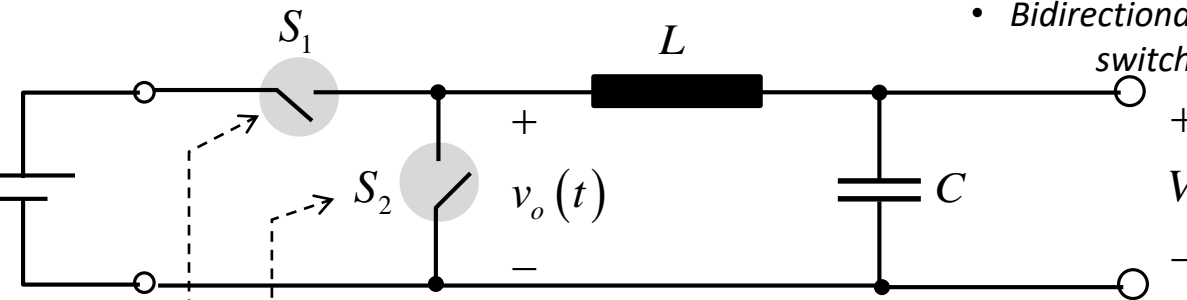

Chapter 3

DC-AC Converter (Inverter)

PWM Buck Converter (Revisited)

- Bidirectional power flow is achieved using controlled switches with anti-parallel diode for S_1 and S_2 .



PWM signal

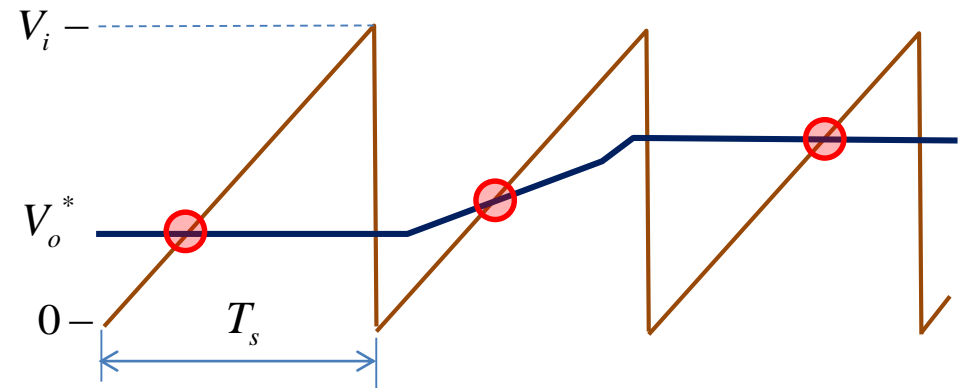
Not Gate

Carrier
(fs kHz range)

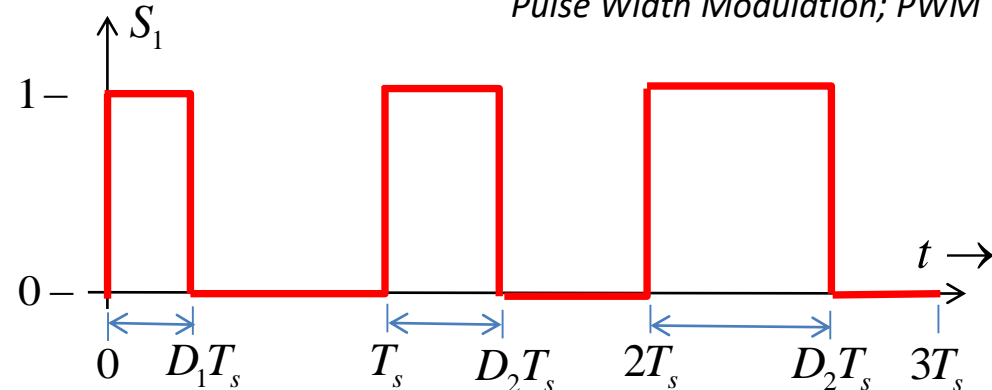
$$T_s = \frac{1}{f_s}$$

$$\frac{V_o}{V_i} = \frac{DT_s}{T_s}$$

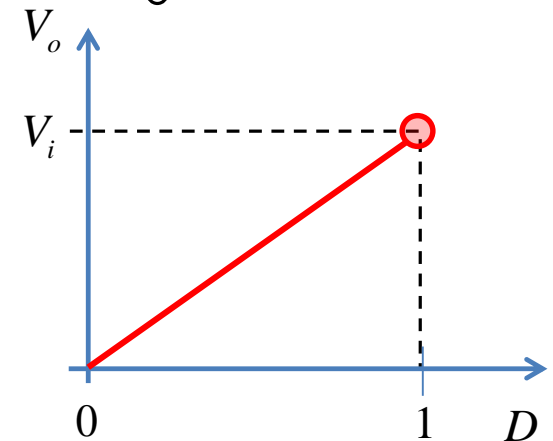
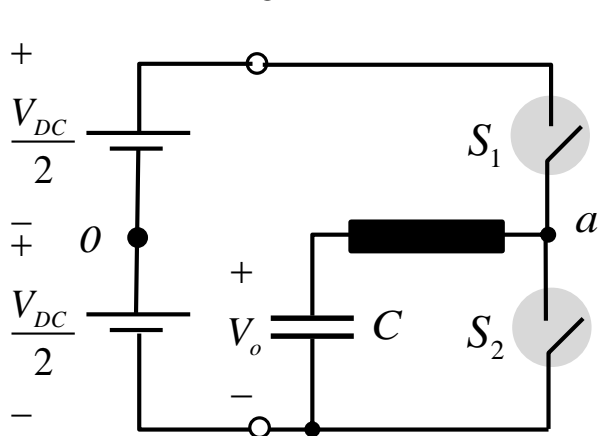
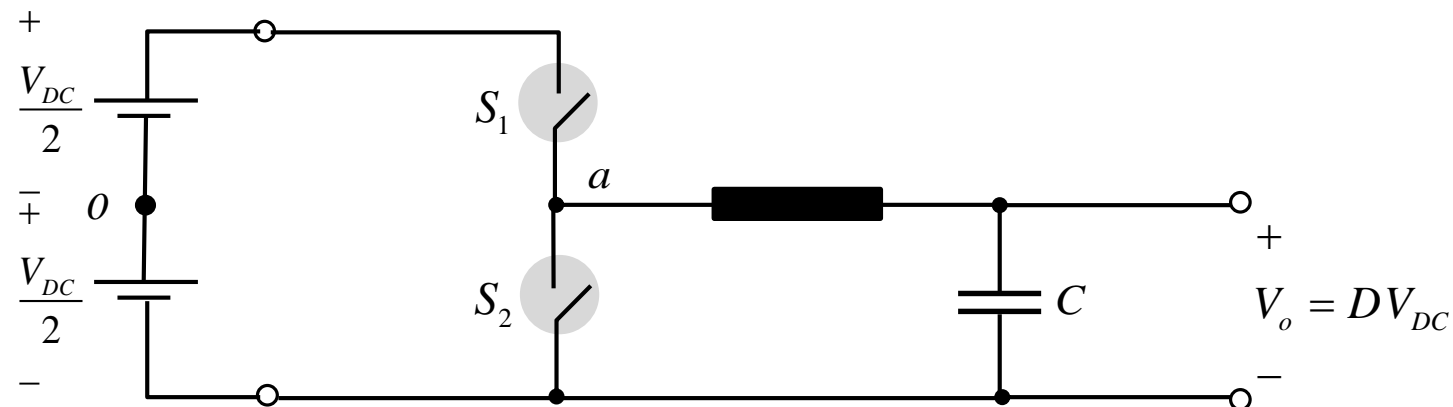
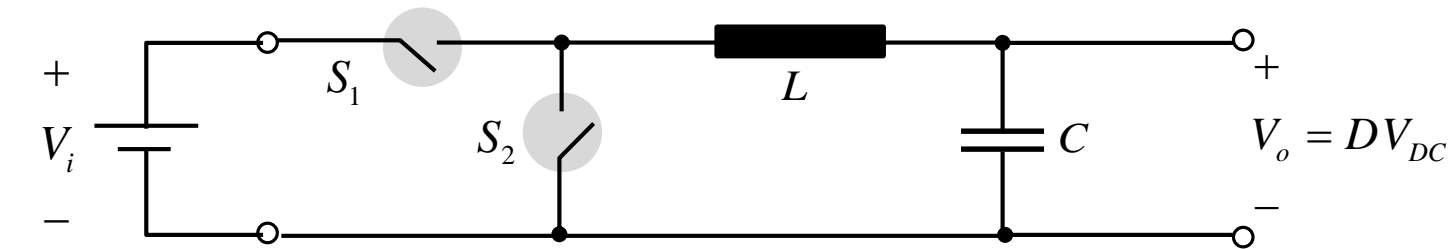
$$0 \leq D \leq 1; \quad 0 \leq V_o \leq V_i$$



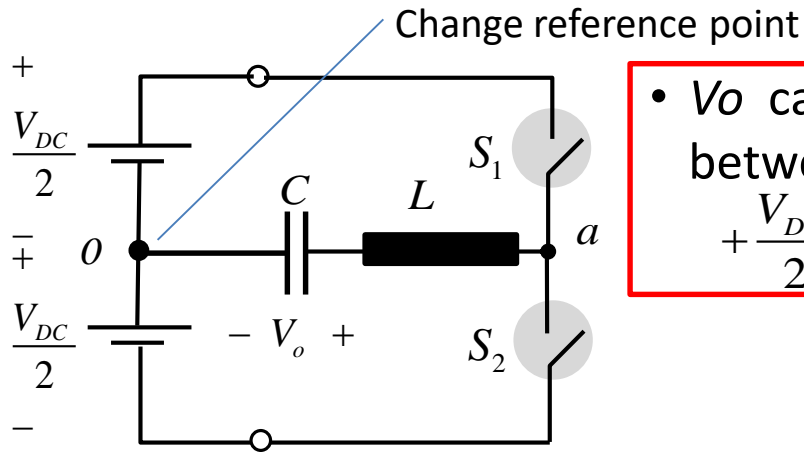
Pulse Width Modulation; PWM



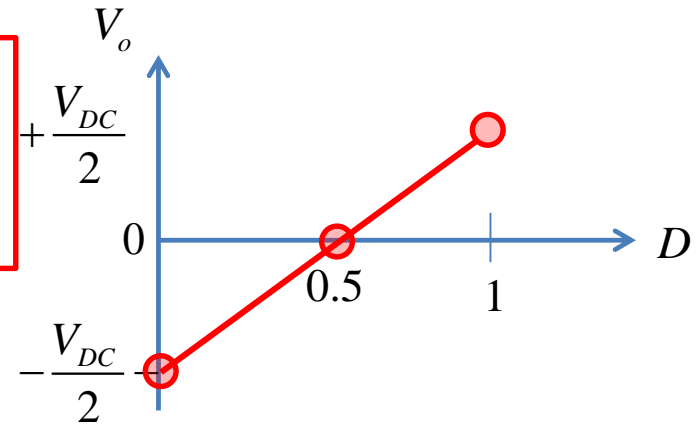
DC-AC Converter : Inverter (*Derivation from buck converter*)



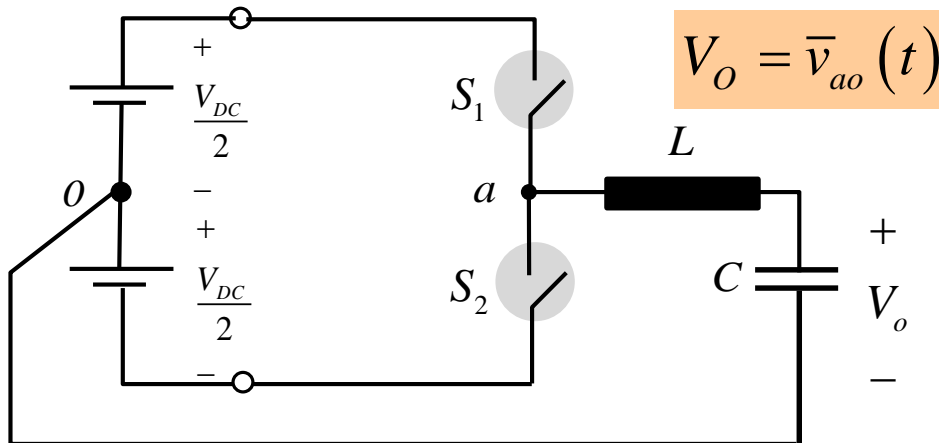
Inverter : *Derivation from buck converter*



- V_o can be varied between $+\frac{V_{DC}}{2}$ and $-\frac{V_{DC}}{2}$

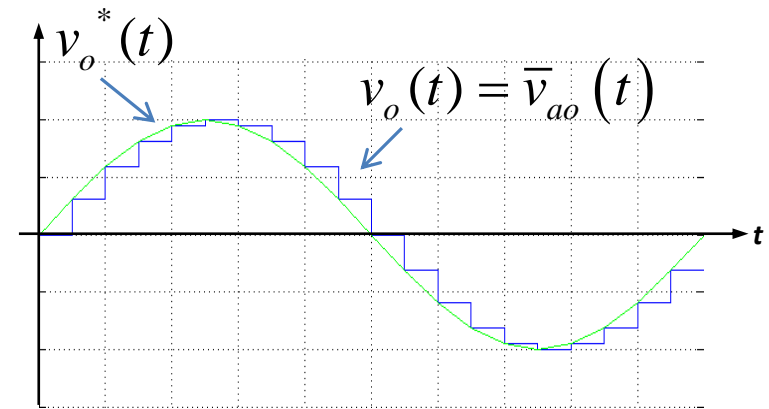
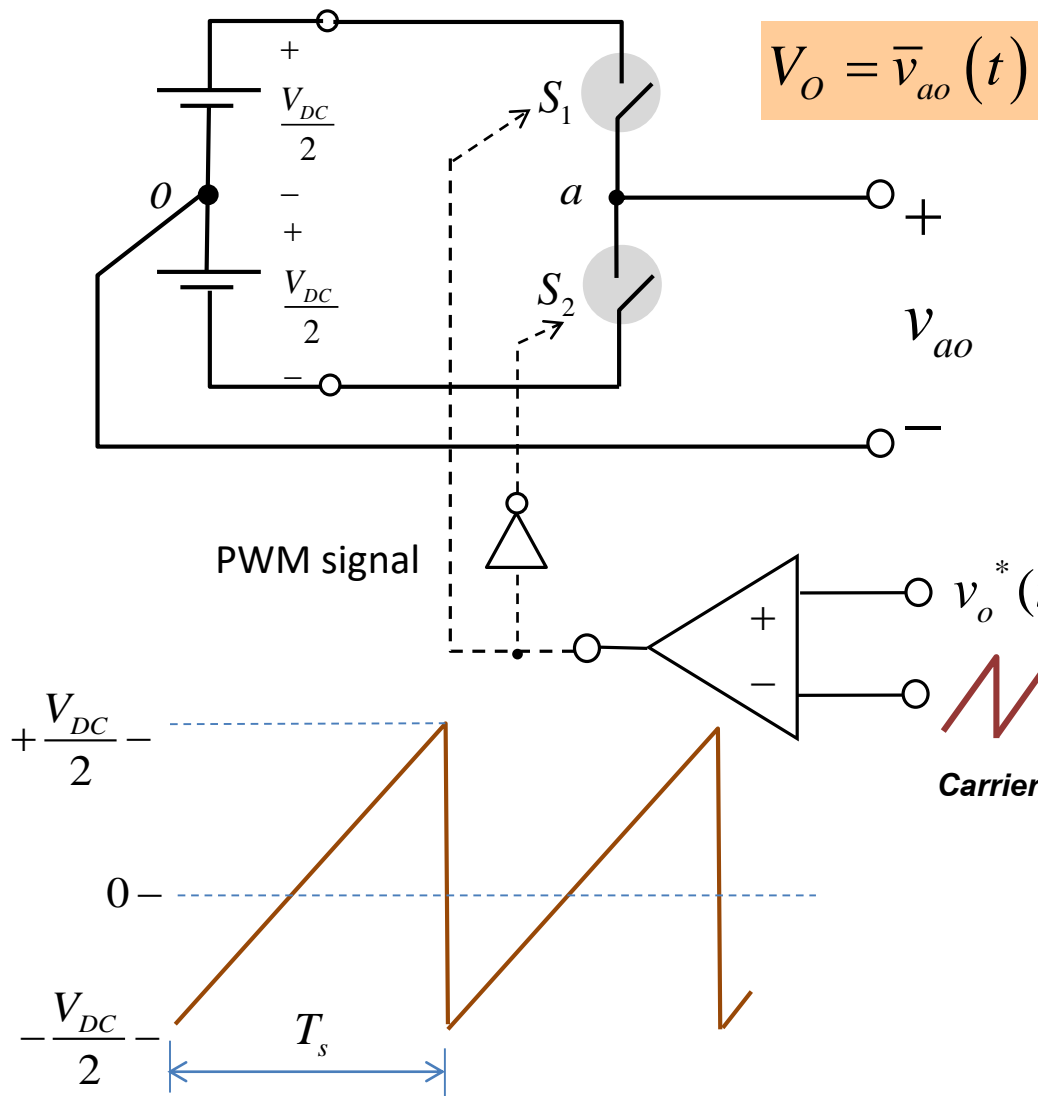


$$V_o = \left(D - \frac{1}{2} \right) V_{DC}$$



S1	S2	v_{ao}
ON	OFF	$+V_{DC} / 2$
OFF	ON	$-V_{DC} / 2$
ON	ON	Not allow
OFF	OFF	Uncontrolled Voltage

Half-Bridge Inverter : Pulse-Width Modulation



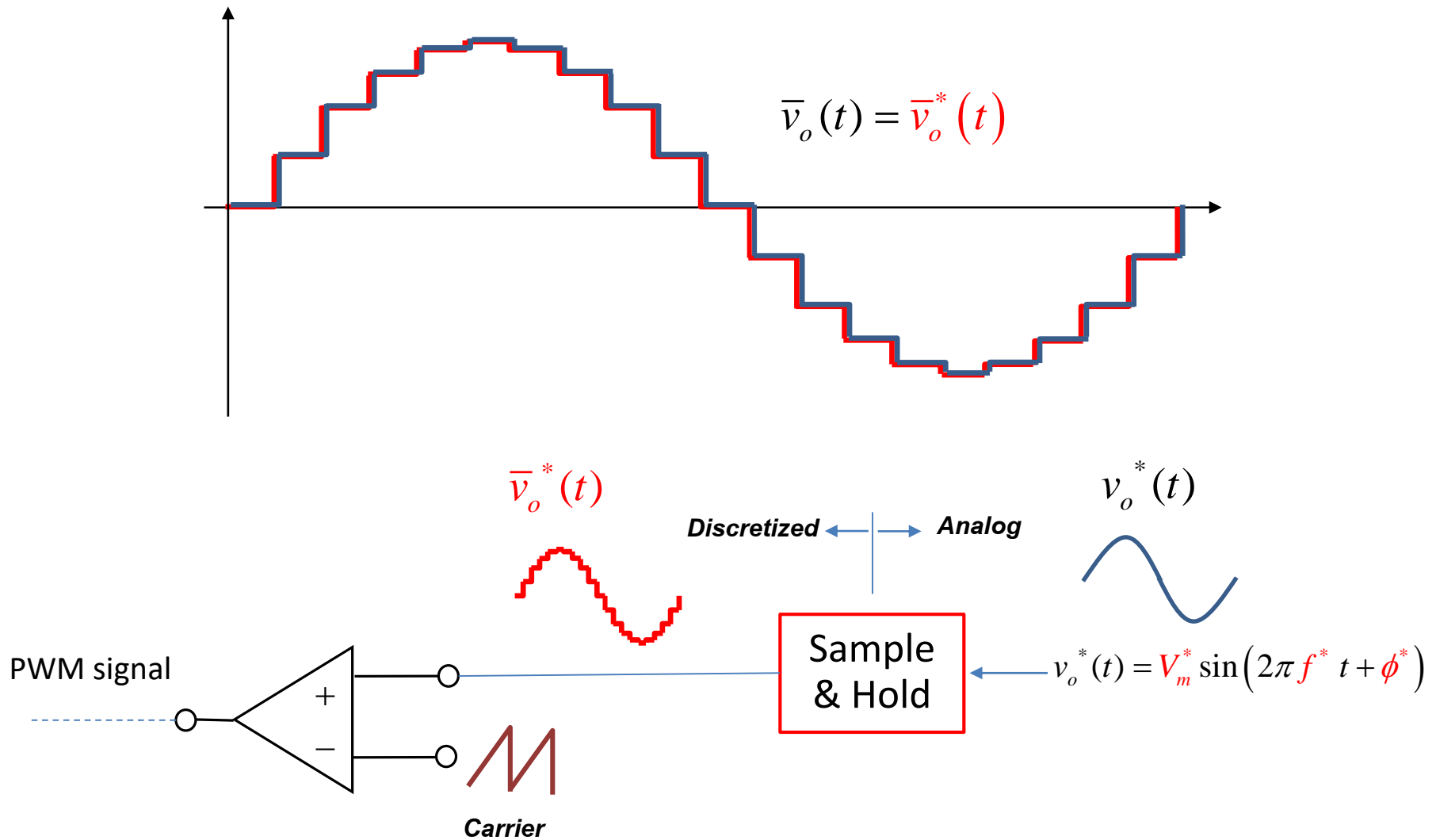
$$v_o^*(t) = V_m^* \sin(2\pi f^* t + \phi^*)$$

Carrier

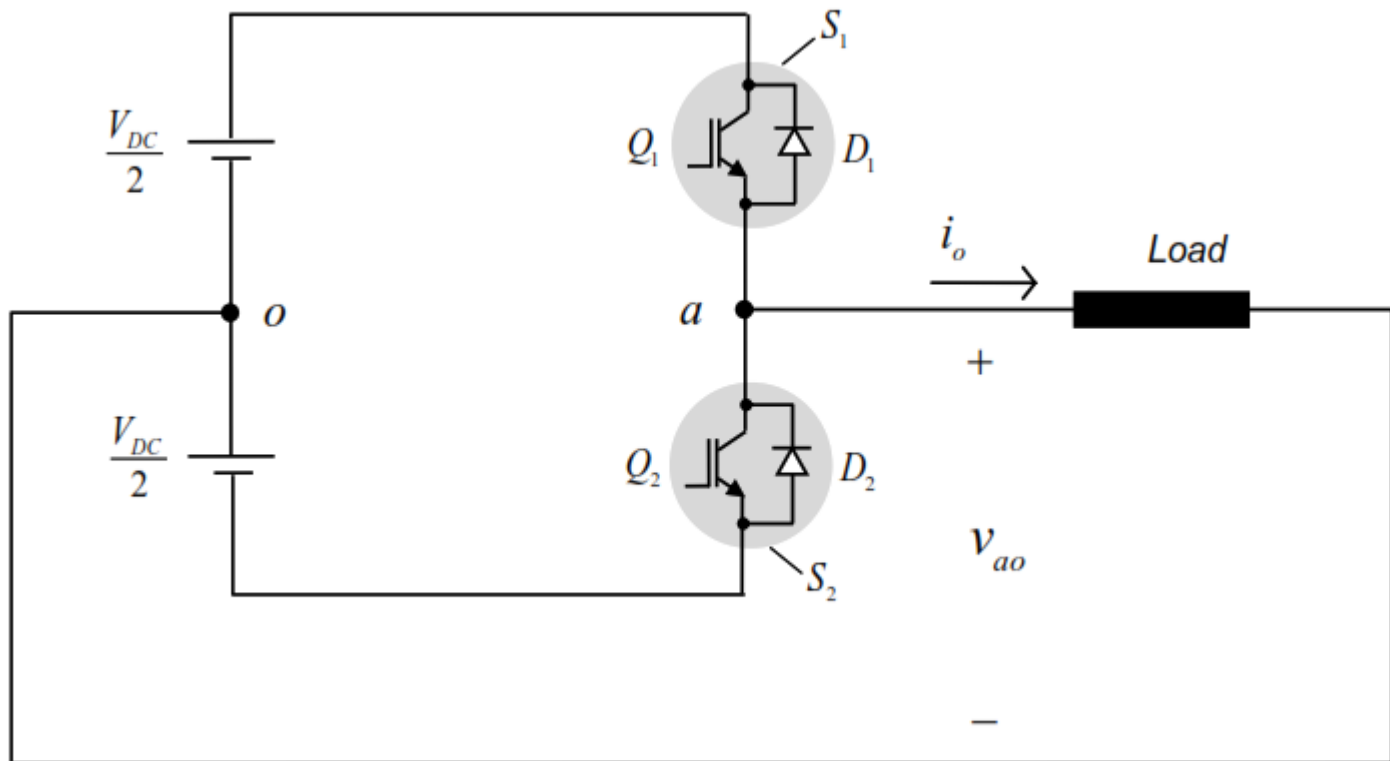
- Inverter can generate AC voltage which corresponds to the commanded voltage amplitude, frequency and phase shift.

$$V_m^* \leq \frac{V_{DC}}{2}$$

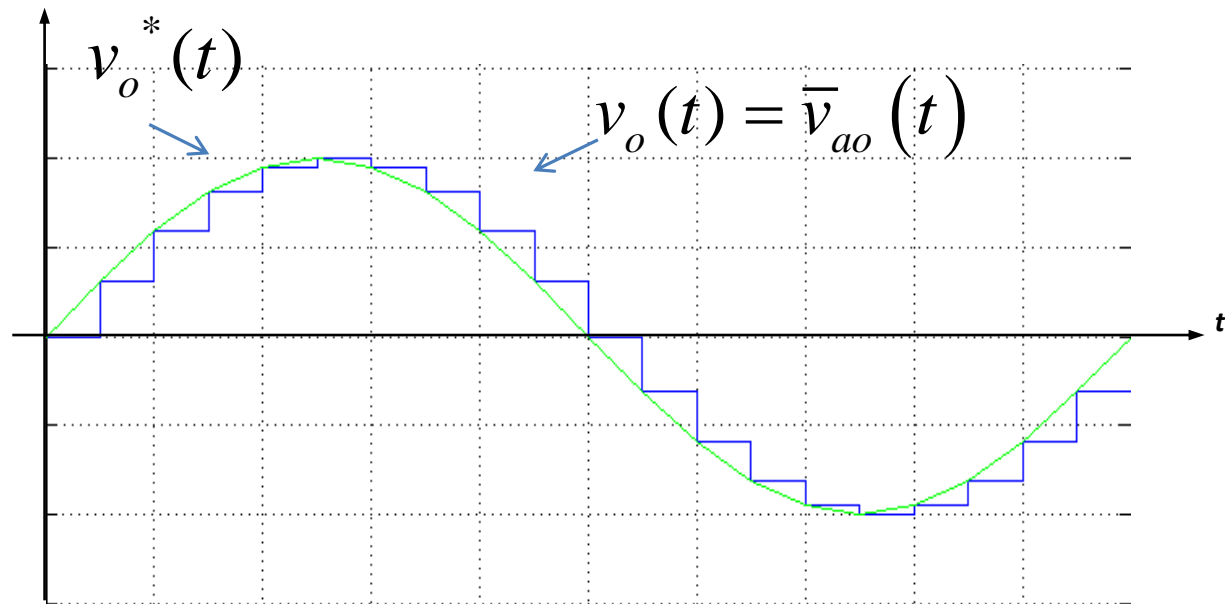
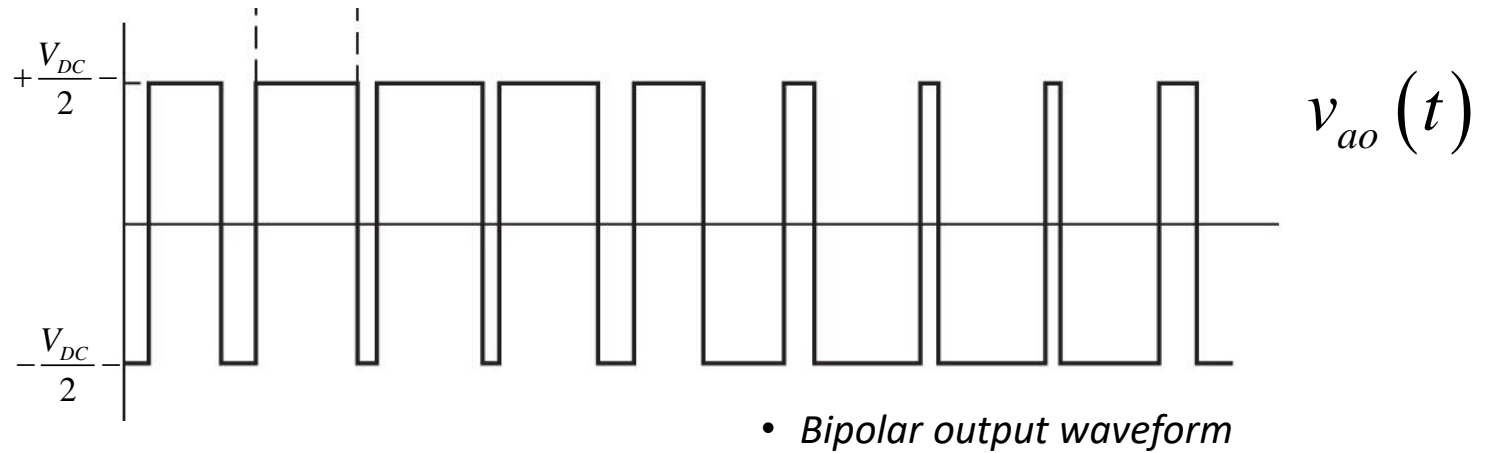
Real-World Pulse-Width Modulation with Embedded System



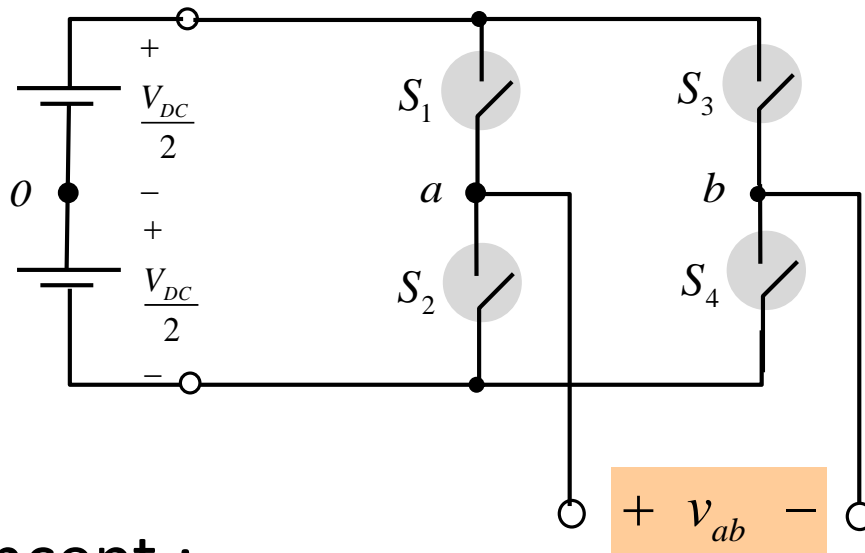
Switch Realization



Half-Bridge Inverter : Output waveform



Full-Bridge Inverter



Concept :

$$v_o^*(t) = v_{ab}^*(t) = V_m^* \sin(2\pi f^* t + \phi^*)$$

$$V_m^* \leq V_{DC}$$

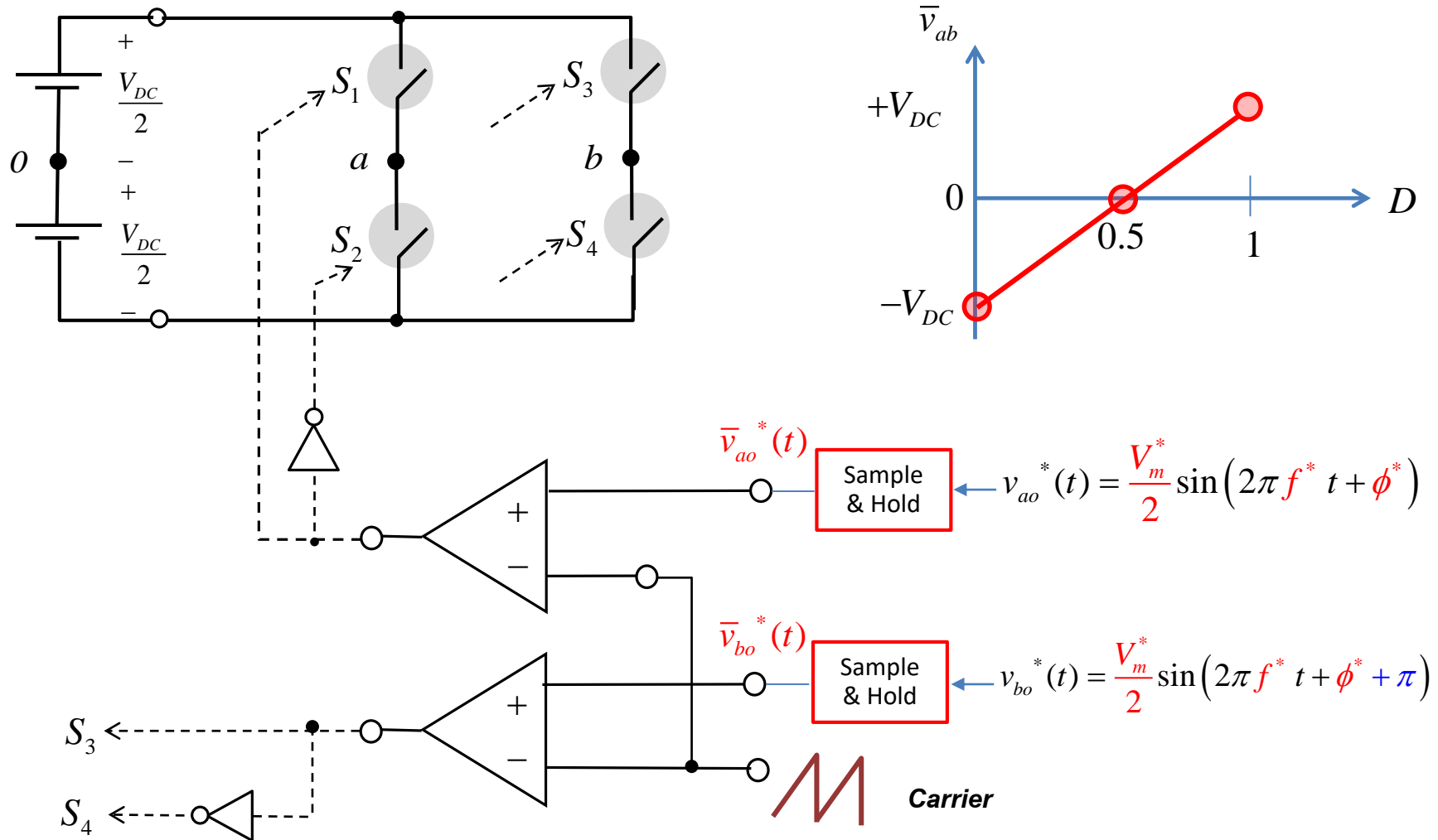
- Utilize the whole DC Bus Voltage: the amplitude of AC voltage can be up to DC bus voltage V_{DC} !!

$$v_{ao}^*(t) = \frac{V_m^*}{2} \sin(2\pi f^* t + \phi^*)$$

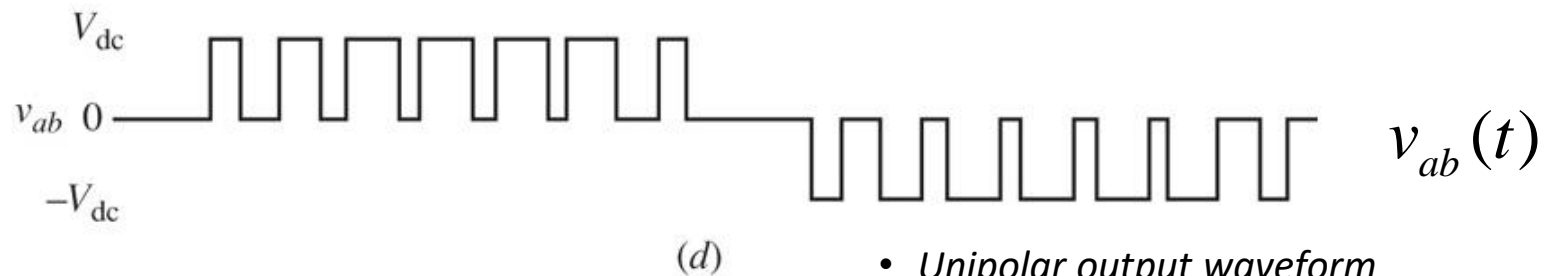
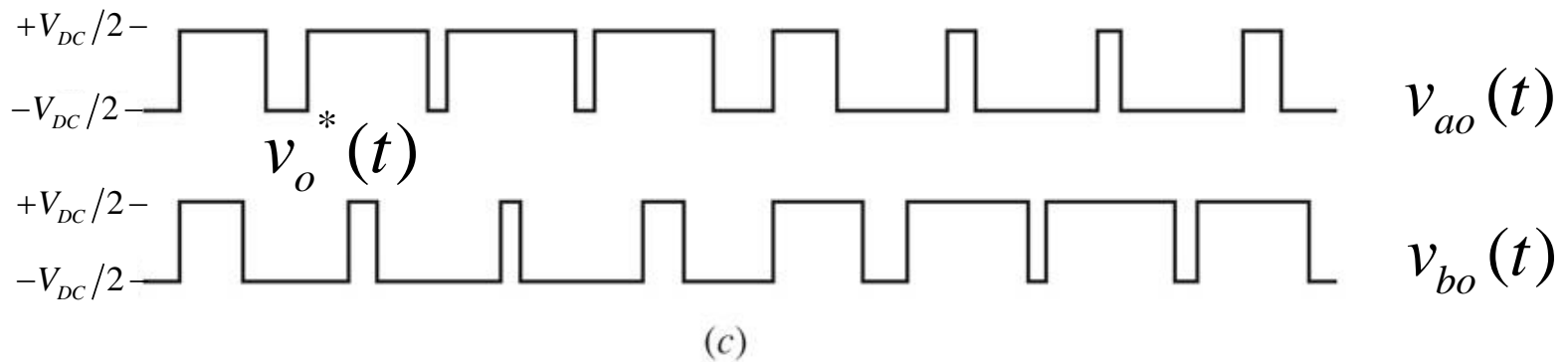
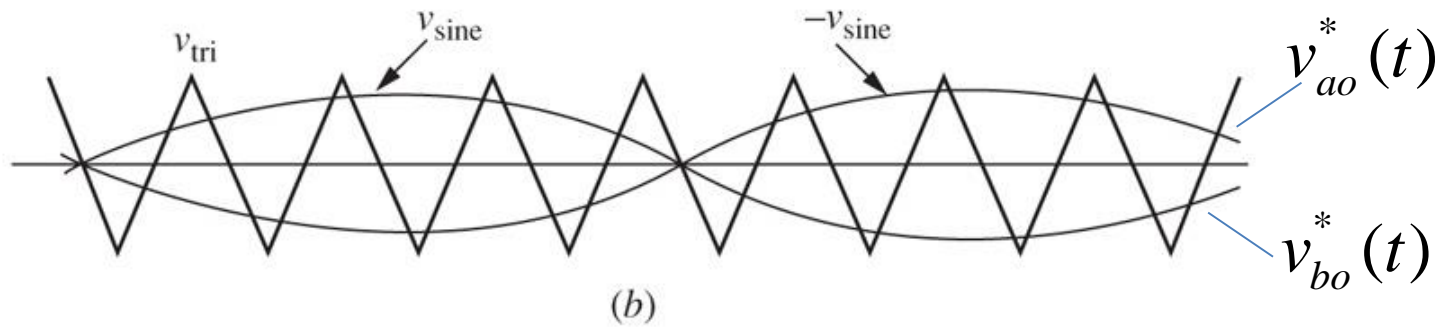
$$v_{bo}^*(t) = \frac{V_m^*}{2} \sin(2\pi f^* t + \phi^* + \pi)$$

- There are 2 ref. voltages which are out of phase.

Full-Bridge Inverter : Pulse-Width Modulation

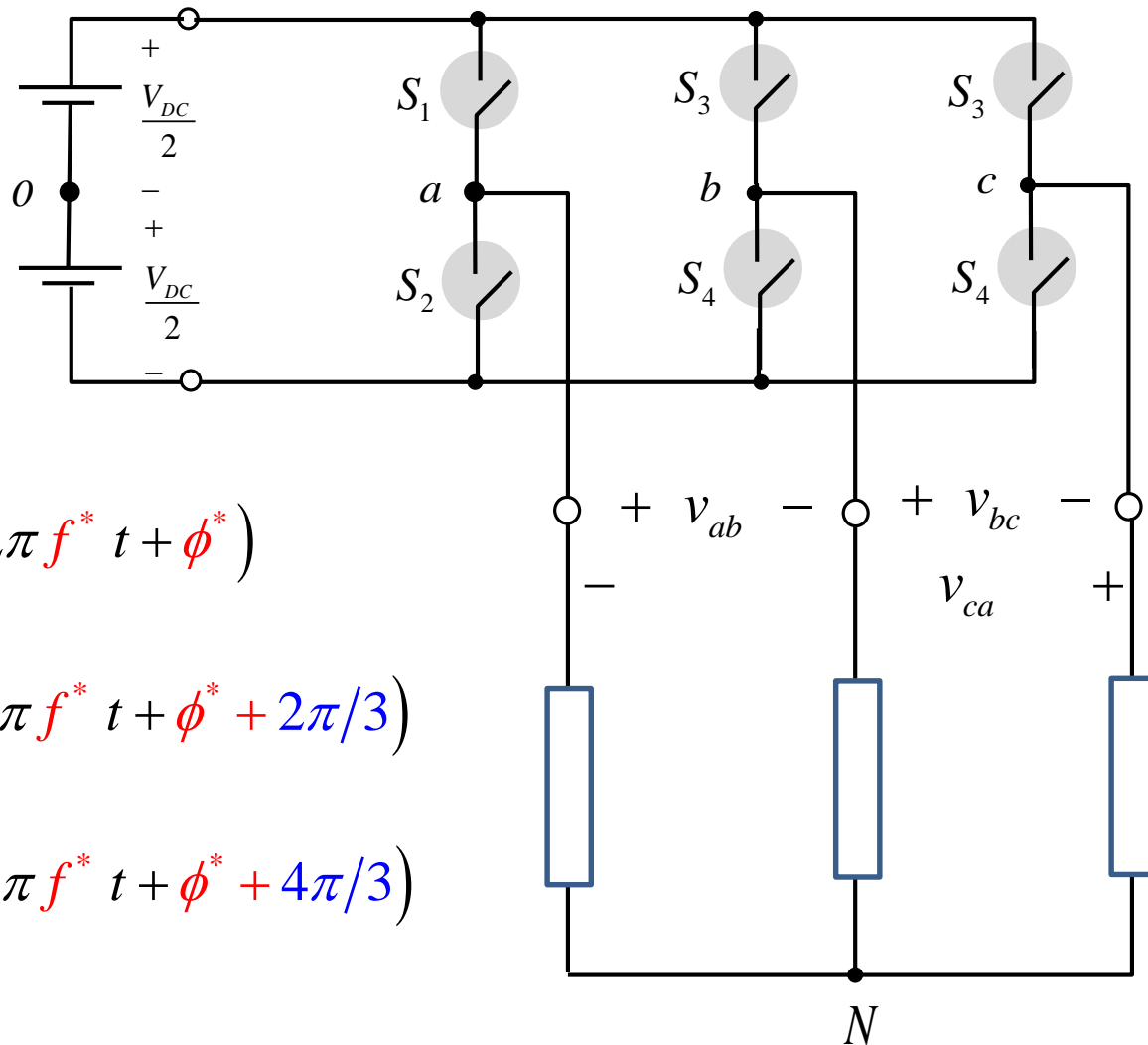


Full-Bridge Inverter : Output waveform



• Unipolar output waveform

3-Phase Inverter



Assume $v_{No} = 0$

$$v_{ao}^*(t) = V_{mp}^* \sin(2\pi f^* t + \phi^*)$$

$$v_{bo}^*(t) = V_{mp}^* \sin(2\pi f^* t + \phi^* + 2\pi/3)$$

$$v_{co}^*(t) = V_{mp}^* \sin(2\pi f^* t + \phi^* + 4\pi/3)$$

$$V_{mp}^* = V_{mL-L}^* / \sqrt{3}$$

3-Phase Inverter : Output waveform

