

Jingyao Su

Doctoral researcher, Institute of Geodesy(IfE), Leibniz University Hannover, Germany

Web: <https://www.jingyao-su.com>

Linkedin, ResearchGate, ORCID, Google Scholar

Email: suj@ife.uni-hannover.de

Tel.: +49-511-762-4542

EDUCATION

- **Leibniz University Hannover** Hannover, Germany
Ph.D in Geodesy and Geoinformation *Jul 2020 - Present*
Research topic: *Bounding and propagating uncertainty with interval mathematics and alternative approach for GNSS integrity* (Prof. Steffen Schön).
- **Technical University of Munich** Munich, Germany
Master of Science in Earth Oriented Space Science and Technology (ESPACE) *Oct 2017 - Jun 2020*
Specification in satellite navigation. Thesis topic: *Precise point positioning with ambiguity resolution for different GNSS signals* (Dr. Bingbing Duan, Prof. Urs Hugentobler).
- **Helmholtz Centre Potsdam - GFZ German Research Centre for Geosciences** Potsdam, Germany
Visiting student at Section 1.1: Space Geodetic Techniques *Jul 2018 - Aug 2018*
- **Wuhan University** Wuhan, China
Bachelor of Science in Geophysics *Aug 2011 - Jun 2015*

EXPERIENCE

- **Leibniz University Hannover** Hannover, Germany
Doctoral researcher at Institute of Geodesy (IfE) *Jul 2020 - Current*
with the DFG research training group *Integrity and Collaboration in Dynamic Sensor Networks (i.c.sens)*
- **Robert Bosch Group** Hildesheim, Germany
R&D internship *Apr 2019 - Oct 2019*
- **Technical University of Munich** Munich, Germany
Research assistant at Institute for Astronomical and Physical Geodesy (IAPG) *Apr 2018 - Mar 2019*
- **Shenyang Institute for Geotechnical Investigation and Surveying** Shenyang, China
Geomatics engineer *Aug 2015 - Aug 2017*

HONORS AND AWARDS

- **Best Student Presentation Award** at NAVITEC 2022, by European Space Agency (ESA) - Apr 2022.
- **Best Presentation Award** at ION GNSS+ 2021, by Institute of Navigation (ION) - Sep 2021.
- **Copernicus Masters 2018** - Top 3 finalist of University Challenge, by AZO Anwendungszentrum on behalf of the European Space Agency (ESA) - Oct 2018
- **Zetai Cup National Student Paper Competition in Geodesy** - First prize, by Education Commission, Chinese Society for Surveying and Mapping - Dec 2014
- **Wang Zhizhuo Innovative Talent Scholarship** by Wuhan University - Nov 2014

PROFESSIONAL MEMBERSHIP

member of IEEE, member of the Society for Imprecise Probabilities (SIPTA)

PROFESSIONAL SKILLS

- **Languages:** Chinese (*mother tongue*), English (*proficient in both writing and speaking*), German (*daily usage*)
- **Programming:** MATLAB, Python, C/C++, Fortran, Perl

PUBLIC SERVICES

- **Workshop organizer and session chair:** *IEEE Symposium of Intelligent Vehicles (IEEE-IV 2022)*, the 1st iLoc workshop *High-integrity Localization for Autonomous Vehicles*, Aachen, Germany. (Jun 2022)
- **Supervision of master students:**
Master thesis:
 - Elesawy M. (2022). Characterizing the ionospheric behaviour for continental network RTK services over Europe.Master course:
 - Advanced Presentation Seminar (in German: Hauptseminar) for the master program *Geodesy and geoinformation*
 - Project Work (in German: Studienarbeit) for the master program *Mechanics and robotics*

PEER-REVIEWD PUBLICATIONS

- **Su, J.**, & Schön, S. (2022). Advances in deterministic approaches for bounding uncertainty and integrity monitoring of autonomous navigation. accepted by *ION GNSS+ 2022*.
- Schön, S., Baasch, K. N., Icking, L., KarimiDoona, A., Lin, Q., Ruwisch, F., Anat Schaper, A. & **Su, J.** (2022, June). Towards Integrity for GNSS-based urban navigation—challenges and lessons learned. In *2022 IEEE Intelligent Vehicles Symposium (IV)* (pp. 1774-1781). IEEE.
- **Su, J.**, & Schön, S. (2022). Deterministic approaches for bounding GNSS uncertainty: A comparative analysis. In *2022 10th Workshop on Satellite Navigation Technology (NAVITEC)* (pp. 1-8). IEEE.
- **Su, J.**, & Schön, S. (2021). Improved observation interval bounding for multi-GNSS integrity monitoring in urban navigation. In *Proceedings of the 34th International Technical Meeting of the Satellite Division of The Institute of Navigation (ION GNSS+ 2021)* (pp. 4141-4156).

SELECTED TALKS

- How to determine uncertainty interval: Practice in GNSS and LiDAR localization. (Jul 2022). In *13th Summer Workshop on Interval Methods (SWIM)*. Hannover, Germany.
- Deterministic approaches for bounding GNSS uncertainty: A comparative analysis. (Jun 2022). In *1st iLoc workshop on High-integrity Localization for Autonomous Vehicles, 33rd IEEE Intelligent Vehicles Symposium*. Aachen, Germany.
- Improved observation interval bounding for GNSS integrity monitoring. (Oct 2021). In *DGK PhD Seminar Engineering Geodesy Division*. Hannover, Germany.
- On the geometrical constraints for interval-based GNSS positioning. (Sep 2021). In *Frontiers of Geodetic Science (FROGS) 2021*. Hannover, Germany.
- Bounding the residual tropospheric error by interval analysis. (Jul 2021). In *IAG 2021-Scientific Assembly of the International Association of Geodesy*. Beijing, China.