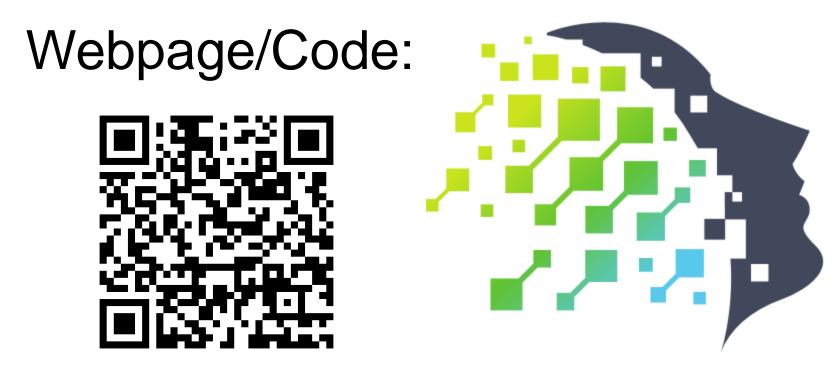


ALBAR: Adversarial Learning approach to mitigate Biases in Action Recognition

Joseph Fioresi, Ishan Rajendrakumar Dave, Mubarak Shah University of Central Florida

https://joefioresi718.github.io/ALBAR\_webpage/





# **Bias in Action Recognition**

- Video action recognition models improperly exploit both background & foreground cues over motion information.
- ❖ Below figure: (a) background change → misclassification, (b) adding motion does not overcome foreground bias.

#### Contributions

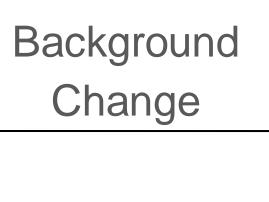
- We propose a novel adversarial setup that uses a static (no motion) clip passed through the same encoder model.
- Designed supplemental static input entropy maximization and gradient penalty objectives to stabilize training.
- ❖ ALBAR achieves SOTA combined debiasing scores on 3 major AR datasets: UCF101, HMDB51, and Kinetics400.
- ❖ Propose a background leakage fix for UCF101 protocol.

# **Background/Foreground Bias**



Baseline Prediction: TennisSwing

ALBAR Prediction: TennisSwing



Baseline Prediction: HorseRiding ALBAR Prediction: TennisSwing

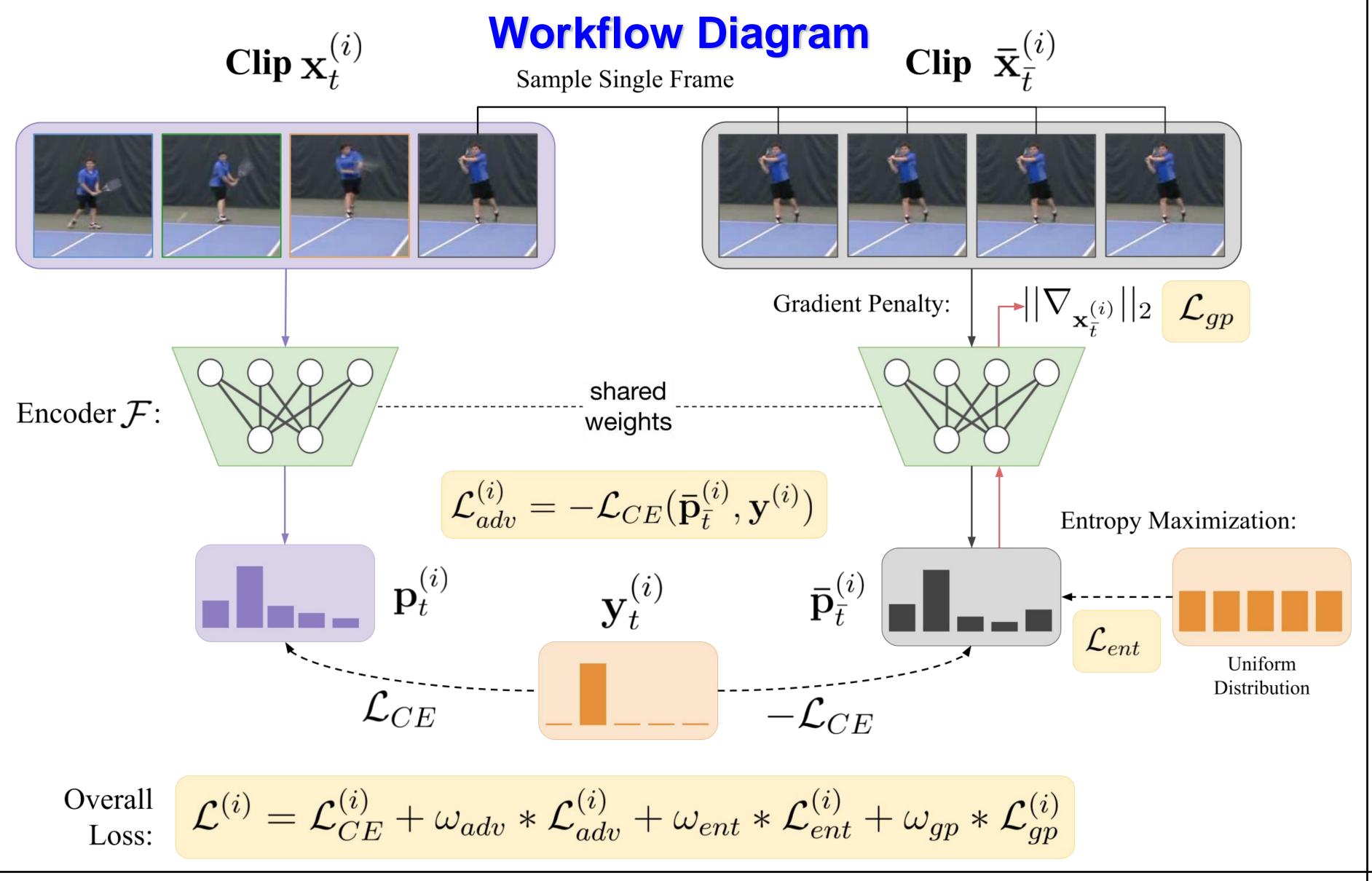
Single Frame – No Motion



Add Motion



Baseline: passing American football (in game) Baseline: passing American football (in game) ALBAR Prediction: ??? (shot put) **ALBAR Prediction: archery** 



## **Comparison With Prior Works (HMDB51)**

Debiasing Method	Original	OOD			
		SCUBA (个)	SCUFO (↓)	Confl-FG (个)	Contra. Acc.
None	73.92	43.93	20.46	36.58	27.84
Mixup [1] ICLR'18	74.58	43.10	21.17	36.62	26.09
VideoMix [2] arXiv'20	73.31	39.39	20.44	32.68	23.13
SDN [3] NeurIPS'19	<u>74.66</u>	40.02	20.22	34.87	22.88
BE [4] CVPR'21	74.31	43.56	19.96	35.99	27.84
ActorCutMix [5] cv1U'23	74.05	46.79	22.07	36.97	28.12
FAME [6] CVPR'22	73.79	51.40	26.92	39.61	29.66
StillMix [7] ICCV'23	74.82	51.81	13.39	47.38	40.28
Ours	73.20	<b>53.2 ↑</b> 21.1%	<b>0.42</b> \$\square\$98.0\%	49.84 ↑36.3%	<b>53.02 ↑</b> 90.5%

#### **Loss Descriptions**

#### Baseline – Cross-Entropy:

 $\mathcal{L}_{CE}^{(i)} = -\sum_{\mathbf{1}}^{N_C} \mathbf{y}_c^{(i)} \log \mathbf{p}_c^{(i)}$ 

Standard action classification, susceptible to bias

Adversarial Loss – Static Inputs:

$$\mathcal{L}_{adv}^{(i)} = -\mathcal{L}_{CE}(\mathbf{ar{p}}_{ar{t}}^{(i)}, \mathbf{y}^{(i)})$$

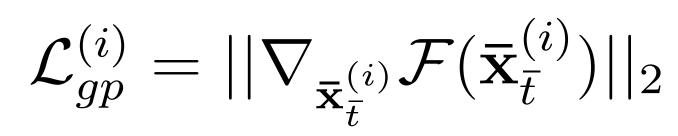
- Negative cross-entropy of <u>static</u> clip prediction
- Leads to class flipping trivial solution on its own

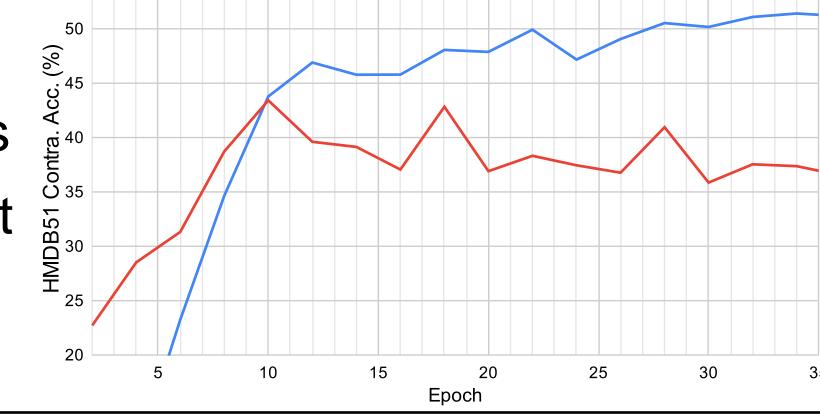
# Static Entropy Maximization:

- $\mathcal{L}_{ ext{ent}}^{(i)} = \sum_{ar{t},c} |ar{\mathbf{p}}_{ar{t},c}^{(i)} \log(ar{\mathbf{p}}_{ar{t},c}^{(i)})|$ Encourages uncertainty in static clip prediction
- Mitigates adversarial trivial solution

#### **Static Gradient Penalty:**

- Static inputs: drastic weight updates
- Regularize gradients, reduce impact





# **Downstream Task Performance**

Method	Action Recognition HMDB51 (OOD)	Anomaly Detection UCF_Crime	Temporal Action Localization THUMOS14
Baseline	27.84	82.39	54.89
Ours	53.02	84.91	55.20

### **UCF101 SCUBA/SCUFO Protocol Fix**



