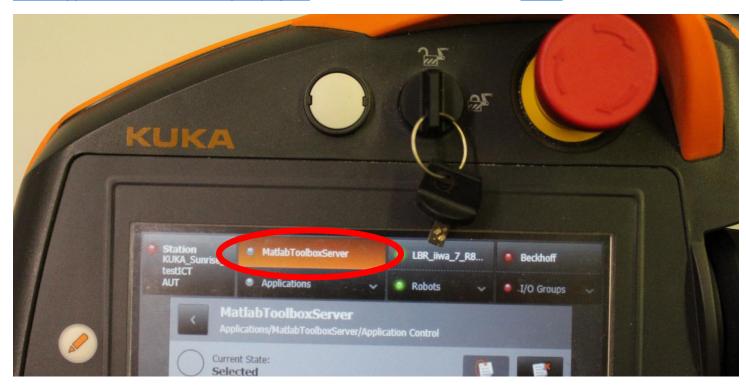
Software Requirements

Robot side:

On the robot side, the MatlabToolboxServer application (figure below) shall be present in the teach pendant of the robot, you can find the JAVA code for it (i.e. the Sunrise.Workbench JVA files) in the following GitHub webpage (click here), copy all of the listed files into your project. A video tutorial on this is available in here.



PC side: Python 3
You need Power (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC), also you need the interpy library. The python files for the interpy are available in the following Git Files (installed on your PC).