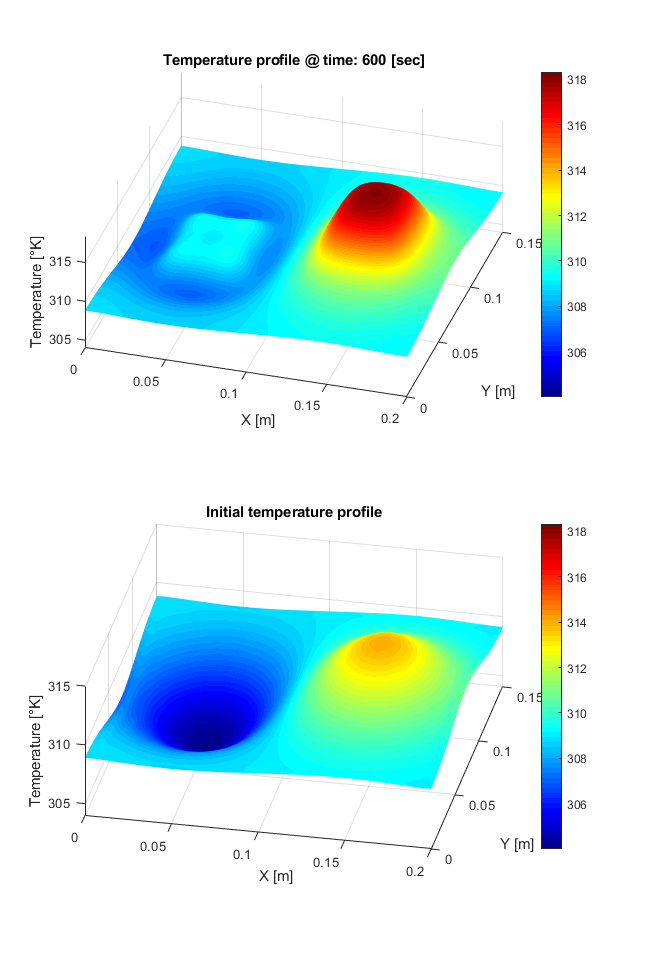
5LMA0 – Project heat diffusion



**Date:**

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# Introduction

In this project a model for hyperthermia is considered which describes how a temperature distribution on a locally heated surface evolves over time. A rectangular area is considered of dimension as shown in Figure 1. Here the green areas and are defined as inputs where the heat fluxes are applied, the yellow area is normal tissue and the orange area is tumor tissue with dimensions .

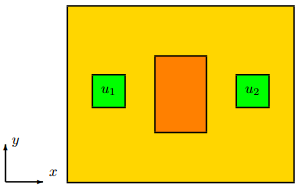


Figure 1 – Configuration of surface with heat flux locations

The model is described by the following parabolic partial differential equation:

where

|  |  |  |  |
| --- | --- | --- | --- |
| **Symbol** | **Description** | **Unit** | **Value** |
| Lx | Length | [m] | 0.2 |
| Ly | Width | [m] | 0.15 |
|  | Material densities (yellow, orange area) | [kg/m3] | 1100, 1000 |
|  | Heat capacities (yellow, orange area) | [J/(kg K)] | 3890, 3350 |
|  | Thermal conductivities (yellow, orange area) | [W/(m K)] | 0.31, 0.31 |
| (X1,Y1) | Location heat flux 1 | ([m],[m]) | (Lx/4, Ly/2) |
| (X2,Y2) | Location heat flux 2 | ([m],[m]) | (3Lx/4, Ly/2) |
| W | Actuator width | [m] | 0.05 |
| Tambient | Ambient temperature | [K] | 309 |

Table 1 – Model properties

Furthermore, the output of the model is the temperature of the surface in degrees Kelvin defined by .

The purpose of this project is to derive a fast and simple model that accurately describes the temperature evolution of this system, as explained in the following ten exercises.

# Exercise 1

In this exercise is proven whether the system is linear or nonlinear and whether the system is time-variant or time-invariant. While doing so, the two cases where the model is homogeneous or non-homogeneous are distinguished.

If the model is **homogeneous**, , c and K do not depend on the position (x,y). The system is linear because , c and K remain constant over time and position, resulting in the same temperature when the position of the input heat flux changes. The system is time-invariant because the output is the same to the same input at different moments in time.

When the model is **non-homogeneous**, , c and K do depend on the position (x,y). The system is now non-linear because , c and K are changing over position, resulting in different temperatures when the position of the input heat flux changes. The system is still time-invariant.

# Exercise 2

For now it is assumed that the model is homogeneous, meaning that (no orange area) and the model is homogeneous meaning that and are positive constants.

Show that under these conditions, (equation 1 from exercise) admits a solution of the form whenever . Here and are scalar-valued functions on , and , respectively, that satisfy the separated differential equations

for suitable constants and .

When , this results in the following equation:

Now is substituted by , resulting in the following equation:

Which can be rewritten in the following three equations:

Now the following lambdas are defined:

Using these lambdas results in the following equations:

These can be substituted which results in:

These lambdas are the initial conditions of the simplified model.

# Exercise 3

In this exercise is shown that for any and the set is an orthonormal set of functions in . Because and have the values this indicates that and .

First the functions for and are defined:

With these functions can be defined that:

Now the inner product space , based on , is computed:

To proof that is an orthonormal set of functions in the following statement has to hold:

The following is defined for any and and :

Where is the remainder of a division of x and returns the nearest integer less than or equal to y.

The next step is to define , which is done for different conditions based on and :

* If :
* If and :
* If and :
* If and :

Also is defined for different conditions based on and :

* If :
* If and :
* If and :
* If and :

When computing the inner product space (3, fix automatische verwijzing) the outcome is 1 if and 0 when , leading to the conclusion that the set is an orthonormal set of functions in for any and .

# Exercise 4

To be able to simulate the model, The Galerkin projection is used to transform the homogeneous and isotropic form of the model into an ordinary differential equation.

Using the spectral decomposition of the temperature evolution and the definition for the combined spectral components , the spectra decomposition of the temperature evolution is defined.

Replacing the double indexing with results in the spectral decomposition of the temperature evolution .

To calculate the Galerkin projection, the inner product of the model and the defined basis function is calculated using a standard inner product as defined in which results in equation .

Substituting the spectral decomposition of the temperature evolution results in equation

Because the defined inner product is a linear operator, the equation can be rewritten into equation and subsequently equation . From the definition it can also be seen that everything that is not a function of or can be treated as a constant which results in equation .

Due to the orthonormality of the basis function the equation can be rewritten into equation .

Rewriting this into matrix form for gives an ordinary differential equation .

Substituting the basis functions results in equation .

To derive the equilibrium solution of the model, the input is set to 0, leading to equation .

The free response of the model, which is in the form , can be calculated using equation resulting in equation .

The equilibrium solution can be obtained by equating the solution at , which results in the coefficients as can be seen in .

Filling in the coefficients in equation gives the equilibrium solution of the model. Substituting the basis function and replacing with the Initial temperature for the model results in equation . Which is as expected the average temperature of the initial temperature profile .

# Exercise 5

During this exercise the model is simulated using model parameters of Table 1 and no input heat fluxes. The initial temperature profile is a 2D Bell curve with height +5 [°K] and a width of 0.02 [m]. The simulation is executed with as shown in Figure 2, Figure 3, Figure 4 and Figure 5.

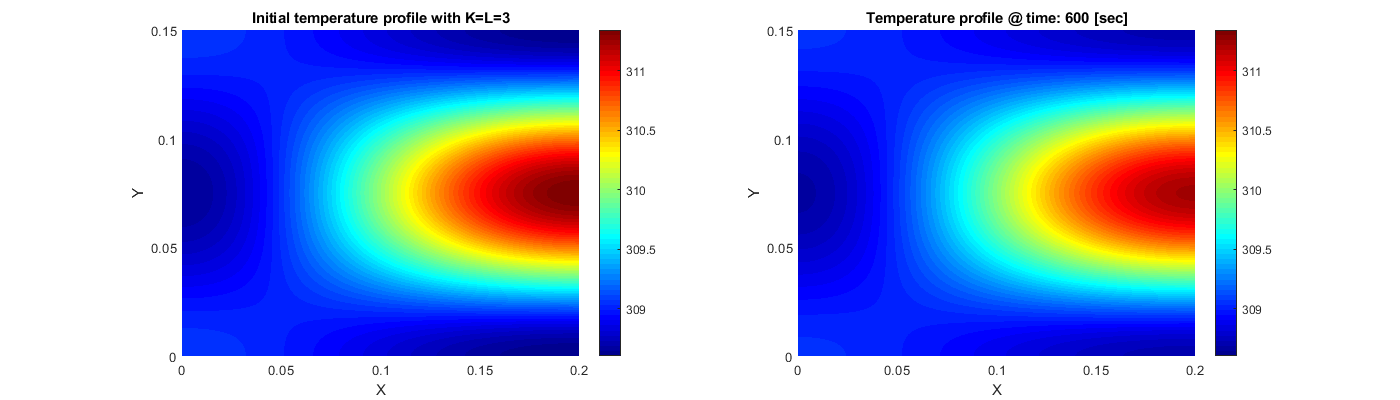
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Figure 2 – Initial temperature profile over time with K=L=3

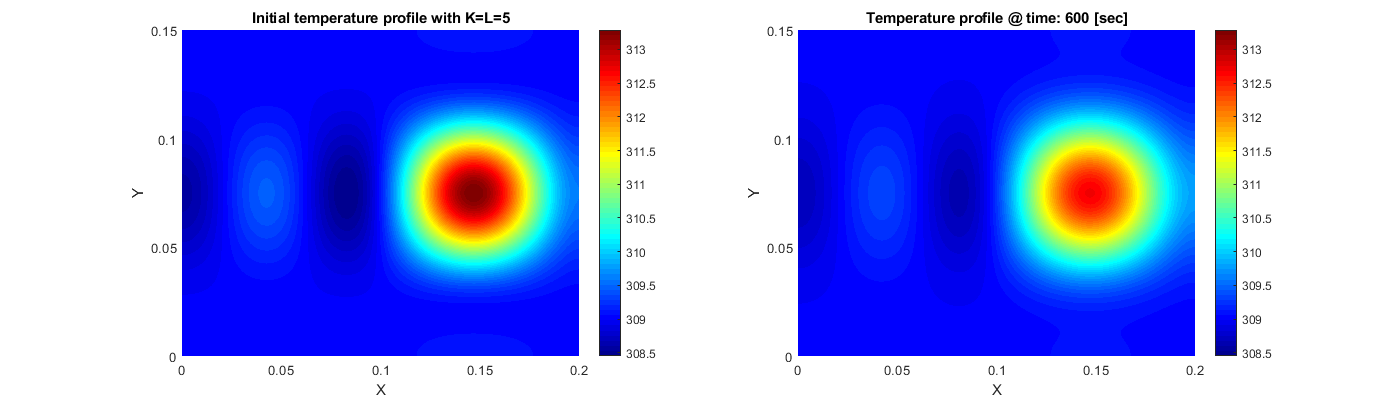


Figure 3 – Initial temperature profile over time with K=L=5

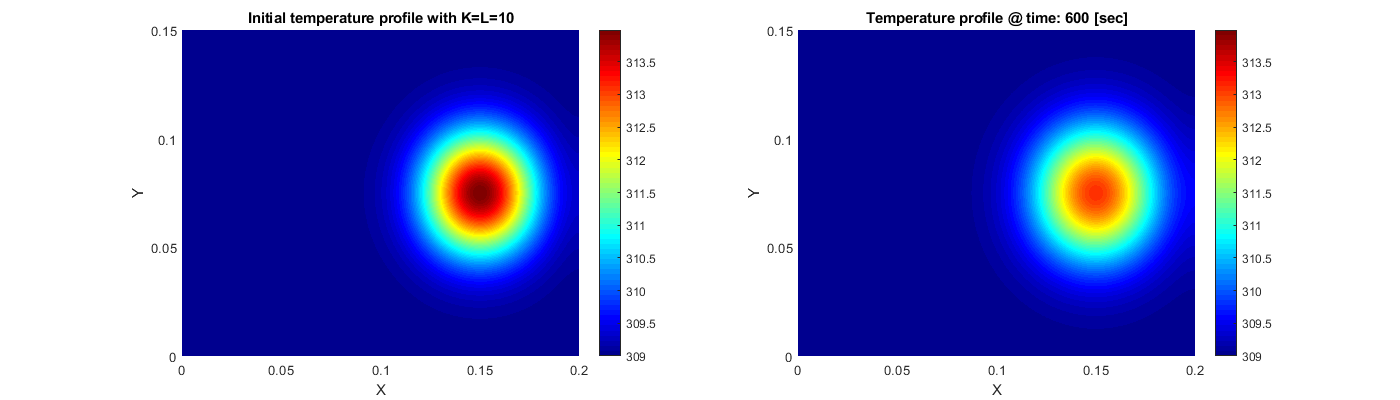


Figure 4 – Initial temperature profile over time with K=L=10

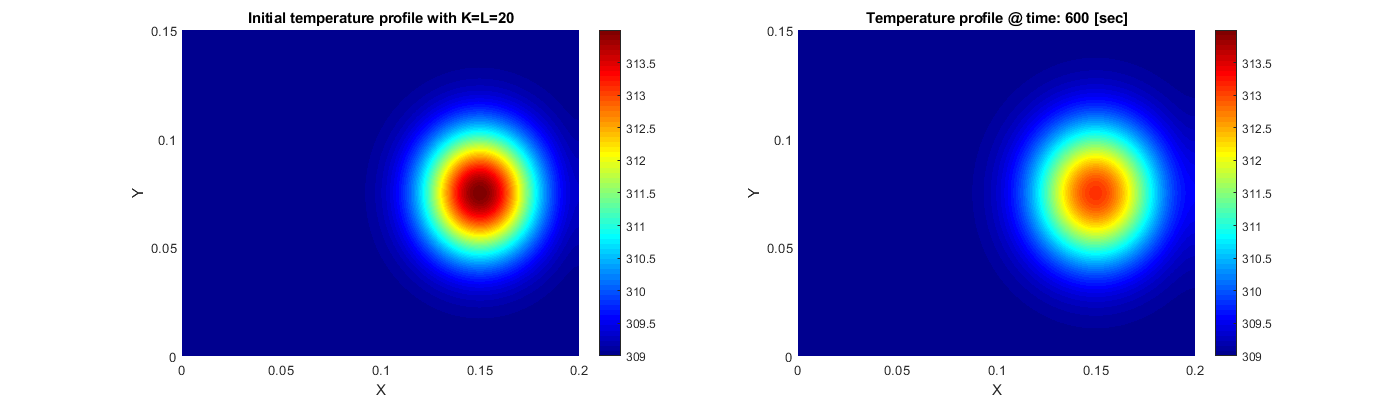


Figure 5 – Initial temperature profile over time with K=L=20

# Exercise 6

During this exercise the simulation is executed with

* Different initial temperature profiles
* Inputs for the heat fluxes and

while varying with the approximation orders and .

The initial temperature profile is now changed to two 2D Bell curves at the location of and and a radius of 0.03 [m]. The Bell curve at the location of has an initial peak temperature of +5 [°K] and the Bell curve at location has an initial peak temperature of -5 [°K]. This initial profile is simulated with the same approximation orders of exercise 5. The results of these simulations are shown in Figure 6, Figure 7, Figure 8 and Figure 9.

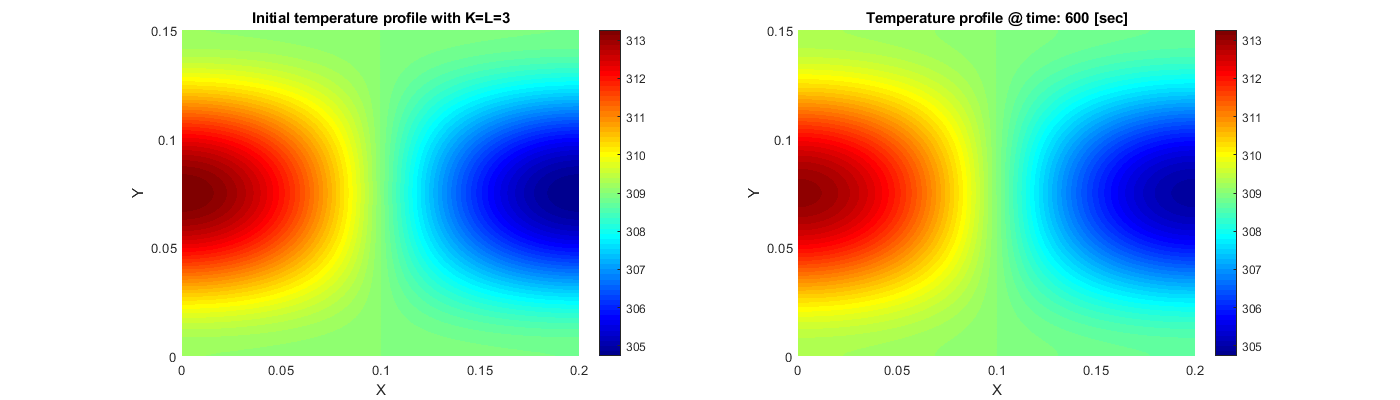


Figure 6 – Double Bell curve initial profile with K=L=3

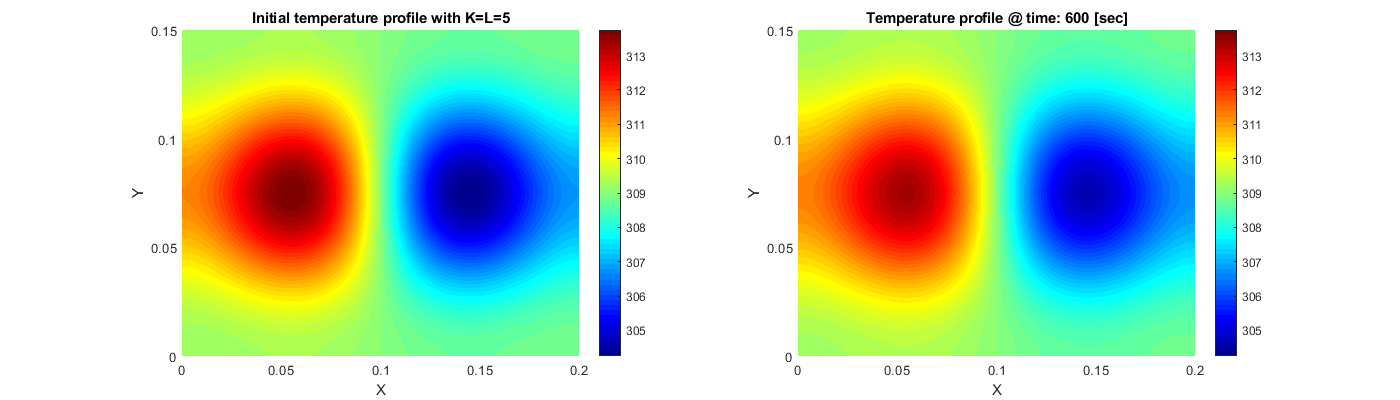


Figure 7 – Double Bell curve initial profile with K=L=5

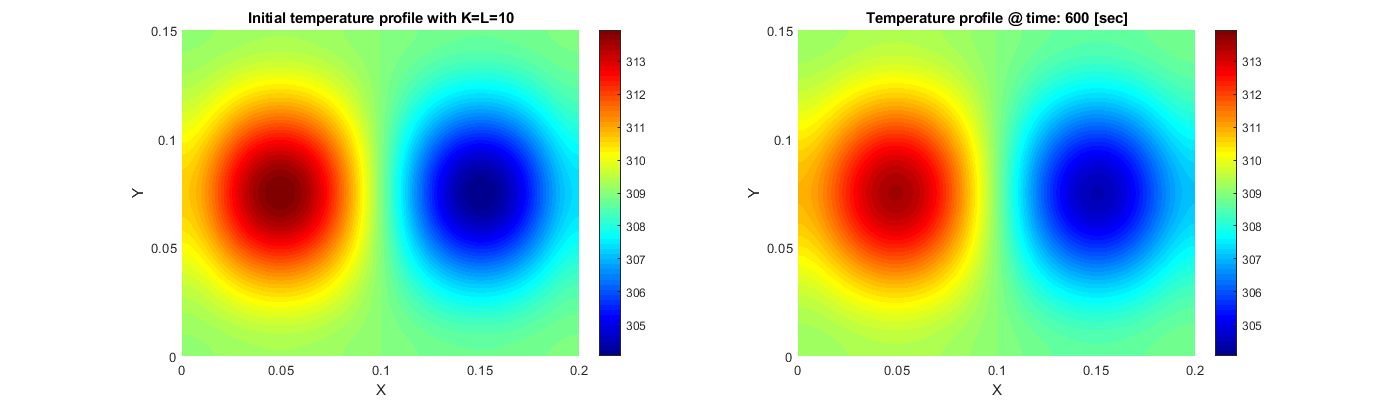


Figure 8 – Double Bell curve initial profile with K=L=10

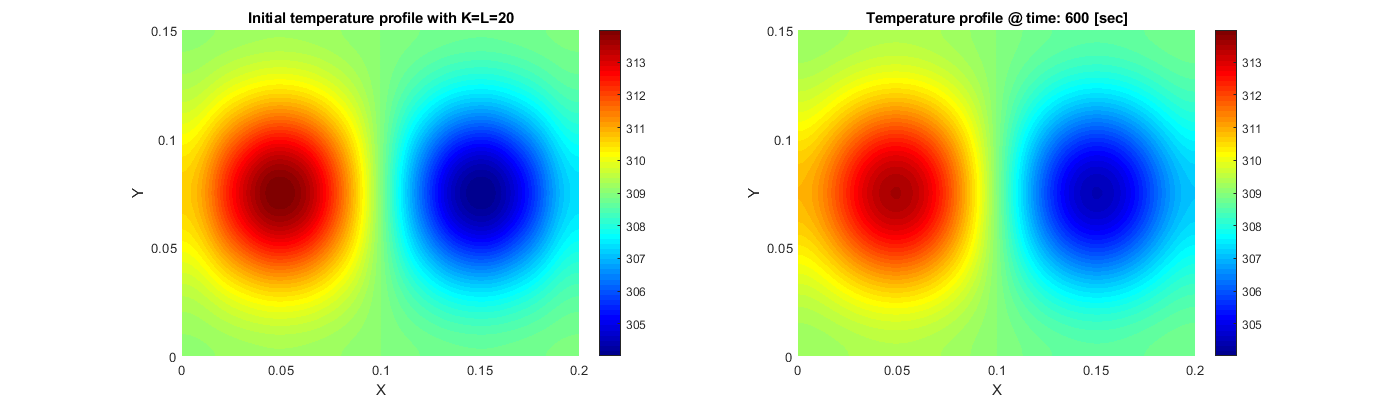


Figure 9 – Double Bell curve initial profile with K=L=20

Now the inputs and are added to the simulation with the following properties:

* Start at t=30
* Stop at t=330
* Heat flux = 60,000

and with the same initial temperature profile and values for and as in exercise 5, resulting in Figure 10, Figure 11, Figure 12 and Figure 13.

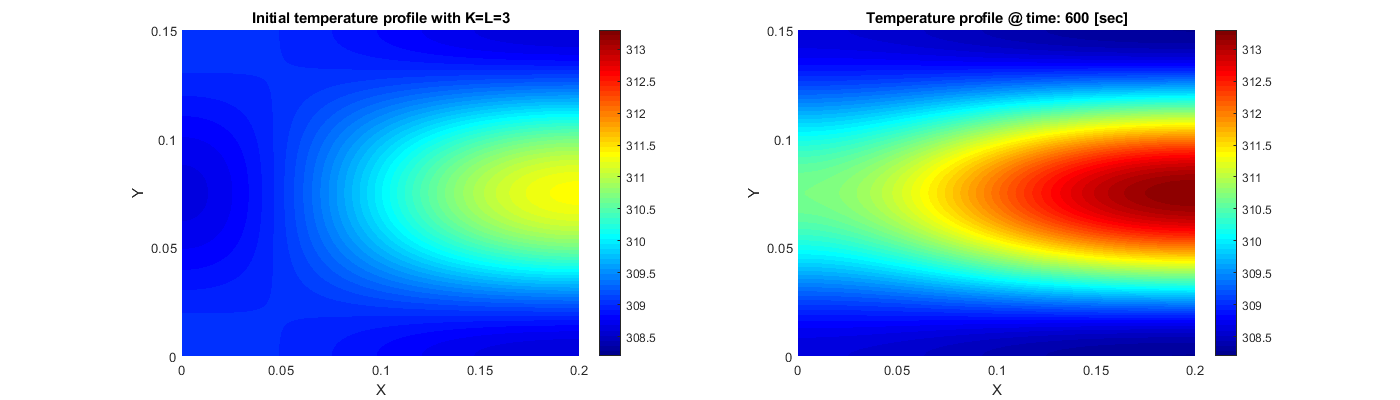


Figure 10 – Initial temperature profile with inputs u1 and u2 over time with K=L=3

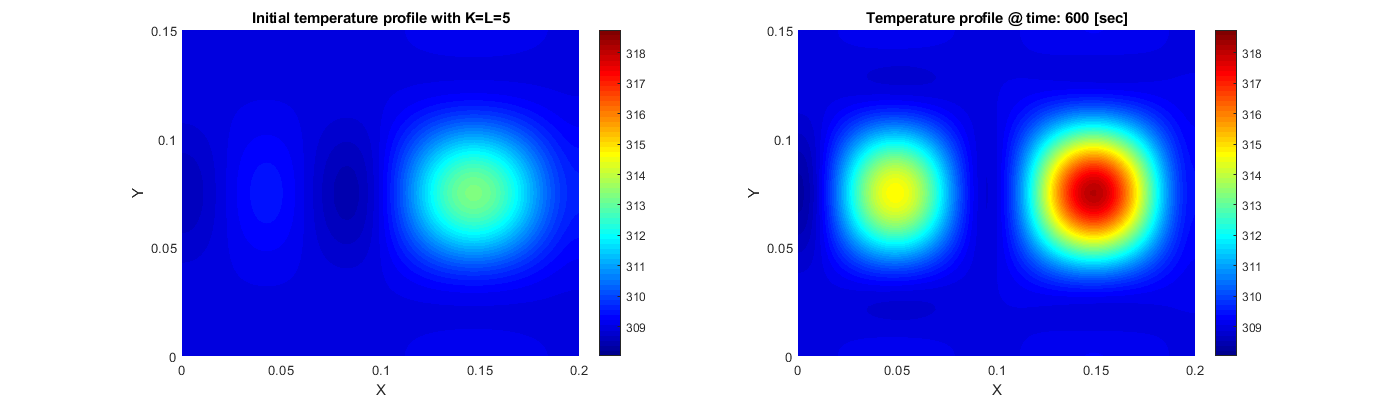


Figure 11 – Initial temperature profile with inputs u1 and u2 over time with K=L=5

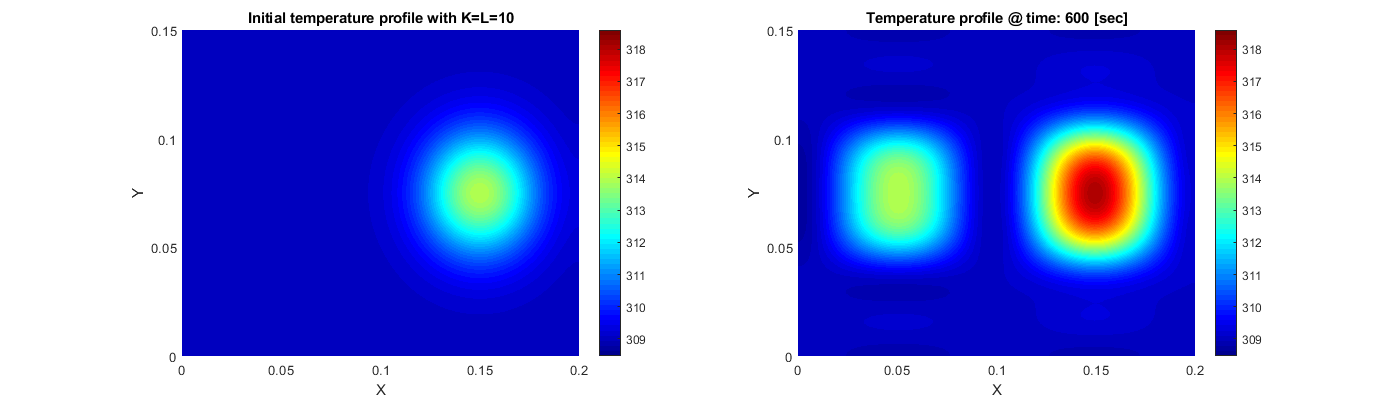


Figure 12 – Initial temperature profile with inputs u1 and u2 over time with K=L=10

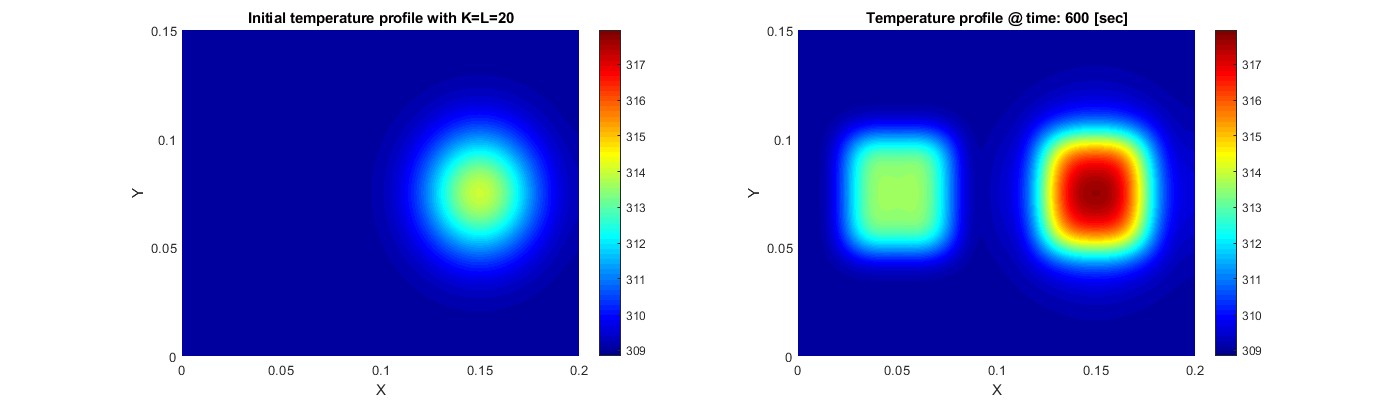


Figure 13 – Initial temperature profile with inputs u1 and u2 over time with K=L=20

From these simulations can be concluded that with higher approximation orders for and the results are more accurate. If the approximation order is low, harmonics are visible in the temperature profile. With an approximation order of 3 or lower the result is inaccurate.

# Exercise 7

In this exercise the output of the simulation is taken with an high approximation order and this data is used to compute a POD basis in of order .

This POD basis is created using the Singular Value Decomposition (SVD) of the data from an simulation.

Now where define the POD basis.

# Exercise 8

Now the POD basis from exercise 7 is used to create a reduced order POD model that takes the heat fluxes and as inputs and outputs the coefficients in the truncated expansion:

# Exercise 9

The next step is to validate the quality of the reduced order POD model from exercise 8 by simulating with different orders of , different initial temperature profiles and different heat fluxes and . To compare the POD basis to the earlier determined basis, the same orders for are used as for and .

First the reduced order POD model is simulated with the same initial temperature profile as during exercise 5 with varying :

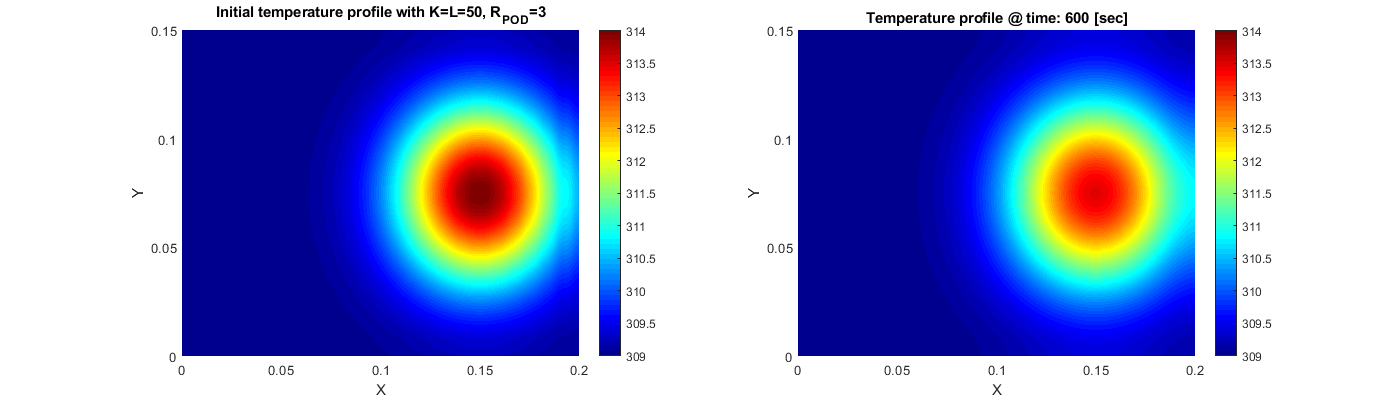


Figure 14 – POD basis initial profile over time with order R=3

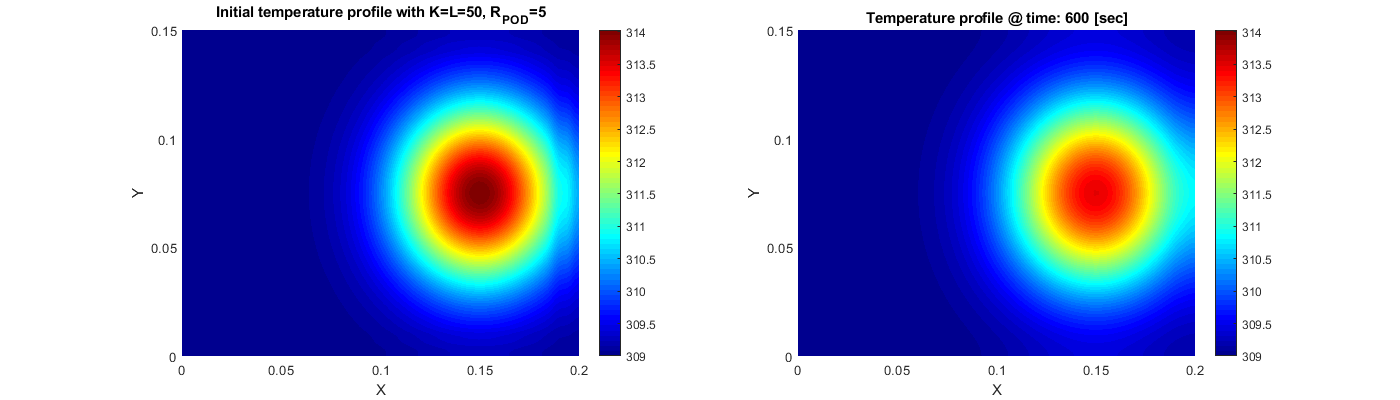


Figure 15 – POD basis initial profile over time with order R=5

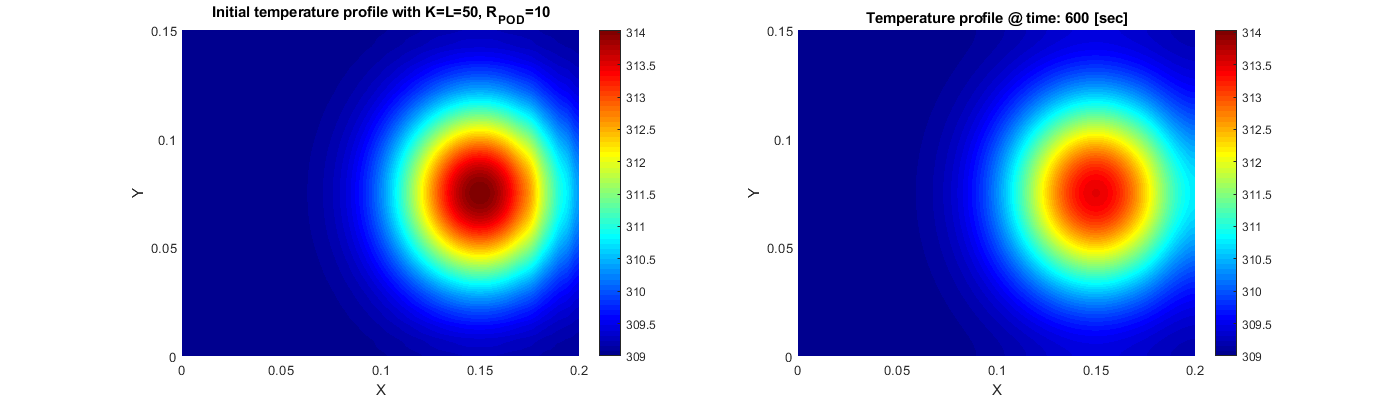


Figure 16 –POD basis initial profile over time with order R=10

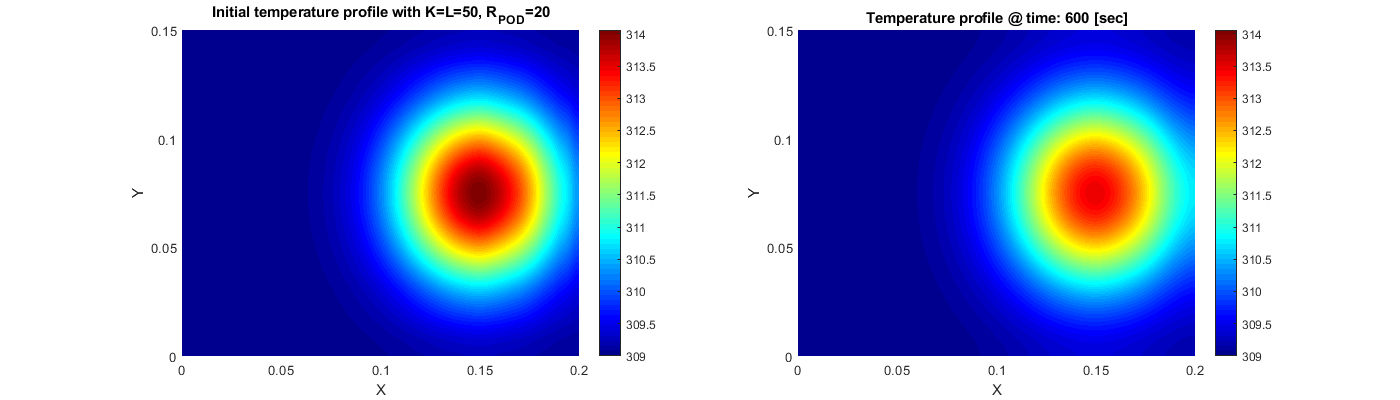


Figure 17 – POD basis initial profile over time with order R=20

Next the reduced order POD model is simulated with the same heat fluxes as during exercise 6 while varying :

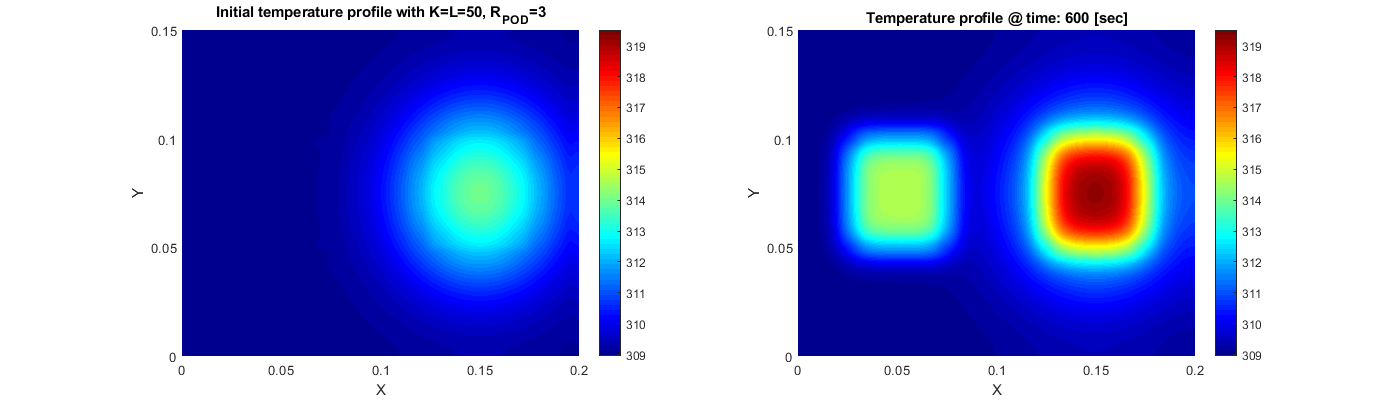


Figure 18 – POD basis initial temperature profile with inputs u1 and u2 over time with R=3

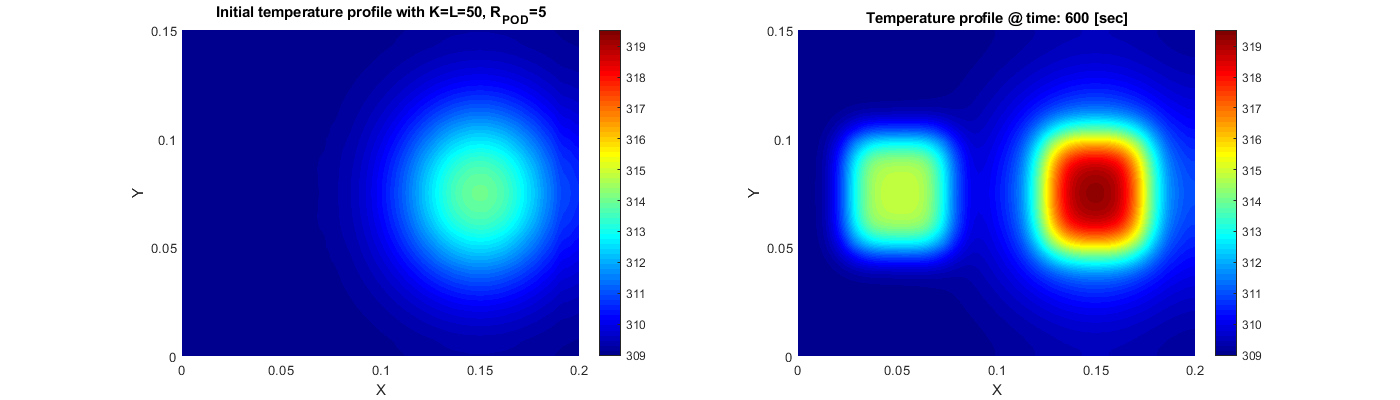


Figure 19 – POD basis initial temperature profile with inputs u1 and u2 over time with R=5

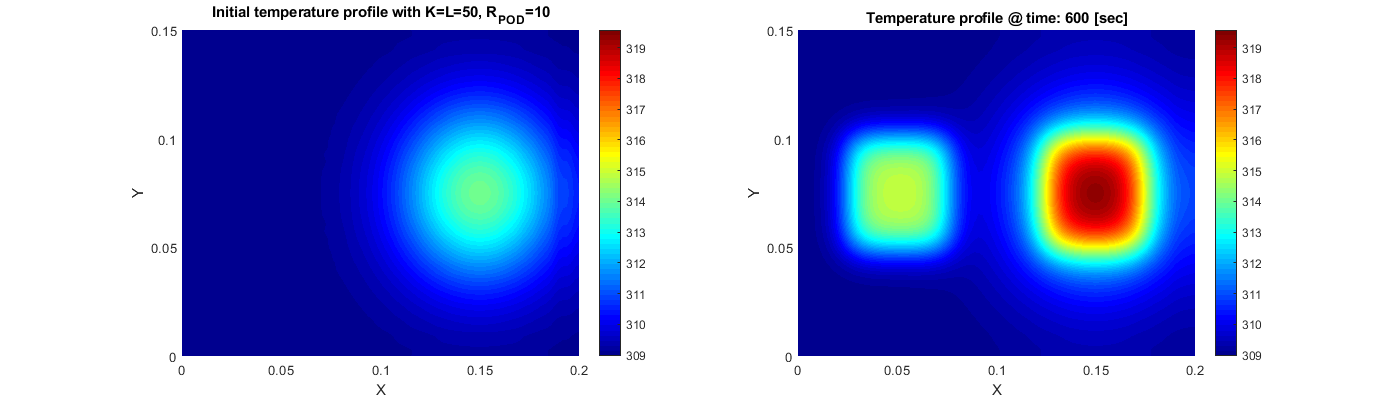


Figure 20 – POD basis initial temperature profile with inputs u1 and u2 over time with R=10

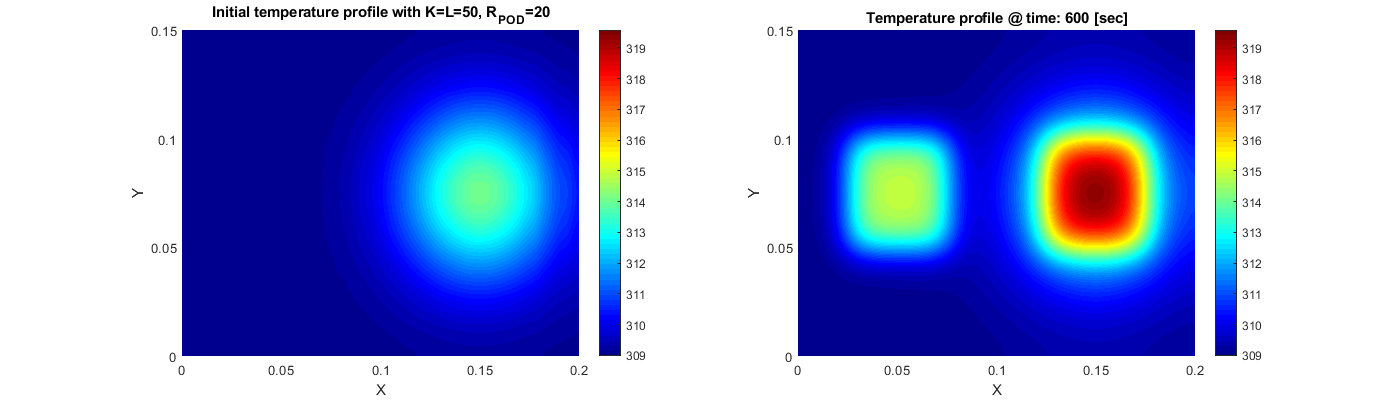


Figure 21 – POD basis initial temperature profile with inputs u1 and u2 over time with R=20

From the figures above can be concluded that the results are almost equal to each other, indicating that a low POD order already has a high accuracy in comparison to the earlier determined basis.

# Exercise 10