

# N-body simulations of the Self-Confinement of Viscous Self-Gravitating Narrow Eccentric Planetary Ringlets

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## ABSTRACT

N-body simulations are used to illustrate how a viscous self-gravitating narrow eccentric planetary ringlet can evolve into a self-confining state.

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## 1. INTRODUCTION

Narrow eccentric planetary ringlets have properties both interesting and not well understood: sharp edges, sizable eccentricity gradients, and a confinement mechanism that opposes radial spreading due to ring viscosity. To date, nearly all of the prevailing ringlet confinement mechanisms assume that there also exists a pair of unseen shepherd satellites that straddle the ringlet, with those shepherds' gravities also torquing the ringlet's edges' in a way that keeps it radially confined (Goldreich & Tremaine 1979a,b, 1981; Chiang & Goldreich 2000; Mosqueira & Estrada 2002). However the Cassini spacecraft failed to detect any such shepherds near Saturn's narrow ringlets, which casts doubt upon that confinement mechanism (Longaretti 2018). Note though that Borderies et al. (1982) showed that a viscous ringlet that has a sufficiently high eccentricity gradient can in fact be self-confining, due to the resulting reversal of the viscous angular momentum flux. Which motivates this study, which uses the `epi.int_lite` N-body integrator to investigate whether a viscous and self-gravitating ringlet might evolve into a self-confining state.

## 2. EPI.INT.LITE

`Epi.int_lite` is a child of the `epi.int` N-body integrator that was used to simulate the outer edge of Saturn's B ring while it is sculpted by satellite perturbations (Hahn & Spitale 2013). The new code is very similar to its parent but differs in two significant ways: (*i.*) `epi.int_lite` is written in python and is recoded for more efficient execution, and (*ii.*) `epi.int_lite` uses a more reliable drift step to handle unperturbed motion around an oblate planet (detailed in Appendix A).

Otherwise `epi_int_lite`'s treatment of ring self-gravity and viscosity are identical to that used by the parent code, see [Hahn & Spitale \(2013\)](#) for additional details. The `epi_int_lite` source code is available at [https://github.com/joehahn/epi\\_int\\_lite](https://github.com/joehahn/epi_int_lite), and the code's numerical quality is benchmarked in Appendix C where the output of several numerical experiments are compared against theoretical expectations.

Calculations by `epi_int_lite` use natural units with gravitation constant  $G = 1$ , central primary mass  $M = 1$ , and the ringlet's inner edge has initial radius  $r_0 = 1$ , and so the ringlet masses  $m_r$  and radii  $r$  quoted below are in units of  $M$  and  $r_0$ . Converting code output from natural units to physical units requires choosing physical values for  $M$  and  $r_0$  and multiplying accordingly, and when this text does so it assumes Saturn's mass  $M = 5.68 \times 10^{29}$  gm and a characteristic ring radius  $r_0 = 1.0 \times 10^{10}$  cm. Simulation time  $t$  is in units of  $T_{\text{orb}}/2\pi$  where  $T_{\text{orb}} = 2\pi\sqrt{r_0^3/GM}$  is the orbit period at  $r_0$ , so divide simulation time  $t$  by  $2\pi$  and multiply by  $T_{\text{orb}}$  to convert simulation time from natural to physical units. The simulated particles' motions during the drift step are also sensitive to the  $J_2$  portion of the primary's non-spherical gravity component (see Appendix A), and all simulations adopt Saturn-like values of  $J_2 = 0.01$  and  $R_p = r_0/2$  where  $R_p$  is the planet's mean radius.

### 2.1. streamlines

Initially all particles are assigned to various streamlines across the simulated ringlet. A streamline is a closed eccentric path around the primary, and each streamline is populated by  $N_p$  particles that are initially assigned a common semimajor axis  $a$  and eccentricity  $e$  while distributed uniformly in longitude. Most of the simulations described below employ only  $N_s = 2$  streamlines, so that the model output can be compared against theoretical treatments that also treat the ringlet as two gravitating streamlines (e.g. [Borderies et al. 1983](#)). But the following also performs a few higher-resolution simulations using  $N_s = 5 - 31$  streamlines, to demonstrate that the  $N_s = 2$  treatment is perfectly adequate and reproduces all the relevant dynamics. All simulations use  $N_p = 241$  particles per streamline, and the total number of particles is  $N_s N_p$ . Note that the assignment of particles to a given streamline is merely for labeling purposes, as particles are still free to wander in response to the ring's internal forces, namely, ring gravity and viscosity. But as [Hahn & Spitale \(2013\)](#) as well as this work shows, the simulated ring stays coherent and highly organized throughout the simulation such that particles on the same streamline do not pass each other longitudinally, nor do they cross adjacent streamlines. Because the simulated ringlet stays highly organized, there is no radial or longitudinal mixing of the ring particles, and simulated particles preserve their streamline membership over time.

The `epi_int_lite` code also monitors all particles and checks whether any have crossed adjacent streamlines. If that happens the simulation is then terminated since the particles' subsequent evolution would no longer be computed reliably.

### 2.2. N-body method

The `epi_int_lite` N-body integrator uses the same drift-kick scheme used by the MERCURY Nbody algorithm ([Chambers 1999](#)) except that `epi_int_lite` particles that do not interact with each other directly. Rather, `epi_int_lite` particles are only perturbed by the accelerations exerted by the ringlet's individual streamlines. Those accelerations are sensitive to the streamline's relative separations and orientations, which are inferred from the particles' positions and velocities. `Epi_int_lite` particles are thus tracer particles that indicate the streamlines' locations and orientations, which the N-body integrator uses to compute the orbital evolution of those tracer particles due to the perturbations

exerted by those streamlines. This streamline approach is widely used in theoretical studies of planetary rings (c.f. Goldreich & Tremaine 1979a; Borderies et al. 1983, 1985) as well as in N-body studies of rings (Hahn & Spitale 2013; Rimlinger et al. 2016). The great benefit of the streamline concept in numerical work is that it allows one to swiftly track the global evolution of the ringlet's streamlines numerically using only a modest numbers of trace particles, typically  $N_s N_p \sim 500$ .

The simulations reported on here account for streamline gravity and ringlet viscosity. Because a ringlet is narrow, all particles are in close proximity to the nearby portions of all streamlines, which allows us to approximate a streamline as an infinitely long wire of matter having linear density  $\lambda$ . Consequently the gravity of each perturbing streamline draws a particle towards that streamline with acceleration

$$A_g = \frac{2G\lambda}{\Delta}, \quad (1)$$

where  $\Delta$  is the particle's distance from the streamline.

The streamline's linear density  $\lambda$  is inferred from a streamline's total mass,  $m_1 = m_r/N_s = \int_0^{2\pi} \lambda d\ell$  where the integration is about the streamline's circumference. Replacing  $d\ell$  with  $v dt$  where  $v$  is the velocity of the streamline's particles allows replacing the spatial integral with a timewise integral,  $m_1 = \int_0^T \lambda v dt = \lambda v T$  where the streamline's orbital period  $T = 2\pi/\Omega$  and  $\Omega$  its mean orbital frequency, hence

$$\lambda = \frac{m_1 \Omega}{2\pi v}. \quad (2)$$

The hydrodynamic approximation is used here to account for the dissipation that occurs as particles in adjacent particle streamlines shear past and collide with the perturbed particle, without having to monitor individual particle-particle collisions. The particle's acceleration due to the ring particles' shear viscosity is

$$A_{\nu,\parallel} = -\frac{1}{\sigma r} \frac{\partial \mathcal{F}_L}{\partial r}, \quad (3)$$

where  $r$  is the particle's radial coordinate,  $\sigma$  is the surface density of ringlet matter, and  $\mathcal{F}_{L,\nu}$  is the flux of angular momentum that is transported radially across the particle's streamline due to its collisions with particles in adjacent streamlines, *i.e.*

$$\mathcal{F}_{L,\nu} = -\nu_s \sigma r^2 \frac{\partial \omega}{\partial r} \quad (4)$$

where  $\nu_s$  is the ringlet's kinematic shear viscosity and  $\omega = v_\theta/r$  is the particle's angular velocity (Hahn & Spitale 2013). The acceleration  $A_{\nu,\parallel}$  is parallel to the perturbed particle's streamline *i.e.* parallel to particle's velocity vector  $\mathbf{v} = \dot{\mathbf{r}} = v_r \hat{r} + v_\theta \hat{\theta}$  where  $\mathbf{r} = r \hat{r}$  is the particle's position vector.

Dissipative collisions also transmits linear momentum in the perpendicular direction, which results in the additional acceleration

$$A_{\nu,\perp} = -\frac{1}{\sigma} \frac{\partial \mathcal{G}}{\partial r}, \quad (5)$$

where the radial flux of linear momentum due to ringlet viscosity is

$$\mathcal{G} = -\left(\frac{4}{3}\nu_s + \nu_b\right) \sigma \frac{\partial v_r}{\partial r} - \left(\nu_b - \frac{2}{3}\nu_s\right) \frac{\sigma v_r}{r}, \quad (6)$$

$\nu_b$  is the ringlet's kinematic bulk viscosity, and  $v_r$  is the particle's radial velocity (Hahn & Spitale 2013).

In the hydrodynamic approximation there is also the acceleration due to ringlet pressure  $p$  that is due to particle-particle collisions,

$$A_p = -\frac{1}{\sigma} \frac{\partial p}{\partial r}. \quad (7)$$

Epi\_lite treats the particle ring as a dilute gas of colliding particles for which the 1D pressure is  $p = c^2 \sigma$  where  $c$  is the particles dispersion velocity. However [Hahn & Spitale \(2013\)](#) found ring pressure to be inconsequential in N-body simulations of Saturn’s A ring, and the ringlet simulation examined in great detail in Section 3.1 also showed no sensitivity to pressure effects, so all other simulations reported on here have  $c = 0$ .

### 3. N-BODY SIMULATIONS OF VISCOUS GRAVITATING RINGLETS

The folowing describes a suite of N-body simulations of narrow viscous gravitating planetary ringlets, to highlight the range of initial ringlet conditions that do evolve into a self-confining state, and those that do not.

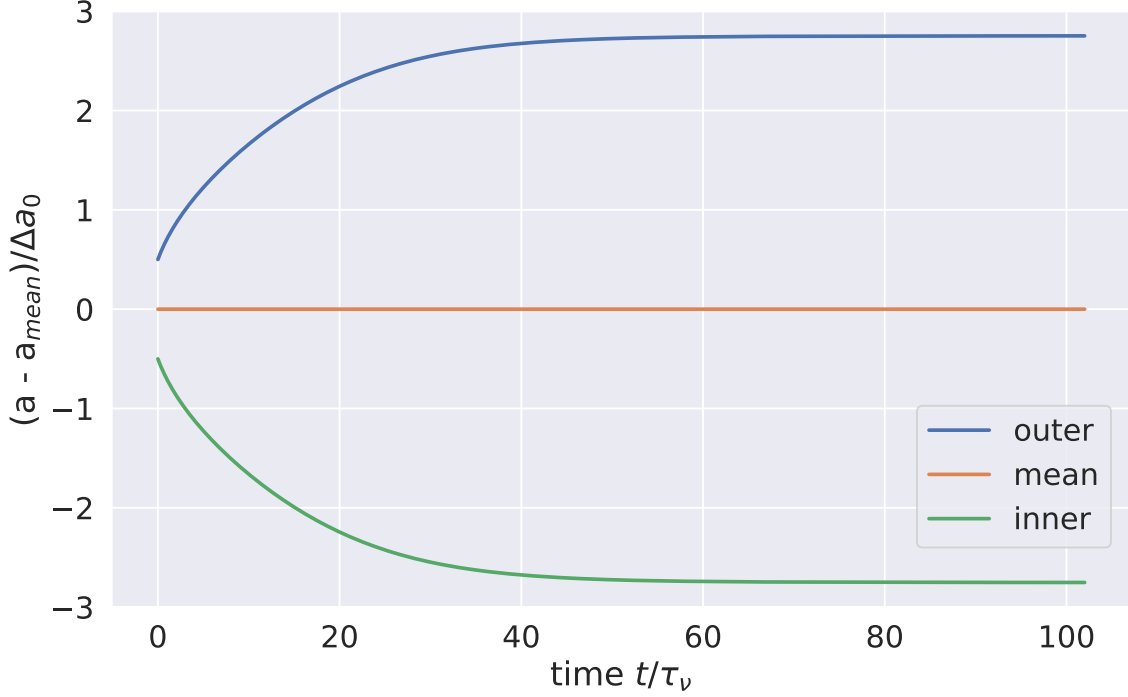
#### 3.1. *nominal model*

Figure 1 shows the semimajor axis evolution of what is referred to as the nominal model since this ringlet readily evolves into a self-confining state. The simulated ringlet is composed of  $N_s = 2$  streamlines having  $N_p = 241$  particles per streamline, and the integrator timestep is  $\Delta t = 0.5$  in natural units, so the integrator samples the particles’ orbits  $2\pi/\Delta t \simeq 13$  times per orbit, and this ringlet is evolved for  $1.4 \times 10^5$  orbits, which requires 50 minutes execution time on a ten year old laptop. The ringlet’s mass is  $m_r = 10^{-10}$ , its shear viscosity is  $\nu_s = 10^{-13}$ , and its bulk viscosity is  $\nu_b = \nu_s$ . The ringlet’s initial radial width is  $\Delta a_0 = 10^{-4}$ , its initial eccentricity is  $e = 0.01$ , and its eccentricity gradient is initially zero. A convenient measure of time is the ringlet’s viscous radial spreading timescale

$$\tau_\nu = \frac{\Delta a_0^2}{12\nu_s} \quad (8)$$

which can be inferred from Eqn. (2.13) of [Pringle \(1981\)](#). This simulation’s viscous timescale is  $\tau_\nu = 8.3 \times 10^3$  in natural units or  $\tau_\nu/2\pi = 1.3 \times 10^3$  orbital periods. If this ringlet were orbiting Saturn at  $r_0 = 1.0 \times 10^{10}$  cm then the simulated ringlet’s physical mass would be  $m_r = 5.7 \times 10^{19}$  gm which is equivalent to the mass of a 24 km radius iceball assuming a volume density  $\rho = 1$  gm/cm<sup>3</sup>, and the ringlet’s initial physical radial width would be  $\Delta a_0 = 10^{-4} r_0 = 10$  km. This ringlet’s orbit period would be  $T_{orb} = 2\pi\sqrt{r_0^3/GM} = 9.0$  hours in physical units, so the ringlet’s viscous timescale is  $\tau_\nu = 1.4$  years, and so its shear viscosity is  $\nu_s = \Delta a_0^2/12\tau_\nu = 1.9 \times 10^3$  cm<sup>2</sup>/sec when evaluated in physical units. This ringlet’s initial surface density would be  $\sigma = m_r/2\pi r_0 \Delta a_0 = 900$  gm/cm<sup>2</sup>, but Figs. 1–2 show that shrinks by a factor of about 5 as the ringlet’s sememajor axis width  $\Delta a$  grows via viscous spreading until it settles into the self-confining state at time  $t \sim 40\tau_\nu$ . This so-called nominal ringlet is probably somewhat overdense and overly viscous compared to known planetary ringlets, but that is by design so that the simulated ringlet quickly settles into the self-confining state. Section 4.5 also shows how outcomes vary when a wide variety of alternate initial masses, widths, and viscosities are also considered.

Figure 3 shows that the outer streamline’s eccentricity initially grows at the expense of the inner streamline’s, and that is a consequence the self-gravitating ringlet’s secular perturbations of itself, which is also demonstrated in Appendix D. Figure 4 shows the ringlet’s eccentricity difference



**Figure 1.** Evolution of the nominal ringlet’s semimajor axes  $a$  versus time  $t$  in units of the ringlet’s viscous timescale  $\tau_\nu = 1.3 \times 10^3$  orbital periods. This ringlet is composed of  $N_s = 2$  streamlines, and the outer (blue) and inner (green) streamlines’ semimajor axes are plotted relative to their mean  $a_{\text{mean}}$ , and displayed in units of the ringlet’s initial width  $\Delta a_0 = 10^{-4}$  in natural units (*i.e.*  $G = M = r_0 = 1$ ). The simulated ringlet has total mass  $m_r = 10^{-10}$ , shear viscosity  $\nu_s = 10^{-13}$ , and initial eccentricity  $e = 0.01$ . See Section 3.1 to convert  $m_r$ ,  $a$  and  $\nu_s$  from natural units to physical units.

$\Delta e = e_{\text{outer}} - e_{\text{inner}}$  and longitude of periapse difference  $\Delta \tilde{\omega} = \tilde{\omega}_{\text{outer}} - \tilde{\omega}_{\text{inner}}$ , which both settle into equilibrium values after the ringlet arrives at the self-confining state.

In all self-confining ringlet simulations examined here, the ringlet’s periapse twist  $\Delta \tilde{\omega} = \tilde{\omega}_{\text{outer}} - \tilde{\omega}_{\text{inner}}$  is negative, so the outer streamline’s longitude of periapse  $\tilde{\omega}$  trails the inner streamline’s, which in turn causes the streamlines’ separations along the ringlet’s pre-periapse side (where  $\varphi = \theta - \tilde{\omega} < 0$ ) to differ slightly from the post-periapse ( $\varphi > 0$ ) side. Which in turn makes the ringlet’s surface density asymmetric *i.e.* is maximal just prior to periapse, see Figs. 5–6.

It is convenient to recast these orbit element differences as dimensionless gradients

$$e' = a \frac{de}{da} \quad \text{and} \quad \tilde{\omega}' = ea \frac{d\tilde{\omega}}{da} \quad (9)$$

as these are the terms that contribute to the nonlinearity parameter of Borderies et al. (1983):

$$q = \sqrt{e'^2 + \tilde{\omega}'^2}. \quad (10)$$

See also Fig. 7 which plot’s the nominal ringlet’s dimensionless eccentricity gradient  $e'$ , dimensionless periapse twist  $\tilde{\omega}'$ , and nonlinearity parameter  $q$  versus time. All simulated self-confining ringlets have a positive eccentricity gradient and a negative periapse twist such that the outer ringlet’s periapse trails the inner ringlet’s, consistent with the findings of Borderies et al. (1983).



**Figure 2.** The nominal ringlet's semimajor axis width  $\Delta a = a_{\text{outer}} - a_{\text{inner}}$  over time and in units of its initial radial width  $\Delta a_0$ .



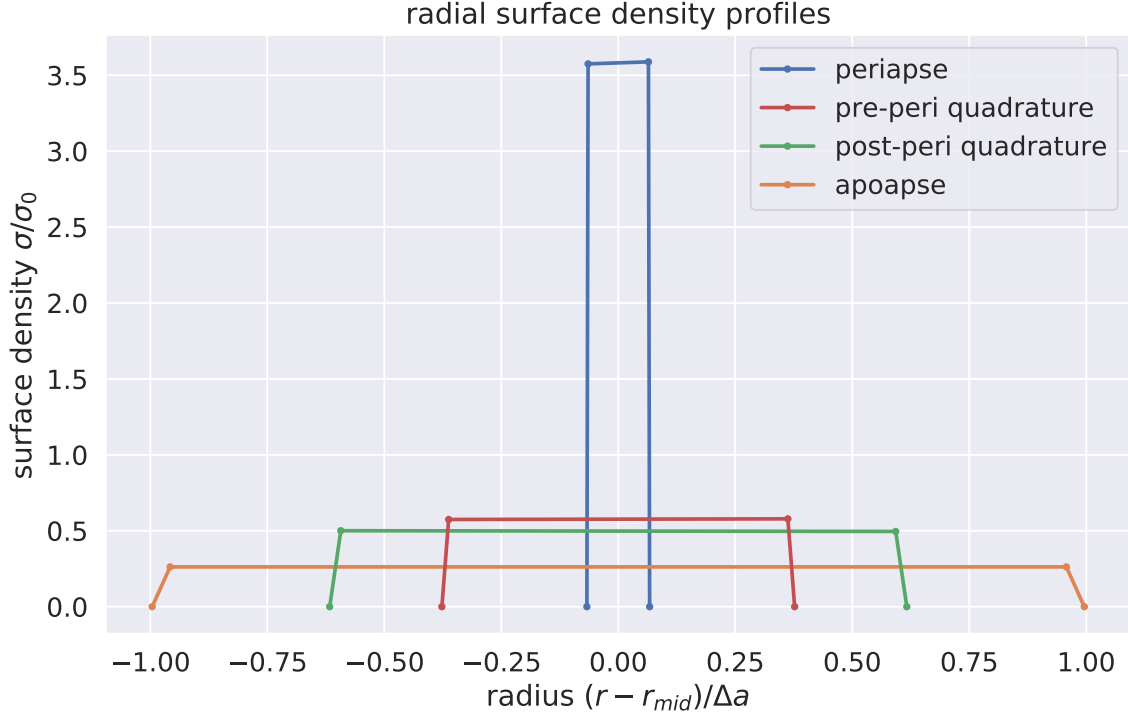
**Figure 3.** The nominal ringlet's eccentricity evolution.



**Figure 4.** The nominal ringlet's eccentricity difference  $\Delta e = e_{\text{outer}} - e_{\text{inner}}$  and longitude of periaapse difference  $\Delta\tilde{\omega} = \tilde{\omega}_{\text{outer}} - \tilde{\omega}_{\text{inner}}$  in radians divided by 10.



**Figure 5.** Nominal ringlet's surface density  $\sigma(\varphi)$  versus relative longitude  $\varphi$  at selected times  $t$  and plotted in units of ringlet's initial mean surface density  $\sigma_0$ . Note that the ringlet's surface density maxima occurs just before peripase, and is due to the ringlet's negative periaapse twist  $\Delta\tilde{\omega} = \tilde{\omega}_{\text{outer}} - \tilde{\omega}_{\text{inner}} < 0$ .



**Figure 6.** Radial profiles of the nominal ringlet’s surface density  $\sigma(\varphi)$  at time  $t/\tau_\nu = 100$  when the ringlet is self-confining. Each surface density profile is plotted versus radial distance  $r$  relative to  $r_{mid}$ , which is the ringlet’s midpoint along relative longitude  $\varphi = \theta - \tilde{\omega}$ , with those radial distances  $r - r_{mid}$  measured in units of the ringlet’s final semimajor axis width  $\Delta a$ , and surface density is shown in units of the ringlet’s longitudinally-averaged surface density  $\sigma_0$ . Radial surface density profiles are plotted along the ringlet’s periapse ( $\varphi = 0$ , blue curve), which is where the ringlet’s streamlines are most concentrated and surface density  $\sigma$  is greatest due to the ringlet’s eccentricity gradient  $e'$ , at the pre-periapse quadrature ( $\varphi = -\pi/2$ , red curve), post-periapse quadrature ( $\varphi = \pi/2$ , green curve) and at apoapse ( $|\varphi| = \pi$ , orange curve) where streamlines have their greatest separation and ringlet surface density is lowest. This ringlet’s surface density contrast between periapse and apoapse is about 14.

#### 4. ANGULAR MOMENTUM AND ENERGY FLUXES & LUMINOSITIES

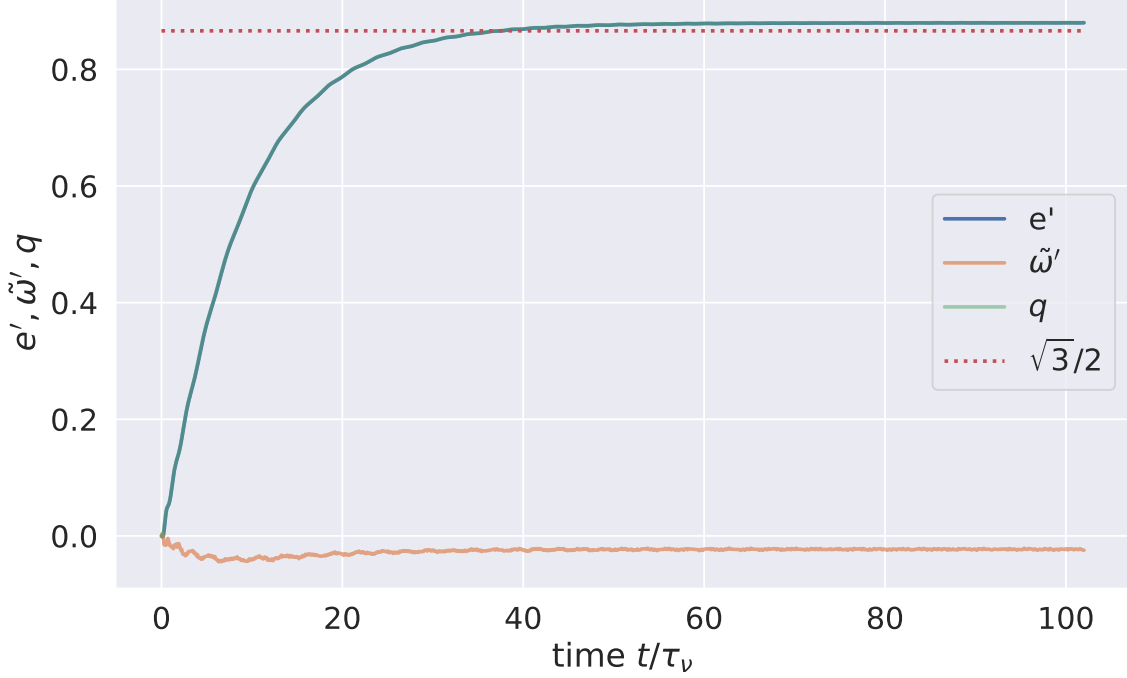
The nominal ringlet’s evolution is readily understood when the ringlet’s radial flux of angular momentum and energy are considered.

##### 4.1. angular momentum and energy fluxes

The torque that is exerted on a small streamline segment of mass  $\delta m$  at location  $\mathbf{r} = r\hat{\mathbf{r}}$  due to the streamlines orbiting interior to it is  $\delta T = \delta m \mathbf{r} \times \mathbf{A}^1$  where  $\mathbf{A}^1 = A_r^1 \hat{\mathbf{r}} + A_\theta^1 \hat{\boldsymbol{\theta}}$  is the so-called one-sided acceleration that is exerted on  $\delta m$  by the interior streamline. Since  $\delta m = \lambda \delta \ell$  where  $\lambda$  is the streamline’s linear mass density, and  $\delta \ell$  is the segment’s length, then the radial flux of angular momentum flowing into that segment due to the accelerations that are exerted by streamlines orbiting interior to that segment is

$$\mathcal{F}_L(r, \theta) = \frac{\delta T}{\delta \ell} = \lambda r A_\theta^1, \quad (11)$$





**Figure 7.** The nominal ringlet's dimensionless eccentricity gradient  $e' = a\Delta e/\Delta a$  (blue curve), dimensionless periapse twist  $\tilde{\omega}' = ea\Delta\tilde{\omega}/\Delta a$  (orange), and nonlinearity parameter  $q = \sqrt{e'^2 + \tilde{\omega}'^2}$  (green curve which overlaps blue) versus time  $t/\tau_\nu$ . Dotted red line is the threshold for self-confinement in a non-gravitating ringlet,  $e' = \sqrt{3}/2 \simeq 0.866$

where  $A_\theta^1$  is the tangential component of the one-sided acceleration, and the streamline's linear mass density  $\lambda$  is computed using Eqn. (2). The radial angular momentum flux, Eqn. (11), is due to the ringlet's viscosity and self-gravity, so  $\mathcal{F}_L = \mathcal{F}_{L,\nu} + \mathcal{F}_{L,g}$ .

The work that the interior streamlines exert on  $\delta m$  as that segment travels a small distance  $\delta \mathbf{r} = \mathbf{v}\delta t$  in time  $\delta t$  is  $\delta W = \delta m \mathbf{A}^1 \cdot \delta \mathbf{r}$  where  $\mathbf{v} = v_r \hat{\mathbf{r}} + v_\theta \hat{\boldsymbol{\theta}}$  is the segment's velocity, and that work accrues at  $\delta m$  at the rate  $\delta W/\delta t = \lambda \mathbf{A}^1 \cdot \mathbf{v} \delta \ell$ , so the radial flux of energy entering that ringlet segment due to accelerations exerted by the interior streamlines is

$$\mathcal{F}_E(r, \theta) = \frac{\delta W}{\delta \ell \delta t} = \lambda \mathbf{A}^1 \cdot \mathbf{v}. \quad (12)$$

The radial energy flux is due to the ringlet's viscosity and self-gravity, so  $\mathcal{F}_E = \mathcal{F}_{E,\nu} + \mathcal{F}_{E,g}$ .

#### 4.2. luminosities

The streamline containing segment  $\delta m$  has semimajor axis  $a$ , and integrating the radial angular momentum flux  $\mathcal{F}_L$  about the entire streamline then yields the radial luminosity of angular momentum entering streamline  $a$ ,

$$\mathcal{L}_L(a) = \oint \mathcal{F}_L d\ell, \quad (13)$$

which is the torque that is exerted on streamline  $a$  by those orbiting interior to it. Similarly, integrating the radial energy flux  $\mathcal{F}_E$  about streamline  $a$  also yields the ringlet's radial energy luminosity

$$\mathcal{L}_E(a) = \oint \mathcal{F}_E d\ell, \quad (14)$$

which is the rate that the interior streamlines communicate energy to streamline  $a$ .

#### 4.3. viscous transport of angular momentum

Angular momentum is transported radially through the ring via viscosity and self-gravity, so  $\mathcal{F}_L = \mathcal{F}_{L,\nu} + \mathcal{F}_{L,g}$ , where the ringlet's viscous flux of angular momentum is

$$\mathcal{F}_{L,\nu}(r, \theta) = -\nu_s \sigma r^2 \frac{\partial \omega}{\partial r} \quad (15)$$

when Eqn. (4) is written as a function of spatial coordinates and angular velocity  $\omega = \dot{\theta}$ . If we consider a small arc of ring material of length  $d\ell$ , then  $\mathcal{F}_{L,\nu} d\ell$  is the torque that arc exerts on ring matter just exterior, due to viscous friction, so that is the rate that friction transmits angular momentum radially across that arc. And when  $\mathcal{F}_{L,\nu}$  is evaluated along a single eccentric streamline of semimajor axis  $a$ , the above simplifies to

$$\mathcal{F}_{L,\nu}(a, \varphi) = \mathcal{F}_{L,\nu,c} \frac{1 - \frac{4}{3}e' \cos \varphi}{(1 - e' \cos \varphi)^2} \quad (16)$$

where the angular shear  $\omega' = \partial \omega / \partial r$  in Eqn. (15) is derived in Appendix B,  $\varphi = \theta - \tilde{\omega}$  is the longitude relative to periapse,  $\mathcal{F}_{L,\nu,c} = \frac{3}{2} \nu_s \sigma_0 a \Omega$  is the viscous angular momentum flux through a circular streamline of semimajor axis  $a$  and angular speed  $\Omega(a)$ , and Eqn. (16) assumes that  $|\tilde{\omega}'| \ll e'$  so that  $q \simeq e'$  (Borderies et al. 1982). Integrating the above around the streamline's circumference then yields its angular momentum luminosity,

$$\mathcal{L}_{L,\nu}(a) = \oint \mathcal{F}_{L,\nu}(a, \varphi) r d\varphi = \mathcal{L}_{L,\nu,c} \frac{1 - \frac{4}{3}e'^2}{(1 - e'^2)^{3/2}}, \quad (17)$$

which is the torque that one streamline exerts on its exterior neighbor due to viscous friction (Borderies et al. 1982) with  $\mathcal{L}_{L,\nu,c} = 3\pi \nu_s \sigma_0 a^2 \Omega$  being the viscous angular momentum luminosity of a circular streamline.

Borderies et al. (1982) examine angular momentum transport through a viscous eccentric but non-gravitating ringlet, and use Eqns. (16–17) to show that this transport has three regimes distinguished by the ringlet's  $e'$ :

1.  $e' < 3/4$ . The ringlet's viscous angular momentum flux  $\mathcal{F}_{L,\nu}(\varphi) > 0$  at all longitudes  $\varphi$ . The ringlet's viscous angular momentum luminosity  $\mathcal{L}_{L,\nu} > 0$ , so viscous friction transports angular momentum radially outwards, and the inner ring matter evolves to smaller orbits while exterior ring matter evolves outwards, and the ringlet spreads radially.
2.  $3/4 \leq e' < \sqrt{3}/2$ . In this regime there is a range of longitudes  $\varphi$  where the viscous angular momentum flux is reversed such that  $\mathcal{F}_{L,\nu}(\varphi) < 0$ . That angular momentum flux reversal is due to the  $\partial \omega / \partial r$  term in Eqn. (4) changing sign near periapse when  $e' > 0.75$ , see Fig. 8. Nonetheless  $\mathcal{L}_{L,\nu}$ , which is proportional to the orbit-average of  $\mathcal{F}_{L,\nu}(\varphi)$ , is positive and the ringlet still spreads radially, albeit slower than when  $e' < 0.75$ .

3.  $e' \geq \sqrt{3}/2$ . Viscous angular momentum flux reversal is complete such that  $\mathcal{L}_{L,\nu} \leq 0$ , viscous friction transports angular momentum radially inwards, and the ringlet shrinks radially. But if  $e' = \sqrt{3}/2 \simeq 0.866$  then  $\mathcal{L}_{L,\nu} = 0$  and the ringlet's radial evolution ceases, and the viscous but non-gravitating ringlet is self-confining.

Note though that the nominal ringlet's eccentricity gradient exceeds the  $e' = \sqrt{3}/2 \simeq 0.866$  threshold (dotted red line in Fig. 7) when it settles into self-confinement. This is due to the ringlet's self-gravity, which also transports a flux of angular momentum  $\mathcal{F}_{L,g}$  radially through the ringlet.

Figure 9 shows the nominal ringlet's viscous angular momentum flux  $\mathcal{F}_{L,\nu}$  versus relative longitude  $\varphi = \theta - \tilde{\omega}$  at selected times  $t$ . Early in the ringlet's evolution when time  $t \leq 10\tau_\nu$  (blue, orange, green, red, purple and brown curves), the ringlet is in regime 1 since  $e' < 0.75$  and  $\mathcal{F}_{L,\nu}(\varphi) > 0$  at all longitudes. But by time  $t \geq 20\tau_\nu$  (pink curve), this ringlet's eccentricity gradient exceeds 0.75, and angular momentum flux reversal  $\mathcal{F}_{L,\nu}(\varphi) < 0$  occurs near periapse where  $|\varphi| \simeq 0$  where the ringlet is most overdense due to its eccentricity gradient, see also Fig. 6. This ringlet is now in regime 2 and its radial spreading is reduced by angular momentum flux reversal. And by time  $t = 60\tau_\nu$  (yellow curve), this ringlet is seemingly in regime 3 since  $e' > 0.866$ , so one might expect the ringlet to start contracting now, but keep in mind that the above analysis ignores any transport of angular momentum via ringlet self-gravity. Figure 2 in fact shows that this gravitating ringlet's spreading had ceased by time  $t \simeq 80\tau_\nu$ , at which point  $e' = 0.88$  (Fig. 9 yellow curve), angular momentum flux reversal is nearly complete, and the ringlet's total angular momentum luminosity  $\mathcal{L}_L = \mathcal{L}_{L,\nu} + \mathcal{L}_{L,g}$  is very close to zero. Figures 10 and 11 also show that, when the ringlet is self-confining at times  $t \geq 80\tau_\nu$ , its small but positive viscous angular momentum luminosity  $\mathcal{L}_{L,\nu} \simeq 0.006\mathcal{L}_{L,\nu,c}$  is counterbalanced by its negative gravitational angular momentum luminosity  $\mathcal{L}_{L,g} \simeq -0.006\mathcal{L}_{L,\nu,c}$ , so radial spreading has ceased and the ringlet is self-confining.

#### 4.4. gravitational transport

The nominal ringlet's viscous  $\mathcal{F}_{L,\nu}$  and gravitational  $\mathcal{F}_{L,g}$  angular momentum fluxes are shown Fig. 12 after it has settled into the self-confining state. That figure shows how viscous friction tends to transport angular momentum radially inwards,  $\mathcal{F}_{L,\nu}(\varphi) < 0$ , at longitudes nearer periapse where  $|\varphi| \sim 0$ , and outwards at all other longitudes, with that flux reversal being due to the reversal of the ringlet's angular velocity gradient, Fig. 8. Figure 12 also shows that the ringlet's gravitational transport of angular momentum is inwards as ring-matter approaches periapse where  $\varphi < 0$ , and is outwards  $\mathcal{F}_{L,g}(\varphi) > 0$  post-periapse, with that asymmetry being due to the ringlet's negative periapse twist,  $\tilde{\omega}' < 0$  (Fig. 7).

Figure 13 shows the ringlet's energy fluxes due to viscosity (blue curve) and gravity (orange) at simulation end. Integrating these fluxes about a streamline's circumference at various times  $t$  then yields the the ringlet's viscous  $\mathcal{L}_{E,\nu}$  and gravitational energy luminosity  $\mathcal{L}_{E,g}$  over time, Fig. 14, where the gravitational energy luminosity is computed via

$$\mathcal{L}_{E,g}(a) = \oint \mathcal{F}_{E,g}(\varphi) r d\varphi = \oint \lambda r \mathbf{A}_g^1 \cdot \mathbf{v} d\varphi \quad (18)$$

where  $\mathbf{A}_g^1$  is the one-sided gravitational acceleration experienced by a particle in streamline  $a$ . Note that even though  $\mathcal{F}_{E,\nu}$  and  $\mathcal{F}_{E,g}$  have very different spatial dependences (see Fig. 13), the influence of the ringlet's viscosity and gravity still conspire such that their orbit-integrated luminosities  $\mathcal{L}_E = \oint (\mathcal{F}_{E,\nu} + \mathcal{F}_{E,g}) r d\varphi$  are zero once the ringlet has settled into the self-confining state.



**Figure 8.** The nominal ringlet’s angular shear  $\partial\omega/\partial r$  is plotted versus relative longitude  $\varphi$  at selected moments in time; this quantity is negative where the inner streamline has the higher angular speed  $\omega = v_\theta/r$ . When the simulation starts, the ringlet has eccentricity  $e = 0.01$  and eccentricity gradient  $e' = 0$  so  $\partial\omega/\partial r \simeq -3\Omega/2r \simeq -1.5$  when evaluated natural units (blue curve). The ringlet’s  $e'$  then grows over time (orange, green, red curves), which reverses the sign of  $\partial\omega/\partial r$  near periapse when  $e' > 0.75$ ; here the inner ringlet’s angular speed is slower than the outer ringlet, and viscous friction causes angular momentum to instead flow inwards at these longitudes. Dashed curve is Eqn. (B11) with  $e' = \sqrt{3}/2$  and assuming  $|\tilde{\omega}'| \ll 1$ .

Note that Fig. 14 also shows that the ringlet’s gravitational energy luminosity is zero. Which is to be expected since the streamlines’ gravitating ellipses only interact via their secular perturbations, and secular perturbations do no work (Brouwer & Clemence 1961), hence  $\mathcal{L}_{E,g} = 0$ . That this quantity evaluates to zero within  $\pm 5 \times 10^{-24}$  (in natural units) can also be regarded as another test of the epi.int.lite integrator’s numerical quality.

#### 4.5. variations with ringlet width, mass, and viscosity

To assess whether the nominal ringlet’s evolution is typical of other ringlets having alternate values of initial width  $\Delta a$ , total mass  $m_r$ , and shear viscosity  $\nu_s$ , a survey of 571 additional ringlet simulations are executed. These survey ringlets are similar to the nominal ringlet with  $N_s = 2$  streamlines having  $N_p = 241$  particles per streamline, initial eccentricity  $e = 0.01$ , initial eccentricity gradient  $e' = 0$ , and viscosities  $\nu_b = \nu_s$ . But the survey ringlets instead have total masses that are geometrically distributed between  $10^{-14} \leq m_r \leq 10^{-9}$ , shear viscosities distributed between  $10^{-15} \leq \nu_s \leq 10^{-11}$ , and initial radial widths distributed between  $2.5 \times 10^{-5} \leq \Delta a \leq 2.0 \times 10^{-4}$ . Survey results are summarized in Fig. 15 where circles indicate those ringlets that do evolve into a self-confining state. All simulations of self-confining ringlets are evolved in time until  $10\tau_{dyn}$  where the so-called dynamical time  $\tau_{dyn}$  is the moment when the ringlet’s nonlinearity parameter  $q$  first exceeds 0.6, since Fig. 7



**Figure 9.** The nominal ringlet's viscous angular momentum flux  $\mathcal{F}_{L,\nu}(\phi)$ , Eqn. (16), is plotted in units of  $\mathcal{F}_{L,\nu,c}$  (the angular momentum flux in a circular ringlet) and versus the ringlet's relative longitude  $\phi = \theta - \tilde{\omega}$  at selected times  $t/\tau_\nu$ , with the ringlet's eccentricity gradient  $e'$  also indicated.



**Figure 10.** Nominal ringlet's viscous angular momentum luminosity  $\mathcal{L}_{L,\nu}$  (blue curve) versus time  $t/\tau_\nu$  and in units of a circular ring's viscous angular momentum luminosity  $\mathcal{L}_{L,\nu,c}$ , as well as the ringlet gravitational angular momentum luminosity  $\mathcal{L}_{L,g}$  (orange curve).



**Figure 11.** Figure 10 is replotted to show that the ringlet’s viscous angular momentum luminosity  $\mathcal{L}_{L,\nu}$  (blue curve) always stays positive (indicating that the viscous transport of angular momentum is radially outwards) and is eventually balanced by the ringlet’s negative (*i.e.* inwards) gravitational angular momentum luminosity  $\mathcal{L}_{L,g}$  (orange) after time  $t \geq 80\tau_\nu$ . Green curve is total angular momentum luminosity  $\mathcal{L}_{L,\nu} + \mathcal{L}_{L,g}$  whose time-average is zero when  $t \geq 80\tau_\nu$ . Dashed lines are  $\pm 0.006\mathcal{L}_{L,\nu,c}$ .

suggests that  $10\tau_{dyn}$  is sufficient time to assess whether the ringlet has truly arrived at the self-confining state.

The  $\times$  simulations in Fig. 15 terminated early when an `epi_int_lite` particle crossed a neighboring streamline. In reality, strong pressure forces would have developed as adjacent streamlines converged and enhanced particle densities and particle collisions, with ring particles possibly rebounding off this high-density region and/or splashing vertically, none of which is accounted for with this version of `epi_int_lite`. So this survey simply terminates all such simulations and flags that occurrence with an  $\times$  in Fig. 15. Keep in mind though that this does not mean that these particular ringlets would not evolve into a self-confining state. Instead, the streamlines in these ringlets have evolved so close to each other that a more sophisticated and possibly nonlinear treatment of pressure effects is needed to accurately assess these ringlets’ fates.

Each circle in Fig. 15 represents a self-confining ringlet whose nonlinearity parameter settles into a value that is close to the anticipated value,  $q \simeq 0.9$ . But these self-confining ringlets’ final eccentricity gradients  $e'$  also settle into a spectrum of values,  $0 \leq e' \leq 0.9$ , with outcomes indicated by circle color in Fig. 15: blue for a high-eccentricity gradient ringlets having  $e' > 0.8$ , cyan for smaller eccentricity gradients  $0.13 > e' > 0.8$ , green for  $0.037 > e' > 0.13$ , and yellow for very low eccentricity gradients  $e < 0.037$ , with these intervals chosen so that there are approximately 60 simulations in each color-bin. Inspection of Fig. 15 also shows that ringlets having lower  $e'$  also have lower masses and higher viscosities than the higher  $e'$  ringlets.



**Figure 12.** The nominal ringlet’s viscous angular momentum flux  $\mathcal{F}_{L,\nu}(\varphi)$  (blue curve) is computed via Eqn. (4) and plotted in units of a circular ringlet’s flux  $\mathcal{F}_{L,\nu,c}$  versus relative longitude  $\varphi$  at the simulation’s end time  $t = 100\tau_\nu$ , as well as the ringlet’s gravitational angular momentum flux  $\mathcal{F}_{L,g}(\varphi)$  (orange curve via Eqn. 11).



**Figure 13.** Blue curve is the nominal ringlet’s viscous energy flux  $\mathcal{F}_{E,\nu}(\varphi)$ , plotted in units of a circular ringlet’s viscous energy flux  $\mathcal{F}_{E,\nu,c}$  and versus the ringlet’s relative longitude  $\varphi$  at the simulation’s end time  $t = 100\tau_\nu$ , as well as the ringlet’s gravitational energy flux  $\mathcal{F}_{E,g}(\varphi)$ .



**Figure 14.** Nominal ringlet’s viscous energy luminosity  $\mathcal{L}_{E,\nu}$  (blue curve) versus time  $t/\tau_\nu$  and in units of a circular ring’s viscous energy luminosity  $\mathcal{L}_{E,\nu,c}$ , as well as the ringlet gravitational energy luminosity  $\mathcal{L}_{E,g}$  (orange curve).

Figure 16 shows how eccentricity gradient varies over time  $t/\tau_{dyn}$  for a sample of self-confining ringlet simulations. That Figure also shows that the range of simulated  $e'$  outcomes also agrees with the range of eccentricity gradients of several of Saturn’s more well-studied narrow eccentric ringlets, namely the Maxwell, Titan, and Laplace ringlets, whose  $e'$  are indicated by the black horizontal lines. Figure 16 also shows there is a pileup of simulated outcomes near Laplace’s eccentricity gradient  $e' \simeq 0.04$ , as well as a dearth of simulations at significantly lower values of  $e'$ . Which indicates that the Huygens ringlet, whose  $e' \lesssim 0.01$ , can not be accounted for by the self-confining mechanism considered here.

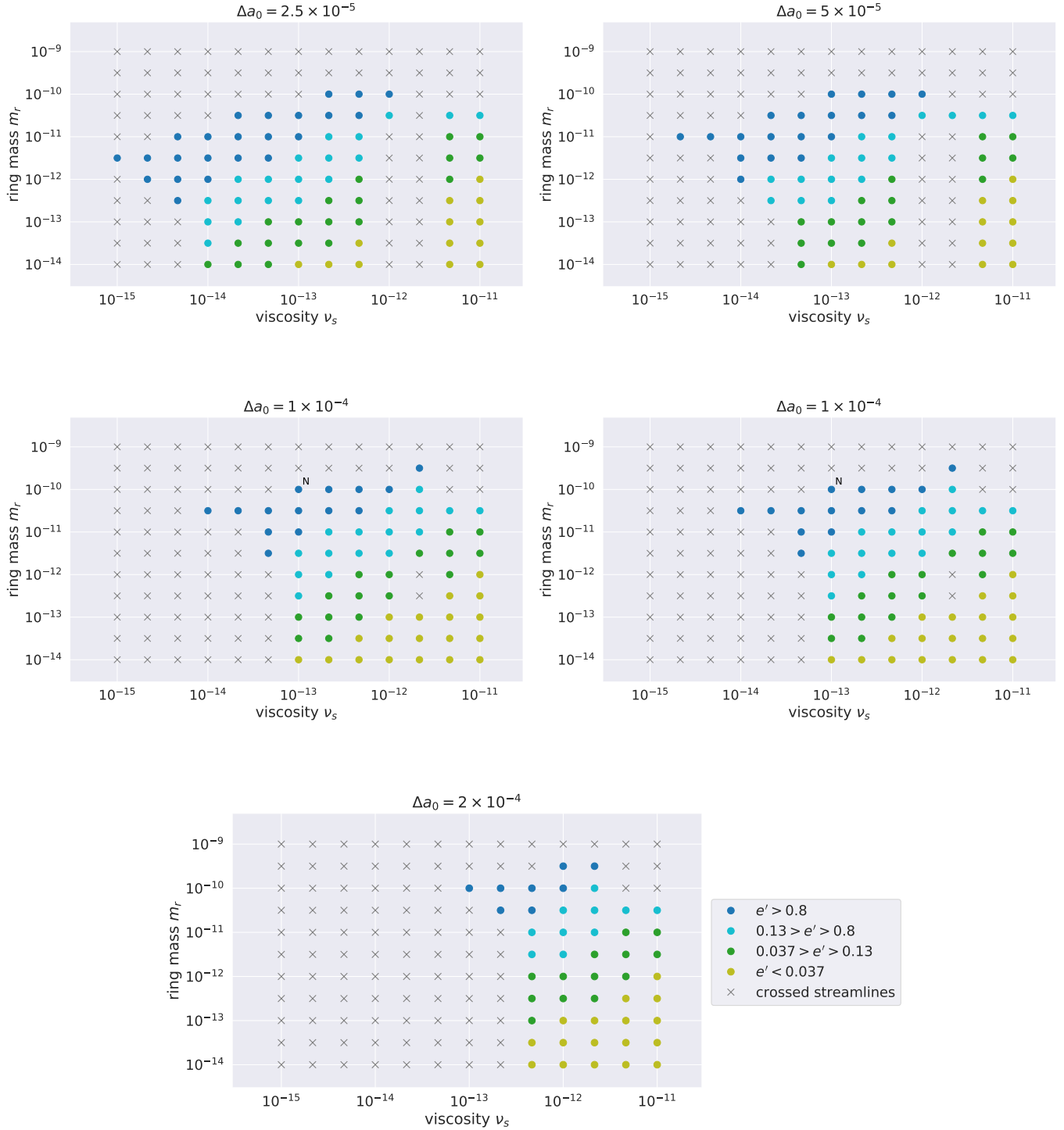
Also keep in mind that Fig. 16 is not an apples-to-apples comparison of simulated ringlets to observed ringlets, since no attempt is made here to match the observed ringlet’s semimajor-axis width  $\Delta a$  to the simulated ringlet’s final  $\Delta a$ . Rather, Fig. 16’s main point is that many of the the observed narrow eccentric ringlets that have  $e' \gtrsim 0.04$  are consistent with this model of a viscous self-gravitating ringlet that is also self-confining. And lastly, recall that  $q = \sqrt{e'^2 + \tilde{\omega}'^2}$  which tells us that lower eccentricity gradient ringlets have a larger periapse twist  $|\tilde{\omega}'|$ .

#### 4.5.1. variations with ringlet viscosity

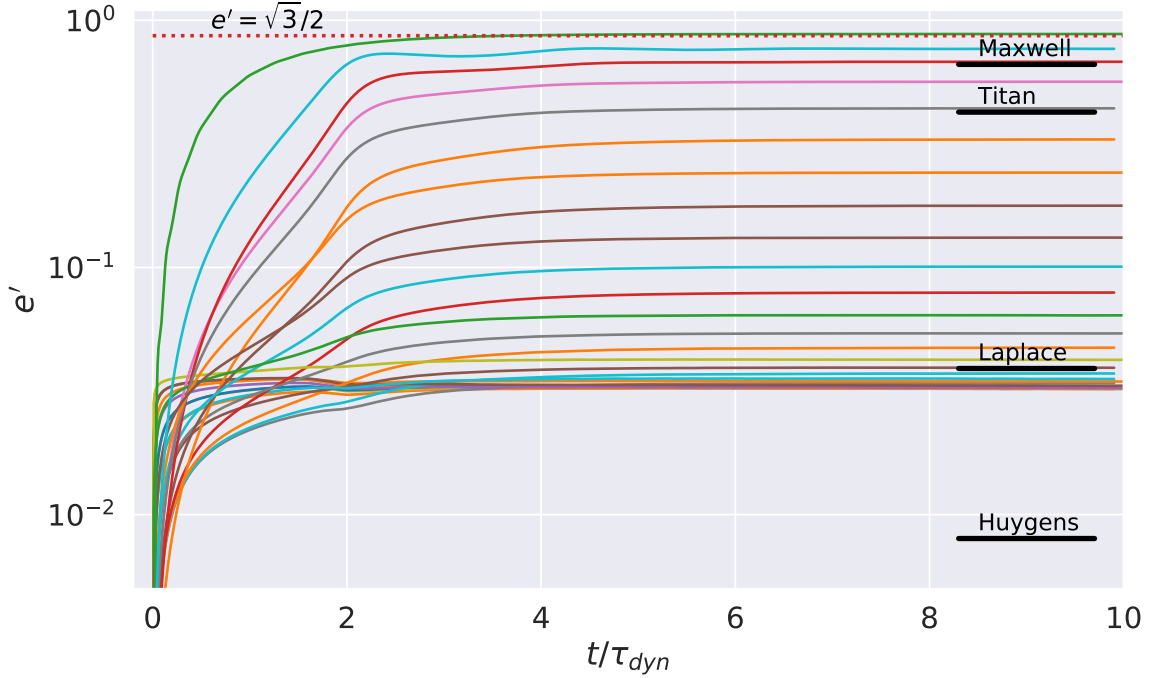
Figure 17 shows the periapse twist  $\tilde{\omega}' \simeq ea\Delta\tilde{\omega}/\Delta a$  versus time for five ringlets having the same initial  $e_0$ ,  $\Delta a$ , and  $m_r$  as the nominal ringlet but differing viscosities  $\nu_s$ , and that plot shows that twist  $|\tilde{\omega}'|$  varies with  $\nu_s$ . Which indicates that if the twist  $|\tilde{\omega}'|$  could be observed in a self-confining ringlet, then the ringlet’s viscosity could then be inferred.

#### 4.5.2. variations with initial radial width





**Figure 15.** Outcomes for 572 ringlet simulations having a variety of ringlet masses  $m_r$  and shear viscosities  $\nu_s$ , with each panel showing results for those ringlets having the same initial radial width  $\Delta a = 2.5 \times 10^{-5}$ ,  $5 \times 10^{-5}$ ,  $1 \times 10^{-4}$ , or  $2 \times 10^{-4}$ . Circles indicate those ringlets that evolve into the self-confining state, while an  $\times$  is for those simulations that terminate early when an epi.int.lite particle crossed an adjacent streamline, and N indicates the nominal ringlet simulation. The color of each self-confining ringlet shows whether the ringlet settled into a high-eccentricity gradient state with  $e' > 0.8$  (blue), or smaller eccentricity gradients  $0.13 > e' > 0.8$  (cyan),  $0.037 > e' > 0.13$  (green), or  $e < 0.037$  (yellow). All simulations are evolved for the greater of ten dynamical timescales  $\tau_{dyn}$  or ten viscous timescales  $10\tau_\nu$ . The middle-right plot is redundant and is here to trick latex into rendering all plots on same page, please ignore.



**Figure 16.** Eccentricity gradient  $e'$  versus time  $t/\tau_{dyn}$  for a sample of self-confining ringlets such that their eccentricity gradients  $e'$  span the range of values exhibited by the simulations reported in Fig. 15. The ringlet's dynamical timescale  $\tau_{dyn}$  is time when its nonlinearity parameter  $q$  exceeds 0.6. Horizontal black lines indicated the observed eccentricity gradients exhibited by the Maxwell, Titan, Laplace, and Huygens ringlets at Saturn (Nicholson et al. 2014, French et al. 2016, Spitale & Hahn 2016). Dotted line is the  $e' = \sqrt{3}/2$  threshold.

blah

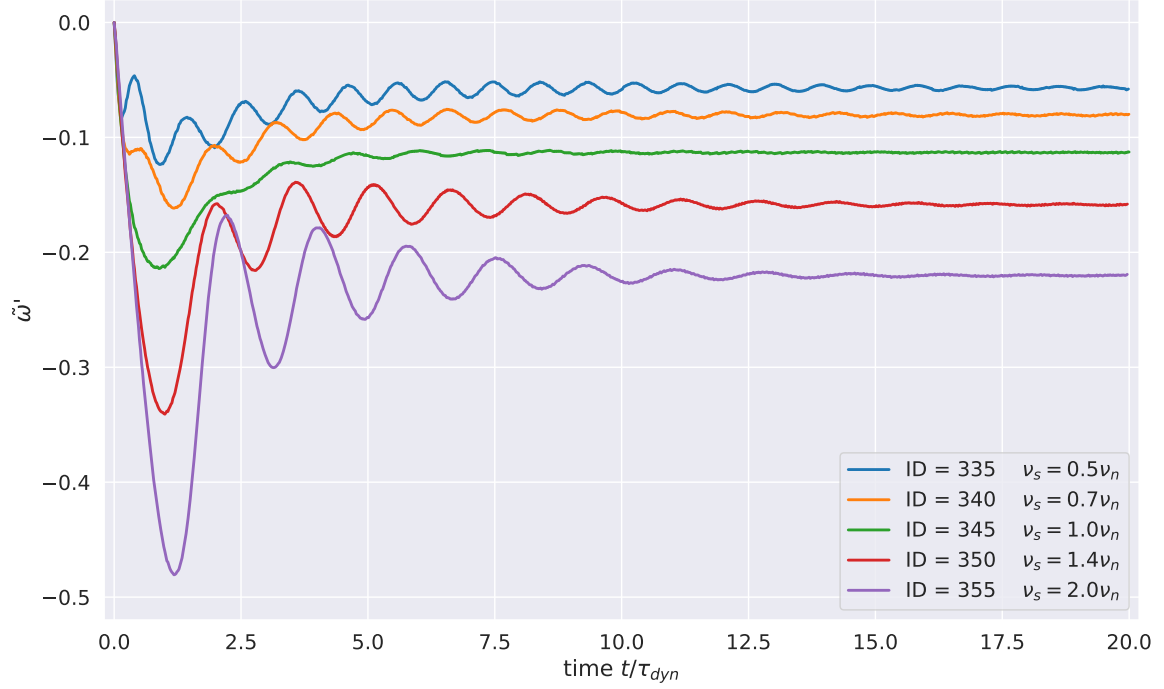
#### 4.5.3. variations with initial eccentricity

Additional simulations illustrate how outcomes depend upon the ringlet's initial eccentricity  $e_0$ . Figure 18 shows seven simulations of the nominal ringlet that all have identical physical properties (mass  $m_r$ , viscosity  $\nu_s$ , and initial width  $\Delta a$ ) but differing initial  $e_0$  ranging over  $0 \leq e_0 \leq 0.04$ . That plot shows that higher- $e$  ringlets settle into the self-confining state sooner than the lower- $e$  ringlets. This is because the higher- $e$  ringlet's secular gravitational perturbation of itself drives its eccentricity gradient and hence  $q$  towards  $q \simeq \sqrt{3}/2$  faster than the lower- $e$  ringlets. Consequently, higher- $e$  ringlets tend to be narrower than lower- $e$  ringlets because they will have had less time to spread before settling into self-confinement. Also note that the  $e_0 = 0$  ringlet (blue curve) experiences zero secular gravitational perturbations, so its  $q$  is always zero and is destined to spread forever.

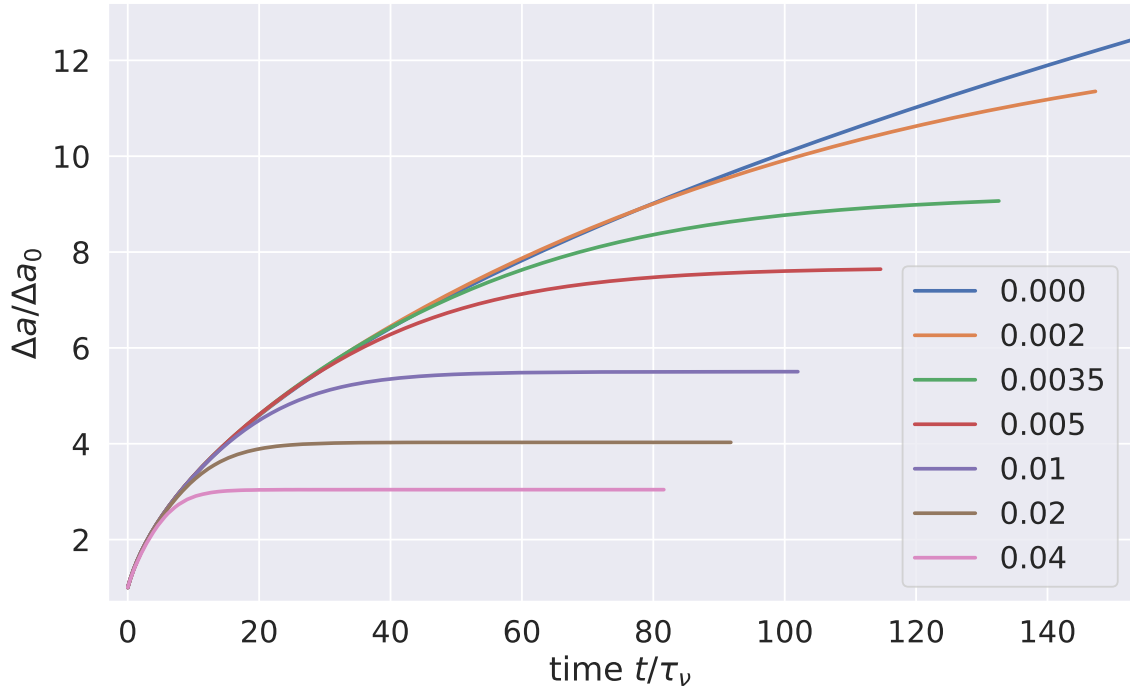
The next Subsection will examine the rate at which a self-confining ringlet's eccentricity  $e$  decays over time due to viscosity, and all ringlets shows in Figs. 1–16 have eccentricities  $e$  that decay at the expected rates.

#### 4.6. eccentricity damping

Viscous friction within the ringlet is a result of dissipative collisions among ringlet particles. Particle collisions generate heat that is radiated into space, and the source of that radiated energy is the



**Figure 17.** Periaapse twist  $\tilde{\omega}'$  is plotted versus time  $t/\tau_\nu$  for five ringlets having the same initial  $e_0$ ,  $\Delta a$ ,  $m_r$  as the nominal ringlet (whose simulation ID=345) but differing viscosities  $\nu_s$  that range over  $0.5\nu_n \leq \nu_s \leq 2\nu_n$  where  $\nu_n = 2.5 \times 10^{-12}$  is the nominal ringlet's shear viscosity.



**Figure 18.** Simulations of seven nominal ringlets having a variety of initial eccentricities  $0 \leq e_0 \leq 0.04$ . Curves give each ringlet's semimajor axis width  $\Delta a$  in units of its initial  $\Delta a_0$  versus time  $t/\tau_\nu$ , and show that higher- $e$  ringlets settle into self-confinement sooner than the lower- $e$  ringlets.

ringlet's orbital energy  $E_r = -m_r GM/2a + E_{sg}$  where  $m_r$  is the ringlet's total mass,  $a$  its semimajor axis, and  $E_{sg}$  is the ringlet's energy due to its self gravity which is constant when the ringlet is self-confining. Collisions conserve angular momentum, so the ringlet's total angular momentum  $L_r = m_r \sqrt{GMa(1-e^2)}$  is constant so  $dL_r/dt = 0$  implies

$$\frac{de^2}{dt} \simeq \frac{1}{a} \frac{da}{dt} \quad (19)$$

to lowest order in the ringlet's small eccentricity  $e$ . The ringlet's energy dissipation rate is  $\dot{E}_r = dE_r/dt = m_r GM \dot{a}/2a^2$  so  $\dot{a} \simeq 2\dot{E}_r/m_r a \Omega^2$  and

$$\frac{de^2}{dt} \simeq \frac{2\dot{E}_r}{m_r a^2 \Omega^2} \quad (20)$$

where  $GM \simeq a^3 \Omega^2$  to lowest order in  $J_2$ . Also note that the surface area of energy dissipation within a viscous disk is

$$\delta = -\nu_s \sigma (r\omega')^2 \quad (21)$$

(Pringle 1981 I think) where  $\omega = v_\theta/r$  is the angular velocity and  $\omega' = \partial\omega/\partial r$  its radial gradient.

Now consider a small tangential segment within the ringlet whose length is  $d\ell = r d\varphi$  where  $\varphi$  is the segment's longitude measured from the ringlet's periapse and  $d\varphi$  is the small segment's angular extent. The segment's area is  $dA = \Delta r d\ell = r \Delta r d\varphi$  where  $\Delta r$  is the ringlet's radial width. The rate at which that patch's viscosity dissipates orbital energy is  $d\dot{E}_r = \delta dA$ , so the ringlet's total energy dissipation rate is  $\dot{E}_r = \oint d\dot{E}_r$  when integrated about the ringlet's circumference, and so  $\dot{E}_r = -2\nu_s \lambda \int_0^\pi r^3 \omega'^2 d\varphi$  since the ringlet's linear density  $\lambda = \sigma \Delta r \simeq m_r/2\pi a$ . So the total energy loss rate due to ringlet viscosity becomes

$$\dot{E}_r \simeq -\frac{9}{4} I(e') m_r \nu_s \Omega^2 \quad (22)$$

when Eqn. (B11) is used to replace  $\omega'$ , and the integral

$$I(e') = \frac{1}{\pi} \int_0^\pi \left( \frac{1 - \frac{4}{3} e' \cos \varphi}{1 - e' \cos \varphi} \right)^2 d\varphi. \quad (23)$$

Note that  $I(e')$  is of order unity except when  $e'$  is very close to 1, and numerical evaluation shows that  $I(e') \simeq 0.889$  when  $e' = \sqrt{3}/2$ .

Inserting Eqn. (22) into (20) then yields the rate at which  $e^2$  is damped,

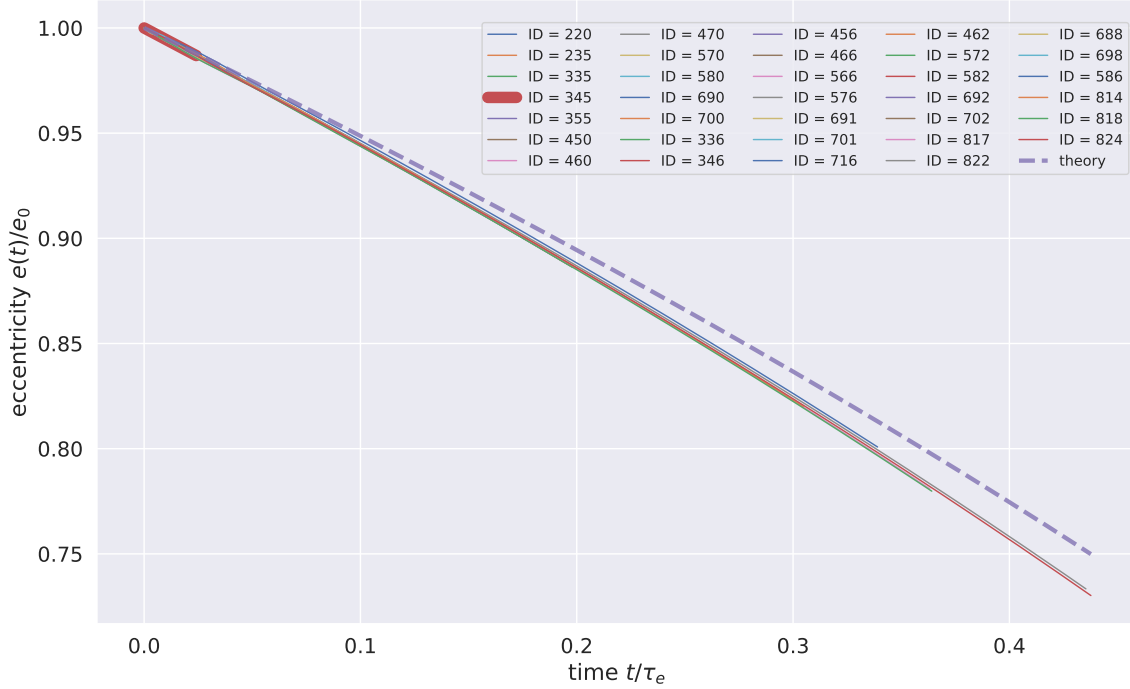
$$\frac{de^2}{dt} = -\frac{9I\nu_s}{2a^2} \quad (24)$$

which is easily integrated to obtain

$$e(t) = e_0 \sqrt{1 - \frac{t}{\tau_e}} \quad (25)$$

where  $e_0$  is the ringlet's initial eccentricity and

$$\tau_e = \frac{2a^2 e_0^2}{9I\nu_s} \quad (26)$$



**Figure 19.** Plot of  $e(t)/e_0$  versus time  $t/\tau_e$  for each of the numbered simulations seen in Figs. 15–??, while the dashed curve is the expected behavior, Eqn. (25). These simulations have values of  $\tau_e$  ranging over..., and thick red curve is the nominal ringlet whose ID=345.

is the ringlet’s eccentricity damping timescale. These expectations are also confirmed in Fig. 19, which plots  $e(t)/e_0$  versus time  $t/\tau_e$  using Eqns. (25–26), for each of the numbered simulations seen in Figs. 15–??, with good agreement seen between theory and numerical simulation.

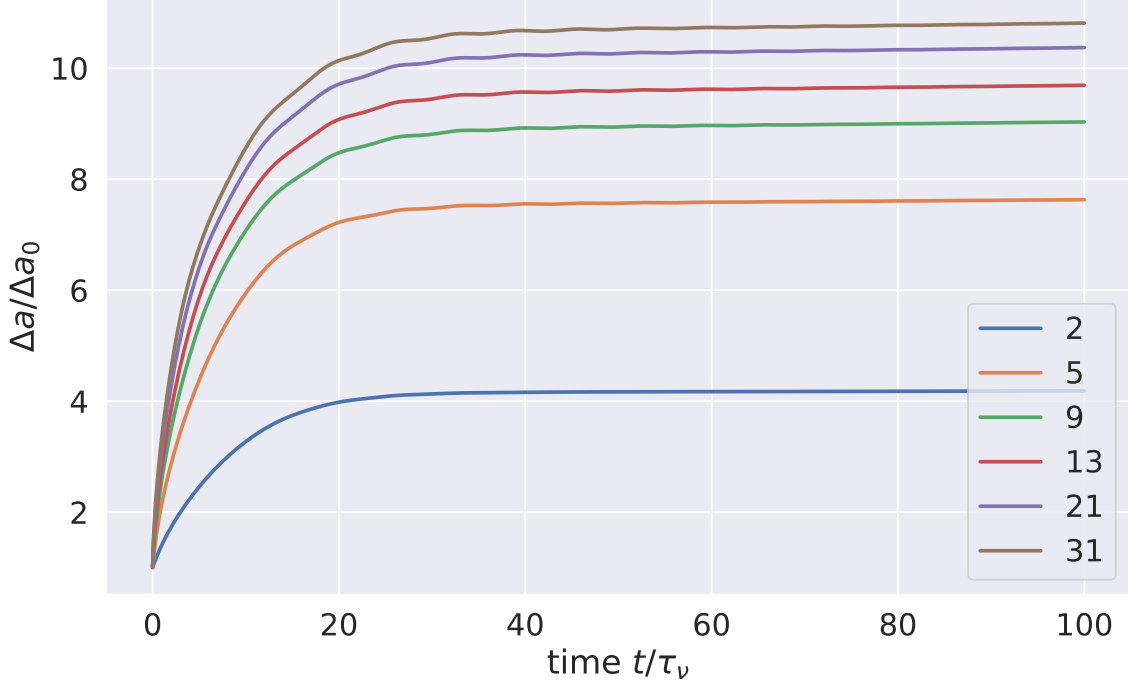
So viscosity circularizes the ringlet in time  $\tau_e$ , during which time the ringlet’s semimajor axis will have shrunk by  $\Delta a = \dot{a}\tau_e = -e_0^2 a$  by Eqns (19) and (24), so the ringlet’s fractional drift inwards due to viscous damping is

$$\frac{\Delta a}{a} = -e_0^2, \quad (27)$$

which is small. And after the ringlet’s inner edge damps to zero, its eccentricity gradient  $e'$  will then shrink over time, angular momentum flux reversal will diminish, and the ringlet’s viscous spreading will resume. So self-confinement of narrow eccentric ringlets is only temporary after all, until time  $\tau_e$  has elapsed, which is  $\tau_e/2\pi \sim 1.6 \times 10^6$  orbits for the nominal model considered here, which is only  $\sim 10^3$  years for a ringlet orbiting at  $a \sim 10^{10}$  cm about Saturn. Recall from Section 3.1 that the viscous lifetime of a non-self-confining nominal ringlet is only  $\tau_\nu/2\pi \sim 500$  orbits, so self-confinement evidently extends the lifetime of a narrow eccentric ringlet by factor of  $\sim 3000$ . But self-confinement does not solve the ringlet’s lifetime problem, because self-confinement is ultimately defeated by viscous damping of the ringlet’s eccentricity.

#### 4.7. number of streamlines $N_s$

When the simulated ringlet is composed of  $N_s = 2$  streamlines, the ringlet’s evolution is largely analytic (*c.f.* Borderies et al. 1982, 1983), and those analytic predictions also provide excellent bench-



**Figure 20.** The nominal ringlet simulation is repeated for ringlets composed of  $N_s = 2, 5, 9, 13, 21, 31$  streamlines as indicated by the legend, with all other parameters are identical to that used in Fig. 1. Plot shows how the simulated ringlets’ semimajor axis width  $\Delta a = a_{outer} - a_{inner}$  evolve over time  $t$  in units of the nominal ringlet’s viscous timescale  $\tau_\nu$ .

mark tests for the `epi_int_lite` integrator. This subsection assesses whether the results obtained for the simpler  $N_s = 2$  ringlet also applies to more realistic ringlets having  $N_s > 2$ .

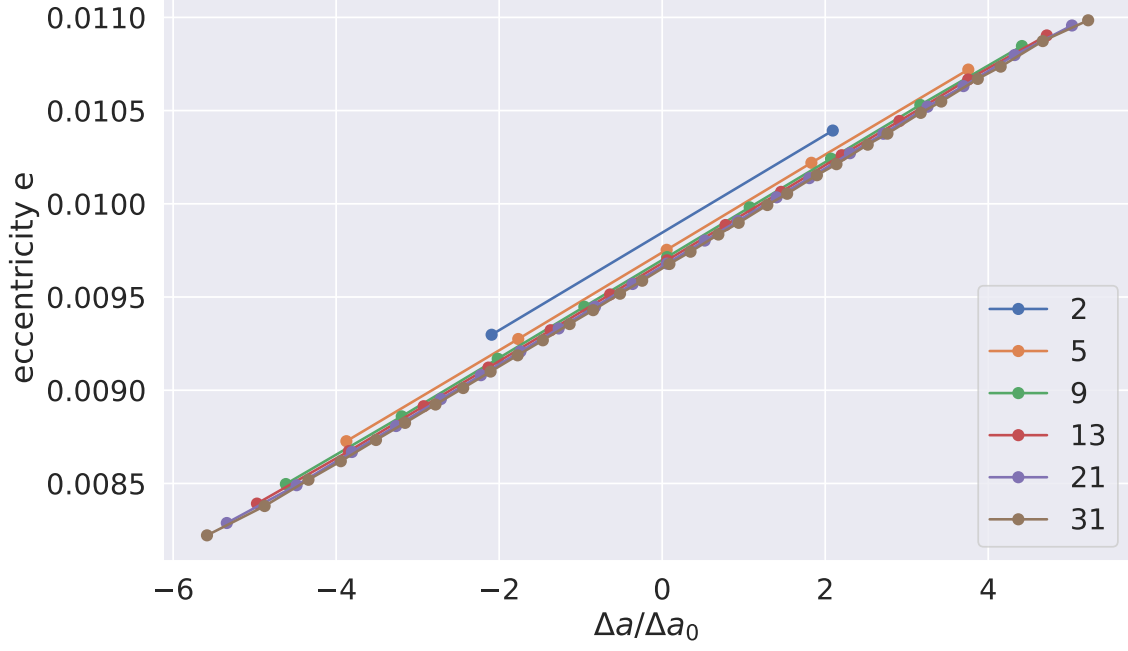
Figures 20–22 recompute the nominal ringlet’s evolution but for ringlets having a range of streamlines,  $2 \leq N_s \leq 31$ . Figure 20 shows that ringlets having larger  $N_s$  also achieve larger semimajor axis widths  $\Delta a = a_{outer} - a_{inner}$ . Figure 21 plots each streamlines’ final eccentricities  $e$  versus their final  $\Delta a$ , and this plot shows that all curves have the same  $e$  versus  $\Delta a$  slope *i.e.* all simulated ringlets have the same eccentricity gradient regardless of number of streamlines  $N_s$ . Ditto for  $\tilde{\omega}$  versus  $\Delta a$ , Fig. 22. Consequently, the evolution of the simulated ringlets nonlinearity parameter  $q$ , which depends on those gradients via Eqn. (10), and also controls how viscosity communicate angular momentum between the streamlines [e.g. Eqn. (17) and note that  $q \simeq e'$  in all simulations considered here], is very similar over time for various  $N_s$ , see Fig. 23. The only noteworthy difference between the  $N_s = 2$  ringlet and the higher  $N_s$  ringlets is seen in Fig. 22, which shows that the  $N_s > 2$  ringlets have an outer longitude of peripase that trails the inner streamline by a factor of  $\sim 2$ . Except for this one distinction, the evolution of the  $N_s > 2$  ringlets is very similar to that exhibited by nominal ringlet composed of  $N_s = 2$  streamlines

#### 4.7.1. *partially confined ringlets*

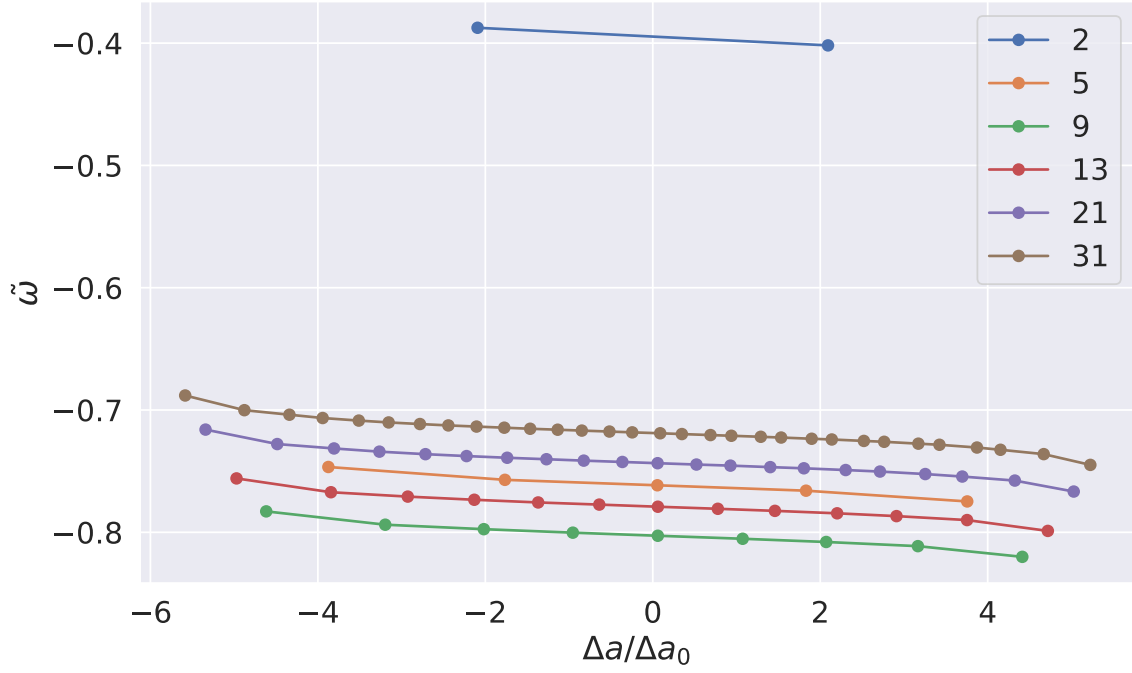
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## 5. RINGLET ORIGIN SCENARIOS

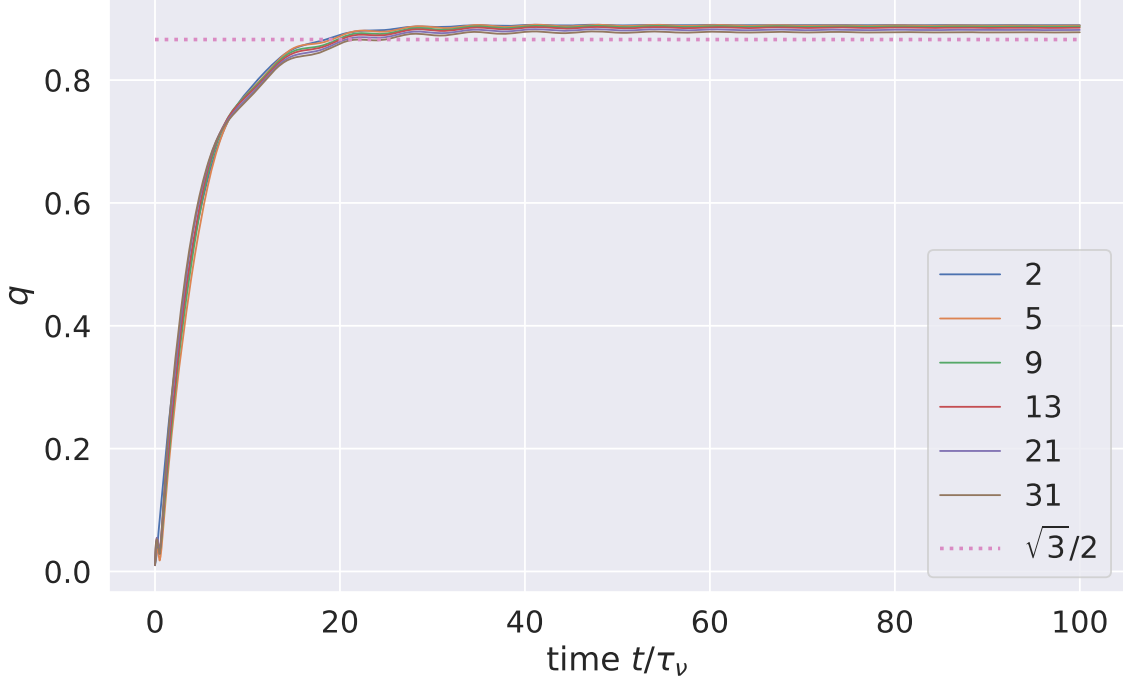
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**Figure 21.** Simulated ringlets' final eccentricities  $e$  are plotted versus their final semimajor axis displacement  $\Delta a = a - \bar{a}$  where  $\bar{a}$  is the mean semimajor axis of all particles in each ringlet.



**Figure 22.**  $\tilde{\omega} = \tilde{\omega}_{outer} - \tilde{\omega}_{inner}$



**Figure 23.** Caption...

## 6. SUMMARY OF FINDINGS

Main findings:

1. Simulations show that narrow eccentric ringlets having a wide variety of initial physical properties (mass, initial width, viscosity) do evolve into the self-confining state (see Fig. 15), provided that the ringlet's initial eccentricity is sufficiently high (Section 4.5.3). Self-gravity causes the ringlet's eccentricity gradient  $e'$  to grow over time until they near the  $\simeq e' \simeq \sqrt{3}/2 \simeq 0.866$  threshold where viscous angular momentum flux reversal is nearly complete and there is *almost* no radial orbit-averaged transmission of angular momentum due to the ringlet's viscous friction.

Simulations also show that these self-confining ringlets all have a small periapse twist  $|w'| \ll e'$  so that the ringlet's nonlinearity parameter is dominated by their eccentricity gradient  $q = \sqrt{e'^2 + \tilde{\omega}'^2} \simeq e'$ .

2. Self confining ringlets have  $L_E = 0$
3. partial self confinement

## 7. FOLLOWUP STUDIES

Possible followup studies...

## 8. ACKNOWLEDGMENTS



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## APPENDIX

### A. APPENDIX A

The drift step implemented in the original `epi_int` code utilized the epicyclic equations of [Borderies-Rappaport & Longaretti \(1994\)](#) to advance an unperturbed particle along its trajectory about an oblate planet. Those equations convert a particle's spatial coordinates  $r, \theta, v_r, v_\theta$  into epicyclic orbit elements  $a, e, M, \tilde{\omega}$  that are easily advanced by timestep  $\Delta t$ , after which the epicyclic elements are converted back to spatial coordinates with an accuracy to  $\mathcal{O}(e^2)$ . Note though that those epicyclic equations are not reversible; every conversion from spatial to epicyclic coordinates or vice-versa also introduces an error of order  $\mathcal{O}(e^3)$ , and the accumulation of those errors causes the orbits of the `epi_int` particles to slowly drift over time. But that slow numerical drift was not problematic for the relatively short `epi_int` simulations reported in [Hahn & Spitale \(2013\)](#) that evolved Saturn's B ring for typically  $\sim 10^4$  orbit periods. However the viscous self-gravitating ringlets considered here must be evolved for  $10^5$  to  $10^6$  orbit periods in order for self-confinement to occur, and simulations having those longer execution times were being defeated by this orbital drift. The remedy is to derive an alternate set of epicyclic equations that *are* reversible such that the `epi_int_lite`'s drift step will not be a significant source of numerical error.

Begin with the equation of motion for an unperturbed particle in orbit about the central planet,

$$\ddot{\mathbf{r}} = -\nabla\Phi \quad (\text{A1})$$

where the planet's gravitational potential is

$$\Phi = -\frac{GM}{r} - \frac{J_2 GMR^2}{2r^3} \quad (\text{A2})$$

where  $M$  is the planet's mass,  $R$  its radius,  $J_2$  its second zonal harmonic due to oblateness, and with higher-order  $J_{n>2}$  terms ignored here. The angular part of Eqn. (A1) is

$$\frac{1}{r} \frac{d}{dt}(r^2 \dot{\theta}) = -\frac{\partial \Phi}{\partial \theta} = 0 \quad (\text{A3})$$

so the particle's specific angular momentum  $h = r^2 \dot{\theta} = rv_\theta$  is conserved *i.e.*

$$\dot{\theta} = \frac{h}{r^2}, \quad (\text{A4})$$

and inserting that into the radial part of Eqn. (A1) yields

$$\ddot{r} = \frac{h^2}{r^3} - \frac{GM}{r^2} - \frac{3J_2 GMR^2}{2r^4}. \quad (\text{A5})$$

Solving the above to first-order accuracy  $\mathcal{O}(e^1)$  ordinarily yields

$$\begin{aligned} r &\simeq a(1 - e \cos M) \\ \theta &\simeq \frac{\Omega}{\kappa}(M + 2e \sin M) + \tilde{\omega} \\ v_r &= \dot{r} \simeq ea\kappa \sin M \\ v_\theta &= r\dot{\theta} \simeq a\Omega(1 + e \cos M) \end{aligned} \quad (\text{A6})$$

where

$$\Omega(a) = \sqrt{\frac{GM}{a^3}} \left[ 1 + \frac{3}{2} J_2 \left( \frac{R}{a} \right)^2 \right]^{1/2} \quad (\text{A7})$$

is the particle's mean orbital frequency and

$$\kappa(a) = \sqrt{\frac{GM}{a^3}} \left[ 1 - \frac{3}{2} J_2 \left( \frac{R}{a} \right)^2 \right]^{1/2} \quad (\text{A8})$$

its epicyclic frequency. In the above,  $a$ ,  $e$ ,  $\tilde{\omega}$  and  $M = \kappa t$  are the epicyclic orbit elements that have errors of order  $\mathcal{O}(e^2)$ . Equations (A6) are easily inverted, which would then provide epicyclic orbit elements  $a$ ,  $e$ ,  $\tilde{\omega}$ ,  $M$  as functions of the particle's spatial coordinates  $r$ ,  $\theta$ ,  $v_r$ ,  $v_\theta$ , but applying them here would be even more problematic since the conversion from spatial coordinates to orbit elements would accrue  $\mathcal{O}(e^2)$  errors during every drift step, which is even worse than the rate at which the particle's drift step accrues errors.

The remedy is to choose an alternate set of equations (A6) that also solve the equation of motion (A1) to the same accuracy while satisfying Eqn. (A4) exactly. Begin with the above expression for the angular coordinate,  $\theta = (\Omega/\kappa)(M + 2e \sin M) + \tilde{\omega}$ , so that  $\dot{\theta} = \Omega(1 + 2e \cos M)$ . Then require the constant  $h = r^2 \dot{\theta} = a^2 \Omega$  be satisfied exactly, which provides the revised expression for  $r$  as a function of orbit elements,  $r = a/\sqrt{1 + 2e \cos M}$ , noting that this expression differs from that in Eqn. (A6) by an amount of order  $\mathcal{O}(e^2)$  which is this solution's allowed error. It is then straightforward to complete the revisions to Eqn. (A6):

$$\begin{aligned} r &= \frac{a}{\sqrt{1 + 2e \cos M}} \\ \theta &= \frac{\Omega}{\kappa}(M + 2e \sin M) + \tilde{\omega} \\ v_r = \dot{r} &= \frac{ea\kappa \sin M}{(1 + 2e \cos M)^{3/2}} = ea\kappa \sin M \left( \frac{r}{a} \right)^3 \\ v_\theta = r\dot{\theta} &= a\Omega\sqrt{1 + 2e \cos M} = \frac{a^2\Omega}{r} \end{aligned} \quad (\text{A9})$$

where  $\Omega$  and  $\kappa$  are Eqns. (A7–A8) and  $M = \kappa t$ .

Eqns. (A9) must also be inverted so that the particle's epicyclic orbit elements  $a, e, \tilde{\omega}, M$  can be obtained from the particle's spatial coordinates  $r, \theta, v_r, v_\theta$ , which is done via the following:

1. Calculate the particle's specific angular momentum  $h = rv_\theta$  and then solve  $h^2 = a^4\Omega^2 = GMa[1 + (3J_2/2)(R/a)^2]$  for the particle's semimajor axis  $a$ , which is

$$a = R \left( C + \sqrt{C^2 - 3J_2/2} \right) \quad (\text{A10})$$

where constant  $C = h^2/2GMR$ .

2. Calculate  $\Omega$  and  $\kappa$  using Eqns. (A7–A8).
3. Note that  $e \sin M = (v_r/a\kappa)(a/r)^3$  and  $e \cos M = \frac{1}{2}[(a/r)^2 - 1]$ , which provides the particle's eccentricity via  $e = \sqrt{(e \sin M)^2 + (e \cos M)^2}$  and its mean anomaly  $M$  inferred from  $\tan M = e \sin M / e \cos M$ .

4. The particle's longitude of periapse is  $\tilde{\omega} = \theta - (\Omega/\kappa)(M + 2e \sin M)$ .

These equations satisfy the equation of motion (A1) to accuracy  $\mathcal{O}(e)$  and with errors of order  $\mathcal{O}(e^2)$ . To advance a particle during `epi_int_lite`'s drift step from time  $t$  to time  $t + \Delta t$ , use the above steps 1-4 to convert the particle's spatial coordinates  $r, \theta, v_r, v_\theta$  to epicyclic orbit elements  $a, e, M, \tilde{\omega}$ , update the particle's mean anomaly via  $M \rightarrow \kappa(t + \Delta t)$ , and then use Eqns. (A9) to compute the particle's revised spatial coordinates. And because steps 1-4 convert coordinates to elements exactly, `epi_int_lite`'s drift step is not a significant source of numerical error.

## B. APPENDIX B

Derive the angular shear  $\partial\omega/\partial r$ . The angular velocity  $\omega = v_\theta/r = \Omega(a/r)^2$  by Eqn. (A9) so  $\omega \simeq \Omega(1 + 2e \sin \varphi)$  to first order in  $e$  and relative longitude  $\varphi = \theta - \tilde{\omega} \simeq M$ . Thus  $\partial\omega/\partial a \simeq -(3\Omega/2a)(1 - \frac{4}{3}e' \cos \varphi)$  since  $J_2$  and  $e$  are small though the eccentricity gradient  $e' = a(\partial e/\partial a)$  might not be small. Likewise  $r \simeq a(1 - e \cos \varphi)$  so  $\partial r/\partial a \simeq 1 - e' \cos \varphi$  and so

$$\omega' = \frac{\partial\omega}{\partial r} = \frac{\partial\omega}{\partial a} / \frac{\partial r}{\partial a} \simeq - \left( \frac{3\Omega}{2a} \right) \frac{1 - \frac{4}{3}e' \cos \varphi}{1 - e' \cos \varphi}, \quad (\text{B11})$$

which interestingly changes sign near periapse when the eccentricity gradient is large enough,  $e' > 3/4$ .

## C. APPENDIX C

Compare `epi_int_lite` to theoretical predictions

## D. APPENDIX D

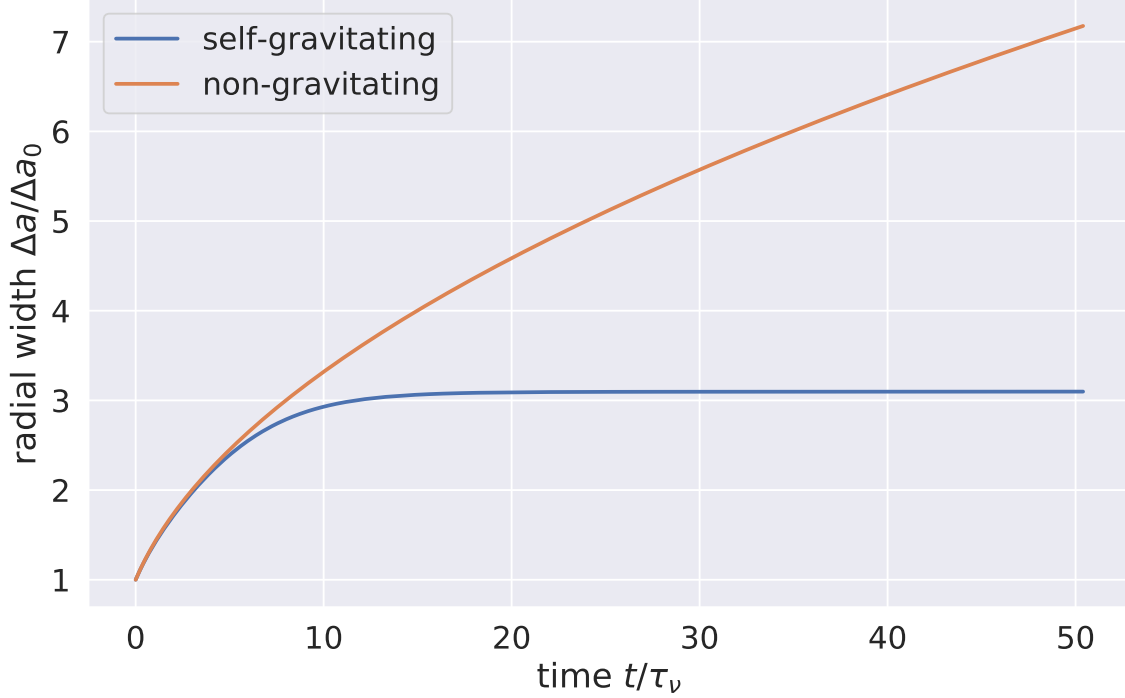
This examines the viscous evolution of a narrow eccentric non-gravitating ringlet that is identical to the nominal ringlet of Section 3.1 but with ringlet self-gravity neglected and  $J_2 = 0$ . As the orange curve in Fig. 24 shows, the non-gravitating ringlet's radial width  $\Delta a$  grows steadily over time due to ringlet viscosity, long after the nominal self-gravitating ringlet (blue curve) has settled into the self-confining state by time  $t \sim 15\tau_\nu$ . This is due to the ringlet's secular gravitational perturbations of itself, which tends to excite the ringlet's outer streamline's eccentricity at the expense of the inner streamline (see Fig. 3) until the ringlet eccentricity gradient  $e'$  (blue curve in Fig. 25) grows beyond the limit required for complete angular momentum flux reversal that results in the ringlet's radial confinement (dotted line). Note that viscosity also excites the non-gravitating ringlet's eccentricity gradient some (orange curve), but not sufficiently to halt the ringlet's viscous spreading.

## E. APPENDIX F

Viscous and gravitational energy transport...

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|---|--|



**Figure 24.** Blue curve is the nominal ringlet’s semimajor axis width  $\Delta a$  versus time  $t$ , and this ringlet’s radial spreading ceases by time  $t \sim 15\tau_v$  when it’s self-gravity has excited the ringlet’s eccentricity gradient  $e'$  sufficiently; see blue curve in Fig. 25. Orange curve shows that the non-gravitating ringlet’s  $\Delta a$  grows without limit due to the ringlet’s much lower eccentricity gradient. Note that planetary oblateness would cause the non-gravitating streamlines to precess differentially and eventually cross when  $J_s > 0$ , so the non-gravitating simulation also sets  $J_2 = 0$  to avoid differential precession.

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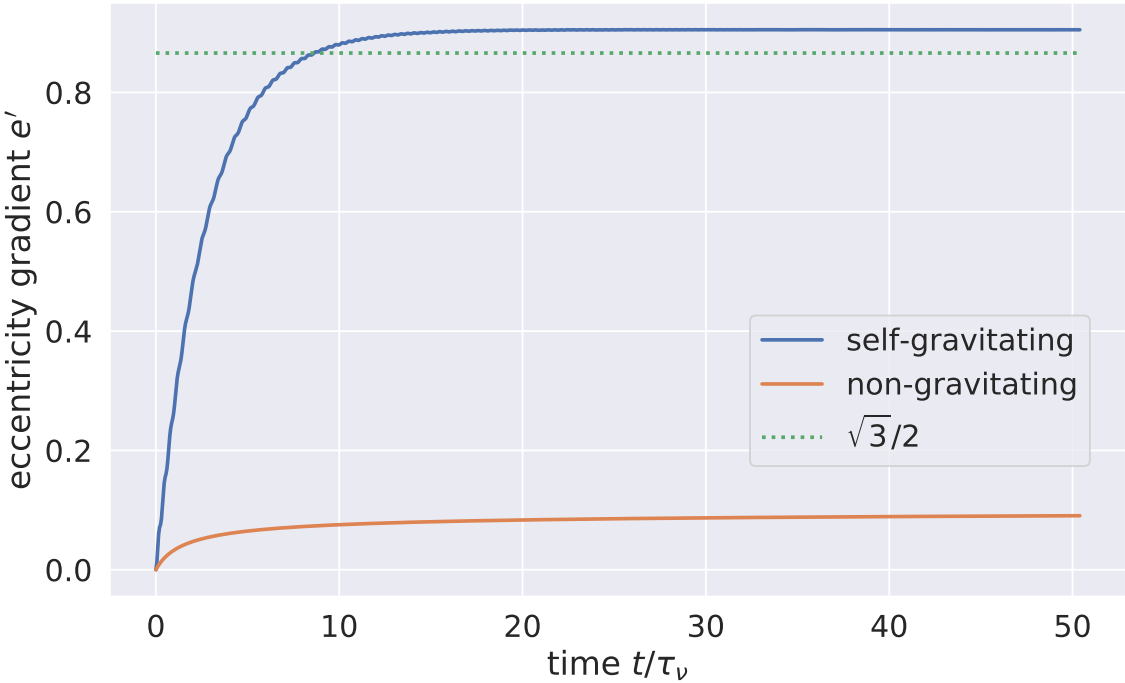


Figure 25. blah