## Image Analysis

Identifying trash from recycling material



#### Outline

- Problem definition
- Data
- Method
- Results
- Further considerations



## Problem definition

- Major part of sorting is being made by hands
- Multiple workers needed to do the job
- The full process of recycling is expensive



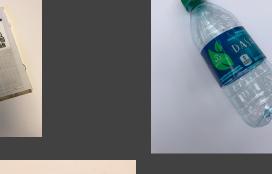


## Data

- 2527 images in 6 categories
- 501 images of glass, 594 paper, 403 cardboard, 482 plastic, 410 metal, 137 trash
- Divided 80/20 for every categories















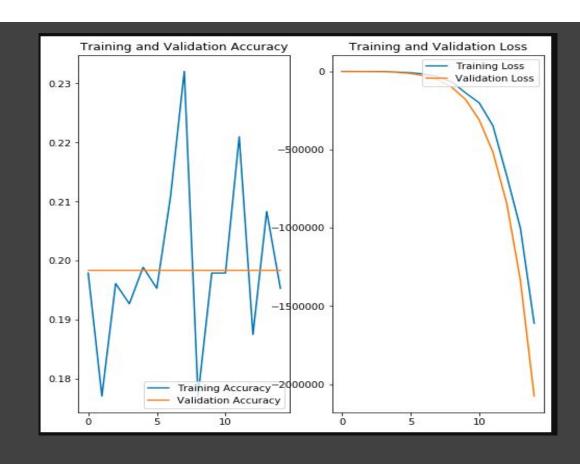
#### Method

- Building a basic CNN --> poor result (~20% accuracy)
- Using data augmentation --> poor result (~20% accuracy)
- Adding dropout layers --> poor result (~20% accuracy)
- Using support vector machines -->



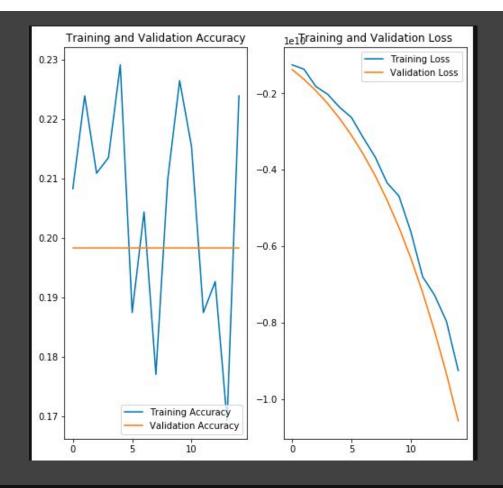
## Model - CNN

| Layer (type)  | Output | Shape         | Param # |
|---|--------|---------------|---------|
| conv2d_6 (Conv2D)   | (None, | 300, 300, 32) | 896     |
| max_pooling2d_6 (MaxPooling2  | (None, | 150, 150, 32) | 0       |
| conv2d_7 (Conv2D)   | (None, | 150, 150, 64) | 18496   |
| max_pooling2d_7 (MaxPooling2  | (None, | 75, 75, 64)   | 0       |
| conv2d_8 (Conv2D)   | (None, | 75, 75, 32)   | 18464   |
| max_pooling2d_8 (MaxPooling2  | (None, | 37, 37, 32)   | 0       |
| flatten_2 (Flatten)   | (None, | 43808)        | 0       |
| dense_4 (Dense)   | (None, | 64)           | 2803776 |
| dropout (Dropout)   | (None, | 64)           | 0       |
| dense_5 (Dense)   | (None, | 32)           | 2080    |
| dropout_1 (Dropout)   | (None, | 32)           | 0       |
| dense_6 (Dense)   | (None, | 6)            | 198     |
| Total params: 2,843,910<br>Trainable params: 2,843,910<br>Non-trainable params: 0 |        |               |         |





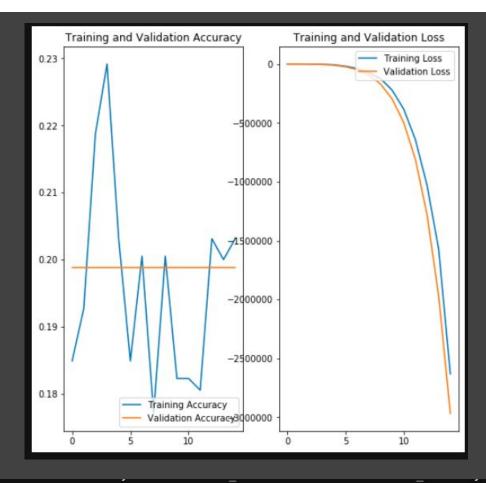
# Model - CNN + Data Augmentation





# Model - CNN + Dropout layers

| Layer (type)  | Output | Shape         | Param #  |
|---|--------|---------------|----------|
| conv2d_3 (Conv2D)   | (None, | 150, 150, 16) | 448      |
| max_pooling2d_3 (MaxPooling2  | (None, | 75, 75, 16)   | 0        |
| dropout (Dropout)   | (None, | 75, 75, 16)   | 0        |
| conv2d_4 (Conv2D)   | (None, | 75, 75, 32)   | 4640     |
| max_pooling2d_4 (MaxPooling2  | (None, | 37, 37, 32)   | 0        |
| conv2d_5 (Conv2D)   | (None, | 37, 37, 64)   | 18496    |
| max_pooling2d_5 (MaxPooling2  | (None, | 18, 18, 64)   | Θ        |
| dropout_1 (Dropout)   | (None, | 18, 18, 64)   | 0        |
| flatten_1 (Flatten)   | (None, | 20736)        | 0        |
| dense_2 (Dense)   | (None, | 512)          | 10617344 |
| dense_3 (Dense)   | (None, | 1)            | 513      |
| Total params: 10,641,441<br>Trainable params: 10,641,441<br>Non-trainable params: 0 |        |               |          |





## Further considerations

- Data augmentation did not improve -> need more different images, use colors
- CNN model did not have good accuracy -> try another architecture, use another method (i.e.: support vector machines), change hyperparameters
- Experiments took time and crashed often -> use GPU,
  more hardware resources, a different optimizer



## Conclusion

- Detecting trash from recycling material is an environmentally good problem that needs further analysis
- It is a project that need further ressources
- Images gathering is important and CNN might not always be the best choice for computer vision





# EnhanceIT

