

Linux Kernel Training: Lecture 2

Booting the BeagleBone Black

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GlobalLogic

Agenda

1. U-Boot Basics
2. IDE Considerations
3. Workshop: Bringing up the BBB

U-Boot Basics

Embedded Board

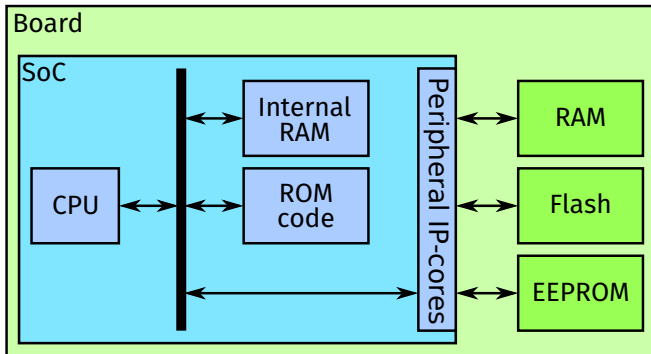


Figure 1: Simplified view of Embedded board

What is Bootloader?

ROM code has limitations:

- Doesn't know about RAM
- Doesn't know board name
- Not flexible enough



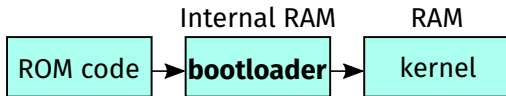
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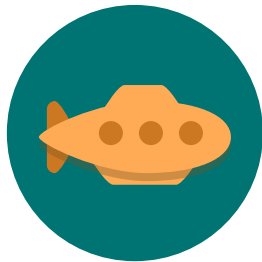
Bootloader to the rescue:

- Resides in flash (can be upgraded)
- Able to configure RAM
- Knows boot procedure
- Convenient features



Why U-Boot?

- Bootloader for Embedded boards
 - Popular for Android devices
 - Adoption in automotive
- GPLv2
- 13 architectures (consider ARM)
- ~300 boards
- Device drivers, lib routines
- Resembles Linux kernel a lot
- Scripting, extensive command set



U-Boot Features

- Boots from various sources
- Boots various OSs
- Monitor (U-Boot shell)
 - Commands
 - Environment
- 2 stage boot (SPL + U-Boot)
- “Falcon” mode (SPL only)

Two Stage Boot

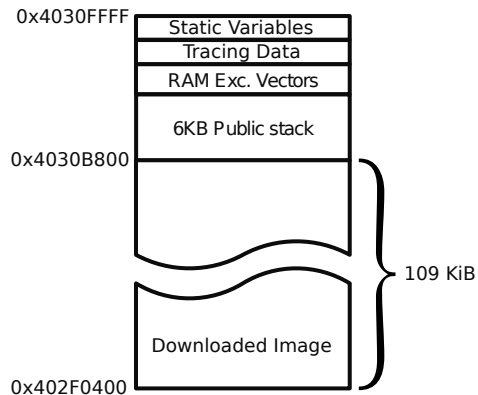
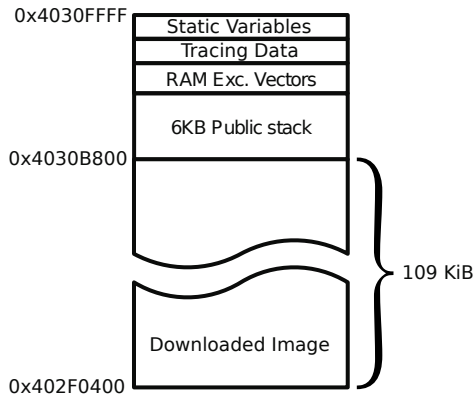


Figure 2: SRAM layout (from AM335x TRM)

Two Stage Boot



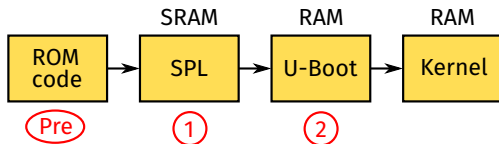
But bootloader is bigger!

For **BEAGLEBONE BLACK**, `u-boot.img` is 391 KiB.

Figure 2: SRAM layout (from AM335x TRM)

Two Stage Boot (cont'd)

Let's add an intermediate stage (SPL):

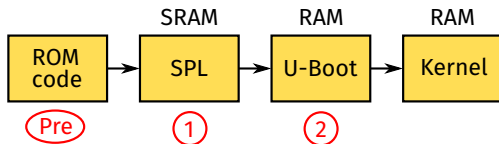


For **BEAGLEBONE BLACK**:

Stage	Size
SPL	75 KiB
U-Boot	391 KiB

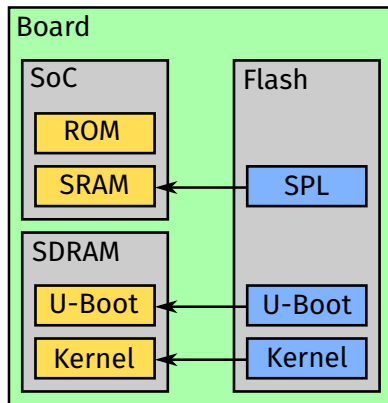
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Boot Sources

ROM code boot source is usually selected:

- Via **SYSBOOT** DIP switch
- By hard-wiring SYSBOOT lines (pull-up/pull-down)
- Using some USER button
- By inserting SD card (“Card Detect” pin)

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- Using some USER button
- By inserting SD card (“Card Detect” pin)

U-Boot can boot kernel from:

- Flash devices (eMMC, SD card)
- Network boot (TFTP, NFS)
- Peripheral boot (USB, serial console)

Flashing Methods

Most commonly used flashing methods:

- Via USB:
 - fastboot (Android)
 - DFU
- Via SD card

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To unbrick the board (bad U-Boot on eMMC):

- Boot from SD card and re-flash
- Use JTAG
- USB peripheral boot

U-Boot Shell

- U-Boot is a “monitor” program
- Command line interface
- A set of commands is implemented
- Resembles Bash (has scripting capabilities)
- Press “Space” to get into U-Boot shell

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Most commonly used commands:

```
bdinfo, bootm, bootz, crc32, dfu, dhcp, env,  
fastboot, fatload, fdt, gpt, i2c, md, mmc, mw,  
part, ping, reset, run, tftpboot, version, ...
```

U-Boot Environment

- Keeps all U-Boot shell variables
- Just a set of strings in **key=value** format

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Set default environment:

```
=> env default -f -a
```

```
=> env save
```

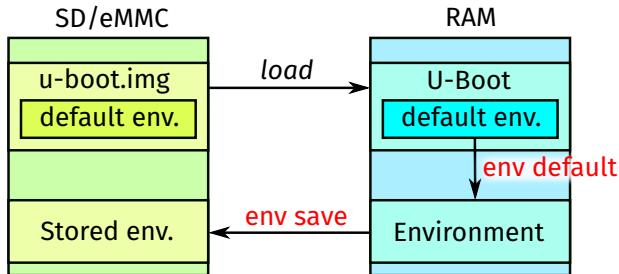
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Set default environment:

```
=> env default -f -a
```

```
=> env save
```



```
=> env print
```

```
board_name=A335BNLT
```

```
board_rev=0A5A
```

```
board_serial=1813BBBK4642
```

```
bootargs=
```

```
bootcmd=if test ${boot_fit} -eq 1; then ...
```

```
fdtfile=am335x-boneblack.dtb
```

```
findfdt=if test $board_name = A335BONE; then ...
```

```
partitions=uuid_disk=${uuid_gpt_disk}; ...
```

Use-case: Format eMMC

Using **gpt** command:

```
=> gpt write mmc 1 $partitions
```

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or Android way:

```
=> fastboot 0
```

```
$ fastboot oem format
```


Use-case: Format eMMC

Using **gpt** command:

```
=> gpt write mmc 1 $partitions
```

or Android way:

```
=> fastboot 0  
$ fastboot oem format
```

- Consider **\$partitions** variable...
- Check with **part list mmc 1**

Use-case: Flashing eMMC

Via DFU:

```
=> setenv dfu_alt_info $dfu_alt_info_emmc  
=> dfu 0 mmc 1  
$ dfu-util -D MLO -a MLO.raw
```

Use-case: Flashing eMMC

Via DFU:

```
=> setenv dfu_alt_info $dfu_alt_info_emmc  
=> dfu 0 mmc 1  
$ dfu-util -D MLO -a MLO.raw
```

Via fastboot (Android way):

```
=> fastboot 0  
$ fastboot flash rootfs rootfs.img
```

Use-case: Boot Linux

```
=> setenv mmcdev 1  
=> setenv bootpart 1:2  
=> run findfdt  
=> run mmcboot
```

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```
=> setenv mmcdev 1
=> setenv bootpart 1:2
=> run findfdt
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```

mmcboot=

```
mmc dev ${mmcdev}; mmc rescan;
load mmc ${bootpart} ${loadaddr} /boot/zImage
load mmc ${bootpart} ${fdtaddr} /boot/${fdtfile}
setenv bootargs console=tty00,115200n8 root=... rw ...
bootz ${loadaddr} - ${fdtaddr}
```

Boot Sequence

`do_bootm_linux()` calls:

- 1:
 - `boot_prep_linux()`
 - `boot_setup_linux()`
 - `image_setup_libfdt()`
 - Populates `/chosen` node with `bootargs`, `initrd-start`, etc.
- 2:
 - `boot_jump_linux()`
 - `kernel_entry(0, machid, r2)`
 - FDT blob address is passed to kernel via `r2`

Boot Methods Table

Boot method	Description
SD card boot	<ul style="list-style-type: none">- Unbrick the board- Doesn't touch eMMC
eMMC boot	<ul style="list-style-type: none">- Regular boot- Fastest and easiest for user
TFTP boot	<ul style="list-style-type: none">- Network boot- Doesn't touch eMMC- Volatile RootFS (RAM disk)
NFS boot	<ul style="list-style-type: none">- Network boot- Transparent RootFS (from host)- Useful for kernel development

IDE Considerations

IDE for Kernel Development: Vim

Pros:

- Very fast
- Available everywhere
- A lot of kernel hackers using it

Cons:

- Learning curve rather steep
- Some functionality is missing
- Requires some configuration

Indexing example (simplified):

```
make ARCH=arm SUBARCH=omap2 cscope tags
```

Details: <https://stackoverflow.com/a/33682137/3866447>

IDE for Kernel Development: Vim (cont'd)

```
vim: gpio-max732x.c (~/.repos/linux-mainline/drivers/gpio) - VIM

" Press ? for help
.. (up a dir)
</joe/repos/linux-mainline>
  arch/
  block/
  certs/
  crypto/
  Documentation/
  drivers/
  firmware/
  fragments/
  fs/
  include/
  init/
  ipc/
  kernel/
  lib/
  LICENSES/
  mm/
  net/
  samples/
  scripts/
  security/
  sound/
  tools/
  usr/
  virt/
  built-in.a
  COPYING
  CREDITS
  Kbuild
  Kconfig
  MAINTAINERS
  Makefile
  Module.symvers
  modules.builtin

1475
1476 static irqreturn_t max732x_irq_handler(int irq, void *devid)
1477 {
1478     struct max732x_chip *chip = devid;
1479     uint8_t pending;
1480     uint8_t level;
1481
1482     pending = max732x_irq_pending(chip);
1483
1484     if (!pending)
1485         return IRQ_HANDLED;
1486
1487     do {
1488         level = __ffs(pending);
1489         handle_nested_irq(irq_find_mapping(chip->gpio_chip.irq.domain,
1490                                           level));
1491     } while (pending &= ~(1 << level));
1492
1493     return IRQ_HANDLED;
1494 }
1495
1496 static int max732x_irq_setup(struct max732x_chip *chip,
1497                             const struct i2c_device_id *id)
1498 {
1499     struct i2c_client *client = chip->client;
1500     struct max732x_platform_data *pdata = dev_get_platdata(&client->dev);
1501     int has_irq = max732x_features[id->driver_data] >> 32;
1502     int irq_base = 0;
1503     int ret;
1504
1505     if ((pdata && pdata->irq_base) || client->irq)
1506         has_irq = INT_NONE;
1507
1508     if (pdata)
1509         irq_base = pdata->irq_base;
1510
1511     chip->irq_features = has_irq;
1512
1513     max732x_id
1514     max732x_init
1515     max732x_irq_chip
1516     max732x_of_table
1517
1518     functions
1519     -is_group_a(struct ma
1520     -max732x_exit(void)
1521     -max732x_gpio_directi
1522     -max732x_gpio_directi
1523     -max732x_gpio_get_val
1524     -max732x_gpio_set_mas
1525     -max732x_gpio_set_mul
1526     -max732x_gpio_set_val
1527     -max732x_init(void)
1528     -max732x_irq_bus_lock
1529     -max732x_irq_bus_sync
1530     -max732x_irq_handler(
1531     -max732x_irq_mask(str
1532     -max732x_irq_pending(
1533     -max732x_irq_set_type
1534     -max732x_irq_set_wake
1535     -max732x_irq_setup(st
1536     -max732x_irq_unmask(s
1537     -max732x_irq_update_m
1538     -max732x_probe(struc
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```

IDE for Kernel Development: Eclipse

Pros:

- Easy to use
- Nice tools (indexing, macro unwrapping, etc)

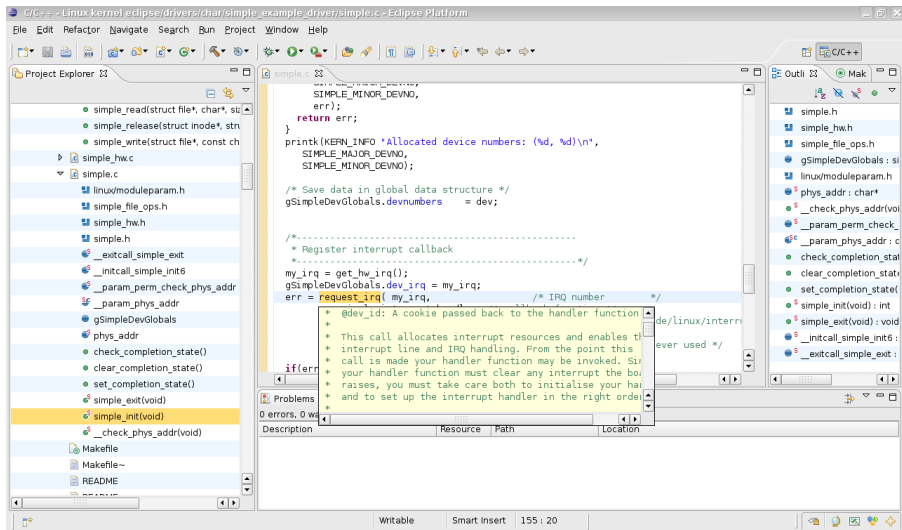
Cons:

- Very slow
- Uses a lot of resources
- Not available on servers, etc.

Be sure to configure CDT for kernel development. Details:

https://wiki.eclipse.org/HowTo_use_the_CDT_to_navigate_Linux_kernel_source

IDE for Kernel Development: Eclipse (cont'd)



Other possible IDEs:

- Emacs
- KDevelop
- QtCreator

Kernel source web-browser (very useful):

- elixir.bootlin.com

Questions so far?

Take Five

Workshop: Bringing up the BBB

Short Quiz

1. Who didn't manage to build all the SW?
2. Who doesn't have a laptop along?

Training Centre Infrastructure

Training Centre PC info:

- Press F9 on boot (show boot menu)
- Select second drive (TS64GSSD370S, 64 GB)
- Login: Lin-Ker
- Password: 123

What does it have?

- Ubuntu 18.04, internet connection, prepared environment
- Toolchains (**/opt/***)
- U-Boot, Linux kernel, BusyBox (see **~/repos/***)
- **Missing:** TRM, datasheet, schematic, BBB instructions guide

Notes:

- Better to use home laptop to keep the single environment
- We only have one card reader :(

Hardware Equipment

- **The board:** BeagleBone Black Rev C
- **Serial cable:** TTL-232R-3V3
- **OTG USB cable:** mini-USB to USB
- **micro-SD card + adapter:** 8 GB, class 10
- **Ethernet patch cord:** for network boot and networking tasks
- **Development kit:** a set of hardware, will be used later

ESD Safety Note



- Discharge before touching
- Use ESD mat and wrist strap
- Don't wear ESD unsafe clothes
- Remove power plug before touching



Don't do this just yet!

- Connect mini-USB cable
 - Powering the board (low consumption use-case)
 - Flashing (**fastboot**, **dfu-util**)
- Connect serial console cable (white dot = black wire = GROUND)
 - Will be used via **minicom** tool
- Insert SD card to the slot (once it's flashed with software)

Connectivity: Serial Console

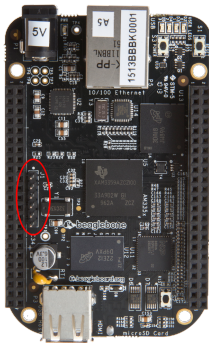


Figure 3: BeagleBone Black serial connection



Figure 4: TTL-232R-3V3 FTDI cable

Connectivity: Serial Console (cont'd)

- Board uses UART port (TTL levels, 3.3V) to communicate:
 - Rx line for receiving characters from host
 - Tx line for transceiving characters to host
- Chip in adapter cable converts UART <-> USB
 - FT232R (FTDI): reliable, recommended
 - PL2303: cheap alternative
- Chip driver exposes `/dev/ttyUSB` file (char device)
- **minicom** (or similar tool) allows user to interact with board via `/dev/ttyUSB`

Connectivity: Client USB (OTG)

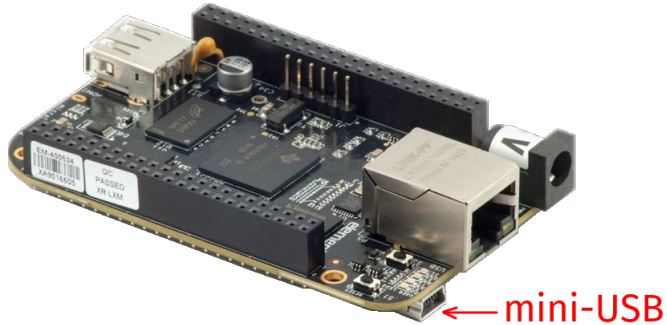


Figure 5: BeagleBone Black USB connection

Configure and Run minicom

- Run minicom configuration:

```
$ sudo minicom -s
```

- Select “Serial port setup” menu item and choose next settings:

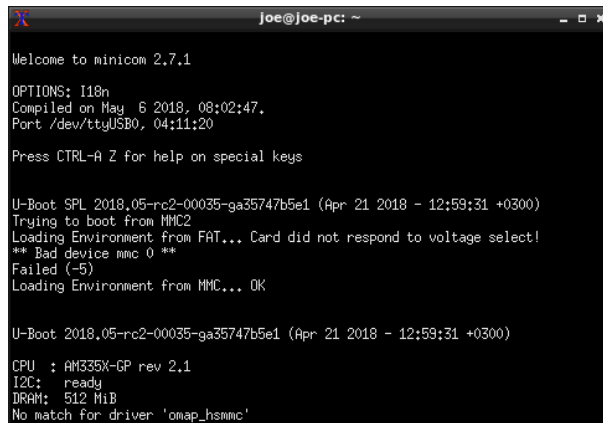
- Serial Device: `/dev/ttyUSB0`
- Bps/Par/Bits: 115200 8N1
- Hardware Flow Control: **No**

- Then select “Save setup as dfl” and “Exit from Minicom”

- Run minicom:

```
$ sudo minicom
```

Configure and Run minicom (cont'd)

A terminal window titled 'joe@joe-pc: ~' with standard window controls. The output shows minicom 2.7.1 welcome message, options (I18n), compilation date (May 6 2018), and port (/dev/ttyUSB0). It then shows U-Boot boot attempts: first trying MMC2, failing with 'Card did not respond to voltage select!' and 'Bad device mmc 0', then successfully loading the environment from MMC. Finally, it shows U-Boot version and hardware details: CPU (AM335X-GP rev 2.1), I2C (ready), DRAM (512 MiB), and a warning 'No match for driver 'omap_hsmmc''.

```
joe@joe-pc: ~  
Welcome to minicom 2.7.1  
OPTIONS: I18n  
Compiled on May  6 2018, 08:02:47.  
Port /dev/ttyUSB0, 04:11:20  
  
Press CTRL-A Z for help on special keys  
  
U-Boot SPL 2018.05-rc2-00035-ga35747b5e1 (Apr 21 2018 - 12:59:31 +0300)  
Trying to boot from MMC2  
Loading Environment from FAT... Card did not respond to voltage select!  
** Bad device mmc 0 **  
Failed (-5)  
Loading Environment from MMC... OK  
  
U-Boot 2018.05-rc2-00035-ga35747b5e1 (Apr 21 2018 - 12:59:31 +0300)  
  
CPU  : AM335X-GP rev 2.1  
I2C:  ready  
DRAM: 512 MiB  
No match for driver 'omap_hsmmc'
```

Figure 6: Terminal with minicom

Formatting SD Card (page 1)

- Insert your SD card in your laptop (use adapter)
- Locate SD card device file (should be `/dev/mmcblk0`):

```
$ sudo dmesg | tail
```

```
$ sudo fdisk -l
```

- Unmount SD card (mounted automatically by Ubuntu):

```
$ sudo umount /dev/mmcblk0p1
```

```
$ sudo umount /dev/mmcblk0p2
```

- Clear SD card MBR:

```
$ sudo dd if=/dev/zero of=/dev/mmcblk0 bs=1M count=1
```

- Create new partition table:

```
$ sudo sfdisk /dev/mmcblk0 << EOF
2048,100M,0x0c,*
,,L,-
EOF
```

- Format both partitions:

```
$ sudo mkfs.vfat -F 32 -n "boot" /dev/mmcblk0p1
$ sudo mkfs.ext4 -F -L "rootfs" /dev/mmcblk0p2
```

- Check new partitions:

```
$ sudo fdisk -l
```

- You should see something like this:

Device	Boot	Start	Size	Id	Type
/dev/mmcblk0p1	*	2048	100M	c	W95 FAT32 (LBA)
/dev/mmcblk0p2		206848	14.9G	83	Linux

Prepare Bootable SD Card (page 1)

- Unmount SD card (mounted automatically by Ubuntu):

```
$ sudo umount /dev/mmcblk0p1
```

```
$ sudo umount /dev/mmcblk0p2
```

- Mount partitions:

```
$ sudo mkdir /mnt/{boot,rootfs}
```

```
$ sudo mount /dev/mmcblk0p1 /mnt/boot
```

```
$ sudo mount /dev/mmcblk0p2 /mnt/rootfs
```

- Check that partitions mounted properly:

```
$ mount | grep mmcblk
```

Prepare Bootable SD Card (page 2)

- Copy U-Boot files to SD card (“boot” partition):

```
$ cd ~/repos/u-boot
```

```
$ sudo cp MLO u-boot.img /mnt/boot
```

- Copy rootfs files to SD card (“rootfs” partition):

```
$ cd ~/repos/busybox/_install
```

```
$ sudo cp -R . /mnt/rootfs
```


- Unmount SD card:
\$ sudo umount /mnt/boot
\$ sudo umount /mnt/rootfs
- Remove your SD card from your laptop

Booting from SD Card

- Unplug mini-USB cable from the board
- Insert SD card in board's slot
- Press and hold **USER/BOOT** button
- Plug power cable and mini-USB cable back to board
- Release **USER/BOOT** button
- BusyBox will be loaded from SD card

Assignments

Assignment #1

- Finish up the whole BBB guide:
 - Do all kinds of boot, using 3rd chapter (eMMC boot, TFPT boot, NFS boot)
 - Use previously built software (from lecture 1 assignment)
- Proof:
 - Send me screenshots that prove eMMC boot works for you
 - Send me screenshots that prove NFS boot works for you

Assignment #2

- Install and configure IDE of your choice (use links from slides)
- In your IDE (work dir must be the kernel source dir):
 - Open `init/main.c` file
 - Find `start_kernel()` function implementation
 - In `start_kernel()`, look for `setup_arch()` call
 - Jump to `setup_arch()` (using IDE capabilities)
 - Get back to `start_kernel()` (using IDE capabilities)
 - Find where `start_kernel()` is being called from (using IDE capabilities)
- Proof: send me screenshot that shows your configured IDE

Thank you!

Appendix: Abbreviations

Abbreviations

- BBB - BeagleBone Black
- DFU - Device Firmware Upgrade
- DTB - Device Tree Blob
- eMMC - Embedded MMC (MultiMedia Card)
- ESD - Electrostatic Discharge
- FDT - Flattened Device Tree (the same as DTB)
- FTDI - Future Technology Devices International
- GPIO - General Purpose Input Output
- GPT - GUID Partition Table
- IDE - Integrated Development Environment
- LED - Light-Emitting Diode

Abbreviations (cont'd)

- MBR - Master Boot Record
- MLO - MMC Loader (the same as SPL)
- NFS - Network File System
- OTG - USB On-The-Go
- PCB - Printed Circuit Board
- PHY - Physical layer chip
- PMIC - Power Management IC (Integrated Circuit)
- RootFS - Root File System
- SD card - Secure Digital card
- SoC - System on Chip
- SPL - Secondary Program Loader

Abbreviations (cont'd)

- TFTP - Trivial File Transport Protocol
- TRM - Technical Reference Manual
- TTL - Transistor-to-Transistor Logic
- UART - Universal Asynchronous Receiver-Transmitter