

# Investment Management Course Notes

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## 1.1 Fundamentals of risk and returns

Compounding returns with different return rates:

$$(1 + r_1)(1 + r_2) - 1.$$

Compounding returns with the same return rate:

$$((1 + r)^t - 1).$$

To compare different time period standard deviations multiply (or divide) by the square root of the number of time periods. The sharpe ratio:

$$\frac{R_p - R_f}{\sigma_p}.$$

Pandas standard deviation method uses the sample standard deviation and not the population standard deviation. Similar to the sharpe ratio, the calmar ratio is a risk adjusted return where risk is measured by drawdown. Use index method to period to convert from datetime to period. Use series method cummax to find the highest value for each timestep. Drawdown is then:

$$\frac{Value - PreviousPeak}{PreviousPeak}.$$

## 1.2 Beyond The Gaussian Case

Skew and kurtosis are the third and fourth moments of a distribution respectively. A distribution with a greater than three kurtosis is considered fat tailed.

The Jarque Bera is a test that determines whether or not a sample distribution fits a normal distribution based on its skew and kurtosis. If the test is close to zero it signals that the distribution is close to normal. The test:

$$JB = \frac{n}{6} \left( S^2 + \frac{1}{4}(K - 3)^2 \right).$$

Semi-deviation is the volatility of below-average or below-zero returns:

$$\sigma_{semi} = \sqrt{\frac{1}{N} \sum_{R_t \leq \bar{R}} (R_t - \bar{R})^2}.$$

Value at risk (VaR) represents the maximum "expected" loss over a time period. A 99% one month VaR gives the maximum loss excluding the 1% of worst cases. The VaR is also typically expressed as a positive number. The conditional value at risk (CVaR) is the expected loss beyond VaR:

$$CVaR = -E(R | R \leq -VaR).$$

Setting ddof as zero for pandas standard deviation calculates the population standard deviation.

There are four methods to calculate VaR. The historical methodology calculates the VaR from the historical outcomes. The parametric gaussian methodology assumes a gaussian distribution. In this methodology the VaR is simple to calculate:

$$VaR_\alpha = -(\mu + z_\alpha \sigma),$$

where  $z_\alpha$  is the  $\alpha$ -quantile of the normal distribution with mean zero and standard deviation one. The gaussian is almost inaccurate. A parametric non-gaussian distribution doesn't assume gaussian. The Cornish-Fisher VaR is a semi-parametric approach. The expansion states:

$$\tilde{z}_\alpha = z_\alpha + \frac{1}{6}(z_\alpha^2 - 1)S + \frac{1}{24}(z_\alpha^3 - 3z_\alpha)(K - 3) - \frac{1}{36}(2z_\alpha^3 - 5z_\alpha)S^2,$$

where  $\tilde{z}_\alpha$  is the updated quantile.

Use numpy's percentile for historical VaR and scipy.stats' ppf function for gaussian, parametric, and Cornish-Fisher VaR.

## 2.1 Optimization and the Efficient Frontier

The return of a portfolio is equal to the weighted average of the return of the components. The volatility of a portfolio, however, depends on the correlation:

$$\sigma^2(w_a, w_b) = \sigma_A^2 w_A^2 + \sigma_B^2 w_B^2 + 2w_A w_B \sigma_A \sigma_B \rho_{A,B}.$$

The efficient frontier is the boundary of regions created from the assets with a given correlation. Each point on this line represents the best return for each volatility.

## 2.2 Implementing Markowitz

The capital market line is the tangent line from the risk free rate to the efficient frontier. The portfolios from this line have the highest sharpe ratio. This

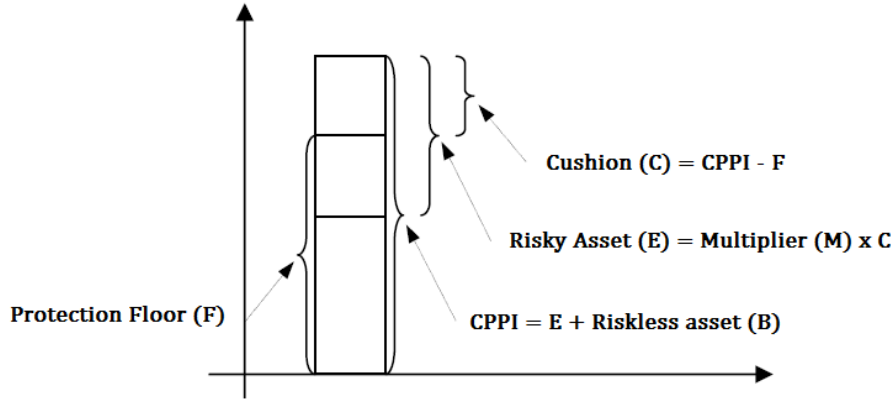
maximum sharpe ratio portfolio (MSR) also has no exposure to unrewarded risks.

As a result of estimation errors and misleading expected returns, some use the global minimum variance (GMV), which is the nose of the efficient frontier. Even small estimation errors result in large portfolio changes.

### 3.1 CPPI and Drawdown constraints

You cannot diversify out all risk. Dynamic hedging allows for upside exposure with less downside exposure. Correlation often rises when returns fall.

The CPPI procedure allows for the construction of convex payoffs. The risky asset is a multiplier multiplied by the cushion. The CPPI is the riskless asset plus the risky asset. The cushion is then the CPPI minus the protection floor set in place. Therefore, as the cushion decreases, more of the portfolio is riskless assets, and as the cushion increases, more of the portfolio is risky assets.



Gap risk occurs when trading discretely.

Given a max drawdown constraint

$$V_t > \alpha M_t,$$

where:  $V_t$  is the value of the portfolio,  $M_t$  is the peak of the portfolio between time 0 and time  $t$ , and  $1 - \alpha$  is the maximum acceptable drawdown. Then choosing a multiplier multiplied by  $M_t \alpha$  will also provide a convex payoff.

A cap can also be used to reduce risk taking passed a value. In this system, if the floor is closer, the distance to the floor is used while if the ceiling cap is closer, the distance to the ceiling is used.

Instead of constructing a new DataFrame using an array, use the DataFrame method `reindex_like`.

We can model the return process of a stock  $S_t$  with risk-free rate  $r$ , sharpe ratio  $\lambda$ , and volatility  $\sigma$ :

$$\frac{dS_t}{S_t} = (r + \sigma \lambda)dt + \sigma dW_t.$$

For discrete time:

$$\frac{S_{t+dt} - S_t}{S_t} = (r + \sigma\lambda)dt + \sigma\sqrt{dt}\xi_t.$$

## 3.2 Monte Carlo

A more general model of a return process with the same variables:

$$\frac{dS_t}{S_t} = \left(r_t + \sqrt{V_t}\lambda_t^S\right)dt + \sqrt{V_t}dW_t^S.$$

We can also define the risk-free rate and variance in terms of brownian motion:

$$\begin{aligned} dr_t &= a(b - r_t)dt + \sigma_r dW_t^r \\ dV_t &= \alpha(\bar{V} - V_t)dt + \sigma_V \sqrt{V_t} dW_t^V \end{aligned}$$

Here,  $b$  is the long term mean of the risk-free rate. Both of these processes are mean reverting.

In a CPPI system, raising the risky-asset multiplier when the market is less volatile and vice-versa results in less breaches of the floor and less need for rebalancing more frequently.

## 4.1 Asset-Liability Management

The funding ratio  $F_t = A_t/L_t$  and surplus  $S_t = A_t - L_t$  is what really matters for asset-liability management.

The present value of a set of liabilities is

$$PV(L) = \sum_{i=1}^k B(t_i)L_i,$$

and if the yield curve is flat, the price of a pure discount bond is

$$B(t) = \frac{1}{(1+r)^t},$$

where  $r$  is the annual rate of interest.

Liability-hedging portfolios attempt to match the cashflows of the liability side in order to pay liabilities in the future. Often, cash-flow matching is not feasible or practicle, so one may use factor exposure matching. These factor exposure matching portfolios often use bonds to gain similar exposure to interest rates that affect liabilities.

The Cox Ingersoll Ross (CIR) model that is used to model interest rates:

$$dr_t = a(b - r_t)dt + \sigma\sqrt{r_t}dW_t,$$

where  $b$  is the long term mean of the interest rate.

Since performance generation and hedging are incompatible aims, creating a performance-seeking portfolio (PSP) and a liability-hedging portfolio (LHP) is the best option. This two portfolio style is called liability-driven investing (LDI). The formal expression of the goal is:

$$\max_w E \left[ u \left( \frac{A_t}{L_t} \right) \right] \Rightarrow w^* = \frac{\lambda_{PSP}}{\gamma \sigma_{PSP}} w^{PSP} + \beta_{L,LHP} \left( 1 - \frac{1}{\gamma} \right) w^{LHP}.$$

The greeks of LDI are these greek letters.  $\lambda_{PSP}$  is the sharpe ratio of the PSP,  $\gamma$  is the risk aversion,  $\sigma_{PSP}$  is the standard deviation of the PSP,  $\beta_{L,LHP}$  is the beta of the liabilities with respect to the LHP.

## 1.2 Introduction to Machine Learning

Adequate data is needed for a train-test split, and data must be stable (stationary). While traditional statistics builds model and relies on assumptions, machine learning relies on large data.

Taking the average classification of multiple classifiers does best with respect to reducing estimation errors. Implementing a voting system, called boosting, is another way to combine different classifiers.

Dimensional reduction such as PCA helps with feature selection. Clustering algorithms can also be used.

## 2.1 Introduction to Factor Models

Macro-factors such as GDP growth, interest rate, and inflation are applicable to many asset classes. Micro-factors, on the other hand, are only applicable to specific asset classes. Investing with an aim for diverse factor exposure is better than investing for general diversification as different asset classes may have the same factors.

The simplest factor model, the market model:

$$R_{i,t} - r_{f,t} = \alpha_i + \beta_i(R_{M,t} - r_{f,t}) + \epsilon_{i,t},$$

where  $r$  is the risk-free rate,  $R_{i,t}$  is the return of the specific asset, and  $R_{M,t}$  is the return of the market. The explanatory power or  $R^2$ , is the part of the variance explained by the factor model:

$$R^2 = \frac{\beta_i^2 \sigma_M^2}{\sigma_i^2}.$$

A multi-factor model then relates the excess return of the asset to the excess return of other factors:

$$R_{i,t} - r_{f,t} = \alpha_i + \beta_{i,1}F_{1,t} + \dots + \beta_{i,k}F_{k,t} + \epsilon_{i,t}.$$

Fama and French's 1992 model used this to show that stocks' market cap, market size, and value were statistically significant in predicting returns. The momentum factor is also a highly recognized factor.

Instead of calculating covariance for a large number of assets, we can estimate covariance as a function of exposure to the factors:

$$\sigma_{ij} = \text{cov}(R_i, R_j) = \sum_{k=1}^K \beta_{ik} \beta_{jk} \sigma_k$$

$$\sigma_{ii} = \text{cov}(R_i, R_i) = \sum_{k=1}^K \beta_{ik}^2 \sigma_{F_k}^2.$$

This assumes uncorrelated factors and uncorrelated residuals, but it also leads to less estimation errors and overfitting.

## 2.2 Estimation of Factor Models

A penalty method called ridge regression is used to prevent overfitting from overly high coefficients. In the equation:

$$\hat{\beta}(\lambda) = \arg \min_{\beta} \{ \|y - X\beta\|^2 + \lambda \|\beta\|^2 \},$$

$\lambda$  is the penalty term and as the  $\|\beta\|$ , the normed sum of coefficients, increases the model is penalized. The lasso method is similar, except the normed  $\beta$  isn't squared. Finding a middleground penalty term  $\lambda$  is important.

Train and test, a cross-validation method, involves testing on a different subset of the data and taking the average of the performance. Each subset is often called a fold.

Penalty terms are one type of shrinkage. Stein's paradox states that when estimating three or more parameters, the best model is the average of three parameters as this lowers variance and minimizes the mean squared error. This shows that biasing and shrinking are useful in minimizing error.

In scikit-learn, instead of  $\lambda$  they use

$$\alpha = \frac{\lambda}{2n}.$$

Additionally, the formulas for their ridge and lasso regressions are different.

Best subset regression is a regression method that constrains the number of factors.

## 3.1 Measuring Diversification

Unsupervised learning can be used to more accurately measure diversification. This is especially useful as diversification can change over time.

The effective number of constituents can be measured as such:

$$ENC \equiv \frac{1}{\sum_{i=1}^N w_i^2}.$$

This shows that because the S&P 500 is market cap weighted, it only has about 100 effective constituents. Instead of measuring a portfolio as a portfolio of assets, we can measure it as a portfolio of factor exposure. The effective number of bets is then given by:

$$ENB = \frac{1}{\sum_{i=1}^N p_k^2},$$

where

$$p_k = \frac{w_{F_k}^2 \sigma_{F_k}^2}{\sigma_p^2}.$$

In the former equation,  $\sigma_p^2$  is the variance of the portfolio.

## 3.2 Maximizing Diversification Benefits

Sparse PCA is a machine learning alternative to traditional PCA. Clustering, another unsupervised learning method, seeks to minimize the distance between points and their clusters' median.

Conditional independence is a concept where two objects may be related by a mutual connection but are independent of each other. The conditional independence of two variables  $x$  and  $y$ , given that  $z$  has occurred:

$$X \perp Y \mid Z \Leftrightarrow P(x, y \mid z) = P(x \mid z)P(y \mid z).$$

The precision matrix is the inverse of the correlation matrix, and if the entry is zero, then the two variables are conditionally independent.

Improving sparsity helps with diversification and can be achieved by using lasso a penalty function. Testing this concept on the top 50 stocks in the S&P 500, we find that clustering and PCA yield the highest sharpe ratio and returns.

There is no need to know the number of clusters for the affinity propagation algorithm while the number of clusters must be known for k-means. Multi dimensional scaling allows for visulization of multi dimensional data in to two dimensions.

## 4.1 Varying Market Conditions

Since correlations increase in crash periods, identifying these regimes can be helpful with risk management and portfolio choice.

A GARCH model tries to model the current variance based on the long-run variance rate  $V_L$ :

$$\sigma_T^2 = \gamma V_L + \sum_{t=1}^T \alpha_t R_t^2 + \beta \sigma_{T-1}^2,$$

where

$$\gamma + \beta + \sum_{t=1}^T \alpha_t = 1,$$

and

$$\alpha_t = \frac{\lambda^{T-t}}{\sum_{t=1}^T \lambda^{T-t}}.$$

The lower the lambda the higher the weight assigned to recent observations.

A markov regime switching model implies that volatility is not a function of time but a function of a state. The parameters of the transition matrix can be estimated by maximizing log likelihood. Machine learning can also be used for non-parametric identification.

## 4.2 Regime Switching with Machine Learning

Even two regime models perform much better at forecasting the tails of returns. A long term model is one that uses a historical transition matrix. The optimization problem to solve is this:

$$\hat{\beta} = \arg \min_{\beta} ||x - \beta||_2^2 + \lambda ||D\beta||_1.$$

In this equation,  $\hat{\beta}$  is the updated values of the timeseries. If we increase  $\lambda$  the timeseries must be flat, and if we decrease  $\lambda$  to zero then the series must be equal to  $x$ .

## 5.1 Traditional Statistics and Machine Learning

Traditional regression models are often ineffective at forecasting crash periods.

Logistic regression is often used for binary classification as it gives a probability measure:

$$h_{\beta} = \frac{1}{1 + e^{-(\beta_0 + \beta x)}}.$$

Typically, the final classification is done by choosing a threshold value. To learn this model we maximize the maximum-likelihood where  $y_i$  is the predicted class/state:

$$J(\beta) = \sum_{i=1}^N y_i \log(h_{\beta}(x_i)) + (1 - y_i) \log(1 - h_{\beta}(x_i)).$$

To create sparsity, decrease variance, improve a model, and prevent overfitting, there are many ways. Elastic net, a model with two penalty terms, is best when features are correlated. Stepwise regression, a model that increases the degree of each polynomial term, is another alternative. Subset selection, a method where the model is built with only a certain amount of parameters, is



another method to reduce overfitting. Using an ensemble method to combine multiple models is also useful.

For k-nearest neighbors (k-NN), the k defines how many neighbors will be used to classify the point. Training errors often increase with k. The algorithm can use euclidean distance (L-2 norm) or manhattan distance (L-1 norm).

A decision tree divides the data into subsets on feature at a time. It does this by selecting the feature level that best splits the data. The algorithm can be used for regression or classification.

Boosting is a machine learning algorithm that combines multiple models. It does this by creating a weak learning model and then creating more models that have loss functions that reward getting high error datapoints more correct. It then iteratively creates more models and finds a weighted average of the prediction. The higher the error of the model, the lower the weight in the voting system.

## 5.2 Predicting Crash Regimes

Several different models were used to attempt to predict if the next month would be a crash regime or not. Logistic regression did poorly, k-NN performed amazing, decision tree did worse than k-NN, and gradient boosting did slightly worse than k-NN. An ensemble model performed better than most of the models but still worse than k-NN.

Balanced and imbalanced data refers to the distribution of classes in the data. In a typical two state, growth and constraction model, the data is imbalanced.

The ROC metric represents the true positive rate (TPR) and the false positive rate (FPR):

