

Kernel Course: Lecture 19

Hardware Tools in Embedded Kernel Development

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Agenda

1. Multimeter
2. Scope
3. Logic Analyzer
4. JTAG

Hardware Tools Overview

Where it can be useful?

- Debugging hardware issues (obviously)
- Board bringup (measuring clocks, voltages, etc)
- Fixing adapter drivers
- Performance optimizations
- Power management optimizations
- Investigating low-level components
- Debugging subtle problems

Multimeter

Multimeter Overview

Masures constant electrical values:

- Voltage:
 - $R_V = \infty$
 - Can be used for power issues diagnostics
 - Helpful during board bring-up
- Current:
 - $R_A = 0$
 - **Don't measure the current in power outlets!**
 - Useful for power management improvements
 - Sometimes “10A” input jack must be used
- Resistance:
 - Resistors must be unsoldered before measurement
 - Use beeper mode to check a loop



Multimeter Demo: Suspend/Resume Current

Current Measurement

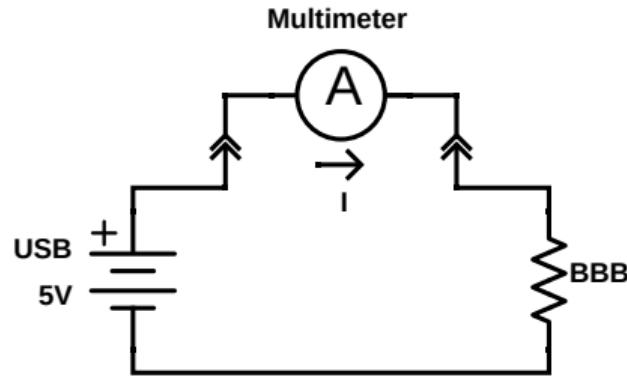


Figure 1: Ammeter Connection



Figure 2: Measurement Cable

Power can be calculated:

$$P = V \cdot I$$

Current Measurement Setup



Figure 3: Setup for BBB suspend/resume current measurement

Measuring BBB suspend/resume current (page 1/3)



Figure 4: Current draw: before suspend ($I = 310 \text{ mA}$)

Measuring BBB suspend/resume current (page 2/3)

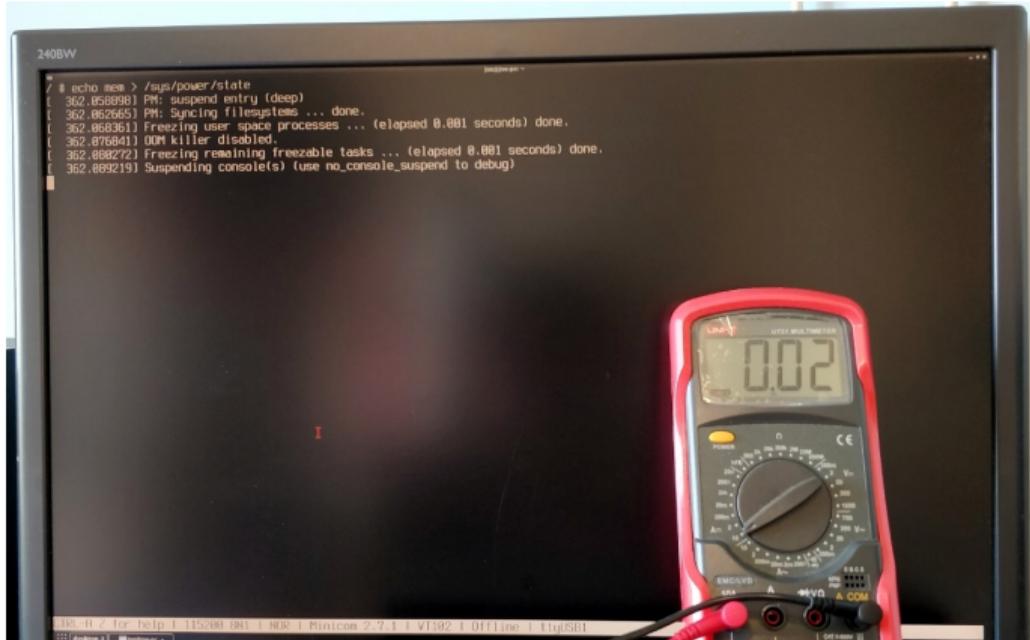


Figure 5: Current draw: during suspend ($I = 20 \text{ mA}$)

Measuring BBB suspend/resume current (page 3/3)



Figure 6: Current draw: after resume ($I = 310 \text{ mA}$)

Scope

Scope Overview

- Software vs hardware
- Parameters: frequency, data rate; + probes (capacity)
- Trigger feature
- Divisors (/1, /10)
- 2 channels (common ground!)
- Scale: time, voltage
- “Auto” button
- Measure mode

Useful:

- To debug fast-changing stuff (can't be done in software)
- To see what is actually happening on the line

Demo 1

Scope Demo #1: Measuring Delay

Button and LED Device

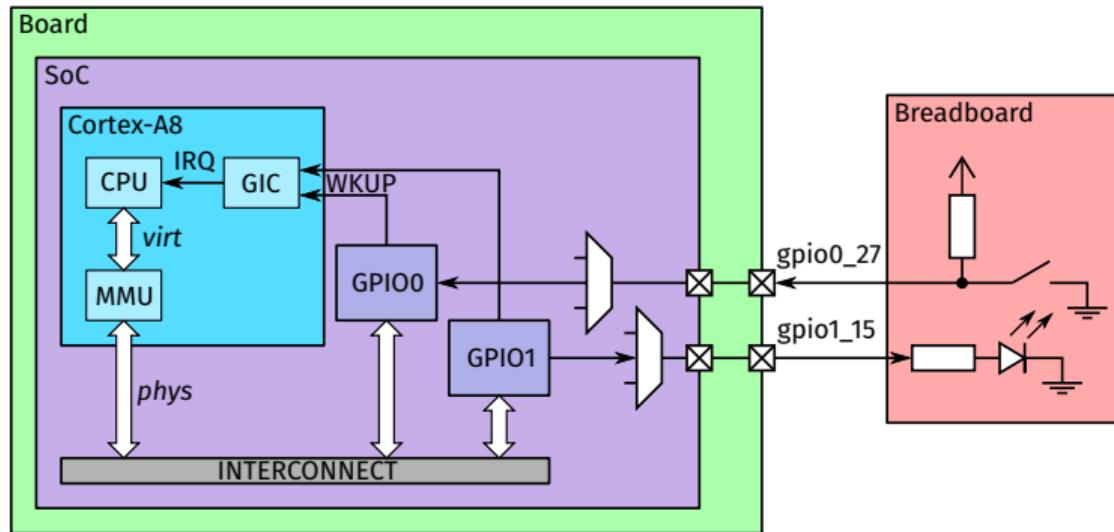


Figure 7: Button and LED Device: Functional Block Diagram

- There is a delay between button press and LED toggle events (`hw1.c`)

Scope Setup

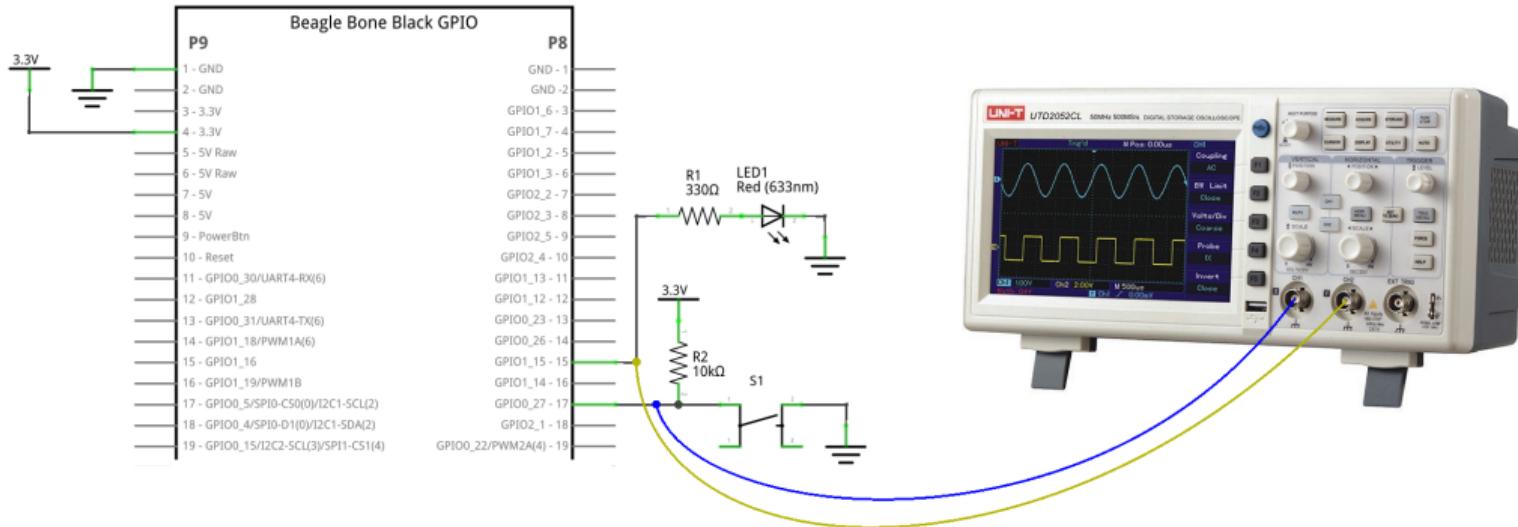


Figure 8: Setup for button/LED delay measurement

Scope Settings

Channel settings:

- CH1 (blue): Button line
- CH2 (yellow): LED line
- Coupling: DC
- Probe: 10X
- Voltage scale: 1 V/div
- Time scale: 1 ms/div

Trigger menu:

- Type: Edge; Slope: Rise,Fall
- Source: CH2 (LED line)
- Mode: Normal
- Coupling: DC
- Trigger level: 1 V (0 V ... 3.3 V)

Measuring Delay (page 1/2)

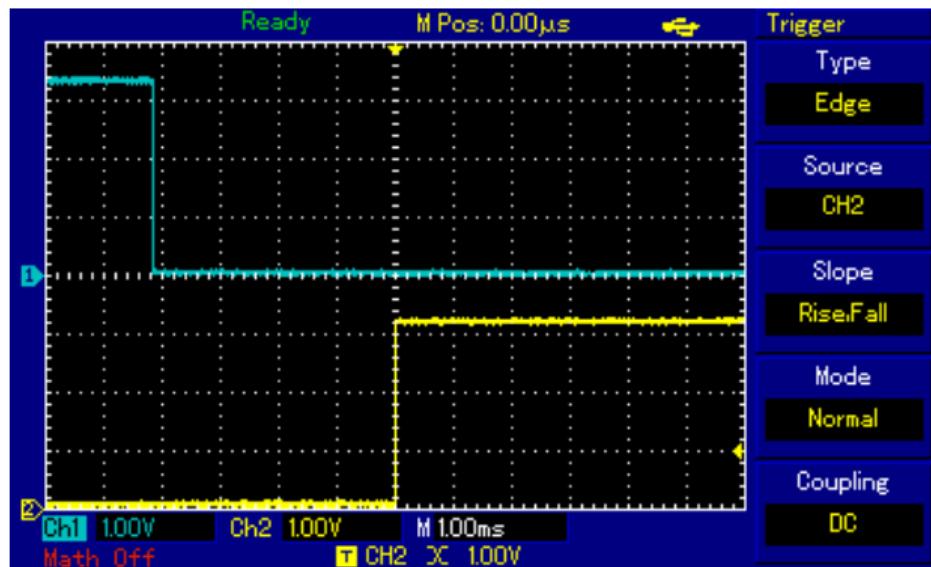


Figure 9: Scope screenshot: LED off → on

Measuring Delay (page 2/2)

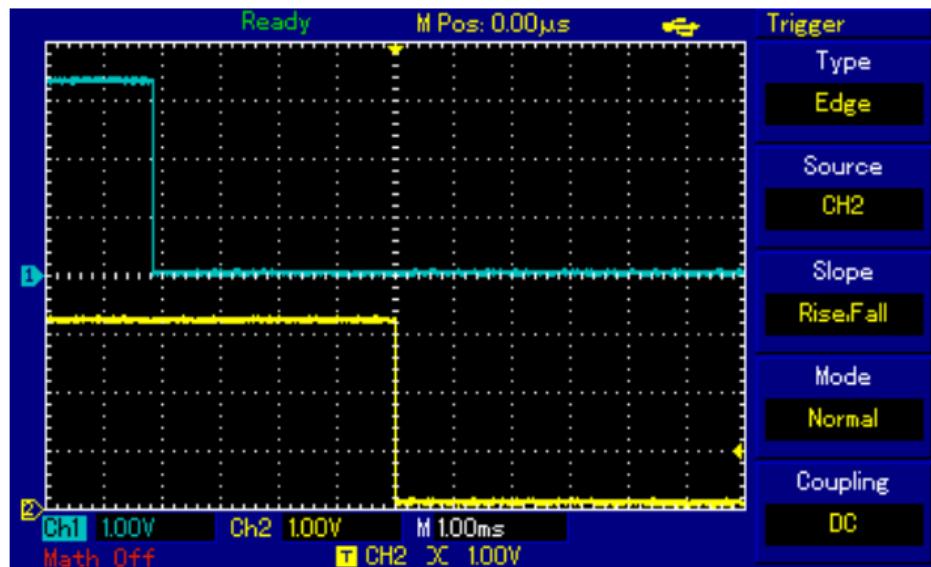


Figure 10: Scope screenshot: LED on → off

Demo 2

Scope Demo #2: Investigating Kernel Sleeps

Square Wave Module (1/3)

Listing 1: sqw.c

```
1 #include <linux/module.h>
2 #include <linux/gpio.h>
3 #include <linux/interrupt.h>
4 #include <linux/kthread.h>
5 #include <linux/delay.h>
6
7 #define AM335_GPIO(bank,line)    (32 * bank + line)
8 #define LED_GPIO                  AM335_GPIO(1, 15)
9
10 static struct task_struct *tthread;
11 static int led_val;
12
13 static int sqw_thread_func(void *data)
14 {
15     while (!kthread_should_stop()) {
16         gpio_set_value(LED_GPIO, led_val);
17         led_val ^= 0x1;
18         /* Documentation/timers/timers-howto.txt */
19         /* Don't use udelay(), we need to yield to scheduler */
20         usleep_range(20, 20); /* can be 10 us - 20 ms */
```

Square Wave Module (2/3)

```
21         }
22
23     return 0;
24 }
25
26 static int __init sqw_init(void)
27 {
28     int err;
29
30     err = gpio_request(LED_GPIO, "my_led");
31     if (err) {
32         pr_err("Unable to request LED GPIO\n");
33         return -EINVAL;
34     }
35     gpio_direction_output(LED_GPIO, 0); /* init LED value = 0 */
36
37     thread = kthread_run(sqw_thread_func, NULL, "sqw_thread");
38     if (IS_ERR(thread)) {
39         pr_err("kthread_run() failed\n");
40         err = PTR_ERR(thread);
41         return err;
42     }
43 }
```

Square Wave Module (3/3)

```
44         return 0;
45 }
46
47 static void __exit sqw_exit(void)
48 {
49     if (thread)
50         kthread_stop(thread);
51     gpio_free(LED_GPIO);
52 }
53
54 module_init(sqw_init);
55 module_exit(sqw_exit);
56
57 MODULE_AUTHOR("Sam Protsenko <joe(skb7@gmail.com)>");
58 MODULE_DESCRIPTION("Square Wave Module");
59 MODULE_LICENSE("GPL");
```

Load CPU script (1/1)

Listing 2: load_cpu.sh

```
1 #!/bin/sh
2
3 fulload() {
4     dd if=/dev/zero of=/dev/null | \
5     dd if=/dev/zero of=/dev/null | \
6     dd if=/dev/zero of=/dev/null | \
7     dd if=/dev/zero of=/dev/null &
8 }
9
10 fulload
11 read
12 killall dd
```

Stable Scope Display

To make periodic signal “stand still”, trigger must be configured:

- Type: Edge
- Source: CH2
- Slope: Rise
- Mode: Auto
- Coupling: DC
- Trigger level: put it in the wave center

Or just use “Auto” button to configure that for you.

Checking Square Wave (page 1/2)

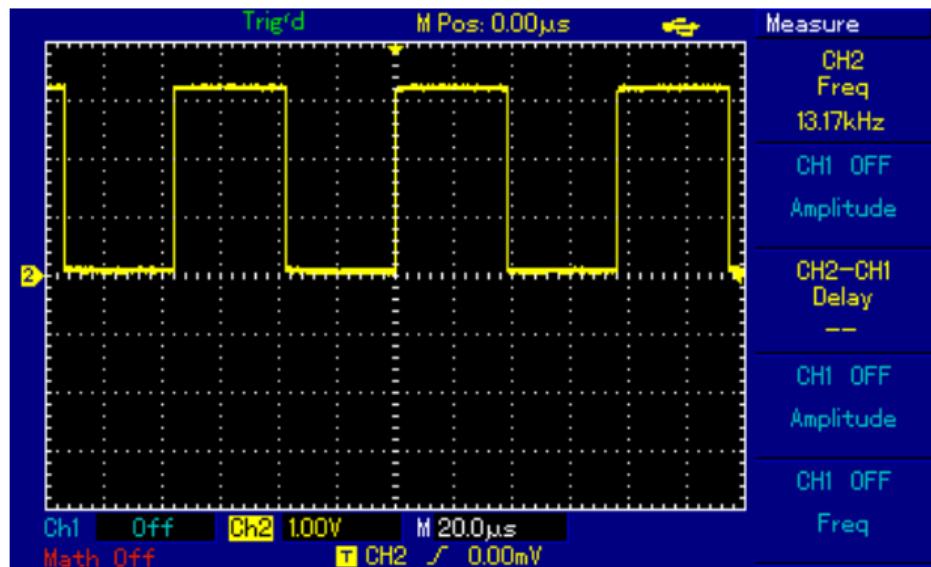


Figure 11: Scope screenshot: CPU load 0%

Checking Square Wave (page 2/2)

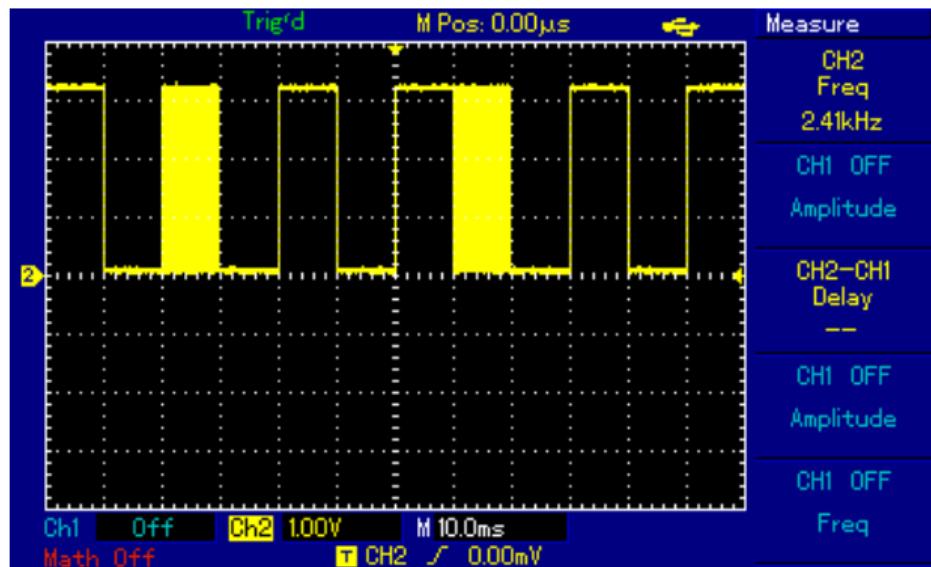


Figure 12: Scope screenshot: CPU load 100%

Demo 3

Scope Demo #3: Investigating I2C Transmission

Probes

- Use “10X” mode for regular operation:
 - $C_{in} = 20 \text{ pF} \Rightarrow T = R_{PU} \cdot C_{in} = 50 \text{ k}\Omega \cdot 20 \text{ pF} = 1 \mu\text{s}$
- Use “1X” mode for low voltage signals:
 - $C_{in} = 100 \text{ pF} \Rightarrow T = R_{PU} \cdot C_{in} = 50 \text{ k}\Omega \cdot 100 \text{ pF} = 5 \mu\text{s}$

$$T_{SDC} = \frac{1}{100 \text{ kHz}} = 10 \mu\text{s}$$

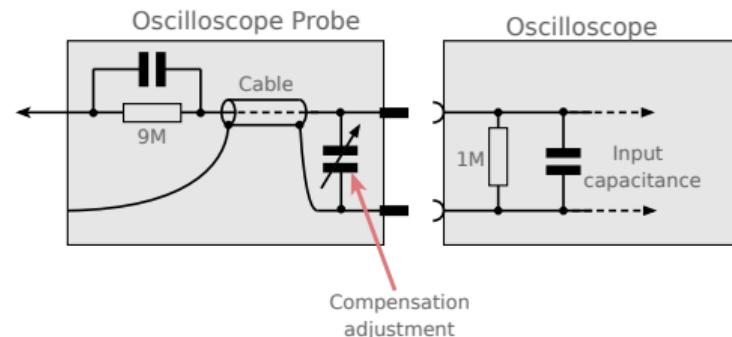


Figure 13: Oscilloscope probe (X10) circuit

Checking I2C Transmission (page 1/2)

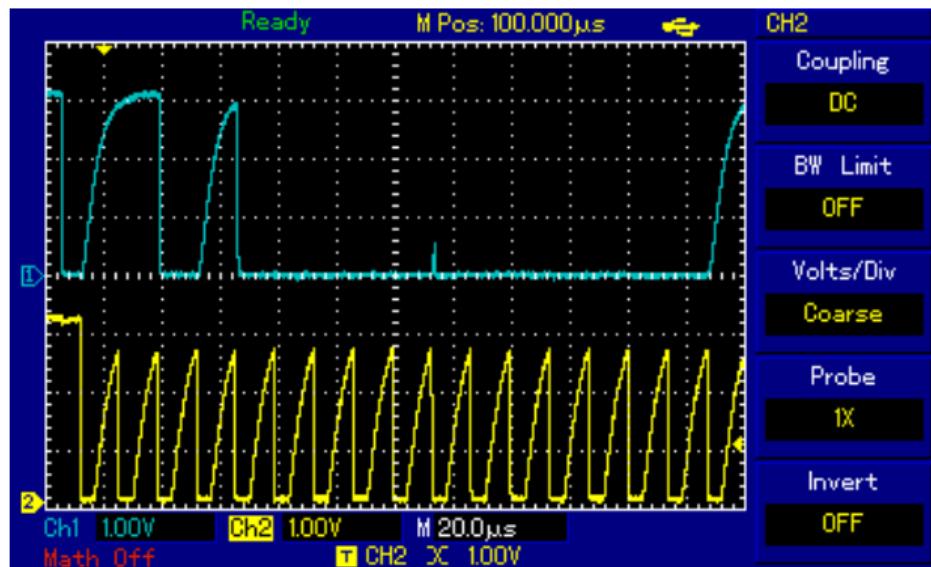


Figure 14: Scope screenshot: I2C Transmission using X1 probe

Checking I2C Transmission (page 2/2)

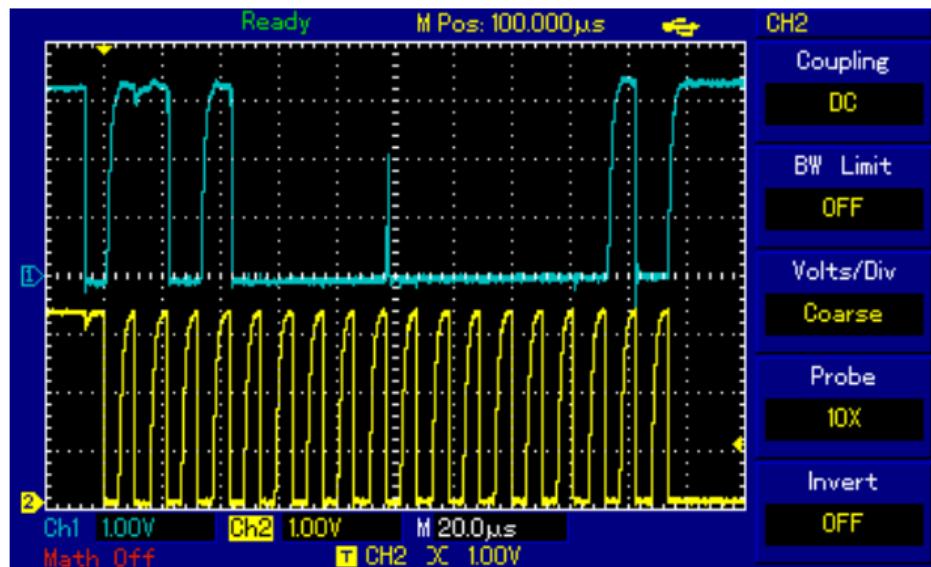


Figure 15: Scope screenshot: I2C Transmission using X10 probe

Logic Analyzer

Logic Analyzer Overview

- Catches digital levels
- Stores collected data to internal (hardware) buffer
- App can parse protocols (I2C, UART)
- Parameters: max data rate (freq), ports count, protocols support
- Some specialized LAs exist (e.g. USB)
- **Useful:**
 - For problem isolation / root-causing
 - For reverse engineering (“sniffing”)

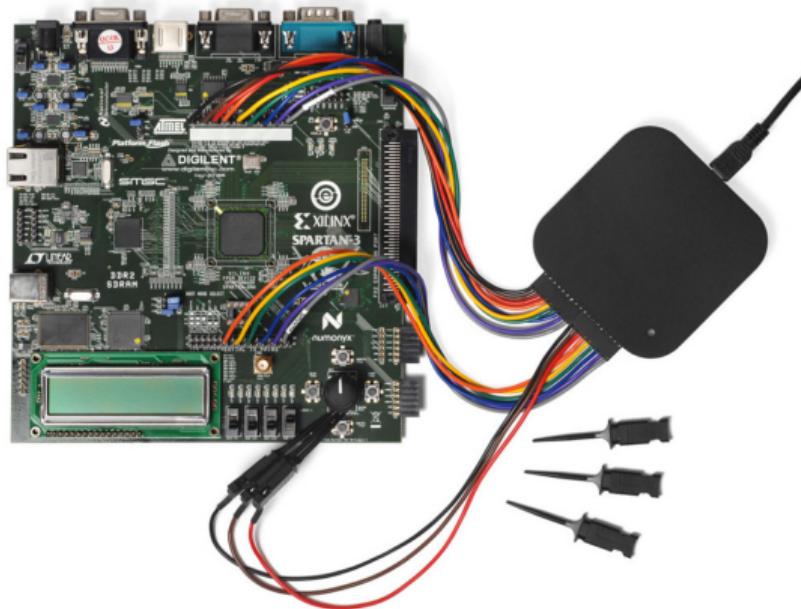


Figure 16: Saleae 16 Logic Analyzer

Demo 1

LA Demo #1: I2C (SDA, SCL)

I2C data exchange with RTC (page 1/3)

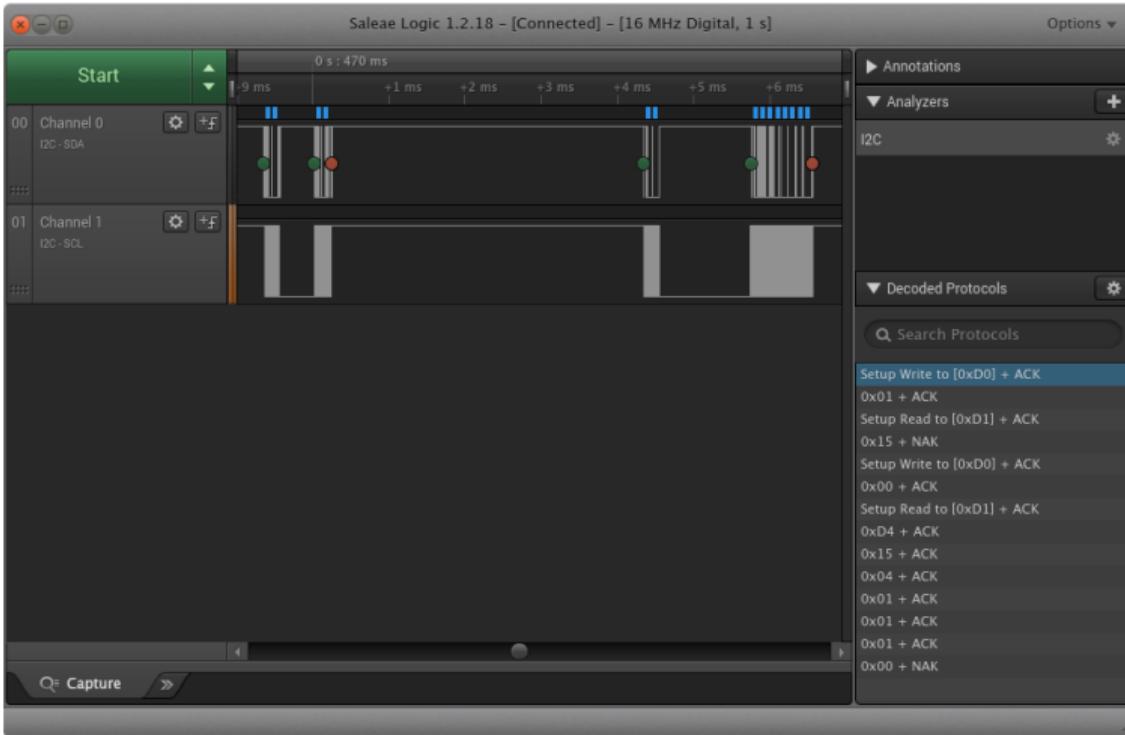


Figure 17: I2C data exchange with DS1307 sniffed by Logic Analyzer

I2C data exchange with RTC (page 2/3)

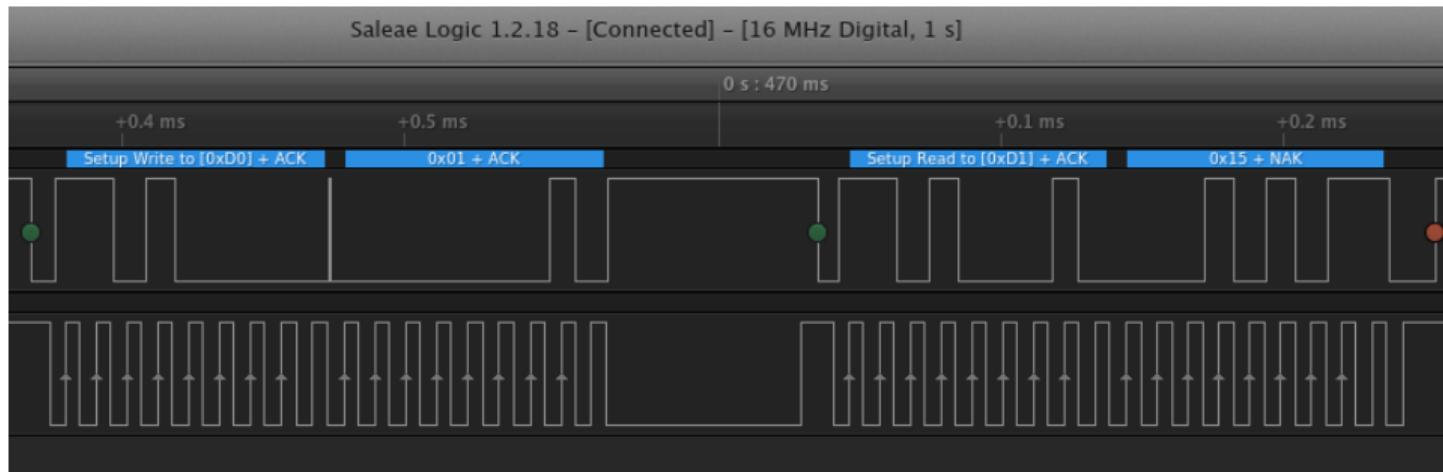


Figure 18: I₂C read from 0x01 register

```
[15347.357045] ### my_rtc_probe(): enter  
[15347.362433] ### read data = 0x15
```

I2C data exchange with RTC (page 3/3)

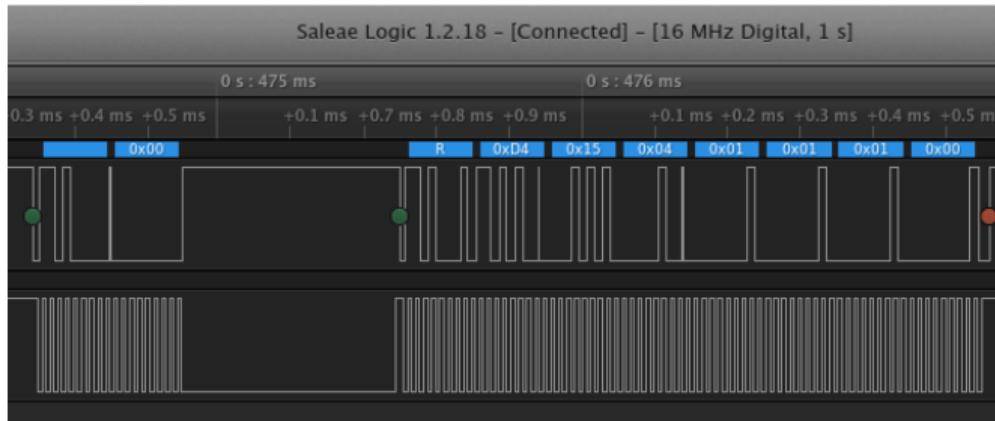


Figure 19: I2C bulk read (starting from 0x00 register)

```
[15347.368436] ds1307x 2-0068: reg 0x0  = 0xd4
[15347.372824] ds1307x 2-0068: reg 0x1  = 0x15
[15347.377113] ds1307x 2-0068: reg 0x2  = 0x4
[15347.381395] ds1307x 2-0068: reg 0x3  = 0x1
[15347.385593] ds1307x 2-0068: reg 0x4  = 0x1
[15347.389808] ds1307x 2-0068: reg 0x5  = 0x1
[15347.394005] ds1307x 2-0068: reg 0x6  = 0x0
```

Demo 2

LA Demo #2: UART (Tx, Rx)

LA UART Setup

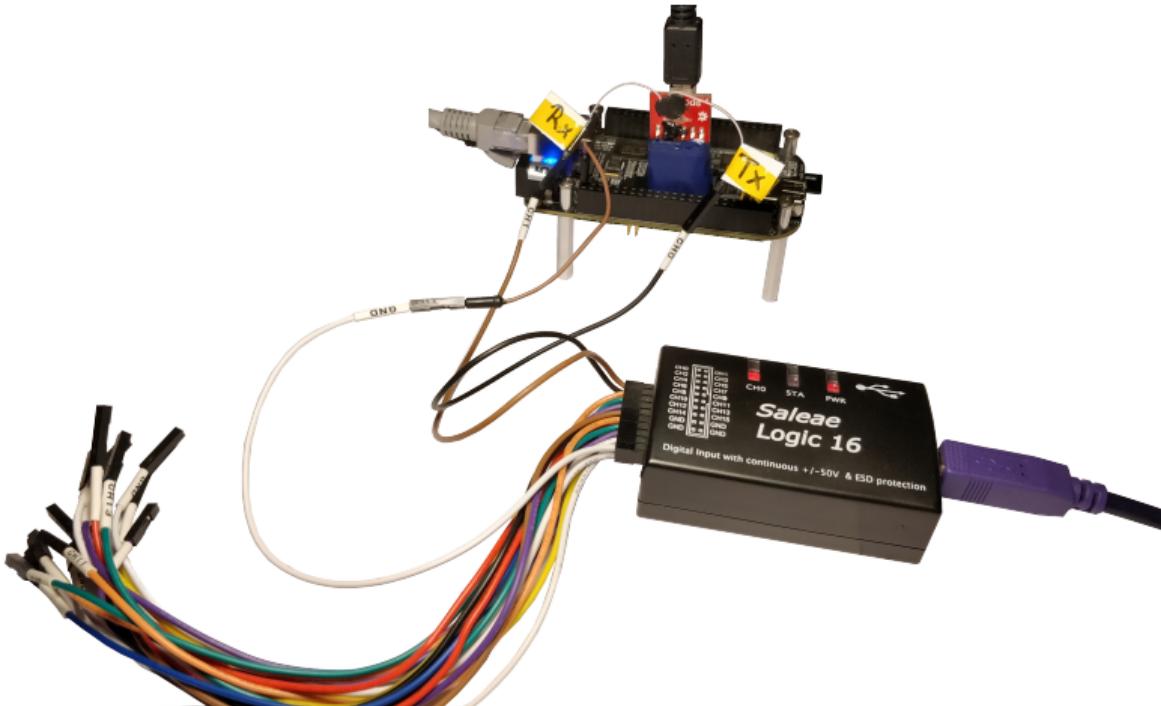


Figure 20: Setup for tracing UART with Logic Analyzer

UART data exchange with serial console (page 1/3)

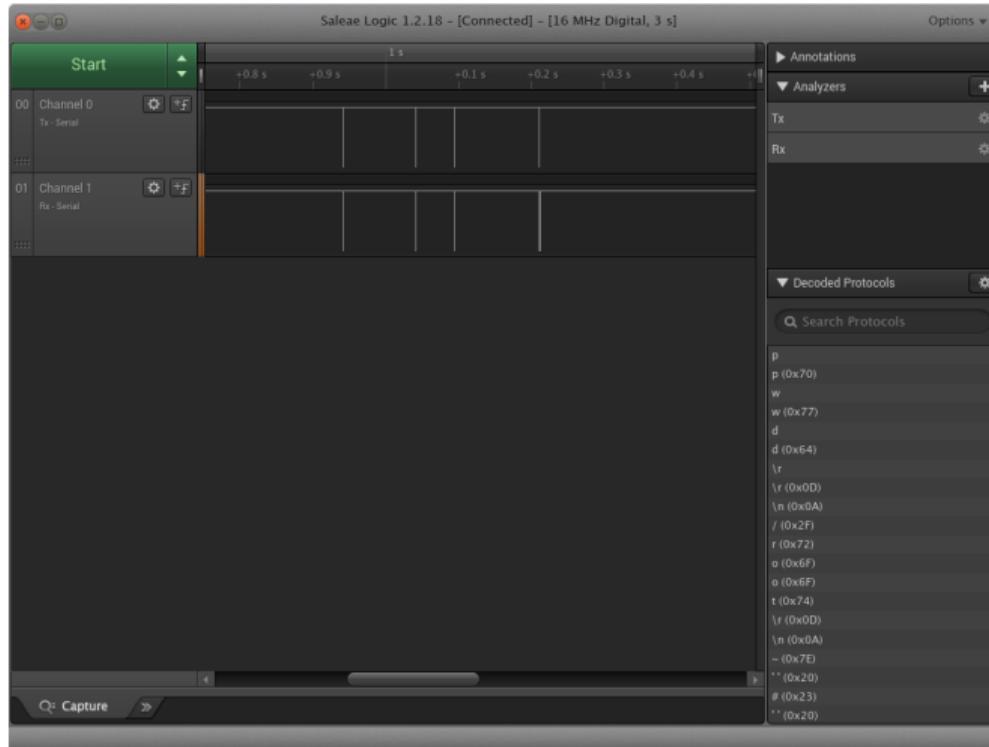


Figure 21: UART data exchange with FTDI sniffed by Logic Analyzer

UART data exchange with serial console (page 2/3)

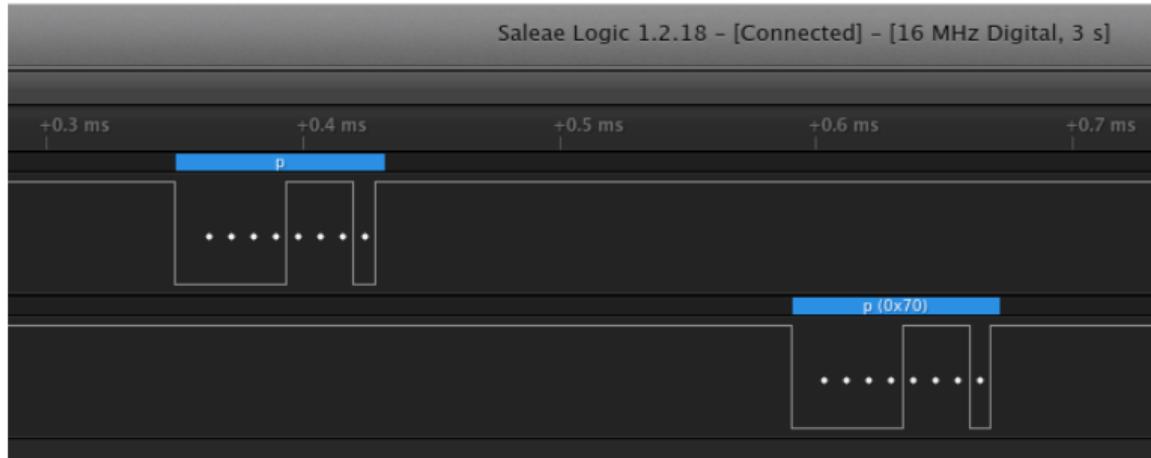


Figure 22: Type in ‘p’ character and get it back in minicom

UART data exchange with serial console (page 3/3)

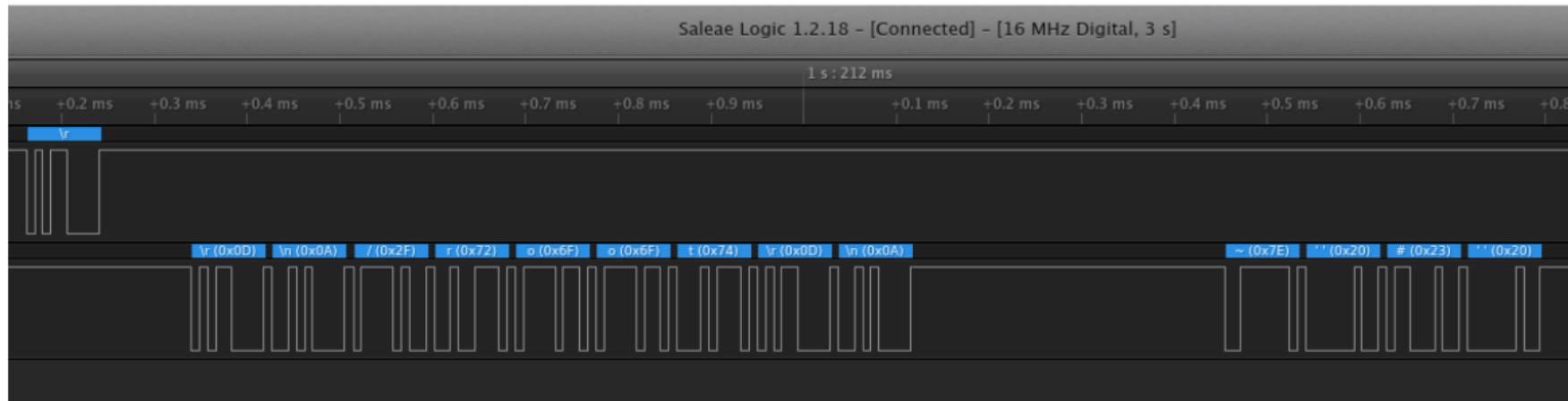


Figure 23: `pwd` command response

Take Five

JTAG

JTAG Intro

Allows one to debug program running on board just like user-space application with GDB:

- Breakpoints
- Read/write registers
- Stop/run CPU
- Read/write memory
- Load images
- Examine stack
- Can debug U-Boot, kernel, user-space apps/libs, even ROM-code...

JTAG Bus

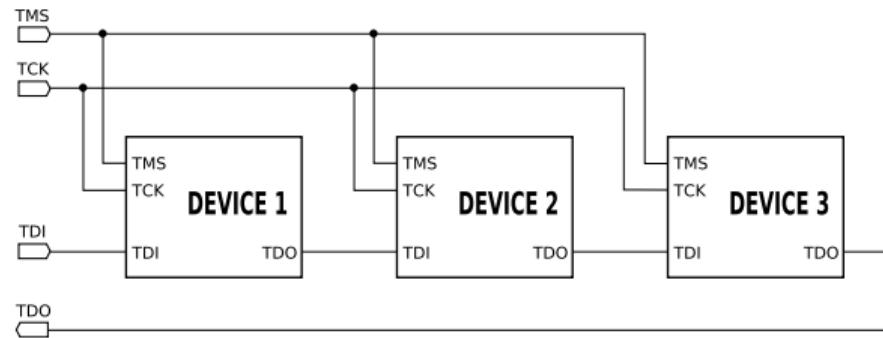


Figure 24: Daisy-chained JTAG

- JTAG is a serial bus (IEEE1149.1 standard)
- AM335x implements JTAG (has JTAG pins)
- PC doesn't have JTAG controller, so **JTAG adapter** must be used

JTAG Adapters

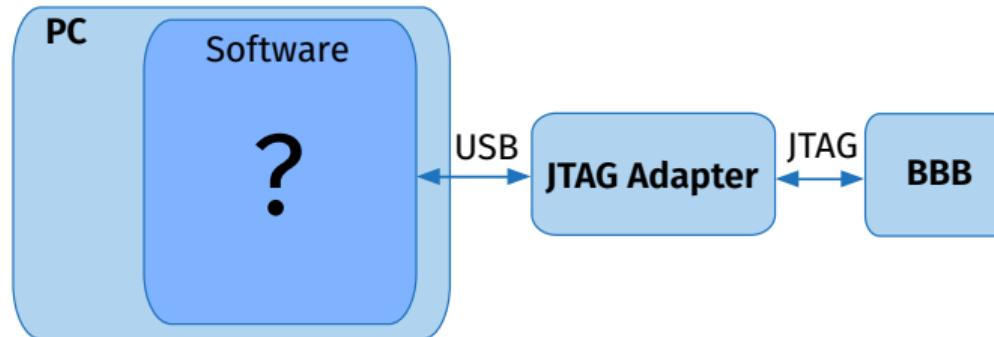


Figure 25: Connecting BBB JTAG to PC

Adapters require some software. Some examples for BBB:

- Flyswatter 2 (FT2232H based, MPSSE): OpenOCD
- XDS100v2: Proprietary software

JTAG support in AM335x

AM335x

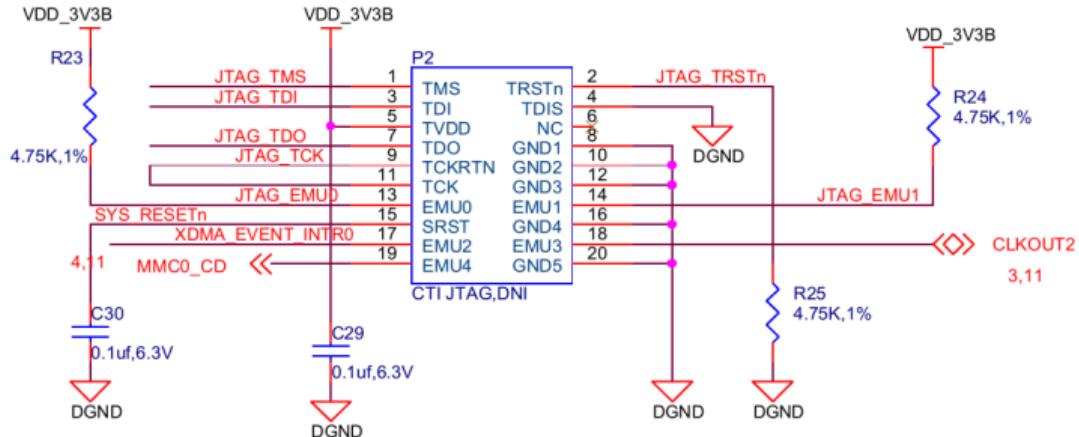
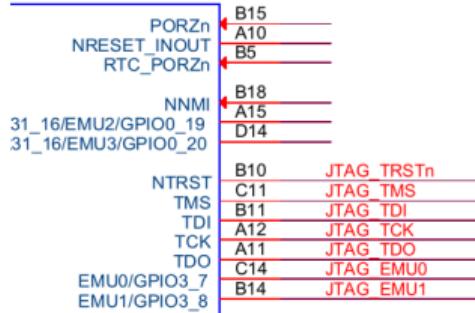


Figure 26: JTAG connector in BBB

See TRM for details on debug interface implementation in AM335x.

Flyswatter2 Overview

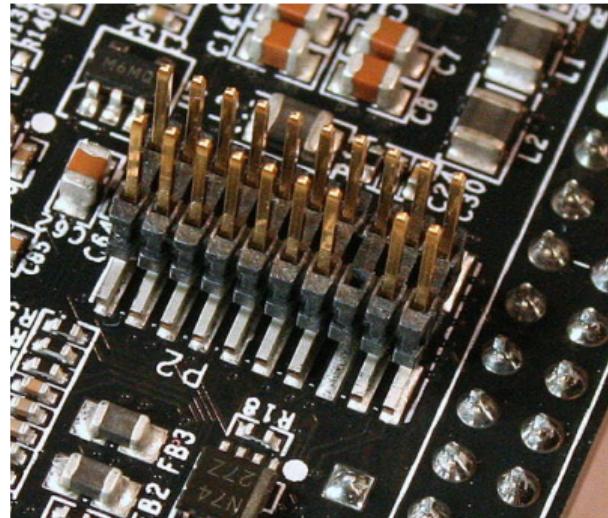


Figure 27: BBB JTAG Connector

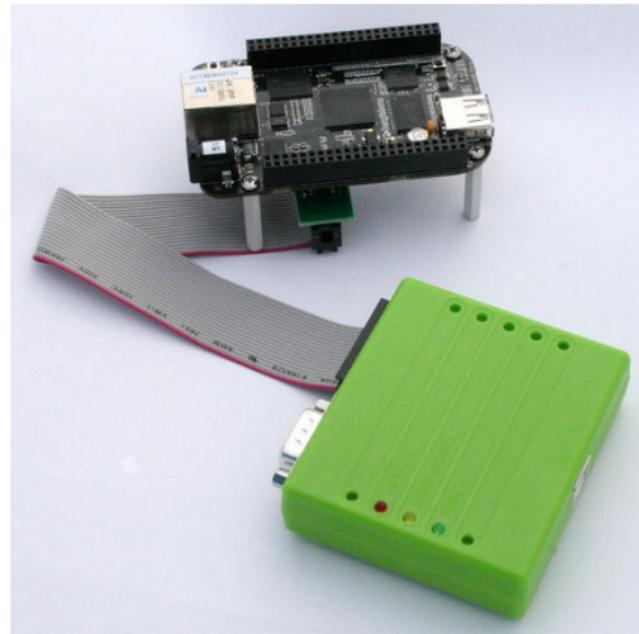


Figure 28: BBB and Flyswatter2

OpenOCD Overview

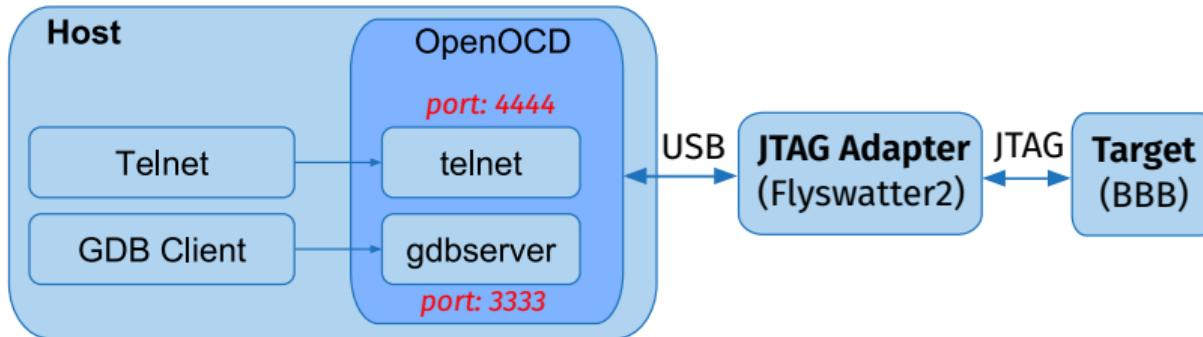


Figure 29: Debugging BBB with OpenOCD

OpenOCD creates servers for:

- Telnet (port 4444 on localhost)
- GDB (port 3333 on localhost)

Once OpenOCD is running, you can run:

```
1 $ telnet localhost 4444
2 or
3 $ arm-eabi-gdb vmlinux
```

Kernel Preparations

- Enable `CONFIG_DEBUG_INFO` (the same as `-g`)
- Disable `CONFIG_WATCHDOG` (just in case)
- Make sure JTAG clock (DEBUGSS on BBB) is alive in kernel (see next slide)
- Rebuild, add `zImage` to rootfs, flash to BBB

Kernel Preparations (cont'd)

arch/arm/mach-omap2/omap_hwmod_33xx_data.c:

```
1 static struct omap_hwmod am33xx_debugss_hwmod = {
2     .name          = "debugss",
3     .class         = &am33xx_debugss_hwmod_class,
4     .clkdm_name   = "l3_aon_clkdm",
5 +    .flags         = (HWMOD_INIT_NO_IDLE | HWMOD_INIT_NO_RESET),
6     .main_clk     = "trace_clk_div_ck",
7     .prcm          = {
```

Without this patch you'll see STICKY BIT errors (in OpenOCD terminal) when kernel starts running.

OpenOCD Preparations

Install OpenOCD (my version is 0.10.0):

```
1 $ sudo apt update  
2 $ sudo apt install openocd
```

- Figure out correct OpenOCD interface and target config files:
 - `interface/ftdi/flyswatter2.cfg`
 - `target/am335x.cfg`
- ...but those files from upstream OpenOCD won't work
- Use Flyswatter2 config from TinCanTools site (see next page)

OpenOCD Working Script for Flyswatter2 (1/5)

Listing 3: ti_beaglebone_with_fs2_mod.cfg

```
1 # AM335x Beaglebone, for use with the TinCanTools Flyswatter2
2 # http://beagleboard.org/bone
3 # http://www.tincantools.com
4
5 # The JTAG interface is built directly on the board.
6 interface ftdi
7   ftdi_device_desc "Flyswatter2"
8   ftdi_vid_pid 0x0403 0x6010
9
10  ftdi_layout_init 0x0538 0x057b
11  ftdi_layout_signal LED -ndata 0x0400
12  ftdi_layout_signal nTRST -data 0x0010
13  ftdi_layout_signal nSRST -data 0x0020 -noe 0x0100
14
15  adapter_khz 16000
16
17
18 if { [info exists CHIPNAME] } {
19   set _CHIPNAME $CHIPNAME
20 } else {
```

OpenOCD Working Script for Flyswatter2 (2/5)

```
21     set _CHIPNAME am335x
22 }
23
24 # This chip contains an IcePick-D JTAG router. The IcePick-C configuration is almost
25 # compatible, but it doesn't work. For now, we will just embed the IcePick-D
26 # routines here.
27 proc icepick_d_tapenable {jrc port} {
28     # select router
29     irscan $jrc 7 -endstate IRPAUSE
30     drscan $jrc 8 0x89 -endstate DRPAUSE
31
32     # set ip control
33     irscan $jrc 2 -endstate IRPAUSE
34     drscan $jrc 32 [expr 0xa0002108 + ($port << 24)] -endstate DRPAUSE
35
36     # for icepick_D
37     irscan $jrc 2 -endstate IRPAUSE
38     drscan $jrc 32 0xe0002008 -endstate DRPAUSE
39
40     irscan $jrc 0x3F -endstate RUN/IDLE
41     runtest 10
42 }
43
```

OpenOCD Working Script for Flyswatter2 (3/5)

```
44 #
45 # M3 DAP
46 #
47 if { [info exists M3_DAP_TAPID] } {
48     set _M3_DAP_TAPID $M3_DAP_TAPID
49 } else {
50     set _M3_DAP_TAPID 0x4b6b902f
51 }
52 jtag newtap $_CHIPNAME m3_dap -irlen 4 -ircapture 0x1 -irmask 0xf -expected-id $_M3_DAP_TAPID -disable
53 jtag configure $_CHIPNAME.m3_dap -event tap-enable "icepick_d_tapenable $_CHIPNAME.jrc 11"
54
55 #
56 # Main DAP
57 #
58 if { [info exists DAP_TAPID] } {
59     set _DAP_TAPID $DAP_TAPID
60 } else {
61     set _DAP_TAPID 0x4b6b902f
62 }
63 jtag newtap $_CHIPNAME dap -irlen 4 -ircapture 0x1 -irmask 0xf -expected-id $_DAP_TAPID -disable
64 jtag configure $_CHIPNAME.dap -event tap-enable "icepick_d_tapenable $_CHIPNAME.jrc 12"
65
66 #
```

OpenOCD Working Script for Flyswatter2 (4/5)

```
67 # ICEpick-D (JTAG route controller)
68 #
69 if { [info exists JRC_TAPID] } {
70     set _JRC_TAPID $JRC_TAPID
71 } else {
72     set _JRC_TAPID 0x0b94402f
73 }
74 jtag newtap $_CHIPNAME jrc -irlen 6 -ircapture 0x1 -irmask 0x3f -expected-id $_JRC_TAPID -ignore-version
75 jtag configure $_CHIPNAME.jrc -event setup "jtag tapenable $_CHIPNAME.dap"
76 # some TCK cycles are required to activate the DEBUG power domain
77 jtag configure $_CHIPNAME.jrc -event post-reset "runtest 100"
78
79 #
80 # Cortex A8 target
81 #
82 set _TARGETNAME $_CHIPNAME.cpu
83 target create $_TARGETNAME cortex_a8 -chain-position $_CHIPNAME.dap -dbgbase 0x80001000
84
85 # SRAM: 64K at 0x4030.0000; use the first 16K
86 $_TARGETNAME configure -work-area-phys 0x40300000 -work-area-size 0x4000
87
88 $_TARGETNAME configure -event gdb-attach {
89     cortex_a dbinit
```

OpenOCD Working Script for Flyswatter2 (5/5)

```
90      halt
91 }
92
93
94 reset_config trst_and_srst
```

Run OpenOCD

1. Connect Flyswatter2 to BBB using adapter kit
2. Connect Flyswatter2 to PC via USB
3. Connect BBB to PC via USB (power);
“TARGET RESET” LED on Flyswatter is glowing, CPU is in reset state
4. Run OpenOCD command:

```
$ openocd -f ./ti_beaglebone_with_fs2_mod.cfg -c "init" -c "reset init"
```

We will use this terminal to track OpenOCD log.

Correct OpenOCD Command Output

```
adapter speed: 16000 kHz
Info : auto-selecting first available session transport "jtag". To override use 'transport select <transport>'.
Warn : target name is deprecated use: 'cortex_a'
trst_and_srst separate srst_gates_jtag trst_push_pull srst_open_drain connect_deassert_srst
Info : ftdi: if you experience problems at higher adapter clocks, try the command "ftdi_tdo_sample_edge ←
      falling"
Info : clock speed 16000 kHz

Info : JTAG tap: am335x.jrc tap/device found: 0x2b94402f (mfg: 0x017 (Texas Instruments), part: 0xb944, ver: 0x2)
Info : JTAG tap: am335x.dap enabled
Info : DAP transaction stalled (WAIT) - slowing down
Info : DAP transaction stalled (WAIT) - slowing down
Info : DAP transaction stalled (WAIT) - slowing down
Error: target->coreid 0 powered down!

Info : JTAG tap: am335x.jrc tap/device found: 0x2b94402f (mfg: 0x017 (Texas Instruments), part: 0xb944, ver: 0x2)
Info : JTAG tap: am335x.dap enabled
Info : DAP transaction stalled (WAIT) - slowing down
Info : DAP transaction stalled (WAIT) - slowing down
Info : DAP transaction stalled (WAIT) - slowing down
Info : am335x.cpu: hardware has 6 breakpoints, 2 watchpoints
```

OpenOCD over GDB (page 1)

Let's start debug session in GDB:

```
$ arm-eabi-gdb vmlinux  
  
(gdb) target remote localhost:3333  
(gdb) monitor cortex_a dacrfixup on  
(gdb) continue
```

What we did here:

1. Connect to OpenOCD's GDB server, using Linux kernel symbols
2. Using OpenOCD **cortex_a** command, do a workaround for software breakpoints (Linux kernel maps **.text** read-only, and the debugger cannot write a breakpoint due to that)
3. Continue CPU execution (as it was in reset state initially); we use GDB commands for debugging (not **monitor resume**, etc)

OpenOCD over GDB (page 2)

Set a breakpoint and trigger it:

```
^C  
(gdb) break do_sys_open  
(gdb) continue  
  
/ # cat /proc/cmdline
```

1. Stop CPU execution by pressing **Ctrl-C**
2. Set breakpoint for **do_sys_open()** kernel function (it's a handler for **open()** syscall. Another interesting functions would be **load_module()**, **start_kernel()**, etc)
3. Continue CPU execution
4. Print **/proc/cmdline** file, so that **open()** is triggered
5. Now we are in breakpoint, CPU is halted

OpenOCD over GDB (page 3)

Investigate code in breakpoint:

```
(gdb) monitor cortex_a maskisr on
(gdb) continue
(gdb) ...
(gdb) bt, list, info registers, disas, step, print, ...
(gdb) monitor cortex_a maskisr off
(gdb) continue
```

1. Don't process interrupts when stepping (otherwise we won't be able to perform `continue`)
2. Wait for `open("/proc/cmdline")`
3. Investigate caught code
4. Once we are done, enable interrupts processing and continue normal execution

OpenOCD Telnet Commands

In Telnet, you can use regular OpenOCD monitor commands:

- help
- reset
- halt
- resume
- reg
- bp <address> <len> [hw]
- step [address]
- mdw, mww

See **OpenOCD User's Guide** for details.

Proprietary JTAG: XDS100v2 via CodeComposerStudio

15_0 (Suspended)
589 0x08000EDC

oot] at 0x08000528
, int() at omap24xx_i2c.c:404 0x08015EC4
:] at 0xEE070F94

Name	Value
R0	0x00000000
R1	0x00000058
R2	0x00002300
R3	0x00000000
R4	0x0803DBB4
R5	0x0803DA54

Disassembly

Enter location here

```
582     val = optimize_vcore_voltage(&vcores->core);
08000eb4: E1A01000 MOV      R1, R0
583     do_scale_vcore(vcores->core.addr, val, vcores->core.pmic);
08000eb8: E5940018 LDR      R0, [R4, #24]
08000ebc: EBFFFFCF BL      do_scale_vcore
585     val = optimize_vcore_voltage(&vcores->mpu);
08000ec0: E1A00004 MOV      R0, R4
08000ec4: EBFFFF1D BL      optimize_vcore_voltage
586     do_scale_vcore(vcores->mpu.addr, val, vcores->mpu.pmic);
08000ec8: E5942010 LDR      R2, [R4, #16]
585     val = optimize_vcore_voltage(&vcores->mpu);
08000ecc: E1A01000 MOV      R1, R0
586     do_scale_vcore(vcores->mpu.addr, val, vcores->mpu.pmic);
08000ed0: E5940004 LDR      R0, [R4, #4]
08000ed4: EBFFFFC9 BL      do_scale_vcore
589     abb_setup((*ctrl)->control_std_fuse_opp_vdd_mpu_2,
08000ed8: E59F30E0 LDR      R3, 0x8000FC0
◆ 08000edc: E3A00080 MOV      R0, #128
◆ 08000ee0: E5933000 LDR      R3, [R3]
08000ee4: E5932000 LDR      R2, [R3]
591             (*prcm)->prm_abbldo_mpu_setup,
08000ee8: E5953000 LDR      R3, [R5]
08000eec: E5933000 LDR      R3, [R3]
```

Error: dereferencing NULL

Demo

JTAG Demo #1: Flyswatter2

Demo

JTAG Demo #2: XDS560v2

JTAG References

- <https://www.tincantools.com/flyswatter2-beaglebone-black-how-to/>
- <https://e2e.ti.com/support/embedded/linux/f/354/t/363421>
- <https://www.tincantools.com/beaglebone-black-eclipse-gdb/>
- <https://devel.rtems.org/wiki/Debugging/OpenOCD/BeagleBoneBlack>
- https://elinux.org/Debugging_The_Linux_Kernel_Using_Gdb
- <https://github.com/n-aizu/freertos-multicore/wiki/Debugging-with-openocd>
- <http://openocd.org/doc/html/GDB-and-OpenOCD.html>
- <http://openocd.org/doc/html/General-Commands.html>
- <https://habr.com/post/206036/>

Thank you!