

# Analysis of Equations of State for Neutron Star Modeling and Simulation

Joseph Nyhan

College of the Holy Cross

6 May 2022

# Outline

- What is a neutron star?

# Outline

- What is a neutron star?
- What is an equation of state (EoS)?

# Outline

- What is a neutron star?
- What is an equation of state (EoS)? How does it fit into our model of a neutron star?

# Outline

- What is a neutron star?
- What is an equation of state (EoS)? How does it fit into our model of a neutron star?
- How can we use an EoS to make macroscopic predictions about neutron stars?

# Outline

- What is a neutron star?
- What is an equation of state (EoS)? How does it fit into our model of a neutron star?
- How can we use an EoS to make macroscopic predictions about neutron stars?
- What is the importance and role of an equation of state in a temporal simulation of a neutron star?

# Outline

- What is a neutron star?
- What is an equation of state (EoS)? How does it fit into our model of a neutron star?
- How can we use an EoS to make macroscopic predictions about neutron stars?
- What is the importance and role of an equation of state in a temporal simulation of a neutron star?
- A derivation of an EoS and its predictions:



- What is a neutron star?
- What is an equation of state (EoS)? How does it fit into our model of a neutron star?
- How can we use an EoS to make macroscopic predictions about neutron stars?
- What is the importance and role of an equation of state in a temporal simulation of a neutron star?
- A derivation of an EoS and its predictions:
  - ▶ Quantum Hydrodynamics and the QHD-I parameter set

# Introduction

# Neutron Stars

# Neutron Stars

- Dense core left behind after a supernovae explosion

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .



# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction
  - ▶ Gravitational acceleration on Earth's Surface:  $\approx 10$  m/s<sup>2</sup>

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction
  - ▶ Gravitational acceleration on Earth's Surface:  $\approx 10$  m/s<sup>2</sup>
  - ▶ Neutron star:  $\approx 10^{12}$  m/s<sup>2</sup>

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction
  - ▶ Gravitational acceleration on Earth's Surface:  $\approx 10$  m/s<sup>2</sup>
  - ▶ Neutron star:  $\approx 10^{12}$  m/s<sup>2</sup> (escape velocity  $\sim 100\,000$  km/s =

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction
  - ▶ Gravitational acceleration on Earth's Surface:  $\approx 10$  m/s<sup>2</sup>
  - ▶ Neutron star:  $\approx 10^{12}$  m/s<sup>2</sup> (escape velocity  $\sim 100\,000$  km/s =  $c/3$ )

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction
  - ▶ Gravitational acceleration on Earth's Surface:  $\approx 10$  m/s<sup>2</sup>
  - ▶ Neutron star:  $\approx 10^{12}$  m/s<sup>2</sup> (escape velocity  $\sim 100\,000$  km/s =  $c/3$ )
- Why are they interesting?

# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction
  - ▶ Gravitational acceleration on Earth's Surface:  $\approx 10$  m/s<sup>2</sup>
  - ▶ Neutron star:  $\approx 10^{12}$  m/s<sup>2</sup> (escape velocity  $\sim 100\,000$  km/s =  $c/3$ )
- Why are they interesting?
  - ▶ Smallest, densest observed stellar objects



# Neutron Stars

- Dense core left behind after a supernovae explosion
- Made mostly of neutrons, protons, and electrons; overall, is neutral
- Radius:  $\sim 10$  km; Mass:  $\sim 1 \odot$ .
- Approximately the density of atomic nuclei ( $\sim 10^{17}$  kg/m<sup>3</sup>)
- Core held together by intense gravitational attraction
  - ▶ Gravitational acceleration on Earth's Surface:  $\approx 10$  m/s<sup>2</sup>
  - ▶ Neutron star:  $\approx 10^{12}$  m/s<sup>2</sup> (escape velocity  $\sim 100\,000$  km/s =  $c/3$ )
- Why are they interesting?
  - ▶ Smallest, densest observed stellar objects
  - ▶ Exotic physics

# Equation of State (EoS)

What is an equation of state?

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ )

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P)$

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$
- Encodes the fundamental interparticle interactions within a neutron star

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$
- Encodes the fundamental interparticle interactions within a neutron star
- True EoS within a neutron star is unknown;



# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$
- Encodes the fundamental interparticle interactions within a neutron star
- True EoS within a neutron star is unknown; multitude of candidates, each based on a slightly different model and fit of empirical data

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$
- Encodes the fundamental interparticle interactions within a neutron star
- True EoS within a neutron star is unknown; multitude of candidates, each based on a slightly different model and fit of empirical data
  - ▶ Models can be very complicated

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$
- Encodes the fundamental interparticle interactions within a neutron star
- True EoS within a neutron star is unknown; multitude of candidates, each based on a slightly different model and fit of empirical data
  - ▶ Models can be very complicated; often simplifications must be made to be solved practically

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$
- Encodes the fundamental interparticle interactions within a neutron star
- True EoS within a neutron star is unknown; multitude of candidates, each based on a slightly different model and fit of empirical data
  - ▶ Models can be very complicated; often simplifications must be made to be solved practically
- Often a tabulated list of  $P$  and  $\epsilon$  values;

# Equation of State (EoS)

What is an equation of state?

- A relationship between *energy density* (denoted  $\epsilon$ ) and pressure (denoted  $P$ )
  - ▶  $\epsilon = \epsilon(P) \Leftrightarrow P = P(\epsilon)$
- Encodes the fundamental interparticle interactions within a neutron star
- True EoS within a neutron star is unknown; multitude of candidates, each based on a slightly different model and fit of empirical data
  - ▶ Models can be very complicated; often simplifications must be made to be solved practically
- Often a tabulated list of  $P$  and  $\epsilon$  values; however, in simulation work, analytical fits may be required

## Using an Equation of State to Make Predictions

# Using an EoS to Make Predictions

We want a way to understand the effects of an EoS on the observable properties of a star

# Using an EoS to Make Predictions

We want a way to understand the effects of an EoS on the observable properties of a star

- e.g. total mass, total radius



# Using an EoS to Make Predictions

We want a way to understand the effects of an EoS on the observable properties of a star

- e.g. total mass, total radius

We create *static solutions*; “images” of neutron star

# Using an EoS to Make Predictions

We want a way to understand the effects of an EoS on the observable properties of a star

- e.g. total mass, total radius

We create *static solutions*; “images” of neutron star

- solve the Tolman-Oppenheimer-Volkoff (TOV) equations

# Using an EoS to Make Predictions

We want a way to understand the effects of an EoS on the observable properties of a star

- e.g. total mass, total radius

We create *static solutions*; “images” of neutron star

- solve the Tolman-Oppenheimer-Volkoff (TOV) equations
- extract information about maximum mass and radius allowed by the EoS

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.”

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.” Use EoS to determine  $\epsilon$

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.” Use EoS to determine  $\epsilon = \epsilon(P)$ .



# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.” Use EoS to determine  $\epsilon = \epsilon(P)$ .

- Initial conditions:

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.” Use EoS to determine  $\epsilon = \epsilon(P)$ .

- Initial conditions:

$$m(r = 0) = 0, \quad P(r = 0) \equiv P_0 = \text{const.}$$

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.” Use EoS to determine  $\epsilon = \epsilon(P)$ .

- Initial conditions:

$$m(r=0) = 0, \quad P(r=0) \equiv P_0 = \text{const.}$$

Each solution is uniquely defined by  $P_0$ , the *central pressure*.

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.” Use EoS to determine  $\epsilon = \epsilon(P)$ .

- Initial conditions:

$$m(r=0) = 0, \quad P(r=0) \equiv P_0 = \text{const.}$$

Each solution is uniquely defined by  $P_0$ , the *central pressure*.

- Outer conditions: Let  $R, M$  to be the total radius and total mass of the star, respectively.

# The Tolman-Oppenheimer-Volkoff (TOV) Equations

Used to describe a static (time independent) spherically symmetric star.  
Given by

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

where  $\epsilon$  is energy density,  $P$  is pressure, and  $m$  is “mass.” Use EoS to determine  $\epsilon = \epsilon(P)$ .

- Initial conditions:

$$m(r=0) = 0, \quad P(r=0) \equiv P_0 = \text{const.}$$

Each solution is uniquely defined by  $P_0$ , the *central pressure*.

- Outer conditions: Let  $R, M$  to be the total radius and total mass of the star, respectively. Defined by:

$$P(R) = 0, \quad M = m(R).$$

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r = 0) = P_0$

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r = 0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )



# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r = 0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )
- Use a numerical integration technique

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r = 0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )
- Use a numerical integration technique
  - ▶ The Runge-Kutta 4 Algorithm

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r = 0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )
- Use a numerical integration technique
  - ▶ The Runge-Kutta 4 Algorithm
  - ▶ In practice, use Scipy `solve_ivp`; faster due to optimized step size

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r=0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )
- Use a numerical integration technique
  - ▶ The Runge-Kutta 4 Algorithm
  - ▶ In practice, use Scipy `solve_ivp`; faster due to optimized step size
- Integrate outwards until  $P = 0$ ; use to define  $R$ , calculate  $M$

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r=0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )
- Use a numerical integration technique
  - ▶ The Runge-Kutta 4 Algorithm
  - ▶ In practice, use Scipy `solve_ivp`; faster due to optimized step size
- Integrate outwards until  $P = 0$ ; use to define  $R$ , calculate  $M$
- Store curves for  $m(r), P(r)$ ,

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r=0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )
- Use a numerical integration technique
  - ▶ The Runge-Kutta 4 Algorithm
  - ▶ In practice, use Scipy `solve_ivp`; faster due to optimized step size
- Integrate outwards until  $P = 0$ ; use to define  $R$ , calculate  $M$
- Store curves for  $m(r)$ ,  $P(r)$ , use to calculate  $\epsilon(r)$

# TOV Equations: Computing a Solution

$$\frac{dm}{dr} = 4\pi r^2 \epsilon, \quad \frac{dP}{dr} = -\frac{(4\pi r^3 P + m)(\epsilon + P)}{r^2(1 - 2m/r)}.$$

- Specify a central pressure  $P(r=0) = P_0$
- Begin at very small  $r \approx 0$ ; ( $10^{-8}$ )
- Use a numerical integration technique
  - ▶ The Runge-Kutta 4 Algorithm
  - ▶ In practice, use Scipy `solve_ivp`; faster due to optimized step size
- Integrate outwards until  $P = 0$ ; use to define  $R$ , calculate  $M$
- Store curves for  $m(r)$ ,  $P(r)$ , use to calculate  $\epsilon(r)$
- *Note*: works well with tabulated EoSs; an interpolating function is often used

# Static Solution: Example



# Static Solution: Example

Use an EoS called “SLy” from [3]. A realistic equation of state from an analytical fit of empirical neutron star data.

# Static Solution: Example

Use an EoS called “SLy” from [3]. A realistic equation of state from an analytical fit of empirical neutron star data.

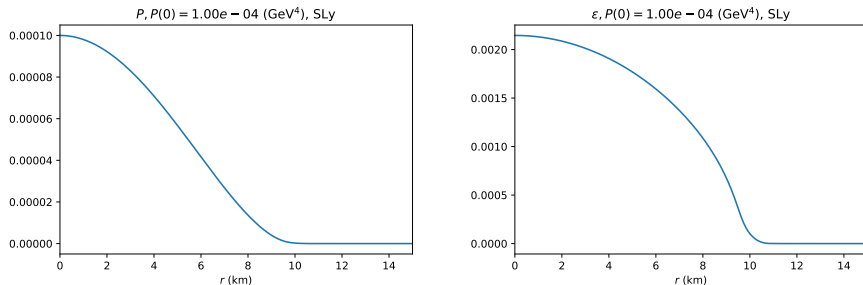


Figure: Example static solution for  $P_0 = 10^{-4} \text{ GeV}^4$  for an EoS called “SLy.”

# Static Solutions: $M(R)$ and $M(P_0)$ diagrams

# Static Solutions: $M(R)$ and $M(P_0)$ diagrams

Single solutions don't tell much about star as a whole; instead, look at trends over lots of solutions

## Static Solutions: $M(R)$ and $M(P_0)$ diagrams

Single solutions don't tell much about star as a whole; instead, look at trends over lots of solutions

- 1 Solve TOV equations for lots of  $P_0$  values:

## Static Solutions: $M(R)$ and $M(P_0)$ diagrams

Single solutions don't tell much about star as a whole; instead, look at trends over lots of solutions

- 1 Solve TOV equations for lots of  $P_0$  values:  $P_0 \in [10^{-6}, 10^{-1}](\text{GeV}^4)$ .

# Static Solutions: $M(R)$ and $M(P_0)$ diagrams

Single solutions don't tell much about star as a whole; instead, look at trends over lots of solutions

- 1 Solve TOV equations for lots of  $P_0$  values:  $P_0 \in [10^{-6}, 10^{-1}](\text{GeV}^4)$ .
- 2 Calculate the total mass  $M$  and total radius  $R$  for each value of  $P_0$

# Static Solutions: $M(R)$ and $M(P_0)$ diagrams

Single solutions don't tell much about star as a whole; instead, look at trends over lots of solutions

- 1 Solve TOV equations for lots of  $P_0$  values:  $P_0 \in [10^{-6}, 10^{-1}](\text{GeV}^4)$ .
- 2 Calculate the total mass  $M$  and total radius  $R$  for each value of  $P_0$
- 3 Plot  $M(R)$  and  $M(P_0)$



# Static Solutions: $M(R)$ and $M(P_0)$ diagrams

Single solutions don't tell much about star as a whole; instead, look at trends over lots of solutions

- 1 Solve TOV equations for lots of  $P_0$  values:  $P_0 \in [10^{-6}, 10^{-1}](\text{GeV}^4)$ .
- 2 Calculate the total mass  $M$  and total radius  $R$  for each value of  $P_0$
- 3 Plot  $M(R)$  and  $M(P_0)$

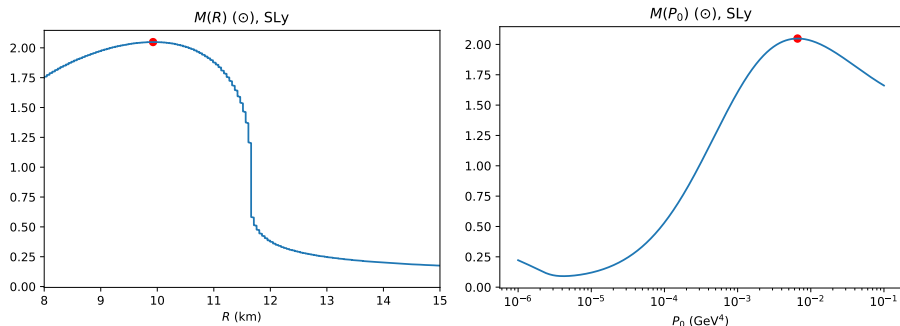
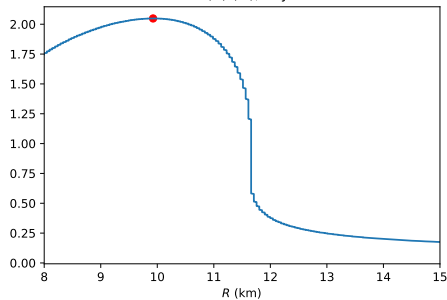


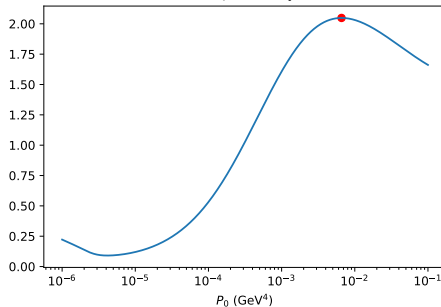
Figure: Example curves for EoS “SLy.”  $1 \odot = 1.989 \times 10^{30} \text{ kg}$  (solar mass)

# Critical Values of $P$ , $R$ , and $M$

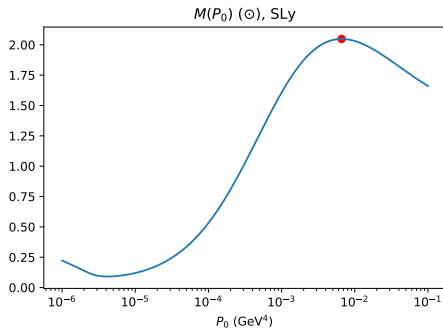
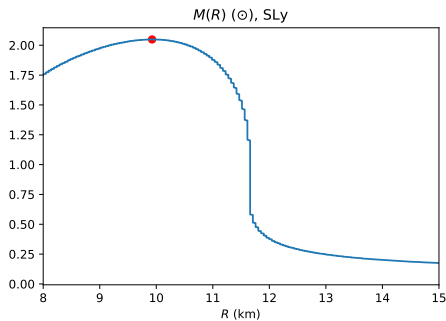
$M(R) (\odot)$ , SLy



$M(P_0) (\odot)$ , SLy

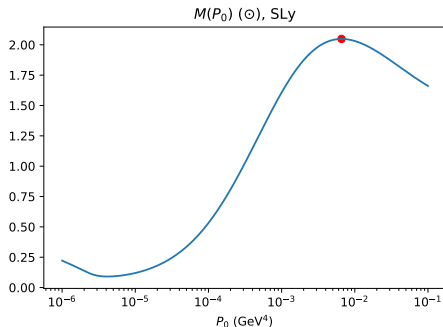
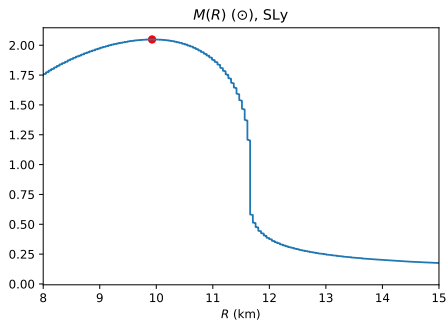


# Critical Values of $P$ , $R$ , and $M$



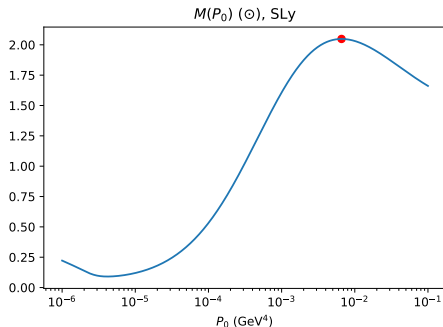
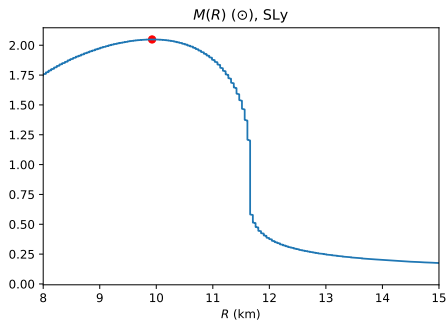
Three important values:

# Critical Values of $P$ , $R$ , and $M$



Three important values: *critical pressure*, *critical mass*, and *critical radius*.

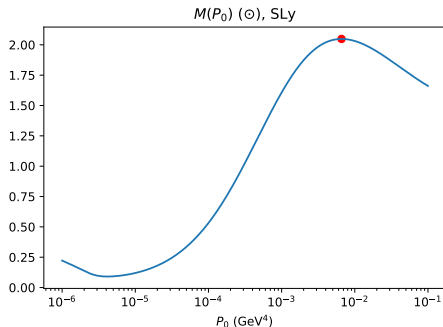
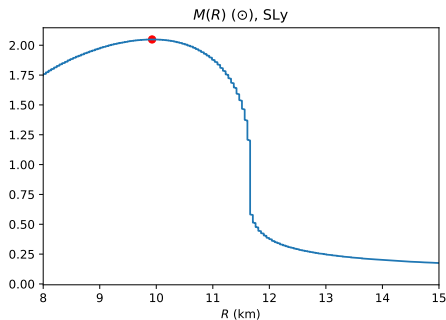
# Critical Values of $P$ , $R$ , and $M$



Three important values: *critical pressure*, *critical mass*, and *critical radius*.

- Determined by “peaks” of graph

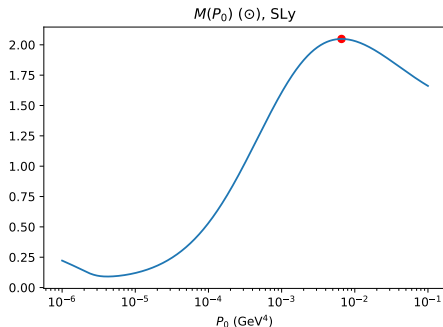
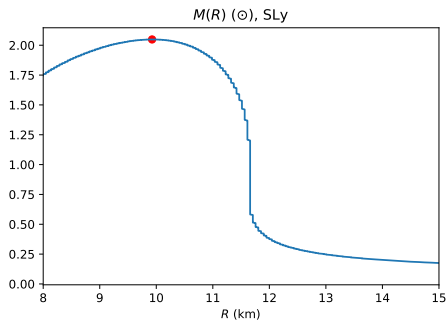
# Critical Values of $P$ , $R$ , and $M$



Three important values: *critical pressure*, *critical mass*, and *critical radius*.

- Determined by “peaks” of graph; calculated using an optimization routine

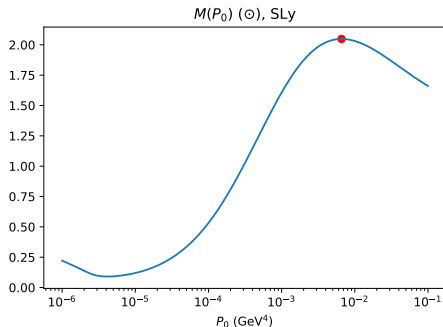
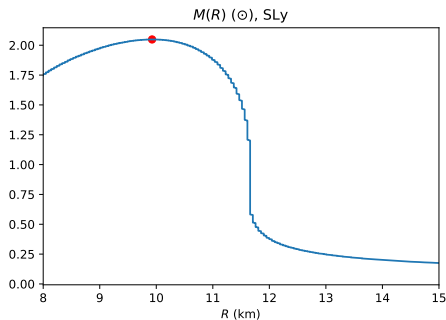
# Critical Values of $P$ , $R$ , and $M$



Three important values: *critical pressure*, *critical mass*, and *critical radius*.

- Determined by “peaks” of graph; calculated using an optimization routine
- Maximum mass and radius predicted by EoS

# Critical Values of $P$ , $R$ , and $M$

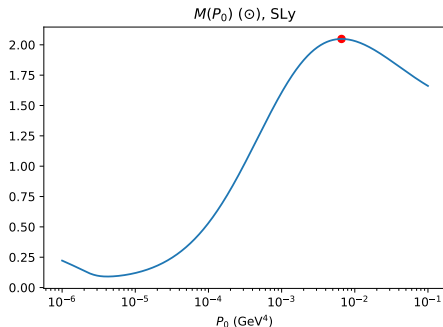
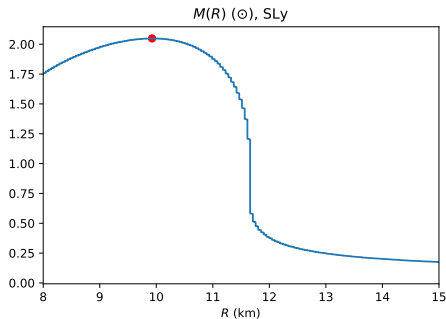


Three important values: *critical pressure*, *critical mass*, and *critical radius*.

- Determined by “peaks” of graph; calculated using an optimization routine
- Maximum mass and radius predicted by EoS
- Largest “stable” pressure



# Critical Values of $P$ , $R$ , and $M$



Three important values: *critical pressure*, *critical mass*, and *critical radius*.

- Determined by “peaks” of graph; calculated using an optimization routine
- Maximum mass and radius predicted by EoS
- Largest “stable” pressure
- SLy:  $M_{\text{max}} = 2.05 \odot$ ,  $R_{\text{max}} = 9.93 \text{ km}$ , and  $P_{\text{crit}} = 6.59 \times 10^{-3} \text{ GeV}^4$ .

# Predictions of Other Equations of State

# Predictions of Other Equations of State

There are other realistic, analytical fit EoSs of a similar form SLy given in [3, 5]:

# Predictions of Other Equations of State

There are other realistic, analytical fit EoSs of a similar form SLy given in [3, 5]: FPS, BSk19, BSk20, BSk21

# Predictions of Other Equations of State

There are other realistic, analytical fit EoSs of a similar form SLy given in [3, 5]: FPS, BSk19, BSk20, BSk21

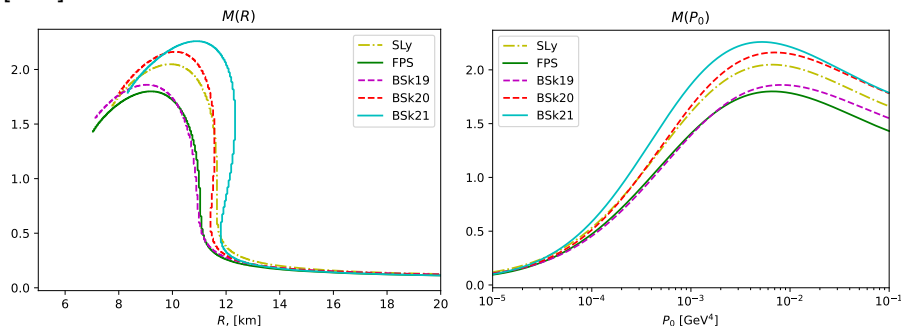


Figure:  $M(R)$  and  $M(P_0)$  for SLy family EoSs.  $M$  in  $\odot$ .

# Predictions of Other Equations of State

There are other realistic, analytical fit EoSs of a similar form SLy given in [3, 5]: FPS, BSk19, BSk20, BSk21

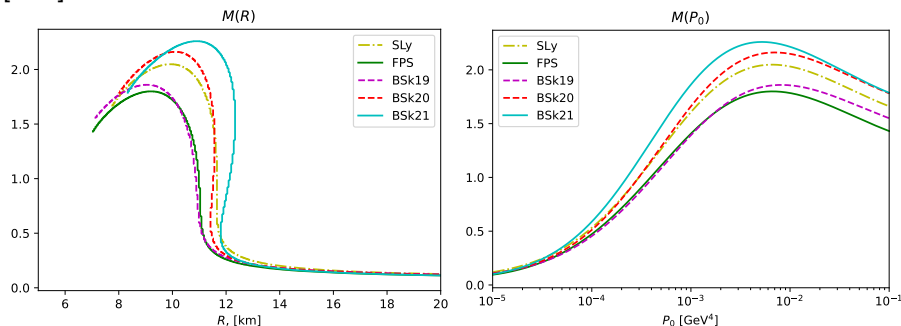


Figure:  $M(R)$  and  $M(P_0)$  for SLy family EoSs.  $M$  in  $\odot$ .

Critical values of the extreme EoSs:

# Predictions of Other Equations of State

There are other realistic, analytical fit EoSs of a similar form SLy given in [3, 5]: FPS, BSk19, BSk20, BSk21

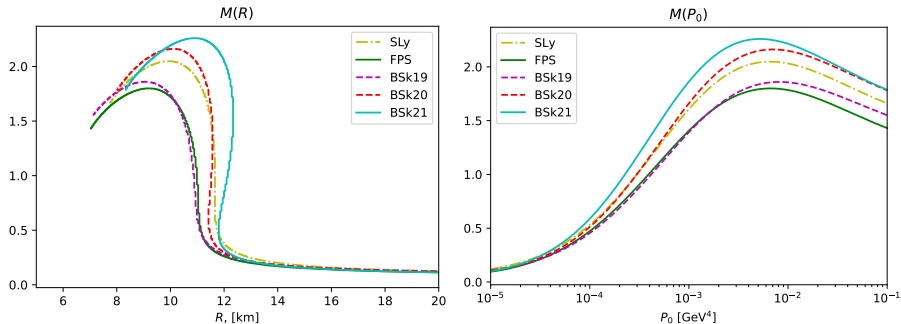


Figure:  $M(R)$  and  $M(P_0)$  for SLy family EoSs.  $M$  in  $\odot$ .

Critical values of the extreme EoSs:

- FPS:  $R_{\text{max}} = 9.20$  km,  $M_{\text{max}} = 1.80 \odot$ ,  $P_{\text{crit}} = 6.67 \times 10^{-3} \text{ GeV}^4$ .
- BSk21:  $R_{\text{max}} = 10.9$  km,  $M_{\text{max}} = 2.26 \odot$ ,  $P_{\text{crit}} = 5.17 \times 10^{-3} \text{ GeV}^4$ .

# Temporal Simulations of Neutron Stars



# Temporal Simulations of Neutron Stars: Background

# Temporal Simulations of Neutron Stars: Background

- Neutron star as a spherically symmetric hydrodynamical system

# Temporal Simulations of Neutron Stars: Background

- Neutron star as a spherically symmetric hydrodynamical system
- Three *primitive* variables: pressure  $P$ , energy density  $\epsilon$ , and velocity  $v$

# Temporal Simulations of Neutron Stars: Background

- Neutron star as a spherically symmetric hydrodynamical system
- Three *primitive* variables: pressure  $P$ , energy density  $\epsilon$ , and velocity  $v$
- $\epsilon$  and  $P$  related by an EoS

# Temporal Simulations of Neutron Stars: Background

- Neutron star as a spherically symmetric hydrodynamical system
- Three *primitive* variables: pressure  $P$ , energy density  $\epsilon$ , and velocity  $v$
- $\epsilon$  and  $P$  related by an EoS
- Define *conservative* variables  $\Pi, \Phi$  in terms of primitive variables

$$\Pi = \frac{\epsilon + P}{1 - v} - P, \quad \Phi = \frac{\epsilon + P}{1 + v} - P.$$

# Temporal Simulations of Neutron Stars: Background

- Neutron star as a spherically symmetric hydrodynamical system
- Three *primitive* variables: pressure  $P$ , energy density  $\epsilon$ , and velocity  $v$
- $\epsilon$  and  $P$  related by an EoS
- Define *conservative* variables  $\Pi, \Phi$  in terms of primitive variables

$$\Pi = \frac{\epsilon + P}{1 - v} - P, \quad \Phi = \frac{\epsilon + P}{1 + v} - P.$$

- $\Pi, \Phi$  obey a conservation equation

$$\partial_t \vec{u} = -\frac{1}{r^2} \partial_r \left( r^2 \frac{\alpha}{a} \vec{f}^{(1)} \right) - \partial_r \left( \frac{\alpha}{a} \vec{f}^{(2)} \right) + \vec{s}, \quad \vec{u} = \begin{bmatrix} \Pi \\ \Phi \end{bmatrix},$$

where  $a, \alpha$  are the *gravity* variables.

# Temporal Simulations of Neutron Stars: Background

- Neutron star as a spherically symmetric hydrodynamical system
- Three *primitive* variables: pressure  $P$ , energy density  $\epsilon$ , and velocity  $v$
- $\epsilon$  and  $P$  related by an EoS
- Define *conservative* variables  $\Pi, \Phi$  in terms of primitive variables

$$\Pi = \frac{\epsilon + P}{1 - v} - P, \quad \Phi = \frac{\epsilon + P}{1 + v} - P.$$

- $\Pi, \Phi$  obey a conservation equation

$$\partial_t \vec{u} = -\frac{1}{r^2} \partial_r \left( r^2 \frac{\alpha}{a} \vec{f}^{(1)} \right) - \partial_r \left( \frac{\alpha}{a} \vec{f}^{(2)} \right) + \vec{s}, \quad \vec{u} = \begin{bmatrix} \Pi \\ \Phi \end{bmatrix},$$

where  $a, \alpha$  are the *gravity* variables.

- $\vec{f}^{(1)} = \vec{f}^{(1)}(\vec{u}, v), \quad \vec{f}^{(2)} = \vec{f}^{(2)}(P), \quad \vec{s} = \vec{s}(\vec{u}, P, \epsilon, v, a, \alpha).$

# Temporal Simulations of Neutron Stars: Background

- Neutron star as a spherically symmetric hydrodynamical system
- Three *primitive* variables: pressure  $P$ , energy density  $\epsilon$ , and velocity  $v$
- $\epsilon$  and  $P$  related by an EoS
- Define *conservative* variables  $\Pi, \Phi$  in terms of primitive variables

$$\Pi = \frac{\epsilon + P}{1 - v} - P, \quad \Phi = \frac{\epsilon + P}{1 + v} - P.$$

- $\Pi, \Phi$  obey a conservation equation

$$\partial_t \vec{u} = -\frac{1}{r^2} \partial_r \left( r^2 \frac{\alpha}{a} \vec{f}^{(1)} \right) - \partial_r \left( \frac{\alpha}{a} \vec{f}^{(2)} \right) + \vec{s}, \quad \vec{u} = \begin{bmatrix} \Pi \\ \Phi \end{bmatrix},$$

where  $a, \alpha$  are the *gravity* variables.

- $\vec{f}^{(1)} = \vec{f}^{(1)}(\vec{u}, v)$ ,  $\vec{f}^{(2)} = \vec{f}^{(2)}(P)$ ,  $\vec{s} = \vec{s}(\vec{u}, P, \epsilon, v, a, \alpha)$ .
- Separate evolution equations for  $a, \alpha$



# Temporal Simulations of Neutron Stars: Background

# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques

# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques
  - ▶ Finite differencing (for spatial derivatives) and the method of lines

# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques
  - ▶ Finite differencing (for spatial derivatives) and the method of lines
  - ▶ High-resolution shock-capturing methods

# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques
  - ▶ Finite differencing (for spatial derivatives) and the method of lines
  - ▶ High-resolution shock-capturing methods
  - ▶ Evolve through time using numerical integration (Runge-Kutta 3, Modified Euler's Method)

# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques
  - ▶ Finite differencing (for spatial derivatives) and the method of lines
  - ▶ High-resolution shock-capturing methods
  - ▶ Evolve through time using numerical integration (Runge-Kutta 3, Modified Euler's Method)
- Use EoSs that are analytical fits for numerical stability and root-finding abilities

# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques
  - ▶ Finite differencing (for spatial derivatives) and the method of lines
  - ▶ High-resolution shock-capturing methods
  - ▶ Evolve through time using numerical integration (Runge-Kutta 3, Modified Euler's Method)
- Use EoSs that are analytical fits for numerical stability and root-finding abilities
  - ▶ Determine  $P, \epsilon, \nu$  numerically from  $\Pi, \Phi$

# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques
  - ▶ Finite differencing (for spatial derivatives) and the method of lines
  - ▶ High-resolution shock-capturing methods
  - ▶ Evolve through time using numerical integration (Runge-Kutta 3, Modified Euler's Method)
- Use EoSs that are analytical fits for numerical stability and root-finding abilities
  - ▶ Determine  $P, \epsilon, \nu$  numerically from  $\Pi, \Phi$ ; need to be able to differentiate (e.g. Newton-Raphson Method)



# Temporal Simulations of Neutron Stars: Background

- Evolve a set of discrete spatial gridpoints  $\rightarrow$  advanced numerical techniques
  - ▶ Finite differencing (for spatial derivatives) and the method of lines
  - ▶ High-resolution shock-capturing methods
  - ▶ Evolve through time using numerical integration (Runge-Kutta 3, Modified Euler's Method)
- Use EoSs that are analytical fits for numerical stability and root-finding abilities
  - ▶ Determine  $P, \epsilon, \nu$  numerically from  $\Pi, \Phi$ ; need to be able to differentiate (e.g. Newton-Raphson Method)
  - ▶ Extensive studies of realistic, analytical EoSs from [3, 5]; SLy family

# Temporal Simulations of Neutron Stars

# Temporal Simulations of Neutron Stars

- Use static solutions as initial data for temporal simulation

# Temporal Simulations of Neutron Stars

- Use static solutions as initial data for temporal simulation
  - ▶ Above *critical pressure*:

# Temporal Simulations of Neutron Stars

- Use static solutions as initial data for temporal simulation
  - ▶ Above *critical pressure*: unstable; below: stable

# Temporal Simulations of Neutron Stars

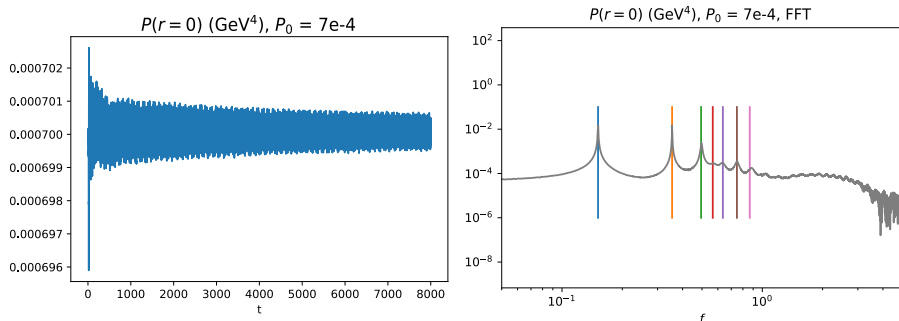
- Use static solutions as initial data for temporal simulation
  - ▶ Above *critical pressure*: unstable; below: stable
- Stable solutions exhibit *radial oscillations*

# Temporal Simulations of Neutron Stars

- Use static solutions as initial data for temporal simulation
  - ▶ Above *critical pressure*: unstable; below: stable
- Stable solutions exhibit *radial oscillations*
  - ▶ Evolve out to large  $t$  and perform a Fourier transform

# Temporal Simulations of Neutron Stars

- Use static solutions as initial data for temporal simulation
  - ▶ Above *critical pressure*: unstable; below: stable
- Stable solutions exhibit *radial oscillations*
  - ▶ Evolve out to large  $t$  and perform a Fourier transform

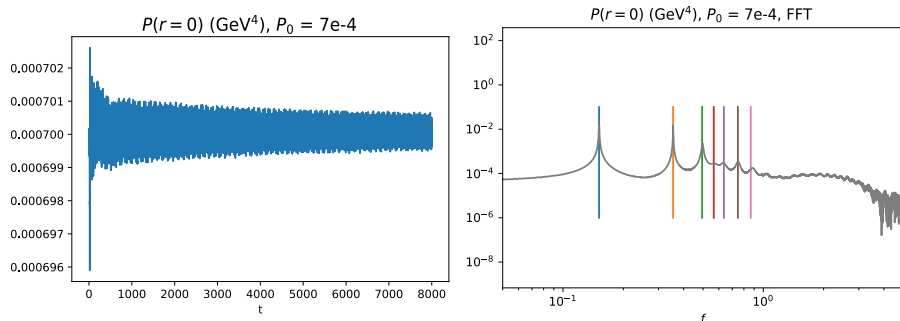


**Figure:** Plots of  $P(r=0)$  for EoS “SLy” and initial  $P_0 = 7 \times 10^{-4} \text{ GeV}^4$ . Colored lines on FFT plot represent predicted frequencies.



# Temporal Simulations of Neutron Stars

- Use static solutions as initial data for temporal simulation
  - ▶ Above *critical pressure*: unstable; below: stable
- Stable solutions exhibit *radial oscillations*
  - ▶ Evolve out to large  $t$  and perform a Fourier transform

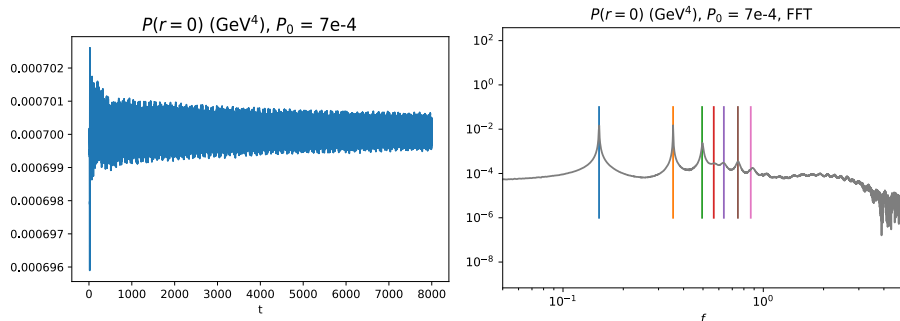


**Figure:** Plots of  $P(r=0)$  for EoS “SLy” and initial  $P_0 = 7 \times 10^{-4} \text{ GeV}^4$ . Colored lines on FFT plot represent predicted frequencies.

- Radial oscillations differ by EoS;

# Temporal Simulations of Neutron Stars

- Use static solutions as initial data for temporal simulation
  - ▶ Above *critical pressure*: unstable; below: stable
- Stable solutions exhibit *radial oscillations*
  - ▶ Evolve out to large  $t$  and perform a Fourier transform



**Figure:** Plots of  $P(r=0)$  for EoS “SLy” and initial  $P_0 = 7 \times 10^{-4} \text{ GeV}^4$ . Colored lines on FFT plot represent predicted frequencies.

- Radial oscillations differ by EoS; they could soon be measurable!

# Simulations of Neutron Stars: Nearing Publication

“Dynamical evolution of fermion-boson stars with realistic equations of state” under Prof. Ben Kain, College of the Holy Cross

# Simulations of Neutron Stars: Nearing Publication

“Dynamical evolution of fermion-boson stars with realistic equations of state” under Prof. Ben Kain, College of the Holy Cross

- Simulate presence of dark matter as a boson; superimpose a complex scalar field

# Simulations of Neutron Stars: Nearing Publication

“Dynamical evolution of fermion-boson stars with realistic equations of state” under Prof. Ben Kain, College of the Holy Cross

- Simulate presence of dark matter as a boson; superimpose a complex scalar field
- First temporal simulations of these “mixed” stars using *realistic* equations of state;

# Simulations of Neutron Stars: Nearing Publication

“Dynamical evolution of fermion-boson stars with realistic equations of state” under Prof. Ben Kain, College of the Holy Cross

- Simulate presence of dark matter as a boson; superimpose a complex scalar field
- First temporal simulations of these “mixed” stars using *realistic* equations of state; hope is to see how dark matter could affect observable properties of neutron stars

# Simulations of Neutron Stars: Nearing Publication

“Dynamical evolution of fermion-boson stars with realistic equations of state” under Prof. Ben Kain, College of the Holy Cross

- Simulate presence of dark matter as a boson; superimpose a complex scalar field
- First temporal simulations of these “mixed” stars using *realistic* equations of state; hope is to see how dark matter could affect observable properties of neutron stars
- Interesting finding: there is a range of unstable static solutions that *migrate* to stable solutions

# Derivation and Computation of an Equation of State



# Computing an EoS: Quantum Hadrodynamics

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)
  - ▶ *mesons* are quark/anti-quark pairs

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)
  - ▶ *mesons* are quark/anti-quark pairs
- Requires experimental input for constraint;

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)
  - ▶ *mesons* are quark/anti-quark pairs
- Requires experimental input for constraint; implemented using *coupling constants*

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)
  - ▶ *mesons* are quark/anti-quark pairs
- Requires experimental input for constraint; implemented using *coupling constants*
  - ▶ Models the strength of the interactions between particles



# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)
  - ▶ *mesons* are quark/anti-quark pairs
- Requires experimental input for constraint; implemented using *coupling constants*
  - ▶ Models the strength of the interactions between particles
  - ▶ Multiple *parameter sets* have been developed by fitting observed nuclear properties of nuclear matter

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)
  - ▶ *mesons* are quark/anti-quark pairs
- Requires experimental input for constraint; implemented using *coupling constants*
  - ▶ Models the strength of the interactions between particles
  - ▶ Multiple *parameter sets* have been developed by fitting observed nuclear properties of nuclear matter
- Considered quite complicated to solve

# Computing an EoS: Quantum Hadrodynamics

A theory of the quantum mechanical, interparticle interactions within a neutron star.

- Formulation of nuclear interactions between *baryons* by the exchange of *mesons*
  - ▶ *baryons* are particles containing three quarks (e.g. protons, neutrons)
  - ▶ *mesons* are quark/anti-quark pairs
- Requires experimental input for constraint; implemented using *coupling constants*
  - ▶ Models the strength of the interactions between particles
  - ▶ Multiple *parameter sets* have been developed by fitting observed nuclear properties of nuclear matter
- Considered quite complicated to solve; we introduce some simplifications in the QHD-I model

# Quantum Hadrodynamics I (QHD-I)

We form the Lagrange Density for QHD-I:

# Quantum Hadrodynamics I (QHD-I)

We form the Lagrange Density for QHD-I:

$$\mathcal{L} = \bar{\psi}[\gamma_{\mu}(i\partial^{\mu} - g_v V^{\mu}) - (M - g_{\phi}\phi)]\psi \\ + \frac{1}{2}(\partial_{\mu}\phi\partial^{\mu}\phi - m_{\phi}^2\phi^2) - \frac{1}{4}V_{\mu\nu}V^{\mu\nu} + \frac{1}{2}m_v^2V_{\mu}V^{\mu},$$

where  $V_{\mu\nu} \equiv \partial_{\mu}V_{\nu} - \partial_{\nu}V_{\mu}$ ,  $\partial_{\mu} \equiv \partial/\partial x^{\mu}$ . The fields:

- Baryon field (protons and neutrons)  $\psi(x^{\mu})$ , with mass  $M$
- Scalar meson field:  $\phi(x^{\mu})$ , with mass  $m_{\phi}$
- Vector meson field:  $V^{\mu}(x^{\mu})$ , with mass  $m_v$
- Experimental coupling constants:  $g_v$  and  $g_{\phi}$

# Quantum Hadrodynamics I (QHD-I)

We form the Lagrange Density for QHD-I:

$$\mathcal{L} = \bar{\psi}[\gamma_{\mu}(i\partial^{\mu} - g_v V^{\mu}) - (M - g_{\phi}\phi)]\psi \\ + \frac{1}{2}(\partial_{\mu}\phi\partial^{\mu}\phi - m_{\phi}^2\phi^2) - \frac{1}{4}V_{\mu\nu}V^{\mu\nu} + \frac{1}{2}m_v^2V_{\mu}V^{\mu},$$

where  $V_{\mu\nu} \equiv \partial_{\mu}V_{\nu} - \partial_{\nu}V_{\mu}$ ,  $\partial_{\mu} \equiv \partial/\partial x^{\mu}$ . The fields:

- Baryon field (protons and neutrons)  $\psi(x^{\mu})$ , with mass  $M$
- Scalar meson field:  $\phi(x^{\mu})$ , with mass  $m_{\phi}$
- Vector meson field:  $V^{\mu}(x^{\mu})$ , with mass  $m_v$
- Experimental coupling constants:  $g_v$  and  $g_{\phi}$

From  $\mathcal{L}$ , we can determine  $\epsilon$  and  $P$ , the EoS we desire.

# QHD-I: Derivation of Equations of Motion

$$\begin{aligned}\mathcal{L} = & \bar{\psi}[\gamma_{\mu}(i\partial^{\mu} - g_v V^{\mu}) - (M - g_{\phi}\phi)]\psi \\ & + \frac{1}{2}(\partial_{\mu}\phi\partial^{\mu}\phi - m_{\phi}^2\phi^2) - \frac{1}{4}V_{\mu\nu}V^{\mu\nu} + \frac{1}{2}m_v^2V_{\mu}V^{\mu},\end{aligned}$$

# QHD-I: Derivation of Equations of Motion

$$\begin{aligned}\mathcal{L} = & \bar{\psi}[\gamma_{\mu}(i\partial^{\mu} - g_v V^{\mu}) - (M - g_{\phi}\phi)]\psi \\ & + \frac{1}{2}(\partial_{\mu}\phi\partial^{\mu}\phi - m_{\phi}^2\phi^2) - \frac{1}{4}V_{\mu\nu}V^{\mu\nu} + \frac{1}{2}m_v^2V_{\mu}V^{\mu},\end{aligned}$$

Applying the Euler-Lagrange equations for  $\mathcal{L}$  over a classical field

$$\partial_{\nu}\left(\frac{\partial\mathcal{L}}{\partial(\partial_{\nu}\varphi_{\alpha})}\right) - \frac{\partial\mathcal{L}}{\partial\varphi_{\alpha}} = 0,$$

for  $\varphi_{\alpha} \in \{\phi, V^{\mu}, \psi\}$ ,



# QHD-I: Derivation of Equations of Motion

$$\begin{aligned}\mathcal{L} = & \bar{\psi}[\gamma_{\mu}(i\partial^{\mu} - g_v V^{\mu}) - (M - g_{\phi}\phi)]\psi \\ & + \frac{1}{2}(\partial_{\mu}\phi\partial^{\mu}\phi - m_{\phi}^2\phi^2) - \frac{1}{4}V_{\mu\nu}V^{\mu\nu} + \frac{1}{2}m_v^2 V_{\mu}V^{\mu},\end{aligned}$$

Applying the Euler-Lagrange equations for  $\mathcal{L}$  over a classical field

$$\partial_{\nu}\left(\frac{\partial\mathcal{L}}{\partial(\partial_{\nu}\varphi_{\alpha})}\right) - \frac{\partial\mathcal{L}}{\partial\varphi_{\alpha}} = 0,$$

for  $\varphi_{\alpha} \in \{\phi, V^{\mu}, \psi\}$ , we obtain the equations of motion:

$$\begin{aligned}\partial_{\nu}\partial^{\nu}\phi + m_s^2\phi &= g_s\bar{\psi}\psi, \\ \partial_{\mu}V^{\mu\nu} + m_{\omega}^2V^{\nu} &= g_v\bar{\psi}\gamma^{\nu}\psi, \\ [\gamma_{\mu}(i\partial^{\mu} - g_v V^{\mu}) - (M - g_s\phi)]\psi &= 0,\end{aligned}$$

# QHD-I: RMF Simplifications

We introduce the *Relativistic Mean Field* (RMF) simplifications.

# QHD-I: RMF Simplifications

We introduce the *Relativistic Mean Field* (RMF) simplifications. We treat the interactions (exchange of mesons) as their average values:

# QHD-I: RMF Simplifications

We introduce the *Relativistic Mean Field* (RMF) simplifications. We treat the interactions (exchange of mesons) as their average values:

$$\phi \rightarrow \langle \phi \rangle = \phi_0, \quad V_\mu \rightarrow \langle V_\mu \rangle = V_0, \quad \bar{\psi}\psi \rightarrow \langle \bar{\psi}\psi \rangle, \quad \bar{\psi}\gamma^\mu\psi \rightarrow \langle \bar{\psi}\gamma^0\psi \rangle,$$

where  $\phi_0$  and  $V_0$  are constants.

# QHD-I: RMF Simplifications

We introduce the *Relativistic Mean Field* (RMF) simplifications. We treat the interactions (exchange of mesons) as their average values:

$$\phi \rightarrow \langle \phi \rangle = \phi_0, \quad V_\mu \rightarrow \langle V_\mu \rangle = V_0, \quad \bar{\psi}\psi \rightarrow \langle \bar{\psi}\psi \rangle, \quad \bar{\psi}\gamma^\mu\psi \rightarrow \langle \bar{\psi}\gamma^0\psi \rangle,$$

where  $\phi_0$  and  $V_0$  are constants. This allows us to simplify  $\mathcal{L}$  considerably:

## QHD-I: RMF Simplifications

We introduce the *Relativistic Mean Field* (RMF) simplifications. We treat the interactions (exchange of mesons) as their average values:

$$\phi \rightarrow \langle \phi \rangle = \phi_0, \quad V_\mu \rightarrow \langle V_\mu \rangle = V_0, \quad \bar{\psi}\psi \rightarrow \langle \bar{\psi}\psi \rangle, \quad \bar{\psi}\gamma^\mu\psi \rightarrow \langle \bar{\psi}\gamma^0\psi \rangle,$$

where  $\phi_0$  and  $V_0$  are constants. This allows us to simplify  $\mathcal{L}$  considerably:

$$\mathcal{L}_{\text{RMF}} = \bar{\psi}[i\gamma_\mu\partial^\mu - g_v\gamma_0V_0 - (M - g_s\phi_0)]\psi - \frac{1}{2}m_s^2\phi_0^2 + \frac{1}{2}m_\omega^2V_0^2,$$

## QHD-I: RMF Simplifications

We introduce the *Relativistic Mean Field* (RMF) simplifications. We treat the interactions (exchange of mesons) as their average values:

$$\phi \rightarrow \langle \phi \rangle = \phi_0, \quad V_\mu \rightarrow \langle V_\mu \rangle = V_0, \quad \bar{\psi}\psi \rightarrow \langle \bar{\psi}\psi \rangle, \quad \bar{\psi}\gamma^\mu\psi \rightarrow \langle \bar{\psi}\gamma^0\psi \rangle,$$

where  $\phi_0$  and  $V_0$  are constants. This allows us to simplify  $\mathcal{L}$  considerably:

$$\mathcal{L}_{\text{RMF}} = \bar{\psi}[i\gamma_\mu\partial^\mu - g_v\gamma_0V_0 - (M - g_s\phi_0)]\psi - \frac{1}{2}m_s^2\phi_0^2 + \frac{1}{2}m_\omega^2V_0^2,$$

Applying the same simplifications to the equations of motions gives:

$$m_s^2\phi_0^2 = g_s \langle \bar{\psi}\psi \rangle$$

$$m_\omega^2V_0 = g_v \langle \bar{\psi}\gamma^0\psi \rangle$$

$$[i\gamma_\mu\partial^\mu - g_v\gamma_0V_0 - (M - g_s\phi_0)]\psi = 0$$

# QHD-I: Solving for $\epsilon$ and $P$



## QHD-I: Solving for $\epsilon$ and $P$

We can now solve for  $\epsilon$  and  $P$ .

## QHD-I: Solving for $\epsilon$ and $P$

We can now solve for  $\epsilon$  and  $P$ . From [1], we have

$$\epsilon = \langle T^{00} \rangle, \quad P = \frac{1}{3} \langle T^{ii} \rangle,$$

where  $T^{\mu\nu}$  is the energy momentum tensor, given by

$$T^{\mu\nu} = \frac{\partial \mathcal{L}}{\partial(\partial_\mu \varphi_\alpha)} \partial^\nu \varphi_\alpha - \mathcal{L} \eta^{\mu\nu}.$$

## QHD-I: Solving for $\epsilon$ and $P$

We can now solve for  $\epsilon$  and  $P$ . From [1], we have

$$\epsilon = \langle T^{00} \rangle, \quad P = \frac{1}{3} \langle T^{ii} \rangle,$$

where  $T^{\mu\nu}$  is the energy momentum tensor, given by

$$T^{\mu\nu} = \frac{\partial \mathcal{L}}{\partial(\partial_\mu \varphi_\alpha)} \partial^\nu \varphi_\alpha - \mathcal{L} \eta^{\mu\nu}.$$

Using  $\mathcal{L}_{\text{RMF}}$ , we obtain

$$T_{\text{RMF}}^{\mu\nu} = i\bar{\psi}\gamma^\mu\partial^\nu\psi - \eta^{\mu\nu}\left(-\frac{1}{2}m_s^2\phi_0^2 + \frac{1}{2}m_\omega^2V_0^2\right).$$

## QHD-I: Solving for $\epsilon$ and $P$

We can now solve for  $\epsilon$  and  $P$ . From [1], we have

$$\epsilon = \langle T^{00} \rangle, \quad P = \frac{1}{3} \langle T^{ii} \rangle,$$

where  $T^{\mu\nu}$  is the energy momentum tensor, given by

$$T^{\mu\nu} = \frac{\partial \mathcal{L}}{\partial(\partial_\mu \varphi_\alpha)} \partial^\nu \varphi_\alpha - \mathcal{L} \eta^{\mu\nu}.$$

Using  $\mathcal{L}_{\text{RMF}}$ , we obtain

$$T_{\text{RMF}}^{\mu\nu} = i\bar{\psi}\gamma^\mu\partial^\nu\psi - \eta^{\mu\nu}\left(-\frac{1}{2}m_s^2\phi_0^2 + \frac{1}{2}m_\omega^2V_0^2\right).$$

This gives

$$\begin{aligned}\epsilon &= \langle i\bar{\psi}\gamma^0\partial^0\psi \rangle + \frac{1}{2}m_s^2\phi_0^2 - \frac{1}{2}m_\omega^2V_0^2, \\ P &= \langle i\bar{\psi}\gamma^i\partial^i\psi \rangle - \frac{1}{2}m_s^2\phi_0^2 + \frac{1}{2}m_\omega^2V_0^2.\end{aligned}$$

## QHD-I: Solving for $\epsilon$ and $P$

We can now solve for  $\epsilon$  and  $P$ . From [1], we have

$$\epsilon = \langle T^{00} \rangle, \quad P = \frac{1}{3} \langle T^{ii} \rangle,$$

where  $T^{\mu\nu}$  is the energy momentum tensor, given by

$$T^{\mu\nu} = \frac{\partial \mathcal{L}}{\partial(\partial_\mu \varphi_\alpha)} \partial^\nu \varphi_\alpha - \mathcal{L} \eta^{\mu\nu}.$$

Using  $\mathcal{L}_{\text{RMF}}$ , we obtain

$$T_{\text{RMF}}^{\mu\nu} = i\bar{\psi}\gamma^\mu \partial^\nu \psi - \eta^{\mu\nu} \left( -\frac{1}{2} m_s^2 \phi_0^2 + \frac{1}{2} m_\omega^2 V_0^2 \right).$$

This gives

$$\begin{aligned} \epsilon &= \langle i\bar{\psi}\gamma^0 \partial^0 \psi \rangle + \frac{1}{2} m_s^2 \phi_0^2 - \frac{1}{2} m_\omega^2 V_0^2, \\ P &= \langle i\bar{\psi}\gamma^i \partial^i \psi \rangle - \frac{1}{2} m_s^2 \phi_0^2 + \frac{1}{2} m_\omega^2 V_0^2. \end{aligned}$$

The above expectation values are non-trivial and are derived in [1].

# QHD-I: Resulting Equations

# QHD-I: Resulting Equations

After calculation the expectation values, we obtain the following equations:

# QHD-I: Resulting Equations

After calculation the expectation values, we obtain the following equations:

$$\phi_0 = \frac{g_\phi}{m_\phi^2} \frac{1}{\pi^2} \int_0^{k_f} dk \frac{(M - g_\phi \phi_0) k^2}{\sqrt{k^2 + (M - g_\phi \phi_0)}},$$

$$V_0 = \frac{g_v}{m_v^2} \frac{k_f^3}{3\pi^2},$$

$$\epsilon = \frac{1}{2} m_\phi^2 \phi_0^2 + \frac{1}{2} m_v^2 V_0^2 + \frac{1}{\pi^2} \int_0^{k_f} dk k^2 \sqrt{k^2 + m^{*2}},$$

$$P = -\frac{1}{2} m_\phi^2 \phi_0^2 + \frac{1}{2} m_v^2 V_0^2 + \frac{1}{3} \left( \frac{1}{\pi^2} \int_0^{k_f} dk \frac{k^4}{\sqrt{k^2 + m^{*2}}} \right).$$

where  $m^* = (M - g_\phi \phi)$ , the *reduced mass*.



## QHD-I: Resulting Equations

After calculation the expectation values, we obtain the following equations:

$$\phi_0 = \frac{g_\phi}{m_\phi^2} \frac{1}{\pi^2} \int_0^{k_f} dk \frac{(M - g_\phi \phi_0) k^2}{\sqrt{k^2 + (M - g_\phi \phi_0)}},$$

$$V_0 = \frac{g_v}{m_v^2} \frac{k_f^3}{3\pi^2},$$

$$\epsilon = \frac{1}{2} m_\phi^2 \phi_0^2 + \frac{1}{2} m_v^2 V_0^2 + \frac{1}{\pi^2} \int_0^{k_f} dk k^2 \sqrt{k^2 + m^{*2}},$$

$$P = -\frac{1}{2} m_\phi^2 \phi_0^2 + \frac{1}{2} m_v^2 V_0^2 + \frac{1}{3} \left( \frac{1}{\pi^2} \int_0^{k_f} dk \frac{k^4}{\sqrt{k^2 + m^{*2}}} \right).$$

where  $m^* = (M - g_\phi \phi)$ , the *reduced mass*.  $k_f$ , the Fermi wavenumber, is a free parameter.

# Resulting Equations

# Resulting Equations

Goal:

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ;

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

To produce the EoS:

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

To produce the EoS: (repeat the following)

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

To produce the EoS: (repeat the following)

- Choose a  $k_f$  value



# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

To produce the EoS: (repeat the following)

- Choose a  $k_f$  value
- calculate  $\phi_0$  and  $V_0$

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

To produce the EoS: (repeat the following)

- Choose a  $k_f$  value
- calculate  $\phi_0$  and  $V_0$ ; use *rootfinding* for  $\phi_0$

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

To produce the EoS: (repeat the following)

- Choose a  $k_f$  value
- calculate  $\phi_0$  and  $V_0$ ; use *rootfinding* for  $\phi_0$
- Using those values, calculate  $P$  and  $\epsilon$  and store in a table

# Resulting Equations

Goal: create a list of values that show us  $\epsilon(P)$ ; each value of  $k_f$  gives us a different  $\epsilon$  and  $P$ .

To produce the EoS: (repeat the following)

- Choose a  $k_f$  value
- calculate  $\phi_0$  and  $V_0$ ; use *rootfinding* for  $\phi_0$
- Using those values, calculate  $P$  and  $\epsilon$  and store in a table

We loop through  $k_f$  values until we have a large range of  $P$  values

$$P \in [10^{-20}, 10^{-1}](\text{GeV}^4).$$

# $M(R)$ and $M(P_0)$ Curves for QHD-I

We use the tabulated values of  $P$  and  $\epsilon$  to solve the TOV equations:

# $M(R)$ and $M(P_0)$ Curves for QHD-I

We use the tabulated values of  $P$  and  $\epsilon$  to solve the TOV equations:

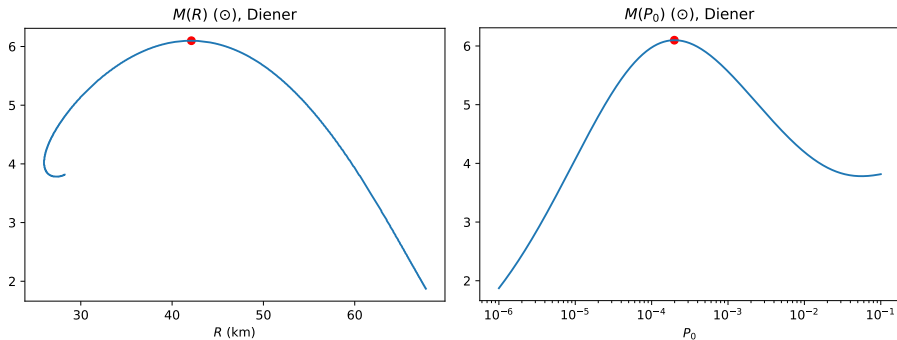


Figure:  $M(R)$  and  $M(P_0)$  curves for QHD-I EoS.

# $M(R)$ and $M(P_0)$ Curves for QHD-I

We use the tabulated values of  $P$  and  $\epsilon$  to solve the TOV equations:

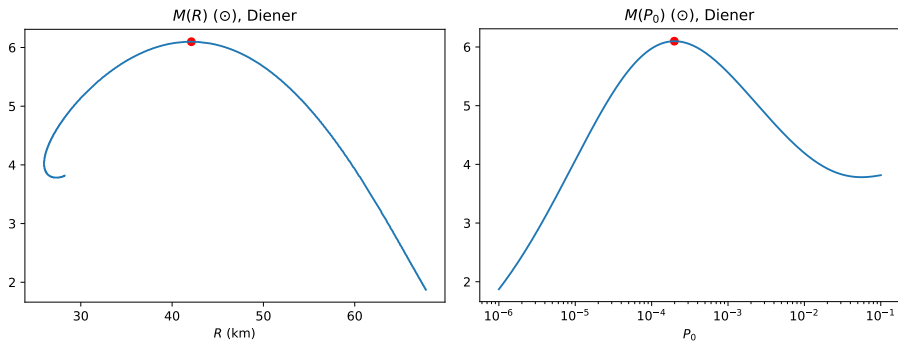


Figure:  $M(R)$  and  $M(P_0)$  curves for QHD-I EoS.

These curves give

$$M_{\text{max}} = 6.1 \odot, \quad R_{\text{max}} = 42.1 \text{ km}, \quad P_{\text{crit}} = 1.98 \times 10^{-4} \text{ GeV}^4.$$

# Conclusion

- An equation of state is a relationship between energy density and pressure within a neutron star



# Conclusion

- An equation of state is a relationship between energy density and pressure within a neutron star
- We use the TOV equations to predict the maximum mass and radius that a given EoS will produce

# Conclusion

- An equation of state is a relationship between energy density and pressure within a neutron star
- We use the TOV equations to predict the maximum mass and radius that a given EoS will produce
- Within a temporal simulation of a neutron star:

# Conclusion

- An equation of state is a relationship between energy density and pressure within a neutron star
- We use the TOV equations to predict the maximum mass and radius that a given EoS will produce
- Within a temporal simulation of a neutron star:
  - ▶ Static solutions are used as initial data

# Conclusion

- An equation of state is a relationship between energy density and pressure within a neutron star
- We use the TOV equations to predict the maximum mass and radius that a given EoS will produce
- Within a temporal simulation of a neutron star:
  - ▶ Static solutions are used as initial data
  - ▶ We can predict radial oscillation frequencies of neutron stars, which could soon be measurable

# Conclusion

- An equation of state is a relationship between energy density and pressure within a neutron star
- We use the TOV equations to predict the maximum mass and radius that a given EoS will produce
- Within a temporal simulation of a neutron star:
  - ▶ Static solutions are used as initial data
  - ▶ We can predict radial oscillation frequencies of neutron stars, which could soon be measurable
- We use the QHD-I parameter set and RMF simplifications to solve a system of equations and generate an equation of state

# References I



Jacobus Petrus William Diener. “Relativistic mean-field theory applied to the study of neutron star properties”. *PhD thesis*. Stellenbosch University, 2008.



Norman K. Glendenning. *Compact Stars*. Springer, 1997.



P. Haensel and A. Y. Potekhin. “Analytical representations of unified equations of state of neutron-star matter”. In: *Astronomy & Astrophysics* 428.1 (Nov. 2004), pp. 191–197. ISSN: 1432-0746. DOI: 10.1051/0004-6361:20041722. URL: <http://dx.doi.org/10.1051/0004-6361:20041722>.



“Neutron Stars”. In: *COSMOS - The SAO Encyclopedia of Astronomy*. URL: <https://astronomy.swin.edu.au/cosmos/n/neutron+star#:~:text=Neutrons%20stars%20are%20extreme%20objects,weigh%20around%20a%20billion%20tonnes..>



A. Y. Potekhin et al. “Analytical representations of unified equations of state for neutron-star matter”. In: *Astronomy & Astrophysics* 560 (Dec. 2013), A48. ISSN: 1432-0746. DOI: [10.1051/0004-6361/201321697](https://doi.org/10.1051/0004-6361/201321697). URL: <http://dx.doi.org/10.1051/0004-6361/201321697>.