

RESEARCH INPUT FOR COMPUTER  
SIMULATION OF AUTOMOBILE COLLISIONS  
VOLUME IV  
STAGED COLLISION RECONSTRUCTIONS

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16. Abstract <p>Volume IV of this document describes and evaluates computer reconstructions of the twelve staged collisions presented in Volumes II and III. Results of the CRASH II program were judged on their degree of correspondence with the measured impact speeds and changes in velocity. Reconstructions using the SMAC program were assessed on the basis of the accuracy of the predicted final rest positions, damage dimensions, and changes in velocity. On the whole, the results from both the reconstruction programs were satisfactory. Recommendations that are made include: 1) to update representative values of vehicle characteristics used in the CRASH II program, 2) to add a stationary vehicle option to the CRASH program, 3) to simulate hard points and corner effects in the SMAC program, and 4) to provide an option to input tire cornering stiffness time history data in order to simulate weight transfer effects.</p>			
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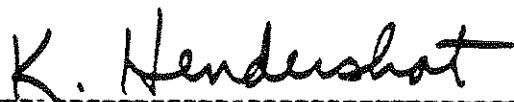
## FOREWORD

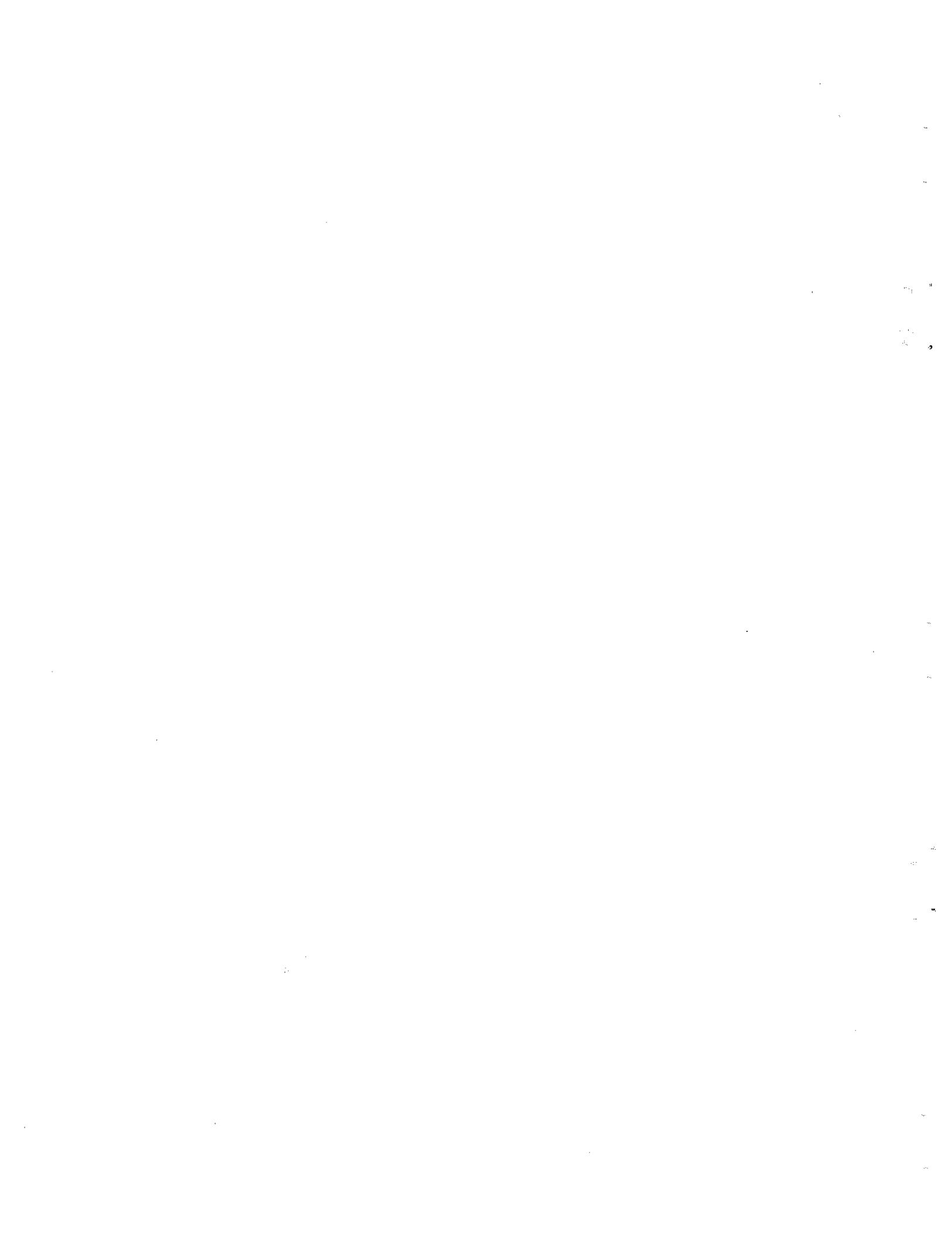
This document summarizes the research achieved under Contract No. DOT-HS-7-01511, "Research Input for Computer Simulation of Automobile Collisions", with National Highway Traffic Safety Administration, U. S. Department of Transportation. Volume I summarizes previous existing experimental data from staged collisions and presents plans for future data needs. The experimental data generated in twelve staged collisions are reported in Volumes II and III of this document. Volume II contains the experimental test data for Test No. 1 through No. 5. Volume III contains the test data for Test No. 6 through No. 12. The reconstruction of these collisions, using the CRASH and SMAC simulation programs, is reported in Volume IV of this document.

The Contract Technical Manager for Phase II was Mr. Thomas Noga of the National Highway Traffic Safety Administration.

The opinions and findings expressed in this publication are those of the authors and not necessarily those of the National Highway Traffic Safety Administration.

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## 1.0

INTRODUCTION

The objective of this program was to run twelve staged collisions and reconstruct them using the CRASH II and SMAC programs. This volume reports these reconstructions, compares the results with the measured data and discusses the shortcomings of the programs. The CRASH II reconstructions are presented and discussed in Section 2, the SMAC reconstructions in Section 3, and conclusions and recommendations in Section 4.

To aid in the reconstruction process, a minimum of ten high speed cameras were used to photograph each collision. Cameras were stationed on the ground at eye level and were located on portable towers as well. Two hand-held motion picture cameras (24 fps) were used to track each of the vehicles before, during, and after impact.

On-board instrumentation provided additional data which were used to assist in, and evaluate the accuracy of, the computer reconstructions. This volume deals almost exclusively with data collected by a triaxial (XYZ) accelerometer mounted on the vehicle's firewall, a linear stroke potentiometer attached to the vehicle steering linkage to measure the vehicle steer angle, and a rate gyroscope to obtain the vehicle yaw rate. Outputs from these instruments were recorded on 14 channel FM tape recorders. The analogue data recorded during the crash test were converted into digital form.

Plots of the digitized data were generated by a computer program, which also integrated the acceleration time histories\* in order to obtain velocity (and displacement) time histories along each of the vehicle's three axes. Also from the time histories of the acceleration, the time at which separation occurred was estimated. It was defined to be the point at which both the involved vehicles' accelerations reapproached 0 g's. Table 1-1 presents the estimated contact durations for each of the twelve tests. It

\*The integration algorithm is a combination of Simpson's and Newton's 3/8 methods.

TABLE 1-1  
COLLISION CONTACT DURATION

<u>Test No.</u>	<u>Contact Duration</u> (Sec)	<u>Test No.</u>	<u>Contact Duration</u> (Sec)
1	.225	7	.200
2	.225	8	.200
3	.200	9	.200
4	.275	10	.200
5	.250	11	.225
6	.200	12	.225

should be noted that the separation point was not always obvious in collisions in which the two vehicles spun out together, e.g., Test 8.

The components of a vehicle's change in velocity ( $\Delta V$ ) were subsequently computed by subtracting the initial velocity at impact from the velocity at the time of separation. These are presented in Table 1-2.

It was discovered that the value of the separation velocity was contaminated by the effects of rotation of the vehicles between impact and separation. The data reduction software which computed the velocity time histories was originally developed in conjunction with prior research programs investigating vehicle crashworthiness. These studies primarily involved frontal collisions with barriers, and hence, very little, if any, rotation. Under these conditions, integrating the output of an accelerometer measuring acceleration along the, say, X-axis of the vehicle, gives one the vehicle's actual x-component of velocity, because the direction-cosine matrix (to be introduced below) essentially does not change throughout the collision and post crash trajectory. Unfortunately, modification of the software to account for the rotation was beyond the scope of this study.

In order to demonstrate the effect of the vehicle rotation, consider the two-dimensional vectors,  $\vec{X}$ ,  $\vec{Y}$  and  $\vec{r}$ , shown in Figure 1-1.

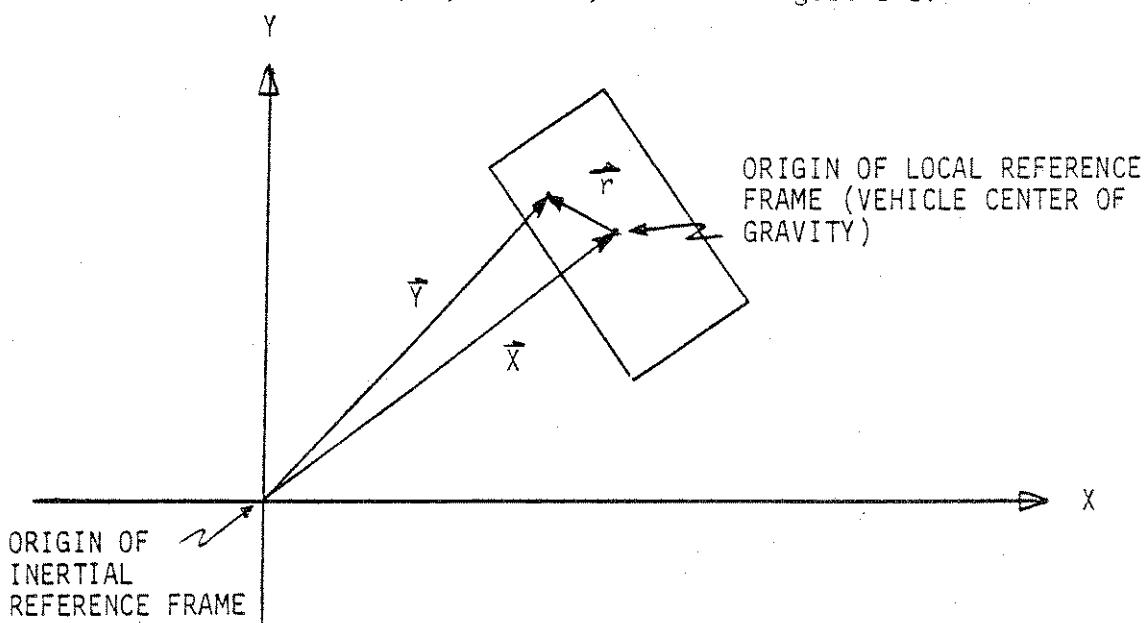


Figure 1-1 SCHEMATIC OF THE RELATION BETWEEN  $\vec{X}$ ,  $\vec{Y}$  AND  $\vec{r}$

TABLE 1-2  
VELOCITY CHANGE MEASURED AT FIREWALL

Test No.	Impact Configuration	Vehicle Size	~ΔV at Firewall		
			ΔV	ΔVx	ΔVy
1	60° Front-to-Side	I	12.2	-10.6	6.0
		SC	15.6	-12.1	-9.8
2	60° Front-to-Side	I	19.6	-16.5	10.5
		SC	--	--	--
6	60° Front-to-Side	I	9.2	-8.5	5.0
		SC	11.9	-11.5	-3.2
7	60° Front-to-Side	I	12.0	-11.5	3.5
		SC	16.5	-14.1	-8.5
8	90° Front-to-Side	I	15.3	-12.7	8.6
		I	10.7	-7.2	-8.0
9	90° Front-to-Side	M	21.4	-17.7	12.0
		I	8.9	-5.0	-7.4
10	90° Front-to-Side	M	35.1	-27.3	22.0
		I	14.1	-8.8	-11.0
11	10° Offset Front-to-Front	SC	24.0	-24.0	0.8
		I	15.7	-15.6	2.0
12	10° Offset Front-to-Front	SC	40.1	-40.0	-2.2
		I	26.4	-26.0	4.8
3	10° Offset Front-to-Rear	I	9.5	-9.5	-0.4
		C	15.8	15.8	-0.2
4	10° Offset Front-to-Rear	I	18.7	-18.7	0.4
		SC	22.2	22.2	-2.8
5	10° Offset Front-to-Rear	I	16.3	-16.3	0.2
		M	25.1	25.0	-1.8

The location of point  $r$  in the inertial reference (denoted by  $\vec{Y}$ ) can be given by the following matrix-vector equation:

$$\vec{Y} = \vec{X} + D^{-1} \vec{r} \quad (1)$$

- where:  $\vec{Y}$  - is a vector, whose components are in the inertial reference, from the inertial reference origin to point  $r$   
 $\vec{X}$  - is a vector, whose components are in the inertial reference, from the inertial reference origin to the local reference origin (vehicle's center of gravity)  
 $\vec{r}$  - is a vector, whose components are in the local reference, from the local reference origin to point  $r$   
 $D$  - is the direction cosine matrix that relates the local reference system to the inertial frame

Differentiating Equation (1) with respect to time, the linear velocity of point  $r$  (in the inertial reference frame) is obtained.

$$\dot{\vec{Y}} = \dot{\vec{X}} + D^{-1} \vec{w} \otimes \vec{r} \quad (2)$$

- where  $\vec{w}$  - is a vector representing the angular velocity of the vehicle about its local axes  
 $\otimes$  - denotes the vector cross-product operation

The linear acceleration of the point  $r$ , in the inertial frame, can be obtained by differentiating Equation (2) to give

$$\ddot{\vec{Y}} = \ddot{\vec{X}} + D^{-1} \ddot{\vec{w}} \otimes \vec{r} + D^{-1} \vec{w} \otimes (\vec{w} \otimes \vec{r}) \quad (3)$$

Equations (2) and (3) can be readily transformed into the local reference frame. Results of this transformation are shown for the linear velocity in Equation (4) and the linear acceleration in Equation (5).

$$D \dot{\vec{Y}} = D \dot{\vec{X}} + \vec{w} \otimes \vec{r} \quad (4)$$

$$D \ddot{\vec{Y}} = D \ddot{\vec{X}} + \dot{\vec{w}} \otimes \vec{r} + \vec{w} \otimes (\vec{w} \otimes \vec{r}) \quad (5)$$

The output of a triaxial accelerometer package located at point  $r$ , is represented by Equation (5). It should be obvious that, if the accelerometers are not placed at the local reference origin (vehicle center of gravity), the data obtained include a rotational effect, dependent not only on the magnitude of the offset, but also on the vehicle's angular velocity and angular acceleration.

Placing the accelerometer package at the local reference center of gravity does not entirely alleviate the problem of the need to account for rotation. Under the assumption that the accelerometer is at the center of gravity, Equations (4) and (5) become Equations (6) and (7), respectively.

$$D \dot{\vec{Y}} = D \dot{\vec{X}} \quad (6)$$

$$D \ddot{\vec{Y}} = D \ddot{\vec{X}} \quad (7)$$

The integration of Equation (7) with respect to time, without regard for the local reference's relation to the inertial frame, will result in Equation (6) only if the direction-cosine matrix remains constant over time, i.e.,  $\int_{t_0}^{t_1} D \dot{\vec{X}} dt = D \int_{t_0}^{t_1} \dot{\vec{X}} dt = D \vec{X}$  if and only if  $D$  is a constant.

The software which reduced the raw accelerometer data from the staged collisions, unfortunately, is based on the assumption of a constant direction cosine matrix. Furthermore, it only calculates velocities and displacements for the position at which the accelerometer is located so that the behavior at other locations in the vehicle (particularly, the center of gravity) cannot be determined.

Neglecting the rotational effects obviously can introduce some error in the values of the velocity changes that are ultimately

derived from the data. An examination of the  $\Delta V$ 's presented in Table 1-2 suggests, for instance, that linear momentum was not necessarily conserved during the impact, nor were the impacts necessarily co-linear. These are, however, artifacts caused by excluding the effects of rotation (and, in some cases, perhaps exacerbated by difficulties in precisely determining the time of separation). In an attempt to estimate the degree to which the data are affected, Table 1-3 has been compiled. It presents the change in heading angle between impact and separation (in order to estimate changes in the direction-cosine matrix), the angular velocity at separation, the maximum angular velocity, and the offset from the center of gravity of the accelerometer package; the latter three variables are useful in approximating the magnitude of the  $\vec{w} \times \vec{r}$  term.

It would appear from Table 1-3, that the failure to consider changes in the D matrix may probably produce significant variations in only one case; specifically, the data for Vehicle 1 in Case 10, which rotated  $55^\circ$  between impact and separation. The cases in which significant error would likely be introduced by assuming that the change in velocity at the firewall was equivalent to that experienced at the center of gravity are: Test 2, Vehicle 1; Test 6, Vehicle 2; Test 7, Vehicle 2; and Vehicle 1 in Tests 8, 9, 10 and 12. The implications of the above discussion when evaluating the SMAC and CRASH II  $\Delta V$  predictions will be considered on a case-by-case basis in Sections 2 and 3.

TABLE 1-3  
FACTOR INFLUENCING MAGNITUDE OF EFFECTS OF ROTATION

Test No.	Vehicle No.	Change in Heading Angle (deg)	Maximum Angular Velocity (deg/sec)	Angular Velocity at Separation (deg/sec)	$r_x$ (ft)	$r_y$ (ft)
1	1	15	120	90	.57	.74
	2	0	0	0	1.12	.52
2	1	18	150	150	.70	.89
	2	-9	-120	90	1.27	.46
3	1	1	20	15	1.31	.01
	2	0	0	0	.49	.57
4	1	lost data	45	37	1.31	.01
	2	lost data	30	30	.35	.52
5	1	5	20	12	-1.32	.03
	2	lost scale factor	90	70	.88	.33
6	1	5	45	30	.54	.73
	2	20	210	180	2.53	.37
7	1	12	65	30	.54	.77
	2	22	210	192	2.48	.38
8	1	15	135	114	.95	.75
	2	0	18	18	.93	.73
9	1	27	210	180	.88	.74
	2	-10	-45	-45	1.21	.56
10	1	55	300	300	.78	.71
	2	-12	-90	-72	1.24	.49
11	1	-5	-45	-30	1.61	1.02
	2	0	0	0	1.20	.23
12	1	-10	-90	-90	1.03	1.01
	2	-2	-60	-60	1.30	.16

Table 2-1 gives a summary of the CRASH II results showing impact configuration and vehicle size together with the measured and predicted values of impact speed and velocity change for each vehicle. Note that two predicted velocity changes are given. The first is that calculated using the spin out routine combined with the conservation of momentum routine for oblique type impacts or the spin out routine combined with the damage routine for axial type impacts; the second is the velocity change calculated using the damage only routine.

To aid interpretation of the results, rather than list the tests in numerical order, the tests have been grouped by impact configuration: Tests 1, 2, 6 and 7 were front-to-side impacts with the bullet car striking at a  $60^\circ$  angle with respect to the longitudinal axis of the struck car; Tests 8, 9 and 10 were front-to-side impacts with the bullet car striking at  $90^\circ$ ; Tests 11 and 12 were front-to-front impacts with the vehicles offset and striking at a  $10^\circ$  angle; and Tests 3, 4 and 5 were front-to-rear impacts with the vehicles offset and striking at a  $10^\circ$  angle.

A cursory inspection of the table shows that on the whole there is good agreement between the CRASH II predictions and the measured values. Looking at impact speeds, the agreement is extremely good for the  $60^\circ$  front-side impacts and the  $90^\circ$  front-side impacts. The largest discrepancy being 3.7 mph for Vehicle 2 in Test 8. Larger discrepancies occur in the axial type impacts. These errors can be attributed to the DAMAGE subroutine underestimating the velocity changes that the vehicles undergo. For example, looking at the head-on impacts, although the agreement for Test 11 is good, for Test 12 the impact speed of Vehicle 1 is underestimated by 11.7 mph because the corresponding velocity change is also underestimated. Similar problems occur with the rear end impacts, Tests 3, 4 and 5. For all these tests, the impact speed of the striking vehicle is underestimated and that for the struck vehicle overestimated because the corresponding velocity changes are underestimated.

TABLE 2-1  
SUMMARY OF CRASH RESULTS

Test No.	Vehicle Size	Measured Values			Crash Values		
		Impact Speed	$\Delta V$	Impact Speed	$\Delta V_1$	$\Delta V_2$	
1	60° Front-to-Side	I	19.8	12.2	20.6	9.6	18.5
		S	19.8	15.6	20.4	14.4	27.7
2	60° Front-to-Side	I	31.5	19.6	29.6	20.6	19.3
		SC	31.5	--	33.3	30.9	29.0
6	60° Front-to-Side	I	21.5	9.2	24.9	12.4	12.7
		SC	21.5	11.9	20.5	20.4	20.9
7	60° Front-to-Side	I	29.1	12.0	26.2	11.6	16.3
		S	29.1	16.5	27.1	25.3	35.5
8	90° Front-to-Side	I	20.75	15.3	19.5	10.3	10.0
		I	20.75	10.7	24.5	9.5	9.5
9	90° Front-to-Side	M	21.2	21.4	23.2	24.2	19.1
		I	21.2	8.9	22.0	11.2	8.8
10	90° Front-to-Side	M	33.3	35.1	32.7	33.6	22.4
		I	33.3	14.1	31.5	15.9	10.9
11	10° Offset Front-to-Front	S	20.4	24.0	17.2	21.0	21.1
		I	20.4	15.7	18.0	15.2	13.2
12	10° Offset Front-to-Front	S	31.5	40.1	19.8	28.2	28.2
		I	31.5	26.4	30.2	20.0	19.6
3	10° Offset Front-to-Rear	I	21.2	9.5	15.2	3.1	3.1
		S	0.0	15.8	10.4	5.4	4.9
4	10° Offset Front-to-Rear	I	38.7	18.7	31.9	10.3	9.1
		S	0.0	22.2	4.9	13.0	14.1
5	10° Offset Front-to-Rear	I	39.7	16.5	33.8	8.1	8.1
		M	0.0	25.1	10.5	15.2	14.8

In summary, discrepancies between CRASH II predictions and measured values of impact speeds appear to be limited to head-on impacts at high speed (closing speeds of 60 mph) and to rear end impacts. It should be stressed that these are impact configurations for which there were limited data available when the stiffness coefficients were originally calculated for the damage analysis of the CRASH II program. Updating these coefficients using the present data should, of course, improve the agreement.

## 2.1 Evaluation of the SPIN II Routine

Since the major discrepancies in impact speed stem from the damage analysis subroutine, it is instructive to compare the separation conditions predicted by the SPIN II routine with the measured values. This enables the effectiveness of the SPIN II routine to be evaluated independently. Table 2-2 gives a summary of the separation conditions for each test. Looking at the resultant velocities, the agreement is extremely good, generally within 5 mph with the exception of Test 2 which has a discrepancy of 6.7 mph for Vehicle 1, and Test 5, in which there is a difference of 6.5 mph for Vehicle 2. Both of these vehicles experienced a significant amount of rotation, the effects of which were neglected in the computation of the separation velocities.

The agreement is better (but not statistically significant) for the axial type collisions than for the oblique intersection type collisions which can be explained by the fact that the spin out trajectories in these cases are more nearly linear and the estimation of the velocity dissipated in the spin out correspondingly more accurate. This trend is more pronounced in the comparison of the velocity components; the average absolute deviation for the axial impacts differed significant from the oblique impacts ( $t_{44} = 2.19$ ,  $p \leq .05$ ). This again is explained by the fact that the trajectories in axial impacts are more linear, so that the lateral component of velocity is small and the estimated heading angle at separation less subject to error. To explain further, the velocity components are calculated by resolving the resultant velocity change using the vehicle's heading angle at separation.

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\* McHenry, R. R., "User's Manual for the CRASH Computer Program," Calspan Report No. ZQ-5708-V-3, January 1976.

TABLE 2-2

SUMMARY OF SEPARATION CONDITIONS  
MEASURED VERSUS SPIN IT PREDICTED VALUES

Test No.	Configuration	Vehicle 1 Separation Velocity				Vehicle 2 Separation Velocity			
		Measured		Predicted		Measured		Predicted	
		<u>V</u>	<u>V<sub>X</sub></u>	<u>V<sub>y</sub></u>	<u>V<sub>x</sub></u>	<u>V</u>	<u>V<sub>x</sub></u>	<u>V<sub>y</sub></u>	<u>V<sub>x</sub></u>
1	60° Front-Side	11.0	9.2	6.0	11.5	11.2	2.4	12.5	7.7
2	60° Front-Side	18.3	15.0	10.5	11.6	9.9	6.1	--	--
6	60° Front-Side	13.3	13.0	3.0	12.9	12.7	2.3	10.5	10.0
7	60° Front-Side	17.9	17.6	3.5	15.3	15.0	3.2	17.2	15.0
8	90° Front-Side	11.8	8.0	8.6	14.3	12.3	7.3	15.7	13.6
9	90° Front-Side	12.5	3.5	12.0	9.9	1.1	9.8	17.8	16.2
10	90° Front-Side	22.8	6.0	22.0	20.0	6.1	19.0	26.9	24.5
11	Offset Head on	-3.7	-3.6	0.8	-3.8	-3.8	0.3	-5.2	4.8
12	Offset Head on	-8.7	-8.5	-2.2	-8.5	-8.3	-1.6	7.3	5.5
3	Offset Rear End	11.7	11.7	0.4	12.1	12.1	0.2	15.8	15.8
4	Offset Rear End	20.0	20.0	-0.4	23.3	22.8	4.9	22.4	22.2
5	Offset Rear End	23.4	23.4	0.2	25.7	25.7	0.0	25.1	25.0

This is estimated to be along the line joining the impact position with the rest or end-of-notation position, or in the case of curved trajectories, the tangent to the circle\* at the impact position. Obviously, for near linear trajectories, which is usually the case for axial type impacts, any error in the heading angle is likely to be small. Conversely, in oblique type impacts, which tend to produce more complicated spin outs with large lateral and angular velocities, the likelihood of error must be higher.

During the course of the study, a problem was detected in the curved trajectory option in situations in which no end-of-rotation point was defined. In the three cases that were applicable, i.e., Tests 4, 9 and 10, the program calculated outlandish values for the separation velocities. This problem was circumvented by considering the curved trajectory as two straight line segments, one joining the point of impact to an end-of-rotation point and a second from end-of-rotation to the final rest position.

The source of this problem was traced to an error in the CRASH II program. The necessary changes to the source code are presented and discussed in Appendix I, but reconstructions reported herein did not utilize the corrected version of the program. It is notable, however, that the results obtained from the corrected curved trajectory routine were almost identical to the ones presented in this report.

## 2.2 Discussion of Individual Cases

A discussion of each case follows. For the convenience of the reader, a schematic diagram of each test configuration is given together with a table comparing predicted and measured data.

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\*The radius of the circle is estimated using the impact position, rest position and an intermediate point in the trajectory.

Test No. 1 - 60° Front-to-Side Impact - Chevrolet Chevelle Vs.  
Ford Pinto - Impact Speeds, 19.8/19.8 mph  
Accident Schematic - Figure 2-1

The estimated impact speeds for both vehicles are in extremely close agreement; 20.6 mph versus 19.8 mph actual for Vehicle 1 and 20.4 mph versus 19.8 mph actual for Vehicle 2. The velocity changes predicted from the conservation of linear momentum are also in good agreement; for Vehicle 1, 9.6 mph versus 12.2 mph actual, and for Vehicle 2, 14.4 mph versus 15.6 mph actual. The velocity changes predicted from the vehicle damage are both grossly overestimated; for Vehicle 1, 18.5 mph versus 12.2 mph actual and 27.7 mph versus 15.6 mph actual for Vehicle 2. However, there was considerable corrosion on the Ford Pinto used in the test such that the stiffness of this vehicle was degraded. This means that the stiffness coefficients in the damage routine would be too high, which when combined with the damage profile (also more severe because of the degraded stiffness), results in an overestimate of the velocity change.

Looking at the separation velocities of each vehicle, both are slightly overestimated by SPIN II, 11.5 mph versus 11.0 mph for Vehicle 1 and 14.6 mph versus 12.5 mph for Vehicle 2. However, because of the relatively small amount of spin out, these velocities were very sensitive to quite small change in the impact and rest positions of the vehicles.

# ACCIDENT SCHEMATIC

## VEHICLES:

- No. 1 - 1974 CHEVROLET CHEVELLE MALIBU  
No. 2 - 1974 FORD PINTO

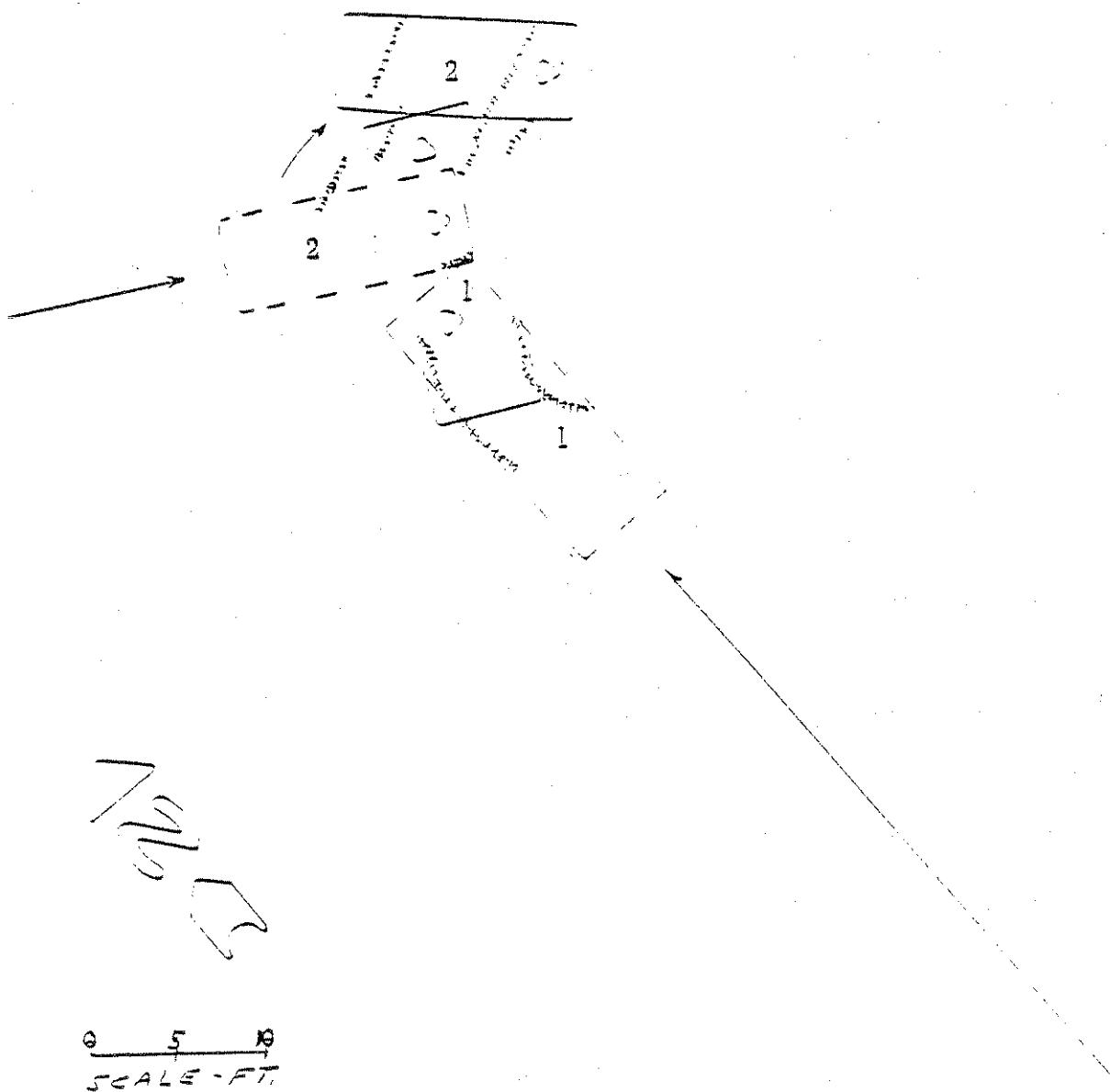


Figure 2-1 TEST NO. 1 - RICKSAC ACCIDENT SCHEMATIC

SUMMARY FORM FOR STAGED COLLISION REPORTING

VEHICLE #1	MEASURED				SMAC				CRASH			
	SPEED AT IMPACT		$\Delta V$	VDI	SPEED AT IMPACT		$\Delta V$	VDI	SPEED AT IMPACT		$\Delta V$	DAMAGE
	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH
Comparison of Result	R 12.2 X-10.6	X 6.0	11FZEW2	19.8	R 14.2 X Y	12FDEW3	20.6	R 9.6 X-9.3 Y 2.4	R 18.5 X-16.0 Y 9.3	R 14.4 X-10.1 Y-10.3	R 27.7 X-24.0 Y-13.9	
VEHICLE #2	R 15.6 X-12.1	X Y -9.8	01RDEW3	19.8	R 20.0 X Y	03RDEW3	20.4					

VEHICLE #1	REST POSITIONS				IMPACT POSITIONS				END OF ROTATIONAL AND/OR LAT. SKID,			
	X'	Y'	Z'	CS	X'	Y'	Z'	C1	Y'	Z'	C1	$\psi$
	GR.	CR.	$\Psi_R$	$\Psi$	FT.	FT.	DEG.	FT.	FT.	FT.	DEG.	ROT.
VEHICLE #1	-2.4	-1.0	-1.5	-10.8	1.0	-30.0	--	--	CW	.01	.01	.2
VEHICLE #2	7.5	2.5	105.0	0.0	-5.5	90.0	--	--	CW	.01	.01	.2

MEASURED DAMAGE DIMENSIONS

VEHICLE #1	WIDTH	DAMAGE EXTENT				MOMENT ARM	DIRECTION	DIRECTION	DIRECTION	DIRECTION	DIRECTION	
		C11	C12	C13	C14							
VEHICLE #1	46.0	4.0	5.5	7.0	10.2	12.1	14.8	14.3	--	-30	1	4621
VEHICLE #2	113.3	0.5	12.0	10.6	11.8	9.0	4.1	21.8	--	-30	S	3082

Summary of  
Physical  
Evidence

COLLISION CONFIGURATION    60° front-to-side impact  
TEST IDENTIFICATION    RICSAC Test No. 1 - Chevrolet Chevelle Vs. Ford Pinto

Test No. 2 - 60° Front-to-Side Impact - Chevrolet Chevelle Vs.  
Ford Pinto - Impact Speeds, 31.5/31.5 mph  
Accident Schematic - Figure 2-2

The estimated impact speeds are in good agreement; for Vehicle 1, 29.6 mph versus 31.5 mph actual and for Vehicle 2, 33.3 mph versus 31.5 mph actual. The velocity changes for Vehicle 1 agree closely, 20.6 mph from conservation of momentum and 19.3 mph from the damage analysis, versus 19.6 mph actual. Unfortunately, the accelerometer traces for Vehicle 2 were lost (due to malfunction of recording equipment) so that it is not possible to make a comparison for this vehicle. Suffice it to say that there is good agreement between the conservation of momentum and damage analysis  $\Delta V$ 's, although there is a small discrepancy in the components. This results from the heading angle used for resolution; in the damage analysis, it is assumed to be the line of maximum force whereas in the conservation of momentum calculation, it is the direction of spin out. Obviously, any difference between these two angles will be reflected in the components of the velocity change.

The separation velocity of Vehicle 1 was underestimated, 11.6 mph versus 18.3 mph actual. As mentioned previously, the SPIN II routine is particularly sensitive to the vehicle positions in estimating short spin out trajectories such that adjustment of the rest position would probably allow a better fit to be obtained. Furthermore, Vehicle 1 experienced a high (150 deg/sec) angular velocity for approximately 100 of the 225 msec. contact duration. The components of  $\dot{r}$  (shown in Table 1-3) are such, that in combination with a clockwise rotation, the x-component of the separation velocity will decrease as will the y-component. This will improve the degree of correspondence between the actual and predicted separation velocities. At the same time, this has the effect of increasing the magnitude of  $\Delta V_x$  and decreasing the magnitude of  $\Delta V_y$ . As a result, the effect on the resultant velocity change should be minimal, thus preserving the good agreement reported above. Because the acceleration time histories for Vehicle 2 were not recorded, the actual separation velocities could not be calculated and, therefore, a comparison with the predicted values was not possible.

## ACCIDENT SCHEMATIC

### VEHICLES:

- No. 1 - 1974 CHEVROLET CHEVELLE MALIBU  
No. 2 - 1974 FORD PINTO

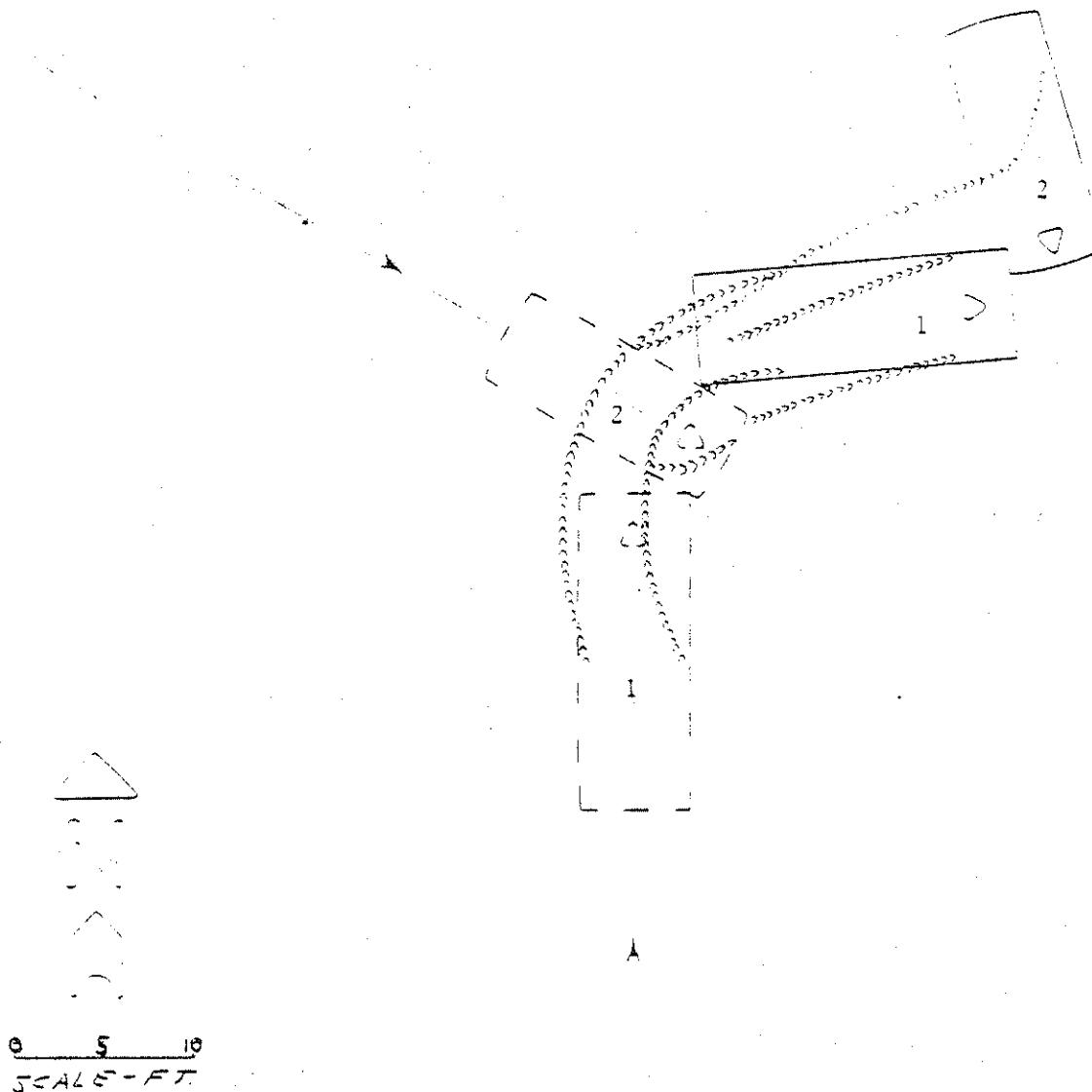


Figure 2-2 TEST NO. 2 - RICSAC ACCIDENT SCHEMATIC

## SUMMARY FORM FOR STAGED COLLISION REPORTING

Comparison of Result	MEASURED						SMAC						CRASH						
	SPEED AT IMPACT		A V		VDI		SPEED AT IMPACT		A V		VDI		SPEED AT IMPACT		A V		A V		DAMAGE
	SPEED AT IMPACT MPH	A V MPH	VDI MPH	A V MPH	VDI MPH	SPEED AT IMPACT MPH	A V MPH	VDI MPH	SPEED AT IMPACT MPH	A V MPH	VDI MPH	SPEED AT IMPACT MPH	A V MPH	VDI MPH	SPEED AT IMPACT MPH	A V MPH	A V MPH	DAMAGE	
VEHICLE #1	R 19.6 X -16.5 Y 10.5	X 11FDEW2	31.5	X 31.5 Y	12FDEW3	R 21.3 X	X 21.3 Y	X 21.3 Y	R 29.6 X	X 29.6 Y	X 29.6 Y	R 20.6 X	X 19.7 Y	X 19.7 Y	R 20.6 X	X 19.7 Y	R 19.3 X -16.7 Y 9.7		
VEHICLE #2	R -- X -- Y --	12RDEW4	31.5	X 31.5 Y	02RYEW5	R 31.7 X	X 31.7 Y	X 31.7 Y	R 33.3 X	X 33.3 Y	X 33.3 Y	R 30.9 X	X 22.7 Y	X 22.7 Y	R 30.9 X	X 21.0 Y	R 29.0 X -14.5 Y -25.1		

TEST IDENTIFICATION	REST POSITIONS						IMPACT POSITIONS						END OF ROTATIONAL AND/OR LAT. SKID.						
	X'	Y'	Z'	CS	Y'	CS	ψ	S	X'	Y'	Z'	CS	ψ	S	X'	Y'	Z'	CS	ψ
	FT.	FT.	DEG.	FT.	FT.	DEG.	FT.	DEG.	FT.	FT.	DEG.	FT.	DEG.	FT.	FT.	DEG.	FT.	FT.	DEG.
VEHICLE #1	11.0	9.4	55.0	-11.2	8.5	-30.0	--	--	--	--	--	CW	.5	0.02	.2	.2	.2	.2	.87
VEHICLE #2	23.6	12.5	134.0	0.0	0.0	90.0	--	--	--	--	--	CW	.02	.02	.2	.2	.2	.2	.87

## MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT						MOMENT ARM	DIRECTION	DIR	VEH. SIZE	VEH. WGT. LBS.	REFERENCE	
	C11	C12	C13	C14	C15	C16							
IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	ROT.	ANG1	VEH. SIZE	VEH. WGT. LBS.	REFERENCE	
VEHICLE #1	75.5	0.5	2.4	3.7	6.9	12.0	16.5	0.0	--	50	1	4621	
VEHICLE #2	118.5	6.75	22.75	23.5	21.3	10.0	0.0	13.7	--	3-	S	3081	

Summary of  
Physical  
Evidence

2-11

EQ-6057-V-6

COLLISION CONFIGURATION 60° Front-to-side impact  
TEST IDENTIFICATION RICSAC Test No. 2 - 1974 Chevrolet Chevelle Vs. 1974 Ford Pinto

Test No. 6 - Front-to-Side Impact - Chevrolet Chevelle Vs.  
VW Rabbit - Impact Speeds, 21.5/21.5 mph  
Accident Schematic - Figure 2-3

The agreement for the predicted impact speeds is good, 24.9 mph versus 21.5 mph actual for Vehicle 1 and 20.5 mph versus 21.5 mph actual for Vehicle 2. There is also close agreement between the predicted  $\Delta V$ 's from the conservation of momentum calculation and the damage analysis for both vehicles. When compared to the actual  $\Delta V$  values, there is good agreement for Vehicle 1, although there is a slight overestimate. A larger overestimation of the  $\Delta V$  is evident for Vehicle 2, but some of this discrepancy is attributable to rotational effects. From Table 1-3, it can be seen that Vehicle 2 has a very large  $r_x$  in combination with high angular velocities. In fact, looking at the yaw rate time history presented in Volume II, it can be seen that Vehicle 2 experienced an angular velocity of at least 180 deg/sec for the last 80 msec (or 40%) of contact. Correcting for this rotation has the effect of drastically increasing the magnitude (but decreasing the value) of both the y-component of the separation velocity and  $\Delta V$ . With an almost negligible change in the x-component ( $r_y$  is small), the result is a higher value in the actual resultant  $\Delta V$  and resultant separation velocity. If the corrected  $\Delta V$  for Vehicle 2 is still less than the CRASH II predictions, it implies, from the point of view of the damage analysis, that the stiffness coefficients are too high for these particular vehicle types and impact configuration.

The separation velocity for Vehicle 1 is in close agreement, 12.9 mph versus 13.3 mph actual although the agreement for Vehicle 2 is not as good, 17.0 mph versus 10.5 mph actual. While this discrepancy will be lessened by including rotational effects in the determination of the separation velocity, much of it stems from the large lateral velocity that is predicted, -15.4 mph compared to -3.2 mph actual. This results from the fact that Vehicle 2 rotated approximately 20 degrees during impact, which the program includes as part of the spin out analysis, i.e., the program assumes that rotation during impact can be neglected such that the impact and separation positions are coincident. Significant amounts of rotation occurring during impact lead to an over-prediction of the lateral velocity during spin out.

## ACCIDENT SCHEMATIC

### VEHICLES:

- No. 1 - 1974 CHEVROLET MALIBU CLASSIC  
 No. 2 - 1975 VOLKSWAGEN RABBIT

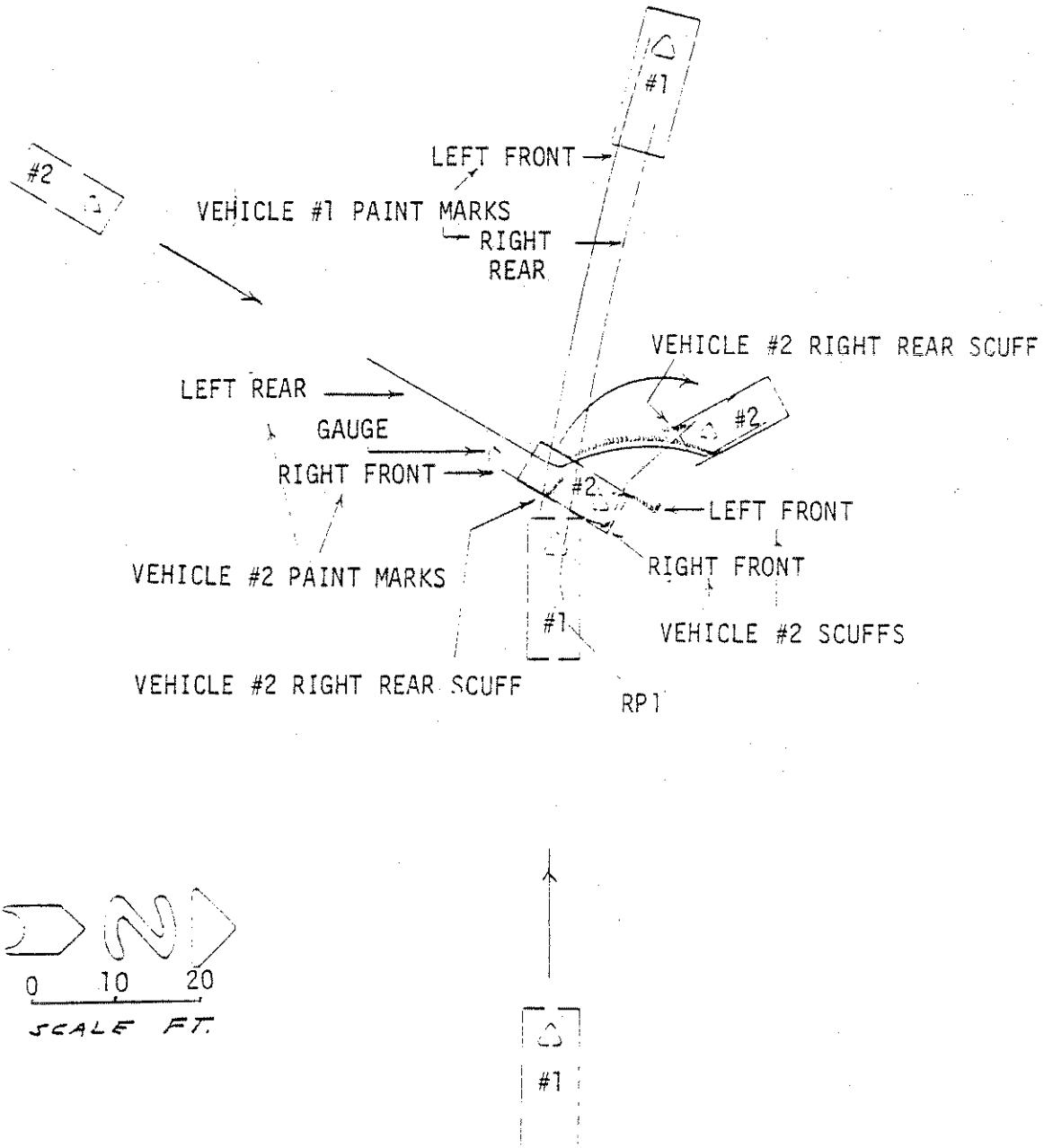


Figure 2-3 TEST NO. 6 - RICSAC ACCIDENT SCHEMATIC

SUMMARY FORM FOR STAGED COLLISION REPORTING

Comparison of Result	MEASURED				SMAC				CRASH			
	SPEED AT IMPACT		$\Delta V$	VDI	SPEED AT IMPACT		$\Delta V$	VDI	SPEED AT IMPACT		$\Delta V$	VDI
	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH
VEHICLE #1	R 9.2 X -8.5 Y 3.0	X 11FZEW1	21.5	X Y	R 10.8 X Y	X Y	X Y	X Y	R 12.4 X -12.2 Y 2.3	R 12.7 X -11.0 Y 6.4	R 20.4 X -13.3 Y -15.4	R 20.9 X -10.4 Y -18.1
VEHICLE #2	R 11.9 X -11.5 Y -3.2	02RDEW3	21.5	X Y	R 16.7 X Y	X Y	X Y	X Y	R 20.5 X Y	R 20.5 X Y	R 20.9 X -10.4 Y -18.1	R 20.9 X -10.4 Y -18.1

VEHICLE #1	REST POSITIONS				IMPACT POSITIONS				END OF ROTATIONAL AND/OR LAT. SKID.			
	X'	Y'	Z'	CR	X'	Y'	Z'	CS	$\psi$	S	C1	$\psi$
	FT.	FT.	DEG.	FT.	FT.	FT.	DEG.	FT.	PR.	DEG.	ROT.	PR.
VEHICLE #1	60.0	11.0	15.0	0.0	0.0	0.0	0.0	--	--	CW	.01	.01
VEHICLE #2	20.0	21.0	242.0	11.1	2.67	120	--	--	--	CW	.01	.01

MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT				MOMENT ARM	DIRECTION	REFERENCE					
	C11	C12	C13	C14								
IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	DEG.	DEG.	DEG.	
VEHICLE #1	54.5	0.5	0.5	1.25	1.5	1.75	2.25	9.75	--	-30	1	4300
VEHICLE #2	77.0	4.0	12.0	17.8	19.3	17.0	8.25	-3.25	--	30	SC	2623

Summary of  
Physical  
Evidence

COLLISION CONFIGURATION    60° Front-to-side impact  
TEST IDENTIFICATION    RICSAC Test No. 6 - Chevrolet Chevelle Vs. VW Rabbit

Test No. 7 - 60° Front-to-Side Impact - Chevrolet Chevelle Vs.

VW Rabbit - Impact Speeds, 39.1/29.1 mph

Accident Schematic - Figure 2-4

The estimated impact speeds for both vehicles are slightly under-estimated although both are within the 12 percent accuracy quoted for the program. The velocity change for Vehicle 1 from the conservation of momentum calculation agrees closely, 11.6 mph versus 12.0 mph actual, although the  $\Delta V$  from the damage analysis, 16.3 mph, is an overestimate. The agreement for Vehicle 2 is not as good, 25.3 mph from conservation of momentum and 35.5 mph from the damage analysis versus 16.5 mph actual. As in Test 6, Vehicle 2 combined a large  $r_x$  component with a large angular velocity; the last 60 msec of contact produced angular velocities in excess of 180 deg/sec. Thus, the magnitude of the y-component of the separation velocity will increase, thereby increasing the magnitude of the  $\Delta V$ 's y-component. As before, a small change in the x-direction results in a larger resultant  $\Delta V$  and separation velocity for Vehicle 2.

It is interesting to note that the velocity change of the struck vehicle is overestimated in both Tests 6 and 7. Since the same model vehicles were used in both tests, this is further evidence that the stiffness coefficient in the program is too high for these vehicles.

The separation velocities are in good agreement, 15.3 mph versus 16.5 mph actual for Vehicle 1 and, despite the rotational effects, 19.6 mph versus 17.2 mph actual for Vehicle 2. Note, however, that the lateral velocity component is again overestimated for Vehicle 2, which results from the significant amount of rotation (22 deg) that occurs during impact, i.e., this is assumed by the program to have occurred during the spin out phase.

## ACCIDENT SCHEMATIC

### VEHICLES:

- No. 1 - 1974 CHEVROLET MALIBU
- No. 2 - 1975 VOLKSWAGEN RABBIT

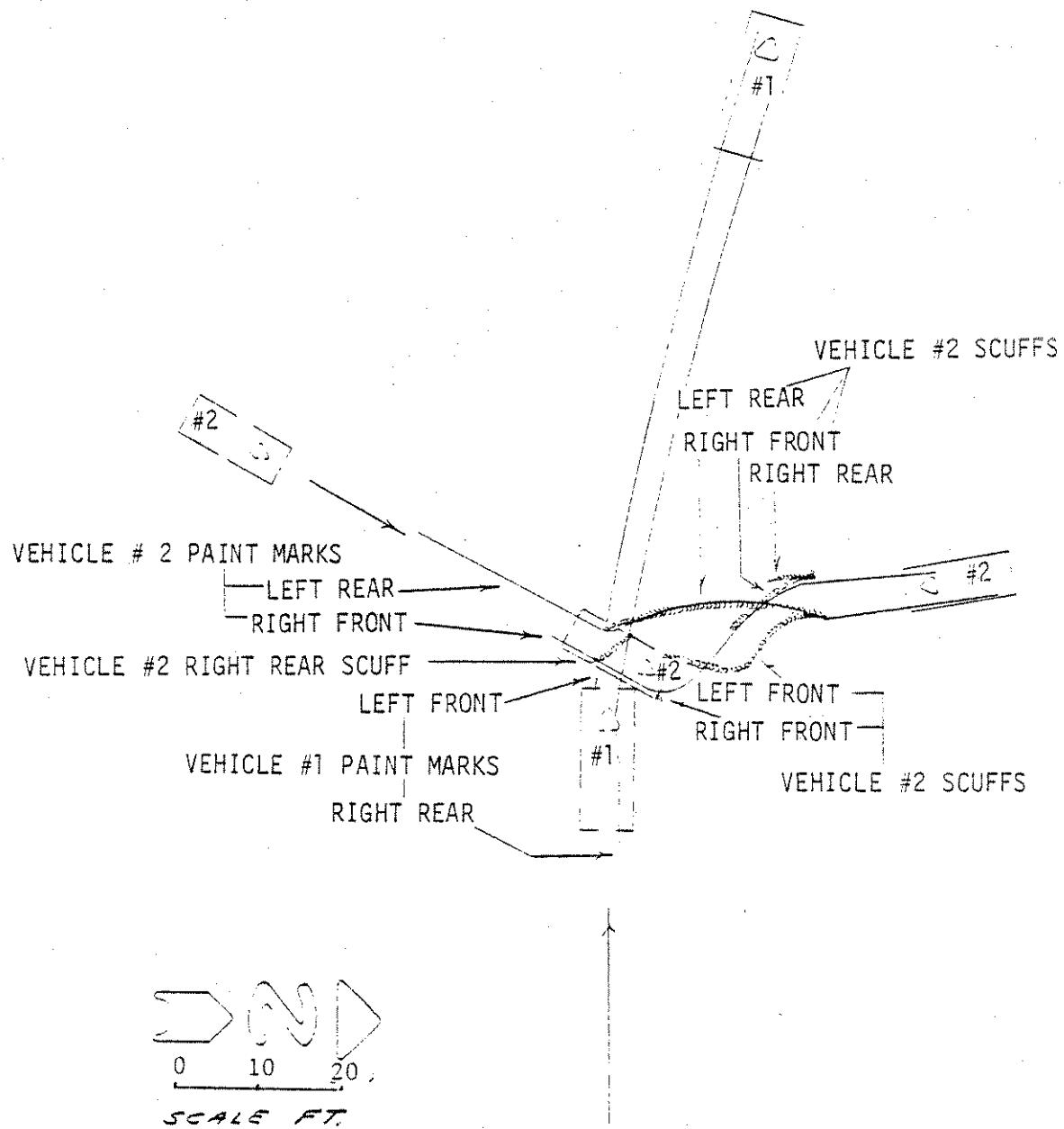


Figure 2-4 TEST NO. 7 - RICSAC ACCIDENT SCHEMATIC

SUMMARY FORM FOR STAGED COLLISION REPORTING

	MEASURED				SMAC				CRASH										
	SPEED AT IMPACT		$\Delta V$	VDI	SPEED AT IMPACT		$\Delta V$	VDI	SPEED AT IMPACT		$\Delta V$	VDI							
	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH							
Comparison of Result	VEHICLE #1		R 12.0 X -11.5 Y -3.5	11FDEW1	29.1	X	X	11FDEW2	26.2	X	11.6 X -11.1 Y -3.2	R 16.3 X -14.1 Y -8.2							
	VEHICLE #2		R 16.5 X -14.1	02RDEW4	29.1	X	X	01RDEW4	27.1	X	25.3 X -18.2 Y -17.5	R 35.5 X -17.8 Y -30.8							
	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -							
Summary of Physical Evidence	REST POSITIONS				IMPACT POSITIONS AND/OR LAT. SKID.				END OF ROTATIONAL										
	X' FT.	Y' FT.	Z' FT.	$\Psi_R$ DEG.	X' CS	Y' CS	Z' CS	$\Psi_S$ DEG.	X' FT.	C1	Y' FT.	C1	$\Psi_1$ DEG.	ROT.	ROT.	ROT.	ROT.	ROLLING RESISTANCE	TYRE PARKMENT
	VEHICLE #1	84.5	18.2	16.5	0.0	0.0	0.0	0.0	--	--	--	--	--	CW	.01	.01	.01	RR	LR
VEHICLE #2	22.9	41.4	262.0	10.7	3.45	120.0	22.0	30.0	250.0	CW	.01	.01	.01	.01	.01	.01	1.0	.2	0.87
MEASURED DAMAGE DIMENSIONS													DIRECTION						
	WIDTH	DAMAGE EXTENT				MOMENT ARM			DIRECTION			VEH. SIZE	VEH. WGT.	REFERENCE					
	L1	C11	C12	C13	C14	C15	C16	DI	IN.	IN.	IN.				DEG.				
VEHICLE #1	66.0	0.0	1.25	2.0	3.75	5.0	6.25	4.0	--	--	-30	I	3700						
VEHICLE #2	108.5	0.0	11.0	17.75	21.0	21.25	7.25	-8.5	--	30	S	1700							

COLLISION CONFIGURATION      60° Front-to-Side Impact  
 TEST IDENTIFICATION      RICSAC Test No. 7 - Chevrolet Chevelle Vs. VW Rabbit

Test No. 8 - 90° Front-to-Side Impact - Chevrolet Chevelle Vs.  
Chevrolet Chevelle - Impact Speeds, 20.75/20.75 mph  
Accident Schematic - Figure 2-5

The estimated impact speeds for both vehicles are in good agreement. Looking at the velocity changes calculated from the conservation of momentum, that for Vehicle 1 is considerably underestimated, 10.3 mph versus 15.3 mph actual; whereas that for Vehicle 2 is slightly underestimated, 9.8 mph versus 10.7 mph actual. This is consistent with an error in the estimation of the separation velocities 14.3 mph versus 11.8 mph actual for Vehicle 1 and 18.8 mph versus 15.7 mph actual for Vehicle 2. Correcting the change in velocity and the separation velocity of Vehicle 1 for the effects of rotation would tend to degrade the degree of agreement between the actual and predicted values. However, the magnitude of the change would be greatly reduced, as compared to Vehicle 2 in both Tests 6 and 7, since the  $r_x$  of Vehicle 1 in this test is only 0.95 feet (versus about 2.5 feet in the other two tests). It is worth noting that the spin out distances for this test were small such that the separation velocities are extremely sensitive to the measured impact and rest positions.

Looking at the velocity changes predicted from the damage analysis, it can be seen that Vehicle 1 is underestimated by about 5 mph, i.e., 10.0 mph versus 15.3 mph actual. Since this is the striking vehicle, this likely results from the fact that the program does not take the effect of energy absorbing bumpers into account. The velocity change for Vehicle 2 is in good agreement, 9.5 mph versus 10.7 mph actual.

ACCIDENT SCHEMATIC

VEHICLES:

No. 1 - 1974 CHEVROLET CHEVELLE

No. 2 - 1974 CHEVROLET CHEVELLE

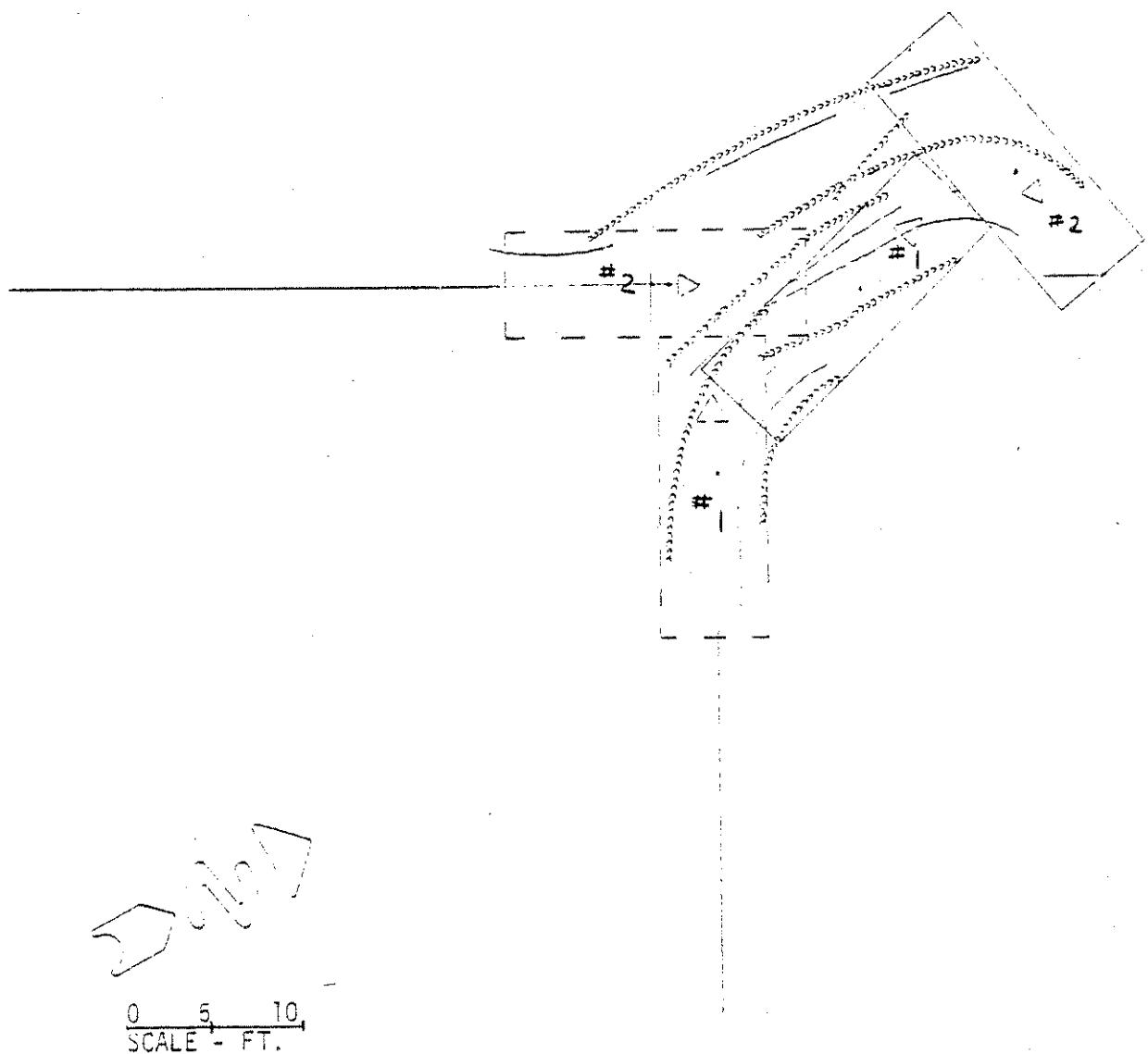


Figure 2-5 TEST NO. 8 - RICSAC ACCIDENT SCHEMATIC

SUMMARY FORM FOR STAGED COLLISION REPORTING

MEASURED		SMAC				CRASH		SPIN II		DAMAGE	
		SPEED AT IMPACT MPH	Δ V MPH	VDI	SPEED AT IMPACT MPH	Δ V MPH	VDI	SPEED AT IMPACT MPH	Δ V MPH	VDI	Δ V MPH
VEHICLE #1	R 15.3	R 16.8	R 10.3	R 10.0	X 12.7	X 7.2	X 7.0	X 7.2	X 7.0	X 7.1	X 7.1
	Y 8.6	Y 12.7	Y 7.5	Y 7.5	12FDEW1	11FDEW2	19.5	Y 7.3	Y 7.3	Y 7.1	Y 7.1
VEHICLE #2	R 10.7	R 15.0	R 9.8	R 9.5	X -7.2	X -6.9	X -6.7	X -6.9	X -6.7	X -6.7	X -6.7
	Y -8.0	Y 20.75	Y 24.5	Y 24.5	03RYEW2	02RD EW3	Y -6.7	Y -6.7	Y -6.7	Y -6.7	Y -6.7

REST POSITIONS		IMPACT POSITIONS AND/OR LAT. SKID.						ROLLING RESISTANCE				TIRE PAVEMENT				
		X' CR	Y' CR	ψ R	X' CS	Y' CS	ψ S	X' C1	Y' C1	ψ 1	ROT. FT.	ROT. RF	LF	RR	LR	H
VEHICLE #1	FT.	FT.	DEG.	FT.	FT.	DEG.	FT.	FT.	DEG.	DEG.	--	--	CW	0.01	0.2	0.2
	-0.5	11.0	46.0	-10.9	3.2	0.0	--	--	--	--	--	--	CW	0.01	0.2	0.2
VEHICLE #2	6.5	21.0	141.0	0.0	1.9	90.0	--	--	--	--	--	--	CW	0.01	0.2	0.2
	--	--	--	--	--	--	--	--	--	--	--	--	CW	0.01	0.2	0.2

MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT				MOMENT ARM	DIRECTION	ANGLE DEG.	RATIO	VEH. SIZE	VEH. WGT. LBS.	REFERENCE
	C11	C12	C13	C14							
VEHICLE #1	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.
	73.0	2.7	3.6	--	--	--	--	0.0	--	--	--
VEHICLE #2	84.5	6.2	8.3	9.2	5.9	4.4	0.8	15.0	45	1	4710

Summary of  
Physical  
Evidence

COLLISION CONFIGURATION 90° Side-to-front impact, Chevrolet Chevelles  
TEST IDENTIFICATION RICSAC Test No. 8

Test No. 9 - 90° Front-to-Side Impact - Honda Civic Vs.  
Ford Torino - Impact Speeds, 21.2/21.2 mph  
Accident Schematic - Figure 2-6

The estimated impact speeds for both vehicles are in good agreement, 23.2 mph versus 21.2 mph actual for Vehicle 1 and 22.0 mph versus 21.2 mph actual for Vehicle 2. The velocity changes predicted from the conservation of linear momentum are also in good agreement, although slightly overestimated; for Vehicle 1, 24.2 mph versus 21.4 mph actual and for Vehicle 2, 11.2 mph versus 8.9 mph actual. The resultant velocity changes from the damage analysis also agree well, 19.1 mph versus 21.4 mph for Vehicle 1 and 8.8 mph versus 8.9 mph for Vehicle 2. The failure to consider the rotation of Vehicle 1 in determining the separation velocity did not appear to adversely affect the agreement between the actual and predicted values of  $\Delta V$ . As demonstrated in Test 8, this is probably due to the fact that the components of the accelerometer offset vector,  $\vec{r}$ , are small, and the corrections, therefore, are also relatively small.

Looking at the separation velocities predicted by SPIN II, the agreement is good, for Vehicle 1, 9.9 mph versus 12.5 mph actual and for Vehicle 2. 20.2 mph versus 17.8 mph actual.

## ACCIDENT SCHEMATIC

### VEHICLES:

No. 1 - 1975 HONDA CIVIC  
No. 2 - 1974 FORD TORINO

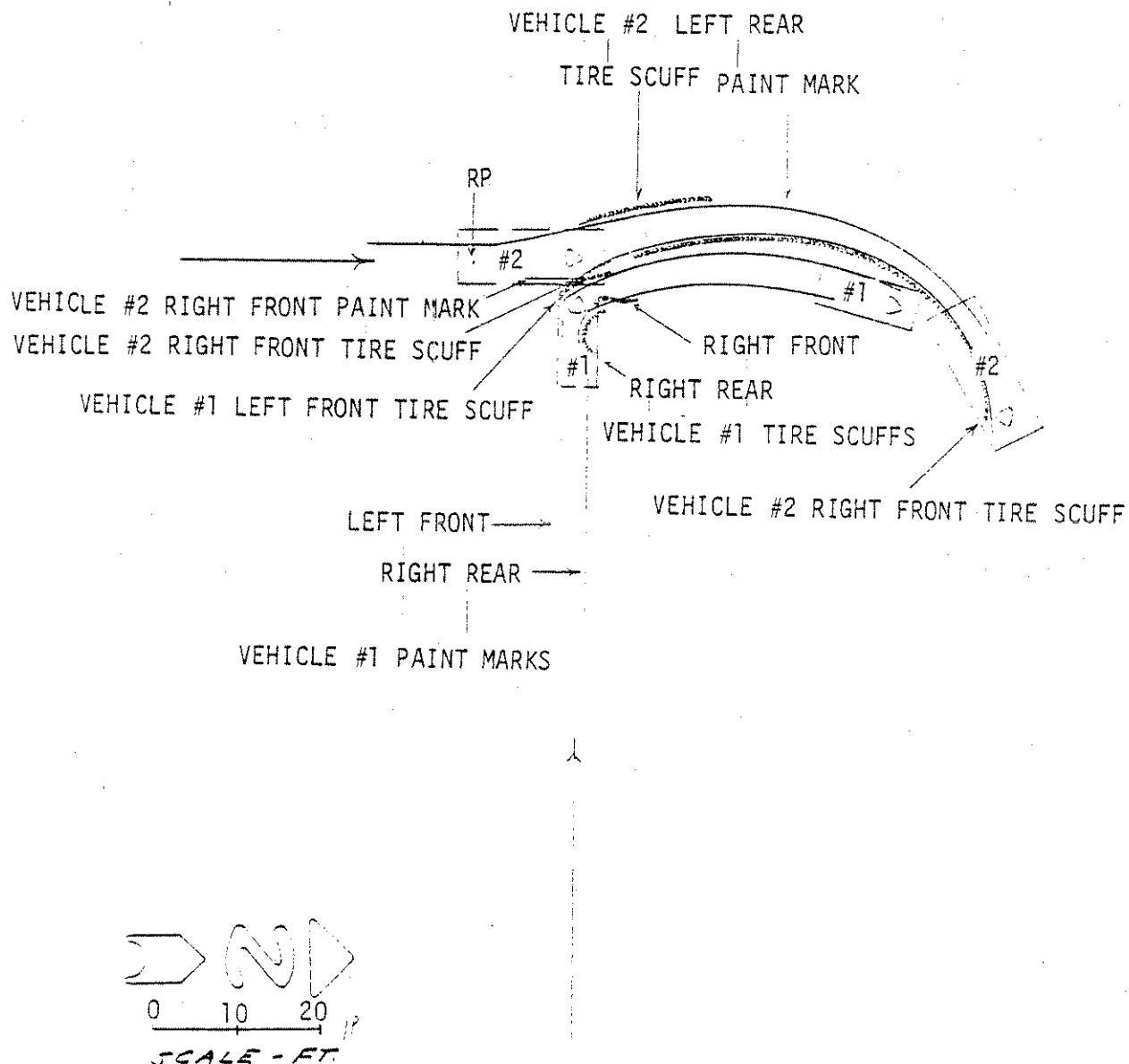


Figure 2-6 TEST NO. 9 - RICSAC ACCIDENT SCHEMATIC

**SUMMARY FORM FOR STAGED COLLISION REPORTING**

Comparison of Results

Summary of  
Physical  
Evidence

ZQ-6057-V-6

Test No. 10 - 90° Front-to-Side Impact - Honda Civic Vs.  
Ford Torino - Impact Speeds, 33.3/33.3 mph  
Accident Schematic - Figure 2-7

The estimated impact speeds are in good agreement for both vehicles, 32.7 mph versus 33.3 mph actual for Vehicle 1 and 31.5 mph versus 33.3 mph actual for Vehicle 2. The velocity changes predicted from the conservation of linear momentum are also in good agreement, 32.6 mph versus 35.1 mph actual for Vehicle 1 and 15.9 mph versus 14.1 mph actual for Vehicle 2. This result is somewhat surprising, since Vehicle 1 underwent the greatest angular velocity of all the vehicles involved in the staged collisions. However, the rotation and location of the accelerometer are such that the magnitude of  $\Delta V_x$  will increase (due to a decrease in the separation velocity) and the magnitude of  $\Delta V_y$  will decrease when the rotational effects are considered. The change in both components will be approximately equal, since the components of the  $\vec{r}$  vector are similar. The effect on the resultant velocity change is shown in Equations (1) through (3).

$$\Delta V = \sqrt{(\Delta V_x - \delta_x)^2 + (\Delta V_y - \delta_y)^2} \quad (1)$$

where  $\delta_x$  is the correction for correction to  $\Delta V_x$  ( $\Delta V_x$  is negative, so an increase in its magnitude is caused by a negative correction term),

$\delta_y$  is the correction for rotation to  $\Delta V_y$

$$\Delta V = \sqrt{\Delta V_x^2 + \Delta V_y^2 + \delta_x^2 + \delta_y^2 - 2\Delta V_x \delta_x - 2\Delta V_y \delta_y} \quad (2)$$

In this case, in which  $\delta_x \approx \delta_y$ ,  $|\Delta V_x| \approx |\Delta V_y|$ , and  $\Delta V_x$  is opposite in sign from  $\Delta V_y$ , Equation (2) can be simplified to:

$$\Delta V = \sqrt{\Delta V_x^2 + \Delta V_y^2 + \delta_x^2 + \delta_y^2} \quad (3)$$

As long as the  $(\delta_x^2 + \delta_y^2)$  term is small relative to  $(\Delta V_x^2 + \Delta V_y^2)$  the resultant velocity will not change appreciably, and for Test 10 the components

of Vehicle 1's computed velocity change are large, i.e., -27.3 mph and 22.0 mph, thus explaining (and confirming) the high degree of correspondence between the predicted and actual resultant  $\Delta V$ 's.

The  $\Delta V$ 's predicted from the damage are underestimated at 22.4 mph for Vehicle 1 and 10.9 mph for Vehicle 2. This suggests that the structural stiffness coefficients in the program are underestimated for this particular vehicle-impact configuration. Note that the same trend was also present in Test 9, which had the same configuration and the same vehicles, i.e., a mini-size vehicle striking an intermediate size vehicle. This is the opposite trend to that exhibited in Tests 6 and 7, where the stiffness coefficients were too high for an intermediate striking a subcompact vehicle.

Looking at the separation velocities, the agreement is extremely good for Vehicle 2, 25.8 mph versus 26.9 mph actual. The agreement for Vehicle 1 is also good, but this may be an artifact of the failure to consider the vehicle's rotation during impact. Inclusion of this factor will decrease both components of the separation velocity, and therefore, the resultant separation velocity. While the magnitude of this change is not known, it is expected to be sufficient to cause the predicted value of the separation velocity to be an overestimate of the actual value. This is based on the fact that the Honda Civic is the smallest vehicle in its size category such that the representative dimensions and vehicle properties in the CRASH II program are probably overestimates.

ACCIDENT SCHEMATIC

VEHICLES:

No. 1 - 1974 HONDA CIVIC  
No. 2 - 1974 FORD TORINO

GRASS FIELD

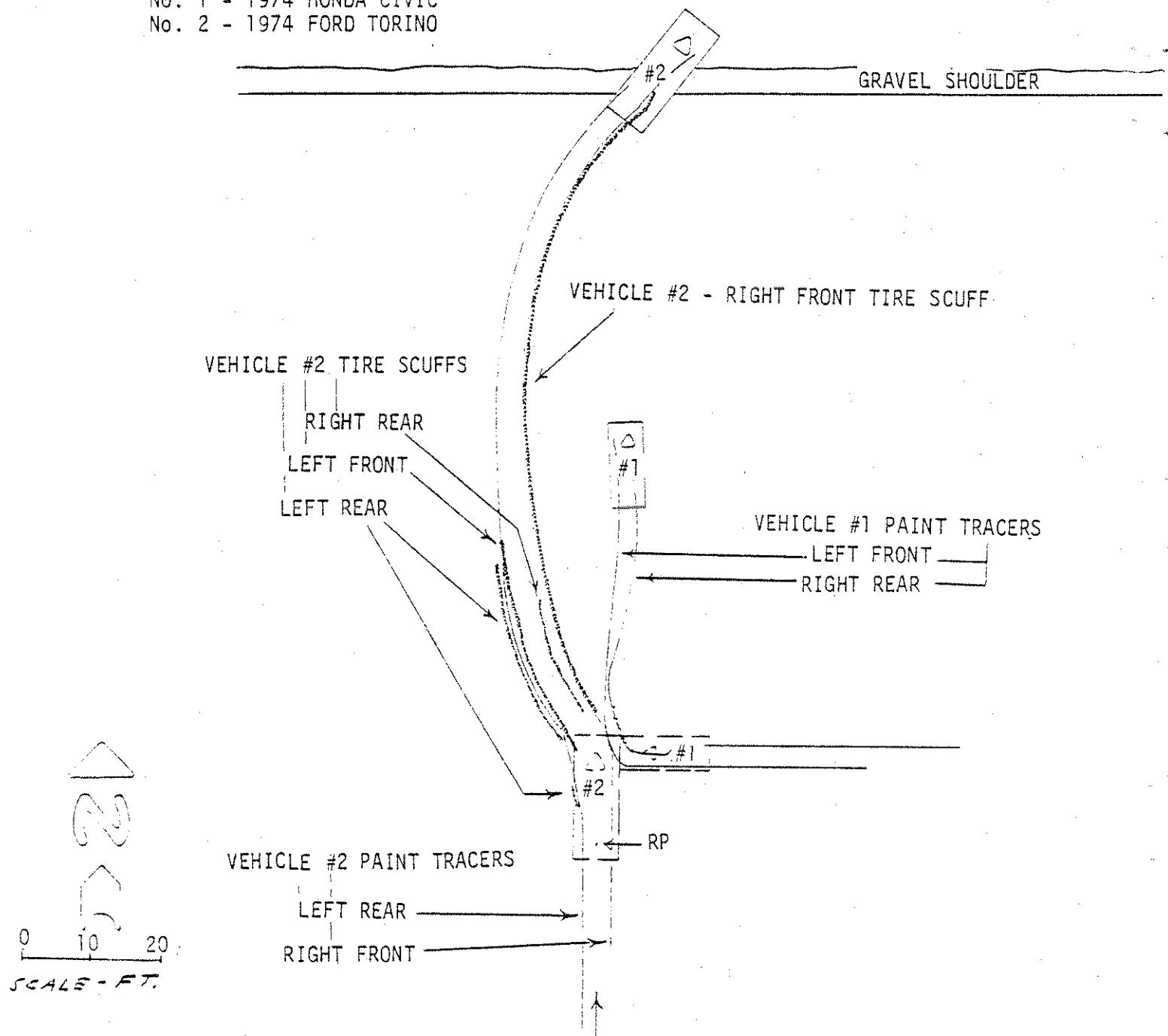


Figure 2-7 TEST NO. 10 - RICSAC ACCIDENT SCHEMATIC

## SUMMARY FORM FOR STAGED COLLISION REPORTING

Comparison of Result	MEASURED				SMAC				CRASH			
	SPEED AT IMPACT	A V	VDI	SPEED AT IMPACT	Δ V	VDI	SPEED AT IMPACT	Δ V	SPIN JI	Δ V	DAMAGE	
	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH
VEHICLE #1	R 35.1 X -27.3 Y 22.0	10FDEW2	33.3	R 36.5 X Y	11LFEW3	32.7	R 32.6 X 26.5 Y 19.0	X -22.4 X -9.4 Y 20.3				
VEHICLE #2	R 14.1 X -8.8 Y -11.0	01RFEW2	33.3	R 15.7 X Y	02RYEW3	31.5	R 15.9 X -9.3 Y -13.0	R 10.9 X -9.9 Y -4.6				
- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -

VEHICLE #1	REST POSITIONS				IMPACT POSITIONS AND/OR LAT. SKID.				END OF ROTATIONAL			
	X'	Y'	Z'	CS	X'	Y'	CS	ψ	X'	Y'	Z'	ψ
	CR	CR	ψ R	ψ R	CR	CS	CS	ψ S	CR	CS	CS	ψ 1
VEHICLE #1	5.0	43.0	87.0	0.0	0.0	0.0	0.0	FT.	FT.	FT.	FT.	ROT.
VEHICLE #2	0.0	99.5	128.5	8.5	-5.9	90.0	23.0	5.0	5.0	25.0	90.0	CW

## Summary of Physical Evidence

## MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT				MOMENT ARM	DIRECTION				REFERENCE	
	C11	C12	C13	C14		C15	C16	DI	ROT		
IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	ANG1	VEL.	
VEHICLE #1	47.5	7.0	10.2	14.0	8.9	7.0	9.0	-2.75	--	-65	MIN
VEHICLE #2	53.0	9.2	6.5	6.1	5.3	4.5	0.5	66.50	--	25	INT

COLLISION CONFIGURATION 90° Front-to-side impact  
TEST IDENTIFICATION RICSAC Test No. 10 - Honda Civic Vs. Ford Torino

Test No. 11 - 10° Offset Front-to-Front Impact - Chevrolet Vega Vs.  
Ford Torino - Impact Speeds, 20.4/20.4 mph  
Accident Schematic - Figure 2-8

The estimated impact speeds are in good agreement although slightly underestimating for both vehicles. The velocity changes agree closely, for Vehicle 1, 21.1 mph versus 24.0 mph actual and for Vehicle 2, 15.2 mph versus 15.7 mph actual. Not surprisingly then, the separation velocities are also in close agreement, -3.8 mph versus -3.7 mph actual for Vehicle 1 and 4.8 mph versus 5.2 mph actual for Vehicle 2.

ACCIDENT SCHEMATIC

RAIL —————

VEHICLES:

No. 1 - 1974 CHEVROLET VEGA  
No. 2 - 1974 FORD GRAN TORINO

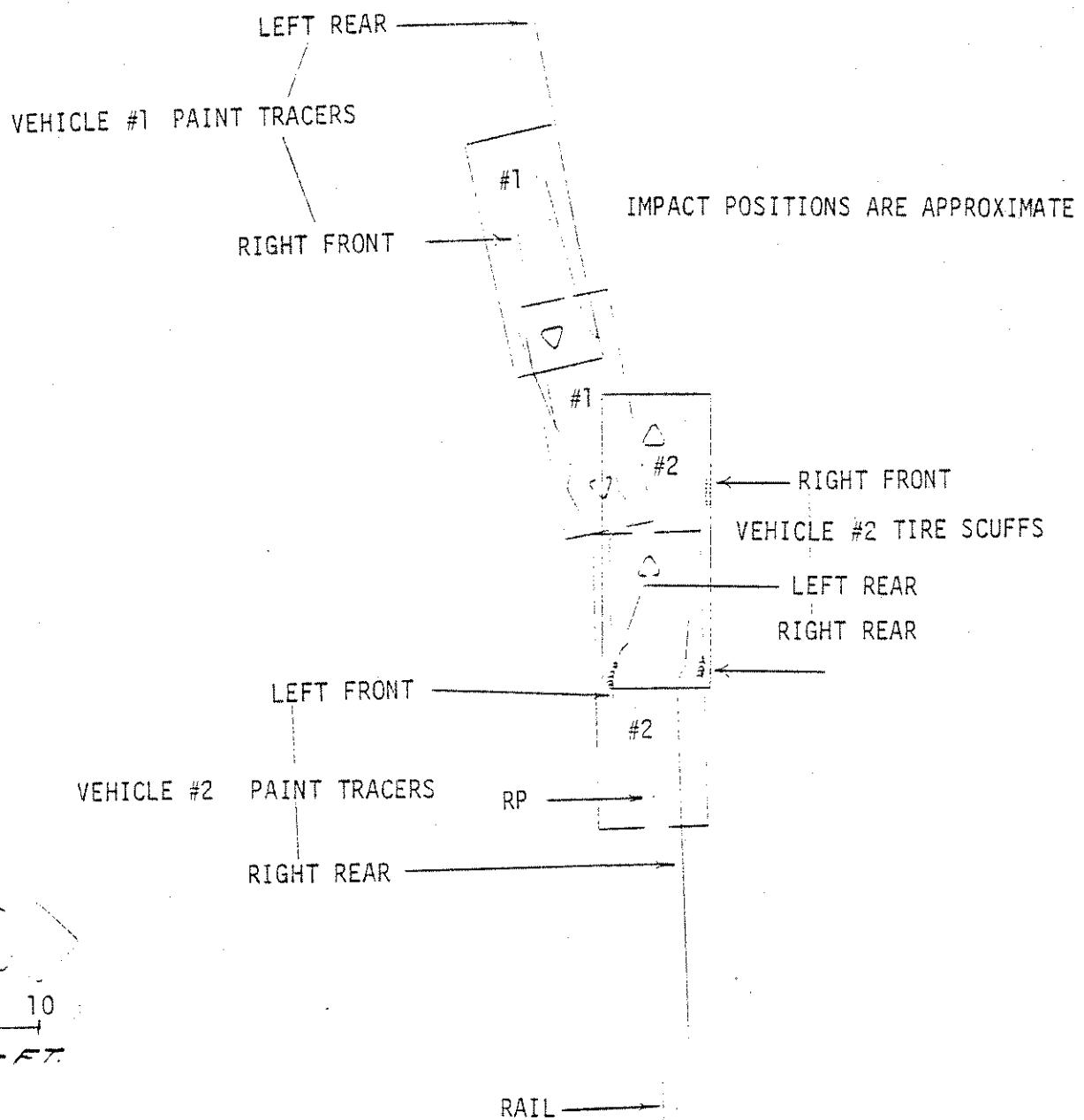


Figure 2-8 TEST NO. 11 - RICSAC ACCIDENT SCHEMATIC

SUMMARY FROM FOR STAGED COLLISION REPORTING

MEASURED	SMAC				CRASH			
	SPEED AT IMPACT		SPEED AT IMPACT		SPEED AT IMPACT		SPIN II	
	SPEED AT IMPACT MPH	Δ V MPH	VDT MPH	Δ V MPH	VDT MPH	Δ V MPH	VDT MPH	Δ V MPH
VEHICLE #1	R 24.0		R 28.7		R 21.0	R 21.1		
	X - 24.0	Y 0.8	12FYEW3	20.4	X 12FYEW3	X - 21.0	X - 21.0	
VEHICLE #2	R 15.7		R 17.6		R 17.2	Y 0.3	Y - 1.8	
	X - 15.6	Y 2.0	12FYEW3	20.4	X 12FYEW2	X - 13.2	X - 13.2	

REST POSITIONS	IMPACT POSITIONS				END OF ROTATIONAL AND/OR LAT. SKID.				TIRE PAVEMENT					
	X' CR	Y' CR	ψ R	X' CS	Y' CS	ψ S	X' C1	Y' C1	ψ 1	ROLLING RESISTANCE	LF	RR	LR	RR
	FT. DEG.	FT. DEG.	FT. DEG.	FT. DEG.	FT. DEG.	FT. DEG.	FT. DEG.	FT. DEG.	FT. DEG.	ROT.	RF	RR	LR	RR
VEHICLE #1	25.6	-6.4	170.0	15.7	-4.0	171.0	--	--	--	CW	.01	.01	.1	.1
	VEHICLE #2	8.6	0.4	0.0	0.0	0.0	--	--	--	CW	.01	.01	.2	.2

MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT				MOMENT ARM	DIRECTION	ANGLE DEG.	VEH. SIZE	VEH. WGT.	LBS.	REFERENCE
	C11 IN.	C12 IN.	C13 IN.	C14 IN.							
VEHICLE #1	32.5	22.0	20.2	18.5	16.8	15.0	12.5	-12.75	--	5	S
VEHICLE #2	32.26	29.5	26.25	23.0	18.7	14.3	11.0	-12.9	--	-5	I

Summary of  
Physical  
Evidence

2-30

COLLISION CONFIGURATION 10° Offset front-to-front  
TEST IDENTIFICATION RICSAC Test No. 11 - Chevrolet Vega Vs. Ford Torino

1Q-6057-V-6

Test No. 12 - 10° Offset Front-to-Front Impact - Chevrolet Vega Vs.  
Ford Torino - Impact Speeds, 31.5/31.5 mph  
Accident Schematic - Figure 2-9

This test is identical in configuration to Test 11 except that the impact speeds are higher. The impact velocity for Vehicle 1 is considerably underestimated, 19.8 mph versus 31.5 mph actual. The separation velocity appears to be in good agreement, -8.5 mph versus -8.7 mph actual. However, this agreement may be degraded somewhat with the inclusion of rotational effects, which tend to decrease the magnitudes of both components of the separation velocity. Consequently, the magnitude of the resultant separation velocity will also be decreased; the amount of this change is not known, but it should not be sufficiently large to have any significant effect on the degree of correspondence with the predicted value of the separation velocity. The rotation would also tend to slightly decrease the measured velocity change of 40.1 mph. There is, however, little reason to believe that this correction would noticeably improve the agreement with the predicted  $\Delta V$  of 28.2 mph.

The predicted impact velocity for Vehicle 2 is in good agreement, 30.2 mph versus 31.5 mph actual. Note, however, that this results from the errors in the velocity change and the separation velocity cancelling one another; the velocity change is underestimated at 20.0 mph versus 26.4 mph actual and the separation velocity overestimated at 11.6 mph versus 7.3 mph actual.

Since Test 11 used the same model vehicles and the agreement between the  $\Delta V$ 's was good, this suggests that vehicles colliding at higher closing speeds could present a higher structural stiffness. Obviously, to change the stiffness to improve the fit for this case would degrade the fit obtained for Test 11.

ACCIDENT SCHEMATIC

VEHICLES:

No. 1 - 1974 CHEVROLET VEGA  
No. 2 - 1974 FORD TORINO

LEFT REAR PAINT TRACER  
VEHICLE #1 RIGHT FRONT PAINT TRACER

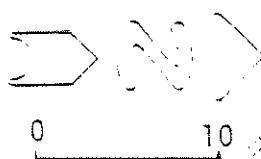
IMPACT POSITION IS APPROXIMATED

GAUGES

VEHICLE #1 RIGHT FRONT TIRE SCUFF

VEHICLE #2 LEFT REAR TIRE SCUFF

VEHICLE #2 LEFT FRONT PAINT TRACER  
RIGHT REAR PAINT TRACER



RAIL →

Figure 2-9 TEST NO. 12 - RICSAC ACCIDENT SCHEMATIC

SUMMARY FORM FOR STAGED COLLISION REPORTING

Comparison of Result	MEASURED				SMAC				CRASH			
	SPEED AT IMPACT		$\Delta V$	VDT	SPEED AT IMPACT		$\Delta V$	VDT	SPEED AT IMPACT		$\Delta V$	DAMAGE
	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH	MPH
VEHICLE #1	R 40.1 X -40.0 Y -2.2	12FDEW4	31.5	X Y	R 40.9 X Y	12FDEW4	31.5	R 40.9 X Y	R 28.2 X -28.1 Y -1.6	R 28.2 X -28.1 Y -2.5	R 28.2 X -28.1 Y -1.6	
VEHICLE #2	R 26.4 X -26.0 Y 4.8	12FYEW4	31.5	X Y	R 27.6 X Y	12LFEW3	31.5	R 27.6 X Y	R 20.0 X -19.5 Y 4.6	R 19.6 X -19.5 Y 1.7	R 20.0 X -19.5 Y 4.6	
- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -

VEHICLE #1	REST POSITIONS				IMPACT POSITIONS				END OF ROTATIONAL AND/OR LAT. SKID.			
	X' GR	Y' GR	Z' CS	Y' CS	$\psi$ R	$\psi$ R	$\psi$ S	$\psi$ C1	X' C1	Y' C1	$\psi$ 1	ROT.
	FT. FT.	FT. DEG.	FT. FT.	FT. DEG.	FT. FT.	FT. DEG.	FT. FT.	FT. DEG.	FT. FT.	FT. DEG.	ROT.	ROT.
VEHICLE #1	22.3 -5.5	118.0 15.7	15.7 -4.0	171.0 --	-- --	-- --	-- --	-- --	-- --	-- --	CW .01	0.01 .2
VEHICLE #2	6.8 2.6	-12.0 0.0	0.0 0.0	0.0 --	-- --	-- --	-- --	-- --	-- --	-- --	CW .01	0.01 .2
- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -

MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT				MOMENT ARM	DIRECTION	VEH. MGT. SIZE	VEH. MGT. SIZE	REFERENCE	
	C11	C12	C13	C14	C15	C16	DT	ROT	ANG1	
IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	
VEHICLE #1	32.0	38.6	34.6	29.5	26.0	19.6	4.25	+2.75	5	SC
VEHICLE #2	28.25	39.5	33.0	28.75	23.75	19.2	15.0	-10.6	-5	I
- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -
2-33	Summary of Physical Evidence	EQ-6057-V-6	Ford Torino	RICSAC Test No. 12 - Chevrolet Vega Vs.	10° Offset - front-to-front	COLLISION CONFIGURATION	TEST IDENTIFICATION			

Test Nos. 3, 4 and 5 - 10° Offset Front-to-Rear Impacts

Accident Schematics - Figures 2-10, 2-11 & 2-12

The results of these tests are discussed jointly since they all suffer from the same deficiency. It can be seen from Table 2-1 that the predicted impact speeds do not agree closely with the actual values. Table 2-2 shows that the separation velocities predicted by SPIN II are in extremely close agreement for all three tests so that the source of error lies in the estimation of the velocity change. Since these are axial type impact configurations, the velocity changes are estimated using the damage analysis. In every case, the velocity change is severely underestimated as can be seen from the summary table below. This must stem from the fact that the test vehicles were all fitted with 5 mph energy absorbing bumpers which are not taken into account in the stiffness coefficients in the CRASH II program.

Test No.	Velocity Change; Vehicle 1		Velocity Change; Vehicle 2	
	Actual (mph)	Predicted (mph)	Actual (mph)	Predicted (mph)
3	9.5	3.1	15.8	5.4
4	18.7	10.3	22.2	13.0
5	16.3	8.1	25.1	15.2

This means that the stiffness coefficients used to calculate the energy absorbed in rear end impacts are too low. Adding 5 mph to each  $\Delta V$  improves the agreement, although the  $\Delta V$ 's are still underestimates which leads to the conclusion that vehicles with 5 mph energy absorbing bumpers are also stiffer than earlier models without.

## ACCIDENT SCHEMATIC

### VEHICLES:

No. 1 - 1974 FORD TORINO

No. 2 - 1974 FORD PINTO

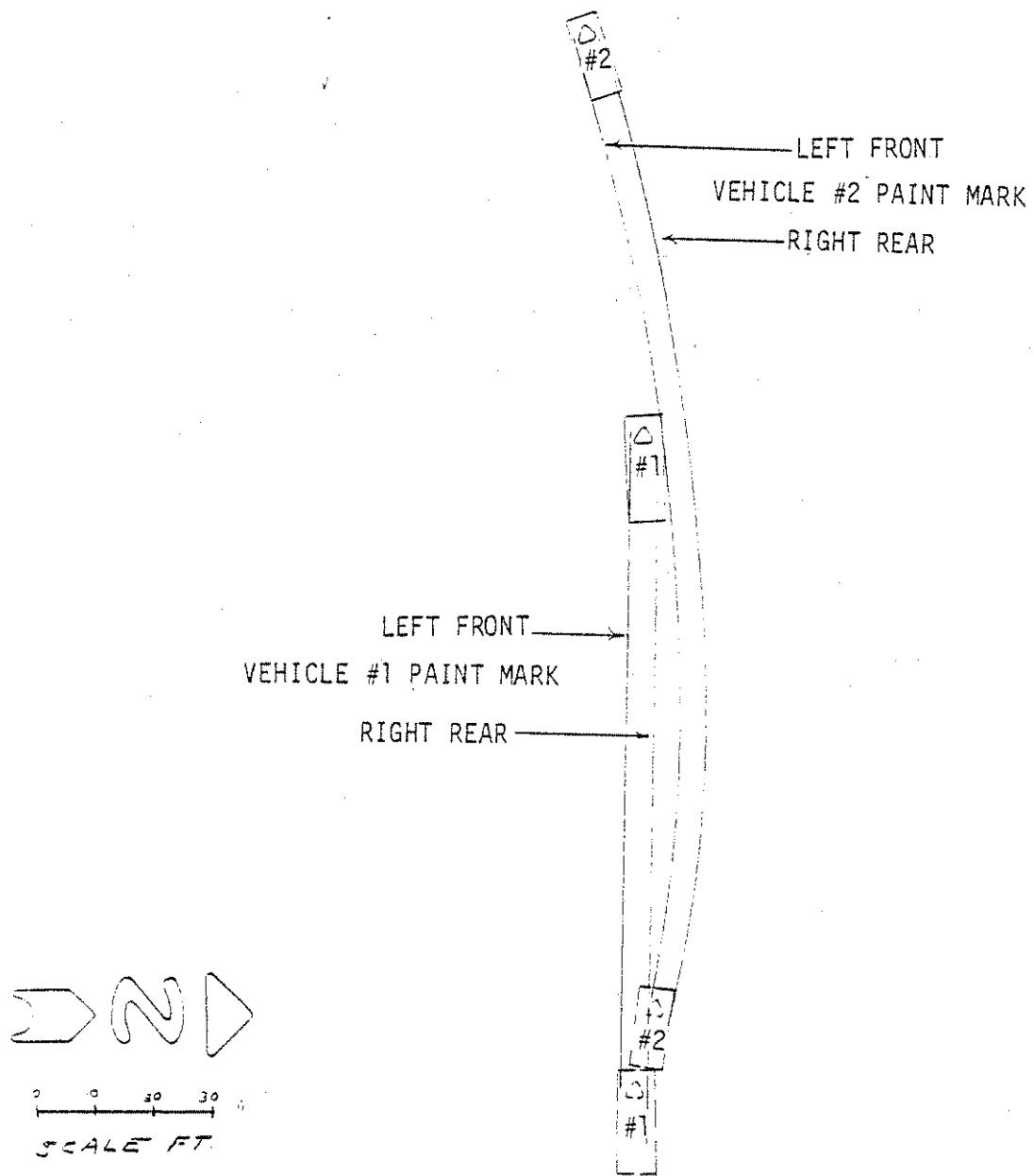


Figure 2-10 TEST NO. 3 - RICSAC ACCIDENT SCHEMATIC

## ACCIDENT SCHEMATIC

### VEHICLES:

- No. 1 - 1974 FORD TORINO  
No. 2 - 1974 FORD PINTO

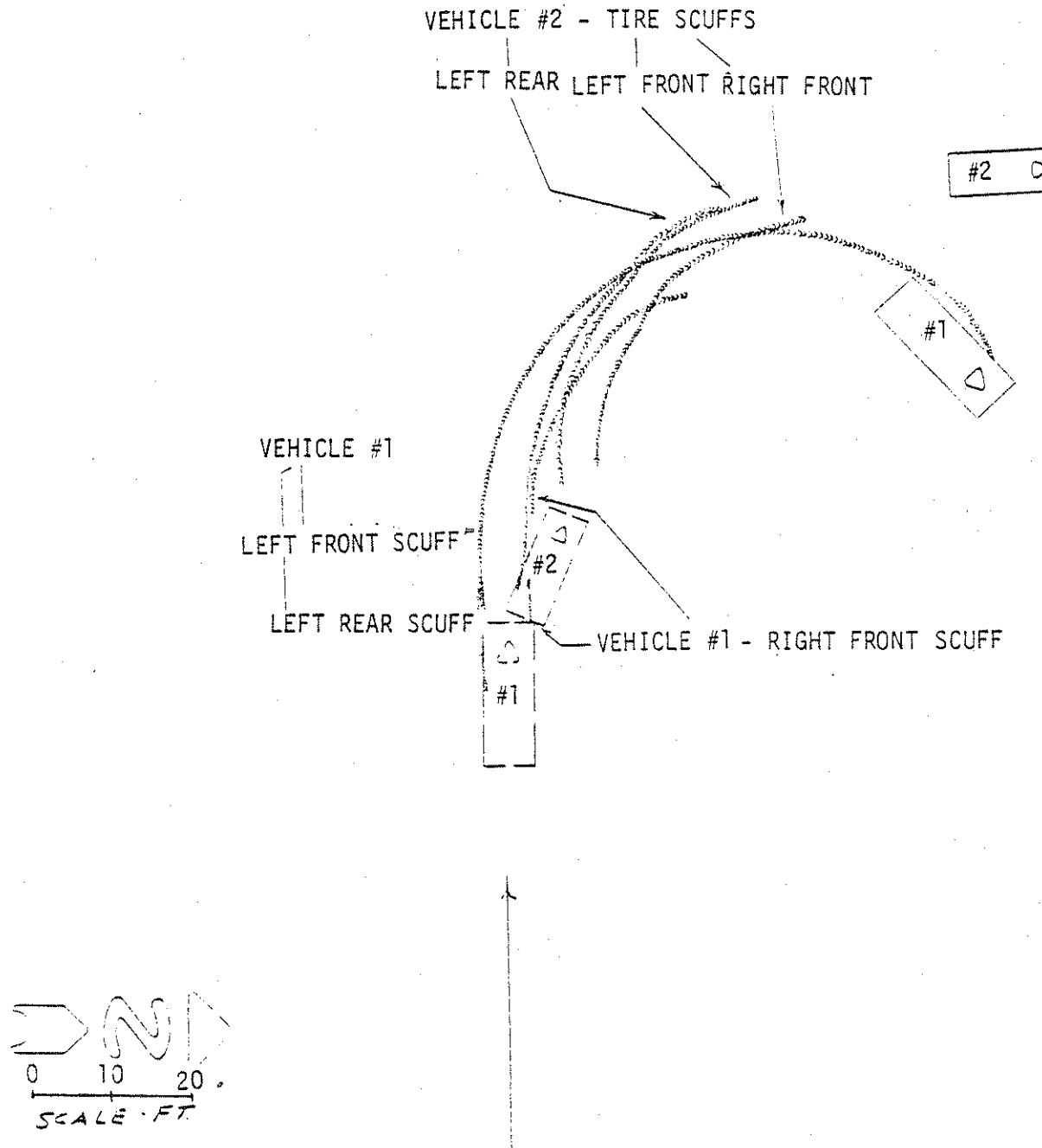


Figure 2-11 TEST NO. 4 - RICSAC ACCIDENT SCHEMATIC

# ACCIDENT SCHEMATIC

## VEHICLES:

No. 1 - 1974 FORD TORINO  
No. 2 - 1975 HONDA CIVIC CVCC

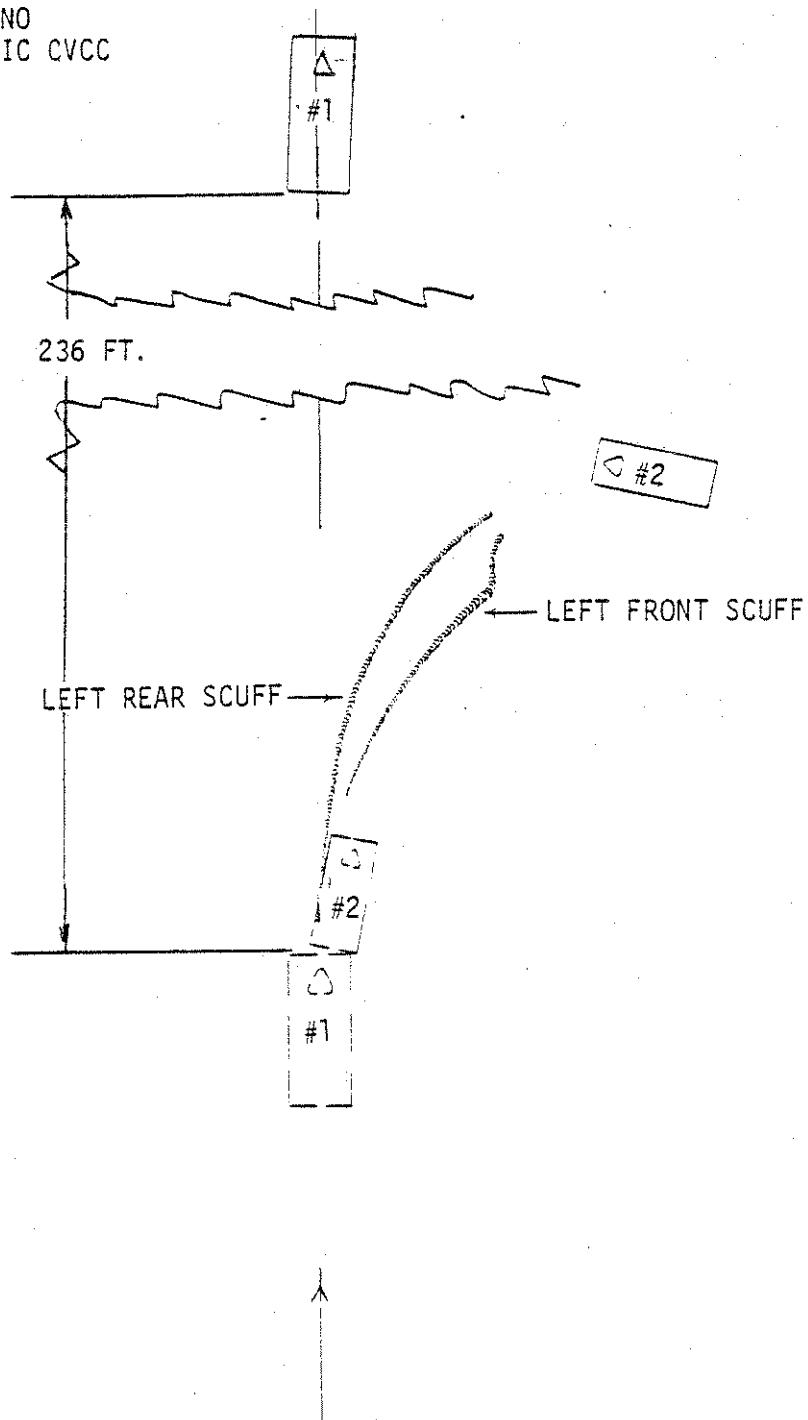


Figure 2-12 TEST NO. 5 - RICSAC ACCIDENT SCHEMATIC

SUMMARY FORM FOR STAGGER COLLISION REPORTING

Comparison of Result	MEASURED			SMAC			CRASH		
	SPEED AT IMPACT MPH	Δ V MPH	WDT	SPEED AT IMPACT MPH	Δ V MPH	WDT	SPEED AT IMPACT MPH	Δ V MPH	DAMAGE
VEHICLE #1	R 9.5 X -9.5 Y -0.4	12FZEW1	21.2	X Y	9.6	:	R 3.1 X -3.1 Y 0.2	R 3.1 X -3.1 Y 0.0	R 3.1 X -3.1 Y 0.0
VEHICLE #2	R 15.8 X 15.8 Y -0.2	06BZEW1	0.0	X Y	15.6	12FZEW2	15.2		
- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -

VEHICLE #1	REST POSITIONS			IMPACT POSITIONS AND/OR LAT. SKID			END OF ROTATIONAL		
	X' CR	Y' CR	Φ R	X' CS	Y' CS	Ψ S	X' CI	Y' CI	Φ 1
VEHICLE #1	111.4	2.0	-4.0	0.0	0.0	0.0	0.0	0.0	0.0
VEHICLE #2	181.5	-6.4	-19.0	15.0	2.2	10.0	--	--	--

VEHICLE #1	VEHICLE #2	MEASURED DAMAGE DIMENSIONS			DIRECTION			TIRE PAYMENT			
		WIDTH	DAMAGE EXTENT			MOMENT AREA	ROT.	ROLL.	ROT.	ROLL.	TIRE PAYMENT
VEHICLE #1	30.0	IN.	C11	C12	C13	C14	C15	C16	DEG.	DEG.	REFERENCE
VEHICLE #2	30.0	2.0	IN.	IN.	IN.	IN.	IN.	IN.	--	--	
- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	- - - - -	

2-38 Summary of Physical Evidence

HQ-6057-V-6

COLLISION CONFIGURATION      10° Offset front-to-rear impact  
TEST IDENTIFICATION      RICSAC Test No. 3 - Ford Torino Vs. Ford Pinto

## SUMMARY FORM FOR STAGED COLLISION REPORTING

	MEASURED	SMAC				CRASH			
		SPEED AT IMPACT MPH	Δ V MPH	VDI	SPEED AT IMPACT MPH	Δ V MPH	VDI	SPEED AT IMPACT MPH	Δ V MPH
Comparison of Result	VEHICLE #1	R 18.7 X -18.7 Y 0.4	12FZEW3	X Y	R 16.7 X Y	12RFEW2	X Y	R 10.3 X -9.1 Y 4.9	R 9.1 X -9.1 Y 0.0
	VEHICLE #2	R 22.2 X 22.2 Y -2.8	05BYEW5	X Y	R 26.2 X Y	06BDEW4	X Y	R 13.0 X 12.2 Y -4.4	R 14.1 X 12.2 Y -7.1

	REST POSITIONS	IMPACT POSITIONS				END OF ROTATIONAL SKID.				TIRE PAVEMENT						
		X' CR	Y' GR	Ψ R	X' CS	Y' CS	ψ S	X' CL	Y' CL	ψ L	ROT.	WF	LF	RR	LR	μ
	FT.	FT.	DEG.	FT.	FT.	DEG.	FT.	FT.	FT.	DEG.						
	VEHICLE #1	42.8	54.5	137.5	0.0	0.0	1.0	20.0	5.0	10.0	CW	0.01	0.01	0.2	0.2	
	VEHICLE #2	63.9	62.5	88.0	16.4	3.4	10.0	35.0	2.0	10.0	CW	0.01	0.01	0.2	0.2	0.87

## MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT				MOMENT ARM	DIRECTION	ANGLE DEG.	RATIO	WEIGHT LBS.	VEH. SIZE	WEIGHT LBS.	REFERENCE
	C11	C12	C13	C14								
IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.	IN.
VEHICLE #1	41.5	6.3	7.8	9.8	12.5	14.8	18.3	16.1	--	0	1	4980
VEHICLE #2	41.8	36.0	31.8	29.0	24.0	19.5	14.8	-9.1	--	170	S	3190

Summary of Physical Evidence

COLLISION CONFIGURATION 10° Offset - front-to-rear

TEST IDENTIFICATION RICSAC

Test No. 4 - Ford Torino vs. Ford Pinto

SUMMARY FORM FOR STAGED COLLISION REPORTING

Comparison of Result	MEASURED				SMAC				CRASH			
	SPEED AT IMPACT		IMPACT MPH		SPEED AT IMPACT MPH		Δ V MPH		SPEED AT IMPACT MPH		Δ V MPH	
	A V MPH	VDI MPH	A V MPH	VDI MPH	A V MPH	VDI MPH	A V MPH	VDI MPH	A V MPH	VDI MPH	A V MPH	VDI MPH
VEHICLE #1	R 16.3	X - 16.3	R 15.1	X	R 8.1	X	-8.1	X	R 8.1	X	-8.1	X
VEHICLE #2	Y 0.2	12FZEW1	X	Y	12RFEW2	Y	33.8	Y	0.0	Y	0.0	Y

VEHICLE #1	REST POSITIONS				IMPACT POSITIONS AND/OR LAT. SKID.				END OF ROTATIONAL. TIRE PAVEMENT			
	X'	Y'	Z'	CS	X'	Y'	Z'	CS	ψ	S	ψ	1
	CR	CR	ψ	R	FT.	FT.	DEG.	FT.	FT.	DEG.	ROT.	μ
VEHICLE #1	241.6	0.0	3.0	0.0	0.0	0.0	--	--	--	--	.01	.01
VEHICLE #2	56.9	39.0	282.0	14.9	3.4	10.0	55.0	23.0	260.0	CW	.2	.2

MEASURED DAMAGE DIMENSIONS

WIDTH	DAMAGE EXTENT				ROTATION ARM	DIRECTION	VEH. ANGL. DEG.	VEH. SIZE IN.	VEH. MGT. LBS.	REVERENCE
	L1	C11	C12	C13						
VEHICLE #1	33.5	1.4	1.4	2.0	IN.	IN.	IN.	IN.	IN.	RICSAC
VEHICLE #2	53.0	36.0	36.5	31.5	23.0	13.3	6.0	-1.6	--	4600
									M	2530

COLLISION CONFIGURATION 10° Offset - front-to-rear  
TEST IDENTIFICATION RICSAC Test No. 5 - Ford Torino Vs. Honda Civic

\* Trajectory and Damage.

### 3.0 DISCUSSION OF THE SMAC RECONSTRUCTION RESULTS

Unlike the CRASH II program where the impact speeds, as well as velocity changes are predicted, the SMAC program requires the impact speeds to be specified as part of the input such that the predicted velocity changes, final rest positions, and damage profiles are the key elements with which to assess the reconstruction of a given case. By way of summary, Table 3-1 gives the SMAC predicted and actual velocity changes for each vehicle for each test. As an approximate means of comparing the damage profile, the predicted and actual values of the vehicle damage indices are also given. The table shows that the agreement between predicted and actual velocity changes is extremely good; the largest errors being, 4.7 mph for Vehicle 1 in case 11, 4.4 mph for Vehicle 2 in case 1, and 4.3 mph for Vehicle 2 in case 8. Note that none of these are vehicles which experienced significant rotation during impact. Similarly, the vehicle damage indices show no major discrepancies and, in general, are restricted to minor differences in the clock direction of force (columns 1 and 2) the specific horizontal area (column 3) and the extent of damage (column 7).

Summarizing the reconstruction task, in terms of obtaining a good fit to the measured data, the  $60^\circ$  front-to-side impacts were by far the most difficult configurations to reconstruct. This appears to result from the assumption in the SMAC program that the vehicle is an isotropic homogeneous body such that its stiffness is equal in all directions. In a  $60^\circ$  front-to-side impact the corner of the striking vehicle deforms radially producing deformation across the front and along the side of the vehicle. This has the effect that the onset of the collision interface on the struck vehicle is not steep enough (because, in effect, there is no corner on the striking vehicle to dig in) such that the deformation produced in the struck vehicle is too shallow. This makes it difficult to obtain an acceptable match of vehicle rest positions in these impact configurations. However, despite the limitation, it is important to note that the effect on the velocity change is extremely small, i.e., although matching the rest positions of the vehicles is very sensitive to the impact positions and indirectly to the development

TABLE 3-1

VELOCITY CHANGES AND VEHICLE DAMAGE INDICES  
PREDICTED BY SMAC COMPARED TO MEASURED VALUES

Test No.	Impact Configuration	Size	Impact Speed	Velocity Change		Vehicle Damage Index	
				Actual	SMAC	Actual	SMAC
1	60° Front-to-Side	I	19.8	12.2	14.2	2.0	11FZEW2
		S	19.8	15.6	20.0	4.4	01RDEW3
2	60° Front-to-Side	I	31.5	19.6	21.3	1.7	11FDEW3
		SC	31.5	--	31.7	-	02RDEW4
6	60° Front-to-Side	I	21.5	9.2	10.8	1.6	11FZEW1
		SC	21.5	11.9	16.7	4.8	02RDEW3
7	60° Front-to-Side	I	29.1	12.0	11.3	-0.7	11FDEW1
		SC	29.1	16.5	17.3	0.8	02RDEW4
8	90° Front-to-Side	I	20.75	15.3	16.8	1.5	12FDEW2
		I	20.75	10.7	15.0	4.5	03RYEW2
9	90° Front-to-Side	M	21.2	21.4	20.0	-1.4	11FDEW2
		I	21.2	8.9	8.7	-0.2	02RFEW2
10	90° Front-to-Side	M	33.3	35.1	36.5	1.4	10FDEW2
		I	33.3	14.1	15.7	1.6	01RFEW2
11	10° Offset Front-to-Front	SC	20.4	24.0	28.7	4.7	12FYEW3
		I	20.4	15.7	17.6	1.9	12FYEW3
12	10° Offset Front-to-Front	SC	31.5	40.1	40.9	0.8	12FDEW4
		I	31.5	26.4	27.6	1.2	12FIEW4
3	10° Offset Front-to-Rear	I	21.2	9.5	9.6	0.1	12FEEW1
		SC	0.0	15.8	15.6	-0.2	06BZEW1
4	10° Offset Front-to-Rear	I	38.7	18.7	16.7	-2.0	12FZEW3
		SC	0.0	22.2	26.2	4.0	05BYEW5
5	10° Offset Front-to-Rear	I	39.7	16.3	15.1	-1.2	12FZEW1
		M	0.0	25.1	26.8	1.7	05BDEW2

of the correct collision interface the fine tuning that is required to produce such a match has only a small effect on the velocity changes that are predicted. Another limitation that was experienced with the SMAC program was in cases where vehicle roll or pitch was sufficient to unweight one or two of a vehicle's wheels. The SMAC program does not simulate weight transfer effects and assumes that the weight is equally distributed on either side of the vehicle such that the maximum tire force (whether side or circumferential) that the SMAC program will allow for any one side of the vehicle is  $\mu \frac{W}{2}$ . This means that even if the cornering stiffnesses and torques on one side of the vehicle are set to zero to simulate the airborne wheels, the forces on the two remaining wheels will not necessarily be realistic. Based on the films and recorded data of the front-to-side impacts, there does appear to be significant weight transfer effects in collisions between intermediate and subcompact vehicles, such that simulation of these effects would improve the utility of the program in reconstructing these impact configurations.

A discussion of the individual cases follows. Note that for each case, a summary table is provided giving the predicted and measured rest positions and velocity changes, a graphic display of the reconstruction and a figure showing the predicted and measured damage profiles. The input values used in each case are given in Appendix 3.

### 3.1 Discussion of Individual Cases

Test No. 1 - 60° Front-to-Side Impact - Chevrolet Chevelle Vs. Ford Pinto - Impact Speeds, 19.8/19.8 mph

	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	-1.0	5.4	-1.5	12.2	8.5	7.8	105	15.6
SMAC	-0.1	5.7	1.3	14.2	8.6	9.4	104	20.0

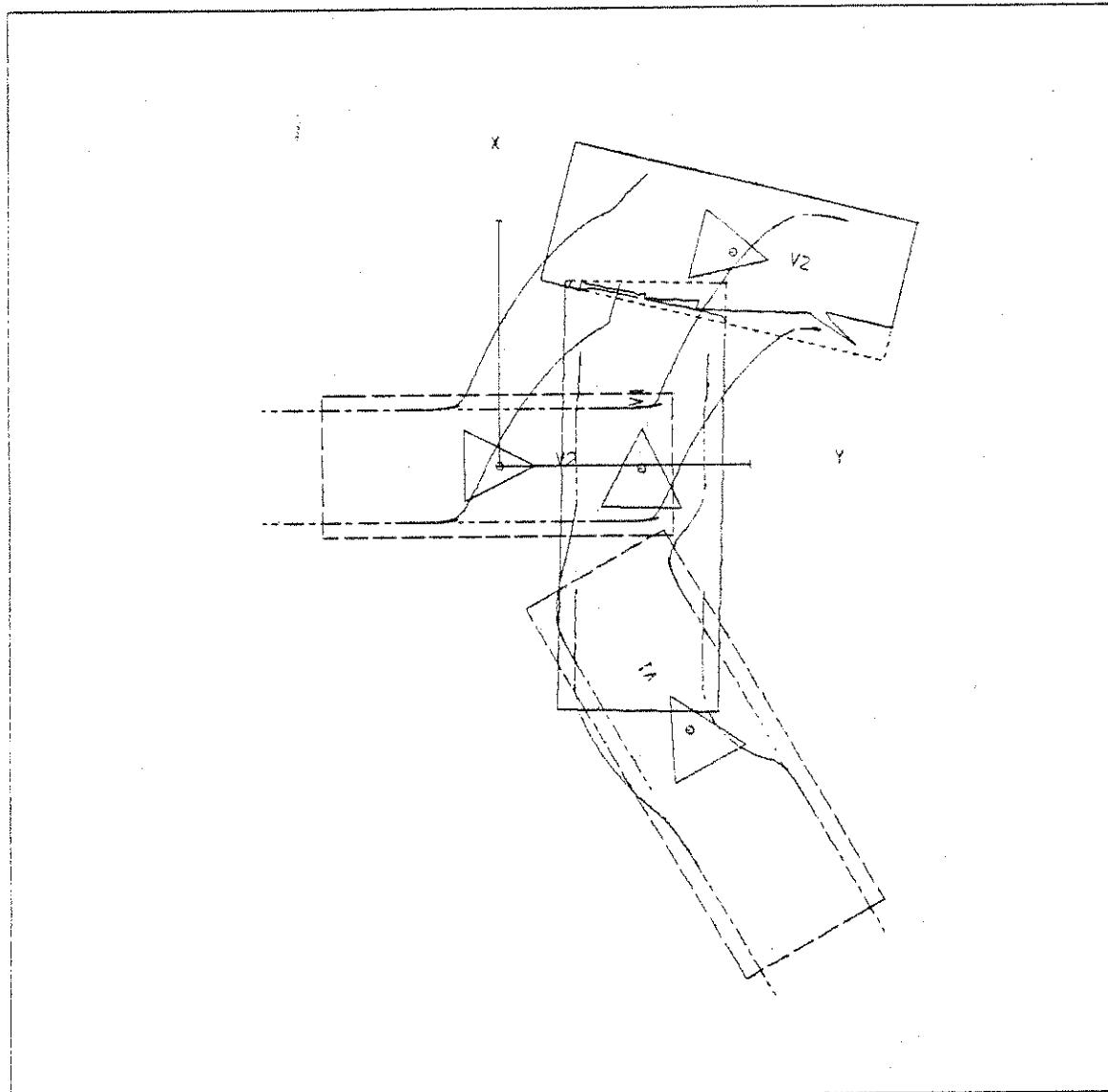
The match between the predicted and measured rest positions is extremely good, although the velocity changes (14.2 mph versus 12.2 mph actual and 20.0 mph versus 15.6 mph actual) are slightly overestimated, particularly for Vehicle 2 (the struck vehicle). This suggests that the engagement of the two vehicles was marginally too long. This is confirmed by looking at the predicted damage which is shown in Figure 3-2. The damage to Vehicle 1 is slightly overpredicted although it is worth noting that the Chevelle was fitted with a 5 mph energy absorbing bumper such that the actual structure was probably more elastic than the one simulated. The predicted damage to Vehicle 2 continues 66 inches to the rear of the car compared to 35 inches actual. However, the damage from 35 to 66 inches results from a secondary impact between the two vehicles which occurred in the simulation, which would have been prevented if the yaw velocity of Vehicle 1 had been marginally larger.

In achieving the match, twelve runs in all were made. The main problem was restricting the Y displacement (space fixed coordinates) of Vehicle 2. This was accomplished by increasing the intervehicle friction coefficient which had the effect of increasing the amount of engagement between the two vehicles and hence reducing the displacement of Vehicle 2. Perhaps surprisingly, the value used to obtain a match was 1.5 after successively increasing it from 0.55. The stiffnesses of the two vehicles were also varied to try and accomplish the same result, however, increasing Vehicle 1's stiffness to 60 lb/in<sup>2</sup> and reducing Vehicle 2's to 30 lb/in<sup>2</sup> produced too much damage to the struck vehicle and too much rotation.

## GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION

## COLLISION AND TRAJECTORY

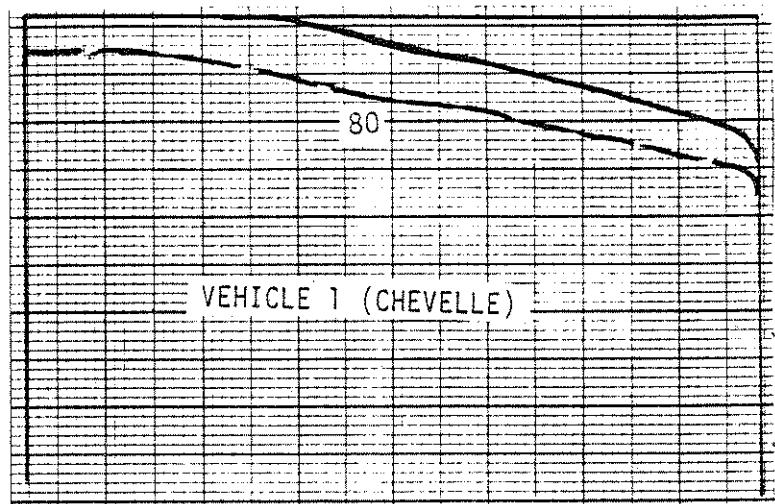
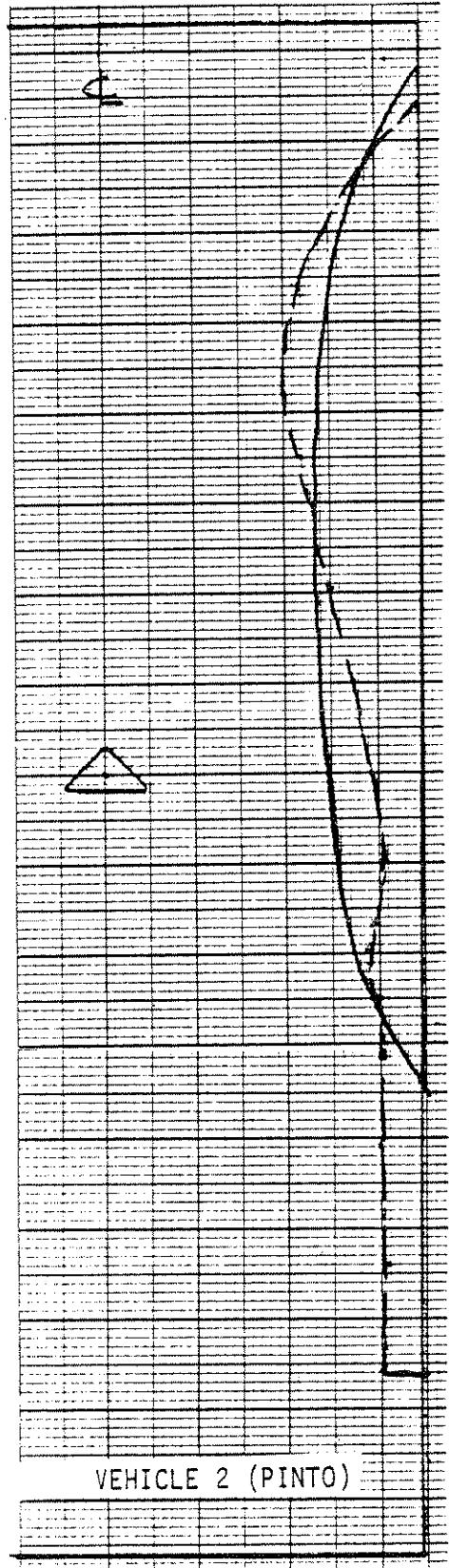
\*RICSA TEST #1 \*



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH
C.G. POSITION		HEADING				C.G. POSITION	HEADING				
XG1	YG1	PSI1	FWD	LATERAL	ANGULAR	XG1F	YG1F	PSI1F			
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.			
VEHICLE # 1	-10.8	7.6	-30.0	19.7	0.0	0.0	-0.1	5.7	1.3	1 2 F D E W 3	14.2
VEHICLE # 2	0.0	0.0	90.0	19.2	0.0	0.0	8.6	9.4	104.0	0 3 R D E W 3	20.0

Figure 3-1 GRAPHIC DISPLAY, TEST NO. 1



— Actual  
- - - Predicted

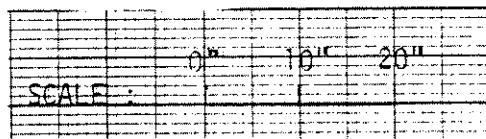


Figure 3-2 TEST NO. 1 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 2 - 60° Front-to-Side Impact - Chevrolet Chevelle Vs.  
Ford Pinto - Impact Speeds, 31.5/31.5 mph

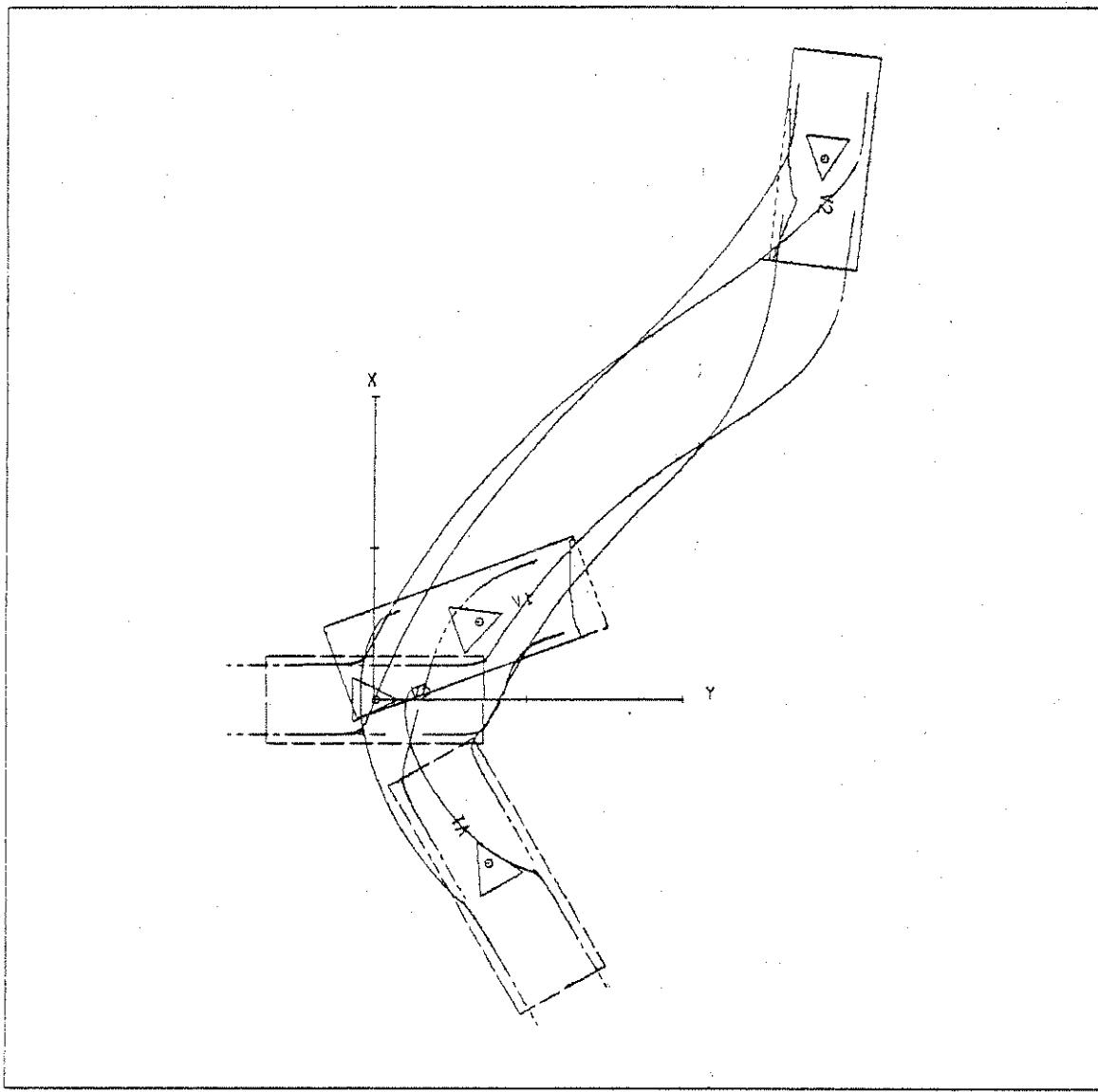
	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	11.0	9.4	55.0	19.6	23.6	12.5	134.0	--
SMAC Computed	5.1	6.9	69.8	21.5	35.7	29.3	186.6	31.2

This case proved extremely difficult to reconstruct. Analysis of the films showed that after the primary impact, a secondary impact occurred which had the effect of halting the rotation of Vehicle 2. This secondary impact is also evident in the schematic since the vehicles actually came to rest in contact with one another. Unfortunately, it was not possible within the time available to simulate the second impact; thus the rotation and displacement of Vehicle 2 are overestimated. The second impact appears not to occur because the damage to Vehicle 1 is overestimated such that the front of this vehicle clears the right front corner of Vehicle 2. The extent of engagement is probably correct because the predicted velocity change for this vehicle is in good agreement, 21.5 mph versus 19.6 mph actual. As discussed in the CRASH II results of this test, the inclusion of rotational effects would produce little change in the resultant value of ΔV. That for Vehicle 2 could not be compared since the velocity change was not recorded due to malfunction of the recording equipment.

The damage profiles are shown in Figure 3-4. As has already been stated, Vehicle 1's damage is overestimated although that for Vehicle 2 is underestimating. Looking at the actual damage to Vehicle 2, it is clear that the right front corner of Vehicle 1 pocketed just ahead of the right rear wheel of Vehicle 2. Unfortunately, this effect cannot be realistically simulated with the present version of SMAC.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION  
COLLISION AND TRAJECTORY

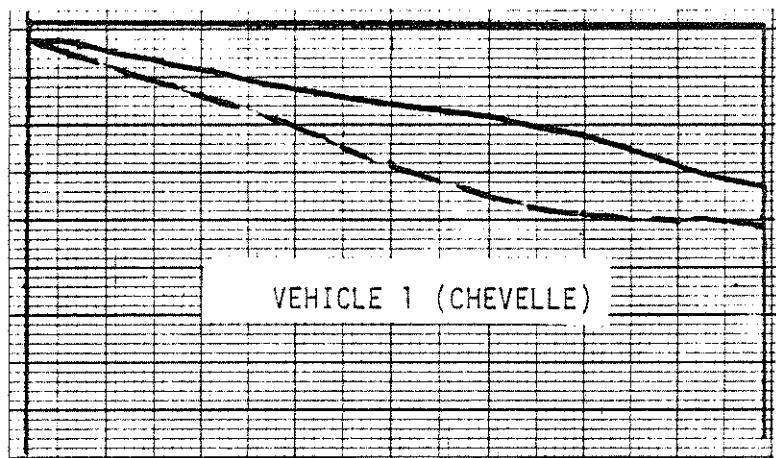
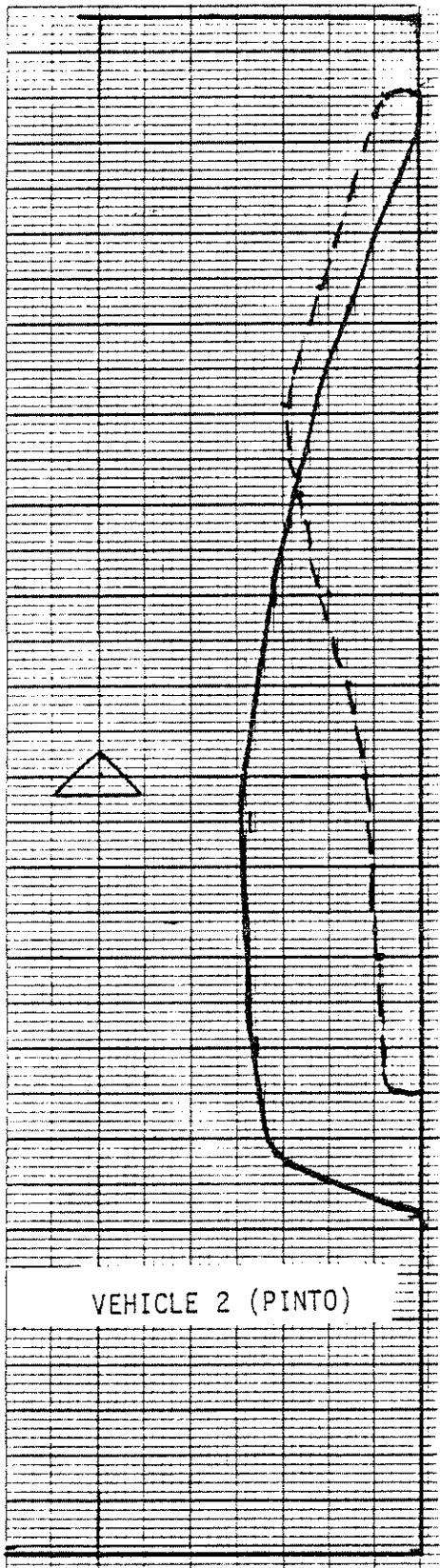
\* RICSAC TEST #2 CHEVELLE-PINTO 31.5MPH \*



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT							DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
	C.G. POSITION		HEADING				C.G. POSITION		HEADING					
	X <sub>C1</sub>	Y <sub>C1</sub>	PSI <sub>1</sub>	FWD	LATERAL	ANGULAR	X <sub>C1F</sub>	Y <sub>C1F</sub>	PSI <sub>1F</sub>					
	FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.					
VEHICLE # 1	-10.3	7.6	-29.9	31.5	-0.0	1.9	5.1	6.9	69.8	VEHICLE AT REST	L1 F D E W 2	21.5		
VEHICLE # 2	-0.0	0.1	90.1	31.2	-0.1	2.9	35.7	29.3	186.6	VEHICLE AT REST	O 3 R Y E W 3	31.2		

Figure 3-3 GRAPHIC DISPLAY, TEST NO. 2



— Actual  
- - - Predicted

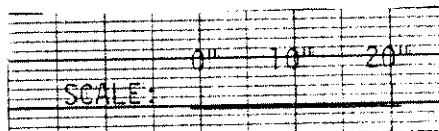


Figure 3-4 TEST NO. 2 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 6 - 60° Front-to-Side Impact - Chevrolet Chevelle Vs.  
VW Rabbit - Impact Speeds, 21.5/21.5 mph

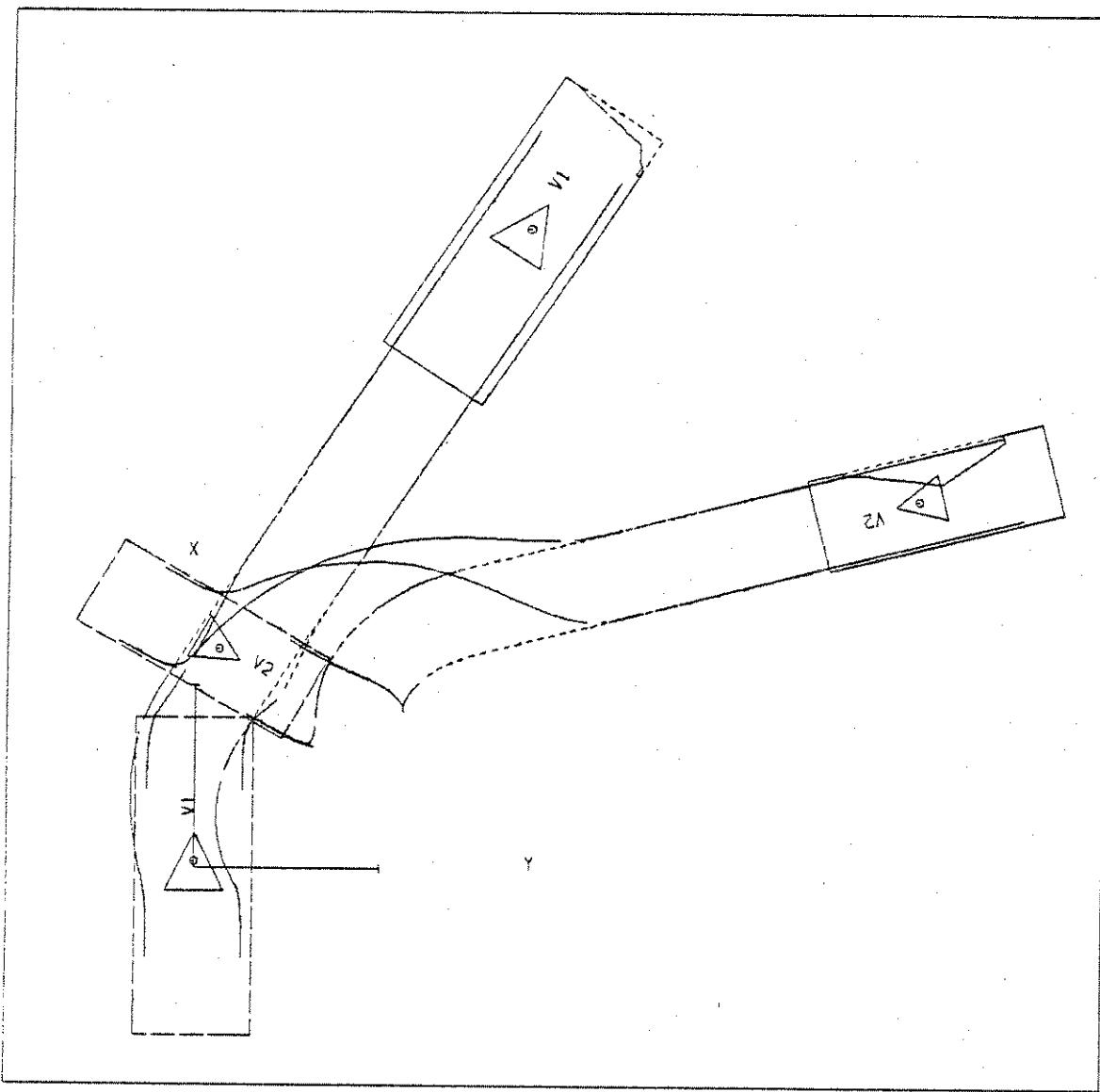
	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	60.0	11.0	15.0	9.2	20.0	21.0	242.0	11.9
SMAC	35.1	17.8	33.3	10.8	20.3	38.8	255.6	16.8
Computed								

To obtain an acceptable reconstruction for this case proved to be very difficult. The problem was in producing a steep enough onset to the damage in Vehicle 2. This can be seen from Figure 3-6; the damage in the struck vehicle built up at a shallower angle than the actual damage. This has the effect of increasing the duration of the frictional force between the two vehicles and producing too much rotation in the striking vehicle, 33.3 degrees versus 15.0 degrees actual. However, if the point of impact is moved rearward to try and compensate, this produces too much rotation in Vehicle 2 and also insufficient lateral displacement. Thus, the extent of vehicle-to-vehicle engagement is probably correct. This is confirmed, in part, by the fact that the velocity change predicted for Vehicle 1 is in close agreement with the measured value, 10.8 mph versus 9.9 mph actual. While the correspondence is not nearly as striking for Vehicle 2, it should be remembered that in Section 2, it was shown that the computed value of Vehicle 2's ΔV was, in fact, a relatively large underestimate (because of the large  $r_x$  component) of the vehicle's actual velocity change. This should improve the agreement substantially and lend further support to the extent of vehicle engagement used in the simulation.

Note that the damage to Vehicle 1 is overpredicted partially due to the effect of the 5 mph bumper but also due to the fact that the program neglects corner stiffness effects. It can be seen from the damage profile the simulation produces lateral deformation at the corner which does not occur in the actual test. If this type of deformation could be prevented by the introduction of corner stiffness effects, it would not only improve the damage match for the striking vehicle but should also increase the angle of damage onset in the struck vehicle.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION  
COLLISION AND TRAJECTORY

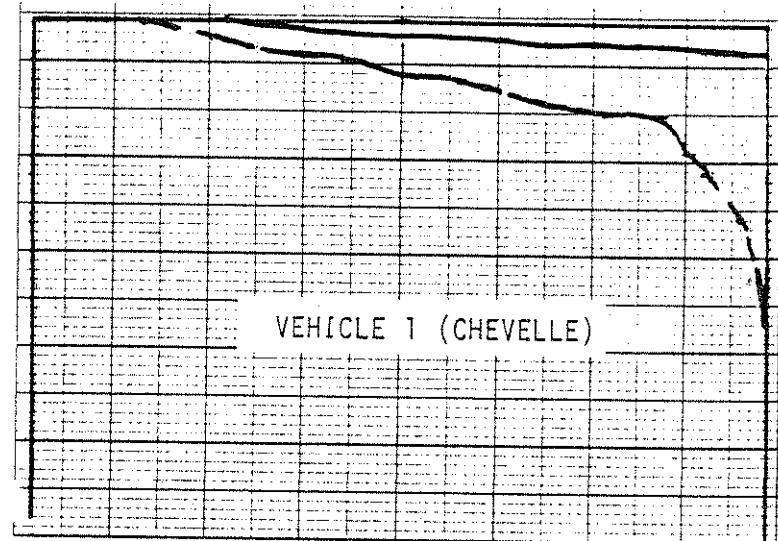
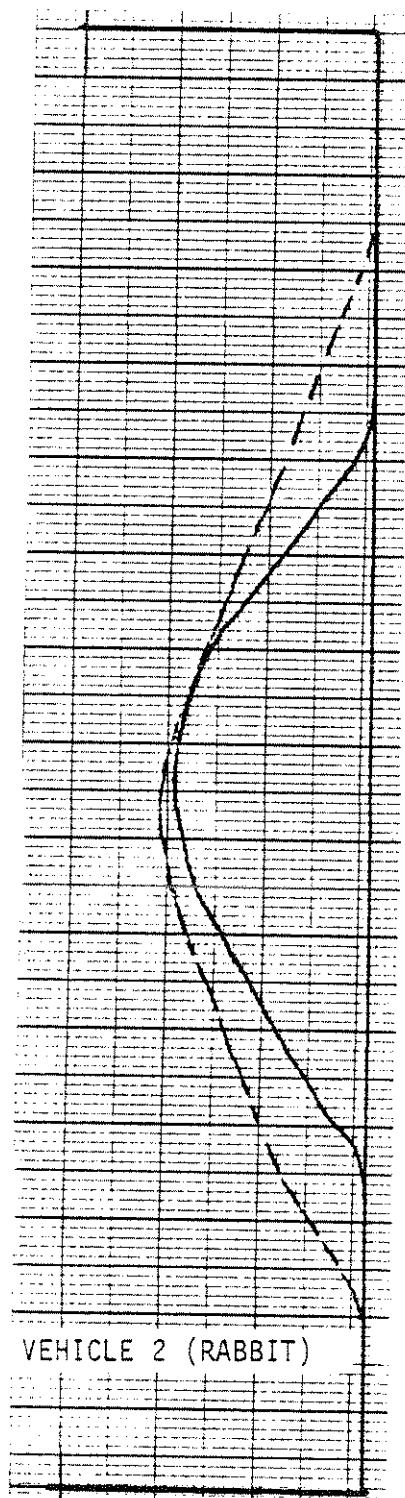
\*\*\* TEST #6 CHEVELLE VS RABBIT \*\*\*



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT							DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
C.G. POSITION		HEADING					C.G. POSITION		HEADING					
XC1	YC1	PSII	FWD	LATERAL	ANGULAR	XC1F	YC1F	PSIIF						
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.						
VEHICLE # 1	0.3	0.0	0.0	21.5	0.0	0.0	35.1	17.8	33.3	IN MOTION AT 4.0 SEC AFTER INITIAL CONTACT	12 F DEW 3	10.8		
VEHICLE # 2	12.0	1.3	120.0	21.4	0.0	0.0	20.3	38.8	255.6	VEHICLE AT REST	0 1 R DEW S	16.8		

Figure 3-5 GRAPHIC DISPLAY, TEST NO. 6



— Actual  
- - - Predicted

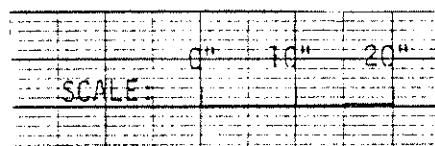


Figure 3-6 TEST NO. 6 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 7 - 60° Front-to-Side Impact - Chevrolet Chevelle Vs.  
VW Rabbit - Impact Speeds, 29.1/29.1 mph

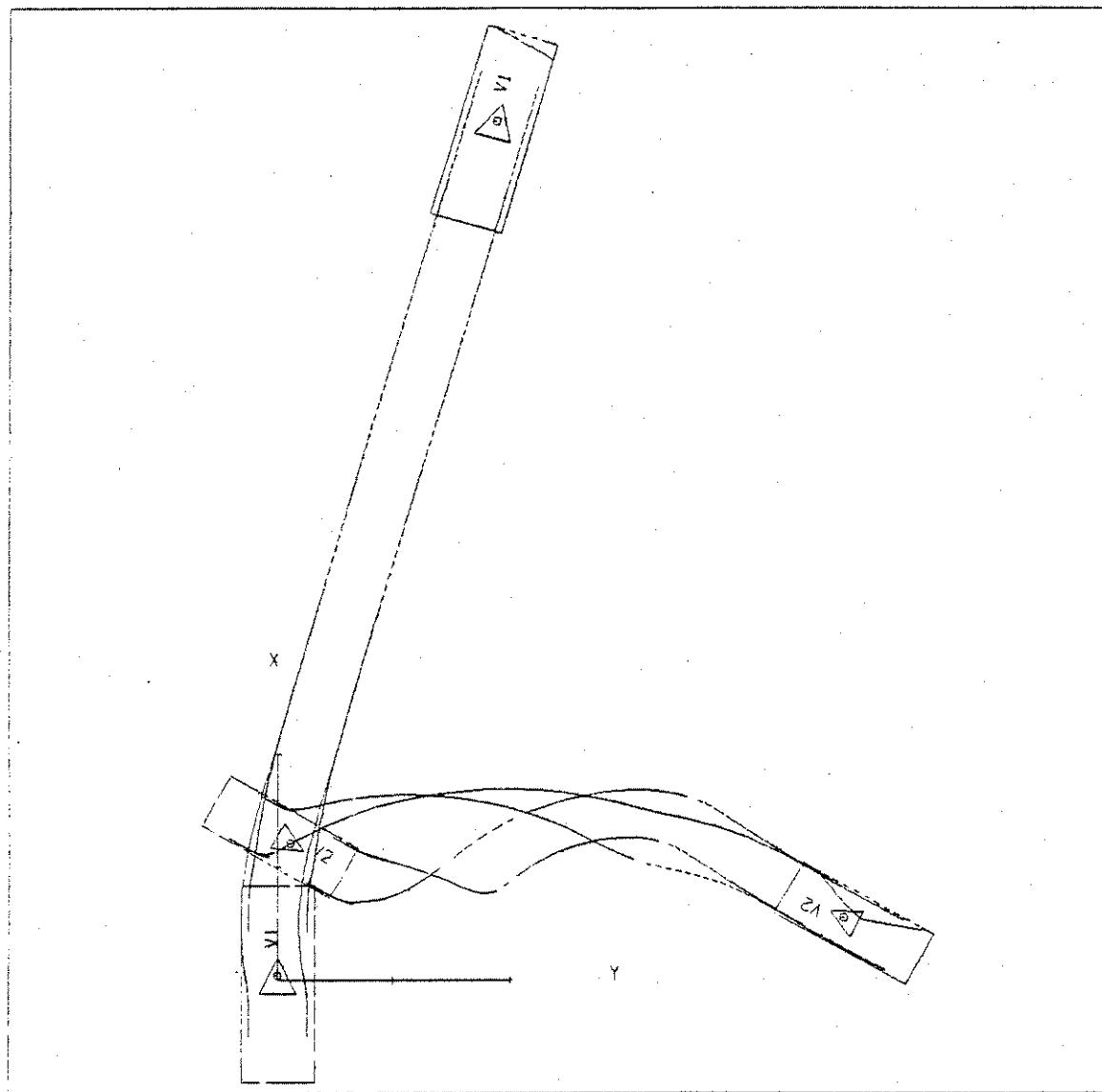
	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	84.5	18.2	16.5	12.0	22.9	41.4	262.0	16.5
SMAC	76.1	18.8	16.4	11.3	5.5	49.3	299.5	17.3
Computed								

As for Case No. 6, reconstruction of this case was not straightforward. The main difficulty was in estimating appropriate values for the stiffness coefficients and the intervehicle friction coefficient. The rest positions of both vehicles were very sensitive to these parameters and to the positions of the vehicles at impact. The final values used for the stiffness coefficients were 70 and 50 lb/in<sup>2</sup> for Vehicles 1 and 2 respectively with an intervehicle friction coefficient of 0.3. It can be seen that for Vehicle 1 the agreement between predicted and measured rest positions is extremely close, although the agreement for Vehicle 2 is not as good, in that the rotation is overestimated by 50 degrees which also has the effect of reducing the X displacement. The velocity change for Vehicle 1 is slightly underestimated, 11.3 mph versus 12.0 mph actual. While it appears that the ΔV is overestimated for Vehicle 2, it should be noted, as discussed in the CRASH II results section, that the actual value that was obtained for the velocity change, may be lower than the actual ΔV at the center of gravity. Because of the large ΔV component coupled with relatively high angular velocities, the prediction of ΔV for Vehicle 2 may, in fact, be an underestimate as well.

Looking at the damage profiles in Figure 3-8, that for Vehicle 1, the striking vehicle, is overestimated. This is, in part, due to the elastic effect of the 5 mph energy absorbing bumper which is not simulated and the lack of corner stiffening effects. The damage match for Vehicle 2 is extremely close which confirms that although the velocity changes are slightly underestimated, the engagement of the two vehicles as simulated is correct.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION  
COLLISION AND TRAJECTORY

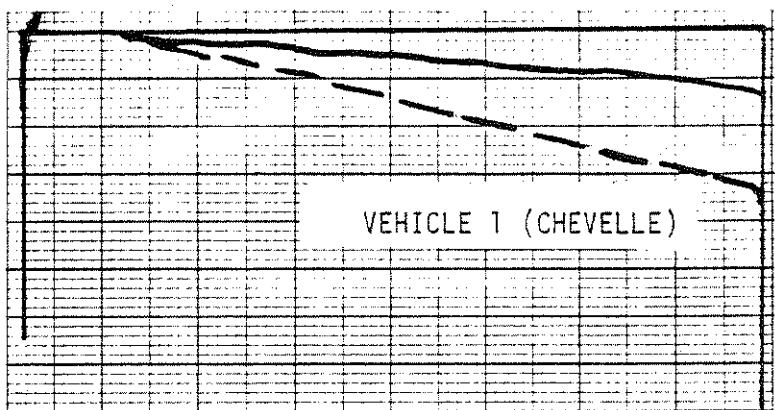
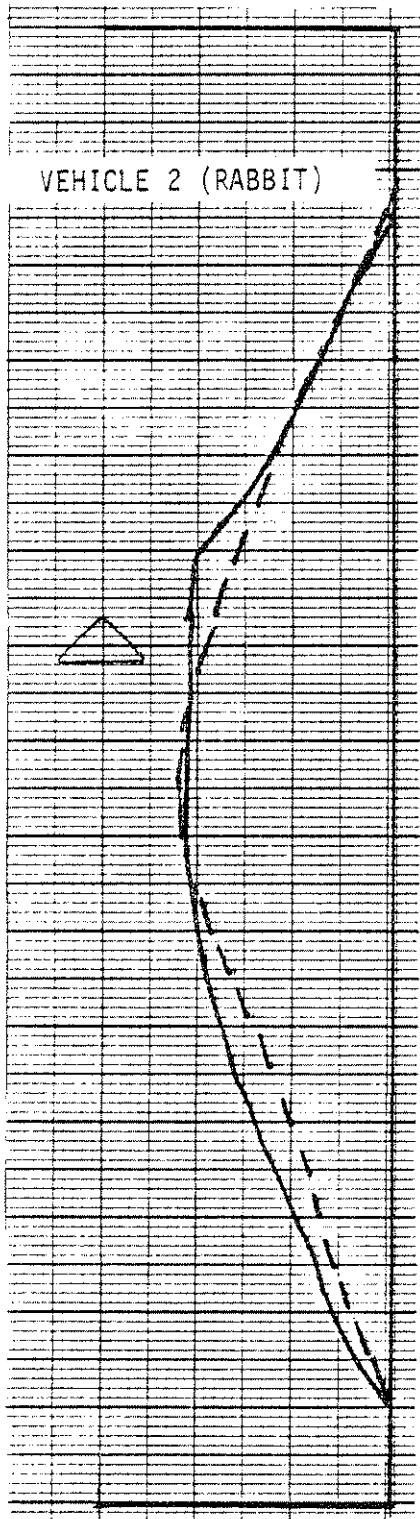
\*\*\* TEST #7 CHEVELLE VS RABBIT \*\*\*



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
C.G. POSITION		HEADING				C.G. POSITION		HEADING					
X <sub>C1</sub>	Y <sub>C1</sub>	PSI <sub>11</sub>	FWD	LATERAL	ANGULAR	X <sub>C1F</sub>	Y <sub>C1F</sub>	PSI <sub>11F</sub>	DEG.				
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.	DEG.				
VEHICLE # 1	3.4	3.0	0.0	29.1	0.0	0.0	76.1	18.8	16.4	IN MOTION AT 4.0 SEC AFTER INITIAL CONTACT	12 F D E W 2 11.3		
VEHICLE # 2	12.1	1.1	120.0	29.1	0.0	-0.0	5.5	49.3	299.5	VEHICLE AT REST	0 2 R D E W 4 17.3		

Figure 3-7 GRAPHIC DISPLAY, TEST NO. 7



— Actual  
- - - Predicted

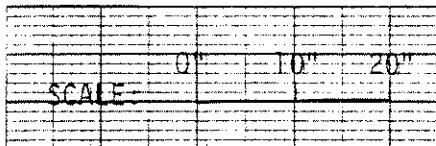


Figure 3-8 TEST NO. 7 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 8 - 90° Front-to-Side Impact - Chevrolet Chevelle Vs.  
Chevrolet Chevelle - Impact Speeds, 20.75/20.75 mph

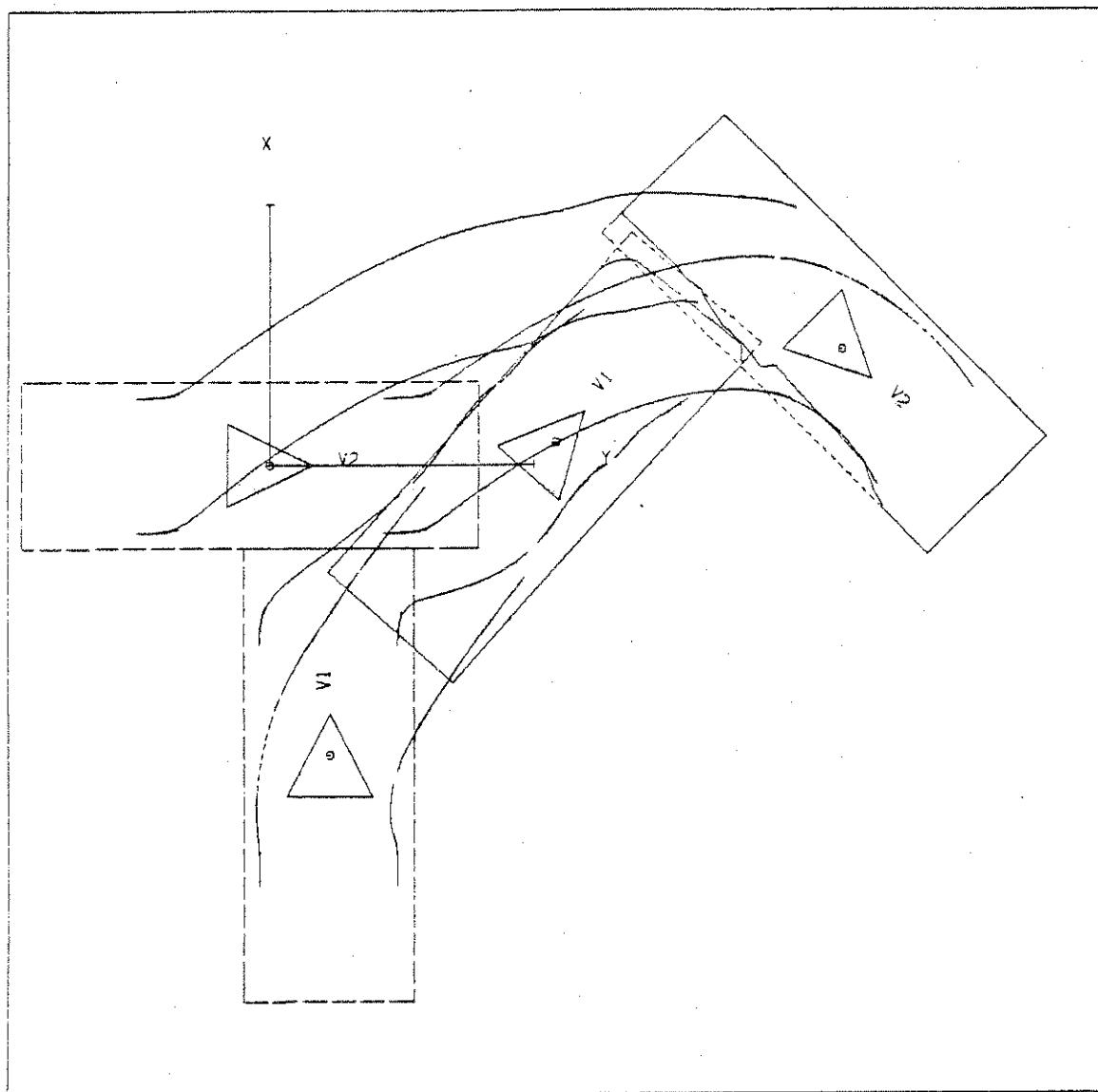
	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	0.0	10.8	45.0	15.3	6.25	19.2	130.0	10.7
SMAC	0.9	10.8	41.8	16.8	4.4	21.5	135.2	15.0
Computed								

There is good agreement between the predicted and measured data, the only major discrepancies being in the velocity change for Vehicle 2 and its damage profile. Looking first at the damage profile, Figure 3-10, it can be seen that the SMAC reconstruction predicts damage which extends almost the entire length of Vehicle 2 (except for 30 inches in the front), whereas the actual damage occurred between the front wheel and "B" pillar. This difference can be attributed to the pocketing that occurred between the left front corner of Vehicle 1 and the "B" pillar of Vehicle 2, i.e., the "B" pillar presents a hard point on the side structure as the corner of the striking vehicle travels down the side of the car. This type of phenomenon cannot, at present, be simulated with the SMAC program since it is assumed that the vehicle is a uniform structure. To facilitate such a simulation would require the provision of hard points in the side structure and corner effects.

In achieving a satisfactory match to the measured data, the major input changes that had to be made were braking torques adjustments for both vehicles, and altering slightly the impact position, so that the initial contact occurred 30 inches rearward of Vehicle 2's right front corner. The intervehicle friction coefficient was also varied to try and improve the damage profile and simulate the pocketing that occurred. However, this appeared to have very little effect. This is perhaps surprising in that the 60 degree front-to-side impacts were quite sensitive to variation of the intervehicle friction coefficient.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION  
COLLISION AND TRAJECTORY

TEST #8 MALIBU VS. MALIBU



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT							DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
C.G. POSITION		HEADING					C.G. POSITION	HEADING	REMARKS					
X <sub>C1</sub>	Y <sub>C1</sub>	PSI1	FWD	LATERAL	ANGULAR	X <sub>C1F</sub>	Y <sub>C1F</sub>	PSI1F						
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.						
VEHICLE # 1	-11.1	2.2	0.0	20.7	0.0	0.0	0.9	10.8	41.8	VEHICLE AT REST	11 F D E W 2	16.8		
VEHICLE # 2	0.0	0.0	90.0	20.7	0.0	0.0	4.4	21.5	135.2	VEHICLE AT REST	02 R D E W 3	15.0		

Figure 3-9 GRAPHIC DISPLAY, TEST NO. 8

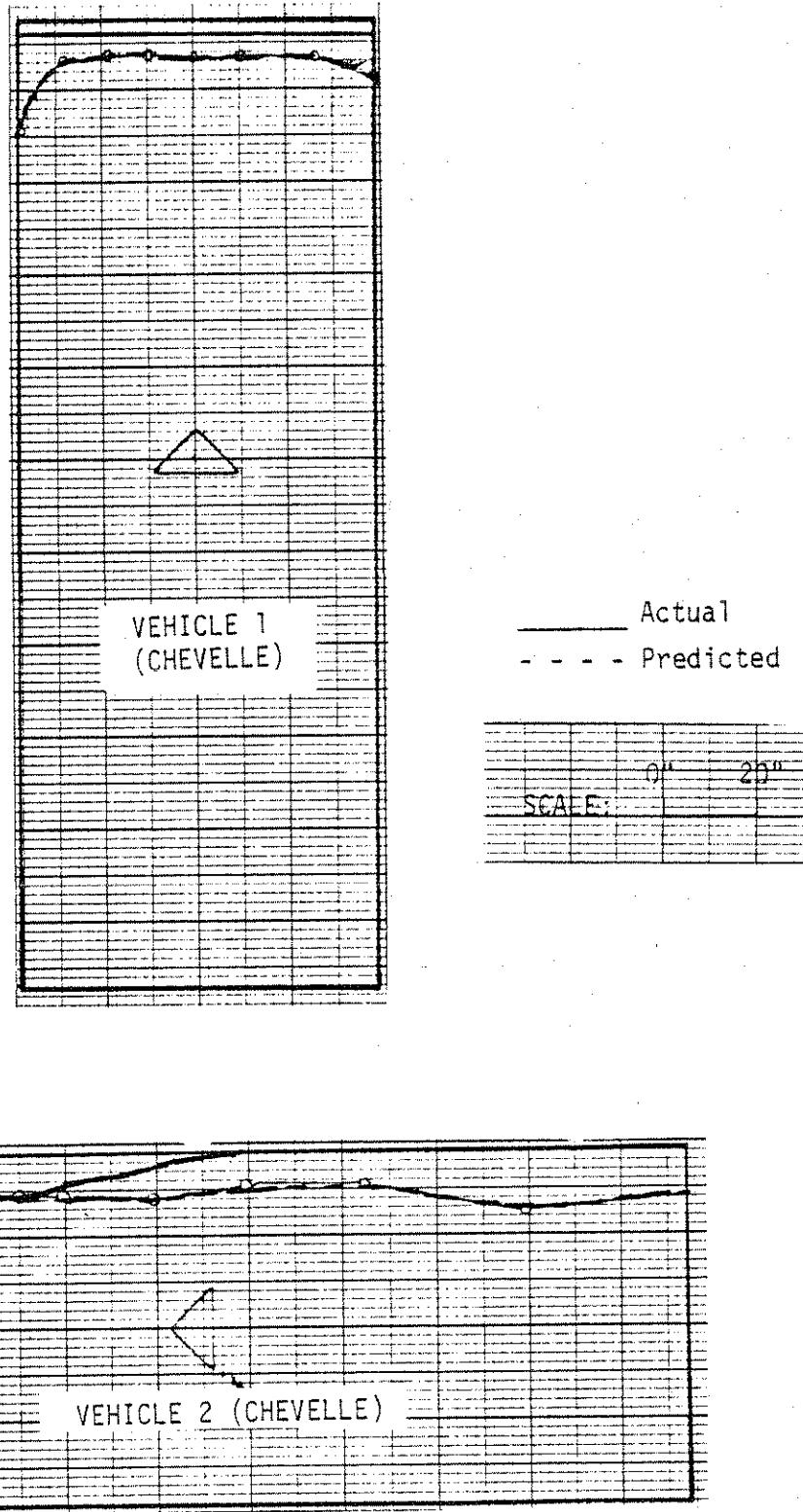


Figure 3-10 TEST NO. 8 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 9 - 90° Front-to-Side Impact - Honda Civic Vs.  
Ford Torino - Impact Speeds, 21.2/21.2 mph

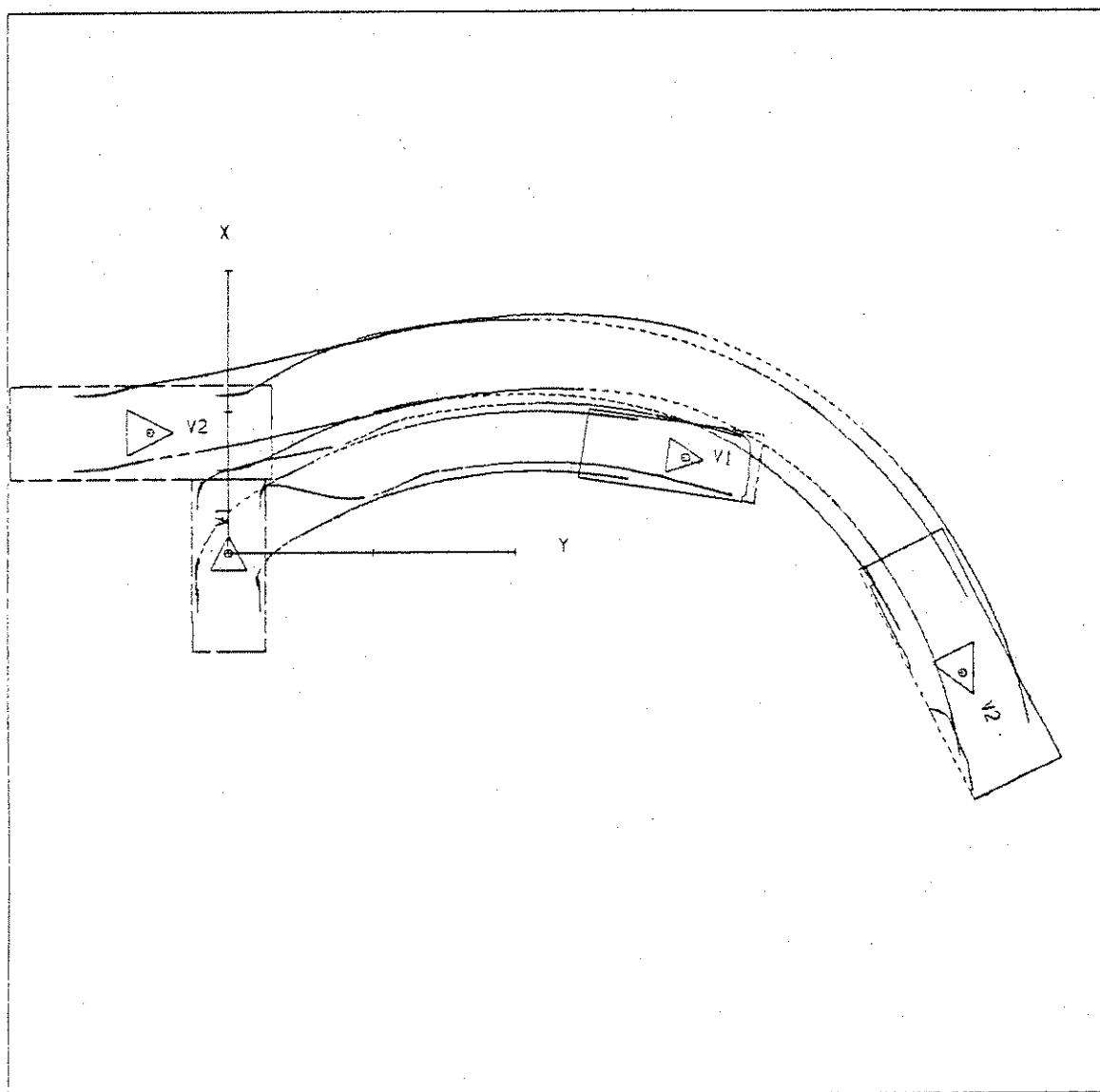
	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	4.0	35.5	104.0	21.4	-5.0	49.5	152.0	8.9
SMAC	6.6	31.7	98.6	20.0	-8.7	51.3	153.4	8.7
Computed								

The agreement for this case is extremely good. The predicted and measured final rest positions and the velocity changes all are within an acceptable range. Looking at the damage profiles, Figure 3-12, that for Vehicle 1, the striking vehicle, agrees very closely although the damage for Vehicle 2 is slightly overestimated.

This case appeared to be particularly sensitive to brake and steer inputs, in fact, the majority of the input changes that were made during the reconstruction process were to steer angles and brake torques. The brake torques were adjusted to "fine tune" the spin out trajectories and changes in the steer angles were made primarily to smooth the effects of short duration spikes in the steering time-history plots.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION  
COLLISION AND TRAJECTORY

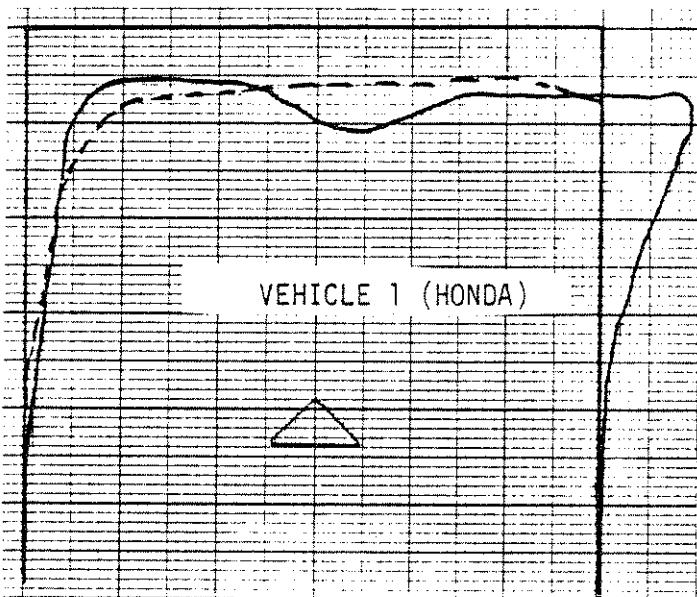
\*\*\* TEST #9 HONDA VS TORINO 90 DEG FRONT/SIDE 21.2/21.2MPH



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
	C.G. POSITION		HEADING				C.G. POSITION	HEADING	REMARKS				
	XC1	YC1	PSII	FWD	LATERAL	ANGULAR	XC1F	YC1F	PSII F				
	FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.				
VEHICLE # 1	0.0	0.0	0.0	21.2	0.0	0.0	6.6	31.7	98.6	VEHICLE AT REST	11LFEE2 20.0		
VEHICLE # 2	8.5	-5.4	90.0	21.2	0.0	0.0	-8.7	51.3	153.4	IN MOTION AT 5.0 SEC AFTER INITIAL CONTACT	02RYEW3 02RZEW2 8.7 8.7		

Figure 3-11 GRAPHIC DISPLAY, TEST NO. 9  
3-20 ZO-6057-V-6



— Actual  
- - - Predicted

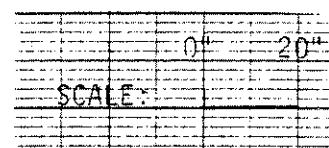
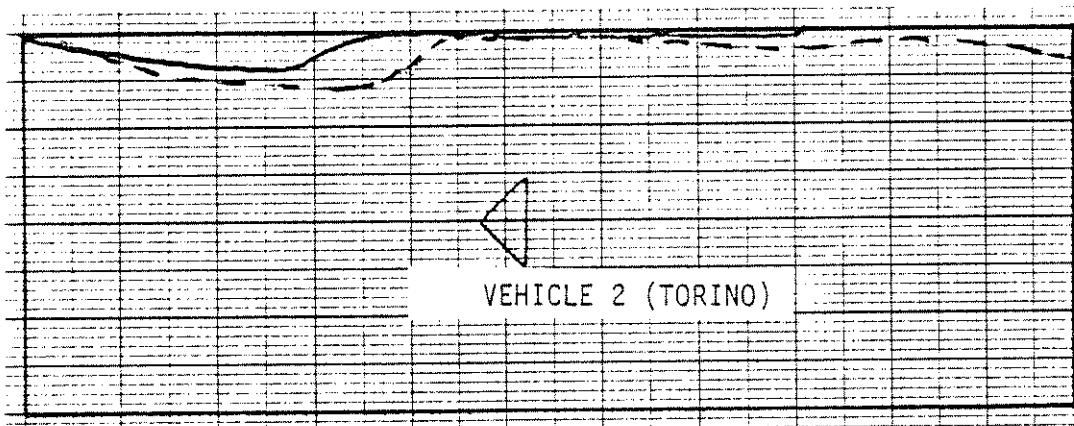


Figure 3-12 TEST NO. 9 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 10 - 90° Front-to-Side Impact - Honda Civic Vs.  
Ford Torino - Impact Speeds, 33.3/33.3 mph

	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	5.0	43.0	87.0	35.1	0.0	99.5	128.5	14.1
SMAC	-1.5	43.4	99.8	36.5*	1.3	100.9	121.1	15.7
Computed								

\* Sum of two impacts

Although the agreement between predicted and measured rest positions is quite close, several factors compounded the reconstruction task; specifically:

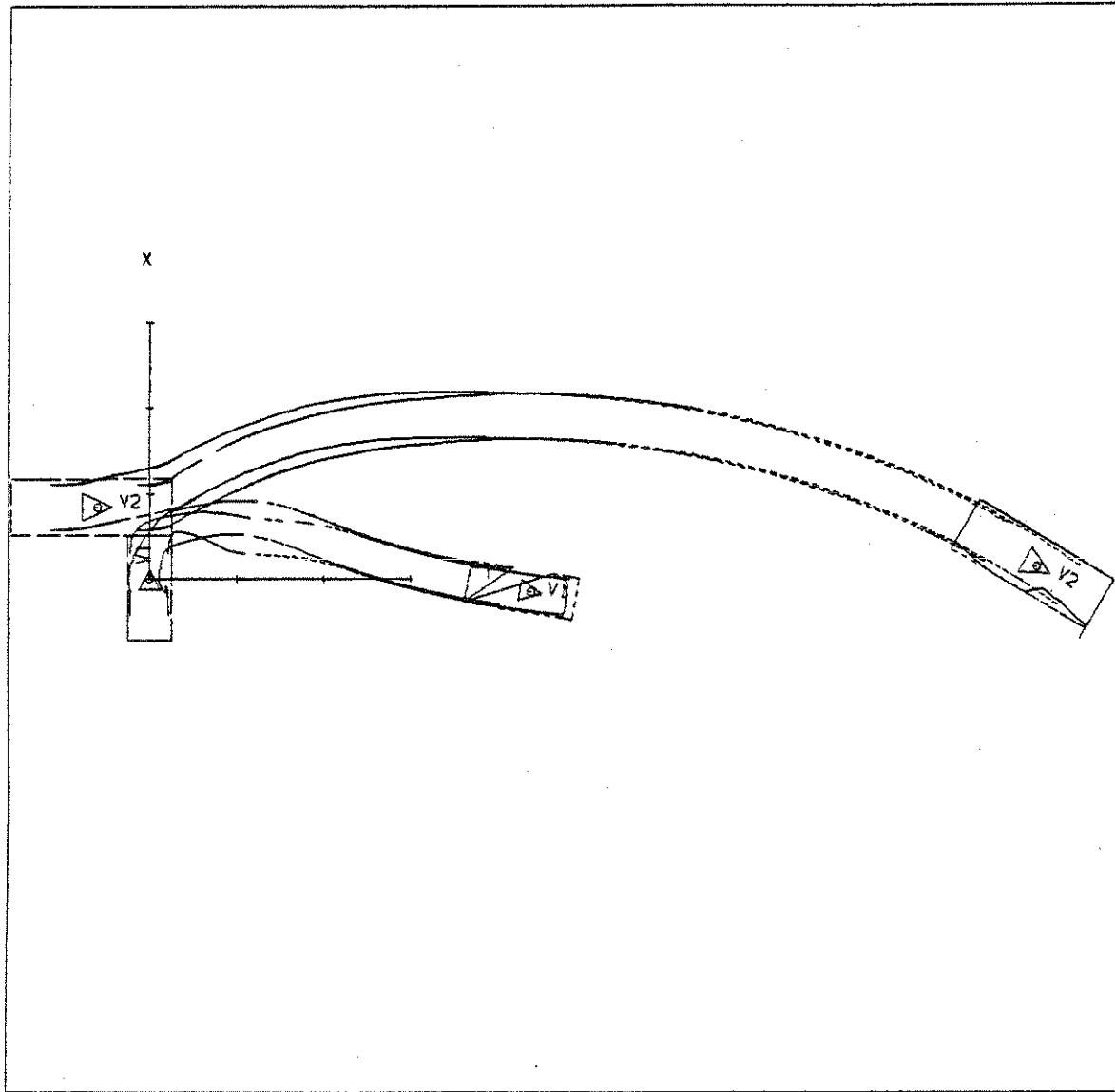
- The right front tie rod was damaged during the impact such that the right front wheel was independent of the rest of the steering assembly; its steer angle had to be estimated from the films and through trial and error.
- Prior to coming to rest, Vehicle 2 mounted a metal transformer base and subsequently the cables connected to Vehicle 2 became fully extended, bringing the vehicle rapidly to a halt.
- A metal bar extending from the rear bumper of Vehicle 1 contacted the rear bumper of Vehicle 2 after the vehicles had separated from their second impact. This contact (on film) appeared to reduce Vehicle 1's angular velocity during spin out.

Once these compounding factors had been appreciated, the reconstruction process essentially entailed adjusting the braking torques and steer angles until acceptable rest positions were achieved. Looking at the vehicle damage, Figure 3-14, the predicted and measured profiles for Vehicle 1 are extremely close although, as in Test 9, that for Vehicle 2 is slightly overestimated.

## GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION

## COLLISION AND TRAJECTORY

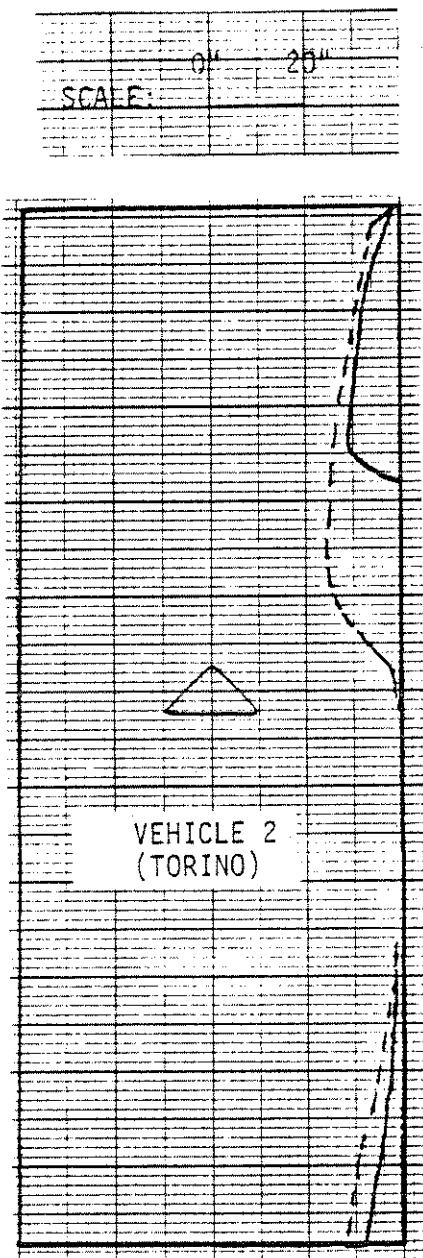
\*\*\* TEST #10 HONDA VS TORINO 90 DEG FRONT/SIDE 33.3/33.3MPH



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT							DISPLAYED FINAL POSITIONS			VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
	C.G. POSITION		HEADING			C.G. POSITION	HEADING	REMARKS					
	XC1	YC1	PSII	FWD	LATERAL	ANGULAR	XC1F	YC1F	PSIIF				
	FT.	FT.	DEC.	MPH	MPH	DEC/SEC	FT.	FT.	DEC.				
VEHICLE # 1	0.0	0.0	0.0	33.3	0.0	0.0	-1.5	43.4	99.8	VEHICLE AT REST	L L F E E 3 0 8 L Z E W 3	29.7 6.8	
VEHICLE # 2	8.4	-6.0	90.0	33.3	0.0	0.0	1.3	100.9	121.1	IN MOTION AT 3.9 SEC AFTER INITIAL CONTACT	O 2 R Y E W 3 O 2 R Z E W 3	15.7 15.7	

Figure 3-13 GRAPHIC DISPLAY, TEST NO. 10



— Actual  
- - - Predicted

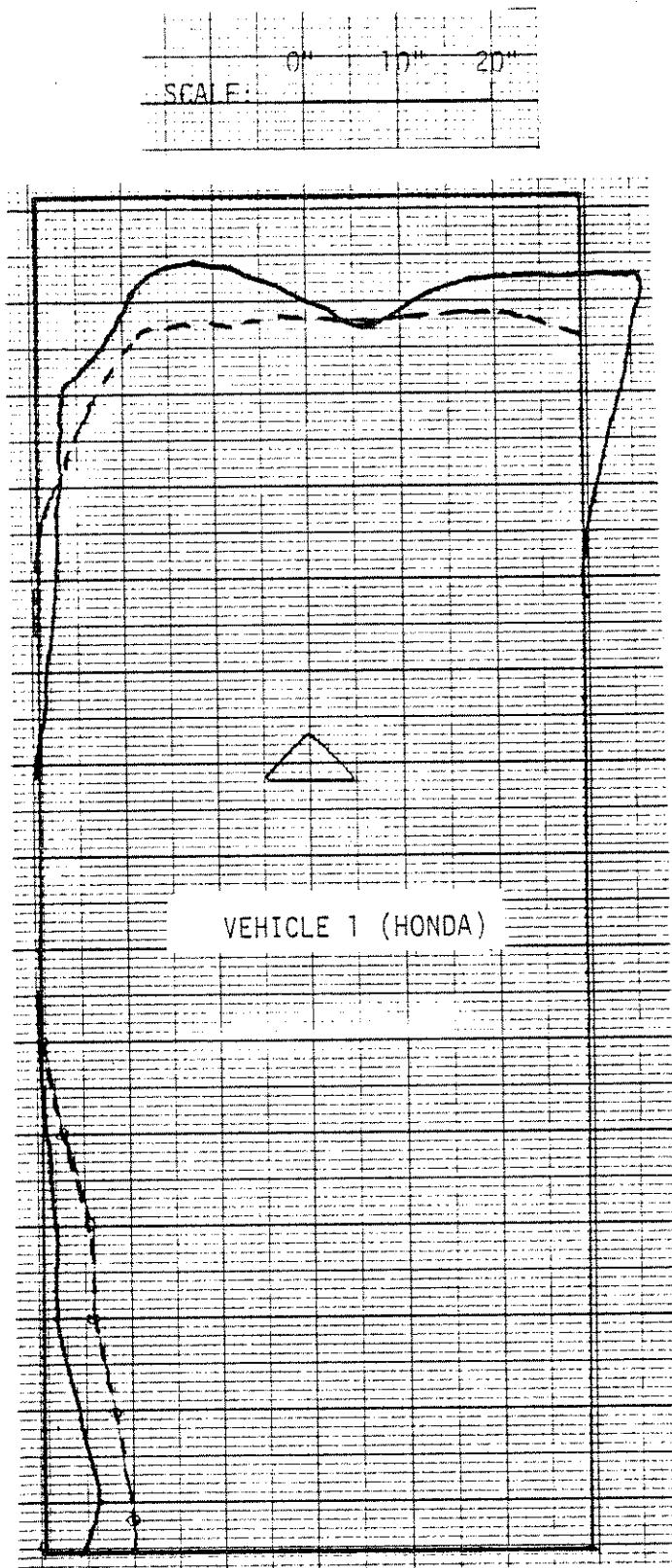


Figure 3-14 TEST NO. 10 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 11 - 10° Offset Front-to-Front Impact - Chevrolet Vega Vs.  
Ford Torino - Impact Speeds, 20.4/20.4 mph

	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	25.6	-6.4	170.0	24.0	8.6	0.4	0.0	15.7
SMAC	23.2	-7.4	167.1	28.7	6.9	0.7	0.3	17.6
Computed								

The predicted and rest positions agree closely. However, the predicted velocity changes are slightly overestimated, 28.7 mph versus 24.0 mph actual for Vehicle 1 and 17.6 mph versus 15.7 mph actual for Vehicle 2.

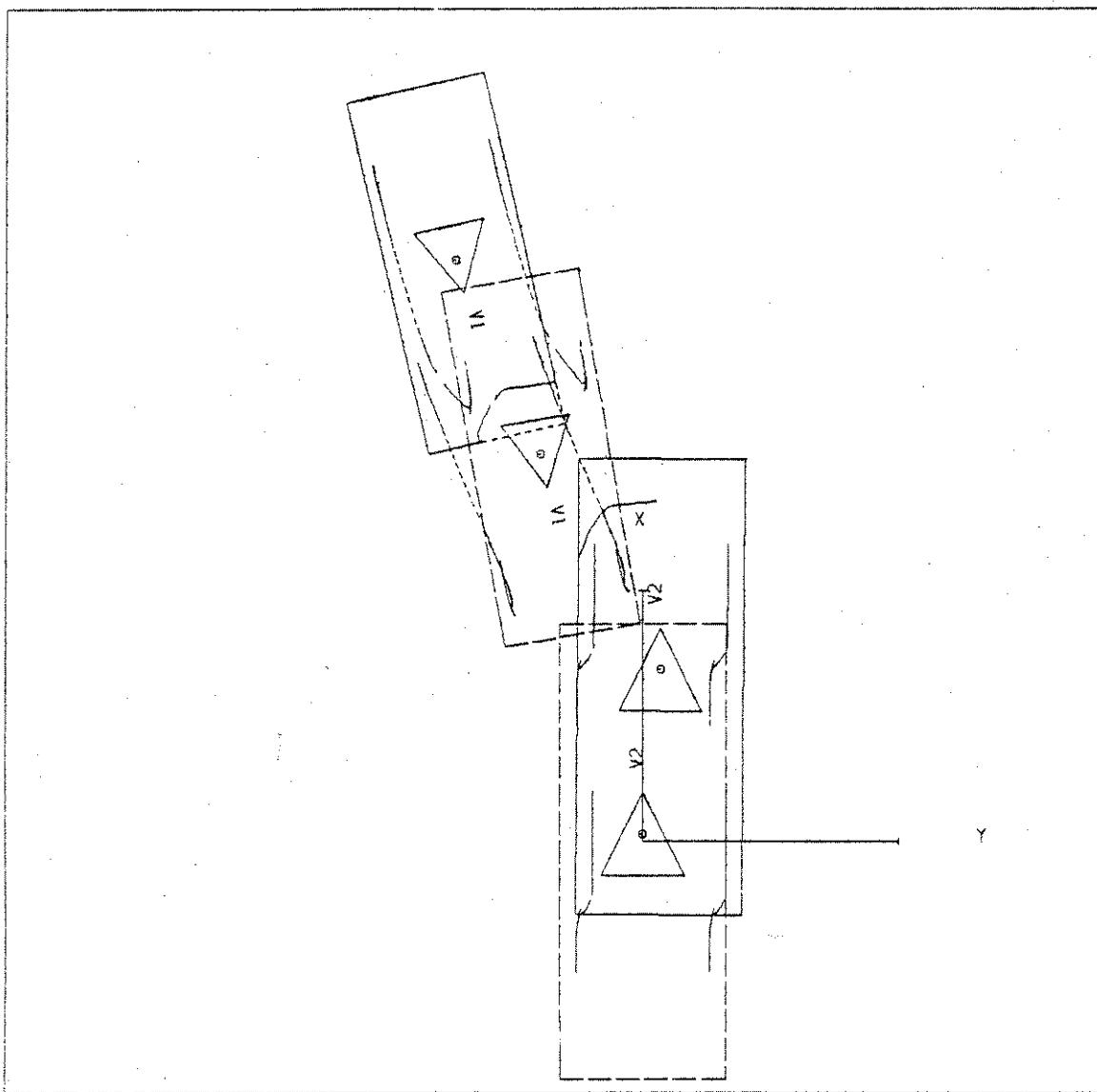
Looking at the damage profiles, Figure 3-16, the predicted extent is acceptable although the effect of the vehicle's bumper is not simulated. This has the effect of smoothing the deformation across the front of the car, whereas the homogenous isotropic body assumed in the program produces more localized effects.

In achieving an acceptable reconstruction, no real problems were encountered; the offset of the two vehicles had to be adjusted slightly to obtain the correct amount of rotation for Vehicle 1 and the stiffnesses of both vehicles increased from 50 to 60 lb/in<sup>2</sup> to match the damage.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION

COLLISION AND TRAJECTORY

\*\*\* TEST #11 VEGA VS TORINO OFFSET HEAD ON 20.4/20.4 MPH



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
C.G. POSITION		HEADING				C.G. POSITION	HEADING		REMARKS				
XCI	YCI	PSII	FWD	LATERAL	ANGULAR	XCIF	YCIF	PSIIF					
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.					
VEHICLE # 1	15.4	-4.1	170.0	20.4	0.0	0.0	23.2	-7.4	167.1	VEHICLE AT REST	12 F Y E W 3 28.7		
VEHICLE # 2	0.3	0.0	0.0	20.4	0.0	0.0	6.9	0.7	0.3	VEHICLE AT REST	12 L F E W 2 17.6		

Figure 3-15 GRAPHIC DISPLAY, TEST NO. 11

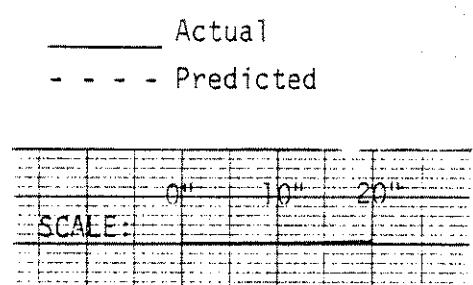
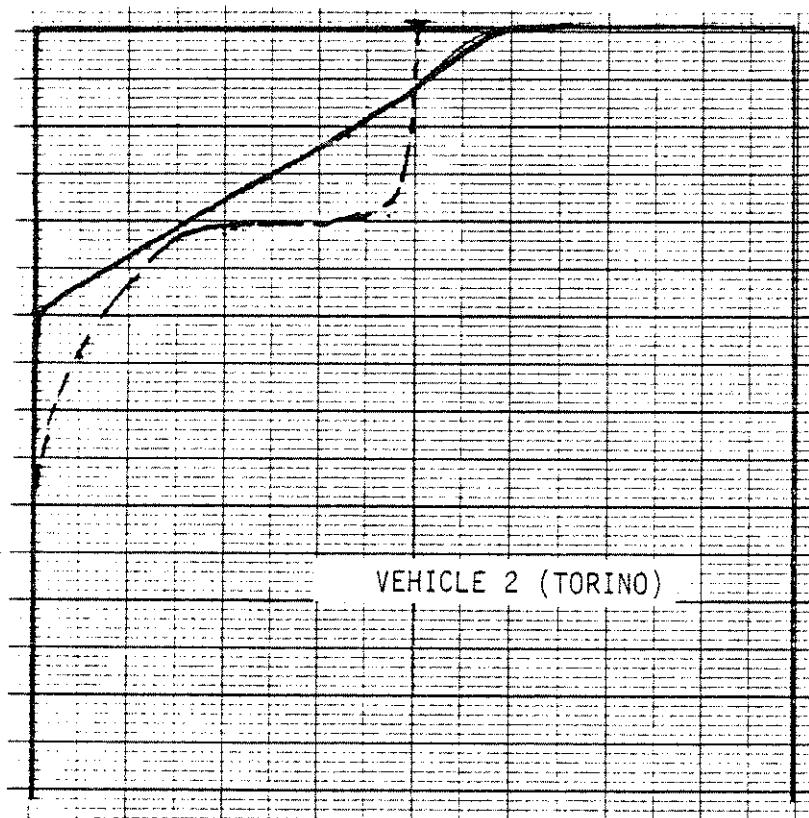
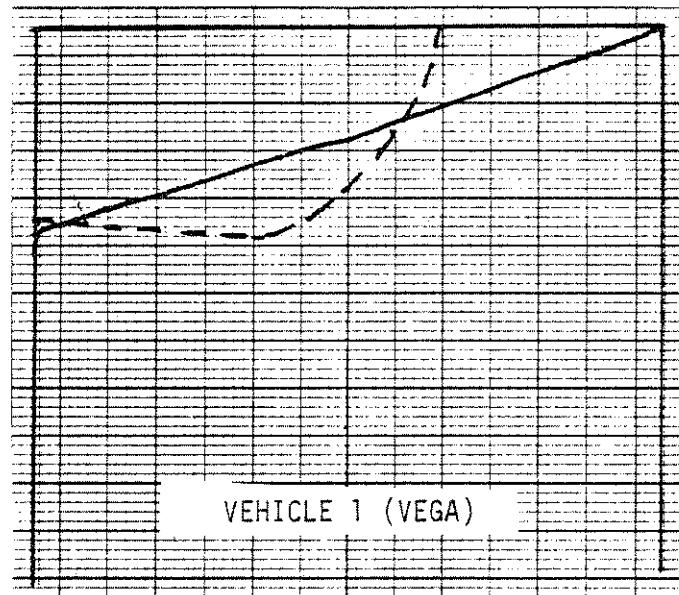


Figure 3-16 TEST NO. 11 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 12 - 10° Offset Front-to-Front Impact - Chevrolet Vega Vs.  
Ford Torino - Impact Speeds, 31.5/31.5 mph

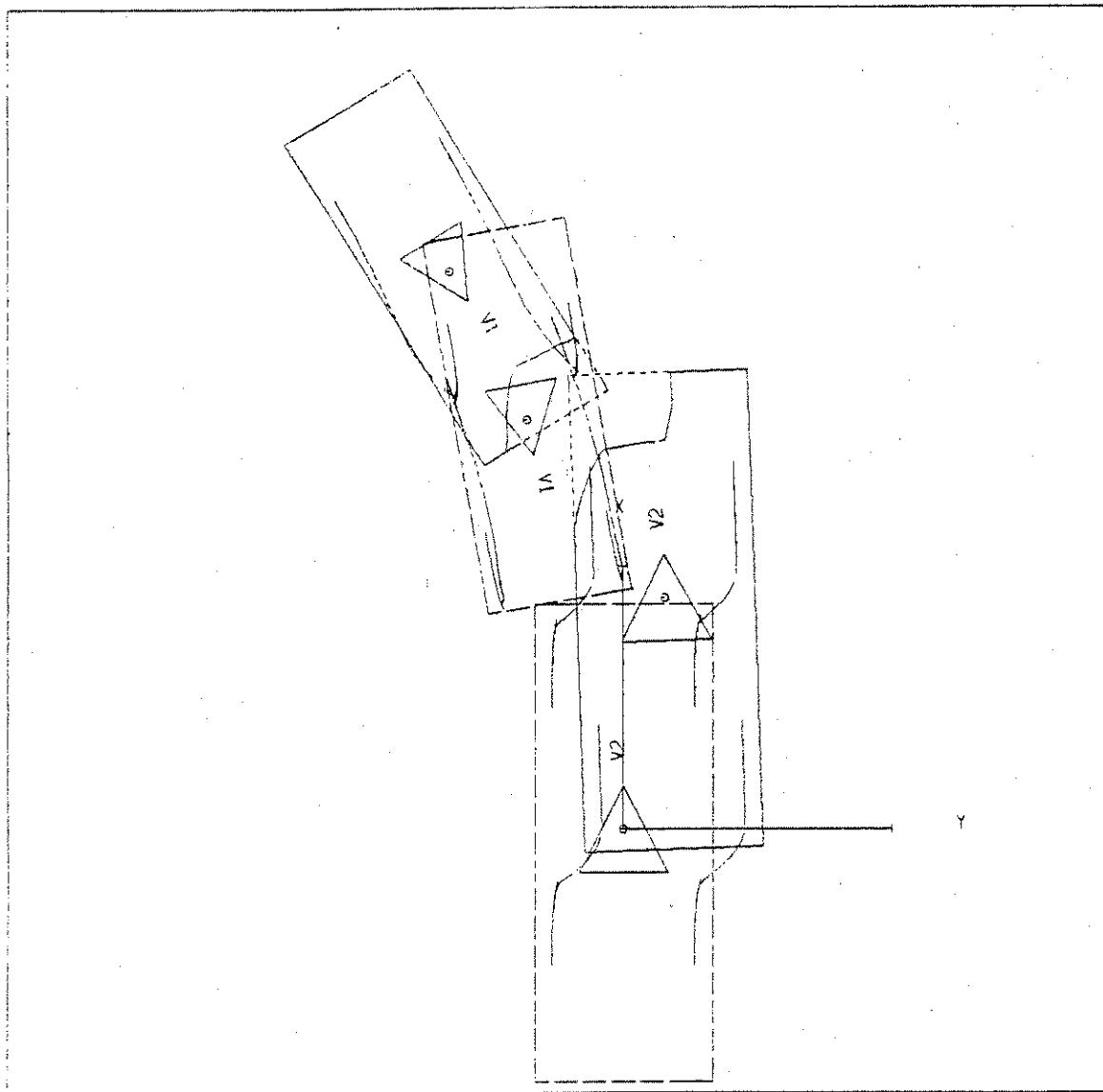
	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	22.5	-5.4	122.0	40.1	6.8	2.6	-12.0	26.4
SMAC Computed	21.8	-6.5	148.7	40.9	8.8	1.6	-1.8	27.6

The match between predicted and measured rest positions is acceptable although the rotation of both vehicles is slightly underestimated. This is due to the fact both right side wheels of Vehicle 1 were airborne during most of the collision phase which will increase the amount of rotation of Vehicle 1. The predicted velocity changes are in good agreement, 40.9 mph versus 40.1 mph actual for Vehicle 1 and 27.6 mph versus 26.4 mph actual for Vehicle 2. The damage profiles, given in Figure 3-18 show that Vehicle 1 is in close agreement although Vehicle 2's damage is slightly overestimated.

Obtaining a match for this case was straightforward, minor adjustments were made to the overlap of the two vehicles, the braking increased on the left front wheel of Vehicle 1 (from 8 to 600 lbs) and the 12 degree steer angle introduced on Vehicle 2.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION  
COLLISION AND TRAJECTORY

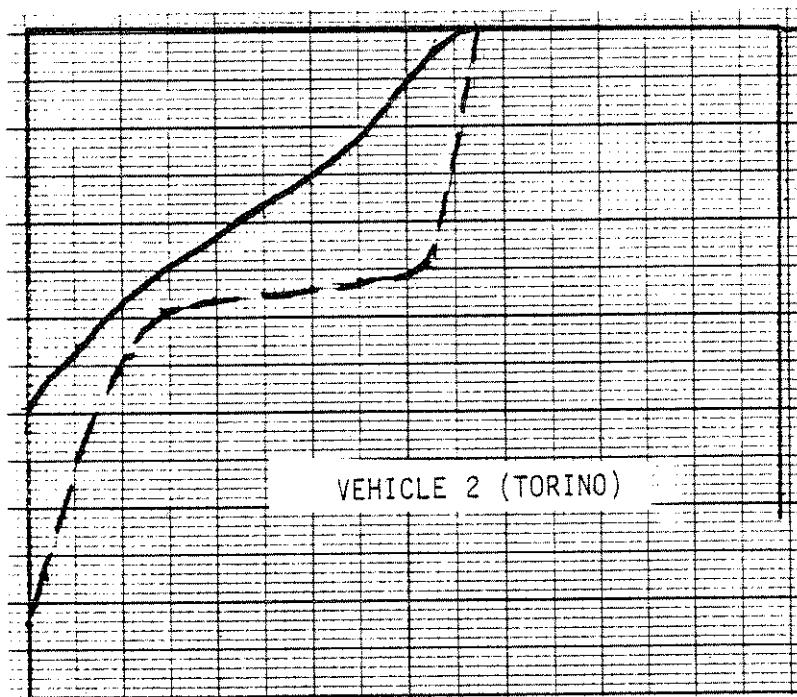
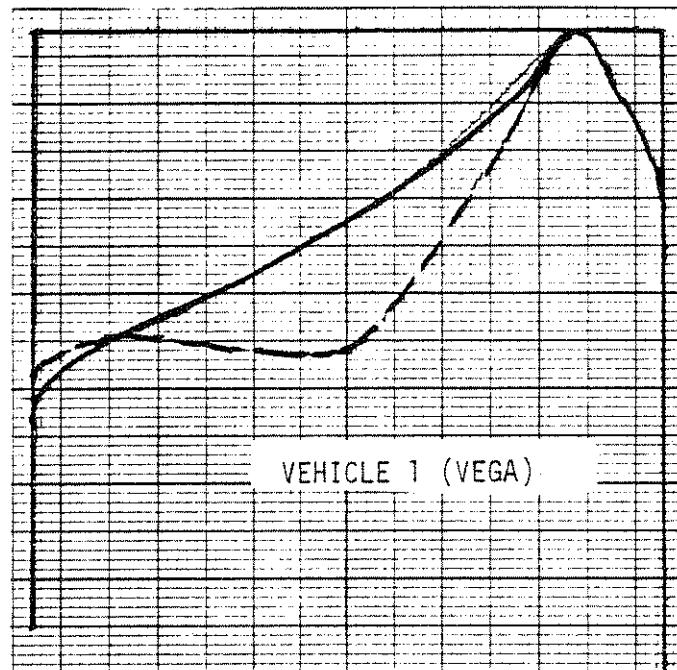
\*\*\* TEST #12 VEGA VS TORINO OFFSET HEAD ON 31.5/31.5MPH



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				REMARKS	VEHICLE DAMAGE INDICES	$\Delta V$ MPH			
C.G. POSITION		HEADING				C.G. POSITION		HEADING							
XG1	YG1	PSI1	FWD	LATERAL	ANGULAR	XG1F	YG1F	PSI1F	FWD						
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.	DEG.						
VEHICLE # 1	15.8	-3.6	170.0	31.5	0.0	0.0	21.3	-6.5	148.7	VEHICLE AT REST	12 F DEH 4	40.9			
VEHICLE # 2	0.0	0.0	0.0	31.5	0.0	0.0	8.8	1.6	-1.8	VEHICLE AT REST	12 L YEW 6	27.6			

Figure 3-17 GRAPHIC DISPLAY, TEST NO. 12



— Actual  
- - - Predicted

	0"	10"	20"
SCALE:			

Figure 3-18 TEST NO. 12 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 3 -  $10^\circ$  Offset Front-to-Rear Impact - Ford Torino Vs.  
Ford Pinto - Impact Speeds, 21.1/0 mph

	Vehicle 1				Vehicle 1			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	$\psi_1$ deg	$\Delta V_1$ mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	$\psi_2$ deg	$\Delta V_2$ mph
Actual	111.4	2.0	-4.0	9.5	181.5	-6.3	-19.0	15.8
SMAC	120.7	3.4	-4.7	9.6	188.7	-0.8	-22.2	15.6
Computed								

The predicted and measured rest positions are in close agreement. The velocity changes are extremely close, 9.6 mph versus 9.5 mph actual for Vehicle 1 and 15.6 mph versus 15.8 mph actual for Vehicle 2.

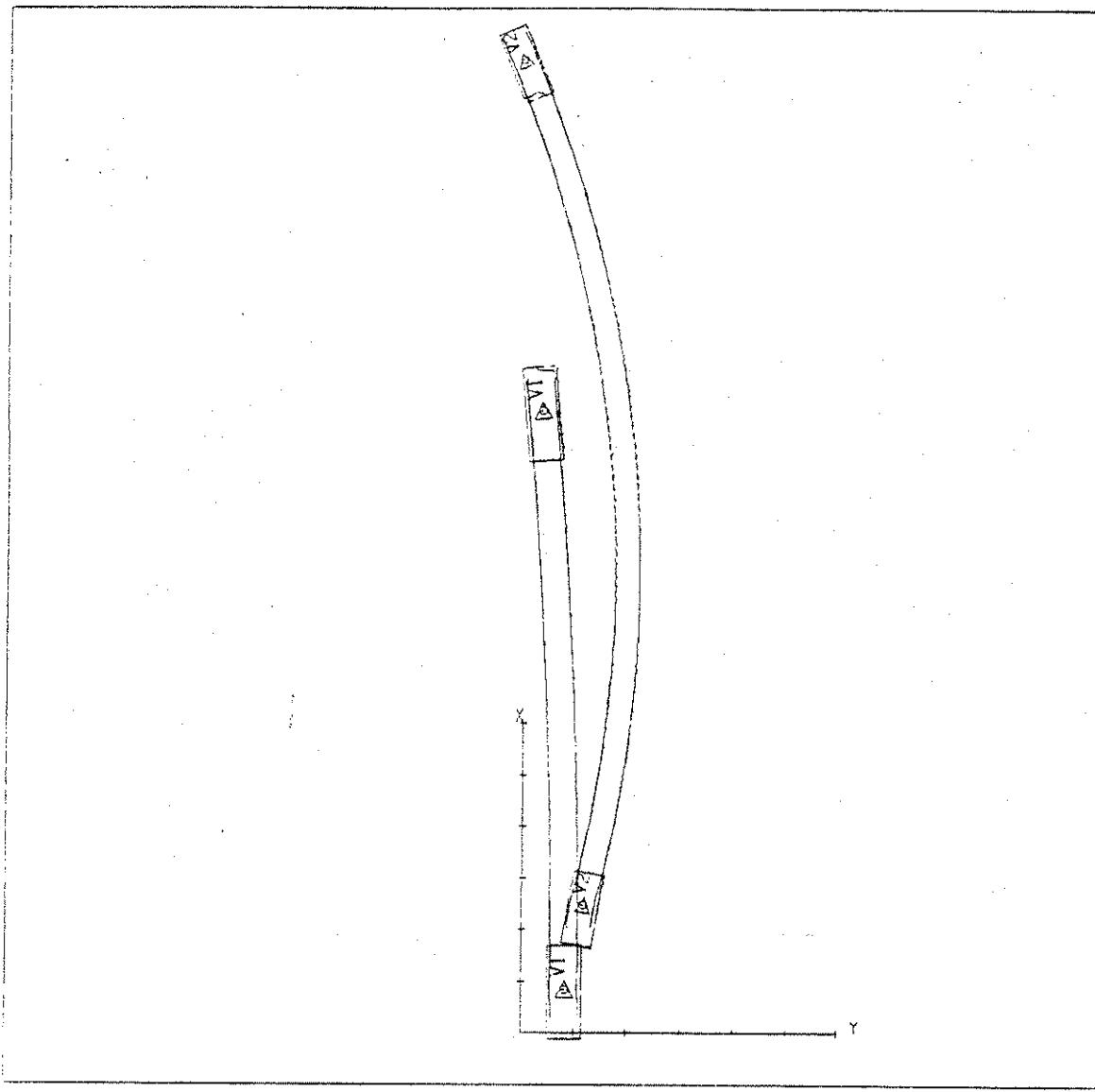
The damage for Vehicle 1, Figure 3-20, is overpredicted, however. The SMAC program does not simulate the elastic properties of the energy absorbing bumper which, according to the accident investigators report, had returned to the undeformed position. Similarly, the damage for Vehicle 2 is overpredicted mainly because of the energy absorbing bumper which again returned to its undeformed position following impact.

Adjustments that were made during the reconstruction to obtain a match with the measured data included: increasing the stiffness of both vehicles to 80 and 60 lb/in<sup>2</sup> for Vehicles 1 and 2, respectively, increasing the rolling resistances of both vehicles and adjusting the steer angles of both vehicles to obtain the desired amount of rotation.

# GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION

## COLLISION AND TRAJECTORY

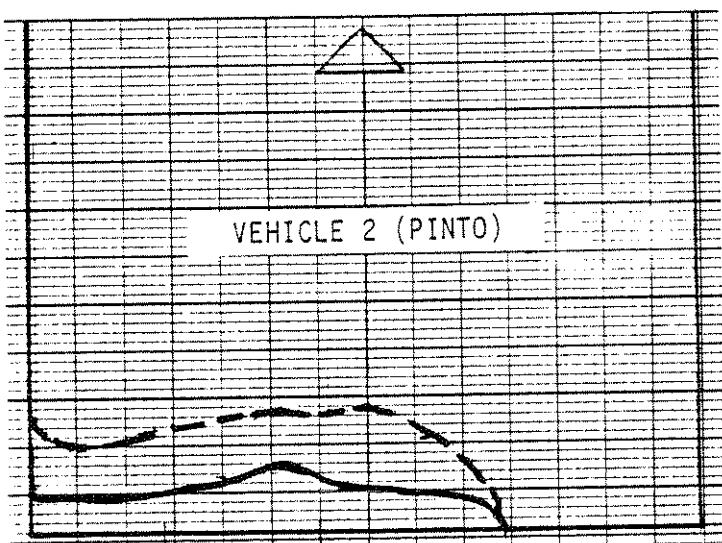
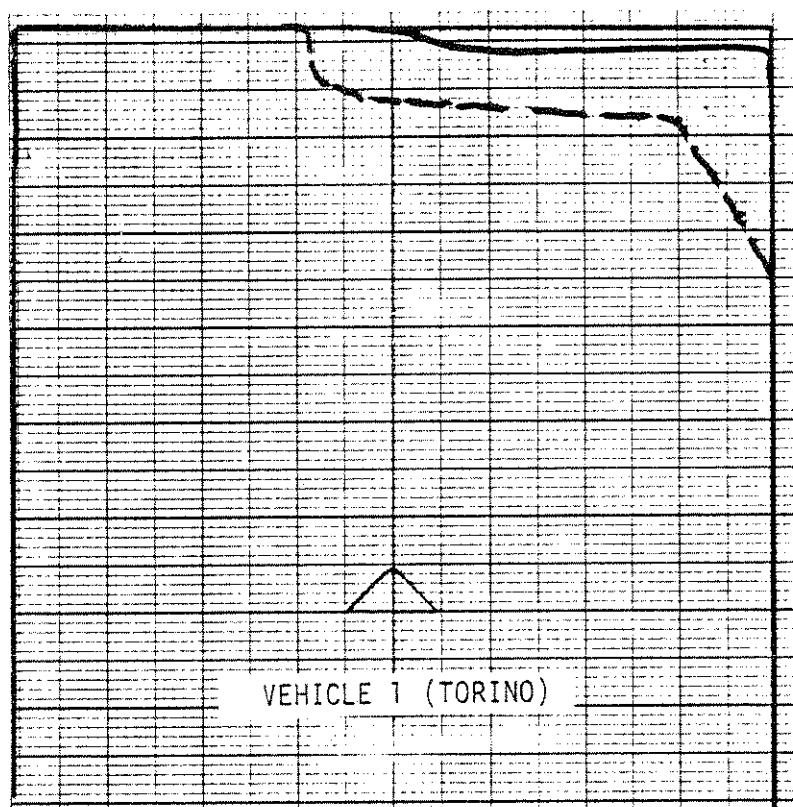
\* RICSAC TEST #3 TORINO-PINTO 21.23MPH \* RUN 15



Axis intervals are 10. feet

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
C.G. POSITION		HEADING				C.G. POSITION		HEADING					
XG1	YG1	PSII	FWD	LATERAL	ANGULAR	XG1F	YG1F	PSIIF					
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.					
VEHICLE # 1	9.5	9.3	-0.0	21.2	-0.0	-0.1	120.7	3.4	-4.7	VEHICLE AT REST	1.2 F Z E W 1 2.6		
VEHICLE # 2	34.7	11.9	10.0	0.0	0.0	188.7	-0.3	-22.2	VEHICLE AT REST	3.6 B Y E W 2	15.6		

Figure 3-19 GRAPHIC DISPLAY, TEST NO. 3



— Actual  
- - - Predicted

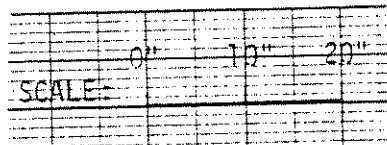


Figure 3-20 TEST NO. 3 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 4 - 10° Offset Front-to-Rear Impact - Ford Torino Vs.  
Ford Pinto - Impact Speeds, 38.7/0 mph

	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	42.8	54.5	137.5	18.7	63.9	62.5	88.0	22.2
SMAC Computed	40.5	55.3	127.1	16.7	73.7	66.5	69.7	26.2

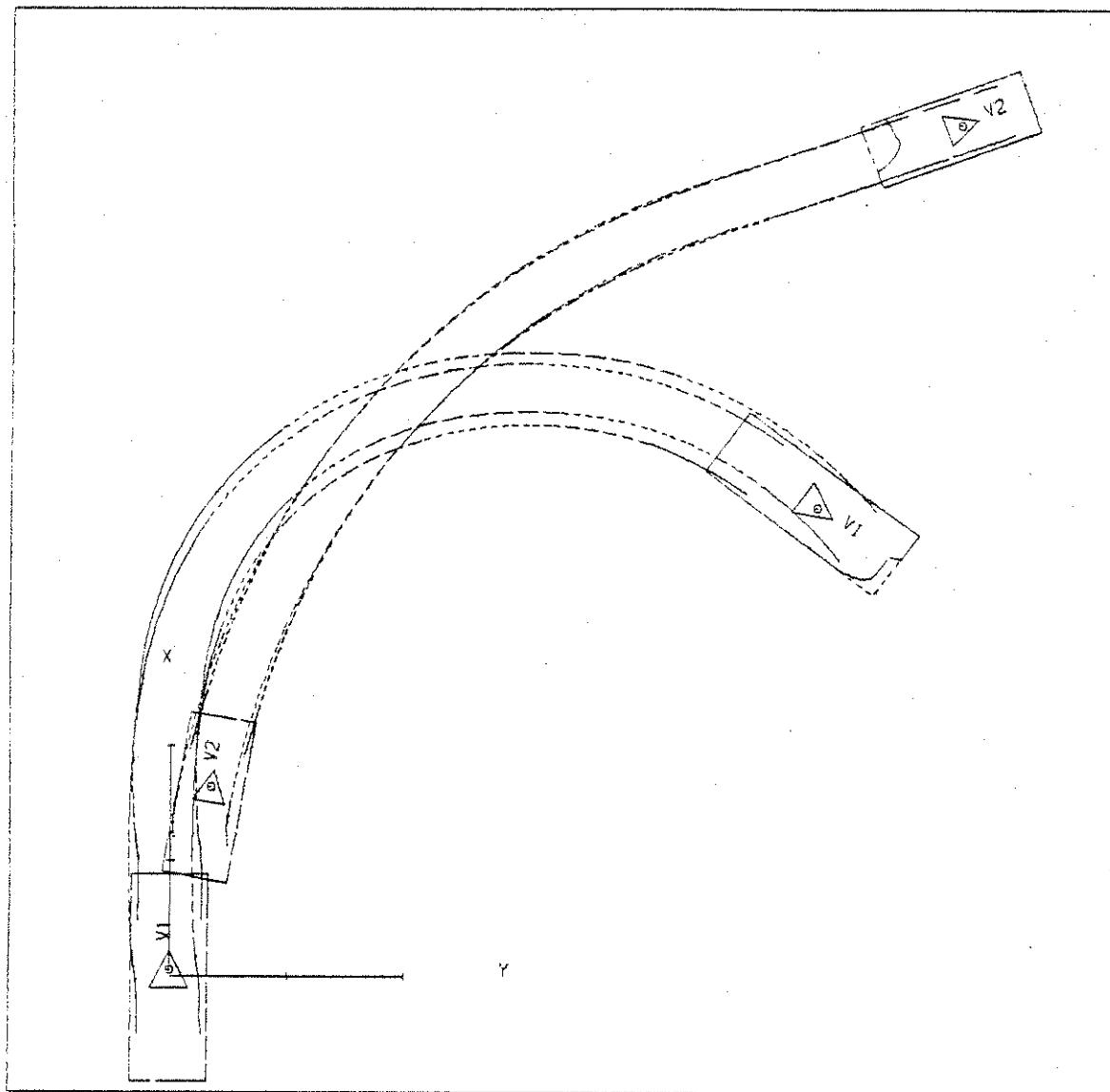
The agreement between the predicted and rest positions is good, although the rotation of both vehicles is slightly underestimated. However, given the amount of rotation that both vehicles underwent and the length of their spin outs, the predicted rotations are very acceptable. The velocity changes are in good agreement, 16.7 mph versus 18.7 mph actual for Vehicle 1 and 26.2 mph versus 22.2 mph actual for Vehicle 2.

The predicted and measured damage profiles are given in Figure 3-22; for Vehicle 1 a good match is obtained apart from the smoothing effects produced by the bumper which does not appear in the simulation. The same limitation is true for Vehicle 2 in that the localized deformation produced at the edge of contact in the simulation does not appear in the actual damage because of the smoothing effect of the bumper.

In attaining an acceptable reconstruction, the stiffness of both vehicles had to be adjusted to obtain a good match of the damage. Final values used were 90 lb/in<sup>2</sup> for Vehicle 1 and 35 lb/in<sup>2</sup> for Vehicle 2. The brake and steer inputs to both vehicles were also adjusted to fine tune the spin out trajectories.

GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION  
COLLISION AND TRAJECTORY

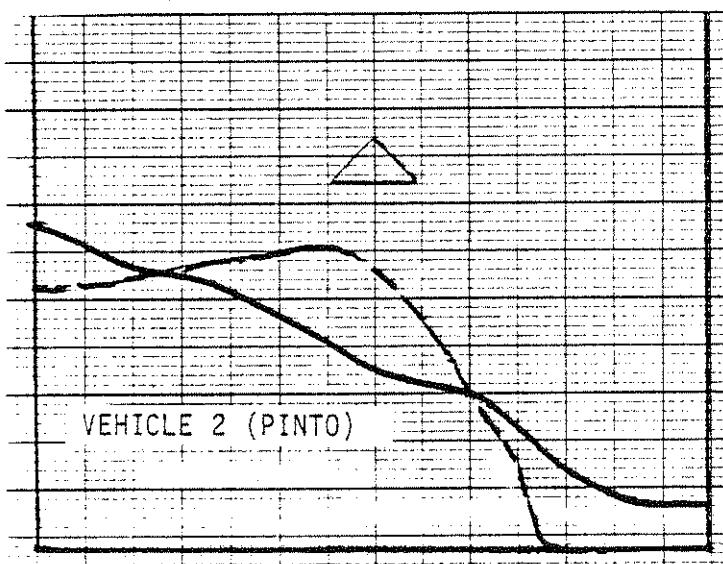
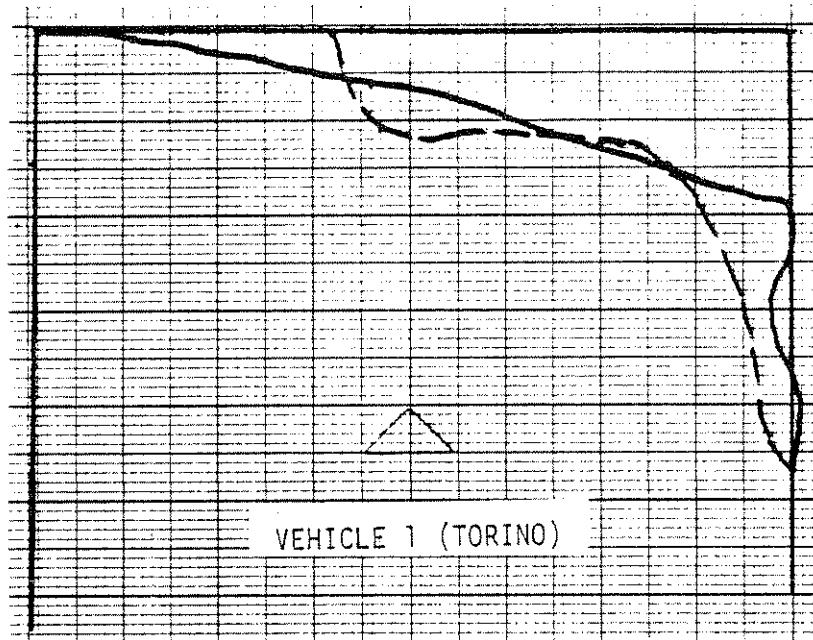
\* RICSAC TEST #4 TORINO-PINTO 38.7MPH \*



Axis intervals are 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
C.G. POSITION		HEADING				C.G. POSITION		HEADING					
XCI	YCI	PSI1	FWD	LATERAL	ANGULAR	XC1F	YC1F	PSI1F					
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.					
VEHICLE # 1	0.6	-0.0	0.0	38.7	-0.0	0.0	40.3	55.1	126.6	IN MOTION AT 5.0 SEC AFTER INITIAL CONTACT	12 R F E W 2 16.9		
VEHICLE # 2	-5.4	3.4	10.0	0.0	0.0	0.0	73.8	67.0	69.6	VEHICLE AT REST	0 6 B D E W 4 26.3		

Figure 3-21 GRAPHIC DISPLAY, TEST NO. 4



— Actual  
- - - Predicted



Figure 3-22 TEST NO. 4 - PREDICTED VERSUS ACTUAL DAMAGE

Test No. 5 - 10° Offset Front-to-Rear Impact - Ford Torino Vs.  
Honda Civic - Impact Speeds, 39.7/0 mph

	Vehicle 1				Vehicle 2			
	X <sub>1</sub> ft	Y <sub>1</sub> ft	ψ <sub>1</sub> deg	ΔV <sub>1</sub> mph	X <sub>2</sub> ft	Y <sub>2</sub> ft	ψ <sub>2</sub> deg	ΔV <sub>2</sub> mph
Actual	252.0	0.0	0.0	16.3	59.0	35.0	282.0	25.1
SMAC Computed	173.8	-22.3	-7.9	15.1	89.7	35.6	285.2	26.8

This case had a variety of complications which made the SMAC reconstruction difficult. The most significant of these problems was that both of the tires on the right side of Vehicle 2, the Honda, were off the ground for the majority of its rotation. This can be simulated by setting the braking torques and cornering stiffnesses for both of these tires to zero. However, the left side tires cannot be handled as easily. For instance, since the entire weight of the vehicle is supported by the two tires, the tire force (whether side or circumferential) that can be supported is  $\mu W$ , where  $W$  equals the weight of the vehicle and  $\mu$  is the tire ground friction coefficient. The SMAC program, however, assumes that the weight is equally distributed among the four tires (except to correct for the position of the center of gravity); thus, the maximum tire force the SMAC program will allow for the left side of the vehicle (regardless of the input values) is  $\frac{W}{2}$ .

Furthermore, the right side tires of Vehicle 2 are not off the ground throughout the entire spin out and once they return to the surface, their cornering stiffnesses are no longer zero. Since the SMAC program allows only one value to be input for the cornering stiffness for each tire, it is not possible to accurately simulate the situation.

Regarding Vehicle 1's trajectory, it should be noted that its umbilical cable became fully extended bringing it to a rapid halt at the end of its spin out.

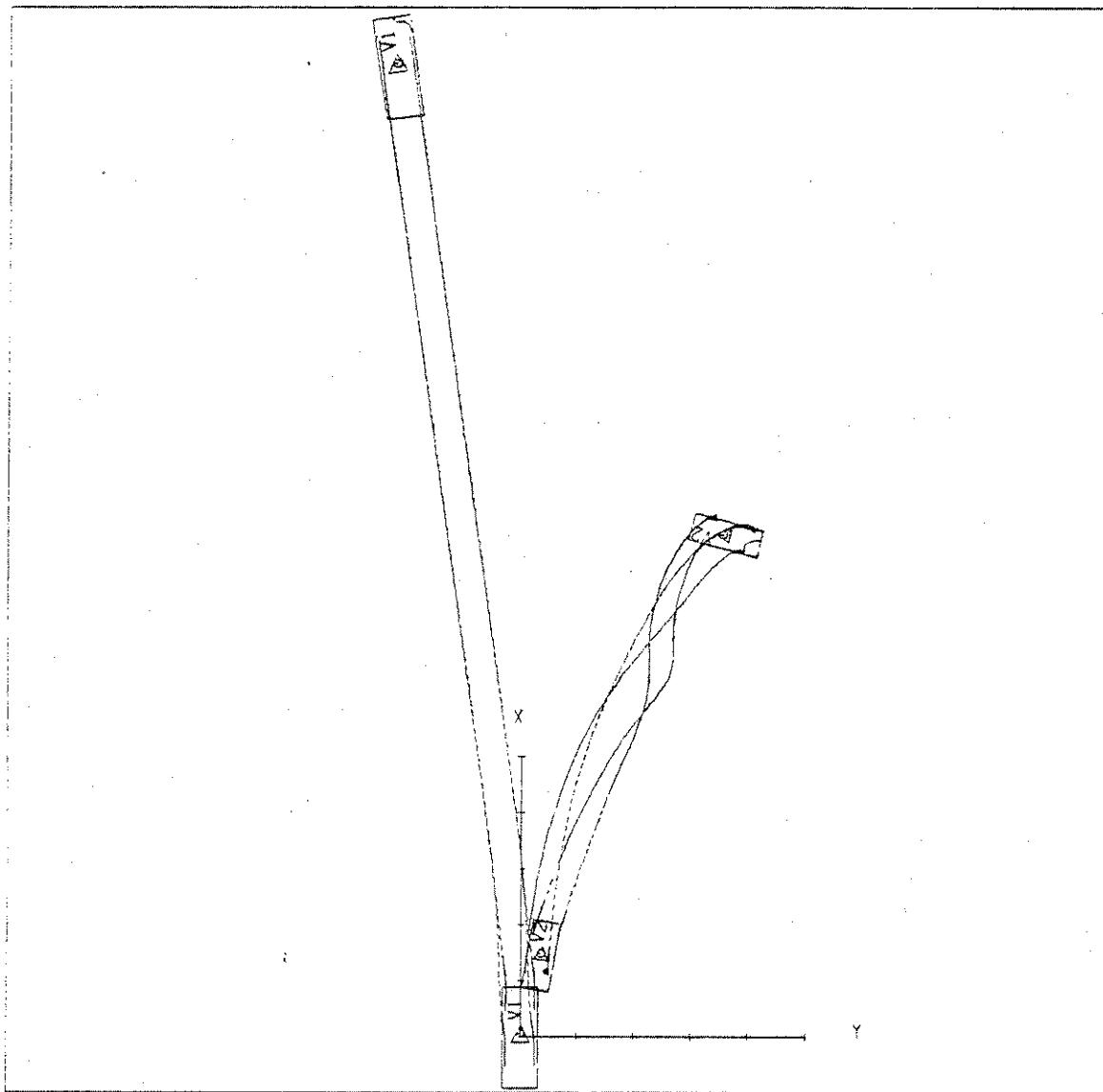
Because of these compounding factors, the final run was selected on the basis of its matching the velocity changes and the rotation of Vehicle 2. The match is surprisingly good. The X displacement of Vehicle 1 is slightly underestimated as is the spin out distance for Vehicle 2 although the latter could probably be improved by reducing its rolling resistance. The brake inputs used for Vehicle 2 were engine braking at 0.08 g, whereas 0.15 g has been used as an established value; however, whether this applies to a vehicle with automatic transmission without the engine running is open to argument.

The damage profiles are shown in Figure 3-24. That for Vehicle 1 is considerably overestimated due, in part, to the elastic recovery of the 5 mph energy absorbing bumper but also to the lack of any corner stiffening effects. Vehicle 2's damage is slightly underestimated but considering the severe damage that occurred to this vehicle is certainly acceptable.

## GRAPHIC DISPLAY OF OUTPUTS OF ACCIDENT RECONSTRUCTION

## COLLISION AND TRAJECTORY

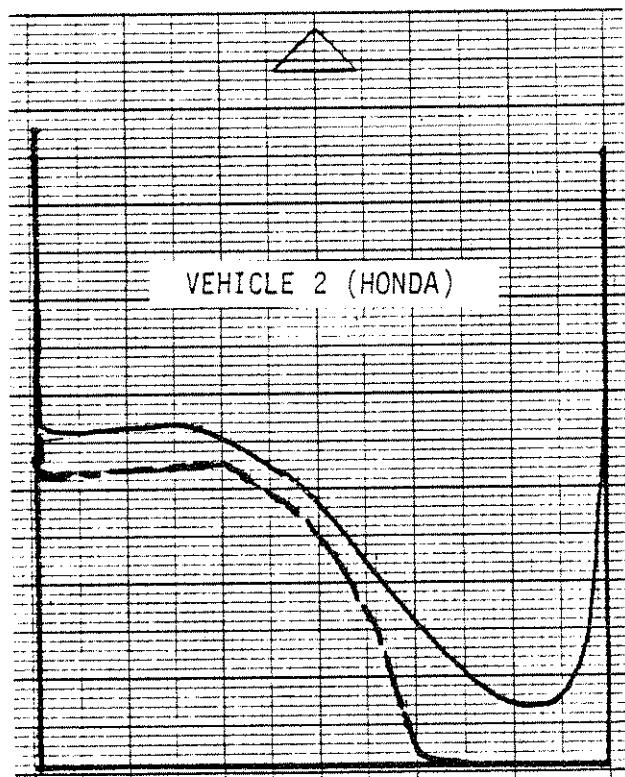
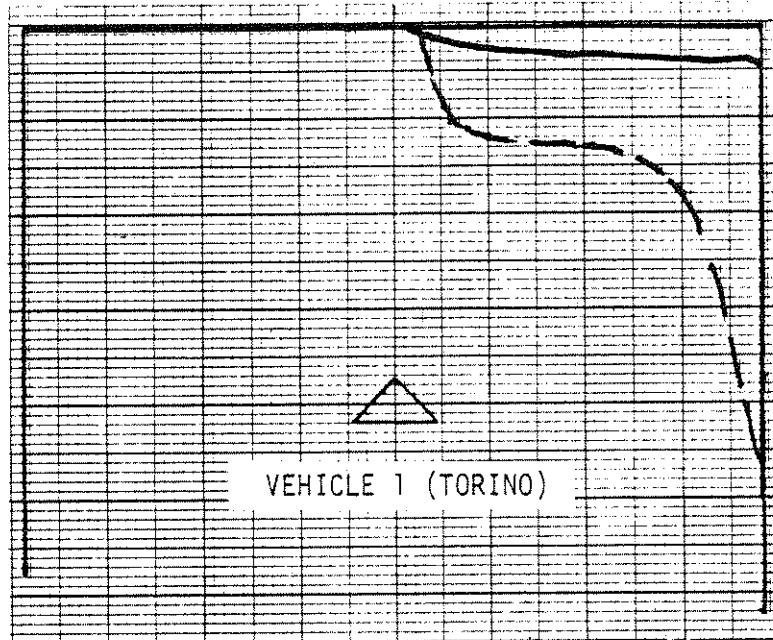
★ RICSAC TEST #5 TORINO-HONDA 39.3MPH/0.0 ★



AXIS INTERVALS ARE 10. FEET

RECONSTRUCTED POSITIONS AND VELOCITIES AT IMPACT						DISPLAYED FINAL POSITIONS				VEHICLE DAMAGE INDICES	$\Delta V$ MPH		
C.G. POSITION		HEADING				C.G. POSITION		HEADING					
X <sub>C1</sub>	Y <sub>C1</sub>	PSI <sub>11</sub>	FWD	LATERAL	ANGULAR	X <sub>C1F</sub>	Y <sub>C1F</sub>	PSI <sub>1F</sub>	DEG.				
FT.	FT.	DEG.	MPH	MPH	DEG/SEC	FT.	FT.	DEG.	DEG.				
VEHICLE # 1	0.7	0.0	0.0	39.2	0.0	0.3	173.8	-22.3	-7.9	IN MOTION AT 6.0 SEC AFTER INITIAL CONTACT	12 R F E W 2 15.1		
VEHICLE # 2	14.9	3.8	10.0	0.0	0.0	0.0	89.7	35.6	285.2	VEHICLE AT REST	06 B Y E W 5 26.8		

Figure 3-23 GRAPHIC DISPLAY, TEST NO. 5



— Actual  
- - - Predicted



Figure 3-24 TEST NO. 5 - PREDICTED VERSUS ACTUAL DAMAGE

4.0 CONCLUSIONS AND RECOMMENDATIONS

4.1 The CRASH Program

The major discrepancies in the CRASH results stemmed from the damage analysis subroutine and, in particular, the values used for the empirical stiffness coefficients for certain vehicle sizes and impact configurations. The velocity changes in the high level head-on impact (Test 12) were overestimated suggesting that the stiffness coefficients are too low for this particular impact/vehicle size configuration. The velocity changes for the corresponding low level test (No. 11) were also underestimated but to a lesser extent. A similar problem occurred with the rear end impacts, the velocity changes in all these tests and for all vehicles were severely underestimated, suggesting that the stiffness coefficients should be upgraded.

The SPIN II routine which calculates the separation velocities from the spin out trajectories was assessed separately. In general, the agreement between predicted and measured velocities was extremely good. The agreement was better for axial type collisions than for oblique or intersection type collisions. This is because spin out trajectories for axial type collisions are, in general, more nearly linear and the estimation of the velocity dissipated in the spin out correspondingly more accurate.

During the course of the reconstructions, an error in the SPIN II routine was discovered involving trajectories where the vehicle was tracking a curved path with no end of rotation point. For this situation, the separation velocities were grossly overestimated; a suggested correction to the problem is given in Appendix 1.

Recommendations

- Update the stiffness coefficients using the present data

- Include stationary vehicle option to minimize errors in damage analysis carrying over to the impact speed estimation.

#### 4.2 The SMAC Program

One of the main problems experienced in evaluating the effectiveness of the SMAC program was the lack of knowledge that exists regarding appropriate values of certain input parameters for particular collision configurations and vehicle sizes. Because of this lack of certainty, it was difficult to determine in some cases whether the lack of success in matching the measured data was the result of inappropriate input values or a limitation of the program. For example, in the 60 degree front-to-side impact tests the inter-vehicle friction coefficient used in reconstructing Test 1 was 1.5, whereas that used for Case 7 was 0.3. The question arises whether this difference is the result of differences between the vehicles (Test 1 used a rather corroded Ford Pinto, whereas Test 7 used a VW Rabbit for the struck vehicle), or are there limitations in the program which are being compensated. An obvious way to resolve this dilemma would be to analyze the crash test data to determine input values for the indirect parameters in each test, i.e., the vehicle stiffness coefficient, intervehicle friction coefficients, coefficients of restitution, etc. This would mean that the input deck for each SMAC reconstruction was completely defined such that any deficiencies in the reconstruction could be attributed to limitations in the program. Ideally, this analysis should also include a film analysis of the overhead cameras to study the build-up of the collision interface to assess whether an isotropic homogenous body is an acceptable simulation of the vehicle structure.

Another limitation that was experienced in using the program was the lack of weight transfer effects. In a number of the staged collisions there were instances where one or more of the wheels on a particular vehicle became airborne. Since the program does not simulate these effects, this would automatically introduce some error in computing both the amount of translation and rotation of the vehicle.

### Recommendations

- Include hard points and corner stiffness effects in the simulation of the vehicle structure.
- Include weight transfer effects.
- Modify reporting format so that output can be summarized in one or two pages.

#### 4.3

### Rotation Effects

The failure to include the effects of vehicle rotation into the determination of the separation velocities, and consequently, the changes in velocity, should detract little from the overall evaluation of the SMAC and CRASH II programs. Concerning the SMAC program, the  $\Delta V$ 's were just one of three measures of performance. The agreement between the predicted rest positions and damage profiles with those observed during the staged collisions, is, by itself, basis enough for believing the SMAC program to be a fairly accurate representation of the physical system being simulated. In those cases, in which rotation was not a significant factor, the  $\Delta V$  comparisons lend additional support to such a hypothesis. Moreover, qualitative analysis of those vehicles undergoing significant rotation, indicated that the predicted  $\Delta V$ 's were certainly within a tolerable range of the true value of the velocity change.

The assessment of the CRASH II program is based entirely on the  $\Delta V$ 's and separation velocities. Again, the cases with little or no rotation provide ample evidence of CRASH's accuracy. Even in tests in which one of the vehicles experienced high angular velocities, the fact that close agreement was obtained for the other vehicle is significant. In the nonaxial collisions, where the rotational problems were encountered, the  $\Delta V$ 's for both the vehicles are not independent of one another; thus good agreement for one of the vehicles, reflects

favorably on the accuracy of the other's reconstruction. Once again, the qualitative analyses on the cases with significant rotation enhances the accuracy judgments of the CRASH II results.

If one were sufficiently concerned about the accuracy of CRASH II and SMAC performance in those cases which had rotational problems, there are two possible courses of action, neither of which was explored during the course of the present study, due to time and financial constraints.

The first, and most obvious, solution is to reduce the raw acceleration data again, using software that takes into consideration the rotational effects. At Calspan, work on this type of software had been initiated, for the problem in three dimensions, but was discontinued due to difficulty in obtaining stable estimates of the angular motion because of biases in the accelerometers. Reducing the problem to two dimensions may alleviate some of the estimation difficulties, but, more importantly, the data collected for the staged collisions includes both yaw angle and yaw rate. If this information could be incorporated into the integration algorithms, the problem may be greatly simplified.

The other approach, which is only applicable to the present study, and would allow one to compare only the SMAC estimates of  $\Delta V$ , involves altering the SMAC program to compute the velocities at the firewall as if any vehicle rotation had been disregarded. All the information necessary to accomplish this transformation is available at the end of the DAUX subroutine. The results could subsequently be compared directly to the experimental data.

APPENDIX I

CRASH II PROGRAM ERROR

Ø

## CRASH II PROGRAM ERROR

In the course of this study, an error was found in the CRASH II program. The error occurred for spin outs in which a non-skidding vehicle had a curved trajectory with no end-of-rotation point defined. For these types of situations, i.e., where the vehicle is tracking, the program sets the end-of-rotation point equal to the separation point in preparation for the calculation of the error term in the trajectory simulation subroutine. This is appropriate since in comparing the predicted to actual end-of-rotation point, for a tracking vehicle, the separation point is the end of rotation.

The SPIN II routine, however, is coded so that it expects the end-of-rotation point to be equal to the final rest position. When it is not, the arc length of the spin-out is grossly overestimated, with the result that the separation velocities, that are subsequently calculated, are too large.

The program was changed in order to correct this error, although an exhaustive check of the new coding has not been done. The changes that were implemented are given below. In SUBROUTINE START2, after the COMMON block /CRASH/ insert:

```
COMMON/STTOSP/XEND,YEND  
after 1500 IF(JCURVC1).EQ. 1)GO TO 1505  
insert: XEND = XCR1  
        YEND = YCR1  
and after 1600 IF(JCURV(2). EQ. 1)GO TO 1605  
insert: XEND = XCR2  
        YEND = YCR2
```

Then in SUBROUTINE SPIN2, after the COMMON block /CRASH/ insert:

```
COMMON/STTOSP/XEND,YEND  
in two places, and then immediately after label 310 and label 350,  
replace: XC1P = XC1[12]*12      and YC1P = YC1[12]*12  
with:    XC1P = XEND  
          YC1P = YEND
```

APPENDIX II

CRASH INPUT AND OUTPUT LISTINGS

1. TITLE?  
?TEST #1 CHEVELLE VS PINTO

2. SIZE CATEGORIES?  
?I S

3. VDI, #1  
?11EZn2

4. VDI, #2  
?01RDEn3

5. ACTUAL WEIGHTS? (Y OR N)  
?Y

6. WEIGHT #1  
?4621

7. WEIGHT #2  
?3082

8. REST & IMPACT? (Y OR N)  
?Y

9. REST COORDINATES?  
?-2.4 -1, -1.5 / .5 2.5 105.

10. IMPACT COORDINATES?  
?-10.8 1, -30. 0, -5.5 90.

11. SKIDDING OF # 1? (Y OR N)  
?Y

12. SKIDDING STOP BEFORE REST? (Y OR N)  
?N

14. CURVED PATH? (Y OR N)  
?N

15. ROTATION DIRECTION #1?  
?Cn

17. MORE THAN 300 DEG? (Y OR N)  
?N

18. SKIDDING OF # 2? (Y OR N)  
?Y

19. SKIDDING STOP BEFORE REST? (Y OR N)  
?N

21. CURVED PATH? (Y OR N)  
?N

22. ROTATION DIRECTION # 2?  
?Cn

24. MORE THAN 300 DEG? (Y OR N)  
?N

25. TIRE-GROUND FRICTION?  
?.07

26. ROLLING RESISTANCE OPTION? (Y OR N)

?Y

27. ROLL. RESISTANCES, INDIV. WHEELS # 1

?0.01 .01 .2 .2

28. ROLL. RESISTANCES, INDIV. WHEELS # 2

?0.01 .01 .2 .2

29. TRAJECTORY SIMULATION? (Y OR N)

?N

30. DAMAGE DIMENSIONS? (Y OR N)

?Y

31. END DAMAGE WIDTH #1

?40.

32. END DAMAGE DEPTH #1

?4. 5.5 7. 10.2 12.1 14.8

33. END DAMAGE MIDPOINT OFFSET #1

?14.3

34. SIDE DAMAGE WIDTH #2

?113.3

35. SIDE DAMAGE DEPTH #2

?5.5 12. 10.0 11.8 9. 4.1

36. SIDE DAMAGE MIDPOINT OFFSET #2

?21.0

37. FORCE DIRECTIONS (Y OR N)

?Y

38. PRINCIPAL FORCE ANGLE #1?

?-30.

39. PRINCIPAL FORCE ANGLE #2?

?30.

THANK YOU VERY MUCH

SUMMARY OF CRASH RESULTS  
TEST #1 CHEVELLE VS PINTO

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	9.0 MPH -14.4 DEG	14.4 MPH 45.5 DEG
SPEED CHANGE (DAMAGE ONLY)	18.5 MPH -30.0 DEG	27.7 MPH 30.0 DEG
IMPACT SPEED	20.6 MPH	20.4 MPH
ENERGY DISSIPATED BY DAMAGE	24652.4 FT-LB	169174.7 FT-LB
SPEED ALONG LINE THRU CGS	20.5 MPH	11.5 MPH
SPEED ORTHOG. TO CG LINE	1.5 MPH	-16.9 MPH
CLOSING VELOCITY	II-3	ZQ-6057-V-6

## SUMMARY OF CRASH RESULTS

TEST #1 CHEVELLE VS PINTO

## VEHICLE # 1

SPEED CHANGE				BASIS OF RESULTS	
IMPACT SPEED	MPH	TOTAL	LONG.		LATERAL
20.6*	9.6*	9.6*	-9.3*	2.4*	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
18.5*	-16.0*	-16.0*	9.3*	DAMAGE DATA ONLY	DAMAGE

## VEHICLE # 2

SPEED CHANGE				BASIS OF RESULTS	
IMPACT SPEED	MPH	TOTAL	LONG.		LATERAL
20.4*	14.4*	14.4*	-10.1*	-10.3*	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
27.7*	-24.0*	-24.0*	-13.9*	DAMAGE DATA ONLY	DAMAGE

### SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	-11.50 FT.	-0.00 FT.
IMPACT Y-POSITION	1.45 FT.	-0.40 FT.
IMPACT HEADING ANGLE	-30.00 DEG.	89.99 DEG.
REST X-POSITION	-2.40 FT.	7.50 FT.
REST Y-POSITION	-1.00 FT.	2.50 FT.
REST HEADING ANGLE	-1.50 DEG.	104.99 DEG.
DIRECTION OF ROTATION	CW	CW
AMOUNT OF ROTATION	<300	<300

### COLLISION CONDITIONS

	VEHICLE # 1	VEHICLE # 2
XCO10	= -11.5 FT.	XCO20 = -0.0 FT.
YCO10	= 1.5 FT.	YC20 = -0.4 FT.
PSI10	= -30.0 DEGREES	PSI20 = 90.0 DEGREES
PSI100	= 0.0 DEG/SEC	PSI200 = 0.0 DEG/SEC
U10	= 20.0 MPH	U20 = 20.4 MPH
V10	= 0.0 MPH	V20 = 0.0 MPH

### SEPARATION CONDITIONS

XCSI	= -10.8 FT.	XCS2 = 0.0 FT.
YCSI	= 1.0 FT.	YCS2 = -0.5 FT.
PSIS1	= -30.0 DEG	PSIS2 = 90.0 DEG
US1	= 11.2 MPH	US2 = 10.3 MPH
VSI	= 2.4 MPH	VS2 = -10.3 MPH
PSISD1	= 45.3 DEG/SEC	PSISD2 = 23.4 DEG/SEC

### RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	9.0 MPH	14.4 MPH
SPEED CHANGE (DAMAGE ONLY)	-14.4 DEG	45.5 DEG
IMPACT SPEED	18.5 MPH	27.7 MPH
ENERGY DISSIPATED BY DAMAGE	-30.0 DEG	30.0 DEG
SPEED ALONG LINE THRU CGS	20.6 MPH	20.4 MPH
SPEED ORTHOG. TO CG LINE	24052.4 FT-LB	109174.7 FT-LB
CLOSING VELOCITY	1.5 MPH	-16.9 MPH
	32.0 MPH	

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

VEHICLE # 1  
 TYPE-----INTERMEDIATE  
 WEIGHT-----4621.0 LBS.  
 VDI-----11FZer2  
 L-----46.0 IN.  
 C1-----4.0 IN.  
 C2-----5.5 IN.  
 C3-----7.0 IN.  
 C4-----10.2 IN.  
 C5-----12.1 IN.  
 C6-----14.8 IN.  
 D-----19.1 IN.  
 RHO-----1.00 \*  
 ANG-----330.0 DEG.

VEHICLE # 2  
 TYPE-----SUBCOMPACT  
 WEIGHT-----3082.0 LBS.  
 VDI-----01RDEW3  
 L-----113.3 IN.  
 C1-----.5 IN.  
 C2-----12.0 IN.  
 C3-----10.8 IN.  
 C4-----11.8 IN.  
 C5-----9.0 IN.  
 C6-----4.1 IN.  
 D-----21.8 IN.  
 RHO-----1.00 \*  
 ANG-----30.0 DEG.

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	54.7 INCHES	A2	=	46.3 INCHES
B1	=	59.2 INCHES	B2	=	50.1 INCHES
TR1	=	51.8 INCHES	TR2	=	54.6 INCHES
I1	=	44739.0 LB-SEC**2-IN	I2	=	23537.7 LB-SEC**2-IN
m1	=	11.959 LB-SEC**2/IN	m2	=	7.976 LB-SEC**2/IN
XF1	=	98.8 INCHES	XF2	=	83.3 INCHES
XR1	=	-114.0 INCHES	XR2	=	-91.6 INCHES
YS1	=	38.5 INCHES	YS2	=	33.6 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

RF-----	.01
LF-----	.01
RR-----	.20
LR-----	.20
MU-----	.87

## VEHICLE # 2

RF-----	.01
LF-----	.01
RR-----	.20
LR-----	.20

1. TITLE?

?TEST # 2 CHEVELLE VS PINTO

2. SIZE CATEGORIES?

?1 S

3. VDI, #1

?11FDen2

4. VDI, #2

?02RDen4

5. ACTUAL WEIGHTS? (Y OR N)

?Y

6. WEIGHT #1

?4021

7. WEIGHT #2

?3081

8. REST & IMPACT? (Y OR N)

?Y

9. REST COORDINATES?

?11. 9.4 55. 23.0 12.5 134.

10. IMPACT COORDINATES?

?-11.2 8.5 -30.0 0.0 90.

11. SKIDDING OF # 1? (Y OR N)

?N

14. CURVED PATH? (Y OR N)

?N

15. ROTATION DIRECTION #1?

?CW

17. MORE THAN 360 DEG? (Y OR N)

?N

18. SKIDDING OF # 2? (Y OR N)

?Y

19. SKIDDING STOP BEFORE REST? (Y OR N)

?N

21. CURVED PATH? (Y OR N)

?N

23. ROTATION DIRECTION # 2?

?CW

24. MORE THAN 360 DEG? (Y OR N)

?N

25. TIRE-GROUND FRICTION?

?01

26. ROLLING RESISTANCE OPTION? (1 OR 2)  
?1

27. ROLL. RESISTANCES, INDIV. WHEELS # 1  
?1. .02 .2 .2

28. ROLL. RESISTANCES, INDIV. WHEELS # 2  
? .02 .02 1. 1.

31. TRAJECTORY SIMULATION? (Y OR N)  
?N

31. DAMAGE DIMENSIONS? (Y OR N)  
?Y

41. END DAMAGE WIDTH #1  
?75.0

42. END DAMAGE DEPTH #1  
? .5 2.4 3.7 6.9 12. 16.5

43. END DAMAGE MIDPOINT OFFSET #1  
?0.

44. SIDE DAMAGE WIDTH #2  
?118.5

45. SIDE DAMAGE DEPTH #2  
?0.75 22.75 23.5 21.3 10. 0.

46. SIDE DAMAGE MIDPOINT OFFSET #2  
?13.7

52. FORCE DIRECTIONS (Y OR N)  
?N

## SUMMARY OF CRASH RESULTS

TEST # 2 CHEVELLE VS PINTO

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	20.6 MPH -17.2 DEG	30.9 MPH 42.8 DEG
SPEED CHANGE (DAMAGE ONLY)	19.3 MPH -30.0 DEG	29.0 MPH 60.0 DEG
IMPACT SPEED	29.6 MPH	33.3 MPH
ENERGY DISSIPATED BY DAMAGE	31832.5 FT-LB	169278.6 FT-LB
SPEED ALONG LINE THRU CGS	29.3 MPH	20.7 MPH
SPEED ORTHOG. TO CG LINE	4.4 MPH	-26.0 MPH
CLOSING VELOCITY	50.0 MPH	

## SUMMARY OF CRASH RESULTS

~~TEST # 2 CHEVELLE VS PINTO~~

VEHICLE # 1

\*\*\*\*\* \* SPEED CHANGE \* \*\*\*\*\*  
 \* IMPACT SPEED \* MPH \* BASIS  
 \* MPH \* OF \* RESULTS  
 \* \* TOTAL \* LONG. \* LATERAL \*  
 \* \* \* \* \*  
 \* 29.0 \* 20.0 \* -19.7 \* \* SPINOUT TRAJECTORIES \*  
 \* \* \* \* \* 6.1 \* AND CONSERVATION OF \*  
 \* \* \* \* \* LINEAR MOMENTUM \*  
 \* \* \* \* \*  
 \* \* \* \* \* SPINOUT TRAJECTORIES \*  
 \* \* \* \* \* AND \*  
 \* \* \* \* \* DAMAGE \*  
 \* \* \* \* \*  
 \* 19.3 \* -10.7 \* 9.7 \* DAMAGE DATA ONLY  
 \* \* \* \*

VEHICLE # 2

\*\*\*\*\*  
 \* IMPACT SPEED \* SPEED CHANCE MPH \*\*\*\*\*  
 \* MPH \*\*\*\*\*  
 \* TOTAL LONG. LATERAL \*\*\*\*\*  
 \* 33.3\* 30.9\* -22.7\* -21.0\*  
 \* SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM  
 \*  
 \* SPINOUT TRAJECTORIES AND DAMAGE  
 \*  
 \* 29.0\* -14.0\* -25.1\* DAMAGE DATA ONLY

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

## VEHICLE # 1

## VEHICLE # 2

TYPE	INTERMEDIATE	TYPE	SUBCOMPACT
WEIGHT	4621.0 LBS.	WEIGHT	3081.0 LBS.
VDT	11FDEn2	VDT	02RDEn4
L	15.5 IN.	L	118.5 IN.
C1	.5 IN.	C1	6.8 IN.
C2	2.4 IN.	C2	22.8 IN.
C3	3.7 IN.	C3	23.5 IN.
C4	6.9 IN.	C4	21.3 IN.
C5	12.0 IN.	C5	10.0 IN.
Co	10.5 IN.	Co	0.0 IN.
D	15.0 IN.	D	5.6 IN.
RHO	1.00 *	RHO	1.00 *
ANG	330.0 DEG. *	ANG	60.0 DEG. *

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	54.7 INCHES	A2	=	46.3 INCHES
B1	=	59.2 INCHES	B2	=	50.1 INCHES
Tr1	=	61.8 INCHES	Tr2	=	54.6 INCHES
rr	=	44739.0 LB-SEC**2-IN	rz	=	23530.1 LB-SEC**2-IN
m1	=	11.959 LB-SEC**2/IN	m2	=	7.974 LB-SEC**2/IN
Xr1	=	98.8 INCHES	Xr2	=	83.3 INCHES
Xr1	=	-114.0 INCHES	Xr2	=	-91.0 INCHES
Yr1	=	38.5 INCHES	Yr2	=	33.6 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

## VEHICLE # 2

RF	.50	RF	.02
Lf	.02	Lf	.02
RR	.20	RR	1.00
LR	.20	LR	1.00

MU .87

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	-11.62 FT.	-0.00 FT.
IMPACT Y-POSITION	8.74 FT.	-0.52 FT.
IMPACT HEADING ANGLE	-30.00 DEG.	89.99 DEG.
REST X-POSITION	11.00 FT.	23.50 FT.
REST Y-POSITION	9.40 FT.	12.50 FT.
REST HEADING ANGLE	54.99 DEG.	133.98 DEG.
END-OF-ROTATION X-POSITION	-11.62 FT.	
END-OF-ROTATION Y-POSITION	8.74 FT.	
END-OF-ROTATION HEADING ANGLE	-30.00 DEG.	
DIRECTION OF ROTATION	CW	CW
AMOUNT OF ROTATION	<360	<360

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
XCI01 = -11.0 FT.	XC201 = -0.0 FT.
YC101 = 8.7 FT.	YC201 = -.5 FT.
PSI101 = -30.0 DEGREES	PSI201 = 90.0 DEGREES
PSI1D01 = 0.0 DEG/SEC	PSI2D01 = 0.0 DEG/SEC
U101 = 29.0 MPH	U201 = 33.3 MPH
V101 = 0.0 MPH	V201 = 0.0 MPH

## SEPARATION CONDITIONS

XCS1	= -11.0 FT.	XCS2	= -0.0 FT.
YCST1	= 8.7 FT.	YCS2	= -.5 FT.
PSIS1	= -30.0 DEG	PSIS2	= 90.0 DEG
UST1	= 9.9 MPH	US2	= 10.0 MPH
VST1	= 0.1 MPH	VS2	= -21.0 MPH
PSISDT1	= 0.0 DEG/SEC	PSISDT2	= 45.0 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (RAJ. ONLY)	20.6 MPH	30.9 MPH
	-17.2 DEG	42.8 DEG
SPEED CHANGE (DAMAGE ONLY)	19.3 MPH	29.0 MPH
	-30.0 DEG	60.0 DEG
IMPACT SPEED	29.6 MPH	33.3 MPH
ENERGY DISSIPATED BY DAMAGE	31832.5 FT-LB	109278.6 FT-LB
SPEED ALONG LINE THRU CGS	29.3 MPH	20.7 MPH
SPEED ORTHOG. TO CG LINE	4.4 MPH	-26.0 MPH
CLOSING VELOCITY	50.0 MPH	

1. TITLE:  
Z1251 # 6

2. SIZE CATEGORIES?  
#1 SC

3. VOL, #1  
111.1600

4. VOL, #2  
102.0000

5. ACTUAL COORDINATES? (Y OR N)  
YY

6. HEIGHT #1  
74500

7. HEIGHT #2  
74520

8. REST & IMPACT? (Y OR N)  
NN

9. REST COORDINATES?  
Z03. 11. 10. 20. 21. 242.

10. IMPACT COORDINATES?  
Z03. 0. 0. 11. 1 2.07 120.

11. SKIDDING OF # 1? (Y OR N)  
NN

12. CURVED PATH? (Y OR N)  
NN

13. ROTATION DIRECTION #1?  
Z0a

14. MORE THAN 300 DEG? (Y OR N)  
NN

15. SKIDDING OF # 2? (Y OR N)  
YY

16. SKIDDING STOP BEFORE REST? (Y OR N)  
NN

17. CURVED PATH? (Y OR N)  
NN

18. ROTATION DIRECTION #2?  
Z0a

19. MORE THAN 300 DEG? (Y OR N)  
NN

20. TIME-OF-CONTACT DIRECTION?  
Z07

26. ROLLING RESISTANCE OPTION? (Y OR N)  
?Y

27. ROLL. RESISTANCES, INDIV. WHEELS # 1  
?0.01 .01 .2 .2

28. ROLL. RESISTANCES, INDIV. WHEELS # 2  
?0.01 .01 1. .2

29. TRAJECTORY SIMULATION? (Y OR N)  
?N

30. DAMAGE DIMENSIONS? (Y OR N)  
?Y

41. END DAMAGE WIDTH #1  
?54.0

42. END DAMAGE DEPTH #1  
?0.5 .5 1.25 1.5 1.75 2.25

43. END DAMAGE MIDPOINT OFFSET #1  
?9.75

44. SIDE DAMAGE WIDTH #2  
?71.

45. SIDE DAMAGE DEPTH #2  
?4. 12. 17.3 19.3 17. 0.25

46. SIDE DAMAGE MIDPOINT OFFSET #2  
?+3.25

52. FORCE DIRECTIONS (Y OR N)  
?N

THANK YOU VERY MUCH

#### SUMMARY OF CRASH RESULTS

TEST # 0

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	12.4 MPH -10.8 DEG	20.4 MPH 49.2 DEG
SPEED CHANGE (DAMAGE ONLY)	12.7 MPH -30.0 DEG	20.9 MPH 00.0 DEG
IMPACT SPEED	24.9 MPH	20.5 MPH
ENERGY DISSIPATED BY DAMAGE	5409.2 FT-LB	83328.5 FT-LB
SPEED ALONG LINE THRU CG	24.5 MPH	1.0 MPH
SPEED ORTHOG. TO CG LINE	-4.3 MPH	-19.3 MPH
CLOSING VELOCITY	31.5 MPH	

II-14

ZQ-6057-V-6

## SUMMARY OF CRASH RESULTS

TEST # 6

## VEHICLE # 1

IMPACT SPEED	SPEED CHANGE	MPH	RESULTS		
			TOTAL	LONG.	LATERAL
24.9*	12.4*	-12.2*	2.3 RATE CONSERVATION OF	SPINOUT TRAJECTORIES	
			LINEAR MOMENTUM		*
					*
12.7*	12.7*	-11.0*	0.4*	DAMAGE DATA ONLY	*
					*

\* SPINOUT TRAJECTORIES AND DAMAGE

## VEHICLE # 2

IMPACT SPEED	SPEED CHANGE	MPH	RESULTS		
			TOTAL	LONG.	LATERAL
20.0*	20.4*	-10.3*	-10.4*	AND CONSERVATION OF	SPINOUT TRAJECTORIES
				LINEAR MOMENTUM	*
					*
20.9*	20.9*	-10.4*	-10.1*	DAMAGE DATA ONLY	*
					*

\* SPINOUT TRAJECTORIES AND DAMAGE

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	-7.73 FT.	11.40 FT.
IMPACT Y-POSITION	0.00 FT.	2.15 FT.
IMPACT HEADING ANGLE	0.00 DEG.	119.99 DEG.
REST X-POSITION	00.00 FT.	20.00 FT.
REST Y-POSITION	11.00 FT.	21.00 FT.
REST HEADING ANGLE	15.00 DEG.	241.97 DEG.
END-OF-ROTATION X-POSITION	0.00 FT.	
END-OF-ROTATION Y-POSITION	0.00 FT.	
END-OF-ROTATION HEADING ANGLE	0.00 DEG.	
DIRECTION OF ROTATION	Ca	Ca
AMOUNT OF ROTATION	<300	<300

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
XCO10' = -7 FT.	XCO20' = 11.4 FT.
YCO10' = 0.0 FT.	YCO20' = 2.1 FT.
PSI10 = 0.0 DEGREES	PSI20 = 120.0 DEGREES
PSI100 = 0.0 DEG/SEC	PSI200 = 0.0 DEG/SEC
V10 = 24.9 MPH	V20 = 20.5 MPH
V10 = 0.0 MPH	V20 = 0.0 MPH

## SEPARATION CONDITIONS

XCS1 = 0.0 FT.	XCS2 = 11.1 FT.
YCS1 = 0.0 FT.	YCS2 = 2.1 FT.
PSIS1 = 0.0 DEG	PSIS2 = 120.0 DEG
V11 = 12.7 MPH	V21 = 7.2 MPH
V11 = 2.3 MPH	V21 = -15.4 MPH
PSISD1 = 0.0 DEG/SEC	PSISD2 = 137.0 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	+2.4 MPH -10.8 DEG	20.4 MPH 49.2 DEG
SPEED CHANGE (DAMAGE ONLY)	+2.7 MPH -30.0 DEG	20.9 MPH 60.0 DEG
IMPACT SPEED	24.9 MPH	20.5 MPH
ENERGY DISSIPATED BY DAMAGE	2409.2 FT-LB	83328.5 FT-LB
SPEED ALONG LINE THRU CGS	24.5 MPH	7.0 MPH
SPEED ORTHOG. TO CG LINE	-4.3 MPH	-19.3 MPH
CLOSING VELOCITY	31.2 MPH	

## SUMMARY OF DAMAGE DATA

(X INDICATES DEFAULT VALUE)

## VEHICLE # 1

TYPE ----- INTERMEDIATE  
 WEIGHT ----- 4300.0 LBS.  
 VUL ----- 0.1HZx1  
 L ----- 24.0 IN.  
 C1 ----- .5 IN.  
 C2 ----- .5 IN.  
 C3 ----- 1.3 IN.  
 C4 ----- 1.5 IN.  
 C5 ----- 1.8 IN.  
 C6 ----- 2.3 IN.  
 C7 ----- 10.4 IN.  
 Rn0 ----- 1.00 \*  
 An0 ----- 330.0 DEG. \*

## VEHICLE # 2

TYPE ----- SUBCOMPACT  
 WEIGHT ----- 2623.0 LBS.  
 VUL ----- 0.2HZx1  
 L ----- 17.0 IN.  
 C1 ----- 4.0 IN.  
 C2 ----- 12.0 IN.  
 C3 ----- 17.0 IN.  
 C4 ----- 17.3 IN.  
 C5 ----- 17.0 IN.  
 C6 ----- 3.0 IN.  
 D ----- -1.0 IN.  
 Rn0 ----- 1.00 \*  
 An0 ----- 65.0 DEG. \*

## DIMENSIONS AND INERTIAL PROPERTIES

Xf1	=	24.7 INCHES	Xz	=	40.3 INCHES
Yf1	=	99.2 INCHES	yz	=	50.1 INCHES
Zr1	=	51.0 INCHES	Iz	=	20032.3 LB-SEC <sup>2</sup> -IN
Ir1	=	41031.2 LB-SEC <sup>2</sup> -IN	m2	=	0.700 LB-SEC <sup>2</sup> -IN
rf1	=	11.125 LB-SEC <sup>2</sup> /IN	Xr2	=	35.3 INCHES
Xr1	=	98.8 INCHES	Xz2	=	-91.0 INCHES
Xn1	=	-114.0 INCHES	yz2	=	35.0 INCHES
Zf1	=	38.5 INCHES			

## ROLLING RESISTANCE

## VEHICLE # 1

Rf ----- .01  
 Lf ----- .01  
 rn ----- .20  
 Lr ----- .20  
  
 An ----- .87

## VEHICLE # 2

Rf ----- .01  
 Lf ----- .01  
 rn ----- 1.00  
 Lr ----- .20

1. TITLE?

?TEST # 7 CHEVELLE VS RABBIT

2. SIZE CATEGORIES?

?I S

3. VDI, #1

?11FDEW1

4. VDI, #2

?02RDEW4

5. ACTUAL WEIGHTS? (Y OR N)

?Y

6. WEIGHT #1

?3700.

7. WEIGHT #2

?1700.

8. REST & IMPACT? (Y OR N)

?Y

9. REST COORDINATES?

?84.5 18.2 16.5 22.9 41.4 262.

10. IMPACT COORDINATES?

?0.0.0.10.7 3.45 120.

11. SKIDDING OF # 1? (Y OR N)

?N

14. CURVED PATH? (Y OR N)

?N

15. ROTATION DIRECTION #1?

?Ca

17. MORE THAN 360 DEG? (Y OR N)

?N

18. SKIDDING OF # 2? (Y OR N)

?Y

19. SKIDDING STOP BEFORE REST? (Y OR N)

?Y

20. END OF SKIDDING COORDINATES?

?22.30.250.

21. CURVED PATH? (Y OR N)

?N

23. ROTATION DIRECTION # 2?

?Ca

24. MORE THAN 360 DEG? (Y OR N)

?N

25. TIKE-GROUND FRICTION?

?0.87

26. ROLLING RESISTANCE OPTION? (1 OR 2)

?1

27. ROLL. RESISTANCES, INDIV. WHEELS # 1

? .01 .01 .2 .2

28. ROLL. RESISTANCES, INDIV. WHEELS # 2

? .01 .01 1. .2

31. TRAJECTORY SIMULATION? (Y OR N)

?N

37. DAMAGE DIMENSIONS? (Y OR N)

?Y

41. END DAMAGE WIDTH #1

?60.

42. END DAMAGE DEPTH #1

?0. 1.25 2. 3.75 5. 0.25

43. END DAMAGE MIDPOINT OFFSET #1

?4.

44. SIDE DAMAGE WIDTH #2

?108.0

45. SIDE DAMAGE DEPTH #2

?0. 11. 17.75 21. 21.25 7.25

46. SIDE DAMAGE MIDPOINT OFFSET #2

?-8.0

52. FORCE DIRECTIONS (Y OR N)

?1

THANK YOU VERY MUCH

SUMMARY OF CRASH RESULTS

TEST # / CHEVELLE VS RABBIT

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	11.0 MPH -16.2 DEG	25.3 MPH 43.8 DEG
SPEED CHANGE (DAMAGE ONLY)	10.3 MPH -30.0 DEG	35.5 MPH 60.0 DEG
IMPACT SPEED	26.2 MPH	27.1 MPH
ENERGY DISSIPATED BY DAMAGE	11494.3 FT-LB	131224.2 FT-LB
SPEED ALONG LINE THRU CGS	23.5 MPH	7.9 MPH
SPEED ORTHOG. TO CG LINE	-5.9 MPH	-26.0 MPH
CLOSING VELOCITY	33.4 MPH	

## SUMMARY OF CRASH RESULTS

## TEST # 7 CHEVELLE VS RABBIT

VEHICLE #

\*\*\*\*\* SPEED CHANGE \*\*\*\*\*  
 \* IMPACT SPEED MPH \*\*\*\*\*  
 \* MPH \*\*\*\*\*  
 \* TOTAL LONG. LATERAL \*\*\*\*\*  
 \* 26.2 11.0 -11.1 3.2 AND CONSERVATION OF  
 \* LINEAR MOMENTUM  
 \*  
 \* SPINOUT TRAJECTORIES AND DAMAGE  
 \*  
 \* 16.3 -14.1 8.2 DAMAGE DATA ONLY

VEHICLE # 2

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	-77 FT.	11.10 FT.
IMPACT Y-POSITION	0.00 FT.	2.70 FT.
IMPACT HEADING ANGLE	0.00 DEG.	119.99 DEG.
REST X-POSITION	84.50 FT.	22.90 FT.
REST Y-POSITION	18.20 FT.	41.40 FT.
REST HEADING ANGLE	16.50 DEG.	261.97 DEG.
END-OF-ROTATION X-POSITION	0.00 FT.	22.00 FT.
END-OF-ROTATION Y-POSITION	0.00 FT.	30.00 FT.
END-OF-ROTATION HEADING ANGLE	0.00 DEG.	249.97 DEG.
DIRECTION OF ROTATION	CW	CW
AMOUNT OF ROTATION	<300	<300

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
XCT0 = -8 FT.	XC20 = 11.1 FT.
YCT0 = 0.0 FT.	YC20 = 2.8 FT.
PSIT0 = 0.0 DEGREES	PSI20 = 120.0 DEGREES
PSITD0 = 0.0 DEG/SEC	PSI2D0 = 0.0 DEG/SEC
U10 = 20.2 MPH	U20 = 27.1 MPH
V10 = 0.0 MPH	V20 = 0.0 MPH

## SEPARATION CONDITIONS

XCSI = 0.0 FT.	XCS2 = 10.7 FT.
YCSI = 0.0 FT.	YCS2 = 3.5 FT.
PSIS1 = 0.0 DEG	PSIS2 = 120.0 DEG
US1 = 15.0 MPH	US2 = 8.9 MPH
VS1 = 3.2 MPH	VS2 = -17.5 MPH
PSISD1 = 0.0 DEG/SEC	PSISD2 = 171.7 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED_CHANGE_(TRAJ. ONLY)	11.6 MPH	25.3 MPH
	-16.2 DEG	43.8 DEG
SPEED_CHANGE_(DAMAGE ONLY)	10.3 MPH	35.5 MPH
	-30.0 DEG	60.0 DEG
IMPACT SPEED	26.2 MPH	27.1 MPH
ENERGY DISSIPATED BY DAMAGE	11494.3 FT-LB	131224.2 FT-LB
SPEED ALONG LINE THRU CGS	25.5 MPH	7.9 MPH
SPEED ORTHOG. TO CG LINE	-5.9 MPH	-26.0 MPH
CLOSING VELOCITY	33.4 MPH	ZQ-6057-V-6

SUMMARY\_OF\_DAMAGE\_DATA

( \* INDICATES DEFAULT VALUE )

## VEHICLE # 1

TYPE	INTERMEDIATE
WEIGHT	3700.0 LBS.
VDI	11FDe1
L	66.0 IN.
C1	0.0 IN.
C2	1.3 IN.
C3	2.0 IN.
C4	3.8 IN.
C5	5.0 IN.
C6	6.3 IN.
D	15.0 IN.
RHO	1.00 *
ANG	330.0 DEG. *

## VEHICLE # 2

TYPE	SUBCOMPACT
WEIGHT	1700.0 LBS.
VDI	02RDe1
L	108.5 IN.
C1	.5 IN.
C2	11.0 IN.
C3	17.8 IN.
C4	21.0 IN.
C5	21.3 IN.
C6	7.3 IN.
D	-1.5 IN.
RHO	1.00 *
ANG	60.0 DEG. *

## DIMENSIONS AND INERTIAL PROPERTIES

A1	= 54.7 INCHES	A2	= 46.3 INCHES
B1	= 59.2 INCHES	B2	= 50.1 INCHES
TR1	= 01.3 INCHES	TR2	= 54.6 INCHES
II	= 35822.2 LB-SEC**2-IN	I2	= 12983.2 LB-SEC**2-IN
M1	= 9.570 LB-SEC**2/IN	M2	= 4.400 LB-SEC**2/IN
Xc1	= 98.8 INCHES	Xc2	= 83.3 INCHES
Xr1	= -114.0 INCHES	Xr2	= -91.6 INCHES
Ys1	= 38.5 INCHES	Ys2	= 33.6 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

RF	.01
LF	.01
RR	.20
LR	.20
MU	.81

## VEHICLE # 2

RF	.01
LF	.01
RR	1.00
LR	.20

1. TITLE?

?TEST # 8 CHEVELLE VS CHEVELLE

2. SIZE CATEGORIES?

?I-I

3. VDI, #1

?12FDent

4. VDI, #2

?03HYent

5. ACTUAL WEIGHTS? (Y OR N)

?Y

6. WEIGHT #1

?4479

7. WEIGHT #2

?410

8. REST & IMPACT? (Y OR N)

?Y

9. REST COORDINATES?

?-0.5 11. 40. 0.5 21. 141.

10. IMPACT COORDINATES?

?S

11. REST COORDINATES?

?-0.5 12. 40. 0.5 21. 141.

12. IMPACT COORDINATES?

?-10.9 3.2 0. 0. 1.9 90.

13. SKIDDING OF #1? (Y OR N)

?Y

14. SKIDDING STOP BEFORE REST? (Y OR N)

?N

15. CURVED PATH? (Y OR N)

?N

16. ROTATION DIRECTION #1?

?CW

17. MORE THAN 300 DEG? (Y OR N)

?N

18. SKIDDING OF #2? (Y OR N)

?Y

19. SKIDDING STOP BEFORE REST? (Y OR N)

?N

20. CURVED PATH? (Y OR N)

?N

21. ROTATION DIRECTION # 2?

?CW

— 24. MORE THAN 300 DEG? (Y OR N)

?N

— 25. TIRE-GROUND FRICTION?

?87

— 26. ROLLING RESISTANCE OPTION? (1 OR 2)

?1

— 27. ROLL. RESISTANCES, INDIV. WHEELS # 1

?01 .01 .2 .2

— 28. ROLL. RESISTANCES, INDIV. WHEELS # 2

?01 .01 .2 .2

— 31. TRAJECTORY SIMULATION? (Y OR N)

?N

— 34. DAMAGE DIMENSIONS? (Y OR N)

?Y

— 41. END DAMAGE WIDTH #1

?73

— 42. END DAMAGE DEPTH #1

?2.1 3.0

— 43. END DAMAGE MIDPOINT OFFSET #1

?0.

— 44. SIDE DAMAGE WIDTH #2

?84.5

— 45. SIDE DAMAGE DEPTH #2

?0.2 8.3 2.2 2.9 4.4 8

— 46. SIDE DAMAGE MIDPOINT OFFSET #2

?15.

— 52. FORCE DIRECTIONS (Y OR N)

?Y

— 53. PRINCIPAL FORCE ANGLE #1?

?45

— 54. PRINCIPAL FORCE ANGLE #2?

?45

## SUMMARY OF CRASH RESULTS

TEST # 8 CHEVELLE VS CHEVELLE

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	10.3 MPH -45.3 DEG	9.8 MPH -44.7 DEG
SPEED CHANGE (DAMAGE ONLY)	10.0 MPH -45.0 DEG	9.5 MPH -45.0 DEG
IMPACT SPEED	19.5 MPH	24.5 MPH
ENERGY DISSIPATED BY DAMAGE	18645.8 FT-LB	31217.2 FT-LB
SPEED ALONG LINE THRU CGS	19.2 MPH	4.3 MPH
SPEED ORTHOG. TO CG LINE	3.4 MPH	-24.1 MPH
CLOSING VELOCITY	23.4 MPH	

## SUMMARY OF CRASH RESULTS

TEST # 8 CHEVELLE VS CHEVELLE

VEHICLE # 1

\*\*\*\* \* SPEED CHANGE \* \*\*\*\*  
 \* IMPACT SPEED MPH \* \*\*\*\* BASIS  
 \* MPH \* \*\*\*\* OF RESULTS  
 \* TOTAL LONG. LATERAL \*  
 \* 19.5\* 10.3\* -7.2\* 7.3\* SPINOUT TRAJECTORIES  
 \* \* \* \* AND CONSERVATION OF  
 \* \* \* \* LINEAR MOMENTUM  
 \* \* \* \* SPINOUT TRAJECTORIES  
 \* \* \* \* AND  
 \* \* \* \* DAMAGE  
 \* 10.0\* -7.0\* 7.1\* DAMAGE DATA ONLY

VEHICLE # 2

\*\*\*\* \* SPEED CHANGE \* \*\*\*\*  
 \* EINSTEIN SPEED \* MPH \* \* \* \* \*  
 \* MPH \* \* \* \* \* BASIS  
 \* MPH \* \* \* \* \* (P)  
 \* TOTAL \* LONG. \* LATERAL \* \* \* \* \* RESULTS  
 \* \* \* \* \* \* \* \* \* \* \*  
 \* \* \* \* \* \* \* \* \* \* \*  
 \* \* \* \* \* \* \* \* \* \* \*  
 \* 24.5\* 9.8\* -0.9\* -0.9\* \* \* \* \* \* SPINOUT TRAJECTORIES  
 \* \* \* \* \* \* \* \* \* \* \* AND CONSERVATION OF  
 \* \* \* \* \* \* \* \* \* \* \* LINEAR MOMENTUM  
 \* \* \* \* \* \* \* \* \* \* \*  
 \* \* \* \* \* \* \* \* \* \* \*  
 \* \* \* \* \* \* \* \* \* \* \* SPINOUT TRAJECTORIES  
 \* \* \* \* \* \* \* \* \* \* \* AND  
 \* \* \* \* \* \* \* \* \* \* \* DAMAGE  
 \* \* \* \* \* \* \* \* \* \* \*  
 \* \* \* \* \* \* \* \* \* \* \*  
 \* \* \* \* \* \* \* \* \* \* \* 9.5\* -0.7\* -0.7\* \* \* \* \* \* DAMAGE DATA ONLY  
 \* \* \* \* \* \* \* \* \* \* \*

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	-11.46 FT.	-0.00 FT.
IMPACT Y-POSITION	3.20 FT.	1.17 FT.
IMPACT HEADING ANGLE	0.00 DEG.	89.99 DEG.
REST X-POSITION	-50 FT.	-0.50 FT.
REST Y-POSITION	11.00 FT.	21.00 FT.
REST HEADING ANGLE	45.99 DEG.	140.98 DEG.
DIRECTION OF ROTATION	CW	CW
AMOUNT OF ROTATION	<360	<360

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
XCO1 = -11.5 FT.	XC201 = -0.0 FT.
YCO1 = 3.2 FT.	YC201 = 1.2 FT.
PSI10 = 0.0 DEGREES	PSI20 = 90.0 DEGREES
PSI1D0 = 0.0 DEG/SEC	PSI2D0 = 0.0 DEG/SEC
U10 = 19.5 MPH	U20 = 24.5 MPH
V10 = 0.0 MPH	V20 = 0.0 MPH

## SEPARATION CONDITIONS

XCSI = -11.5 FT.	XCS2 = -0.0 FT.
YCSI = 3.2 FT.	YCS2 = 1.2 FT.
PSIS1 = 0.0 DEG	PSIS2 = 90.0 DEG
US1 = 12.3 MPH	US2 = 17.5 MPH
VS1 = 7.3 MPH	VS2 = 6.9 MPH
PSISD1 = 58.6 DEG/SEC	PSISD2 = 53.9 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ ONLY)	10.3 MPH	9.8 MPH
SPEED CHANGE (DAMAGE ONLY)	-45.3 DEG	44.7 DEG
IMPACT SPEED	10.0 MPH	9.5 MPH
ENERGY DISSIPATED BY DAMAGE	18645.8 FT-LB	31217.2 FT-LB
SPEED ALONG LINE THRU CGS	19.2 MPH	4.3 MPH
SPEED ORTHOG. TO CG LINE	3.4 MPH	-24.1 MPH
CLOSING VELOCITY	23.4 MPH	

SUMMARY OF DAMAGE DATA  
VEHICLE # 1

(\* INDICATES DEFAULT VALUE)  
VEHICLE # 2

TYPE ----- INTERMEDIATE  
WEIGHT ----- 4479.0 LBS.  
VDI ----- 12FDENT  
L ----- 73.0 IN.  
CL ----- 2.7 IN.  
C2 ----- 3.0 IN.  
C3 ----- 0.0 IN.  
C4 ----- 0.0 IN.  
C5 ----- 0.0 IN.  
Co ----- 0.0 IN.  
D ----- 1.7 IN.  
RHO ----- 1.00 \*  
ANG ----- 315.0 DEG.

TYPE ----- INTERMEDIATE  
WEIGHT ----- 4710.0 LBS.  
VDI ----- 03RYEN2  
L ----- 84.5 IN.  
CI ----- 0.2 IN.  
C2 ----- 8.3 IN.  
C3 ----- 9.2 IN.  
C4 ----- 5.9 IN.  
C5 ----- 4.4 IN.  
Co ----- .8 IN.  
D ----- 7.8 IN.  
RHO ----- 1.00 \*  
ANG ----- 45.0 DEG.

DIMENSIONS AND INERTIAL PROPERTIES

A1	=	54.7 INCHES	A2	=	54.7 INCHES
S1	=	59.2 INCHES	B2	=	59.2 INCHES
TR1	=	61.8 INCHES	TR2	=	61.8 INCHES
II	=	43304.2 LB-SEC**2-IN	I2	=	45600.7 LB-SEC**2-IN
M1	=	11.592 LB-SEC**2/IN	M2	=	12.189 LB-SEC**2/IN
XEL	=	90.8 INCHES	XF2	=	90.8 INCHES
Xr1	=	-114.0 INCHES	Xr2	=	-114.0 INCHES
YS1	=	38.5 INCHES	YS2	=	38.5 INCHES

ROLLING RESISTANCE

VEHICLE # 1

RF	=	.01
LF	=	.01
RR	=	.20
LR	=	.20

VEHICLE # 2

RF	=	.01
LF	=	.01
RR	=	.20
LR	=	.20

MO ----- .84

ENTER TYPE OF CRASH RUN?  
(COMPLETE, ABBREVIATED, RERUN, PRINT, BATCH, SMAC, OR END)  
?c

1. TITLE?  
TEST # 9 HONDA VERSUS TORINO
2. SIZE CATEGORIES?  
?M-I
3. VDI, #1  
?11FDEH2
4. VDI, #2  
?02RFEN2
5. ACTUAL WEIGHTS? (Y OR N)  
?Y
6. WEIGHT #1  
?2250
7. WEIGHT #2  
?4900
8. REST & IMPACT? (Y OR N)  
?Y
9. REST COORDINATES?  
?4. 35.5 104. -5. 49.5 152.
10. IMPACT COORDINATES?  
?0. 0. 0. 0. 0. 0.
11. SKIDDING OF # 1? (Y OR N)  
?N
12. CURVED PATH? (Y OR N)  
?N
13. ROTATION DIRECTION #1?  
?C
14. MORE THAN 360 DEG? (Y OR N)  
?N
15. SKIDDING OF # 2? (Y OR N)  
?Y
16. SKIDDING STOP BEFORE REST? (Y OR N)  
?Y
17. END OF SKIDDING COORDINATES?  
?18. 12.5 120.

21. CURVED PATH? (Y OR N)  
?N
23. ROTATION DIRECTION # 2?  
2CW
24. MORE THAN 300 DEGZ (Y OR N)  
?N
25. TIRE-GROUND FRICTION?  
2.87
26. ROLLING RESISTANCE OPTION? (1 OR 2)  
?1
27. ROLL. RESISTANCES, INDIV. WHEELS # 1  
2 .2 .01 .01
28. ROLL. RESISTANCES, INDIV. WHEELS # 2  
?1 .01 .2 .2
31. TRAJECTORY SIMULATION? (Y OR N)  
?N
37. DAMAGE DIMENSIONS? (Y OR N)  
?Y
41. END DAMAGE WIDTH #1  
?48.75
42. END DAMAGE DEPTH #1  
?5.5 .75 12.5 1.5 7.5 9.5
43. END DAMAGE MIDPOINT OFFSET #1  
?1.03
44. SIDE DAMAGE WIDTH #2  
?54.5
45. SIDE DAMAGE DEPTH #2  
?1.52 4.5 4.75 3.3 2.5 1.5
46. SIDE DAMAGE MIDPOINT OFFSET #2  
?00.
52. FORCE DIRECTIONS (Y OR N)  
?Y
53. PRINCIPAL FORCE ANGLE #1?  
-70.0
54. PRINCIPAL FORCE ANGLE #2?  
?25.

**SUMMARY OF CRASH RESULTS**

TEST # 9 - HONDA VERSUS TORINO

	VEHICLE # 1	VEHICLE # 2
-- SPEED CHANGE (TRAJ. ONLY)	24.2 MPH -23.9 DEG	11.2 MPH 60.1 DEG
-- SPEED CHANGE (DAMAGE ONLY)	19.1 MPH -65.0 DEG	8.8 MPH 25.0 DEG
-- IMPACT SPEED	23.2 MPH	22.0 MPH
ENERGY DISSIPATED BY DAMAGE	68892.3 FT-LB	31370.4 FT-LB
SPEED ALONG LINE THRU CGS	18.9 MPH	12.8 MPH
SPEED ORTHOG. TO CG LINE	13.6 MPH	-17.8 MPH
CLOSING VELOCITY	31.7 MPH	

## SUMMARY OF CRASH RESULTS

## TEST # 9 HONDA VERSUS TORINO

VEHICLE # 1

VEHICLE # 2

## SCENE INFORMATION

VEHICLE # 1 ... VEHICLE # 2

IMPACT X-POSITION	-1.02	FT.	-8.53	FT.
IMPACT Y-POSITION	0.00	FT.	-6.80	FT.
IMPACT HEADING ANGLE	0.00	DEG.	89.99	DEG.
REST X-POSITION	4.00	FT.	-5.00	FT.
REST Y-POSITION	35.50	FT.	49.50	FT.
REST HEADING ANGLE	103.99	DEG.	151.98	DEG.
END-OF-ROTATION X-POSITION	0.00	FT.	18.00	FT.
END-OF-ROTATION Y-POSITION	0.00	FT.	12.50	FT.
END-OF-ROTATION HEADING ANGLE	0.00	DEG.	119.99	DEG.
DIRECTION-OF-ROTATION	CW		CW	
AMOUNT OF ROTATION	<360		<360	

## COLLISION CONDITIONS

VEHICLE # 1

VEHICLE # 2

XCI01	=	-1.0 FT.	XC201	=	8.5 FT.
YCI01	=	0.0 FT.	YC201	=	-6.9 FT.
PSI10	=	0.0 DEGREES	PSI20	=	90.0 DEGREES
PSI1D0	=	0.0 DEG/SEC	PSI2D0	=	0.0 DEG/SEC
U10	=	23.2 MPH	U20	=	22.0 MPH
V10	=	0.0 MPH	V20	=	0.0 MPH

## SEPARATION CONDITIONS

XCS1	=	0.0 FT.	XCS2	=	8.5 FT.
YCS1	=	0.0 FT.	YCS2	=	-5.9 FT.
PSIS1	=	0.0 DEG	PSIS2	=	90.0 DEG
US1	=	1.1 MPH	US2	=	17.4 MPH
VS1	=	9.8 MPH	VS2	=	-10.2 MPH
PSISD1	=	0.0 DEG/SEC	PSISD2	=	54.7 DEG/SEC

## RELATIVE VELOCITY DATA

VEHICLE # 1

VEHICLE # 2

SPEED CHANGE (TRAJ. ONLY)	24.2 MPH	11.2 MPH
	-23.9 DEG	60.1 DEG
SPEED CHANGE (DAMAGE ONLY)	19.1 MPH	8.8 MPH
	-65.0 DEG	25.0 DEG
IMPACT SPEED	23.2 MPH	22.0 MPH
ENERGY DISSIPATED BY DAMAGE	68892.3 FT-LB	31370.4 FT-LB
SPEED ALONG LINE THRU CGS	18.9 MPH	12.8 MPH
SPEED ORTHOG. TO CG-LINE	13.0 MPH	-17.8 MPH
CLOSING VELOCITY	31.7 MPH	

SUMMARY OF DAMAGE DATA (\* INDICATES DEFAULT VALUE)

VEHICLE # 1		VEHICLE # 2	
TYPE	MINICAR	TYPE	INTERMEDIATE
WEIGHT	2250.0 LBS.	WEIGHT	4900.0 LBS.
VDF	11FDEw2	VDF	02RFew2
L	49.7 IN.	L	54.5 IN.
CL	2.0 IN.	CI	7.8 IN.
C2	5.8 IN.	C2	4.6 IN.
C3	12.5 IN.	C3	4.8 IN.
C4	7.5 IN.	C4	3.3 IN.
C5	7.5 IN.	C5	2.8 IN.
Co	9.5 IN.	Co	1.5 IN.
D	2.9 IN.	D	62.4 IN.
RHO	1.00 *	RHO	1.00 *
ANG	295.0 DEG.	ANG	25.0 DEG.

DIMENSIONS AND INERTIAL PROPERTIES

A1	=	45.1 INCHES	A2	=	54.7 INCHES
B1	=	48.1 INCHES	B2	=	59.2 INCHES
TR1	=	51.1 INCHES	TR2	=	61.8 INCHES
II	=	11712.0 LB-SEC**2-IN	I2	=	47440.2 LB-SEC**2-IN
M1	=	5.839 LB-SEC**2/IN	M2	=	12.081 LB-SEC**2/IN
XFL	=	76.0 INCHES	XF2	=	98.8 INCHES
KR1	=	-83.8 INCHES	XR2	=	-114.0 INCHES
YS1	=	30.4 INCHES	YS2	=	38.5 INCHES

ROLLING RESISTANCE

VEHICLE # 1		VEHICLE # 2	
RF	.20	RF	.10
LF	.20	LF	.01
RR	.01	RR	.20
LK	.01	LK	.20
MU	.87		

1. TITLE?  
?TEST # 10 HONDA VS TORINO
2. SIZE CATEGORIES?  
?L
3. VDI, #1  
?10FDEn2
4. VDI, #2  
201REEn2
5. ACTUAL HEIGHTS? (Y OR N)  
?Y
6. HEIGHT #1  
?2300
7. HEIGHT #2  
?4720
8. REST & IMPACT? (Y OR N)  
?Y
9. REST COORDINATES?  
?D. 43. 87. 0. 99.5 128.5
10. IMPACT COORDINATES?  
?0. 0. 0. 0. 0. -5.9 90.
11. SKIDDING OF # 1? (Y OR N)  
?Y
12. SKIDDING STOP BEFORE REST? (Y OR N)  
?Y
13. END OF SKIDDING COORDINATES?  
?D. 25. 90.
14. CURVED PATH? (Y OR N)  
?N
15. ROTATION DIRECTION #1?  
?Cn
16. MORE THAN 300 DEG? (Y OR N)  
?N
17. SKIDDING OF # 2? (Y OR N)  
?Y
18. SKIDDING STOP BEFORE REST? (Y OR N)  
?Y
19. END OF SKIDDING COORDINATES?  
?23. 19. 90.

21. CURVED PATH? (Y OR N)

?N

23. ROTATION DIRECTION # 2?

?Cn

24. MORE THAN 360 DEG? (Y OR N)

?N

25. TIRE-GROUND FRICTION?

?0.7

26. ROLLING RESISTANCE OPTION? (1 OR 2)

?1

27. ROLL. RESISTANCES, INDIV. WHEELS # 1

?0.2 .2 .01 .01

28. ROLL. RESISTANCES, INDIV. WHEELS # 2

?0.1 .01 .2 .2

31. TRAJECTORY SIMULATION? (Y OR N)

?N

37. DAMAGE DIMENSIONS? (Y OR N)

?Y

41. END DAMAGE WIDTH #1

?47.5

42. END DAMAGE DEPTH #1

?7. 10.2 14. 8.9 7. 9.

43. END DAMAGE MIDPOINT OFFSET #1

?-2.12

44. SIDE DAMAGE WIDTH #2

?53.

45. SIDE DAMAGE DEPTH #2

?9.2 0.2 0.1 5.3 4.5 .2

46. SIDE DAMAGE MIDPOINT OFFSET #2

?00.0

52. FORCE DIRECTIONS (Y OR N)

?Y

53. PRINCIPAL FORCE ANGLE #1?

?-50.

54. PRINCIPAL FORCE ANGLE #2?

?20.

## SUMMARY OF CRASH RESULTS

TEST # 10 HONDA VS TORINO

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. ONLY)	32.6 MPH -35.0 DEG	15.9 MPH 54.4 DEG
SPEED CHANGE (DAMAGE ONLY)	22.4 MPH -65.0 DEG	10.9 MPH 25.0 DEG
IMPACT SPEED	32.7 MPH	31.5 MPH
ENERGY DISSIPATED BY DAMAGE	88023.1 FT-LB	44972.8 FT-LB
SPEED ALONG LINE THRU CGS	26.4 MPH	18.6 MPH
SPEED ORTHOG. TO CG LINE	19.2 MPH	-25.5 MPH
CLOSING VELOCITY	45.0 MPH	

## SUMMARY OF CRASH RESULTS

TEST # 10 HONDA VS TORINO

## VEHICLE # 1

SPEED CHANGE				BASIS	
IMPACT SPEED	MPH	TOTAL	LONG.	LATERAL	OF
MPH		*	*	*	RESULTS
32.7*	32.0*	-26.5*	19.0*	19.0*	*SPINOUT TRAJECTORIES*
					*AND CONSERVATION OF
					*LINEAR MOMENTUM
					*
SPEED CHANGE				BASIS	
IMPACT SPEED	MPH	TOTAL	LONG.	LATERAL	OF
MPH		*	*	*	RESULTS
22.4*	22.4*	-9.4*	20.3*	20.3*	DAMAGE DATA ONLY
					*

## VEHICLE # 2

SPEED CHANGE				BASIS	
IMPACT SPEED	MPH	TOTAL	LONG.	LATERAL	OF
MPH		*	*	*	RESULTS
31.5*	15.9*	-9.3*	-13.0*	-13.0*	*SPINOUT TRAJECTORIES*
					*AND CONSERVATION OF
					*LINEAR MOMENTUM
					*
SPEED CHANGE				BASIS	
IMPACT SPEED	MPH	TOTAL	LONG.	LATERAL	OF
MPH		*	*	*	RESULTS
10.9*	10.9*	-9.9*	-4.6*	-4.6*	DAMAGE DATA ONLY
					*

## SCENE INFORMATION

VEHICLE # 1 VEHICLE # 2

IMPACT X-POSITION	-1.20	FT.	8.00	FT.
IMPACT Y-POSITION	0.00	FT.	-7.00	FT.
IMPACT HEADING ANGLE	0.00	DEG.	89.99	DEG.
REST X-POSITION	5.00	FT.	0.00	FT.
REST Y-POSITION	43.00	FT.	99.50	FT.
REST HEADING ANGLE	86.99	DEG.	128.49	DEG.
END-OF-ROTATION X-POSITION	5.00	FT.	23.00	FT.
END-OF-ROTATION Y-POSITION	25.00	FT.	19.00	FT.
END-OF-ROTATION HEADING ANGLE	89.99	DEG.	89.99	DEG.
DIRECTION OF ROTATION	CW		CW	
AMOUNT OF ROTATION	<360		<360	

## COLLISION CONDITIONS

VEHICLE # 1

VEHICLE # 2

XCTO1	=	-1.2	FT.	XCTO2	=	8.0	FT.
YCTO1	=	0.0	FT.	YCTO2	=	-7.0	FT.
PSIT0	=	0.0	DEGREES	PSIT0	=	90.0	DEGREES
PSITD0	=	0.0	DEG/SEC	PSITD0	=	0.0	DEG/SEC
U10	=	32.7	MPH	U20	=	31.5	MPH
V10	=	0.0	MPH	V20	=	0.0	MPH

## SEPARATION CONDITIONS

VEHICLE # 1

VEHICLE # 2

XCSI	=	0.0	FT.	XCS2	=	8.0	FT.
YCSI	=	0.0	FT.	YCS2	=	-5.9	FT.
PSISI	=	0.0	DEG	PSIS2	=	90.0	DEG
JSI	=	0.1	MPH	JS2	=	22.3	MPH
VSI	=	19.0	MPH	VS2	=	-13.0	MPH
PSISDI	=	116.0	DEG/SEC	PSISD2	=	0.0	DEG/SEC

## RELATIVE VELOCITY DATA

VEHICLE # 1

VEHICLE # 2

SPEED CHANGE (TRAJ. ONLY)	32.6	MPH	15.9	MPH
	-35.6	DEG	54.4	DEG
SPEED CHANGE (DAMAGE ONLY)	22.4	MPH	10.9	MPH
	-65.0	DEG	25.0	DEG
IMPACT SPEED	32.7	MPH	31.5	MPH
ENERGY DISSIPATED BY DAMAGE	88023.1	FT-LB	44972.8	FT-LB
SPEED ALONG LINE THRU CGS	26.4	MPH	18.0	MPH
SPEED ORTHOG. TO CG LINE	19.2	MPH	-25.5	MPH
CLOSING VELOCITY	45.0	MPH		

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

## VEHICLE # 1

TYPE ----- MINICAR  
 WEIGHT ----- 2300.0 LBS.  
 VDI ----- LOADER2  
 L ----- 47.5 IN.  
 C1 ----- 7.0 IN.  
 C2 ----- 10.2 IN.  
 C3 ----- 14.0 IN.  
 C4 ----- 8.9 IN.  
 C5 ----- 7.0 IN.  
 C6 ----- 9.0 IN.  
 D ----- -3.8 IN.  
 RHO ----- 1.00 \*  
 ANG ----- 295.0 DEG.

## VEHICLE # 2

TYPE ----- INTERMEDIATE  
 WEIGHT ----- 4720.0 LBS.  
 VDI ----- DRIVER2  
 L ----- 53.0 IN.  
 C1 ----- 9.2 IN.  
 C2 ----- 6.5 IN.  
 C3 ----- 6.1 IN.  
 C4 ----- 5.3 IN.  
 C5 ----- 4.5 IN.  
 C6 ----- .5 IN.  
 D ----- 61.5 IN.  
 RHO ----- 1.00 \*  
 ANG ----- 25.0 DEG.

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	45.1 INCHES	A2	=	54.7 INCHES
$\delta_1$	=	48.1 INCHES	B2	=	59.2 INCHES
TR1	=	51.1 INCHES	TR2	=	61.8 INCHES
I1	=	11971.6 LB-SEC**2-IN	I2	=	45697.5 LB-SEC**2-IN
$\alpha_1$	=	5.908 LB-SEC**2/IN	M2	=	12.215 LB-SEC**2/IN
XF1	=	70.0 INCHES	XF2	=	98.8 INCHES
XR1	=	-83.8 INCHES	XR2	=	-114.0 INCHES
YS1	=	30.4 INCHES	YS2	=	38.5 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

Rf ----- .20  
 Lf ----- .20  
 RR ----- .01  
 LR ----- .01  
  
 mu ----- .87

## VEHICLE # 2

Rf ----- .10  
 Lf ----- .01  
 RR ----- .20  
 LR ----- .20

1. TITLE?  
TEST #11 VEGA VS TORINO

2. SIZE CATEGORIES?  
SA I

3. VDI, #1  
12FYES

4. VDI, #2  
12FYES

5. ACTUAL WEIGHTS? (Y OR N)  
Y

6. WEIGHT #1  
3041

7. WEIGHT #2  
4650

8. REST & IMPACT? (Y OR N)  
Y

9. REST COORDINATES?  
25.0 -0.4 170. 0.0 0.4 0.0

10. IMPACT COORDINATES?  
15.7 -4. 171. 0. 0. 0.

11. SKIDDING OF # 1? (Y OR N)  
N

14. CURVED PATH? (Y OR N)  
N

15. ROTATION DIRECTION #1?  
Cn

17. MORE THAN 360 DEG? (Y OR N)  
N

18. SKIDDING OF # 2? (Y OR N)  
N

21. CURVED PATH? (Y OR N)  
N

23. ROTATION DIRECTION # 2?  
N

25. FRIE-GROUND FRICTION?  
0.07

26. ROLLING RESISTANCE OPTION(1 OR 2)  
1

27. ROLL. RESISTANCES, INDIV. WHEELS # 1  
0.01 .01 .1 .1

28. ROLL RESISTANCES, INDIV. WHEELS # 2  
? .01 .01 .2 .2

31. TRAJECTORY SIMULATION? (Y OR N)  
?N

37. DAMAGE DIMENSIONS? (Y OR N)  
?Y

41. END DAMAGE WIDTH #1  
?32.0

42. END DAMAGE DEPTH #1  
?22. 20.2 18.5 16.8 15. 12.5

43. END DAMAGE MIDPOINT OFFSET #1  
?-12.75

47. END DAMAGE WIDTH #2  
?32.20

48. END DAMAGE DEPTH #2  
?29.5 28.25 23. 18.7 14.3 11.

49. END DAMAGE MIDPOINT OFFSET #2  
?-12.9

52. FORCE DIRECTIONS (Y OR N)  
?Y

53. PRINCIPAL FORCE ANGLE #1?  
?0.

54. PRINCIPAL FORCE ANGLE #2?  
?0.

SUMMARY OF CRASH RESULTS

TEST #11 VEGA VS TORINO

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. + DAMAGE)	21.0 MPH -.8 DEG	13.2 MPH -.9 DEG
SPEED CHANGE (DAMAGE ONLY)	21.1 MPH -9.0 DEG	13.2 MPH -9.0 DEG
IMPACT SPEED	17.2 MPH	18.0 MPH
ENERGY DISSIPATED BY DAMAGE	35274.2 FT-LB	44958.9 FT-LB
SPEED ALONG LINE THRU CGS	17.1 MPH	17.4 MPH
SPEED ORIGIN. TO CG LINE	1.6 MPH	4.4 MPH
CLOSING VELOCITY	34.5 MPH	

## SUMMARY OF CRASH RESULTS

TEST #11 VEGA VS TORINO

VEHICLE # 1

VEHICLE # 2

\*\*\*\*\* SPEED CHANGE \*\*\*\*\*  
 IMPACT SPEED MPH BASIS OF RESULTS  
 MPH \*\*\*\*\*  
 TOTAL LONG. LATERAL  
 \*\*\*\*\*  
 SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM  
 \*\*\*\*\*  
 SPINOUT TRAJECTORIES AND DAMAGE  
 18.0 13.2 -13.2 .2 AND  
 \*\*\*\*\*  
 13.2 -13.2 1.2 DAMAGE DATA ONLY

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	15.70 FT.	0.00 FT.
IMPACT Y-POSITION	-4.00 FT.	0.00 FT.
IMPACT HEADING ANGLE	170.98 DEG.	0.00 DEG.
REST X-POSITION	25.00 FT.	8.00 FT.
REST Y-POSITION	-6.40 FT.	.40 FT.
REST HEADING ANGLE	169.98 DEG.	0.00 DEG.
END-OF-ROTATION X-POSITION	15.70 FT.	0.00 FT.
END-OF-ROTATION Y-POSITION	-4.00 FT.	0.00 FT.
END-OF-ROTATION HEADING ANGLE	170.98 DEG.	0.00 DEG.
DIRECTION OF ROTATION	CW	NONE
AMOUNT OF ROTATION	<360	<360

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
X <sub>C10</sub> = 15.7 FT.	X <sub>C20</sub> = 0.0 FT.
Y <sub>C10</sub> = -4.0 FT.	Y <sub>C20</sub> = 0.0 FT.
PSI <sub>10</sub> = 171.0 DEGREES	PSI <sub>20</sub> = 0.0 DEGREES
PSI <sub>1D0</sub> = 0.0 DEG/SEC	PSI <sub>2D0</sub> = 0.0 DEG/SEC
U <sub>10</sub> = 17.2 MPH	U <sub>20</sub> = 18.0 MPH
V <sub>10</sub> = 0.0 MPH	V <sub>20</sub> = 0.0 MPH

## SEPARATION CONDITIONS

X <sub>CS1</sub> = 15.7 FT.	X <sub>CS2</sub> = 0.0 FT.
Y <sub>CS1</sub> = -4.0 FT.	Y <sub>CS2</sub> = 0.0 FT.
PSI <sub>S1</sub> = 171.0 DEG	PSI <sub>S2</sub> = 0.0 DEG
US1 = -3.8 MPH	US2 = 4.8 MPH
VS1 = .3 MPH	VS2 = .2 MPH
PSISD1 = 0.0 DEG/SEC	PSISD2 = 0.0 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. + DAMAGE)	21.0 MPH -.8 DEG	13.2 MPH -.9 DEG
SPEED CHANGE (DAMAGE ONLY)	21.1 MPH +.0 DEG	13.2 MPH -.5 DEG
IMPACT SPEED	17.2 MPH	18.0 MPH
ENERGY DISSIPATED BY DAMAGE	35274.2 FT-LB	44958.9 FT-LB
SPEED ALONG LINE THRU CGS	17.1 MPH	17.4 MPH
SPEED ORTHOG. TO CG LINE	1.0 MPH	4.4 MPH
CLOSING VELOCITY	34.5 MPH	

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

## VEHICLE # 1

TYPE-----SUBCOMPACT  
 HEIGHT----3041.0 LBS.  
 VDI-----12FYEN3  
 L-----32.5 IN.  
 C1-----22.0 IN.  
 C2-----20.2 IN.  
 C3-----18.5 IN.  
 C4-----16.8 IN.  
 C5-----15.0 IN.  
 C6-----12.5 IN.  
 D------14.2 IN.  
 RHO-----1.00 \*  
 ANG-----5.0 DEG.

## VEHICLE # 2

TYPE-----INTERMEDIATE  
 HEIGHT----4850.0 LBS.  
 VDI-----12FYEN3  
 L-----32.3 IN.  
 C1-----29.5 IN.  
 C2-----28.3 IN.  
 C3-----23.0 IN.  
 C4-----18.7 IN.  
 C5-----14.3 IN.  
 C6-----11.0 IN.  
 D------15.4 IN.  
 RHO-----1.00 \*  
 ANG-----355.0 DEG.

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	40.3 INCHES	A2	=	54.7 INCHES
B1	=	30.1 INCHES	B2	=	59.2 INCHES
T1	=	34.0 INCHES	Tr2	=	61.8 INCHES
I1	=	23224.6 LB-SEC**2-IN	I2	=	46956.1 LB-SEC**2-IN
M1	=	7.870 LB-SEC**2/IN	M2	=	12.552 LB-SEC**2/IN
X1	=	83.3 INCHES	XF2	=	98.8 INCHES
X2	=	-91.0 INCHES	XR2	=	-114.0 INCHES
Y1	=	33.0 INCHES	YS2	=	38.5 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

RF	-----	.01
LF	-----	.01
RH	-----	.10
LH	-----	.10
RD	-----	.07

## VEHICLE # 2

RF	-----	.01
LF	-----	.01
RH	-----	.20
LH	-----	.20

TEST # 12 VEGA VS TORINO

2. SIZE CATEGORIES?

?S 1

3. VDI, #1

?12FYEn4

4. VDI, #2

?S

3. VDI, #1

?12FDEn4

4. VDI, #2

?12FYEn4

5. ACTUAL WEIGHTS? (Y OR N)

?Y

6. WEIGHT #1

?3130.

7. WEIGHT #2

?4512.

8. REST & IMPACT? (Y OR N)

?Y

9. REST COORDINATES?

?22.3 -5.5 118. 6.8 2.6 -12.

10. IMPACT COORDINATES?

?15.7 -4. 171. 0 0 0

11. SKIDDING OF # 1? (Y OR N)

?Y

12. SKIDDING STOP BEFORE REST? (Y OR N)

?N

14. CURVED PATH? (Y OR N)

?N

16. ROTATION DIRECTION #1?

?CCW

17. MORE THAN 360 DEG? (Y OR N)

?N

18. SKIDDING OF # 2? (Y OR N)

?Y

19. SKIDDING STOP BEFORE REST? (Y OR N)

?N

21. CURVED PATH? (Y OR N)  
?N

23. ROTATION DIRECTION # 2?  
?CCW

24. MORE THAN 360 DEG? (Y OR N)  
?N

25. TIRE-GROUND FRICTION?  
?0.7

26. ROLLING RESISTANCE OPTION?(1 OR 2)  
?1

27. ROLL. RESISTANCES, INDIV. WHEELS # 1  
?0.01 .01 .2 .2

28. ROLL. RESISTANCES, INDIV. WHEELS # 2  
?0.01 .01 .2 .2

31. TRAJECTORY SIMULATION? (Y OR N)  
?N

37. DAMAGE DIMENSIONS? (Y OR N)  
?Y

41. END DAMAGE WIDTH #1  
?32.

42. END DAMAGE DEPTH #1  
?38.0 34.0 29.5 20. 19.0 14.25

43. END DAMAGE MIDPOINT OFFSET #1  
?2.75

47. END DAMAGE WIDTH #2  
?28.25

48. END DAMAGE DEPTH #2  
?34.0 33. 28.75 23.75 19.2 15.

49. END DAMAGE MIDPOINT OFFSET #2  
?-10.0

52. FORCE DIRECTIONS (Y OR N)  
?Y

53. PRINCIPAL FORCE ANGLE #1?  
?0.

54. PRINCIPAL FORCE ANGLE #2?  
?0.

SUMMARY OF CRASH RESULTS

TEST # 12 VEGA VS TORINO

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. + DAMAGE)	28.2 MPH 3.1 DEG	20.0 MPH -13.1 DEG
SPEED CHANGE (DAMAGE ONLY)	28.2 MPH 0.0 DEG	19.6 MPH -5.0 DEG
IMPACT SPEED	19.8 MPH	30.2 MPH
ENERGY DISSIPATED BY DAMAGE	82053.4 FT-LB	59966.1 FT-LB
SPEED ALONG LINE THRU CGS	19.7 MPH	29.3 MPH
SPEED ORTHOG. TO CG LINE	1.8 MPH	7.5 MPH
CLOSING VELOCITY	49.0 MPH	

## SUMMARY OF CRASH RESULTS

TEST # 12 VEGA VS TORINO

VEHICLE # 1

VEHICLE # 2

```

*****
*          *          SPEED CHANGE          *
*          *          MPH                  *
*IMPACT SPEED*          MPH          BASIS
*          *          *****          OF
*          *          *          *          RESULTS
*          *          TOTAL  LONG. LATERAL
*          *          *          *          *
*****          *          *          *          *
*          *          *          *          SPINOUT TRAJECTORIES
*          *          *          *          AND CONSERVATION OF
*          *          *          *          LINEAR MOMENTUM
*          *          *          *          *
*****          *          *          *          SPINOUT TRAJECTORIES
*          *          *          *          AND
*          *          *          *          DAMAGE
*          *          *          *          *
*****          *          *          *          DAMAGE DATA ONLY
*          *          *          *          *

```

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	15.70 FT.	0.00 FT.
IMPACT Y-POSITION	-4.00 FT.	0.00 FT.
IMPACT HEADING ANGLE	170.98 DEG.	0.00 DEG.
REST X-POSITION	22.30 FT.	6.80 FT.
REST Y-POSITION	-5.50 FT.	2.00 FT.
REST HEADING ANGLE	117.99 DEG.	-12.00 DEG.
DIRECTION OF ROTATION	CCW	CCW
AMOUNT OF ROTATION	<360	<360

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
XCO1 = 15.7 FT.	XCO2 = 0.0 FT.
YCO1 = -4.0 FT.	YCO2 = 0.0 FT.
PSI10 = 171.0 DEGREES	PSI20 = 0.0 DEGREES
PSI1D0 = 0.0 DEG/SEC	PSI2D0 = 0.0 DEG/SEC
U10 = 19.8 MPH	U20 = 30.2 MPH
V10 = 0.0 MPH	V20 = 0.0 MPH

## SEPARATION CONDITIONS

XCS1 = 15.7 FT.	XCS2 = 0.0 FT.
YCS1 = -4.0 FT.	YCS2 = 0.0 FT.
PSIS1 = 171.0 DEG	PSIS2 = 0.0 DEG
US1 = -8.3 MPH	US2 = 10.7 MPH
VS1 = -1.6 MPH	VS2 = 4.6 MPH
PSISD1 = -106.9 DEG/SEC	PSISD2 = -22.4 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. + DAMAGE)	28.2 MPH 3.1 DEG	20.0 MPH -13.1 DEG
SPEED CHANGE (DAMAGE ONLY)	20.2 MPH 5.0 DEG	19.6 MPH -5.0 DEG
IMPACT SPEED	19.8 MPH	30.2 MPH
ENERGY DISSIPATED BY DAMAGE	82653.4 FT-LB	59960.1 FT-LB
SPEED ALONG LINE THRU CGS	19.7 MPH	29.3 MPH
SPEED ORTHOG. TO CG LINE	1.8 MPH	7.5 MPH
CLOSING VELOCITY	49.0 MPH	

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

## VEHICLE # 1

TYPE ----- SUBCOMPACT  
 WEIGHT ----- 3130.0 LBS.  
 VDI ----- 12FDEn4  
 L ----- 32.0 IN.  
 C1 ----- 38.0 IN.  
 C2 ----- 34.0 IN.  
 C3 ----- 29.5 IN.  
 C4 ----- 20.0 IN.  
 C5 ----- 19.6 IN.  
 C6 ----- 14.3 IN.  
 D ----- .4 IN.  
 RH0 ----- 1.00 \*  
 ANG ----- 5.0 DEG.

## VEHICLE # 2

TYPE ----- INTERMEDIATE  
 WEIGHT ----- 4512.0 LBS.  
 VDI ----- 12FYEn4  
 L ----- 28.3 IN.  
 C1 ----- 39.5 IN.  
 C2 ----- 33.0 IN.  
 C3 ----- 28.8 IN.  
 C4 ----- 23.8 IN.  
 C5 ----- 19.2 IN.  
 C6 ----- 15.0 IN.  
 D ----- -12.7 IN.  
 RH0 ----- 1.00 \*  
 ANG ----- 355.0 DEG.

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	46.3 INCHES	A2	=	54.7 INCHES
B1	=	50.1 INCHES	B2	=	59.2 INCHES
Tr1	=	54.0 INCHES	Tr2	=	61.8 INCHES
II	=	23904.3 LB-SEC**2-IN	I2	=	43663.7 LB-SEC**2-IN
M1	=	8.100 LB-SEC**2/IN	M2	=	11.677 L
Ar1	=	83.3 INCHES	Xr2	=	90.8 INCHES
Kr1	=	-91.0 INCHES	Xr2	=	-114.0 INCHES
Ys1	=	33.6 INCHES	Ys2	=	30.5 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

RF ----- .01  
 LF ----- .01  
 RR ----- .20  
 LR ----- .20

## VEHICLE # 2

RF ----- .01  
 LF ----- .01  
 RR ----- .20  
 LR ----- .20

MU ----- .87

II-52

ZQ-6057-V-6

1. TITLE?  
TEST # 3 TORINO VS PINTO

2. SIZE CATEGORIES?  
?I S

3. VDI, #1  
?12FZEN1

4. VDI, #2  
?00BZEN1

5. ACTUAL WEIGHTS? (Y OR N)  
?Y

6. WEIGHT #1  
?4949

7. WEIGHT #2  
?3120

8. REST & IMPACT? (Y OR N)  
?Y

9. REST COORDINATES?  
?111.4 2. -4. 101.5 6.4 -19.

10. IMPACT COORDINATES?  
?0. 0. 0. 15. 2.2 10.

11. SKIDDING OF # 1? (Y OR N)  
?N

14. CURVED PATH? (Y OR N)  
?N

16. ROTATION DIRECTION #1?  
?N

17. MORE THAN 360 DEG? (Y OR N)  
?N

18. SKIDDING OF # 2? (Y OR N)  
?N

21. CURVED PATH? (Y OR N)  
?N

23. ROTATION DIRECTION # 2?  
?N

24. MORE THAN 360 DEG? (Y OR N)  
?N

25. TIRE-GROUND FRICTION?  
?0.07

26. ROLLING RESISTANCE OPTION? (1 OR 2)  
?1

27. ROLL RESISTANCES, INDIV. WHEELS # 1  
?01 .01 .09 .09

28. ROLL RESISTANCES, INDIV. WHEELS # 2  
?01 .01 .1 .1

31. TRAJECTORY SIMULATION? (Y OR N)  
?N

37. DAMAGE DIMENSIONS? (Y OR N)  
?Y

41. END DAMAGE WIDTH #1  
?30.

42. END DAMAGE DEPTH #1  
?2. 2. 1.5 1.75 2. 2.25

43. END DAMAGE MIDPOINT OFFSET #1  
?22.

47. END DAMAGE WIDTH #2  
?30.

48. END DAMAGE DEPTH #2  
?0.5 0.75 0.75 0. 3.75 3.

49. END DAMAGE MIDPOINT OFFSET #2  
?5.

52. FORCE DIRECTIONS (Y OR N)  
?Y

53. PRINCIPAL FORCE ANGLE #1?  
?0.

54. PRINCIPAL FORCE ANGLE #2?  
?170.

#### SUMMARY OF CRASH RESULTS

##### TEST # 3 TORINO VS PINTO

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. + DAMAGE)	3.1 MPH -3.9 DEG	5.4 MPH 154.7 DEG
SPEED CHANGE (DAMAGE ONLY)	3.1 MPH .0 DEG	4.9 MPH 170.0 DEG
IMPACT SPEED	15.2 MPH	10.4 MPH
ENERGY DISSIPATED BY DAMAGE	2685.4 FT-LB	1795.2 FT-LB
SPEED ALONG LINE THRU CGS	15.1 MPH	-10.4 MPH
SPEED ORTHOG. TO CG LINE	-2.1 MPH	-.4 MPH
CLOSING VELOCITY	4.6 MPH	

## SUMMARY OF CRASH RESULTS

TEST # 3 TORINO VS PINTO

VEHICLE # 1

```

*****
*          * SPEED CHANGE *
*IMPACT SPEED* MPH
*          *          *
*          *          * BASIS
* MPH      *****
*          *          * OF
*          *          *          * RESULTS
*          *          *          *
*          *          * TOTAL LONG. LATERAL *
*          *          *          *
*          *          *          *
*****
```

\*SPINOUT TRAJECTORIES  
AND CONSERVATION OF  
LINEAR MOMENTUM

```

*          *          *          *
*          *          *          *
*          *          *          *
*          *          *          *
*          *          *          *
*****
```

\*SPINOUT TRAJECTORIES  
AND  
DAMAGE

```

*          *          *          *
*          *          *          *
*          *          *          *
*          *          *          *
*          *          *          *
*****
```

DAMAGE DATA ONLY

```

*****

```

**VEHICLE # 2**

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	- .81 FT.	14.48 FT.
IMPACT Y-POSITION	0.00 FT.	2.11 FT.
IMPACT HEADING ANGLE	0.00 DEG.	10.00 DEG.
REST X-POSITION	111.40 FT.	181.50 FT.
REST Y-POSITION	2.00 FT.	6.40 FT.
REST HEADING ANGLE	-4.00 DEG.	-19.00 DEG.
END-OF-ROTATION X-POSITION	- .81 FT.	14.48 FT.
END-OF-ROTATION Y-POSITION	0.00 FT.	2.11 FT.
END-OF-ROTATION HEADING ANGLE	0.00 DEG.	10.00 DEG.
DIRECTION OF ROTATION	NONE	NONE
AMOUNT OF ROTATION	<360	<360

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
XCO10' = - .8 FT.	XC20' = 14.5 FT.
YCO10' = 0.0 FT.	YC20' = 2.1 FT.
PSI10 = 0.0 DEGREES	PSI20 = 10.0 DEGREES
PSI1D0 = 0.0 DEG/SEC	PSI2D0 = 0.0 DEG/SEC
U10 = 15.2 MPH	U20 = 10.4 MPH
V10 = 0.0 MPH	V20 = 0.0 MPH

## SEPARATION CONDITIONS

XCSI = - .8 FT.	XCS2 = 14.5 FT.
YCSI = 0.0 FT.	YCS2 = 2.1 FT.
PSISI = 0.0 DEG	PSIS2 = 10.0 DEG
USI = 12.1 MPH	US2 = 10.3 MPH
VS1 = .2 MPH	VS2 = -2.3 MPH
PSISD1 = 0.0 DEG/SEC	PSISD2 = 0.0 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (TRAJ. + DAMAGE)	3.1 MPH	5.4 MPH
SPEED CHANGE (DAMAGE ONLY)	-3.9 DEG	104.7 DEG
IMPACT SPEED	3.1 MPH	4.9 MPH
ENERGY DISSIPATED BY DAMAGE	.0 DEG	170.0 DEG
SPEED ALONG LINE THRU CG	15.2 MPH	10.4 MPH
SPEED ORTHOG. TO CG LINE	2685.4 FT-LB	1795.2 FT-LB
CLOSING VELOCITY	15.1 MPH	-10.4 MPH
	-2.1 MPH	-.4 MPH
	4.6 MPH	

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

## VEHICLE # 1

TYPE ----- INTERMEDIATE  
 WEIGHT ----- 4949.0 LBS.  
 VDI ----- 12FZen1  
 L ----- 30.0 IN.  
 C1 ----- 2.0 IN.  
 C2 ----- 2.0 IN.  
 C3 ----- 1.5 IN.  
 C4 ----- 1.8 IN.  
 C5 ----- 2.0 IN.  
 C6 ----- 2.3 IN.  
 D ----- 22.3 IN.  
 RHO ----- 1.00 \*  
 ANG ----- 0.0 DEG.

## VEHICLE # 2

TYPE ----- SUBCOMPACT  
 WEIGHT ----- 3120.0 LBS.  
 VDI ----- 0oBZen1  
 L ----- 30.0 IN.  
 C1 ----- 0.5 IN.  
 C2 ----- 0.8 IN.  
 C3 ----- 5.8 IN.  
 C4 ----- 5.0 IN.  
 C5 ----- 3.8 IN.  
 C6 ----- 3.0 IN.  
 D ----- 3.0 IN.  
 RHO ----- 1.00 \*  
 ANG ----- 170.0 DEG.

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	54.7 INCHES	A2	=	40.3 INCHES
B1	=	59.2 INCHES	B2	=	50.1 INCHES
TR1	=	61.8 INCHES	TR2	=	54.6 INCHES
I1	=	47914.6 LB-SEC**2-IN	I2	=	23628.0 LB-SEC**2-IN
M1	=	12.808 LB-SEC**2/IN	M2	=	8.075 LB-SEC**2/IN
XF1	=	98.8 INCHES	XF2	=	83.3 INCHES
XR1	=	-114.0 INCHES	XR2	=	-91.0 INCHES
YS1	=	38.5 INCHES	YS2	=	33.0 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

RF ----- .01  
 LF ----- .01  
 RR ----- .09  
 LR ----- .09  
 MU ----- .87

## VEHICLE # 2

RF ----- .01  
 LF ----- .01  
 RR ----- .10  
 LR ----- .10

1. TITLE?  
?TEST # 4 TORINO VS PINTO

2. SIZE CATEGORIES?  
?I S

3. VDI, #1  
?12FZEN3

4. VDI, #2  
?05BYEWG

5. ACTUAL WEIGHTS? (Y OR N)  
?Y

6. WEIGHT #1  
?4980

7. WEIGHT #2  
?3190

8. REST & IMPACT? (Y OR N)  
?Y

9. REST COORDINATES?  
?42.8 54.5 137.5 03.9 62.5 88.

10. IMPACT COORDINATES?  
?0. 0. 1. 16.4 3.4 10.

11. SKIDDING OF # 1? (Y OR N)  
?Y

12. SKIDDING STOP BEFORE REST? (Y OR N)  
?Y

13. END OF SKIDDING COORDINATES?  
?20. 5. 10.

14. CURVED PATH? (Y OR N)  
?N

15. ROTATION DIRECTION #1?  
?Cn

16. MORE THAN 360 DEG? (Y OR N)  
?N

17. SKIDDING OF # 2? (Y OR N)  
?Y

18. SKIDDING STOP BEFORE REST? (Y OR N)  
?Y

20. END OF SKIDDING COORDINATES?  
?35. 2. 10.

21. CURVED PATH? (Y OR N)  
?N

23. ROTATION DIRECTION # 2?  
?Cn

24. MORE THAN 360 DEG? (Y OR N)  
?N

25. TIRE-GROUND FRICTION?  
?.07

26. ROLLING RESISTANCE OPTION?(1 OR 2)  
?1

27. ROLL. RESISTANCES, INDIV. WHEELS # 1  
?.01 .01 .2 .2

28. ROLL. RESISTANCES, INDIV. WHEELS # 2  
?.01 .01 .2 .2

31. TRAJECTORY SIMULATION? (Y OR N)  
?N

37. DAMAGE DIMENSIONS? (Y OR N)  
?Y

41. END DAMAGE WIDTH #1  
?41.5

42. END DAMAGE DEPTH #1  
?0.3 7.5 9.8 12.5 14.8 16.3

43. END DAMAGE MIDPOINT OFFSET #1  
?10.1

47. END DAMAGE WIDTH #2  
?41.8

48. END DAMAGE DEPTH #2  
?0.3 31.5 29. 24. 19.5 14.8

49. END DAMAGE MIDPOINT OFFSET #2  
?-y.1

52. FORCE DIRECTIONS (Y OR N)  
?N

SUMMARY OF CRASH RESULTS

TEST # 4. TORINO VS PINTO

VEHICLE # 1      VEHICLE # 2

SPEED CHANGE (TRAJ. + DAMAGE)	10.3 MPH -28.4 DEG	13.0 MPH 100.4 DEG
SPEED CHANGE (DAMAGE ONLY)	9.1 MPH .0 DEG	14.1 MPH 150.0 DEG
IMPACT SPEED	31.9 MPH	4.9 MPH
ENERGY DISSIPATED BY DAMAGE	23465.1 FT-LB	30481.1 FT-LB
SPEED ALONG LINE THRU CGS	31.3 MPH	-4.9 MPH
SPEED ORTHOG. TO CG LINE	-5.9 MPH	.1 MPH
CLOSING VELOCITY	20.4 MPH	

## SUMMARY OF CRASH RESULTS

#### TEST # 4 TORINO VS PINO

VEHICLE #

VEHICLE # 2

\*\*\*\*\* SPEED CHANGE \*\*\*\*\*  
 IMPACT SPEED MPH BASIS  
 MPH OF RESULTS  
 TOTAL LONG. LATERAL  
 \*\*\*\*\*  
 \*\*\*\*\* SPINOUT TRAJECTORIES \*\*\*\*\*  
 \*\*\*\*\* AND CONSERVATION OF \*\*\*\*\*  
 \*\*\*\*\* LINEAR MOMENTUM \*\*\*\*\*  
 \*\*\*\*\* SPINOUT TRAJECTORIES \*\*\*\*\*  
 4.9\* 13.0\* 12.2\* -4.4\* AND  
 \* \* \* \* DAMAGE  
 \* \* \* \*  
 \* \* \* \* 14.1\* 12.2\* -7.1\* DAMAGE DATA ONLY  
 \* \* \* \*

## SCENE INFORMATION

## VEHICLE # 1

## VEHICLE # 2

IMPACT X-POSITION	0.00	FT.	16.40	FT.
IMPACT Y-POSITION	0.00	FT.	3.40	FT.
IMPACT HEADING ANGLE	1.00	DEG.	10.00	DEG.
REST X-POSITION	42.80	FT.	63.90	FT.
REST Y-POSITION	54.50	FT.	62.50	FT.
REST HEADING ANGLE	137.48	DEG.	87.99	DEG.
END-OF-ROTATION X-POSITION	20.00	FT.	35.00	FT.
END-OF-ROTATION Y-POSITION	5.00	FT.	2.00	FT.
END-OF-ROTATION HEADING ANGLE	10.00	DEG.	10.00	DEG.
DIRECTION OF ROTATION	CW		CW	
AMOUNT OF ROTATION	<300		<300	

## COLLISION CONDITIONS

## VEHICLE # 1

## VEHICLE # 2

XCO1	=	0.0 FT.	XCO20	=	16.4 FT.
YCO1	=	0.0 FT.	YC020	=	3.4 FT.
PSI10	=	1.0 DEGREES	PSI20	=	10.0 DEGREES
PSI1D0	=	0.0 DEG/SEC	PSI2D0	=	0.0 DEG/SEC
V10	=	31.9 MPH	V20	=	4.9 MPH
V10	=	0.0 MPH	V20	=	0.0 MPH

## SEPARATION CONDITIONS

XCSI	=	0.0 FT.	XCS2	=	16.4 FT.
YCSI	=	0.0 FT.	YCS2	=	3.4 FT.
PSIS1	=	1.0 DEG	PSIS2	=	10.0 DEG
US1	=	22.8 MPH	US2	=	17.1 MPH
VS1	=	4.9 MPH	VS2	=	-4.4 MPH
PSISD1	=	18.2 DEG/SEC	PSISD2	=	0.0 DEG/SEC

## RELATIVE VELOCITY DATA

## VEHICLE # 1

## VEHICLE # 2

SPEED CHANGE (TRAJ. + DAMAGE)	10.3 MPH	13.0 MPH
SPEED CHANGE (DAMAGE ONLY)	-28.4 DEG	100.4 DEG
IMPACT SPEED	9.1 MPH	14.1 MPH
ENERGY DISSIPATED BY DAMAGE	.0 DEG	150.0 DEG
SPEED ALONG LINE THRU CGS	31.9 MPH	4.9 MPH
SPEED ORTHOG. TO CG LINE	23465.1 FT-LB	30461.1 FT-LB
CLOSING VELOCITY	31.3 MPH	-4.9 MPH
	-5.9 MPH	.1 MPH
	26.4 MPH	

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

## VEHICLE # 1

TYPE-----INTERMEDIATE  
 HEIGHT-----4980.0 LBS.  
 VDI-----12FZEW3  
 L-----41.5 IN.  
 C1-----6.3 IN.  
 C2-----7.8 IN.  
 C3-----9.8 IN.  
 C4-----12.5 IN.  
 C5-----14.8 IN.  
 C6-----16.3 IN.  
 D-----19.7 IN.  
 RHO-----1.00 \*  
 ANG-----360.0 DEG. \*

## VEHICLE # 2

TYPE-----SUBCOMPACT  
 WEIGHT-----3190.0 LBS.  
 VDI-----05BYEW5  
 L-----41.8 IN.  
 C1-----36.0 IN.  
 C2-----31.8 IN.  
 C3-----29.0 IN.  
 C4-----24.0 IN.  
 C5-----19.5 IN.  
 C6-----14.8 IN.  
 D------11.9 IN.  
 RHO-----1.00  
 ANG-----150.0 DEG. \*

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	24.7 INCHES	A2	=	46.3 INCHES
B1	=	59.2 INCHES	B2	=	50.1 INCHES
TR1	=	61.0 INCHES	TR2	=	54.0 INCHES
I1	=	48214.8 LB-SEC**2-IN	I2	=	24302.0 LB-SEC**2-IN
M1	=	12.888 LB-SEC**2/IN	M2	=	8.250 LB-SEC**2/IN
Xr1	=	90.0 INCHES	Xr2	=	83.3 INCHES
XR1	=	-114.0 INCHES	XR2	=	-91.0 INCHES
Ys1	=	38.5 INCHES	YS2	=	33.0 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

Rf-----.01  
 Lf-----.01  
 Rr-----.20  
 Lr-----.20  
 M-----.87

## VEHICLE # 2

Rf-----.01  
 Lf-----.01  
 RR-----.20  
 LR-----.20

?TEST # 5 TORINO VS CIVIC

2. SIZE CATEGORIES?  
?I M

3. VDI, #1  
?12FZent

4. VDI, #2  
?0.000000

5. ACTUAL WEIGHTS? -(Y OR N)  
?Y

6. WEIGHT #1  
?4000

7. WEIGHT #2  
?2000

8. REST & IMPACT? (Y OR N)  
?Y

9. REST COORDINATES?  
?241.0 0. 3. 00.9 39. 282.

10. IMPACT COORDINATES?  
?0. 0. 0. 14.9 3.4 10.

11. SKIDDING-OF #1? -(Y OR N)  
?N

12. CURVED PATH? -(Y OR N)  
?N

13. ROTATION DIRECTION #1?  
?Cw

14. MORE THAN 360 DEG? -(Y OR N)  
?N

15. SKIDDING OF # 2? (Y OR N)  
?Y

16. SKIDDING STOP BEFORE REST? -(Y OR N)  
?Y

17. END OF SKIDDING COORDINATES?  
?20. 23. 200.

18. CURVED PATH? -(Y OR N)  
?Y

22. POINT ON CURVE?

?40. 10.

23. ROTATION DIRECTION # 2?

?CII

24. MORE THAN 360 DEG? (Y OR N)

?N

25. FRIE-GROUND FRICTION?

?87

26. ROLLING RESISTANCE OPTION?(1 OR 2)

?1

27. ROLL. RESISTANCES, INDIV. WHEELS # 1

?0.01 .01 .2 .2

28. ROLL. RESISTANCES, INDIV. WHEELS # 2

?0.2 .2 .01 1.

31. TRAJECTORY SIMULATION? (Y OR N)

?N

37. DAMAGE DIMENSIONS? (Y OR N)

?Y

41. END DAMAGE WIDTH #1

?35.0

42. END DAMAGE DEPTH #1

?1.4 1.4 2. 2.1 2.3 2.9

43. END DAMAGE MIDPOINT OFFSET #1

?20.3

47. END DAMAGE WIDTH #2

?53.

48. END DAMAGE DEPTH #2

?30. 30.0 31.5 23. 13.3 6.

49. END DAMAGE MIDPOINT-OFFSET #2

?-1.0

52. FORCE DIRECTIONS (Y OR N)

?Y

53. PRINCIPAL FORCE ANGLE #1?

?0.

54. PRINCIPAL FORCE ANGLE #2?

?170.

II=65

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SUMMARY OF CRASH RESULTS

TEST # 2 TORINO VS CIVIC

VEHICLE # 1 VEHICLE # 2

SPEED CHANGE (TRAD. + DAMAGE)	8.1 MPH .0 DEG	15.2 MPH 162.9 DEG
SPEED CHANGE (DAMAGE ONLY)	8.1 MPH .0 DEG	14.8 MPH 170.0 DEG
IMPACT SPEED	33.8 MPH	10.5 MPH
ENERGY DISSIPATED BY DAMAGE	3114.8 FT-LB	30255.0 FT-LB
SPEED ALONG LINE THRU CGS	33.0 MPH	10.5 MPH
SPEED ORTHOG. TO CG LINE	-7.5 MPH	.5 MPH
LOSING VELOCITY	22.5 MPH	

## SUMMARY OF CRASH RESULTS

TEST # 2 TORINO VS CIVIC

## VEHICLE # 1

SPEED CHANGE				BASIS	
IMPACT SPEED	MPH	TOTAL	LONG.	LATERAL	OF
MPH		*	*	*	RESULTS
		TOTAL	LONG.	LATERAL	
		*	*	*	*
33.8	8.1	8.1	8.1	0.0	*SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
		*	*	*	DAMAGE
		8.1	-8.1	0.0	DAMAGE DATA ONLY

## VEHICLE #2

SPEED CHANGE				BASIS	
IMPACT SPEED	MPH	TOTAL	LONG.	LATERAL	OF
MPH		*	*	*	RESULTS
		TOTAL	LONG.	LATERAL	
		*	*	*	*
10.5	15.2	14.5	14.5	-4.5	*SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
		*	*	*	DAMAGE
		14.5	14.5	-2.0	DAMAGE DATA ONLY

## SCENE INFORMATION

	VEHICLE # 1	VEHICLE # 2
IMPACT X-POSITION	0.00 FT.	14.90 FT.
IMPACT Y-POSITION	0.00 FT.	3.40 FT.
IMPACT HEADING ANGLE	0.00 DEG.	107.00 DEG.
REST X-POSITION	241.00 FT.	58.90 FT.
REST Y-POSITION	0.00 FT.	39.00 FT.
REST HEADING ANGLE	3.00 DEG.	281.97 DEG.
END-OF-ROTATION X-POSITION	0.00 FT.	55.00 FT.
END-OF-ROTATION Y-POSITION	0.00 FT.	23.00 FT.
END-OF-ROTATION HEADING ANGLE	0.00 DEG.	259.97 DEG.
POINT-ON-CURVE X-POSITION		40.00 FT.
POINT-ON-CURVE Y-POSITION		10.00 FT.
DIRECTION OF ROTATION	CH	CH
AMOUNT OF ROTATION	<300	<300

## COLLISION CONDITIONS

VEHICLE # 1	VEHICLE # 2
XCO1 = 0.0 FT.	XC20 = 14.9 FT.
YCO1 = 0.0 FT.	YC20 = 3.4 FT.
PSI10 = 0.0 DEGREES	PSI20 = 10.0 DEGREES
PSI1D0 = 0.0 DEG/SEC	PSI2D0 = 0.0 DEG/SEC
V10 = 33.8 MPH	V20 = 10.5 MPH
VFO = 0.0 MPH	VFO = 0.0 MPH

## SEPARATION CONDITIONS

XCS1 = 0.0 FT.	XCS2 = 14.9 FT.
YCS1 = 0.0 FT.	YCS2 = 3.4 FT.
PSI1S1 = 0.0 DEG	PSI2S2 = 10.0 DEG
VS1 = 25.7 MPH	VS2 = 25.1 MPH
VSI = 0.0 MPH	VS2 = -4.5 MPH
PSISD1 = 0.0 DEG/SEC	PSISD2 = -300.0 DEG/SEC

## RELATIVE VELOCITY DATA

	VEHICLE # 1	VEHICLE # 2
SPEED CHANGE (IRAJ. + DAMAGE)	8.1 MPH -0.0 DEG	15.2 MPH +02.9 DEG
SPEED CHANGE (DAMAGE ONLY)	8.1 MPH -0.0 DEG	14.8 MPH +10.0 DEG
IMPACT SPEED	33.8 MPH	10.5 MPH
ENERGY DISSIPATED BY DAMAGE	3114.8 FT-LB	30255.0 FT-LB
SPEED ALONG LINE THRU CGS	33.0 MPH	-10.5 MPH
SPEED ALONG FORCE LINE	-7.5 MPH	.5 MPH
CLOSING VELOCITY	68	22.5 MPH
		ZQ-6057-V-6

## SUMMARY OF DAMAGE DATA

(\* INDICATES DEFAULT VALUE)

## VEHICLE # 1

TYPE ----- INTERMEDIATE  
 WEIGHT ----- 4600.0 LBS.  
 VDI ----- 12FZEN1  
 L ----- 33.0 IN.  
 C1 ----- 1.4 IN.  
 C2 ----- 1.4 IN.  
 C3 ----- 2.0 IN.  
 C4 ----- 2.1 IN.  
 C5 ----- 2.3 IN.  
 C6 ----- 2.9 IN.  
 D ----- 22.3 IN.  
 RHO ----- 1.00 \*  
 ANG ----- 0.0 DEG.

## VEHICLE # 2

TYPE ----- MINICAR  
 WEIGHT ----- 2530.0 LBS.  
 VDI ----- 05BDENO  
 L ----- 53.0 IN.  
 C1 ----- 30.0 IN.  
 C2 ----- 30.5 IN.  
 C3 ----- 31.5 IN.  
 C4 ----- 23.0 IN.  
 C5 ----- 13.3 IN.  
 C6 ----- 0.0 IN.  
 D ----- -7.7 IN.  
 RHO ----- 1.00 \*  
 ANG ----- 170.0 DEG.

## DIMENSIONS AND INERTIAL PROPERTIES

A1	=	24.7 INCHES	A2	=	45.1 INCHES
B1	=	59.2 INCHES	B2	=	48.1 INCHES
X1	=	61.8 INCHES	X2	=	51.1 INCHES
I1	=	44535.7 LB-SEC**2-IN	I2	=	13134.5 LB-SEC**2-IN
M1	=	11.905 LB-SEC**2/IN	M2	=	8.548 LB-SEC**2/IN
Xr1	=	98.8 INCHES	Xr2	=	70.0 INCHES
XR1	=	114.0 INCHES	XR2	=	-83.8 INCHES
Y1	=	38.0 INCHES	YS2	=	30.4 INCHES

## ROLLING RESISTANCE

## VEHICLE # 1

R1 ----- .01  
 L1 ----- .01  
 RR ----- .20  
 LR ----- .20

## VEHICLE # 2

RF ----- .20  
 LF ----- .20  
 RR ----- .01  
 LR ----- 1.00

AVG ----- .07



APPENDIX III

SMAC INPUT DECKS

SIMULATION MODEL of AUTOMOBILE COLLISION						
*RICSAC TEST #1	*RICSAC TEST #2	*RICSAC TEST #3	*RICSAC TEST #4	*RICSAC TEST #5	*RICSAC TEST #6	*RICSAC TEST #7
0.0	4.0	0.01	0.001	0.01	0.001	0.0
-187.8	124.5	-30.0	0.0	357.26	0.0	2.0
0.0	-6.8	90.0	0.0	357.26	0.0	1
50.69	65.1	61.1	45.019	12.034	0.0	2
45.69	48.51	55.4	230.76	8.023	0.0	3
-123.36	-123.36	-109.91	-109.91	-109.91	0.0	4
-754.7	-754.7	-7108.	-7108.	-7108.	0.0	5
0.0	0.30	0.10	0.0	0.0	0.0	6
-22.3	-2.2.3	-22.3	-22.3	-22.3	-22.3	7
-300.	-300.	-300.	-300.	-300.	-300.	8
-300.	-300.	-300.	-300.	-300.	-300.	9
0.0	0.30	0.10	0.0	0.0	0.0	10
-15.55	-15.55	-15.55	-15.55	-15.55	-15.55	11
-400.	-400.	-400.	-400.	-400.	-400.	12
-400.	-400.	-400.	-400.	-400.	-400.	13
0.0	0.30	0.10	0.0	0.0	0.0	14
-500.	500.	500.	500.	500.	500.	15
2.0	0.2	15.0	5.0	5.0	5.0	16
0.04600	1.7547-31.6711-5					

SIMULATION MODEL OF AUTOMOBILE		COLLISION 2	
#1 RICSAC IN SF	#2 CHEVELLE-PINTO	COLLISION 3	COLLISION 4
0.0	4.0	0.01	0.01
-1.37.8	1.24.5	-30.0	565.0
0.0	-65.8	90.0	565.0
52.45	63.53	61.1	4301.9
4.2.75	47.42	55.4	2367.6
-12.338.	-123.36	-109.41	-1.09.41
-7.347.	-75.47.	-75.08	-75.08
0.0	0.36	0.19	0.3
-2.2.3	-3.06	-30.0	-800.
-2.2.3	-2.2.3	-2.2.3	-22.3
-270.0	-270.0	-270.0	-270.0
-270.0	-270.0	-270.0	-270.0
0.0	0.30	0.10	0.0
-15.55	-15.55	-15.55	-15.55
-270.0	-270.0	-270.0	-270.0
-270.0	-270.0	-270.0	-270.0
0.0	0.30	0.10	0.0
0.0	0.36	0.10	1.0
-300.	500.	500.	500.
2.0	0.2	1.5.0	5.0
0.0466	1.7547	-31.6711	-5

SIMULATION MODEL OF AUTOMOBILE COLLISIONS

SIMULATION MODEL OF AUTOMOBILE COLLISIONS						
TEST #6 CHEVROLET VS RABBIT		TEST #1				
0.0	4.0	0.01	0.001	0.01	0.1	0.0000001
0.0	0.0	0.0	0.0	37.69	0.0	0.0000002
14.6*	12.	120.	0.0	377.9	0.0	0.000003
50.0*	60.0	62.0	352.37	11.2	0.0	0.000004
40.0*	54.6	56.0	156.01	6.83	0.0	0.000005
-111.110*	-111.110	-9266.	-9266.	-9266.	-9266.	0.000006
-7136*	-7136	-5295*	-5295*	-5295*	-5295*	0.000007
0.0	0.3	0.1	0.0	0.0	0.0	0.000008

$\pi_{12}^*$	$\pi_{12}^*$	$\pi_{12}^*$	$\pi_{12}^*$	$\pi_{12}^*$	$\pi_{12}^*$
$-1.96^*$	$-1.96^*$	$-1.96^*$	$-1.96^*$	$-1.96^*$	$-1.96^*$
$-1.96^*$	$-1.96^*$	$-1.96^*$	$-1.96^*$	$-1.96^*$	$-1.96^*$
$0.0^*$	$0.3^*$	$0.1^*$	$0.0^*$	$0.0^*$	$0.0^*$
$-1.50^*$	$-1.50^*$	$-1.50^*$	$-1.50^*$	$-1.50^*$	$-1.50^*$
$-1.50^*$	$-1.50^*$	$-1.50^*$	$-1.50^*$	$-1.50^*$	$-1.50^*$
$-1.1^*$	$-1.1^*$	$-1.1^*$	$-1.1^*$	$-1.1^*$	$-1.1^*$
$-1.1^*$	$-1.1^*$	$-1.1^*$	$-1.1^*$	$-1.1^*$	$-1.1^*$
$0.0^*$	$0.9^*$	$0.1^*$	$0.0^*$	$0.0^*$	$0.0^*$
$0.0^*$	$0.0^*$	$0.0^*$	$-1.5$	$-3.0$	$-3.0$
$0.0^*$	$0.0^*$	$0.0^*$	$0.0^*$	$-3.0$	$-3.0$
$0.0^*$	$0.0^*$	$0.0^*$	$-1.5$	$-3.0$	$-3.0$
$0.0^*$	$0.0^*$	$0.0^*$	$0.0^*$	$-3.0$	$-3.0$
$0.0^*$	$0.0^*$	$0.0^*$	$0.0^*$	$-1.5$	$-1.5$
$0.0^*$	$0.3^*$	$0.1^*$	$0.0^*$	$0.0^*$	$0.0^*$
$-500.0$	$500.0$	$500.0$	$500.0$	$500.0$	$500.0$
$-2.0$	$0.2$	$1.0^*$	$5.0^*$	$70^*$	$30^*$
$0.04606$	$1.647-31.671$	$4-5$			

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SIMULATION TABLE FOR AUTOMATIC CONTROL METHODS							
** * ITST # 0.0	4.0 0.0	0.01 0.0	0.001 0.0	0.0001 0.0	0.00001 0.0	0.000001 0.0	0.0000001 0.0
14.0 0.0	9.0 0.0	1.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0	0.0 0.0
50.0 0.0	60.0 0.0	62.0 0.0	40.0 0.0	11.0 2.	0.0 0	-11.0 3.6	0.0 0.3
39.7 0.0	35.0 0.0	36.0 0.0	15.0 0.0	0.0 7.5	0.0 0	-9.0 4.4	30.0 0.0
-1.1402.	-1.1402.	-1.1402.	-2.41652.	-2.41652.	-2.41652.	-2.41652.	-2.41652.
-7.165.	-7.165.	-7.165.	-5.153.	-5.153.	-5.153.	-5.153.	-5.153.
0.0 0.	0.3 0.	0.4 0.	0.0 0.	0.0 0.	0.0 0.	0.0 0.	0.0 0.
-1.2.	-1.2.	-1.2.	-1.2.	-1.2.	-1.2.	-1.2.	-1.2.
-1.2.	-1.2.	-1.2.	-1.2.	-1.2.	-1.2.	-1.2.	-1.2.
-1.96.	-1.96.	-1.96.	-1.96.	-1.96.	-1.96.	-1.96.	-1.96.
-1.96.	-1.96.	-1.96.	-1.96.	-1.96.	-1.96.	-1.96.	-1.96.
0.0 0.	0.3 0.	0.4 0.	0.0 0.	0.0 0.	0.0 0.	0.0 0.	0.0 0.
-1.10.	-1.10.	-1.10.	-1.10.	-1.10.	-1.10.	-1.10.	-1.10.
-1.10.	-1.10.	-1.10.	-1.10.	-1.10.	-1.10.	-1.10.	-1.10.
-6.	-6.	-6.	-6.	-6.	-6.	-6.	-6.
-8.	-8.	-8.	-8.	-8.	-8.	-8.	-8.
0.0 0.	0.3 0.	0.4 0.	1.0 0.	1.0 0.	1.0 0.	1.0 0.	1.0 0.
0.0 0.	0.3 0.	0.4 0.	0.0 0.	0.0 0.	0.0 0.	0.0 0.	0.0 0.
-3.36.0	5.00.0	5.00.0	30.0.0	70.0	50.0	0.0	0.0
2.0 0.	0.2 0.	2.0 0.	2.0 0.	2.0 0.	2.0 0.	2.0 0.	2.0 0.
0.0 4.00001.	1.72467.	-31.12071.	1.72467.	-31.12071.	1.72467.	-31.12071.	1.72467.

SIMULATION MODEL OF AUTOMOBILE COLLISIONS (SMAC)											
TEST #	MALIBU	VS. MALIBU	TEST #	MALIBU	VS. MALIBU	TEST #	MALIBU	VS. MALIBU	TEST #	MALIBU	VS. MALIBU
0.0	4.0	0.01	0.0	0.01	0.001	0.0	0.01	0.1	30.0	5.0	2.0
-1.3	2.1	2.0	-1.2	0.0	0.0	0.0	3.95	2.2	0.2	0.0	1.2
0.0	0.0	0.0	0.0	0.0	0.0	0.0	3.65	2	0.0	0.0	2
50.5	60.5	62.0	50.5	60.5	62.0	47.654	11.59	6.6	94.8	113.7	38.3
50.5	60.5	62.0	50.5	60.5	62.0	50.121	12.19	6.6	94.8	113.7	38.3
-1.1062	2.4	-1.1024	-1.1062	2.4	-1.1024	-1.0110	8	-1.0116	8	-1.0116	8
-1.2007	8	-1.0589	-6	-1.1156	9	-1.078	7	-1.078	7	-1.078	7
0.0	0.3	0.1	0.0	0.1	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0
-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0
-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.
-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.
0.0	0.3	0.1	0.0	0.1	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0
-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0	-1.2	0
-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.
-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.	-300.
0.0	1.8	0.1	0.0	0.1	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0	2.0	2.0	0	2.0	2.0	1.0	1.0	0	0	0
1.0	2.0	2.0	1.0	2.0	2.0	3.0	4.0	4.0	0	0	0
2.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
0.0	0	0	2.0	0	2.0	1.0	1.0	1.0	0	0	0
1.0	2.0	2.0	2.0	3.0	3.0	3.0	4.0	4.0	0	0	0
9.0	10.0	11.0	11.0	11.0	11.0	11.0	11.0	11.0	0	0	0
0.0	1.5	0.1	0.0	0.1	0.0	0.0	0.0	0.0	0	0	0
0.0	8.0	0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
0.0	8.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	0	0	0
2.0	0.3	2.0	5.0	0.0	80.0	80.0	0.87	0.0	0.0	0.0	0.0
0.04606	1.7247	-3.12671	1.5	-5	-5	-5	1.00	1.00	1.00	1.00	1.00
											999

SIMULATION FOR THE AMOUNT OF

TEST #1 FLUIDA VS TORINO 90 DEG FRONT/SIDE 21.2/21.2 MPa									
0.0	5.0	0.01	0.001	0.01	0.001	0.01	0.001	0.01	0.001
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
102.33	-64.69	90.0	0.0	373.1	0.0	373.1	0.0	30.0	0.0
37.17	49.63	50.8	12261.	5.875	0.0	0.0	0.0	30.0	0.0
54.56	63.94	63.45	5800.	12.76	0.0	0.0	0.0	30.0	0.0
-393.6	-595.9.	-644.6.	-444.6.	-444.6.	-444.6.	-444.6.	-444.6.	100.29	-117.5
-1219.3	-1219.3	-10406.	-10406.	-10406.	-10406.	-10406.	-10406.	29.6	39.65
0.0	0.3	0.1	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
-200.	-200.	-200.	-200.	-200.	-200.	-200.	-200.	100.29	-117.5
-7.	-7.	-7.	-7.	-7.	-7.	-7.	-7.	100.29	-117.5
-7.	-7.	-7.	-7.	-7.	-7.	-7.	-7.	100.29	-117.5
0.0	0.6	0.1	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
-14.00.	-14.00.	-14.00.	-14.00.	-14.00.	-14.00.	-14.00.	-14.00.	100.29	-117.5
-14.	-14.	-14.	-14.	-14.	-14.	-14.	-14.	100.29	-117.5
-14.	-14.	-14.	-14.	-14.	-14.	-14.	-14.	100.29	-117.5
-14.	-14.	-14.	-14.	-14.	-14.	-14.	-14.	100.29	-117.5
-175.	-175.	-175.	-175.	-175.	-175.	-175.	-175.	100.29	-117.5
-175.	-175.	-175.	-175.	-175.	-175.	-175.	-175.	100.29	-117.5
-175.	-175.	-175.	-175.	-175.	-175.	-175.	-175.	100.29	-117.5
0.0	1.5	0.1	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
0.0	4.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
2.0	0.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
6.0	3.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
0.0	4.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
2.0	0.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
3.0	0.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
0.0	1.0	0.1	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
0.0	3.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
6.0	0.0	1.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5
11.0	11.0	11.0	11.0	11.0	11.0	11.0	11.0	100.29	-117.5
0.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	100.29	-117.5
6.0	0.0	6.0	6.0	6.0	6.0	6.0	6.0	100.29	-117.5
11.0	11.0	11.0	11.0	11.0	11.0	11.0	11.0	100.29	-117.5
-500.0	500.0	500.0	500.0	500.0	500.0	500.0	500.0	100.29	-117.5
2.0	0.2	15.	5.0	5.0	5.0	5.0	5.0	100.29	-117.5
0.04000	1.7547-31.6711-5	0.0	0.0	0.0	0.0	0.0	0.0	100.29	-117.5

SIMULATION MODEL OF AUTOMOBILE COLLISIONS

SIMULATION MODEL OF AUTOMOBILE COLLISIONS						
TEST #10 HONDA VS TURINO		90 DEG FRONT SIDE	33° 3/3.3 MPH	2.0	0.0000001	0.0000001
0.0	3.92	0.01	0.001	0.01	0.0000001	0.0000001
0.0	0.0	0.0	0.0	0.0	0.0000001	0.0000001
-101.05	-72.2	90.0	0.0	5.36	0.0	0.0000001
36.37	50.63	50.6	0.0	0.0	0.0	0.0000001
55.38	63.12	63.45	50000.	0.004	0.0	0.0000004
-61.68	-61.88	-4440.	-4440.	0.0	0.0	0.0000005
-11598.	-11598.	-10176.	-10176.	0.0	0.0	0.0000005
0.0	1.0	0.1	0.0	0.0	0.0000008	0.0000007
-14.00.	-14.00.	-14.00.	-14.00.	-14.00.	-275.	0
-0.0	-75.	-275.	-275.	-275.	-275.	-350.
-14.00.	-14.00.	-14.00.	-14.00.	-14.00.	-275.	-275.
-5500.	-275.	-275.	-275.	-275.	-7.	-7.
-7.	-7.	-7.	-7.	-7.	-7.	-7.
-7.	-7.	-7.	-7.	-7.	-7.	-7.
0.0	0.8	0.1	0.0	0.0	0.0000009	0.0000009
0.0	0.0	0.0	0.0	0.0	-1.3.	-1.3.
-13.	-13.	-13.	-13.	-13.	-1.3.	-1.3.
-13.	-13.	-13.	-13.	-13.	-1.3.	-1.3.
-300.	-300.	-300.	-300.	-300.	-300.	-300.
-300.	-300.	-300.	-300.	-300.	-300.	-300.
-300.	-300.	-300.	-300.	-300.	-300.	-300.
0.0	0.8	0.1	0.0	0.0	0.0000010	0.0000011
0.0	4.0	4.0	4.0	4.0	-12.	-12.
-4.0	-4.0	-4.0	-4.0	-4.0	-20.	-20.
0.0	4.0	4.0	4.0	4.0	-20.	-20.
-4.0	-4.0	-4.0	-4.0	-4.0	-4.0.	-4.0.
0.0	2.0	0.1	0.0	0.0	0.0	0.0000011
0.0	4.0	11.0	11.0	11.0	11.0	11.0
11.	11.	11.	11.	10.	9.	8.
6.	6.	6.	6.	5.	5.	5.
0.0	0.0	1.0	1.0	2.0	0.0	0.0
-1.0	-4.0	-8.0	-8.0	-8.0	-4.0	-4.0
1.0	2.0	3.0	4.0	5.0	5.0	5.0
-500.0	1125.	500.0	1125.	500.0	0.0	0.0000012
2.0	0.2	15.	15.	70.0	60.0	0.55
0.04606	1.7547	-31.6711	-5.	-5.	0.0	0.0000014

SIMULATION MODEL OF AUTOMOBILE COLLISIONS

TEST #11 VEGA VS TORINO		COLLISIONS ON HEAD ON	20.4/20.4 MPH
0.0	4.0	0.01	0.01
0.0	-4.0	0.01	0.01
1.88	7	-49.45	170.9
0.0	0.0	0.0	0.0
4.9	4.5	47.5	55.2
54.4	0.3	63.45	223.94
-58.76	0.876	-687.6	7.92
-120.56	-120.56	-103.14	0.0
0.0	0.3	0.1	0.0
-1.6	-1.6	-16.	-16.
-1.6	-1.6	-16.	-16.
-2.85	-2.85	-285.	-285.
-2.85	-2.85	-285.	-285.
0.0	0.3	0.1	0.0
-1.3	-1.3	-13.	-13.
-1.3	-1.3	-13.	-13.
-1.80	-1.80	-180.	-180.
-1.80	-1.80	-180.	-180.
0.0	1.5	0.25	0.0
0.	0.	0.	0.
0.0	0.3	0.1	1.0
-300.0	500.0	500.0	500.0
2.0	0.2	15.	5.0
0.04006	1.7547-31.6711-5	999	999

SIMULATION MODELL		W	AUTO ROTATE	COLISTAMS
*** TEST #12	VGA	V <sub>S</sub>	FORTRAN	FORTRAN
0.0	4.0	0.01	0.01	31.5 / 31.5 MM <sup>2</sup> H
187.1	-4.3.00	170.0	0.01	30.0 30.0
0.0	0.0	0.0	524.3	0.0
47.2	49.5.8	35.2	0.0	554.3 0.0
55.6.2	62.3.8	63.45	2.304.4	6.15 0.0
-7.39.0.	-7.30.0.	-30.00.	2.200.4	11.75 102.7
-11002.	-11002.	-9810.	-320.0.	-115.1 39.65
0.0	0.3	0.1	0.0	0.0 0.0
-8.	-8.	-8.	-8.	0.000007
-600.	-600.	-600.	-600.	6.000008
-156.	-156.	-156.	-156.	-156.
0.0	0.3	0.1	0.0	0.0000009
-13.	-13.	-13.	-13.	-13.
-222.	-222.	-222.	-222.	-222.
-222.	-222.	-222.	-222.	-222.
0.0	27	0.045	0.0	1.0
0.0	0.0	0.0	0.0	0.0
0.0	0.3	0.1	1.0	1.2.
-30.6.0	50.0.0	500.0	220.0	0.0000011
2.0	0.2	15.	5.0	0.0000012
0.04600	1.7.47-31.6711-5	1.7.47-31.6711-5	55.0	0.0000013
			*	0.0000014
			*	9.999

SIMULATION NUMBER		TEST #3		TOKOMA-PINETU		COLLISIONS		RUN 15		RUN 16	
*	RICSAC	*	TEST	*	TIME	*	TEST	*	TEST	*	TEST
0.0	15.0	0.025	0.001	0.01	0.01	0.0	0.0	37.3	64	0.0	0.0000001
-296.53	106.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0000002
55.05	142.33	18.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0000003
37.32	62.32	63.45	30.876	12.000	0.0	1.1	0.48	-116.32	39.65	0.0000004	
56.78	56.78	55.4	226.02	6.0126	0.0	64.92	-94.03	34.7	0.0000005		
-12380.	-12380.	-111231.	-111231.	-111231.	-111231.	-111231.	-111231.	-111231.	-111231.	-111231.	0.0000006
-8793.	-9076.	-5956.	-5662.	-5662.	-5662.	-5662.	-5662.	-5662.	-5662.	-5662.	0.0000007
0.0	0.3	0.1	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0000008
-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	0.0000009
-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	-22.3	0.0000009
-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	0.0000009
-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	-78.4	0.0000009
0.0	0.25	0.005	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0000009
-15.55	-15.55	-15.55	-15.55	-15.55	-15.55	-15.55	-15.55	-15.55	-15.55	-15.55	0.0000009
-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	0.0000009
-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	-58.0	0.0000009
0.0	0.30	0.10	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0000009
-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	0.0000009
-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	-0.45	0.0000009
0.0	5.0	1.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0000009
-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	0.0000009
-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	-1.5	0.0000009
-300.	500.	500.	500.	500.	500.	500.	500.	500.	500.	500.	0.0000009
2.0	0.2	1.5.0	5.0	80.0	80.0	80.0	80.0	80.0	80.0	80.0	0.0000009
*06423	3.5417	-34.7381	-5	-	-	-	-	-	-	-	0.0000009

SIMULATION		EIGHT		AUX		COLLISIONS		COLLISIONS		COLLISIONS	
RICSSAC		TURF #4		TURF #40-21N50		38.7 Mpc		RDN 9		RDN 9	
0.0	5.0	0.25	0.001	0.01	0.001	5.0	5.0	2.0	2.0	0.000001	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.000002	0.0
197.3	41.4	10.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.000003	0.0
55.9	62.1	6.5-4.5	561.74	12.69	0.0	9.5	-115.9	35.4	0.000004	0.000004	0.0
35.7	58.6	5.5-4	227.04	8.26	0.0	72.9	-96.1	33.25	0.000005	0.000005	0.0
-1236.6	-12386.	-11232.	-11002.	-	-	-	-	-	-	0.000006	0.0
-8982.	-9833.	-5673.	-5673.	-	-	-	-	-	-	0.000007	0.0
0.0	5.0	0.5	0.0	-26.2	-26.2	-26.2	-26.2	-26.2	-26.2	0.000008	0.0
-26.2	-22.0	-22.0	-22.0	-26.2	-26.2	-26.2	-26.2	-26.2	-26.2	0.000009	0.0
-26.2	-22.6	-22.6	-22.6	-26.2	-26.2	-26.2	-26.2	-26.2	-26.2	0.000009	0.0
-26.2	-22.6	-22.6	-22.6	-26.2	-26.2	-26.2	-26.2	-26.2	-26.2	0.000009	0.0
-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	0.000009	0.0
-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	0.000009	0.0
-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	0.000009	0.0
-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	-238.	0.000009	0.0
0.0	5.0	0.5	0.0	-19.	-19.	-19.	-19.	-19.	-19.	0.000009	0.0
-19.	-19.	-19.	-19.	-19.	-19.	-19.	-19.	-19.	-19.	0.000009	0.0
-76.0	-76.0	-76.0	-76.0	-76.0	-76.0	-76.0	-76.0	-76.0	-76.0	0.000009	0.0
-20.8	-20.8	-20.8	-20.8	-20.8	-20.8	-20.8	-20.8	-20.8	-20.8	0.000009	0.0
-832.	-832.	-832.	-832.	-832.	-832.	-832.	-832.	-832.	-832.	0.000009	0.0
-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	0.000009	0.0
-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	0.000009	0.0
-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	-120.	0.000009	0.0
-336.	-336.	-336.	-336.	-336.	-336.	-336.	-336.	-336.	-336.	0.000009	0.0
0.0	4.0	0.5	0.0	-20.0	-20.0	-20.0	-20.0	-20.0	-20.0	0.000010	0.0
16.0	16.0	16.0	16.0	20.0	20.0	20.0	20.0	20.0	20.0	0.000010	0.0
0.0	4.0	0.5	0.0	-20.0	-20.0	-20.0	-20.0	-20.0	-20.0	0.000010	0.0
16.0	16.0	16.0	16.0	20.0	20.0	20.0	20.0	20.0	20.0	0.000010	0.0
0.0	6.0	7.0	8.0	9.0	10.0	11.0	12.0	13.0	14.0	0.000011	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.000011	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.000012	0.0
2.0	0.25	1.0	3.0	5.0	8.0	12.0	16.0	20.0	24.0	0.000013	0.0
0.04600	1.7547-31.6711-3	-	-	-	-	-	-	-	-	0.000014	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.000015	0.0



