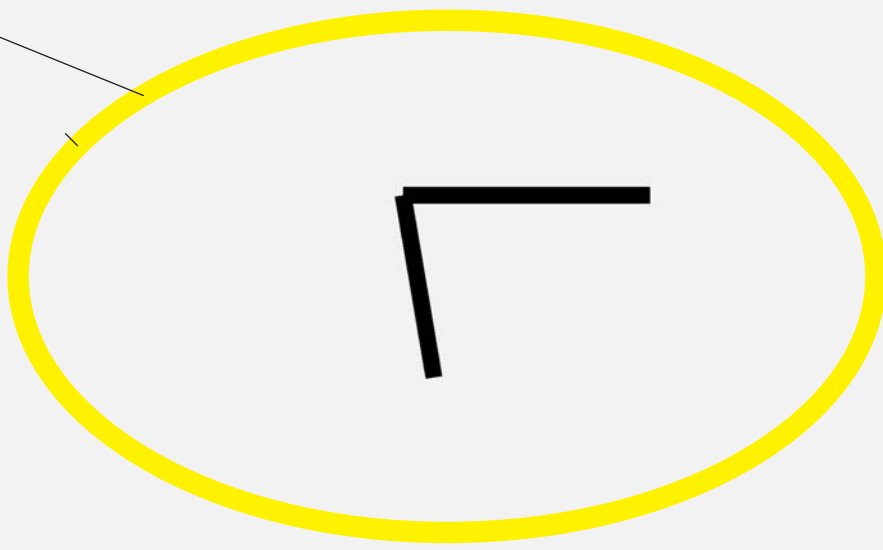




Tap around here to position the arm



Two fingers:
Swipe up/down moves wrist
Swipe left/right rotate base
Pinch close to close gripper
Pinch open to open gripper

Use the scrollbar to rotate the gripper



Move arm to starting position



Load a previously saved recording.



Save the current recording

Add the current position to the current recording

Play the current recording

Wipe all recorded steps and add the current position

Delete the last added servo position