

Analysis of Algorithms, I

CSOR W4231

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Asymptotic notation, mergesort, recurrences

Outline

- 1 Asymptotic notation
- 2 The divide & conquer principle; application: mergesort
- 3 Solving recurrences and running time of mergesort

Review of the last lecture

- ▶ Introduced the problem of **sorting**.
- ▶ Analyzed **insertion-sort**.
 - ▶ Worst-case running time: $T(n) = \frac{3n^2}{2} + \frac{7n}{2} - 4$
 - ▶ Space: **in-place** algorithm
- ▶ **Worst-case running time analysis:** a reasonable measure of algorithmic efficiency.
- ▶ Defined polynomial-time algorithms as “efficient”.
- ▶ Argued that detailed characterizations of running times are not convenient for understanding scalability of algorithms.

Running time in terms of # primitive steps

We need a coarser classification of running times of algorithms;
exact characterizations

- ▶ are **too detailed**;
- ▶ do not reveal similarities between running times in an immediate way as n grows large;
- ▶ are often **meaningless**: high-level language steps will **expand** by a constant factor that depends on the hardware.

Today

1 Asymptotic notation

Can be tight or not tight
tight if the 2 functions you're
comparily are growly @ the same rate.
not tight - one of the 2 functions is
growing strictly faster than the other.

2 The divide & conquer principle; application: mergesort

3 Solving recurrences and running time of mergesort

Aymptotic analysis

A framework that will allow us to compare the **rate of growth** of different running times as the input size n grows.

- ▶ We will express the running time as a function of the number of primitive steps; the latter is a function of the input size n .
- ▶ To compare functions expressing running times, **we will ignore their low-order terms and focus solely on the highest-order term.**

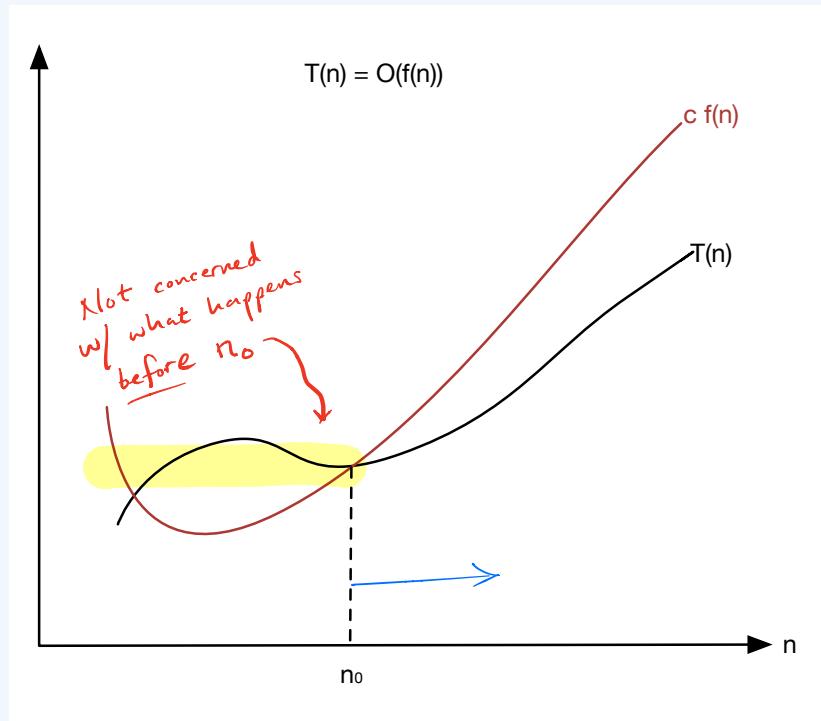
Asymptotic upper bounds: Big- O notation

Definition 1 (O).

We say that $T(n) = O(f(n))$ if there exist constants $c > 0$ and $n_0 \geq 0$ s.t. for all $n \geq n_0$, we have $T(n) \leq c \cdot f(n)$.

$T(n)$ grows
at most as
fast as $f(n)$

$T(n) = O(f(n))$
if \exists some $c > 0$
and $n_0 \geq 0$ s.t.
and $\forall n \geq n_0$ we have
 $T(n) \leq c \cdot f(n)$



After n_0 ,
 $T(n)$ is always
upperbounded by
a constant multiple
of $f(n)$.

Asymptotic upper bounds: Big- O notation

Definition 1 (O).

We say that $T(n) = O(f(n))$ if there exist constants $c > 0$ and $n_0 \geq 0$ s.t. for all $n \geq n_0$, we have $T(n) \leq c \cdot f(n)$.

Examples: Show that $T(n) = O(f(n))$ when

- (1) ► $T(n) = an^2 + b$, $a, b > 0$ constants and $f(n) = n^2$.
- (2) ► $T(n) = an^2 + b$ and $f(n) = n^3$.

$$(1) \quad an^2 + b \leq \underline{c} \cdot \underline{n^2} \quad \text{for all } n \geq \underline{n_0}$$

for your choice of \underline{c} and $\underline{n_0}$

$c = a + b$, $n_0 = 1$ There are many pairs
 (c, n_0) that satisfies this.

$$(2) \quad an^2 + b \leq \underline{c} \cdot \underline{n^3} \quad \text{for all } n \geq \underline{n_0}$$

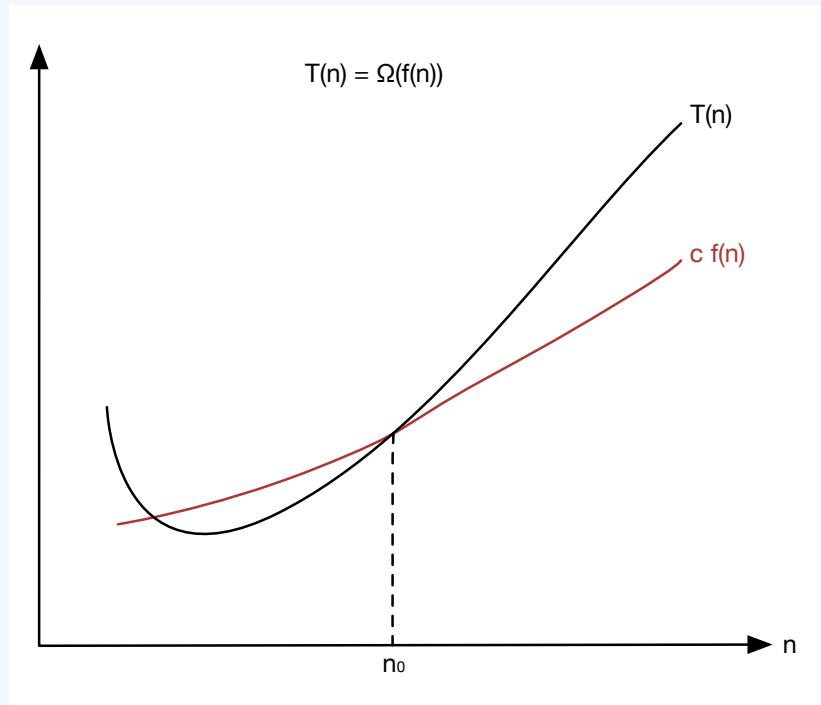
$c = a + b$, $n_0 = 1$ works here as well.

Asymptotic lower bounds: Big- Ω notation

Definition 2 (Ω).

We say that $T(n) = \Omega(f(n))$ if there exist constants $c > 0$ and $n_0 \geq 0$ s.t. for all $n \geq n_0$, we have $T(n) \geq c \cdot f(n)$.

$T(n)$ grows
at least as
fast as $f(n)$



After n_0 ,
 $T(n)$ is always
lower-bounded
by a constant
multiple of $f(n)$

Asymptotic lower bounds: Big- Ω notation

Definition 2 (Ω).

We say that $T(n) = \Omega(f(n))$ if there exist constants $c > 0$ and $n_0 \geq 0$ s.t. for all $n \geq n_0$, we have $T(n) \geq c \cdot f(n)$.

Examples: Show that $T(n) = \Omega(f(n))$ when

- (1) ► $T(n) = an^2 + b$, $a, b > 0$ constants and $f(n) = n^2$.
- (2) ► $T(n) = an^2 + b$, $a, b > 0$ constants and $f(n) = n$.

$$(1) \quad an^2 + b \geq c \cdot n^2 \quad \text{for all } n \geq n_0$$

\uparrow \uparrow
 a 1

$$(2) \quad an^2 + b \geq c \cdot n \quad , \quad \text{use } c=a$$

and $n_0=1$

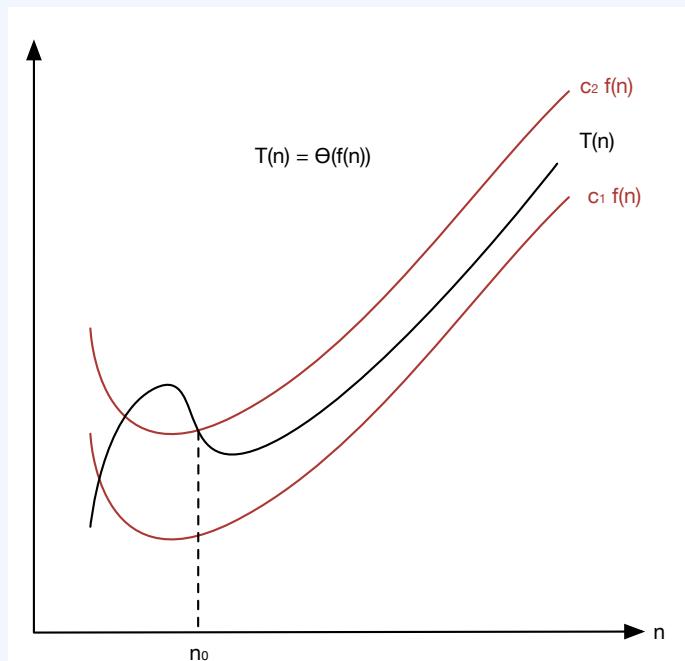
$an^2 + b$ and
 n^2 grow @
the same rate,
so of course you
can lowerbound
 $an^2 + b$ by some
constant multiple
of n^2 .

Asymptotic tight bounds: Θ notation

Definition 3 (Θ).

We say that $T(n) = \Theta(f(n))$ if there exist constants $c_1, c_2 > 0$ and $n_0 \geq 0$ s.t. for all $n \geq n_0$, we have

$$c_1 \cdot f(n) \leq T(n) \leq c_2 \cdot f(n).$$



Asymptotic tight bounds: Θ notation

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We say that $T(n) = \Theta(f(n))$ if there exist constants $c_1, c_2 > 0$ and $n_0 \geq 0$ s.t. for all $n \geq n_0$, we have

$$c_1 \cdot f(n) \leq T(n) \leq c_2 \cdot f(n).$$

Equivalent definition

$$T(n) = \Theta(f(n)) \text{ if } T(n) = O(f(n)) \text{ and } T(n) = \Omega(f(n))$$

$T(n)$ grows at most as fast as $f(n)$ and at least as fast as $f(n)$ $\implies T(n)$ and $f(n)$ grow at the same rate.

(+) : a tight bound means that the 2 functions grow at the same rate.

Asymptotic tight bounds: Θ notation

Definition 3 (Θ).

We say that $T(n) = \Theta(f(n))$ if there exist constants $c_1, c_2 > 0$ and $n_0 \geq 0$ s.t. for all $n \geq n_0$, we have

$$c_1 \cdot f(n) \leq T(n) \leq c_2 \cdot f(n).$$

Equivalent definition

$$T(n) = \Theta(f(n)) \quad \text{if} \quad T(n) = O(f(n)) \text{ and } T(n) = \Omega(f(n))$$

$$c_1 n \log n \leq n \log n + n \leq c_2 n \log n$$

$$\begin{aligned} c_1 &= 1 & n_0 &= 2 \\ c_2 &= 2 \end{aligned}$$

Notational convention: $\log n$ stands for $\log_2 n$

Examples: Show that $T(n) = \Theta(f(n))$ when

- $T(n) = an^2 + b$, $a, b > 0$ constants and $f(n) = n^2$
- $T(n) = n \log n + n$ and $f(n) = n \log n$

The $n \log_2 n$ term grows much faster than the n term which becomes negligible compared to $n \log_2 n$ as the input size increases.

Have shown
that
 $T(n) = O(f(n))$
 $T(n) = \Omega(f(n))$

$$c_1 \cdot n \log n \leq n \cdot \log n + n \leq c_2 \cdot n \log n$$

$\forall n \geq n_0$

Pick $c_1 = 1$, $c_2 = 2$, $n_0 = 2$:

$$\begin{aligned} n \log n &\leq n \log n + n \leq 2n \log n \\ &= n \log n + n \log n \end{aligned}$$

$\forall n \geq 2$

Asymptotic upper bounds that are **not** tight: little- o

Definition 4 (o).

We say that $T(n) = o(f(n))$ if, for any constant $c > 0$, there exists a constant $n_0 \geq 0$ such that for all $n \geq n_0$, we have $T(n) < c \cdot f(n)$.

→ No matter how tiny you pick c , $T(n)$ will always be less than $c \cdot f(n)$ for a large enough input size.
⇒ $f(n)$ grows much faster than $T(n)$

Asymptotic upper bounds that are **not** tight: little-*o*

Definition 4 (*o*).

We say that $T(n) = o(f(n))$ if, **for any** constant $c > 0$, there exists a constant $n_0 \geq 0$ such that for all $n \geq n_0$, we have $T(n) < c \cdot f(n)$.

- ▶ Intuitively, $T(n)$ becomes **insignificant** relative to $f(n)$ as $n \rightarrow \infty$.
- ▶ Proof by showing that $\lim_{n \rightarrow \infty} \frac{T(n)}{f(n)} = 0$ (if the limit exists).

Asymptotic upper bounds that are **not** tight: little-*o*

When we look for improvements in our algorithms, we will be looking for running times that compare in this fashion. The new running time will be little-*o* of the old running time. Because this is a meaningful improvement.

Definition 4 (*o*).

We say that $T(n) = o(f(n))$ if, for any constant $c > 0$, there exists a constant $n_0 \geq 0$ such that for all $n \geq n_0$, we have $T(n) < c \cdot f(n)$.

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Examples: Show that $T(n) = o(f(n))$ when

- (1) ▶ $T(n) = an^2 + b$, $a, b > 0$ constants and $f(n) = n^3$.
- (2) ▶ $T(n) = n \log n$ and $f(n) = n^2$. \hookrightarrow

$$(1) \lim_{n \rightarrow \infty} \frac{an^2 + b}{n^3} = 0$$

$$(2) \lim_{n \rightarrow \infty} \frac{n \log n}{n^2} = \lim_{n \rightarrow \infty} \frac{\log n}{n} = \lim_{n \rightarrow \infty} \frac{1}{n} = 0$$

Asymptotic lower bounds that are **not** tight: little- ω

Definition 5 (ω).

We say that $T(n) = \omega(f(n))$ if, **for any** constant $c > 0$, there exists a constant $n_0 \geq 0$ such that for all $n \geq n_0$, we have

$$T(n) > c \cdot f(n).$$

* $T(n)$ grows much faster than $f(n)$ no matter the value of c .

Asymptotic lower bounds that are **not** tight: little- ω

Definition 5 (ω).

We say that $T(n) = \omega(f(n))$ if, **for any** constant $c > 0$, there exists a constant $n_0 \geq 0$ such that for all $n \geq n_0$, we have $T(n) > c \cdot f(n)$.

- * ► Intuitively $T(n)$ becomes **arbitrarily large** relative to $f(n)$, as $n \rightarrow \infty$.
- $T(n) = \omega(f(n))$ implies that $\lim_{n \rightarrow \infty} \frac{T(n)}{f(n)} = \infty$, if the limit exists. Then $f(n) = o(T(n))$.
- Equivalently, we can show that $\lim_{n \rightarrow \infty} \frac{f(n)}{T(n)} = 0$

If the limit of $\frac{T(n)}{f(n)}$ or $\frac{f(n)}{T(n)}$ is some constant c , then $T(n) = \Theta(f(n))$ and $f(n) = \Theta(T(n))$.

Asymptotic lower bounds that are **not** tight: little- ω

Definition 5 (ω).

We say that $T(n) = \omega(f(n))$ if, **for any** constant $c > 0$, there exists a constant $n_0 \geq 0$ such that for all $n \geq n_0$, we have $T(n) > c \cdot f(n)$.

- ▶ Intuitively $T(n)$ becomes **arbitrarily large** relative to $f(n)$, as $n \rightarrow \infty$.
- ▶ $T(n) = \omega(f(n))$ implies that $\lim_{n \rightarrow \infty} \frac{T(n)}{f(n)} = \infty$, if the limit exists. Then $f(n) = o(T(n))$.

Examples: Show that $T(n) = \omega(f(n))$ when

- ▶ $T(n) = n^2$ and $f(n) = n \log n$. $\xrightarrow{\text{Previously shown that}} n \log n = o(n^2)$
- ▶ $T(n) = 2^n$ and $f(n) = n^5$.
$$\lim_{n \rightarrow \infty} \frac{2^n}{n^5} \xrightarrow{\text{L'H}} \lim_{n \rightarrow \infty} \frac{2^n \cdot c}{5!} = \infty \Rightarrow 2^n = \omega(n^5)$$

Basic rules for omitting low order terms from functions

1. Ignore **multiplicative** factors: e.g., $10n^3$ becomes n^3
 2. n^a dominates n^b if $a > b$: e.g., n^2 dominates n
 3. Exponentials dominate polynomials: e.g., 2^n dominates n^4
 4. Polynomials dominate logarithms: e.g., n dominates $\log^3 n$
- ⇒ For large enough n ,

$$\log n < n < n \log n < n^2 < 2^n < 3^n < n^n$$

$$n! = 1 \cdot 2 \cdot 3 \cdots n$$

$$3^3 = 27$$

$$3! = 6$$

$$\begin{aligned}3^3 &= 27 \\3! &= 6\end{aligned}$$

Properties of asymptotic growth rates

$$\left. \begin{array}{l} 2n = O(n) \\ 5n = O(n) \\ 7n = O(n) \end{array} \right\} \begin{array}{l} \text{and} \\ 2n + 5n = O(n) \\ 2n + 5n + 7n = O(n) \end{array}$$

1. Transitivity

- 1.1 If $f = O(g)$ and $g = O(h)$, then $f = O(h)$.
- 1.2 If $f = \Omega(g)$ and $g = \Omega(h)$, then $f = \Omega(h)$.
- 1.3 If $f = \Theta(g)$ and $g = \Theta(h)$, then $f = \Theta(h)$.

2. Sums of up to a constant number of functions

- 2.1 If $f = O(h)$ and $g = O(h)$, then $f + g = O(h)$.
- 2.2 Let k be a fixed constant, and let f_1, f_2, \dots, f_k, h be functions such that for all i , $f_i = O(h)$. Then
 $f_1 + f_2 + \dots + f_k = O(h)$.

Must be
a constant
number of
functions.

3. Transpose symmetry

- $f = O(g)$ if and only if $g = \Omega(f)$.
- $f = o(g)$ if and only if $g = \omega(f)$.

$$c \cdot O(f) = O(f)$$

$$O(f) \cdot O(g) = O(fg)$$

$$\text{Indeed, } O(f) = c \cdot f$$

$$O(g) = c'g$$

$$cf c'g = c''fg = O(fg)$$

Today

- 1 Asymptotic notation
- 2 The divide & conquer principle; application: mergesort
- 3 Solving recurrences and running time of mergesort

The divide & conquer principle

- ▶ **Divide** the problem into a number of subproblems that are smaller instances of the same problem.
- ▶ **Conquer** the subproblems by solving them recursively.
- ▶ **Combine** the solutions to the subproblems to get the solution to the overall problem.

Divide & Conquer applied to sorting

- ▶ **Divide** the problem into a number of subproblems that are smaller instances of the same problem.
Divide the input array into two lists of equal size.
- ▶ **Conquer** the subproblems by solving them recursively.
Sort each list recursively. (Stop when lists have size 2.)
- ▶ **Combine** the solutions to the subproblems into the solution for the original problem.
Merge the two sorted lists and output the sorted array.

mergesort: pseudocode

$1 \quad n$

mergesort ($A, left, right$)

if $right == left$ then return \leftarrow if size of array is 1

end if

$mid = left + \lfloor (right - left)/2 \rfloor$

mergesort ($A, left, mid$)

mergesort ($A, mid + 1, right$)

merge ($A, left, right, mid$)

All the work
occurs in merge(.)

Extra Space req'd: n

merge ($A, left, mid, right$) ?

Remarks

Extra Space req'd by mergesort : n (Because you
can reuse space.)
(worse than insertion sort)

- mergesort is a recursive procedure (why?) Because it calls itself.
mergesort sorts by calling itself.
It doesn't call any other sorting algorithm.
- Initial call: mergesort($A, 1, n$)
- Subroutine merge merges two sorted lists of sizes $\lfloor n/2 \rfloor, \lceil n/2 \rceil$ into one sorted list of size n . How can we accomplish this?

Prove correctness of mergesort by induction.

Proof of correctness of mergesort (By induction)

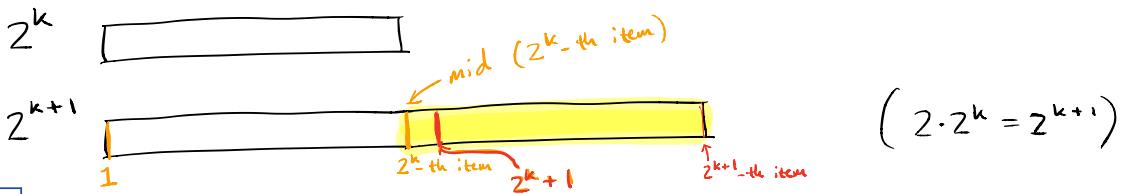
Pf: Spz $n = 2^k$ (In HW have to prove for ANY input size).

Base Case : $k=0 \Rightarrow n=1$

Is mergesort correct on $n=1$? Yes, it does nothing.

Ind. Hyp. : Mergesort sorts correctly for some input size
 $n = 2^k \geq 1$

Step: Show mergesort sorts correctly for input size 2^{k+1}



Run mergesort on the first half. The output would be the sorted half since mergesort is correct on input size 2^k .

$$\underline{\text{mid} = 2^k}$$

Then run mergesort on the second half, which is also of size 2^k since $2^{k+1} = 2 \cdot 2^k = 2^k + 2^k$.

Run mergesort on list/array $(2^k+1, 2^{k+1})$, and again mergesort will have sorted correctly since the input size of second half is 2^k .

$$\Downarrow \text{mid} = 2^k$$

$$\begin{aligned} \text{mid} &= 1 + \lfloor (2^{k+1}-1)/2 \rfloor = 1 + \lfloor 2^k - \frac{1}{2} \rfloor = 1 + 2^k - 1 \\ &= 2^k \end{aligned}$$

Next, merge the two sorted halves into a sorted output, and you know that this will be done correctly because merge is correct (which we have to prove on our own - that merge is correct).

```

Mergesort ( $A, left, right$ )
if  $right == left$  then return
end if
 $mid = left + \lfloor (right - left)/2 \rfloor$ 
Mergesort ( $A, left, mid$ )
Mergesort ( $A, mid + 1, right$ )
Merge ( $A, left, right, mid$ )

```

$$mid = 2^k$$

$\text{mergesort}(A, 1, 2^k)$

$\text{mergesort}(A, 2^k+1, 2^{k+1})$

$\text{Merge}(A, 1, 2^{k+1}, 2^k)$

The output from each $\text{mergesort}(\cdot)$ call would be the sorted arrays, since by the Induction Hypothesis, mergesort correctly sorts arrays up to size 2^k .

Running Time of mergesort

$n \log n$, why?

- * Because merge takes $O(n)$ time and you call it $\log n$ times.

Let $T(n)$ be the running time of mergesort on input size n .

$$T(n) = c + T\left(\frac{n}{2}\right) + T\left(\frac{n}{2}\right) + cn$$

$$(*) = cn + 2T\left(\frac{n}{2}\right)$$

Still need to determine asymptotic solution.
Have to solve the recurrence expression (*)

↑
absorbed all constants since we are only interested in asymptotic solution.

mergesort ($A, left, right$)

$c \rightarrow$ if $right == left$ then return
end if

$c \rightarrow mid = left + \lfloor (right - left)/2 \rfloor$

Because we are running mergesort on half the input size.

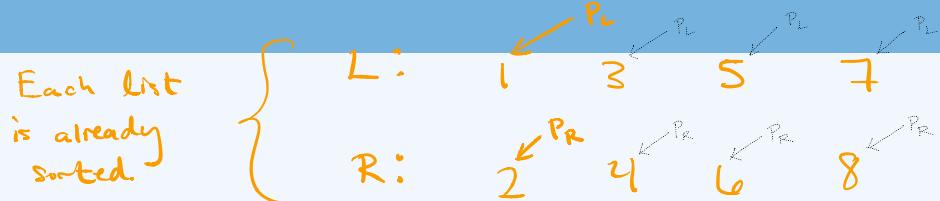
$\left\{ \begin{array}{l} T\left(\frac{n}{2}\right) \rightarrow \text{mergesort } (A, left, mid) \\ T\left(\frac{n}{2}\right) \rightarrow \text{mergesort } (A, mid + 1, right) \\ O(n) \rightarrow \text{merge } (A, left, right, mid) \end{array} \right.$

$$\boxed{T(n) = 2T\left(\frac{n}{2}\right) + cn}$$

$$T(1) = 2T\left(\frac{1}{2}\right) + c = c$$

merge: intuition

Merging Two sorted lists:

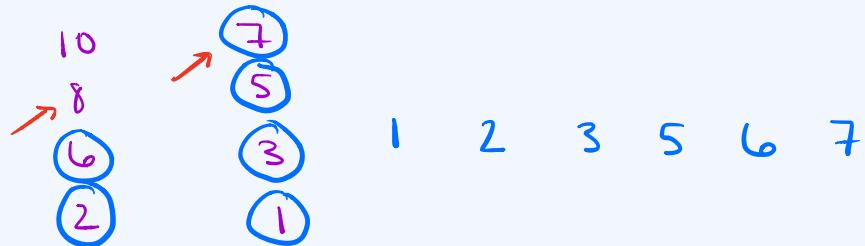


Merge them: Append P_L and P_R to an empty list. Compare the 2 elements and arrange if needed. Advance the pointer down the list and repeat.

Intuition: To merge two sorted lists of size $n/2$ repeatedly

- ▶ compare the two items in the front of the two lists;
- ▶ extract the smaller item and append it to the output;
- ▶ update the front of the list from which the item was extracted.

Example: $n = 8, L = \{1, 3, 5, 7\}, R = \{2, 6, 8, 10\}$



merge: pseudocode

say

$1 \ n \ n/2$

merge ($A, left, right, mid$)

$1 \ n/2$

$\rightarrow L = A[left, mid]$

$\rightarrow R = A[mid + 1, right]$

} Copy each element
of A in future lists

Then what are the space requirements
of merge on input size n ?

n : it allocates $n + \text{constant number}$ of memory
locations, but it's $O(n)$.

Here we need
 n extra
memory locations
because we are
copying the entire
input to 2 lists.

Maintain two pointers p_L, p_R , initialized to point to the first elements of L, R , respectively

while both lists are nonempty **do**

 Let x, y be the elements pointed to by p_L, p_R

 Compare x, y and append the smaller to the output

 Advance the pointer in the list with the smaller of x, y

end while

Append the remainder of the non-empty list to the output.

Remark: the output is stored directly in $A[left, right]$, thus the subarray $A[left, right]$ is sorted after $\text{merge}(A, left, right, mid)$.

How to prove correctness?

A: Induction on the size of the 2 lists

[will typically prove correctness
by induction.]

merge: pseudocode

TIME Requirements:

merge ($A, left, right, mid$)

- $L = A[left, mid]$ ← Time required? You are copying over $n/2$ memory locations into the array L . This requires $\underline{\mathcal{O}(n)}$ time.
- $R = A[mid + 1, right]$ ← Also requires $\underline{\mathcal{O}(n)}$ time.

Maintain two pointers p_L, p_R , initialized to point to the first → $\mathcal{O}(1)$ elements of L, R , respectively

Initialization of pointers requires $\mathcal{O}(1)$ time.

while both lists are nonempty do ← Initializing the pointers: $\mathcal{O}(1)$

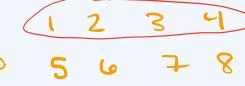
$\mathcal{O}(1) \rightarrow$ Let x, y be the elements pointed to by p_L, p_R

$\mathcal{O}(1) \rightarrow$ Compare x, y and append the smaller to the output

$\mathcal{O}(1) \rightarrow$ Advance the pointer in the list with the smaller of x, y

end while $n \cdot \mathcal{O}(1) = \underline{\mathcal{O}(n)}$

$\mathcal{O}(n)$ → Append the remainder of the non-empty list to the output.

$\mathcal{O}(n)$: Because in the worst case, your lists could be  The top list would append first. Remainder: $n/2 \rightarrow 5 \ 6 \ 7 \ 8$

Remark: the output is stored directly in $A[left, right]$, thus the subarray $A[left, right]$ is sorted after $\text{merge}(A, left, right, mid)$.

Total Time in Algorithm : $\mathcal{O}(n) + \mathcal{O}(n) + \mathcal{O}(1) + \mathcal{O}(n) + \mathcal{O}(n)$
 $= \mathcal{O} n$

merge: pseudocode

Space Requirement : $O(n)$ - It reuses space ,

merge ($A, left, right, mid$)

$L = A[left, mid]$

$R = A[mid + 1, right]$

but is not an
in-place algorithm.

Maintain two pointers p_L, p_R , initialized to point to the first elements of L, R , respectively

while both lists are nonempty **do**

 Let x, y be the elements pointed to by p_L, p_R

 Compare x, y and append the smaller to the output

 Advance the pointer in the list with the smaller of x, y

end while

Append the remainder of the non-empty list to the output.

Remark: the output is stored directly in $A[left, right]$, thus the subarray $A[left, right]$ is sorted after $\text{merge}(A, left, right, mid)$.

merge: optional exercises

Optional exercise 1: write detailed pseudocode or actual code for `merge`

Optional exercise 2: write a recursive `merge`

Analysis of merge

1. Correctness
2. Running time
3. Space

Analysis of merge: correctness

1. **Correctness:** by induction on the size of the two lists
(recommended exercise)
2. **Running time**
3. **Space**

merge: pseudocode

`merge ($A, left, right, mid$)`

$L = A[left, mid]$ →not a primitive computational step!

$R = A[mid + 1, right]$ →not a primitive computational step!

Maintain two pointers p_L, p_R initialized to point to the first elements of L, R , respectively

while both lists are nonempty **do**

 Let x, y be the elements pointed to by p_L, p_R

 Compare x, y and append the smaller to the output

 Advance the pointer in the list with the smaller of x, y

end while

Append the remainder of the non-empty list to the output.

Remark: the output is stored directly in $A[left, right]$, thus the subarray $A[left, right]$ is sorted after `merge($A, left, right, mid$)`.

Analysis of merge: running time

1. **Correctness:** by induction on the size of the two lists
(recommended exercise)
2. **Running time:**
 - ▶ Suppose L, R have $n/2$ elements each
 - ▶ *How many iterations before all elements from both lists have been appended to the output?*
 - ▶ *How much work within each iteration?*
3. **Space**

Analysis of `merge`: space

1. **Correctness:** by induction on the size of the two lists
(recommended exercise)
2. **Running time:**
 - ▶ L, R have $n/2$ elements each
 - ▶ *How many iterations before all elements from both lists have been appended to the output?* At most $n - 1$.
 - ▶ *How much work within each iteration?* Constant.
⇒ `merge` takes $O(n)$ time to merge L, R (*why?*).
3. **Space:** extra $\Theta(n)$ space to store L, R (the output of `merge` is stored directly in A).

Refreshing your memory on recursive algorithms

Exercise (recommended): run `mergesort` on input
1, 7, 4, 3, 5, 8, 6, 2.

Analysis of mergesort

1. **Correctness**
2. **Running time**
3. **Space**

`mergesort`: correctness

For simplicity, assume $n = 2^k$ for integer $k \geq 0$.

We will use induction on k .

- ▶ **Base case:** For $k = 0$, the input consists of 1 item; `mergesort` returns the item.
- ▶ **Induction Hypothesis:** For $k \geq 0$, assume that `mergesort` correctly sorts any list of size 2^k .
- ▶ **Induction Step:** We will show that `mergesort` correctly sorts any list A of size 2^{k+1} .

From the pseudocode of `mergesort`, we have:

- ▶ Line 3: mid takes the value 2^k
 - ▶ Line 4: `mergesort`($A, 1, 2^k$) correctly sorts the leftmost half of the input, by the induction hypothesis.
 - ▶ Line 5: `mergesort`($A, 2^k + 1, 2^{k+1}$) correctly sorts the rightmost half of the input, by the induction hypothesis.
 - ▶ Line 6: `merge` correctly merges its two sorted input lists into one sorted output of size $2^k + 2^k$.
- ⇒ `mergesort` correctly sorts any input of size 2^{k+1} .

Running time of mergesort

Much more efficient than insertion sort.

Note: $n \log n = O(n^2)$

little-o

The running time of mergesort satisfies:

$$T(n) = 2T(n/2) + cn, \text{ for } n \geq 2, \text{ constant } c > 0$$

$$T(1) = c$$

Therefore,
this alg.
is much
more efficient

than insertion sort.

For $n = 10^6$:

$n \log n$ requires $20 \cdot 10^6$

n^2 requires
 $10^6 \cdot 10^6$.

This structure is typical of **recurrence relations**

- an **inequality** or **equation** bounds $T(n)$ in terms of an expression involving $T(m)$ for $m < n$
- a base case generally says that $T(n)$ is constant for small constant n

Remarks

* ► We ignore floor and ceiling notations.

We don't know just by looking that

$$T(n) = O(n \log n).$$

► A recurrence does **not** provide an asymptotic bound for $T(n)$: to this end, we must **solve** the recurrence.

Need to
solve the recurrence
to determine this.

Today

- 1 Asymptotic notation
- 2 The divide & conquer principle; application: mergesort
- 3 Solving recurrences and running time of mergesort

Solving recurrences, method 1: recursion trees

The technique consists of three steps

1. Analyze the first few levels of the tree of recursive calls
2. Identify a pattern
3. Sum the work spent over all levels of recursion

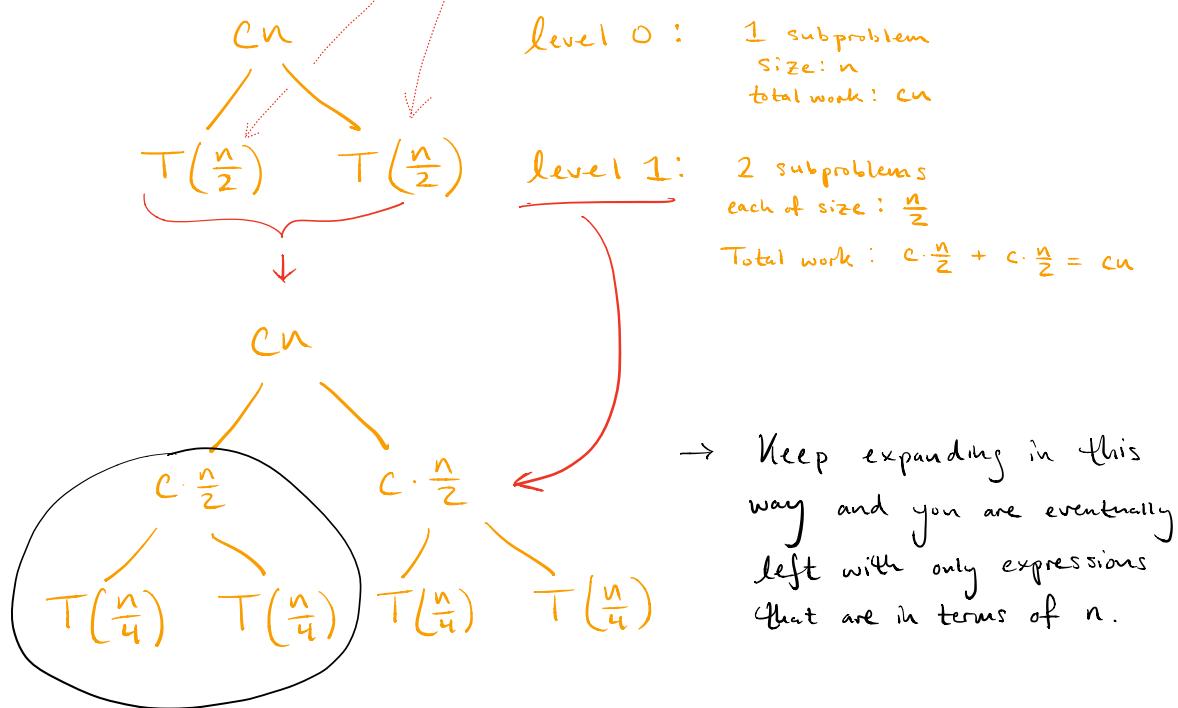
Example: give an asymptotic bound for the recurrence
describing the running time of `mergesort`

$$T(n) = 2T(n/2) + cn, \text{ for } n \geq 2, \text{ constant } c > 0$$
$$T(1) = c$$

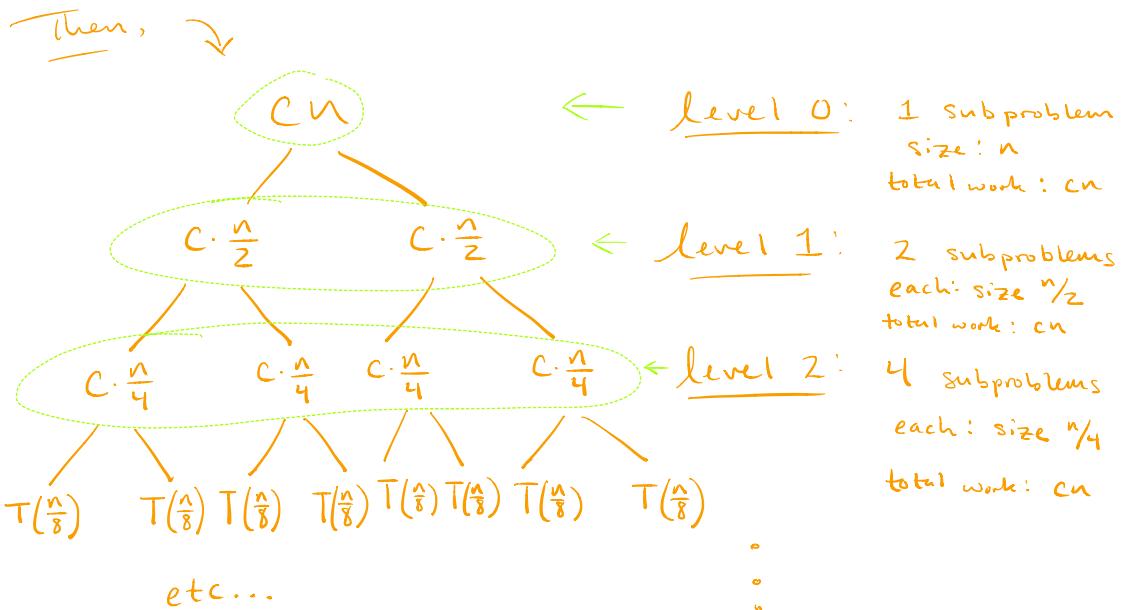
$$T(n) = 2T(n/2) + cn,$$

$$T(1) = c$$

$$T\left(\frac{n}{2}\right) = 2T\left(\frac{n}{4}\right) + c \cdot \frac{n}{2}$$



$$T\left(\frac{n}{4}\right) = 2T\left(\frac{n}{8}\right) + c \cdot \frac{n}{4}$$

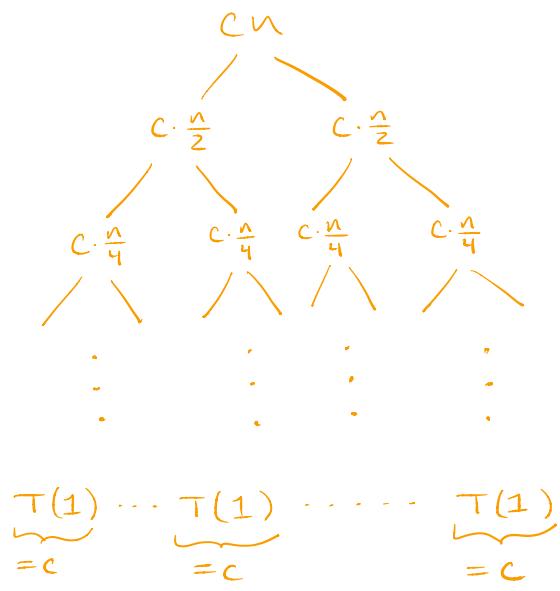


level i : 2^i subproblems

each: size $\frac{n}{2^i}$

total work.: cn

$$(\underline{= 2^i \cdot c \cdot \frac{n}{2^i} = cn})$$



size of each subproblem
is $\frac{n}{2^d} = 1 \Rightarrow d = \log_2 n$

so the depth of
this tree is $\log_2 n$

The tree will eventually
bottom out at some level
 d . It bottoms out because
at the bottom level, each
subproblem will have size 1.
At that point, mergesort will
just terminate.

We reach level d when the
size of the subproblem is 1.

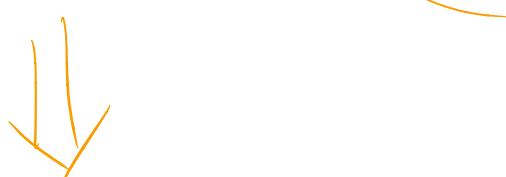
level d : 2^d subproblems

each size: $\frac{n}{2^d} = 1$

$$\Rightarrow n = 2^d$$

$$\Rightarrow \log_2 n = \log_2 2^d$$

$$\Leftrightarrow d = \log_2 n$$



$T(n)$ is the sum of ALL the work spent on every level of the tree :

$$\begin{aligned}
 T(n) &= \sum_{i=0}^d cn = (d+1) \cdot cn \\
 &= (\log_2 n + 1) \cdot cn \\
 &= \Theta(n \log n)
 \end{aligned}$$

Therefore, the running time of mergesort is $\Theta(n \log n)$.

$$\begin{aligned}
 \overline{T(n)} &= 2T\left(\frac{n}{2}\right) + cn = 2\left(2T\left(\frac{n}{4}\right) + c\frac{n}{2}\right) + cn \\
 &= 4T\left(\frac{n}{4}\right) + 2cn \\
 &= 4\left(2T\left(\frac{n}{8}\right) + c\frac{n}{4}\right) + 2cn \\
 &= 8T\left(\frac{n}{8}\right) + cn + 2cn = 8T\left(\frac{n}{8}\right) + 3cn \\
 &= T(n) \\
 T(n) &= 8\left(2T\left(\frac{n}{16}\right) + c\frac{n}{8}\right) + 3cn = 16T\left(\frac{n}{16}\right) + 4cn \dots
 \end{aligned}$$

A general recurrence and its solution

The running times of many recursive algorithms can be expressed by the following recurrence

$$T(n) = aT(n/b) + cn^k, \text{ for } a, c > 0, b > 1, k \geq 0$$

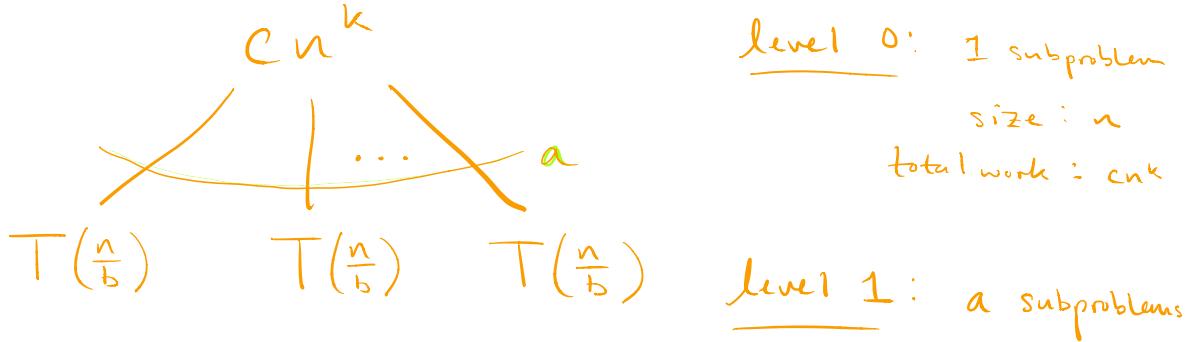
What is the recursion tree for this recurrence?

- ▶ a is the branching factor
 - ▶ b is the factor by which the size of each subproblem shrinks
- ⇒ at level i , there are a^i subproblems, each of size n/b^i
- ⇒ each subproblem at level i requires $c(n/b^i)^k$ work
- ▶ the height of the tree is $\log_b n$ levels
- ⇒ Total work: $\sum_{i=0}^{\log_b n} a^i c(n/b^i)^k = cn^k \sum_{i=0}^{\log_b n} \left(\frac{a}{b^k}\right)^i$

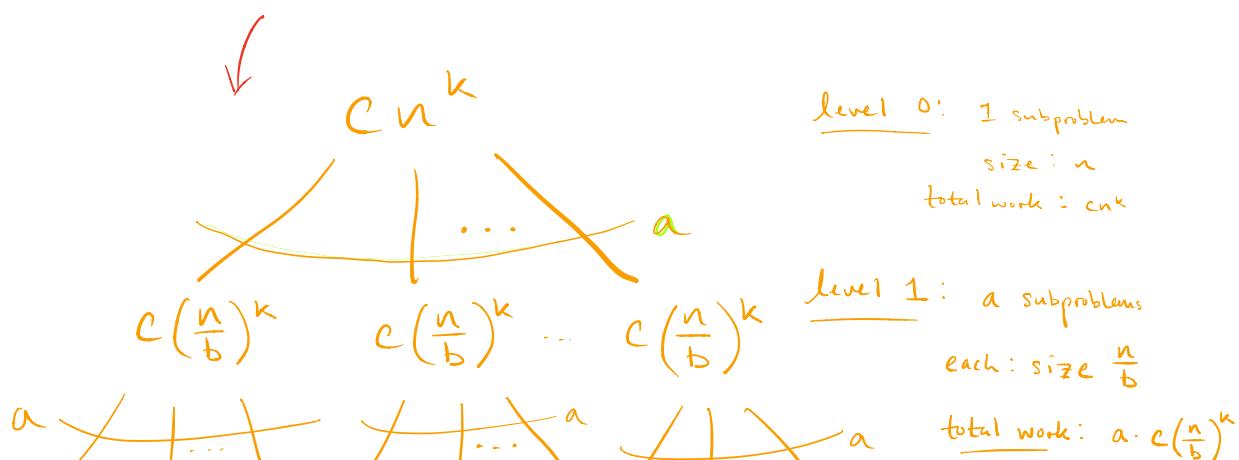
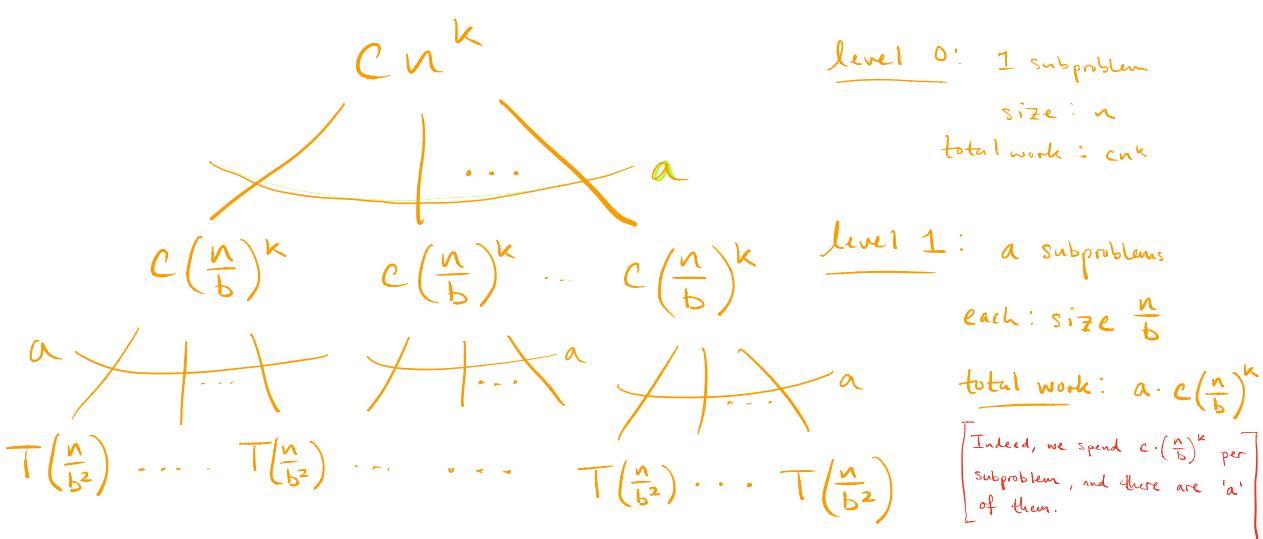
$$T(n) = aT\left(\frac{n}{b}\right) + cn^k,$$

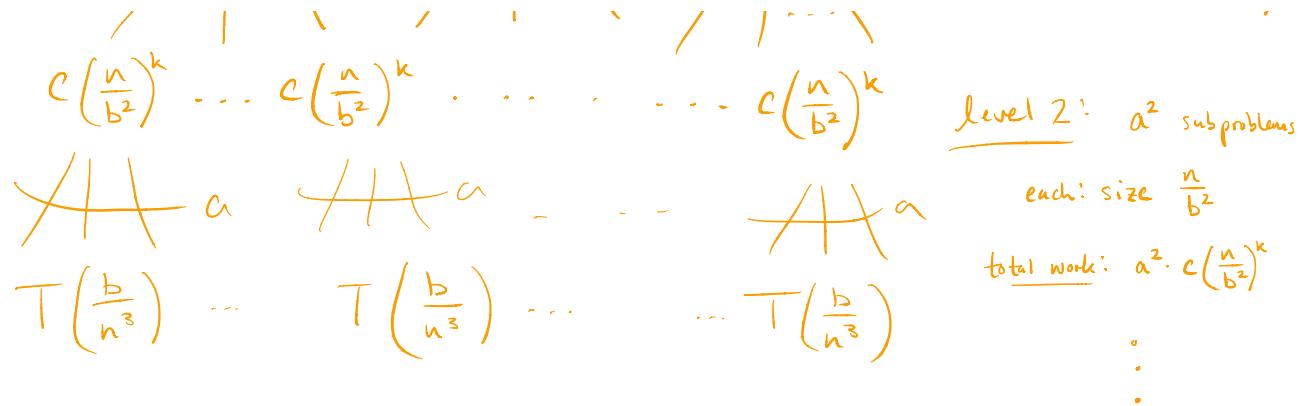
$$T\left(\frac{n}{b}\right) = aT\left(\frac{n}{b^2}\right) + c\left(\frac{n}{b}\right)^k$$

$$T\left(\frac{n}{b^2}\right) = aT\left(\frac{n}{b^3}\right) + c\left(\frac{n}{b^2}\right)^k$$



level 1: a subproblems





Bottoms out at some level d ,
where each subproblem is of size

$$\frac{n}{b^d} = 1 \Rightarrow d = \log_b n$$

level i : a^i subproblems

each: size $\frac{n}{b^i}$

total work: $a^i \cdot c\left(\frac{n}{b^i}\right)^k$

Tree bottoms out at
some level d , where
each subproblem is of size 1.

level d : a^d subproblems

each: size $\frac{n}{b^d} = 1$

$$\Rightarrow d = \log_b n$$

total work: $T(n)$



$$T(n) = \sum_{i=0}^d a^i \cdot c \cdot \left(\frac{n}{b^i}\right)^k = cn^k \cdot \sum_{i=0}^{\log_b n} \left(\frac{a}{b^k}\right)^i$$

$$\Leftrightarrow \boxed{T(n) = cn^k \cdot \sum_{i=0}^{\log_b n} \left(\frac{a}{b^k}\right)^i}$$

$$\left| \quad \quad \quad c=0 \quad \quad \quad \right|$$

- If $a = b^k \Rightarrow T(n) = (\log_b n + 1) \cdot cn^k$

$$T(n) = cn^k \cdot \sum_{i=0}^{\log_b n} 1 = (\log_b n + 1) \cdot cn^k = O(n^k \cdot \log_b n)$$

We can replace $\log_b n$ with $\log_2 n$ in asymptotic notation
(check)

Don't need to keep $\log_b(\cdot)$ in base b notation (why?) $= O(n^k \cdot \log n)$

- If $a < b^k \Rightarrow \dots \sum_{i=0}^{\log_b n} \left(\frac{a}{b^k}\right)^i = O(1)$
(In Homework)

$$\Rightarrow T(n) = O(n^k)$$

- If $a > b^k \Rightarrow \dots \sum_i \left(\frac{a}{b^k}\right)^i = O\left(\left(\frac{a}{b^k}\right)^{\log_b n}\right)$

$$= O\left(\frac{a^{\log_b n}}{b^{k \log_b n}}\right)$$

$$= O\left(\frac{n^{\log_b a}}{n^k}\right)$$

$$\Rightarrow T(n) = O(n^{\log_b a})$$

Recall / Review:

$$\boxed{\log_b n = \frac{\log_2 n}{\log_2 b}}$$

and

$$\frac{\log_2 n}{\log_2 b} > \log_2 n$$

but only by a constant factor.



For $a > b^k$: You are summing terms,

of a geometric progression, that are

continuously increasing. Therefore, the

last term of the (finite) sum

$$\sum_{i=0}^{\log_b n} \left(\frac{a}{b^k}\right)^i$$

is the largest.

Hence,

$$\sum \left(\frac{a}{b^k}\right)^i = \Theta\left(\left(\frac{a}{b^k}\right)^{\log_b n}\right) = \Theta\left(\frac{n^{\log_b a}}{n^k}\right)$$

$$\boxed{\left(\frac{a}{b^k}\right)^{\log_b n} = \frac{a^{\log_b n}}{b^{k \log_b n}} = \frac{n^{\log_b a}}{n^k}}$$

and so $Cn^k \sum_{i=0}^{\log_b n} \left(\frac{a}{b^k}\right)^i = Cn^k \Theta\left(\frac{n^{\log_b a}}{n^k}\right)$

$$\Rightarrow T(n) = \Theta(n^{\log_b a})$$

Solving recurrences, method 2: Master theorem

Theorem 6 (Master theorem).

If $T(n) = aT(\lceil n/b \rceil) + O(n^k)$ for some constants $a > 0$, $b > 1$, $k \geq 0$, then

$$T(n) = \begin{cases} O(n^{\log_b a}) & , \text{ if } a > b^k \\ O(n^k \log n) & , \text{ if } a = b^k \\ O(n^k) & , \text{ if } a < b^k \end{cases}$$

Example: running time of mergesort

► $T(n) = 2T(n/2) + cn$:

$$a = 2, b = 2, k = 1, b^k = 2 = a \Rightarrow T(n) = O(n \log n)$$

$$\begin{array}{c} k=1 \\ b=2, \quad a=1 \\ b^k=1, \quad a=1 \\ a \geq b^k \end{array}$$

Solving recurrences, method 3: the substitution method

The technique consists of two steps

1. Guess a bound
2. Use (strong) induction to prove that the guess is correct

(See your textbook for more details on this technique.)

Remark 1 (simple vs strong induction).

1. **Simple induction:** *the induction step at n requires that the inductive hypothesis holds at step $n - 1$.*
2. **Strong induction** *is just a variant of simple induction where the induction step at n requires that the inductive hypothesis holds at all previous steps $1, 2, \dots, n - 1$.*

How would you solve...

HINT: Use recursion trees to solve.

$$1. \ T(n) = 2T(n - 1) + 1, T(1) = 2$$

$$2. \ T(n) = 2T^2(n - 1), T(1) = 4$$

$$3. \ T(n) = T(2n/3) + T(n/3) + cn$$

$$\text{Ex: } T(n) = 4 T\left(\frac{n}{4}\right) + cn^k$$

$$\left. \begin{array}{l} a=4 \\ b=4 \\ k=1 \end{array} \right\} \quad b^k = 4 \Rightarrow a = b^k$$
$$\Rightarrow T(n) = O(n^k \log n)$$
$$= O(n \log n)$$