

INSTRUMENTAL-VARIABLE ESTIMATION OF GRAVITY EQUATIONS

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Abstract

We develop a theory-consistent approach to estimate cross-sectional gravity equations that accommodates the endogeneity of policy variables. We estimate models from five cross-sections in which the policy decision of interest is the engagement in a free trade agreement. An instrumental variable is constructed based on the transitivity observed in the formation of trade agreements. Our point estimate of the average impact of a free trade agreement (not taking into account estimation noise) increases over the sampling period, starting at 61% and ending with a 117% increase in bilateral trade volume. Not correcting for endogeneity yields stable but considerably smaller numbers.

JEL Classification: C26, F14

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1 Introduction

The gravity equation has a long history. While its origins can be traced back to [Tinbergen \(1962\)](#), the work of [Eaton and Kortum \(2002\)](#) and [Anderson and van Wincoop \(2003\)](#) has provided the gravity model with micro-foundations, establishing its place as the workhorse method for the analysis of bilateral trade patterns. The recent literature has made great strides towards credible estimation of the gravity equation; see [Head and Mayer \(2014\)](#) for a survey. The preferred specification features importer and exporter fixed effects to control for third-country effects through multilateral resistance terms ([Anderson 1979](#), [Anderson and van Wincoop 2003](#), [Redding and Venables 2004](#)) and is estimated in levels rather than in log-linearized form to deal with empirically-relevant issues such as the existence of zero trade flows between countries and conditional heteroskedasticity (see [Santos Silva and Tenreyro 2006](#)).

An important issue that arises when taking this preferred model to the data is how to handle the (potential) endogeneity of policy variables, such as membership of a currency union or participation in preferential trade agreements (see, e.g., [Rose 2000](#) and [Baier and Bergstrand 2004, 2007](#) for discussion). Indeed, the data suggest that countries take such decisions (at least partially) in response to the size of existing trade flows ([Santos Silva and Tenreyro 2010](#), p. 59; [Head and Mayer 2014](#), p. 162). The resulting reverse causality would invalidate the estimates of the model parameters as well as the consequent policy experiments and welfare calculations. While the literature has long since recognized this problem (see, e.g., [Rose 2004](#) for an early acknowledgement), coming up with a satisfactory solution has proven difficult.

The profession has favored an approach that exploits time-series variation in the form of panel data ([Baier and Bergstrand 2007](#), [Glick and Rose 2016](#)). Such an approach may not be satisfactory for the following reasons. First, the existing micro-foundations for the gravity model apply to cross-sectional data and are questionable bases for panel data ([Head and Mayer, 2014](#), p. 189). Second, relying solely on time-series variation rules out the possibility to estimate distance elasticities, border effects, and the impact of other determinants of

trade that are fixed across time. Third, estimation from short panel data leads to estimators that are asymptotically biased (Weidner and Zylkin, 2019). Consequently, the hypothesis tests and confidence intervals reported are invalid. Fourth, if current policy variables react to existing trade flows, the policy variables are not (strictly) exogenous. This renders any fixed-effect estimator inconsistent.

An alternative to relying on panel data would be to resort to an instrumental-variable approach. Egger, Larch, Staub and Winkelmann (2011) have taken a full-information view, simultaneously estimating the gravity equation together with an explicit parametrization of the mechanism that underlies trade policy decisions.¹ Unfortunately, the trade literature provides little guidance on what such an auxiliary specification should look like. In an event, it requires very strong parametric assumptions. Several of these are non-refutable and appear to be in conflict with some stylized facts, such as the (conditional) heteroskedasticity of trade flows (Santos Silva and Tenreyro, 2006), for example. Furthermore, although consistent (under the assumption of correct specification), the parameter estimates in both equations are again asymptotically biased, invalidating any inferential statements on the impact of the policy variables that is based on them.

Here we present a limited-information approach to instrumental-variable estimation of the gravity equation. Our strategy is to construct a set of orthogonality conditions that simultaneously difference-out the importer and exporter fixed effects and control for the endogeneity of policy variables. It allows to remain agnostic about how currency unions or preferential trade agreements are formed and is fully compatible with the theoretical foundations underlying the gravity equation. (It nonetheless fully covers the specification postulated in Egger, Larch, Staub and Winkelmann 2011 as well as many generalizations of it.) In this sense, our approach is like two-stage least squares, although it is designed for the model in levels, which is nonlinear. We note that the existence of orthogonality conditions in this setting is not immediate, as it is well known that dealing with endogeneity is difficult

¹There is earlier work on instrumental-variable estimation of the gravity equation; see Rose (2000) and Barro and Tenreyro (2007), for example. However, these analyses are all based on log-linearized models of trade and do not account for multilateral resistance.

in nonlinear models, even without the presence of fixed effects ([Blundell and Powell, 2003](#)). We use our moment conditions to construct an estimator that can be understood to be an instrumental-variable generalization of [Jochmans \(2017\)](#) (see also [Charbonneau 2013](#) for related work in the exogenous case). We remark that, while an instrumental-variable version of the popular pseudo-Poisson estimator is available for exponential models ([Mullahy 1997](#), [Windmeijer and Santos Silva 1997](#)), this estimator is not designed for situations in which fixed effects (here, multilateral resistance terms) are present. Indeed, the robustness of the pseudo-Poisson estimator to the inclusion of such effects does not carry over to its instrumental-variable counterpart. Whether this estimator can be bias-corrected to rectify the problem has not been investigated.

We apply our estimator to well-known trade data from [Helpman, Melitz and Rubinstein \(2008\)](#). The variable feared to be endogenous in our specification is a dummy for the presence of a free trade agreement. There is precedent in the search for suitable instruments, although with relatively little success. [Head and Mayer \(2014, p. 162\)](#) note that most variables that plausibly cause trade agreements also appear in the trade equation itself. [Rose \(2004, p. 110\)](#) experimented with measures of democracy and polity, and measures of freedom, civil rights and political rights, but reported that these are only quite weak instruments. In our quest for instruments we recognize that decisions on bilateral trade policy are not made in isolation. We find high levels of transitivity in the formation of free trade agreements in our data. Moreover, trade within a country pair is much more likely to be subject to a free trade agreement if the respective countries have such an agreement with one or more common third-parties. Similar findings are reported in [Egger and Larch \(2008\)](#) and [Chen and Joshi \(2010\)](#). This shows that the number of common free-trade partners is a relevant instrument.

The argument underlying the validity of this variable as an instrument is that free trade agreements concluded with third-party countries affect bilateral trade flows only through the importer and exporter effects. These effects absorb both all country-specific variables and multilateral resistance. Such a mechanism is fully consistent with the theory underlying the cross-sectional gravity model ([Anderson and van Wincoop 2003](#), [Anderson and Yotov](#)

2010), where the multilateral resistance terms capture any third-party effects. Hence, the validity of our instrument is theoretically grounded. Dispensing with its validity would amount to rejecting the foundations of the gravity equation that underlies the workhorse specification in a literature now spanning more than a decade. A difficulty for (static) models of bilateral trade is how to deal with multilateral trade agreements or customs unions. In our empirical setup this translates into a possible violation of instrument validity, as we discuss in more detail below. Allowing for free trade agreements to be a result of a simultaneous process is likely to lead to a loss of point identification of the parameters of the gravity equation.

The data of Helpman, Melitz and Rubinstein (2008) cover multiple years; we estimate static gravity equations for each of them. Point estimates of the distance elasticity and border effect take on conventional values. Our estimate of the average impact of a free trade agreement (not taking into account standard errors) increases over time, being 61% in the initial year and 116% in the last year. In contrast, not correcting for endogeneity yields estimates of around 25% that do not change much over time. Our larger point estimates on the impact of increased economic integration on trade flows are in line with earlier work such as Baier and Bergstrand (2007), for example. We do note that our estimates come with substantial estimation uncertainty. This is the price to pay for properly dealing with multilateral resistance terms and endogeneity. Given that identification has been achieved through our instrumental variable we can test whether free trade agreements can be considered endogenous in a statistical sense. We find increasingly strong evidence for this as we move toward the end of the sampling period, with the p-value for the null of exogeneity clocking off at 0.06.

2 Specification and approach

We have cross-sectional data on bilateral trade between n countries. Let $t_{i,j} \geq 0$ denote the trade flow from exporter i to importer j and let $\mathbf{x}_{i,j}$ be a p -vector of covariates that capture trade costs between i and j . These covariates invariably include measures such

a geographical distance, common border and language dummies, and an indicator of the existence of preferential trade agreements.

Model for trade flows The modern specification of the gravity equation as pioneered by [Anderson and van Wincoop \(2003\)](#) states that

$$t_{i,j} = \exp(\alpha_{i,n} + \gamma_{j,n} + \mathbf{x}_{i,j}^\top \boldsymbol{\beta}) \varepsilon_{i,j}, \quad (2.1)$$

where $\alpha_{i,n}$ and $\gamma_{j,n}$ are, respectively, exporter and importer effects and $\varepsilon_{i,j}$ is an unobserved error term. The importer and exporter effects are explicitly indexed by the total number of countries in the data, n , to highlight that they capture multilateral resistance and depend on the country's interaction with third-party trading partners. The primary object of interest in (2.1) is the vector $\boldsymbol{\beta}$. In the structural gravity model the $\alpha_{i,n}$ and $\gamma_{j,n}$ may be of interest in their own right. Estimates of these that satisfy such a model's equilibrium constraints can be obtained in the usual manner ([Faily, 2015](#)) once an estimator of $\boldsymbol{\beta}$ has been constructed.²

The standard approach to estimation of the gravity equation is validated under the assumptions that

$$\overline{\mathbb{E}}(\varepsilon_{i,j} | \mathbf{x}_{1,2}, \dots, \mathbf{x}_{n,n-1}) = 1, \quad (2.2)$$

and that the errors are independent, conditional on all regressors and fixed effects. Here and later, we use the shorthand notation $\overline{\mathbb{E}}$ to indicate that the expectation in question is taken conditional on the set of importer and exporter effects. These two assumptions underlie the use of the pseudo-Poisson estimator ([Gouriéroux, Monfort and Trognon, 1984](#)) advocated by [Santos Silva and Tenreyro \(2006\)](#).³ While the identifying restriction (2.2)

²With $\hat{\boldsymbol{\beta}}$ a consistent estimator of $\boldsymbol{\beta}$, the $\alpha_{i,n}$ and $\gamma_{j,n}$ (subject to the usual normalization) can be estimated via a pseudo-Poisson regression of normalized trade flows $t_{i,j} / \exp(\mathbf{x}_{i,j}^\top \hat{\boldsymbol{\beta}})$ on a set of importer and exporter dummies. When $\hat{\boldsymbol{\beta}}$ is n -consistent the usual (sandwich-type form) standard errors on these effects are valid in large samples.

³The conditional-independence assumption is often left implicit but is an important condition (see also our Footnote 4 below). The same assumptions are also implicit in the use of the pseudo-Poisson estimator when applied to panel data; see [Weidner and Zylkin \(2019, Appendix A\)](#) for the most general setting available.

appears plausible for geographical characteristics that facilitate trade—such as distance or sharing a common border—it is difficult to maintain for most policy variables, such as the establishment of preferential trade agreements.

Orthogonality conditions An instrumental-variable version of (2.2) would take the form

$$\overline{\mathbb{E}}(\varepsilon_{i,j} | \mathbf{z}_{1,2}, \dots, \mathbf{z}_{n,n-1}) = 1, \quad (2.3)$$

where $\mathbf{z}_{i,j}$ is a q_1 -vector of instrumental variables. However, an estimator based on it has not been proposed. We do so here.

To see how (2.3) can be used to construct an estimator of β we introduce the shorthand

$$u_{i,j}(\beta) := \frac{t_{i,j}}{\exp(\mathbf{x}_{i,j}^\top \beta)},$$

which is known up to β . Consider two exporter-importer pairs, (i, j) and (i', j') . Equation (2.3), together with the absence of serial correlation in the errors, immediately implies that

$$\overline{\mathbb{E}}(u_{i,j}(\beta) u_{i',j'}(\beta) | \mathbf{z}_{1,2}, \dots, \mathbf{z}_{n,n-1}) = \exp(\alpha_{i,n} + \alpha_{i',n} + \gamma_{j,n} + \gamma_{j',n}).$$

Next consider the pairs (i, j') and (i', j) , which involve the same countries but concern different trade flows. Then, again,

$$\overline{\mathbb{E}}(u_{i,j'}(\beta) u_{i',j}(\beta) | \mathbf{z}_{1,2}, \dots, \mathbf{z}_{n,n-1}) = \exp(\alpha_{i,n} + \alpha_{i',n} + \gamma_{j,n} + \gamma_{j',n}).$$

The right-hand side in each of these equations is identical. Consequently, taking differences and iterating expectations yields

$$\mathbb{E}(u_{i,j}(\beta) u_{i',j'}(\beta) - u_{i,j'}(\beta) u_{i',j}(\beta) | \mathbf{z}_{1,2}, \dots, \mathbf{z}_{n,n-1}) = 0.$$

This conditional moment condition implies unconditional moment conditions of the form

$$\mathbb{E}(\tilde{\mathbf{z}}_{i,j,i',j'} \{u_{i,j}(\beta) u_{i',j'}(\beta) - u_{i,j'}(\beta) u_{i',j}(\beta)\}) = \mathbf{0}, \quad (2.4)$$

where $\tilde{z}_{i,j,i',j'}$ is any q_2 -vector of transformations of the original q_1 -vectors $z_{1,n}, \dots, z_{n,n-1}$, for example $\tilde{z}_{i,j,i',j'} = z_{i,j}$.⁴ Equation (2.4) is an orthogonality condition in the same spirit as the usual normal equations for two-stage least squares, but it accounts for the nonlinearity of the model as well as for the presence of fixed effects for both importer and exporter. A generalized method-of-moments (GMM) estimator based on (2.4) can be constructed via a generalization of the approach in Jochmans (2017) (see Charbonneau 2013 for a special case of this estimator which, however, does not generalize to a setting with instrumental variables). To maintain focus we relegate details on the estimator to a later section.

Related work Our limited-information view is to be contrasted with the full-information route of Egger, Larch, Staub and Winkelmann (2011). Their approach is to endogenise the decision to establish a preferential trade agreement by complementing (2.1) with an explicit binary-choice model for it. A tight parametrization of the unobservables allows to estimate this system in two steps. An obvious limitation of this control-function approach is that it requires the whole system of equations to be correctly specified. This is problematic as, for example, their assumptions are at odds with the stylized fact that trade data are (conditionally) heteroskedastic (Santos Silva and Tenreyro, 2006). In any event, even under correct specification, the presence of fixed effects implies that the estimators implemented by Egger, Larch, Staub and Winkelmann (2011) are asymptotically biased, so that any inference procedure based on them is incorrect.⁵

⁴The derivation of our moment conditions continues to go through when the errors are correlated at the importer and/or exporter level. The implied estimator remains consistent. It is, however, not clear how to obtain cluster-robust standard errors under this type of dependence. We stress that the use of such clustered standard errors for pseudo-Poisson, although not uncommon in practice, is not theoretically grounded. Moreover, cluster-robust variance estimators as popularized by Cameron, Gelbach and Miller (2011) have only been justified recently (Davezies, D'Haultfoeuille and Guyonvarch, 2018). However, the conditions under which these results are derived rule out the gravity model.

⁵The problem stems from the presence of fixed effects in the first-stage probit specification. The probit estimator is used to construct an auxiliary regressor for the second-stage pseudo-Poisson estimator but is asymptotically biased. The bias carries over to the second-stage estimator. The same issue would

Our approach differs in two main aspects. First, the moment conditions in (2.4) do not require us to fully specify a model for how policy variables are determined. While such models can, of course, be useful to provide guidance in the selection of appropriate instrumental variables, the properties of our estimator do not depend on the precise form of the working model. The working model also does not have to be estimated at any stage. This is a substantial advantage of the limited-information approach, not in the least because the presence of fixed effects in any specification of such a model would create considerable complications. Furthermore, we are not aware of structural econometric models of the formation of currency unions or free trade agreements in the trade literature that could serve as an input here. Nonetheless, our setup is compatible with the network-formation models that have been analysed in more generic settings (see, e.g., [de Paula 2019](#) for a survey), of which the setup of [Egger, Larch, Staub and Winkelmann \(2011\)](#) is a special case.

Second, our moments also do not restrict the (conditional) distribution of the error term, allowing for heteroskedasticity of arbitrary form, for example. Furthermore, (2.4) is free of importer and exporter effects; they have effectively been differenced-out. Moreover, our orthogonality conditions separate estimation of the fixed effects from inference on the parameter of interest. This does not only eliminate the need to solve a high-dimensional optimization problem. It also prevents the associated standard errors from suffering from a large bias such as the one that is observed in those of the pseudo-Poisson estimator ([Jochmans 2017](#), [Pfaffermayer 2019](#)). This bias is a consequence of the estimation noise in the importer and exporter effects. It is usually negative, translating into overoptimistic estimates of statistical precision, on average.

occur if the second-stage would be performed by least squares on a log-linearized gravity equation. See [Fernández-Val and Vella \(2011\)](#) and [Dhaene and Jochmans \(2015\)](#) for further discussion and illustrations.

Table I: Descriptive statistics of regressors (constant across all years)

variable	description	mean	std	min	max
distance	log distance between capitals (in km)	4.177	0.781	-0.151	5.661
colony	former colonial tie dummy	0.100	0.098	0	1
border	common border dummy	0.017	0.131	0	1
language	common language dummy	0.286	0.452	0	1

3 Data, instruments, and results

Bilateral-trade data The data we use are taken from [Helpman, Melitz and Rubinstein \(2008\)](#). They are panel data on trade between 158 countries. We will estimate gravity equations for the years 1985–1989, but will use data going back to 1981.

The regressors that we will use are standard. They are (i) ‘distance’, the log distance between the capitals of the respective countries (in kilometers); (ii) ‘colony’, a dummy indicating whether one of the countries in the dyad ever colonized the other; (iii) ‘border’, a dummy representing the existence of a common physical border between both countries; (iv) ‘language’, a dummy capturing if both countries share a common language; (v) ‘fta’, a dummy measuring whether the countries belong to a common regional trade agreement. Table I contains descriptive statistics for all but the last regressor. Note that these variables do not change over time.

The percentage of trade flows that benefit from a preferential trade agreement on the other hand has steadily increased over the sampling period. While only 0.46% of all trade flows were covered by an agreement in 1981, this number reached .61% by 1989. We refer to [Helpman, Melitz and Rubinstein \(2008, Appendix I\)](#) for additional details on the data and on their construction.

Instrument selection Although the literature has recognized the endogeneity of policy variables in the gravity equation, finding good instruments has proven difficult. On the one hand, most variables that plausibly cause trade agreements also appear in the trade

equation itself (Head and Mayer, 2014, p. 162). On the other hand, as noted by Rose (2004, p. 110) variables such as measures of democracy and polity, or measures of freedom, civil rights and political rights are typically only weakly-correlated with the policy variables that are feared to be endogenous. Egger, Larch, Staub and Winkelmann (2011) search for exogenous variation in the determination of free trade agreements by using dummies for colonial history and for whether or not the countries in question used to be part of the same country.

The variables just mentioned are all bilateral in nature. They do not take into account the relationship of the exporter and importer with their other trading partners. However, networks typically feature a high degree of transitivity (see, e.g., Newman 2010, pp. 198–204 for a definition and discussion). In our data, the probability that a randomly-drawn exporter-importer pair has established a free trade agreement ranges from 0.46% to 0.6%. On the other hand, the probability that this is the case given that both have a free trade agreement with at least one common third country is around 80% in all the years. This observation suggests that the number of common free trade agreement partners—‘common fta’, say—is a relevant instrument.⁶ The literature on the formation of free trade agreements has acknowledged its strong transitivity; see Egger and Larch (2008), Chen and Joshi (2010), Baldwin and Jaimovich (2012), and Baier, Bergstrand and Mariutto (2014). On the other hand, the potential use of this transitivity to construct an instrumental variable appears to have gone unexploited in our context.

To control for importer and exporter effects our moment conditions in (2.4) are based on comparisons of (normalized) bilateral trade flows, $u_{i,j}(\beta)$, to trade flows involving a different

⁶To give another measure of co-movement, the correlation between ‘fta’ and ‘common fta’ is always above .80. This large value is to be contrasted with the very small correlations that are found for other potential instrumental variables. In our data, for example, the ‘religion’ variable used by Helpman, Melitz and Rubinstein (2008) (albeit for different purposes) has a correlation with ‘fta’ ranging between 0.037 and 0.051. Calculations for measures of political stability in the data of Egger, Larch, Staub and Winkelmann (2011) gave similarly low correlations. We remark that all these numbers are unconditional measures of co-movement and are only illustrative for instrument relevance. We are not aware of a formal measure of instrument strength in nonlinear models.

exporter (i') and a different importer (j'). Consequently, we construct our instrument for ‘fta’ using a cross-fit procedure, as

$$\sum_{k \neq i', j'} \text{‘fta’}_{i,k} \text{‘fta’}_{k,j},$$

where the reference third countries i' and j' are excluded from the sum.

Identification hinges on the assumption that the instrument is in itself not driving bilateral trade flows (given the regressors and fixed effects). In our case, this means that the fact that the exporter or importer in a given country-pair have a free trade agreement with a third country affects their trade volume only through their multilateral resistance terms. While any exclusion restriction can be called into question it is important to stress that ours is supported by the theory from which our empirical specification is derived. For example, the original purpose of multilateral resistance as in [Anderson and van Wincoop \(2003\)](#) was to let bilateral trade flows adjust to a change in trade-facilitating conditions with third countries, such as the signing of a free trade agreement. Such adjustment does not impair the validity of our instrument. To give another example, when a country is deciding whether or not to conduct a free trade agreement with another country it would be reasonable for it to take into account the bilateral trade barriers that their potential partner has with any other third country. Again, this type of correlation is accounted for by the presence of importer and exporter effects. These examples also show that a case for an exclusion restriction would be much harder to make in a model that does not feature fixed effects, highlighting again the usefulness of pursuing valid exclusion restrictions in a fully theory-consistent model.

Given that we have access to multiple years of data we will augment our instrument with its lags. This is useful in gaining efficiency, and so in obtaining more precise coefficient estimates. It also leads to overidentification and thus allows us to construct a Sargan statistic to test our specification. This statistic can be used to test the validity of our moment conditions. Although we hasten to stress that the interpretation of such a test should be done with care (see, e.g., [Newey 1985](#) or [Guggenberger 2012](#)), we find below that this test is generally supportive of our exclusion restriction and, with it, of multilateral

resistance as a way to capture third-country effects.

Finally we also note that, given the availability of panel data, an alternative route to identification that has found applicability elsewhere would be to instrument ‘fta’ by its own first (and/or further) lag. Here, a case for credible identification along this route appears more difficult to make, and a theoretical model that can be used for guidance seems absent. We calculated incremental Sargan tests for the validity of the first lag (not reported here) and generally found that these tests do not support the validity of lagged levels of ‘fta’ as an instrument in the current context.

Limitations One potential threat to identification of the effect of free trade agreements on trade flows comes from the fact that some such agreements are not bilateral in nature but, rather, the outcome of a joint decision of multiple countries (for example, the European Union). To see this, consider the situation where free trade agreements are the outcome of a simultaneous game. In such a case all decisions can in principle depend on (both the observed and unobserved) characteristics of all the countries. Hence, if ‘fta’_{*i,j*} is endogenous, it will not only be (conditionally) correlated with $\varepsilon_{i,j}$ but also with $\varepsilon_{i',j'}$ for all (i', j') , invalidating the exclusion restriction on our instrument. This problem is not unique to our approach. It is implicitly ruled out in the standard specification of the gravity equation (and here) as (conditional) cross-sectional independence in the errors is assumed away while the violation would translate into the presence of such dependence between all $\varepsilon_{i,j}$. In fact, it is not clear whether a consistent estimator can be constructed at all in the simultaneous-game setting as just described. If, on the other extreme, a country would have little to no influence in multilateral negotiations, ‘fta’ would effectively be exogenous for that country. Our understanding of how multilateral trade agreements come about is limited and so it is difficult to see what type of additional restrictions could be used here to gain identification power. Consequently, we leave the issue of multilateral agreements to future work. [Bagwell, Staiger and Yurukoglu \(2019\)](#) document some stylized facts in negotiation data from GATT.

Note that a specification of a model of trade agreement formation that features general

forms of transitivity would necessarily be incomplete, in the sense that it would feature multiple equilibria. This implies that the parameters of any such model will often not be point identified (de Paula, 2013). Dealing with such econometric difficulties in the current context appears to be extremely complicated. Neither has it been pursued in the simultaneous-equation framework of Egger, Larch, Staub and Winkelmann (2011) or, indeed, even in much simpler settings.

On the other hand, our approach is compatible with other models of network formation, such as the one of Egger, Larch, Staub and Winkelmann (2011) and others as surveyed, for example, by de Paula (2019). Such models allow (among other things) for decisions on trade agreements to be driven by country fixed effects and pair-specific covariates. These models can generate strong dependence in decision outcomes and can accommodate clustering patterns of trade agreements such as those observed in our data. This would satisfy our exclusion restriction.

Estimation results Table II contains coefficient estimates for the gravity equation in (2.1) estimated by pseudo-Poisson (PMLE) and our instrumental-variable estimator (GMM). Standard errors are provided in parentheses below the point estimates and p-values for the null that the coefficient in question is zero (against a two-sided alternative) are reported in brackets. We find distance elasticities around $-.65$. The existence of colonial ties and sharing a physical border both are economically and statistically significant factors of trade flows. The point estimates for these effects obtained through GMM are somewhat larger than those delivered by PMLE, but the difference is small relative to the standard error. Sharing a common language does not have a significant impact on trade in any of the years. The magnitudes of all these coefficients are in line with those obtained elsewhere in the literature.

The results for PMLE and GMM differ most in their estimate of the importance of free trade agreements. While the PMLE coefficient estimates are small and fairly constant over time—with an average of .240 and a standard deviation of .029— instrumentation gives coefficient estimates that are both larger and display a steady upward trend over time,

with an average of .642 and a standard deviation of .110. This is summarized visually in Figure I. The left plot gives the coefficient estimates while the right plot contains the corresponding average marginal effect of a free trade agreement. PMLE (x) estimates the latter from 21% in 1985 to 31% in 1989, corresponding to a 10 pp. increase over five years. The instrumental-variable estimates (*) are always larger, being 61% in 1985 and 117% in 1989, which is an almost 60 pp. increase over the sampling period. There is, of course, a standard error on our point estimates. The (pointwise) confidence interval do not rule out that the effect has remained constant or, indeed, has decreases over time. The standard errors on GMM are larger than on those obtained by PMLE, both because of the instrumentation and the fact that PMLE standard errors tend to be much too small.⁷ Dealing with both endogeneity and two-way fixed effects is quite demanding on the data, even more so in highly-unbalanced regressor designs, and reasonable standard errors should reflect this.

The lower part of Table II provide the values and associated p-values (in brackets) of two Sargan statistics. Such statistics are a natural by-product of our estimation procedure. The first Sargan statistic, ‘exogeneity’, can be used to assess whether there is strong statistical evidence that ‘fta’ is endogenous.⁸ The p-value decreases over the sampling period, clocking off at .065, and thus providing less credibility for the null of exogeneity. The second Sargan statistic (‘validity’) can be used to shed light on the null that our instruments are valid. We do not find strong support against the validity of our instrumental variable in any of the cross sections. An implication of this result is that our findings support the structural gravity model where third-country effects are captured via importer and exporter effects. Of course, as usual, this interpretation of any of these Sargan tests is conditional on having achieved identification.

⁷For the average marginal effect the larger standard error is also mechanical, as it is partly due to the increase in the estimated coefficient. Indeed, the effect is estimated as $(e^{\hat{\beta}} - 1)$, with $\hat{\beta}$ the coefficient estimate on ‘fta’. Its (delta-method) standard error is $e^{\hat{\beta}} \times \text{se}(\hat{\beta})$. This increases with $\hat{\beta}$ even if the standard error on $\hat{\beta}$ remains the same.

⁸The validity of such tests stems from (4.6) below. See, for example Hayashi (2000, Section 3.6) for details and examples of such statistics.

Table II: Estimation results

	PMLE					GMM				
	1985	1986	1987	1988	1989	1985	1986	1987	1988	1989
distance	-.670	-.640	-.652	-.686	-.664	-.688	-.630	-.633	-.650	-.622
	(.044)	(.043)	(.041)	(.036)	(.035)	(.058)	(.053)	(.050)	(.048)	(.049)
	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]
colony	.612	.532	.478	.448	.463	.745	.592	.550	.493	.547
	(.115)	(.106)	(.103)	(.098)	(.098)	(.180)	(.159)	(.152)	(.151)	(.151)
	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.001]	[.000]
border	.745	.771	.747	.625	.621	.977	1.027	1.008	.771	.689
	(.113)	(.112)	(.103)	(.075)	(.076)	(.193)	(.192)	(.184)	(.131)	(.178)
	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]	[.000]
language	-.110	-.061	-.056	-.066	-.055	-.111	-.027	-.029	-.019	.009
	(.092)	(.090)	(.087)	(.088)	(.087)	(.157)	(.152)	(.141)	(.130)	(.129)
	[.231]	[.497]	[.521]	[.457]	[.524]	[.480]	[.859]	[.838]	[.883]	[.945]
fta	.193	.237	.244	.256	.270	.479	.608	.655	.691	.778
	(.088)	(.087)	(.084)	(.077)	(.066)	(.318)	(.320)	(.295)	(.238)	(.202)
	[.000]	[.006]	[.004]	[.001]	[.000]	[.132]	[.058]	[.026]	[.004]	[.000]
exogeneity	—	—	—	—	—	.204	1.077	1.546	2.058	3.405
						[.652]	[.299]	[.214]	[.151]	[.065]
validity	—	—	—	—	—	6.743	7.730	7.742	8.878	9.712
						[.150]	[.172]	[.258]	[.262]	[.286]

Table notes: Robust standard errors in parentheses. p-values in brackets. ‘validity’ is the value of the Sargan test statistic for the null that the instruments are valid. ‘exogeneity’ is the value of the Sargan test statistic for the null that ‘fta’ is exogenous. The instrumental-variable estimator uses all lags of our ‘common fta’ variable ranging back to 1981.

Figure I: The impact of ‘fta’ on trade flows

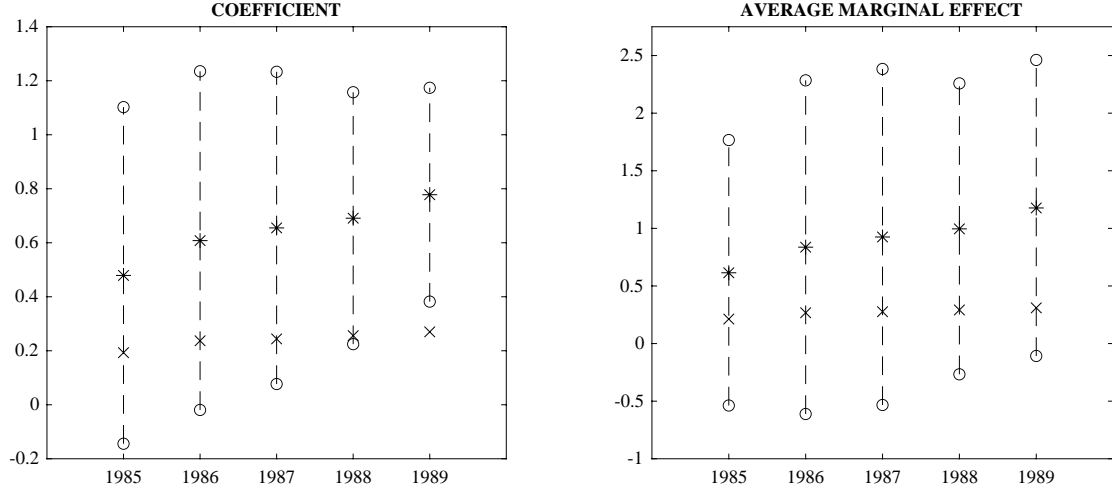


Figure notes: Point estimates (*) and 95% confidence intervals (— ◦) obtained by instrumental-variable estimation together with point estimates (x) obtained by pseudo-Poisson.

4 Estimator and Monte Carlo

Details on the estimator A sample counterpart to the left-hand side of (2.4) takes the form

$$\mathbf{s}_n(\mathbf{b}) := \sum_{i=1}^n \sum_{j \neq i} \sum_{i' \neq i, j} \sum_{j' \neq i, i', j} \tilde{\mathbf{z}}_{i,j,i',j'} \{u_{i,j}(\mathbf{b}) u_{i',j'}(\mathbf{b}) - u_{i,j'}(\mathbf{b}) u_{i',j}(\mathbf{b})\}, \quad (4.5)$$

where we assume without loss of generality that the summand is symmetric in i and i' as well as in j and j' . The optimal (two-step) GMM estimator based on this vector of sample moments is equal to

$$\hat{\boldsymbol{\beta}} := \arg \min_{\mathbf{b}} \mathbf{s}_n(\mathbf{b})^\top \hat{\mathbf{V}}_n^{-1} \mathbf{s}_n(\mathbf{b}),$$

where $\hat{\mathbf{V}}_n$ is an estimator of the asymptotic variance of $\mathbf{s}_n(\boldsymbol{\beta})$. To construct this matrix a preliminary estimator of $\boldsymbol{\beta}$ is needed. An intuitive choice is to use the GMM estimator $\hat{\boldsymbol{\beta}} := \arg \min_{\mathbf{b}} \mathbf{s}_n(\mathbf{b})^\top \mathbf{s}_n(\mathbf{b})$, i.e., the estimator that assigns the same weight to each moment condition. Without additional prior information this is a natural choice. Standard GMM theory (Hansen, 1982) implies that the large-sample behavior of $\hat{\boldsymbol{\beta}}$ does not depend on the first-step estimator used. With this auxiliary estimator at hand we construct the plug-in

estimator

$$\hat{\mathbf{V}}_n := \sum_{i=1}^n \sum_{j \neq i} \mathbf{v}_{i,j}(\hat{\boldsymbol{\beta}}) \mathbf{v}_{i,j}(\hat{\boldsymbol{\beta}})^\top,$$

where $\mathbf{v}_{i,j}(\mathbf{b})$ is defined as

$$\sum_{i' \neq i, j} \sum_{j' \neq i, i', j} \{(\tilde{\mathbf{z}}_{i,j,i',j'} + \tilde{\mathbf{z}}_{i',j',i,j}) - (\tilde{\mathbf{z}}_{i,j',i',j} + \tilde{\mathbf{z}}_{i',j,i,j'})\} \{u_{i,j}(\mathbf{b}) u_{i',j'}(\mathbf{b}) - u_{i,j'}(\mathbf{b}) u_{i',j}(\mathbf{b})\}.$$

The structure of $\hat{\mathbf{V}}_n$ is non-standard because the summands in $\mathbf{s}_n(\mathbf{b})$ are not independent. It is nonetheless straightforward to construct. We refer to [Jochmans \(2017\)](#) for details and discussion.

Under conventional regularity conditions our GMM estimator is asymptotically normal. An estimator of its covariance matrix is $\hat{\boldsymbol{\Omega}}_n := (\hat{\mathbf{Q}}_n^\top \hat{\mathbf{V}}_n^{-1} \hat{\mathbf{Q}}_n)^{-1} / n(n-1)$, where we denote by $\hat{\mathbf{Q}}_n$ the Jacobian matrix of the moment conditions at $\hat{\boldsymbol{\beta}}$ and $\hat{\mathbf{V}}_n$ is defined as $\hat{\mathbf{V}}_n$ but constructed using $\hat{\boldsymbol{\beta}}$ in stead of $\hat{\boldsymbol{\beta}}$. The square-root of the diagonal entries of $\hat{\boldsymbol{\Omega}}_n$ provide valid standard errors on $\hat{\boldsymbol{\beta}}$.

When we have more moments than parameters to estimate our model is overidentified and the criterion function evaluated at its minimizer satisfies

$$n(n-1) \mathbf{s}_n(\hat{\boldsymbol{\beta}})^\top \hat{\mathbf{V}}_n^{-1} \mathbf{s}_n(\hat{\boldsymbol{\beta}}) \stackrel{a}{\sim} \chi_{q-p}^2 \quad (4.6)$$

when all moments in (2.4) hold. Consequently, this quantity can be used to test the validity of (some or all of) the moment conditions in the usual way (see [Sargan 1958](#) and [Hansen 1982](#)).

Although the multiple sums in the empirical moments in (4.5) may suggest that our estimator is cumbersome to compute, this is not the case. Careful re-arrangement makes the evaluation of the criterion function straightforward in any matrix-based language. An efficient Stata[©] implementation of our procedure for settings where $\tilde{\mathbf{z}}_{i,j,i',j'} = \tilde{\mathbf{z}}_{i,j}$ is made available through `ssc`⁹.

⁹The package `ivgravity` can be installed from within Stata[©] by typing `ssc install ivgravity` in the command window.

Table III: Monte Carlo results for $n = 50$

ρ		mean	median	std	se	rej freq
-0.50	$\hat{\beta}_1$	-1.0011	-1.0008	0.0317	0.0331	0.0444
	$\hat{\beta}_2$	0.9829	0.9913	0.1796	0.1870	0.0354
	validity	—	—	—	—	0.0552
	exogeneity	—	—	—	—	0.9966
-0.25	$\hat{\beta}_1$	-1.0006	-1.0008	0.0300	0.0305	0.0478
	$\hat{\beta}_2$	0.9869	0.9928	0.1783	0.1789	0.5910
	validity	—	—	—	—	0.0489
	exogeneity	—	—	—	—	0.5836
0	$\hat{\beta}_1$	-1.0016	-1.0027	0.0273	0.0282	0.0446
	$\hat{\beta}_2$	0.9791	0.9781	0.1755	0.1774	0.0474
	validity	—	—	—	—	0.0534
	exogeneity	—	—	—	—	0.0444
0.25	$\hat{\beta}_1$	-1.0021	-1.0032	0.0262	0.0263	0.0588
	$\hat{\beta}_2$	0.9741	0.9667	0.1872	0.1815	0.0592
	validity	—	—	—	—	0.0472
	exogeneity	—	—	—	—	0.4622
0.50	$\hat{\beta}_1$	-1.0027	-1.0037	0.0246	0.0246	0.0560
	$\hat{\beta}_2$	0.9686	0.9566	0.1934	0.1920	0.0584
	validity	—	—	—	—	0.0506
	exogeneity	—	—	—	—	0.9836

Table notes: All results obtained over 10,000 Monte Carlo replications. True values: $\beta = (-1, 1)^\top$. Nominal size of all tests is .05.

Table IV: Monte Carlo results for $n = 100$

ρ		mean	median	std	se	rej freq
-0.50	$\hat{\beta}_1$	-1.0002	-1.0001	0.0160	0.0161	0.0482
	$\hat{\beta}_2$	0.9958	0.9985	0.0906	0.0906	0.0440
	validity	—	—	—	—	0.0490
	exogeneity	—	—	—	—	1.0000
-0.25	$\hat{\beta}_1$	-0.9998	-0.9997	0.0148	0.0149	0.0472
	$\hat{\beta}_2$	0.9973	0.9978	0.0886	0.0879	0.0482
	validity	—	—	—	—	0.0542
	exogeneity	—	—	—	—	0.9912
0	$\hat{\beta}_1$	-1.0007	-1.0011	0.0135	0.0138	0.0500
	$\hat{\beta}_2$	0.9925	0.9926	0.0867	0.0877	0.0472
	validity	—	—	—	—	0.0474
	exogeneity	—	—	—	—	0.0490
0.25	$\hat{\beta}_1$	-1.0009	-1.0013	0.0128	0.0129	0.0502
	$\hat{\beta}_2$	0.9914	0.9891	0.0906	0.0904	0.0518
	validity	—	—	—	—	0.0486
	exogeneity	—	—	—	—	0.9832
0.50	$\hat{\beta}_1$	-1.0008	-1.0012	0.0121	0.0122	0.0552
	$\hat{\beta}_2$	0.9913	0.9873	0.0988	0.0962	0.0586
	validity	—	—	—	—	0.0510
	exogeneity	—	—	—	—	1.0000

Table notes: All results obtained over 10,000 Monte Carlo replications. True values: $\beta = (-1, 1)^\top$. Nominal size of all tests is .05.

Numerical illustrations We next provide simulation results on the performance of the instrumental-variable estimator. Our design has two covariates $\mathbf{x}_{i,j} = (x_{i,j}^1, x_{i,j}^2)^\top$ and three instruments $\mathbf{z}_{i,j} = (z_{i,j}^1, z_{i,j}^2, z_{i,j}^3)^\top$. The design is symmetric in the sense that $\mathbf{x}_{i,j} = \mathbf{x}_{j,i}$ and $\mathbf{z}_{i,j} = \mathbf{z}_{j,i}$ for all pairs (i, j) . For each pair we draw the first regressor from a lognormal distribution. Hence, $x_{i,j}^1$ is continuous and non-negative. We next generate the binary covariate via the threshold-crossing rule $x_{i,j}^2 = 1\{\mathbf{z}_{i,j}^\top \boldsymbol{\gamma} \geq \epsilon_{i,j}\}$, where

$$\begin{pmatrix} \log \epsilon_{i,j} \\ \log \epsilon_{j,i} \\ \epsilon_{i,j} \end{pmatrix} \sim \mathbf{N} \left(\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 & \rho \\ 0 & 1 & \rho \\ \rho & \rho & 1 \end{pmatrix} \right)$$

for correlation ρ . This setup ensures that the dummy variable is endogenous in (2.1) as long as $\rho \neq 0$. For our three instrumental variables we set $z_{i,j}^1 = x_{i,j}^1$ and, as excluded instruments, use $z_{i,j}^2 = 1\{1 + x_{i,j}^1 < u_{i,j}\}$ and $z_{i,j}^3 = 1\{z_{i,j}^2 \geq v_{i,j}\}$, where the errors $(u_{i,j}, v_{i,j})$ are bivariate standard normal. Both these instruments are dummies. The first one is generated with a success probability that is decreasing in $x_{i,j}^1$. The second one has success probability .841 when $z_{i,j}^2 = 1$ and .500 when $z_{i,j}^2 = 0$. In our simulations we set $\boldsymbol{\gamma} = (-1, 1, 1)^\top$ and $\boldsymbol{\beta} = (-1, 1)^\top$, ensuring that $x_{i,j}^1$ has a negative impact on both $t_{i,j}$ and $x_{i,j}^2$. In what follows we instrument by setting $\tilde{\mathbf{z}}_{i,j,i',j'} = \mathbf{z}_{i,j}$ for all (i', j') in (2.4).

Tables III and IV contain simulation results for our estimator for samples of size $n = 50$ and $n = 100$, respectively, as obtained over 10,000 Monte Carlo replications. The designs vary in the severity of the endogeneity, as governed by $\rho \in \{-.50, -.25, 0, .25, .50\}$. The tables contain the mean, median, and standard deviation of the point estimates, together with the average estimated standard errors and the rejection frequency of the two-sided t-test for the null that the coefficient in question is equal to its true value. We also provide the rejection frequency of Sargan's overidentification test (that tests whether the instruments are valid) and the exogeneity test. All tests were implemented with critical values corresponding to a 5% significance level.

Our estimator is close to unbiased for all designs and both sample sizes considered. The estimated standard errors of our estimator also perform well, being close (on average) to

the actual standard deviations over the Monte Carlo replication. They tend to be slightly too large here when $\rho < 0$ and slightly too small when $\rho > 0$. Nonetheless, the bias is small in magnitude, and the t-tests based on them provide reliable inference throughout. The same can be concluded for both Sargan tests. Although we do not report it here (as it was not designed for this situation) the pseudo-Poisson estimator suffers from substantial bias for all non-zero values of ρ . The t-tests based on this estimator almost always reject, making them an unreliable tool for inference in situations where endogeneity is feared to be present.

5 Conclusion

We have introduced an instrumental-variable approach to estimate the gravity equation of [Anderson and van Wincoop \(2003\)](#). Our procedure is meant to accommodate the potential endogeneity of policy variables and is fully theory-consistent, in the sense of [Head and Mayer \(2014\)](#). They are based on the model in levels and account for multilateral resistance terms by means of importer and exporter fixed effects. The implementation is limited-information in nature, and so is silent on the determinants that drive the actual policy decisions. A Stata[©] implementation of our estimator is available.

We estimate gravity equations for multiple cross-sections of bilateral-trade data where the policy decision of interest is the engagement in a free trade agreement. We rely on the interaction of the countries in the pair with third-party trading partners to construct a credible instrumental variable based on the substantial transitivity in the formation of trade agreements that is observed in the data. This instrument is strongly correlated with the policy variable and its validity is consistent with models of structural gravity. Our estimate of the average marginal effect of a free trade agreement varies over time, with values ranging from 61% to 117%, implying more than a doubling of trade volume. This puts trade agreements broadly on par, in terms of magnitude of their impact, with sharing a common border or having a colonial history. In contrast, not correcting for endogeneity yields estimates of around 25%.

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