J O S E P H   A L E X A N D E R   B I N N S

Work Sample for Game Programming

2022

I've written this PDF in LaTeX.
The dice below are automatically shuffled whenever the PDF is compiled.
Check the dice out for yourself on Overleaf.

How very... impractical

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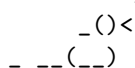
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        /                                        \
        |          Give credit where credit's due!  |
        \     The ASCII art is based on ducksay!   /
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   _____
 /       \
 \  Hi!   /
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                                  \   BAA- Who are y..?  /
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```

```
 /  I'm Joe, a British game programmer and designer, working and study-  \
 |  ing in Sweden. I'm soon to graduate from Lund University with a BSc   |
 |  in Theoretical Physics, where I've specialised in Artificial Neural Net- |
 |  works. I create tools, games and STEM inspired simulations through    |
 |  Unity and custom game engines. I put a focus on leveraging my know-   |
 |  ledge of maths and physics to create robust and reliable game mechan- |
 \  ics.                                                                   /
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```
                                  _____
                                /                            \
                                \   Woah buddy! Slow down th...  /
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```
 /                                                            \
 |  Almost five years ago, I was presented with a video explain-  |
 |  ing how an artificial neural network had been trained with    |
 |  genetic algorithm to play Super Mario World. I was inspired.  |
 |  That initial curiosity has continued to grow ever since; I am  |
 |  now writing my bachelor's thesis on the topic of neural net-  |
 |  works.                                                        |
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```
 /                                                            \
 |  Always eager to learn and find better ways of doing        |
 |  things, I'm dedicated to utilising my skills to facil-      |
 |  itate unforgettable gameplay experiences. Here you         |
 |  can see a selection of professional and educational        |
 |  projects that I've have the opportunity to work on,        |
 |  as well as some of the personal fun-things that have       |
 \  led me here.                                               /
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Personal

Stylised Character Controller

August 2021 - present

GitHub itch.io YouTube

`Language` `C#` `Language` `ShaderLab`

A stylised physics-based character controller made in Unity 3D. Before you read on, get a hands-on feel for the project over at itch.io. Alternatively, watch the demo on YouTube!

The character controller is based on the floating capsule approach devised by Toyful Games for Very Very Valet. In a video from the team's development blog, the various techniques for the movement are outlined and explained. The video also provides snippets of code, though incomplete in places. The source code was not provided by Toyful Games due to it being tied up in the complex other workings of Very Very Valet. This project contains a fan-made pure re-creation of their physics-based character controller.

Additional stylisation inspired by discussions found in Toyful Games blog posts on character animations and shaders and effects are also included. These implementations exist from a personal desire to have them in my own projects. The project makes use of Unity's Universal Render Pipeline (URP) to facilitate some of these graphical features.

Features

- Physics-based character controller.

- Squash and stretch, a principle of animation, makes the character's motion appear more fluid and bouncy.

- Dithered silhouettes appear on the character when obscured from view, letting the player know where they are at all times.

- Top down blob shadows on characters make 3D platforming feel sharper, and they look great when combined with Unity's inbuilt shadows on the environment.

- Dust particles appear when characters move, making the character feel more alive.

Motivation

The motivation to start this project came after implementing the physics-based character controller into a game prototype of my own. I had been struggling for a long time to complete a project as University was taking priority. With heaps of scrapped projects accruing, I felt a strong desire to just get something out there. So I took what I already had, and released it in the hope that other game developers may find it useful. Here it is!

Raymarch Explorer   April 2019 - September 2019

For this project I familiarised myself with graphics programming and ray marching techniques.

Unity build

`Language HLSL` `Language C#`

Before you read on, check out the results on YouTube!

Raymarch Explorer is a real-time 3D fractal explorer developed in Unity. Prototyping a method for deep-zoom functionalities, minimum distance values are passed from compute shader to C# script. The minimum distance value is used to determine appropriate velocities and level of detail, such as to give the effect of zooming into the fractal surface.

The depth of the fractal is restricted by data-type precision. In order to achieve true deep-zoom functionality, arbitrary precision arithmetics on the Graphics Processing Unit (GPU) is required. Unfortunately, this task does not seem well suited to Unity due to inbuilt limitations on the data-type of the transform component. The project has therefore been moved to the Lightweight Java Game Library (LWJGL).

Developed from Sebastian Lague's Ray-Marching `repository`.

Lightweight Java Game Library build

`Language GLSL` `Language Java`

Before you read on, check out the results on YouTube!
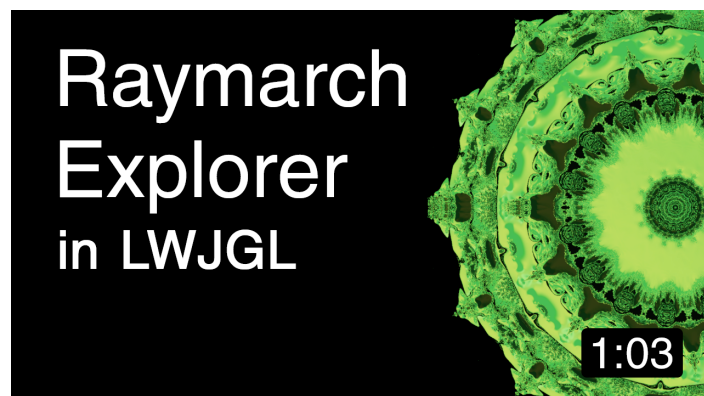
Raymarch Explorer is a real-time 3D fractal explorer developed in a custom-built engine. The custom-built engine is developed from the Light Weight Java Game Library (LWJGL) for the Open Graphics Library (OpenGL). The depth of computed fractals is restricted by data-type precision. In order to achieve true deep-zoom functionality, Arbitrary Precision Arithmetics is required. This project explores arbitrary precision arithmetics on the Graphics Processing Unit (GPU).

Bloomerang Game Maker's Toolkit Game Jam   August 2019
Collaborators: Seelocanth (Art & Music).
GitHub itch.io

`Language` `C#`

The garden is swarming with angry bees! Luckily, you've got your trusty 'Bloomerang' to help ward them off. Be careful though, you only get one shot to take enemies out. If you miss, the Bloomerang won't come back, and you may be finished!

Bloomerang is a procedural, top-down roguelike. This game was conceptualised and made in 48 hours for the Game Maker's Toolkit Jam (GMTK) 2019. The theme of the jam was 'only one'. Before you read on, get a hands on feel for the project over at `itch.io`!

Post-mortem

I was inspired at the time to attempt a 'Hotline Miami' style of aiming. This is where the camera follows the cursor position, to an extent. I was however a little disappointed with the results. Others gave feedback that it didn't quite feel right. I agree that it does feel to be a little un-intuitive and disorienting. I wanted to determine why this was. A short side-by-side video was put together in order to analyse why it worked poorly in Bloomerang compared to the original inspiration. Check out the comparison on YouTube!

Did you spot it? I didn't at first. The main difference I wish to highlight is only seen in the behaviour of the mouse when close to the player. It's not very well illustrated in the video, so I recommend getting a feeling for it yourself over at `itch.io`. I implemented a minimum radius that the cursor can be to the player. The idea was that it would prevent players from throwing the boomerang little to no distance. Though this seemed to be a good idea to me (as why would a player ever want to throw the boomerang to no effect?), it means the player's control over the cursor is obstructed. While the player expects the cursor to continue in a straight line as it moves over the character, it now moves in a minimum-distance radius around the character. This resulted in an un-predictable, fast moving cursor. The message is clear; design decisions that are at risk of obstructing the control of the player must be tested and iterated, regardless of good intent.

**Dare to Dance** Ludum Dare   April 2019

Language C#

The floor's come alive with zombies. Dance on the beat to ignite their disco spirit.

Dare to Dance is a fast-paced, disco-themed rhythm game. This game was conceptualised and made in 48 hours for the Ludum Dare 44 game jam. The theme of the jam was 'your life is currency'. Before you read on, get a hands-on feel for the project over at itch.io!

Post-mortem

For a first attempt at a game jam, I am pleased with Dare to Dance. I especially enjoy it for its visual simplicity. The beat was synced to the Beats Per Minute (BPM) of the music, and the beat itself was emphasised by both the closing spotlight and flashing disco balls.
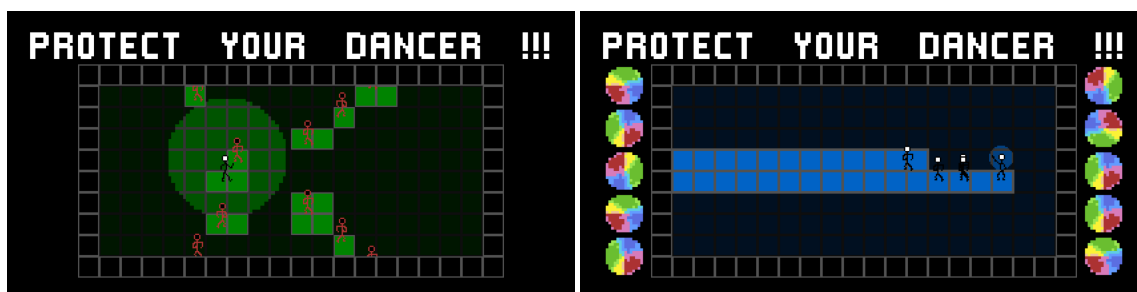
| 1. Don't get touched... | 2. Strike on the beat! |

However, there is a whole lot of room for improvement:

- The controls can be hard to use and unforgiving.

- The timing window for attacking should be increased, for greater leniency.

- The player should not be required to move while attacking.

- The last direction of movement should automatically be used as the attack direction.

At the moment, a lack of feedback on missed attacks is resulting in a frustrating, un-supervised learning experience for the player. Beyond polishing the player controls, the game has a lot to gain from additional layers of complexity. The life of the player should not be restricted to the single central dancer, but spread across all the dancers you have acquired. The game should continue as long as a single dancer remains. I would also like enemy spawn locations, e.g. with enemies rising out of certain highlighted floor tiles. The fundamental premise also needs to be built upon. For example, certain dance moves could be required to be performed in order to progress. These could be performed by fluidly moving over a pattern of highlighted tiles.

Professional

MLabs Simulation , London   July 2019 – August 2019
YouTube

`Language` `C#`

Fresh out of school, with a few projects to show, I was fortunate enough to acquire a software engineering position at a London-based start-up. Hired for my experience in Unity, I worked within a small team. We spent the summer developing a realistic, real-time, urban environment simulation. The simulation was designed for use by an automated transport planning system.

The simulation accesses OpenStreetMap data via the Mapbox Source Development Kit (SDK) for Unity. This provided the simulation instant access to the open-source data required to build urban environments from across the globe. After establishing the core framework for future developments, I left this project to begin my BSc in Theoretical Physics at Lund University.

Check out the initial build on YouTube!

Features

- Buildings, roads, and pavements generated in real-time from OpenStreetMaps data from anywhere in the world.

- Pedestrian pavement path-finding and collision avoidance.

- Parks and grasslands, scattered with trees and bushes for added depth.

- Performance efficient clouds.

- A day and night cycle.

Educational

BSc Theoretical Physics Thesis Lund University   January 2022 - June 2022

Supervisors: Patrik Edén, Mattias Ohlsson.

Collaborators: Rasmus Sjöö, Alexander Degener, Oscar Bolinder.

`Language` `Python`

Artificial Neural Networks: Testing the Weak Decay Regularisation Strength

Artificial Neural Networks (ANNs) are prone to over-fitting. Over-fitting is when a network trains too exactly to a data set, resulting in the particular noise of the data being learnt. Learning noise causes the network to generalise poorly to other data sets, regardless of being from the same statistical distribution. What we aim to learn instead is this underlying statistical distribution of the data. Weak decay (L2) is a common regularisation technique used to reduce over-fitting. L2 acts to minimise complexity by penalising excessively large weights. However, there is a fine line to be drawn. Too much L2, and large weights will be penalised so much that the model will tend to set all weights to zero. The L2 regularisation strength is varied in order find this fine line.
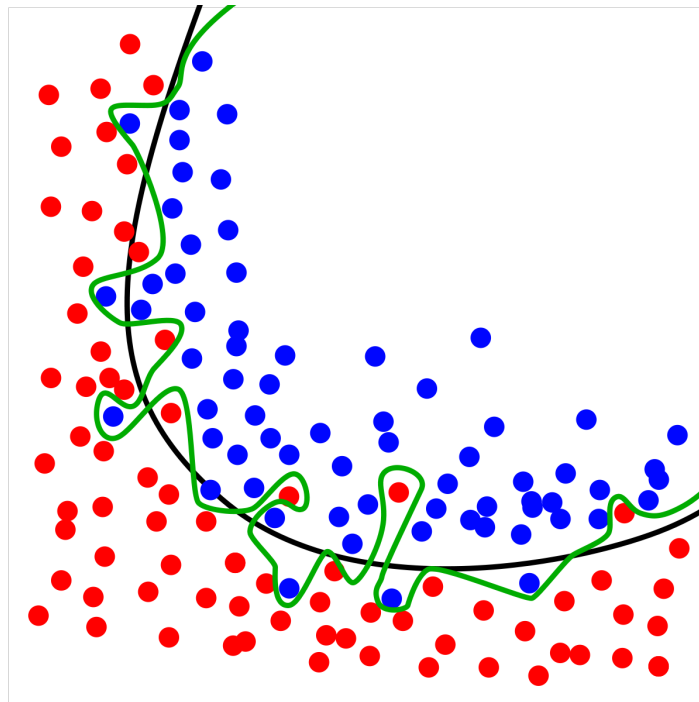

Illustration of Overfitting.
By Ignacio Icke, licensed under Creative Commons.

My thesis will test theoretical arguments that determine the weak decay (L2) regularisation strength. If it works, it would mean that the parameter can be set without trial-and-error. It could also mean that it is best to have different strengths for different nodes, and even bias weights. As the questions cannot be studied in standard Keras code, the first part of the project is to code my own ANN.

Disease Projection using Ordinary Differential Equations
Lab Report

`Language` `Python`

The main purpose of this project was to explore and experiment with a variety of models involved on the topic of disease spreading. As the starting point of the mathematical models focused on how the infected and susceptible population change over time, the equations would need to be solved in order to yield the number of infected at a given time. As this is a computational physics course, I was directed to computationally solve the equations! Computational solutions are often practical, but introduce new sources of errors. As such, the project also served as a lesson on error estimation, as well as error reduction through improved techniques and solvers. Further improvements were made to the models, such as the introduction of vaccinations and the movement of populations between discrete locations. Once the appropriate toolkit had been assimilated, an appropriate model for a chosen case-study disease outbreak was simulated: HIV in western Africa in the middle of the 20$^{\text{th}}$ century.

Read the lab report.

Image Restoration using Partial Differential Equations
Collaborators: Joshua Greaves, Daniel Larsson Persson.
GitHub YouTube

`Language` `Python`

Equations originating from physics have recently found their way to other areas. One, possibly surprising, application is that of restoring art or images. To understand how Partial Differential Equations (PDEs) from physics can help in image restoration, consider a greyscale image of your own choice. Due to graffiti painters, let us assume that a piece is missing (black region). Can we fill in the missing region without any information of what is missing? This may seem like a hopeless task, but PDEs are here to help!

PDE-based methods for image restoration are based on propagating the information (typically, colour-specific intensity values and gradients) at the boundaries of the missing region inwards. The propagation is performed by solving a partial differential equation for the missing regions' given boundary conditions.

Check out the results on YouTube!

Vicious Walkers

Language Python

The main purpose of this project was to explore and analyse various scenarios surrounding random walkers. The number of dimensions, initial conditions and a variety of other factors were used to facilitate these experiments. The results were compared to theoretical expectations.

Check out the results on YouTube!

Read the lab report.


N-body simulator   Forest Hill School, London   August 2017 - March 2018

Language C#

A real-time, *N*-body gravitational simulator and Graphical User Interface (GUI) in Unity. The program accesses planetary data from the NASA Horizons database via Telnet. Various complexity-reducing algorithms have been utilised, to optimise the large-scale physics-based simulation.

Excited by the utilisation of programming in support of physics, this project initially started as an old blog article and excel spreadsheet. The project is a follow up inspired by a great Feynman lecture on Newton's Laws of Dynamics.
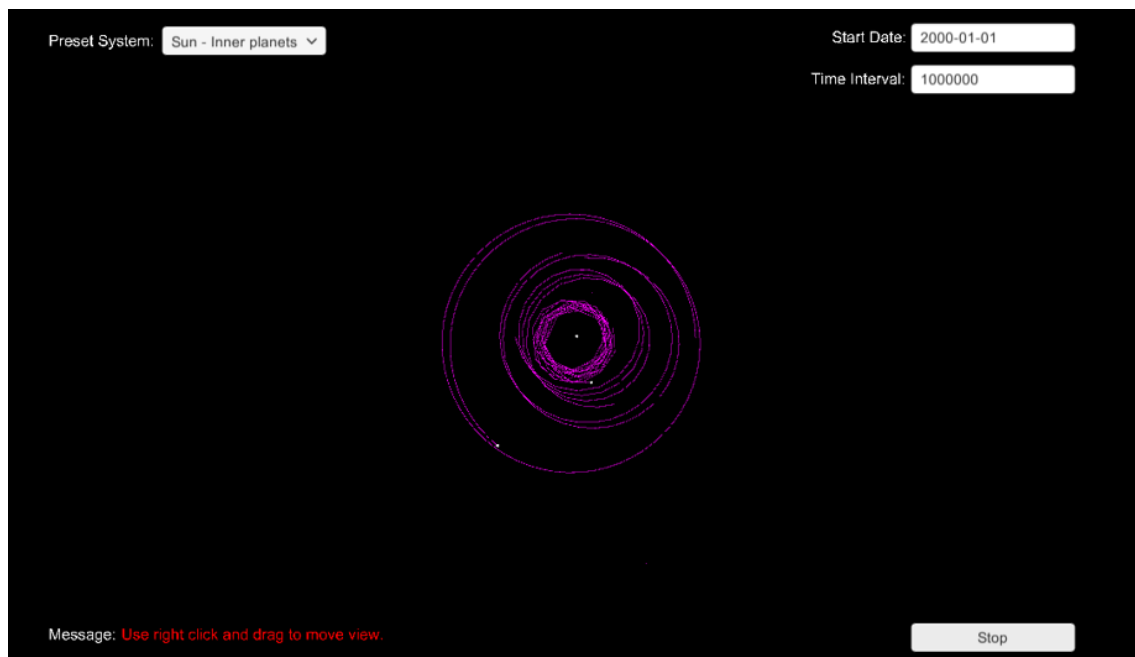
Screenshot from *N*-body simulator.

Read the development log.