HW 10 R Code and Results

```
> #Problem A
> #Part (a)
> P = pnorm(3.5, mean = 0, sd = 1, lower.tail = FALSE) #Probability X
> 3.5 (Uppertail only)
> L = 2*P #Since N(0,1) is a symmetric distribution, P(abs(X) > 3.5)
= 2*P(X > 3.5)
> #Thus, 1 = P(abs(X) > 3.5) = 0.0004652582
>
> #Part (b) - Estimating using CMC
> set.seed(1)
> N = 10^5
                          #number of independent samples
> x = matrix(NA, N, 10); #storage for the 10 estimates
> H = matrix(NA, N, 10); #storage for the 10 estimates
> L.hat = matrix(NA, 1, 10);
> for(j in 1:10){
    x[,j] = rnorm(N, mean = 0, sd = 1) # sampling from f
    for (i in 1:N) {
      if (x[i,j] \ge qnorm(1-P)) {
+
        H[i,j] = 1
+
+
     else if (x[i,j] \le qnorm(P)) {
+
       H[i,j] = 1
+
      }
     else {
+
       H[i,j] = 0
+
    for(k in 1:10) {
     L.hat[,k] = (1/N)*sum(H[,k])
+
    }
+ }
> show(L.hat) #list of all 10 estimates of Prob(abs(X) >= 3.5)
        [,1]
               [,2]
                        [,3] [,4]
                                    [,5] [,6]
                                                   [,7]
                                                           [,8]
[,9]
[1,] 0.00047 0.00045 0.00054 5e-04 0.00044 3e-04 0.00037 0.00051
0.00058
       [,10]
[1,] 0.00044
> #Variance of L.hat:
> var.Lhat = (1/N)*(L - L^2)
> var.Lhat #Var(L.hat) = ~ 4.650417e-09
[1] 4.650417e-09
>
> #Part (c) - Estimating using IS with g = N(3.5, 1):
```

```
> y = matrix(NA, N, 10);
> h = matrix(NA, N, 10);
> w = matrix(NA, N, 10);
> f = matrix(NA, N, 10);
> g = matrix(NA, N, 10);
> Lhat.IS = matrix(NA, 1, 10);
> for(j in 1:10){
    y[,j] = rnorm(N, mean = 3.5, sd = 1) #sampling from g
    f[,j] = dnorm(y[,j], mean = 0, sd = 1)
    g[,j] = dnorm(y[,j], mean = 3.5, sd = 1)
    w[,j] = f[,j]/g[,j] #weights
    for (i in 1:N) {
      if (y[i,j] \ge qnorm(1-P)) {
+
        h[i,j] = 1
+
+
      else {
+
        h[i,j] = 0
+
+
    }
    for(k in 1:10) {
      Lhat.IS[,k] = 2*(1/N)*sum(h[,k]*w[,k]) #Since g is symmetric,
multiply
                                               #by 2 to attain an
estimate for
                                               #both tails.
      }
+ }
> show(Lhat.IS)
                         [,2]
             [,1]
                                       [,3]
                                                    [,4]
[1,] 0.0004628242 0.0004625311 0.000467592 0.0004650986 0.0004611431
                         [,7]
                                       [,8]
                                                    [,9]
[1,] 0.000460414 0.0004627089 0.0004642176 0.0004686603 0.0004671747
> #Variance of Lhat.IS:
> var.LhatIS = var(Lhat.IS[,])
> var.LhatIS #Variance of Importance Sampling estimate = ~ 7.958055e-
12
[1] 7.958055e-12
> #Part (d)
> #Relative Error, RE = sqrt(Var(L.hat))/E(L.hat) = sqrt(Var(L.hat))/L
> RE.Standard = sqrt(var.Lhat)/L
> RE.IS = sqrt(var.LhatIS)/L
> RE.Standard \#0.1465723 \sim 14.66\% error relative to the true value
[1] 0.1465723
> RE.IS #0.006063306 \sim 0.61% error relative to the true value
[1] 0.006063306
> #The Relative error for the Importance Sampling method is
significantly
> #smaller than the Relative Error for the standard CMC method. Thus,
the
```

```
> #relative accuracy of the IS estimates to the true value is much
greater
> #than that of the standard CMC estimates. Indeed, the IS method uses
> #standard normal distribution centered at 3.5, significantly
increasing the
> #probability that samples of X >= 3.5 are generated.
> #Extra Credit Part (e)
y = matrix(NA, N, 10);
h = matrix(NA, N, 10);
w = matrix(NA, N, 10);
f = matrix(NA, N, 10);
g = matrix(NA, N, 10);
Lhat. IS = matrix(NA, 1, 10);
for(j in 1:10){
  y[,j] = rnorm(N, mean = mu*, sd = 1) #sampling from g
  f[,j] = dnorm(y[,j], mean = 0, sd = 1)
  g[,j] = dnorm(y[,j], mean = mu*, sd = 1)
  w[,j] = f[,j]/g[,j] #weights
  for (i in 1:N) {
    if (y[i,j] \ge qnorm(1-P)) {
     h[i,j] = 1
    }
    else {
     h[i,j] = 0
    }
  for(k in 1:10) {
    Lhat.IS[,k] = 2*(1/N)*sum(h[,k]*w[,k]) #Since g is symmetric,
multiply
                                             #by 2 to attain an
estimate for
                                             #both tails.
    }
}
```