



nota:  $y = \text{sgm}(s) = \frac{1}{1 + \exp(-s)}$ , donde  $s = w \cdot x + b$

Parte a: Derive una regla de aprendizaje por gradiente descendente para el ajuste del peso  $w$  y del bias  $b$ .

De las clases:  $W_{k+1} = W_k + \mu \cdot (-\nabla_k)$

$$\begin{aligned} (1) \quad \frac{\partial y}{\partial b} &= \frac{\exp(-(wx+b))}{(\exp(-(wx+b))+1)^2} = y^2 \cdot \exp(-(wx+b)) \\ (2) \quad \frac{\partial y}{\partial w} &= \frac{\exp(-(wx+b))}{(\exp(-(wx+b))+1)^2} \cdot x = y^2 \cdot \exp(-(wx+b)) \cdot x \end{aligned}$$

1) Usando el error cuadrático

$$E(w, b) = (t - y)^2 = \left( t - \frac{1}{1 + \exp(-(wx+b))} \right)^2$$

$$b_{k+1} = b_k - \mu \cdot \frac{\partial E(w, b)}{\partial b} \quad *$$

Luego reemplazando:

$$y = \frac{1}{1 + \exp(-(wx+b))}$$

$$b_{k+1} = b_k - \mu \cdot 2 \cdot (t - y) \cdot \left( -\frac{\partial y}{\partial b} \right)$$

$$b_{k+1} = b_k + \mu \cdot 2 \cdot (t - y) \cdot \frac{\exp(-(wx+b))}{(\exp(-(wx+b))+1)^2}$$

$$b_{k+1} = b_k + 2 \cdot \mu \cdot (t - y) \cdot y^2 \cdot \exp(-(wx+b))$$

Ahora para los pesos:

$$W_{k+1} = W_k + \mu \cdot (-\nabla_k) \quad *$$

$$W_{k+1} = W_k - \mu \cdot 2 \cdot (t - y) \cdot \left( -\frac{\partial y}{\partial w} \right)$$

$$W_{k+1} = W_k + 2 \cdot \mu \cdot (t - y) \cdot \frac{\exp(-(wx+b))}{(\exp(-(wx+b)) + 1)^2} \cdot x$$

$$\Leftrightarrow W_{k+1} = W + 2 \cdot \mu \cdot (t - y) \cdot y^2 \cdot \exp(-(wx+b)) \cdot x$$

En Resumen, las reglas para el ajuste del Bias y de los pesos son:

b	$b_{k+1} = b + \mu \cdot 2 \cdot \left(t - \frac{1}{1 + \exp(-(wx+b))}\right) \cdot \frac{\exp(-(wx+b))}{(\exp(-(wx+b)) + 1)^2}$
W	$W_{k+1} = W + 2 \cdot \mu \cdot \left(t - \frac{1}{1 + \exp(-(wx+b))}\right) \cdot \frac{\exp(-(wx+b))}{(\exp(-(wx+b)) + 1)^2} \cdot x$

o de forma más simplificada:

b	$b_{k+1} = b + 2 \cdot \mu \cdot (t - y) \cdot y^2 \cdot \exp(-(wx+b))$
W	$W_{k+1} = W + 2 \cdot \mu \cdot (t - y) \cdot y^2 \cdot \exp(-(wx+b)) \cdot x$

2) Usando la Entropía Cruzada

$$E(w, b) = -t \cdot \ln(y) - (1 - t) \ln(1 - y)$$

primero, para tener una idea de como es la derivada, derivemos con respecto a y:

$$\frac{dE(y)}{dy} = -t \cdot \frac{1}{y} \cdot y' - (1 - t) \cdot \frac{1}{(1 - y)} \cdot (-y')$$

$$\text{Con } y = \frac{1}{1 + \exp(-(wx+b))}$$

$$b_{k+1} = b - \mu \cdot \frac{\partial E(w, b)}{\partial b}$$

$$w_{k+1} = w - \mu \cdot (\nabla_k)$$

Para el bias (b):

$$\frac{\partial E(w, b)}{\partial b} = -t \cdot \frac{1}{y} \cdot \frac{\partial y}{\partial b} - (1-t) \cdot \frac{1}{(1-y)} \cdot \left( \frac{\partial y}{\partial b} \right)$$

por ①

$$= -t \cdot \frac{1}{y} \cdot y^2 \cdot \exp(-(wx+b)) + (1-t) \cdot \frac{1}{(1-y)} \cdot y^2 \cdot \exp(-(wx+b))$$

$$= -t \cdot y \cdot \exp(-(wx+b)) + \frac{(1-t) \cdot y^2 \cdot \exp(-(wx+b))}{(1-y)}$$

Para los pesos:

$$\frac{\partial E(w, b)}{\partial w} = -t \cdot \frac{1}{y} \cdot \frac{\partial y}{\partial w} + (1-t) \cdot \frac{1}{(1-y)} \cdot \left( \frac{\partial y}{\partial w} \right)$$

por ②

$$= -t \cdot \frac{1}{y} \cdot y^2 \cdot \exp(-(wx+b)) \cdot x + (1-t) \cdot \frac{1}{(1-y)} \cdot y^2 \cdot \exp(-(wx+b)) \cdot x$$

$$= -t \cdot y \cdot \exp(-(wx+b)) \cdot x + \frac{(1-t) \cdot y^2 \cdot \exp(-(wx+b)) \cdot x}{(1-y)}$$

En Resumen:

$$b_{k+1} = b - \mu \cdot \left( -t \cdot y \cdot \exp(-(wx+b)) + \frac{(1-t) \cdot y^2 \cdot \exp(-(wx+b))}{(1-y)} \right)$$

$$w_{k+1} = w - \mu \cdot \left( -t \cdot y \cdot \exp(-(wx+b)) \cdot x + \frac{(1-t) \cdot 1}{(1-y)} \cdot y^2 \cdot \exp(-(wx+b)) \cdot x \right)$$