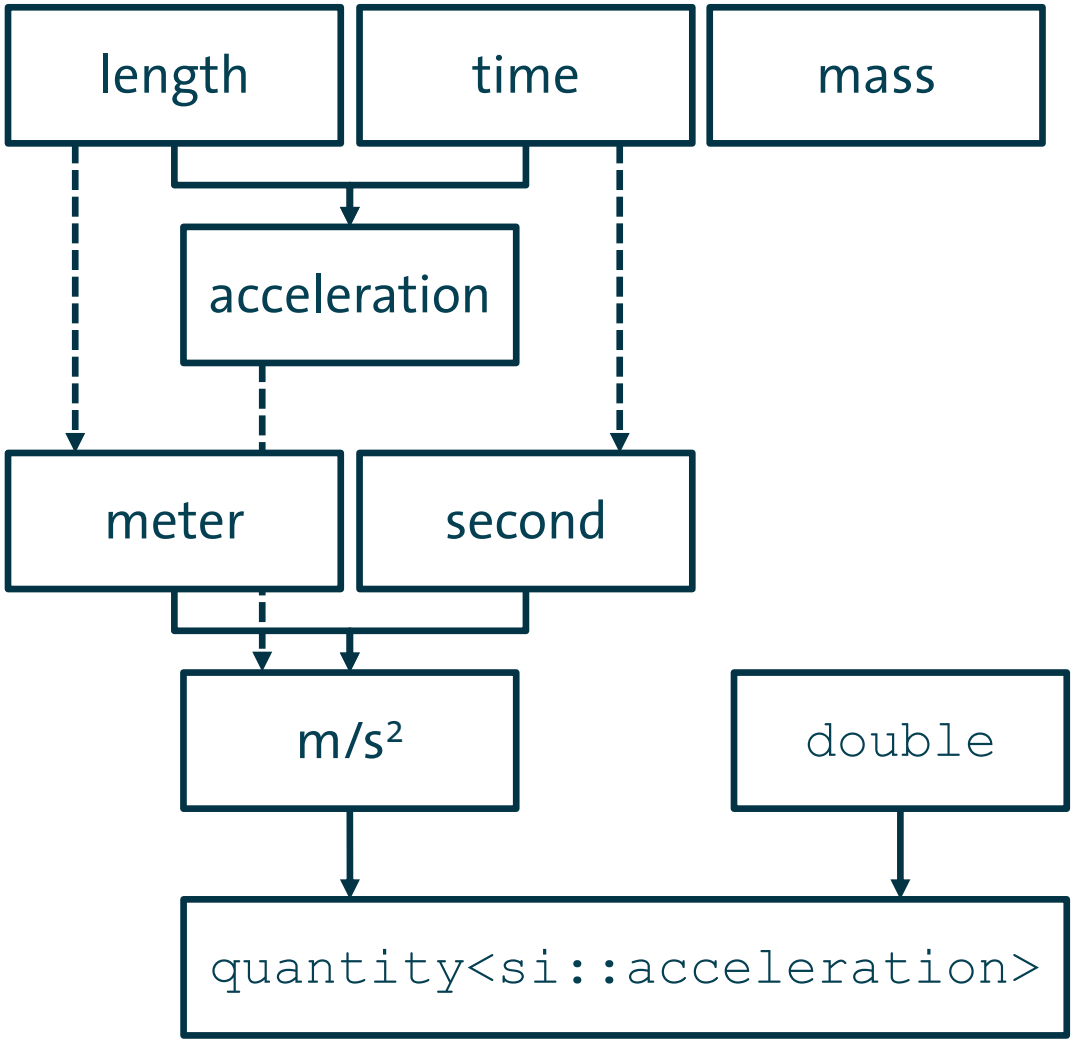
Macho style

```
#include <cmath>
#include <iostream>

int main()
{
  const double g=9.8;   // m/s2
  const double l=50.0;  // cm
  const double dt=0.02; // s

  double theta=30.0;    // degrees
  double theta_v=0.0;   // degrees/s

  std::cout<<"time\tangle\n";
  for(double t=0.0;t<2.0;t+=dt){
    double theta_a=-sin(theta*2.0*3.14159265/360)*g/(l/100.0);
    theta_v+=theta_a*dt;
    theta+=theta_v*dt;
    std::cout<<t<<" s\t"<<theta<<" deg\n";
  }
}
```

Results: go launch the probe!

time	angle	time	angle	time	angle	time	angle
0 s	29.9961 deg	0.5 s	28.6336 deg	1 s	24.938 deg	1.5 s	19.1909 deg
0.02 s	29.9882 deg	0.52 s	28.5293 deg	1.02 s	24.7451 deg	1.52 s	18.9242 deg
0.04 s	29.9765 deg	0.54 s	28.4212 deg	1.04 s	24.5488 deg	1.54 s	18.655 deg
0.06 s	29.9608 deg	0.56 s	28.3094 deg	1.06 s	24.3493 deg	1.56 s	18.3833 deg
0.08 s	29.9412 deg	0.58 s	28.1939 deg	1.08 s	24.1466 deg	1.58 s	18.109 deg
0.1 s	29.9177 deg	0.6 s	28.0747 deg	1.1 s	23.9406 deg	1.6 s	17.8324 deg
0.12 s	29.8903 deg	0.62 s	27.9518 deg	1.12 s	23.7315 deg	1.62 s	17.5533 deg
0.14 s	29.859 deg	0.64 s	27.8252 deg	1.14 s	23.5192 deg	1.64 s	17.2719 deg
0.16 s	29.8238 deg	0.66 s	27.695 deg	1.16 s	23.3038 deg	1.66 s	16.9882 deg
0.18 s	29.7846 deg	0.68 s	27.5611 deg	1.18 s	23.0853 deg	1.68 s	16.7021 deg
0.2 s	29.7416 deg	0.7 s	27.4236 deg	1.2 s	22.8637 deg	1.7 s	16.4139 deg
0.22 s	29.6947 deg	0.72 s	27.2824 deg	1.22 s	22.639 deg	1.72 s	16.1234 deg
0.24 s	29.6439 deg	0.74 s	27.1377 deg	1.24 s	22.4114 deg	1.74 s	15.8307 deg
0.26 s	29.5892 deg	0.76 s	26.9894 deg	1.26 s	22.1807 deg	1.76 s	15.5359 deg
0.28 s	29.5307 deg	0.78 s	26.8376 deg	1.28 s	21.9471 deg	1.78 s	15.2389 deg
0.3 s	29.4683 deg	0.8 s	26.6822 deg	1.3 s	21.7106 deg	1.8 s	14.94 deg
0.32 s	29.402 deg	0.82 s	26.5233 deg	1.32 s	21.4712 deg	1.82 s	14.639 deg
0.34 s	29.3319 deg	0.84 s	26.3609 deg	1.34 s	21.2289 deg	1.84 s	14.336 deg
0.36 s	29.258 deg	0.86 s	26.195 deg	1.36 s	20.9837 deg	1.86 s	14.031 deg
0.38 s	29.1802 deg	0.88 s	26.0256 deg	1.38 s	20.7358 deg	1.88 s	13.7242 deg
0.4 s	29.0986 deg	0.9 s	25.8528 deg	1.4 s	20.485 deg	1.9 s	13.4155 deg
0.42 s	29.0132 deg	0.92 s	25.6766 deg	1.42 s	20.2316 deg	1.92 s	13.105 deg
0.44 s	28.924 deg	0.94 s	25.497 deg	1.44 s	19.9754 deg	1.94 s	12.7927 deg
0.46 s	28.8309 deg	0.96 s	25.314 deg	1.46 s	19.7165 deg	1.96 s	12.4787 deg
0.48 s	28.7342 deg	0.98 s	25.1277 deg	1.48 s	19.455 deg	1.98 s	12.163 deg

Boost.Units


length
time
mass
acceleration
meter
second
m/s²
double
quantity<si::acceleration>

Boost.Units to the rescue

```
int main()
{
  using boost::units::quantity;
  using boost::units::degree::degree;
  using boost::units::cgs::centimeter;
  using namespace boost::units::si;

  const auto                  g=9.8*meter_per_second_squared;
  const quantity<length>      l{50.0*centimeter};
  const auto                  dt=0.02*second;

  quantity<plane_angle>       theta{30.0*degree};
  quantity<angular_velocity> theta_v;

  std::cout<<"time\tangle\n";
  for(auto t=0.0*second;t<2.0*second;t+=dt){
    auto theta_a=-sin(theta)*radian*g/l;
    theta_v+=theta_a*dt;
    theta+=theta_v*dt;
    std::cout<<t<<"\t"<<
      quantity<boost::units::degree::plane_angle>{theta}<<"\n";
  }
}
```

Results

time	angle	time	angle	time	angle	time	angle
0 s	29.7754 deg	0.5 s	-20.226 deg	1 s	-6.8586 deg	1.5 s	27.948 deg
0.02 s	29.3277 deg	0.52 s	-22.0792 deg	1.02 s	-4.27676 deg	1.52 s	26.8919 deg
0.04 s	28.66 deg	0.54 s	-23.7635 deg	1.04 s	-1.66143 deg	1.54 s	25.6326 deg
0.06 s	27.7769 deg	0.56 s	-25.2668 deg	1.06 s	0.966924 deg	1.56 s	24.179 deg
0.08 s	26.6844 deg	0.58 s	-26.5784 deg	1.08 s	3.5877 deg	1.58 s	22.5415 deg
0.1 s	25.3902 deg	0.6 s	-27.6889 deg	1.1 s	6.18037 deg	1.6 s	20.7317 deg
0.12 s	23.9034 deg	0.62 s	-28.5908 deg	1.12 s	8.72467 deg	1.62 s	18.7629 deg
0.14 s	22.2346 deg	0.64 s	-29.2777 deg	1.14 s	11.2008 deg	1.64 s	16.6496 deg
0.16 s	20.3958 deg	0.66 s	-29.7449 deg	1.16 s	13.5898 deg	1.66 s	14.4077 deg
0.18 s	18.4005 deg	0.68 s	-29.9892 deg	1.18 s	15.8731 deg	1.68 s	12.0539 deg
0.2 s	16.2633 deg	0.7 s	-30.009 deg	1.2 s	18.0336 deg	1.7 s	9.60637 deg
0.22 s	14.0004 deg	0.72 s	-29.8042 deg	1.22 s	20.0551 deg	1.72 s	7.08386 deg
0.24 s	11.6288 deg	0.74 s	-29.3761 deg	1.24 s	21.9225 deg	1.74 s	4.50595 deg
0.26 s	9.16663 deg	0.76 s	-28.7276 deg	1.26 s	23.6222 deg	1.76 s	1.89275 deg
0.28 s	6.63292 deg	0.78 s	-27.8632 deg	1.28 s	25.1419 deg	1.78 s	-0.735286 deg
0.3 s	4.04732 deg	0.8 s	-26.7889 deg	1.3 s	26.4707 deg	1.8 s	-3.35756 deg
0.32 s	1.43001 deg	0.82 s	-25.5122 deg	1.32 s	27.5993 deg	1.82 s	-5.95352 deg
0.34 s	-1.1985 deg	0.84 s	-24.0419 deg	1.34 s	28.5199 deg	1.84 s	-8.50289 deg
0.36 s	-3.81762 deg	0.86 s	-22.3887 deg	1.36 s	29.2259 deg	1.86 s	-10.9858 deg
0.38 s	-6.40684 deg	0.88 s	-20.5644 deg	1.38 s	29.7126 deg	1.88 s	-13.3832 deg
0.4 s	-8.94592 deg	0.9 s	-18.5822 deg	1.4 s	29.9767 deg	1.9 s	-15.6766 deg
0.42 s	-11.4152 deg	0.92 s	-16.457 deg	1.42 s	30.0163 deg	1.92 s	-17.8486 deg
0.44 s	-13.7955 deg	0.94 s	-14.2045 deg	1.44 s	29.8312 deg	1.94 s	-19.8829 deg
0.46 s	-16.0687 deg	0.96 s	-11.8417 deg	1.46 s	29.4227 deg	1.96 s	-21.7644 deg
0.48 s	-18.2176 deg	0.98 s	-9.38679 deg	1.48 s	28.7935 deg	1.98 s	-23.4794 deg

Extra ball: user-defined literals

User-defined literals

```
quantity<boost::units::si::acceleration> operator"" _m_s2(long double x)
{
  return double(x)*meter_per_second_squared;
}

quantity<boost::units::si::length> operator"" _cm(long double x)
{
  return quantity<boost::units::si::length>{double(x)*centimeter};
}

quantity<boost::units::si::time> operator"" _s(long double x)
{
  return double(x)*second;
}

quantity<boost::units::si::plane_angle> operator"" _deg(long double x)
{
  return quantity<boost::units::si::plane_angle>{double(x)*degree};
}

quantity<boost::units::si::angular_velocity> operator"" _deg_s(long double x)
{
  return quantity<boost::units::si::angular_velocity>{double(x)*degree/second};
}
```

User-defined literals

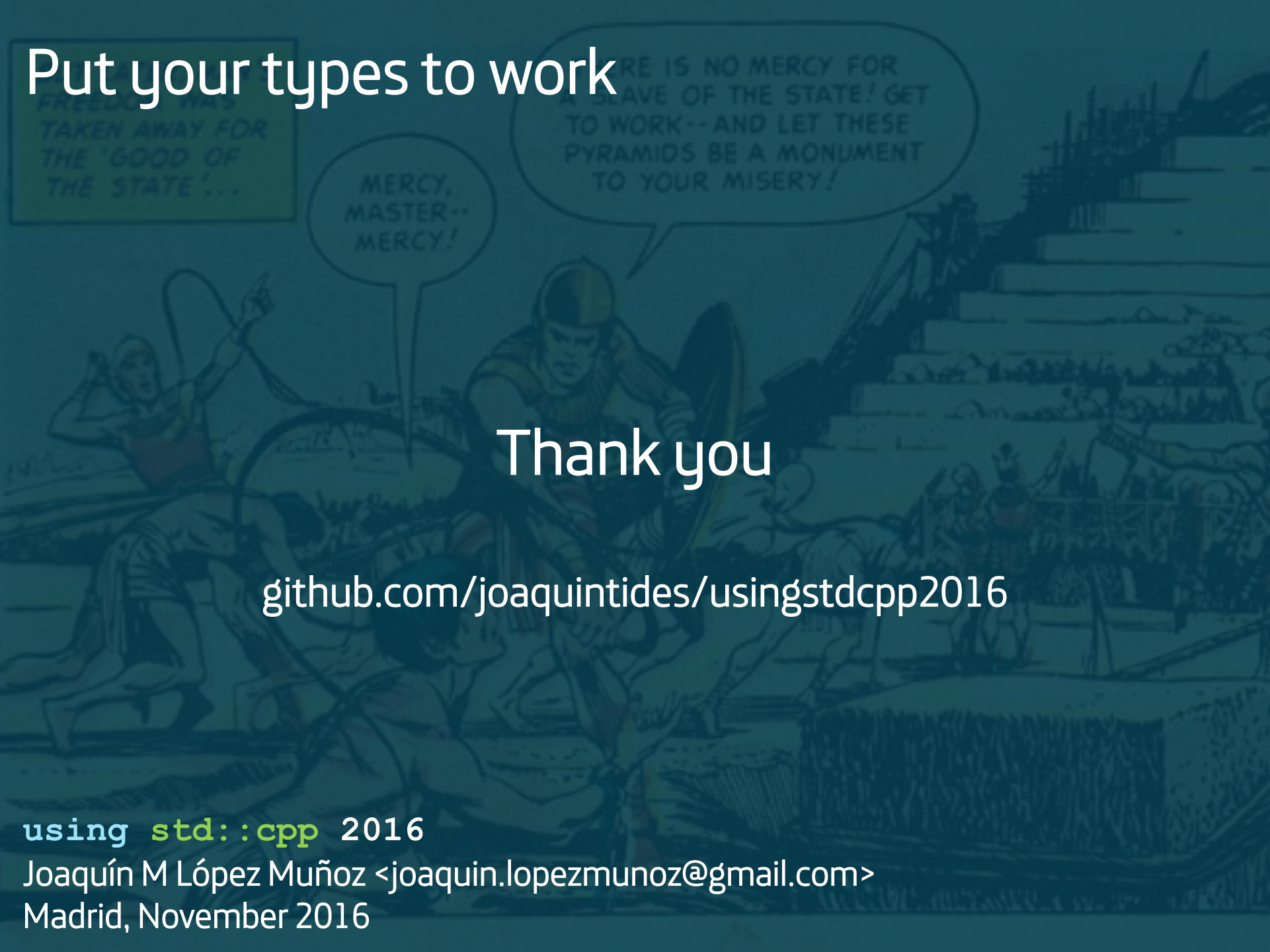
```
int main()
{
  const auto g=9.8_m_s2;
  const auto l=50.0_cm;
  const auto dt=0.02_s;

  auto       theta=30.0_deg;
  auto       theta_v=0.0_deg_s;

  std::cout<<"time\tangle\n";
  for(auto t=0.0_s;t<2.0_s;t+=dt){
    auto theta_a=-sin(theta)*radian*g/l;
    theta_v+=theta_a*dt;
    theta+=theta_v*dt;
    std::cout<<t<<"\t"<<
      quantity<boost::units::degree::plane_angle>{theta}<<"\n";
  }
}
```

Summary

Summary

- Types model the real world of your application
  - Let them multiply and fill the earth
- Bad practices with types
  - Identifying objects and representations: tell them apart!
  - Not enforcing invariants
    - Go for construction/assignment checking at least
    - Domain-specific libs are even better
- Rethink your representations
- Physical calculations are hard: let the compiler help you
  - User-defined literals can be thrown in for better readability

Put your types to work



Thank you

github.com/joaquintides/usingstdcpp2016

`using std::cpp 2016`
Joaquín M López Muñoz <joaquin.lopezmunoz@gmail.com>
Madrid, November 2016