

Interests

Brain-Computer Interfaces, NeuroAI, Embodied AI, AR/VR, Machine Perception

Education

Carnegie Mellon University

PhD Program in Neural Computation | GPA: 4.0 / 4.0

2021-

Advisors: Robert Gaunt, Leila Wehbe. Expected graduation: 2026

Georgia Institute Of Technology

M.S. Computer Science | Machine Learning Specialization | GPA: 4.0 / 4.0

2021

B.S. Computer Science | Minor in Mathematics | GPA: 4.0 / 4.0

2017-2020

Publications and Presentations

Neural Latents Benchmark '21: Evaluating latent variable models of neural population activity. *Neural Information Processing Systems (NeurIPS) Benchmarks and Datasets*, 2021.

F. Pei*, J. Ye*, D. Zoltowski, A. Wu, R. Chowdhury, H. Sohn, J. O'Doherty, K. Shenoy, M. Kaufman, M. Churchland, M. Jazayeri, L. Miller, J. Pillow, M. Park, E. Dyer, C. Pandarinath.

Auxiliary Tasks and Exploration Enable ObjectNav. *International Conference on Computer Vision (ICCV)* 2021.

J. Ye, D. Batra, A. Das, and E. Wijmans.

Auxiliary Tasks Speed Up Learning PointGoal Navigation. *Conference on Robot Learning (CoRL)*, 2020.

J. Ye, D. Batra, E. Wijmans, and A. Das.

Representation learning for neural population activity with Neural Data Transformers. *Neurons, Behavior, Data analysis, and Theory (NBDT)*, 2021. Poster at SfN 2021, Neuromatch 3.0, 2020.

J. Ye, C. Pandarinath.

Awards

Donald V. Jackson Fellowship. Award for academic excellence and leadership. 1 of 3 awards for 250 eligible MS students in the Georgia Tech College of Computing.

Experience

Amazon

Summer 2021

- Studied embodied agent navigation in dynamic settings

Microsoft, Visual Document Intelligence, Software Engineering Intern - Remote

Summer 2020

- Prototyped region annotation and data augmentation for doc. understanding frontend + C# backend

Ubiquity6, Software Engineering Intern - San Francisco, CA

Summer 2019

- Prototyped wayfinding experience for navigating AR scenes, using a custom navigation mesh
- Analyzed ARKit (Obj-C) and ARCore (Java) anchor drift, assessing viability for better pose priors

Projects

A Saccading Model for Temporal Illusions | Report: github.com/joel99/illusions

2021

- We apply a self-supervised recurrent vision model to reproduce the uniformity illusion.

Learning from Different Expert Agents | Report: joel99.github.io/lfd_7648_final.pdf

2021

- How can one robot learn from demonstrations given by another robot?
- We propose Seq2Seq domain translation to overcome the action space mismatch between robots.

Perturbome of Graphs of RNNs | Report: github.com/joel99/noised-rnn-networks

2020

- How do deep neural networks compute in the presence of internal noise, or targeted perturbation?
- Evaluated this dynamical robustness by noising recurrent networks built with pytorch-geometric

- Interfaced with style-transfer server to collect styled photos, built masking app with HTML canvas
- Set up server polling endpoint to interface with DSLR camera trigger, provide fallback laptop camera