

# A generalist model for intracortical motor brain-computer interfaces

Preprint



## The Team

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Nicholas Hatsopoulos  
Andrew Schwartz  
Jennifer L. Collinger  
Leila Wehbe  
Robert A. Gaunt

DNNs excel at  
**single tasks.**

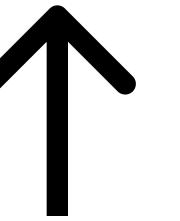


DNNs can be scaled  
to **use everywhere.**

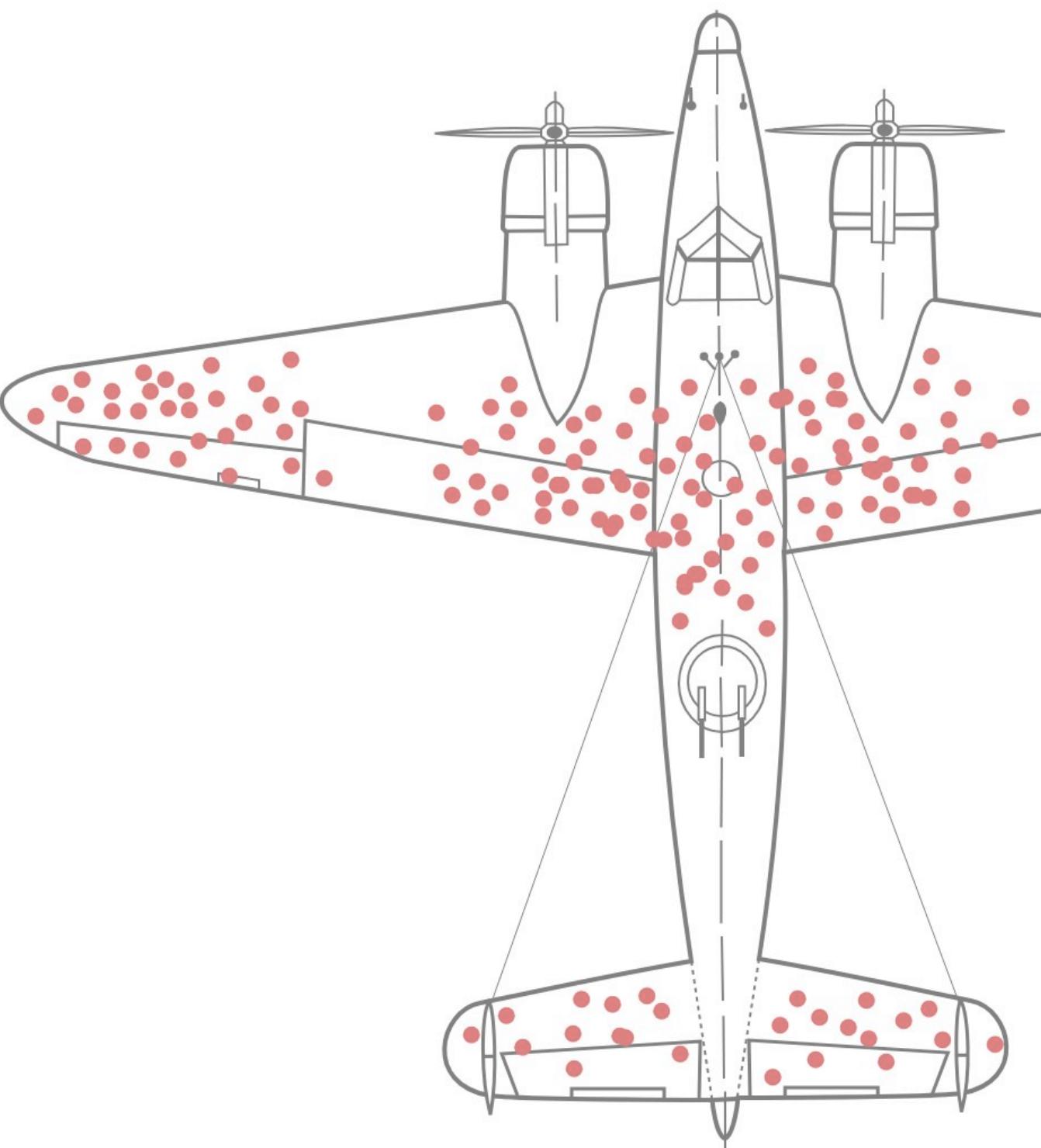
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**We're here (?) Now what?**



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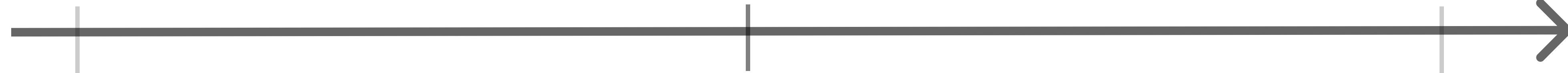


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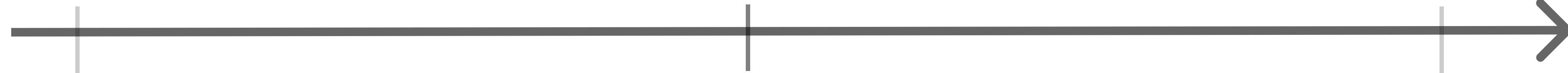
In machine learning,  
**evaluations** drive our understanding of progress.

(Guess and check will never end)

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We're here (?) Now what?

In machine learning,  
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**How should we prioritize evaluations?**

**1. Evaluating for pragmatics**

**2. Evaluating for generalization**

In machine learning,  
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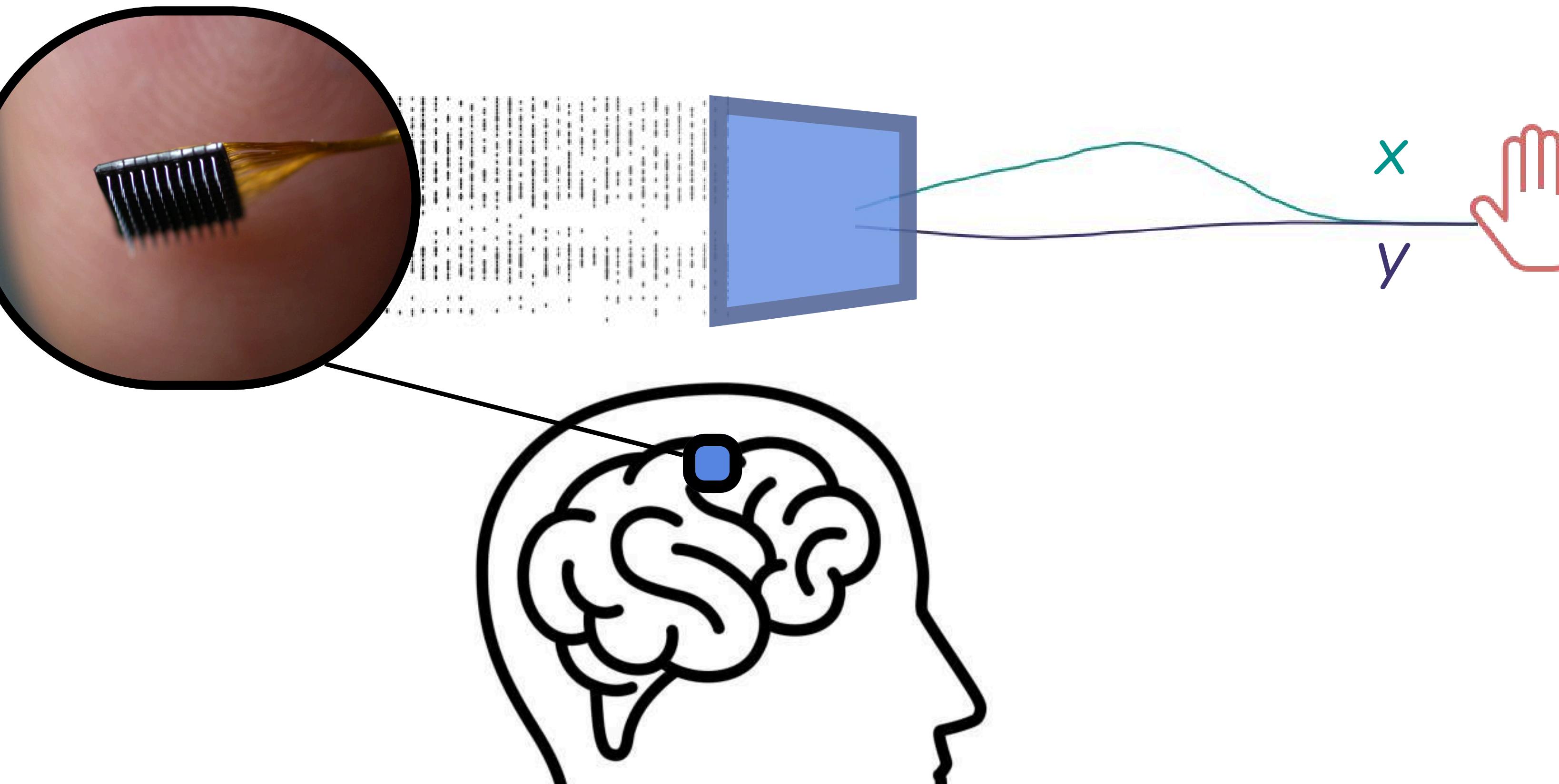
How should we prioritize evaluations?

What is the **practical** benefit of **unified** pretraining?

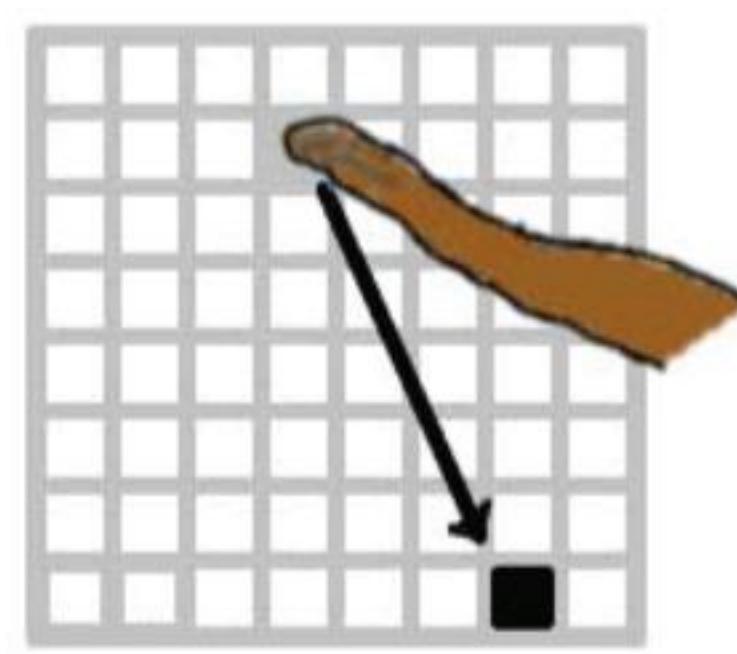
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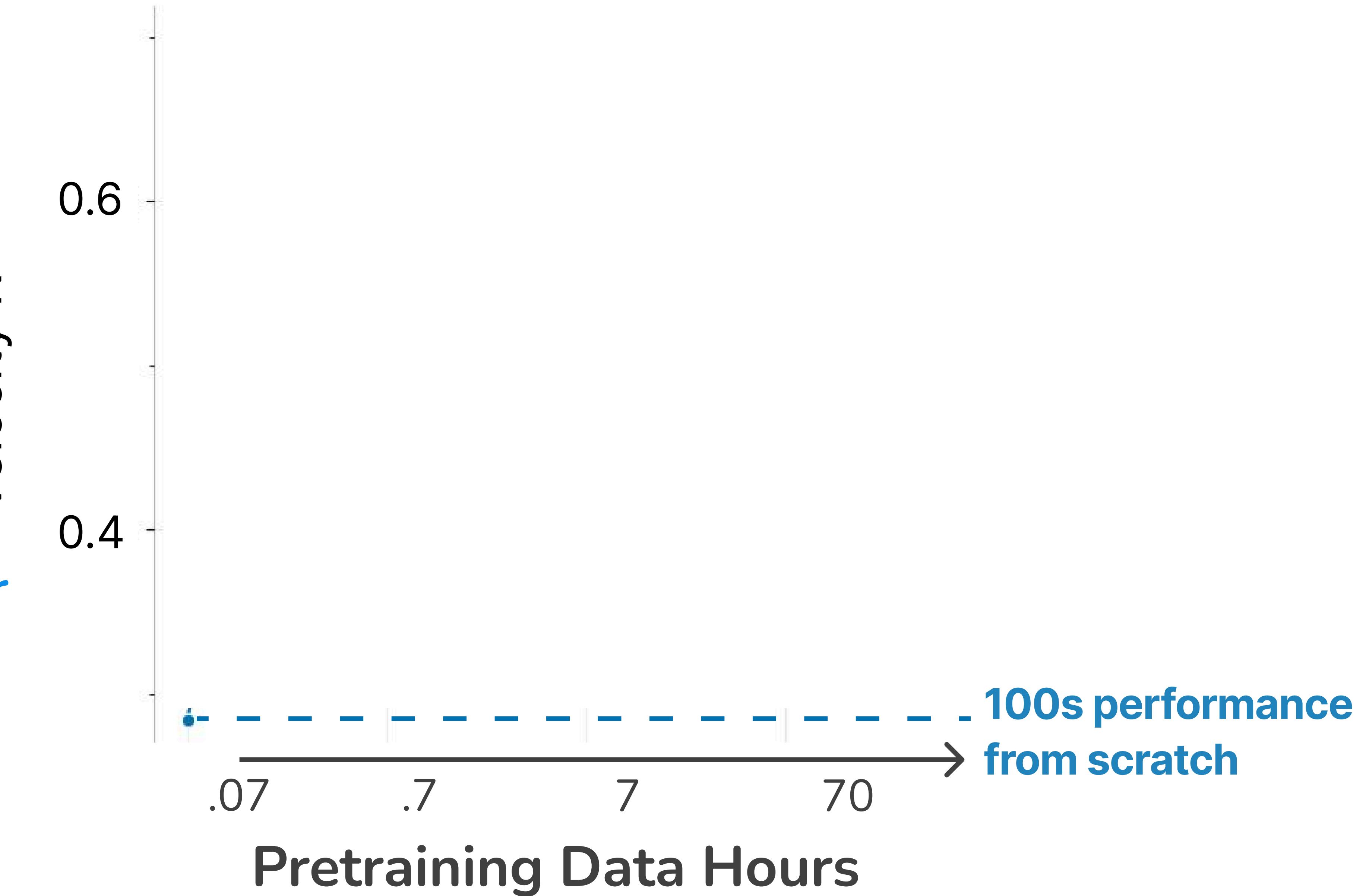
## 1. Evaluating for pragmatics



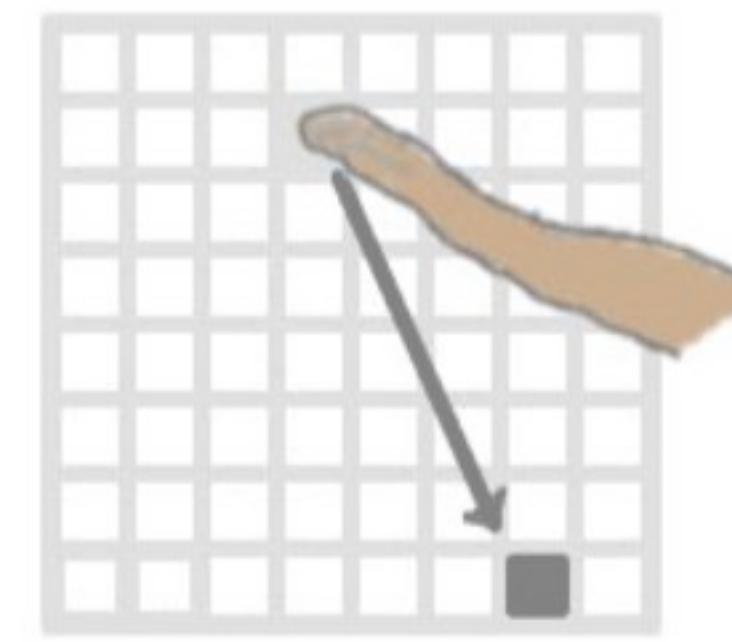
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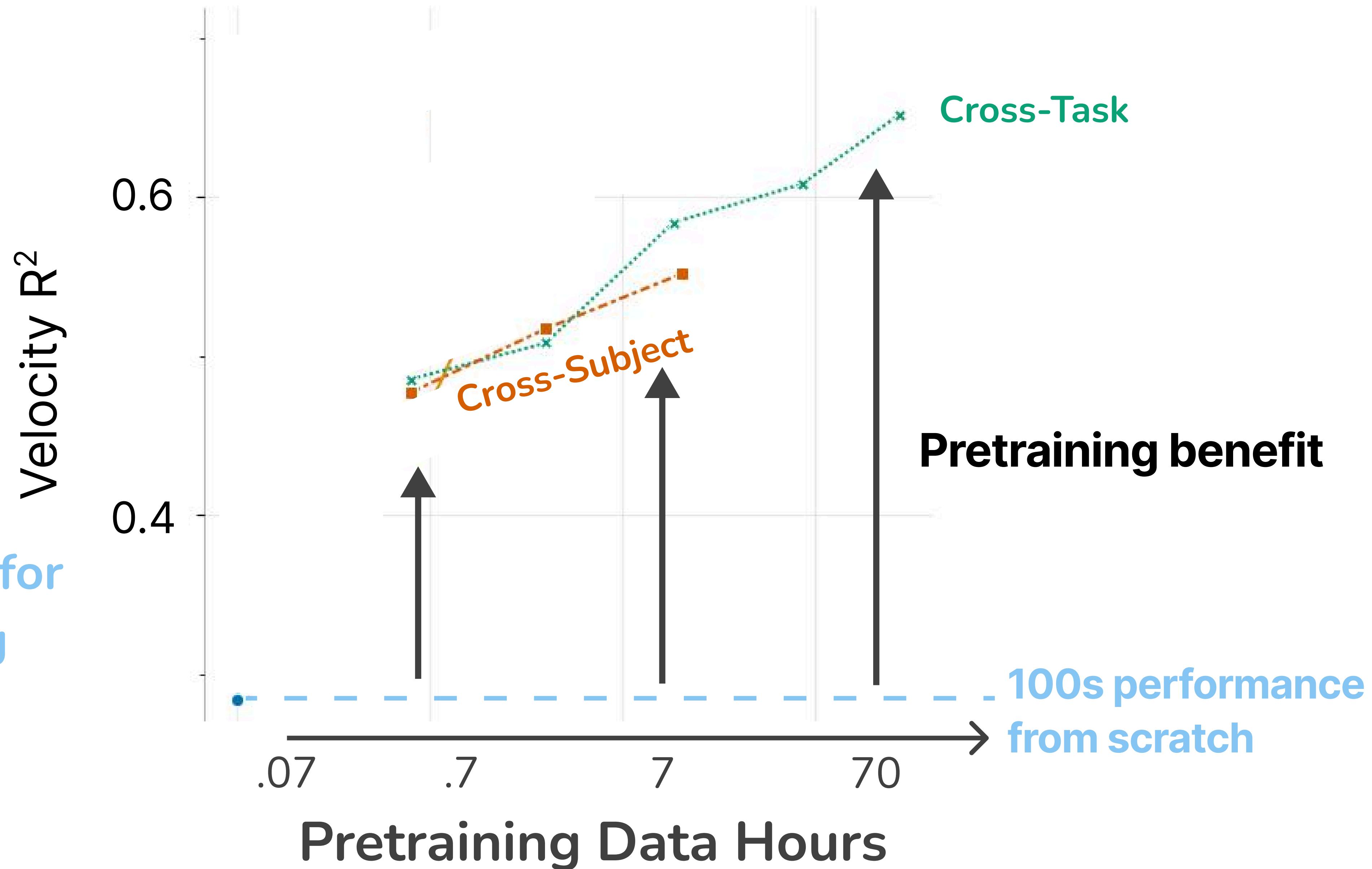
**100 seconds for  
fine-tuning**



What is the **practical** benefit of **unified** pretraining?

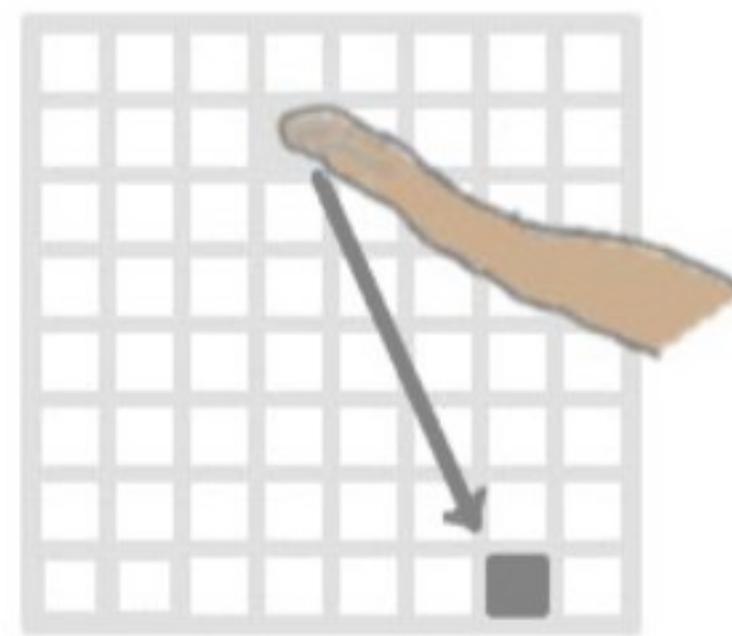


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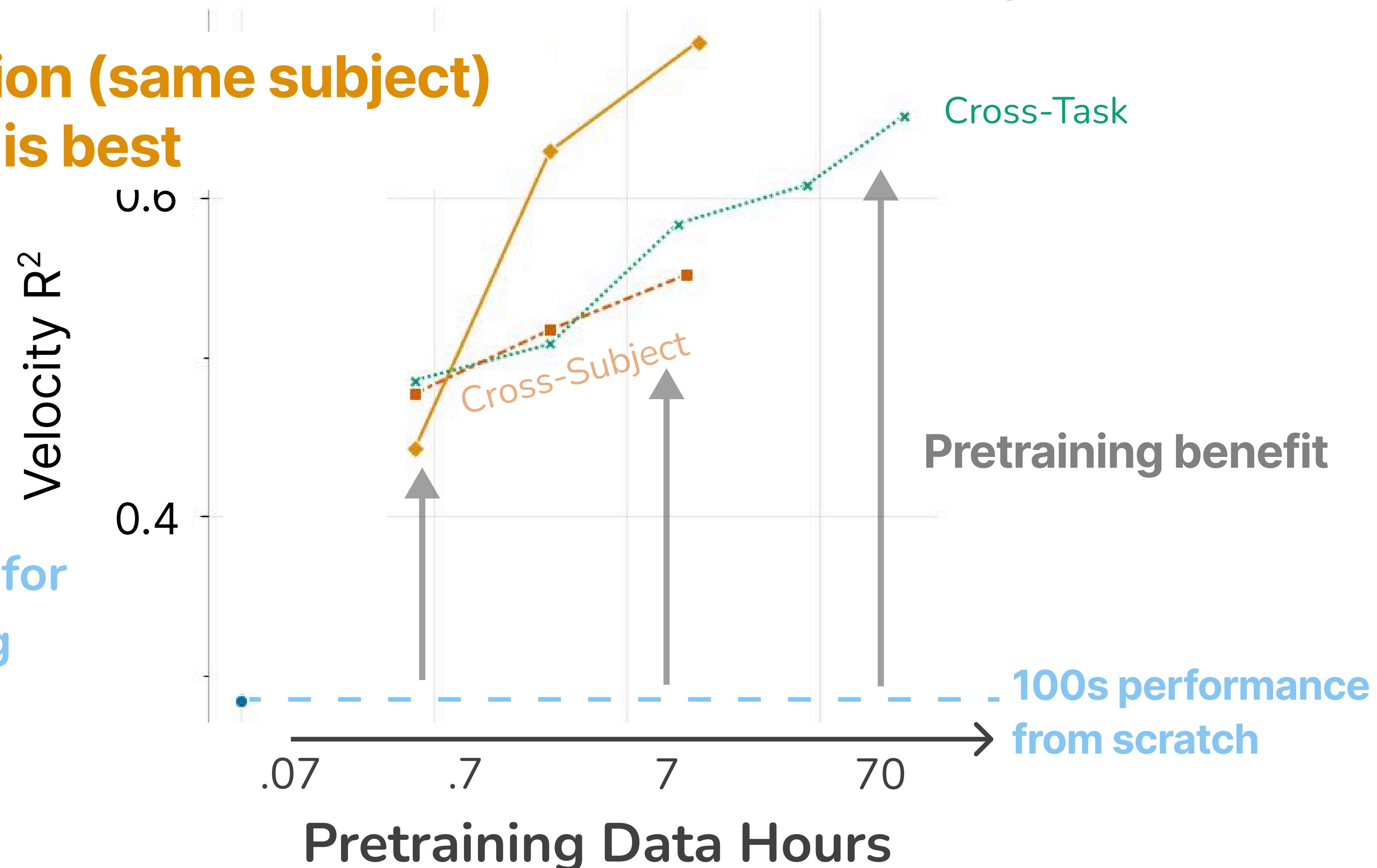


What is the **practical** benefit of **unified** pretraining?

**Cross session (same subject)  
is best**

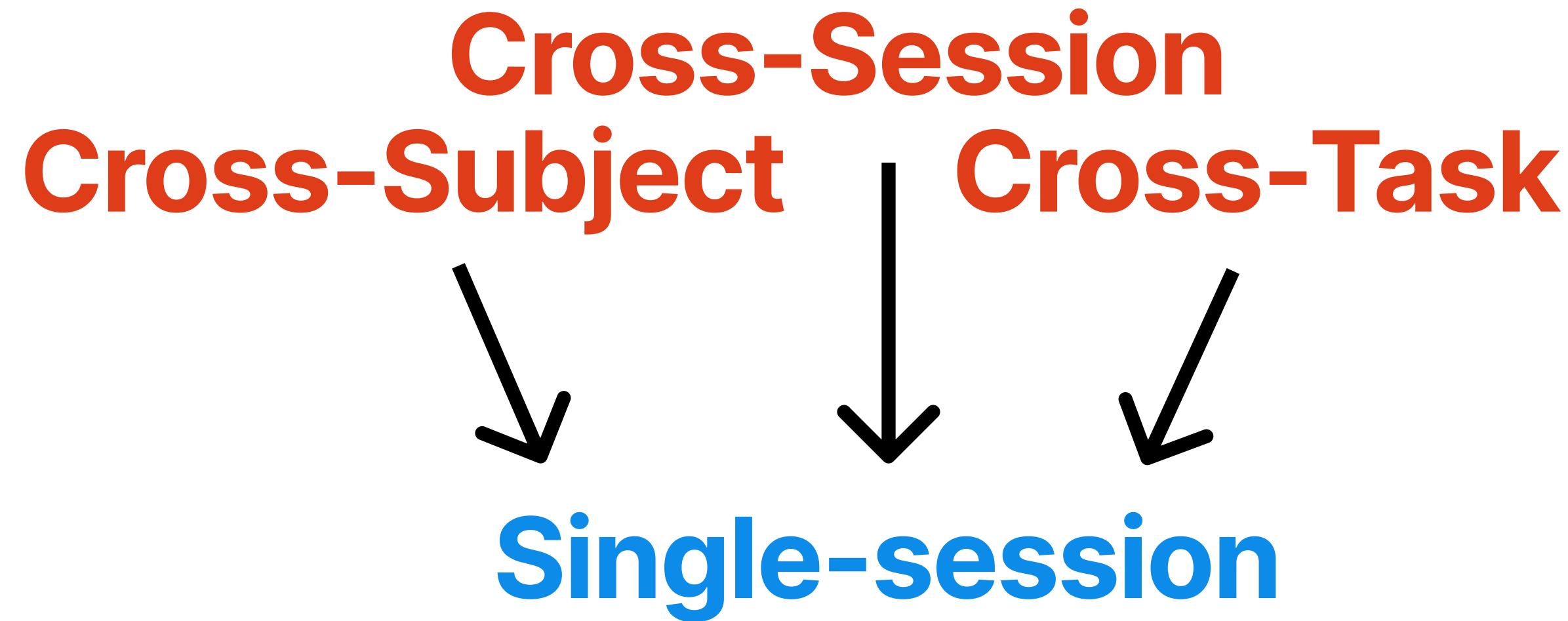


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What is the **practical** benefit of **unified** pretraining?

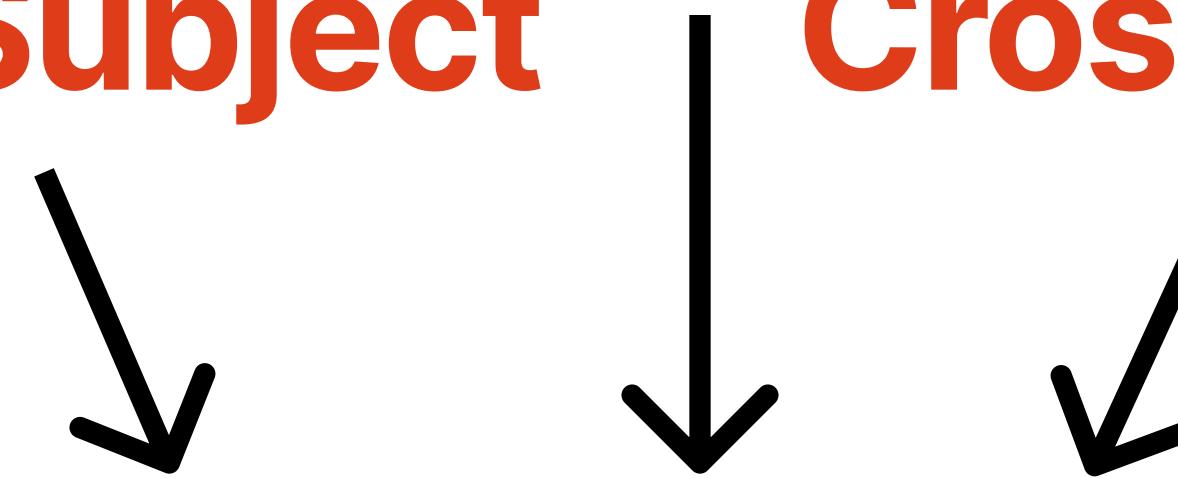
## THE NORM



What is the **practical** benefit of **unified** pretraining?

## THE NORM

**Cross-Session**  
**Cross-Subject**



**Single-session**

## PRAGMATIC EVAL

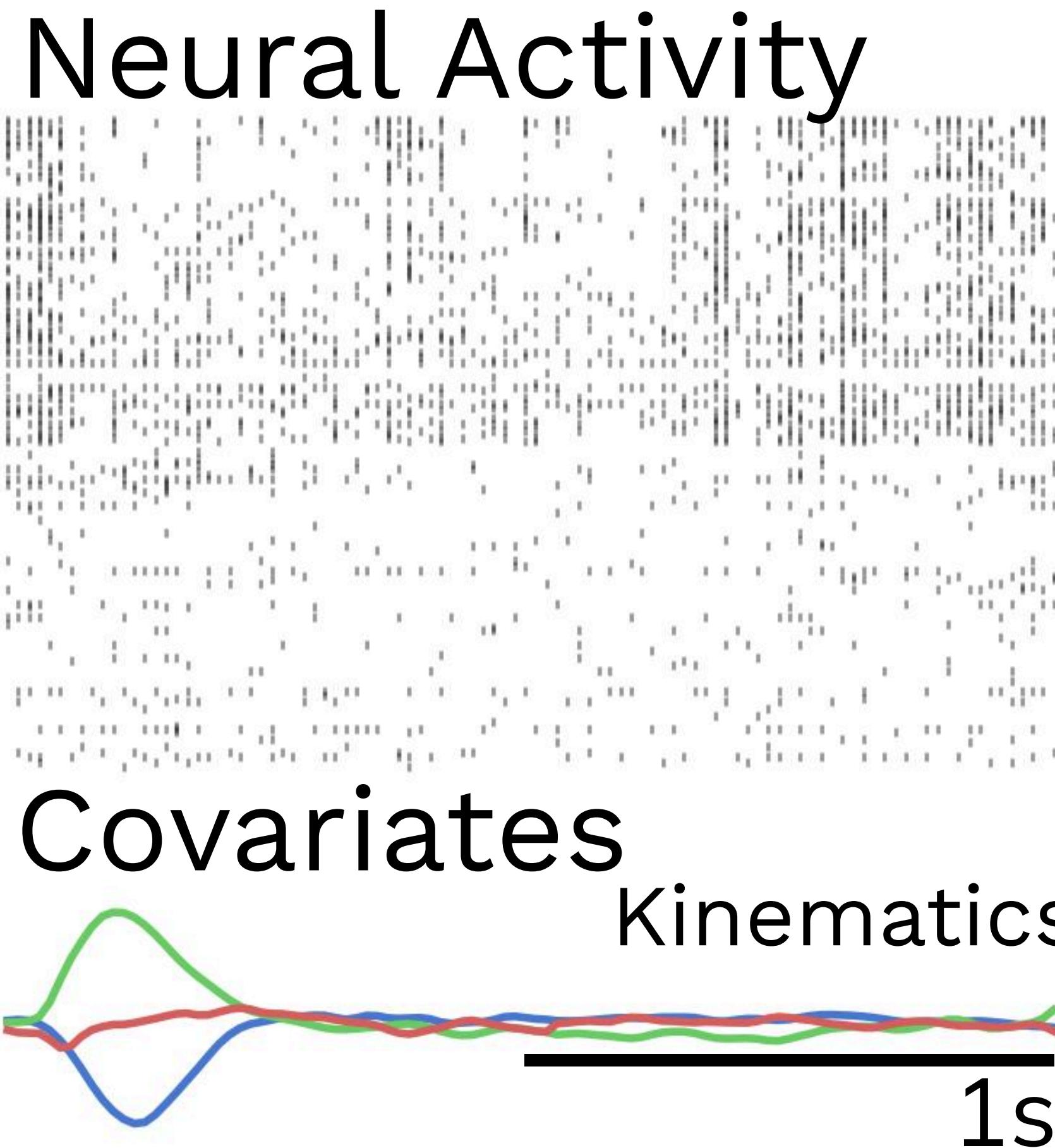
(For chronic BCI)

**Cross-Subject** **Cross-Task**

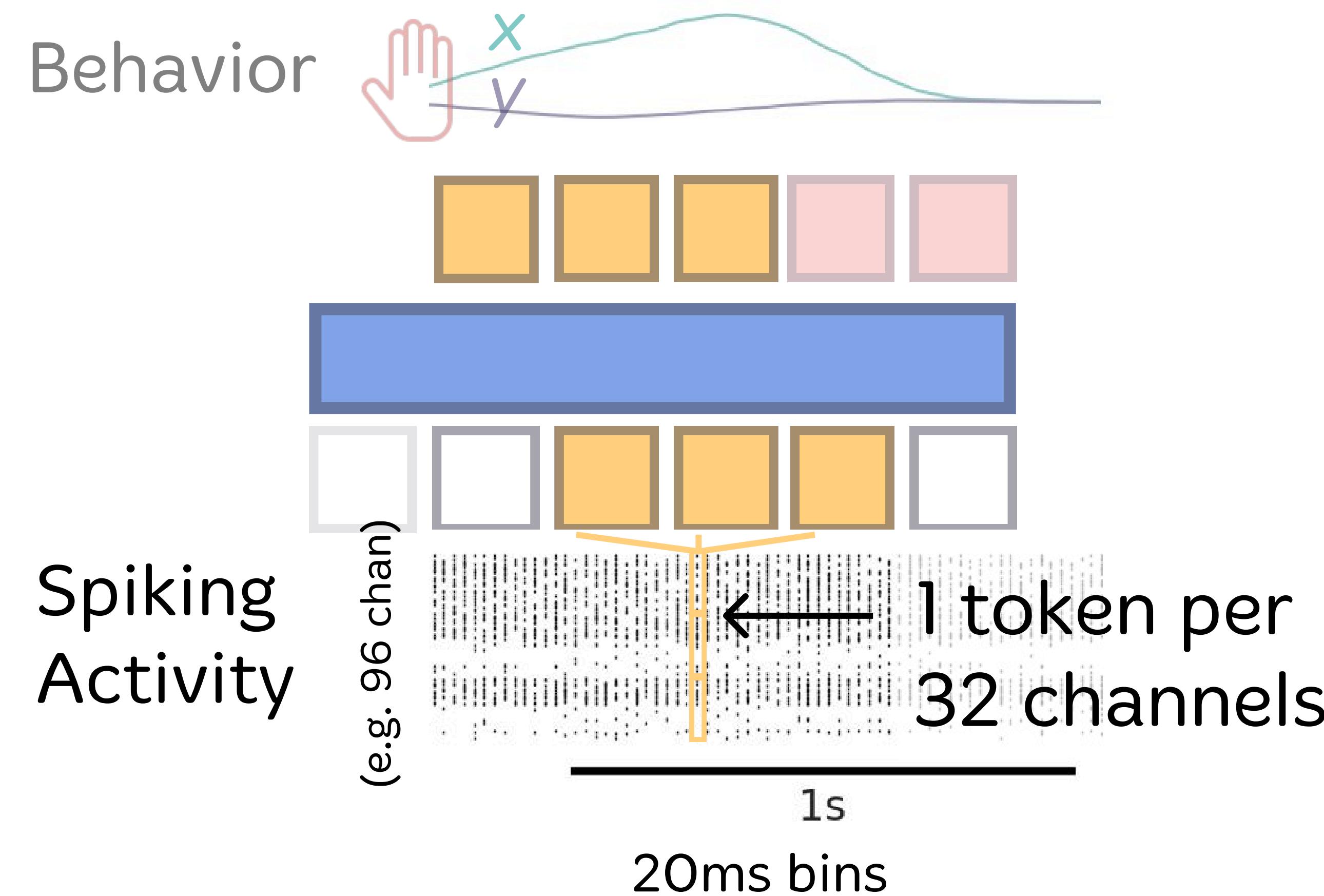


**Multi-session**

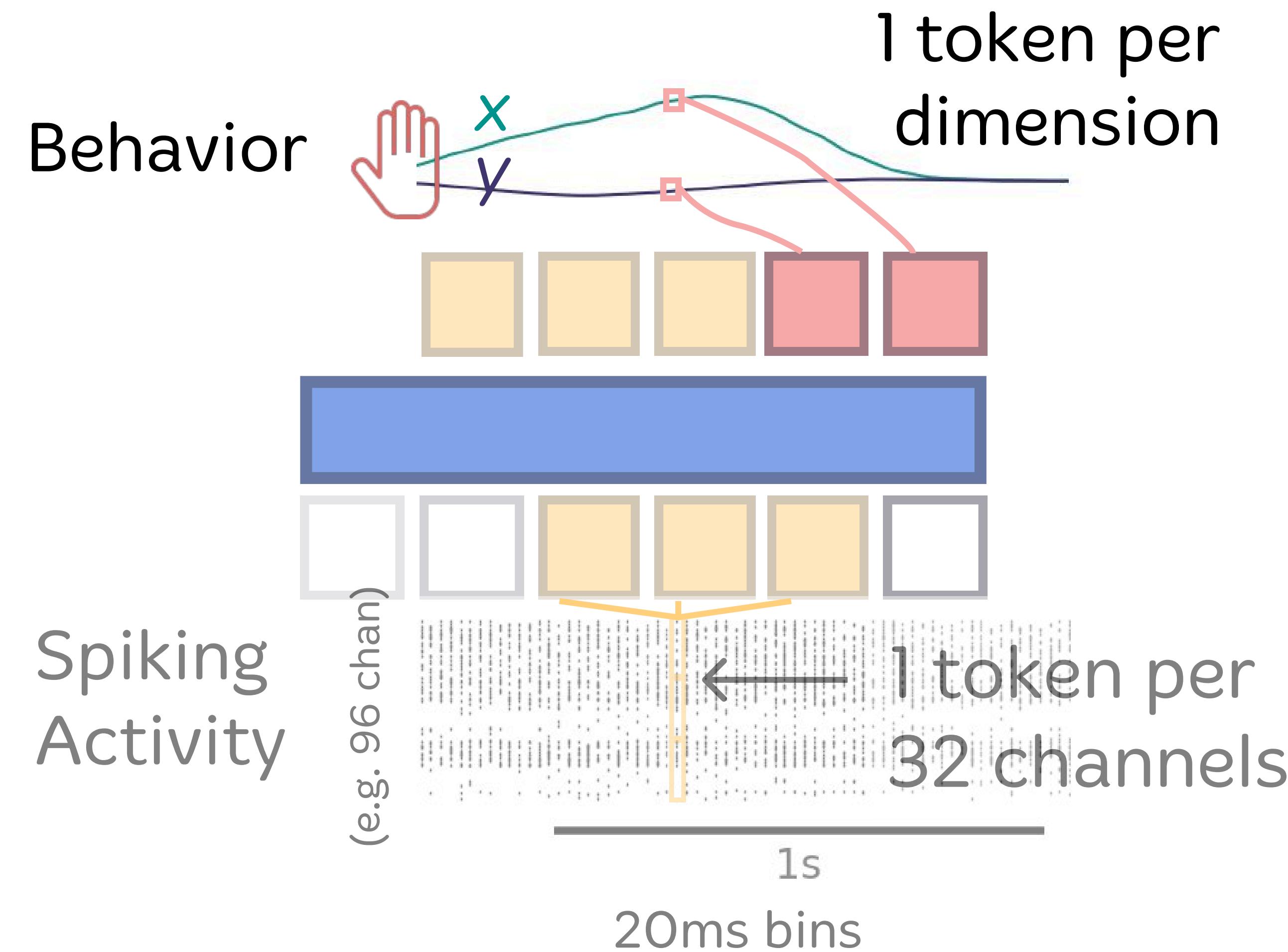
# Neural Data Transformer 3 (NDT3): Scaling motor BCI pretraining to 2000 hours



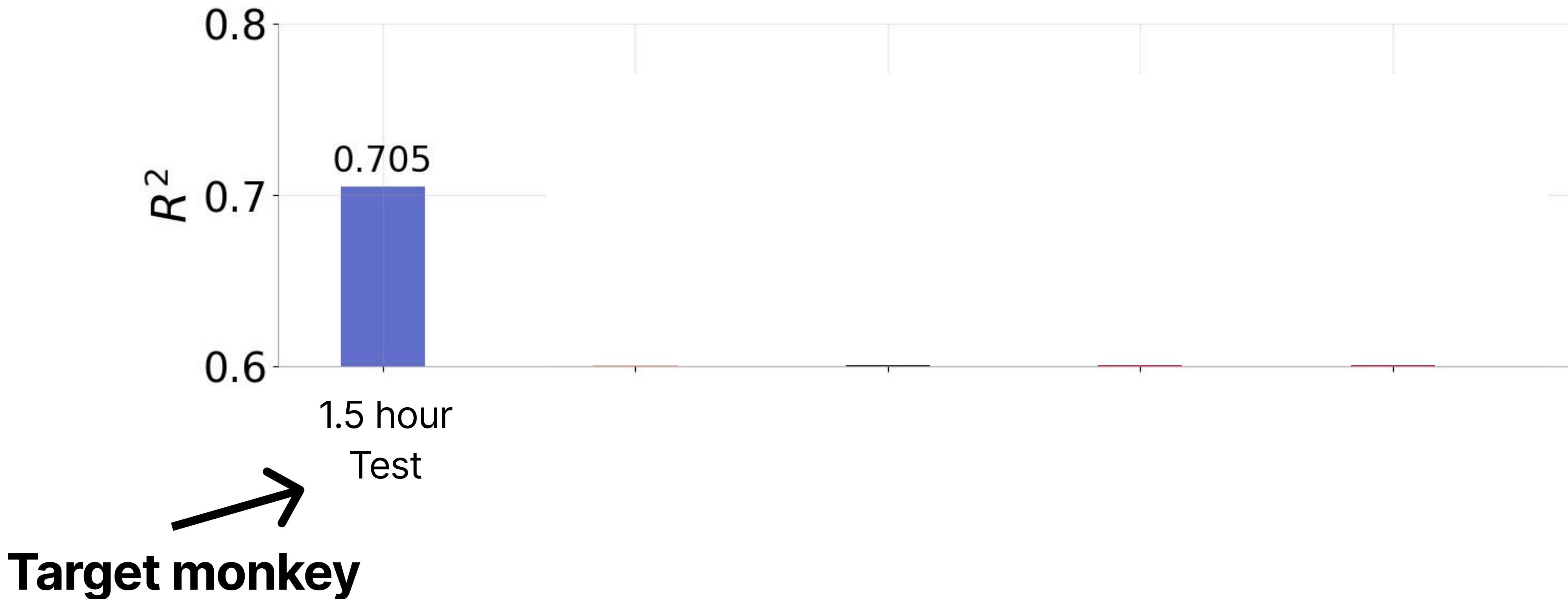
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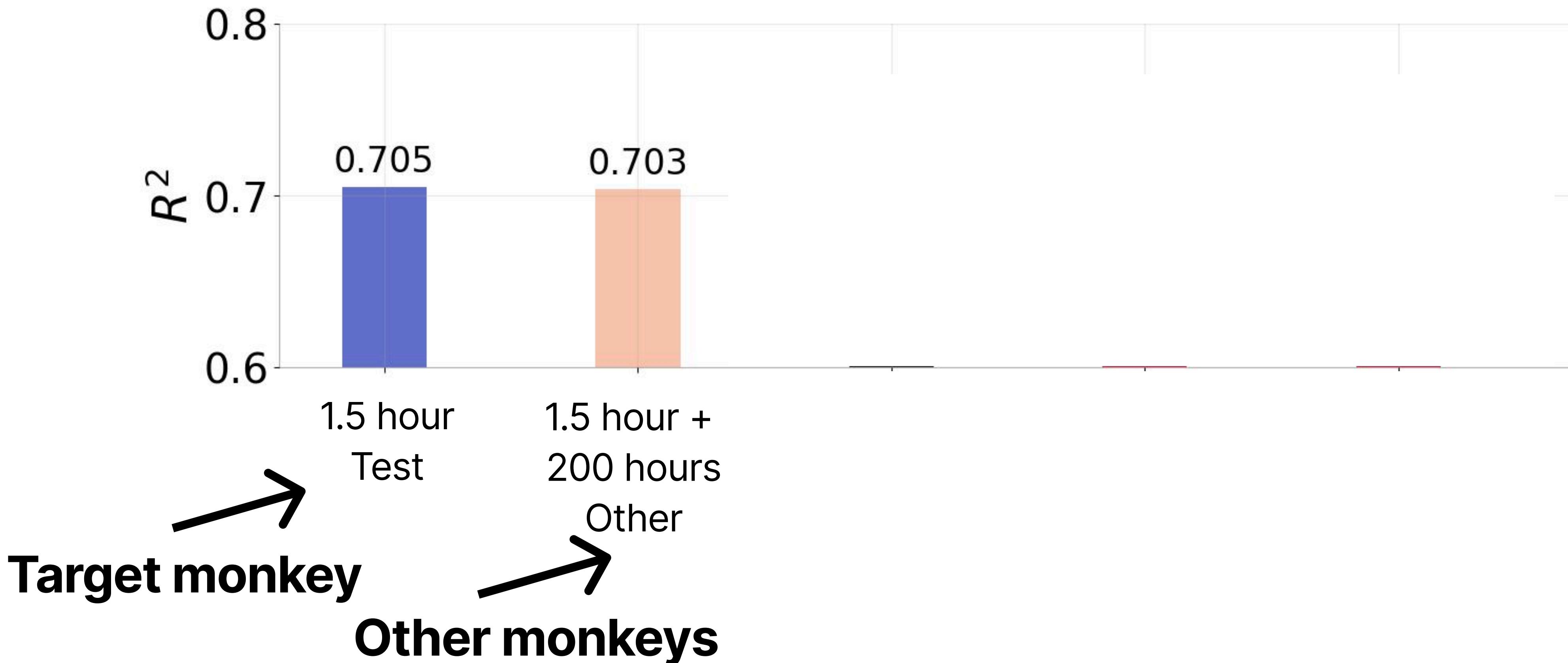
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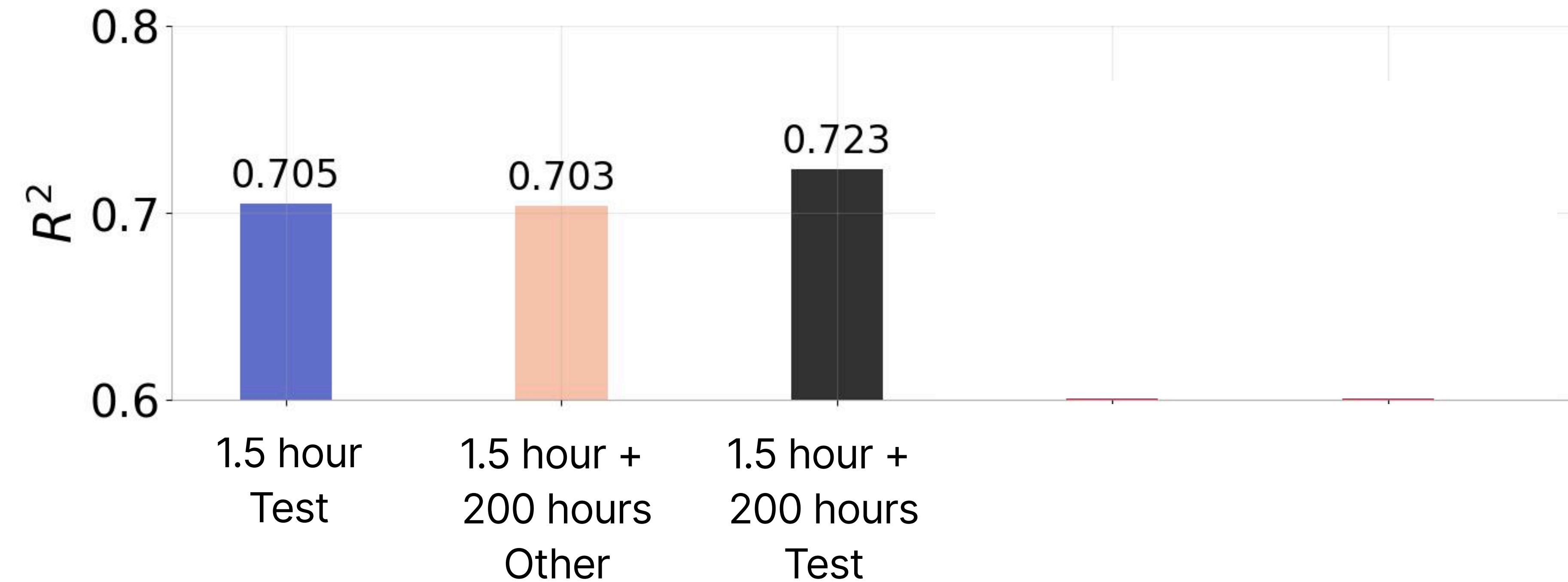
## Scaled pretraining shows weak pragmatic (cross-subject) transfer



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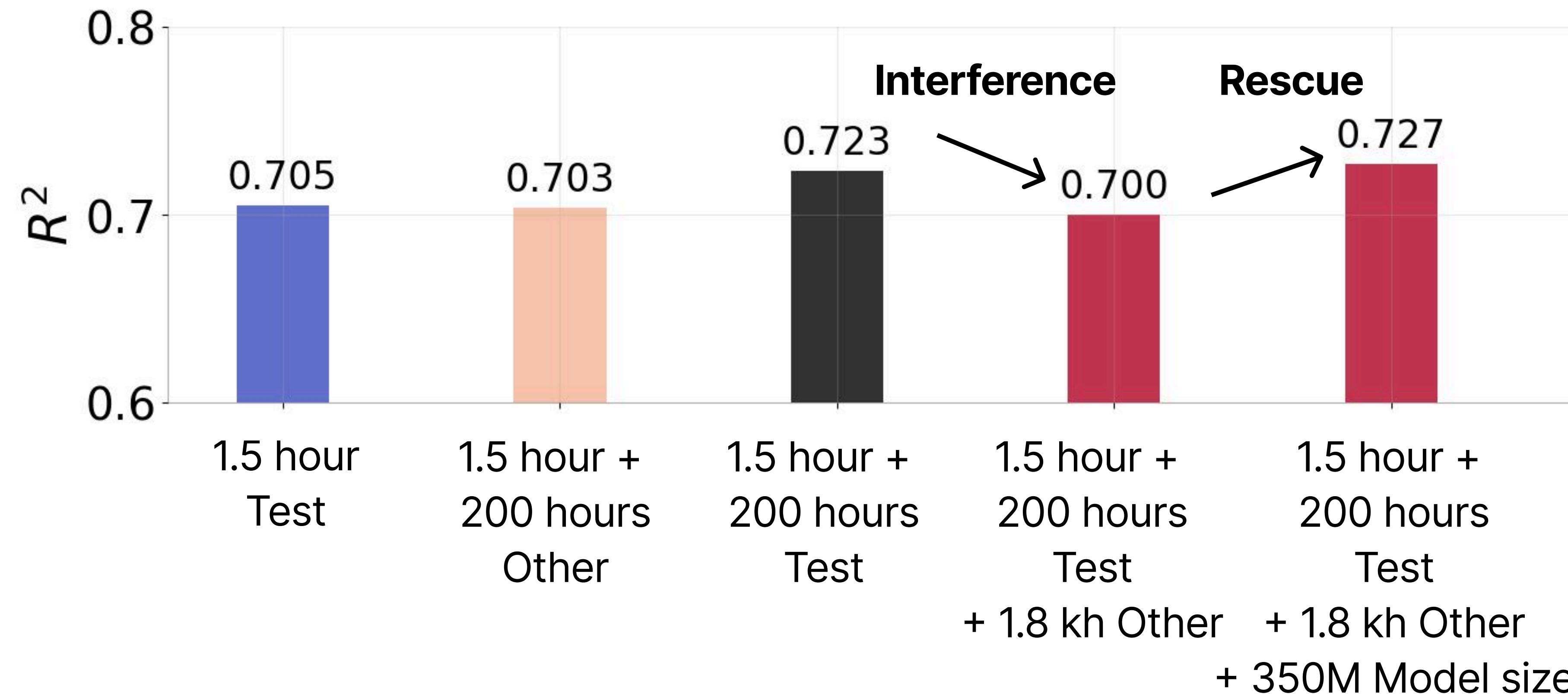


## Scaled pretraining shows weak pragmatic (cross-subject) transfer

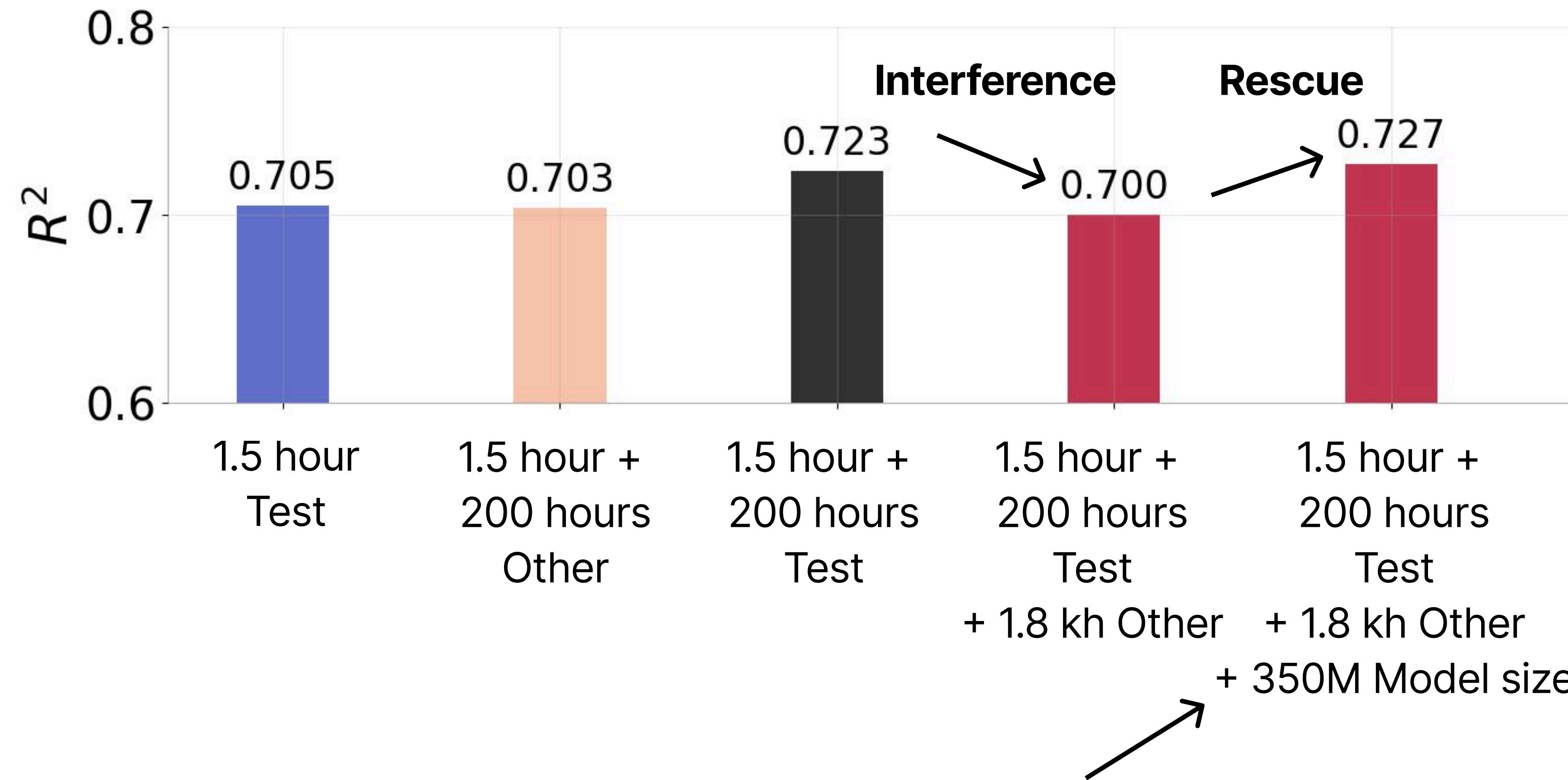


Cross-subject transfer fails for the long tail?

# Scaled pretraining shows weak pragmatic (cross-subject) transfer

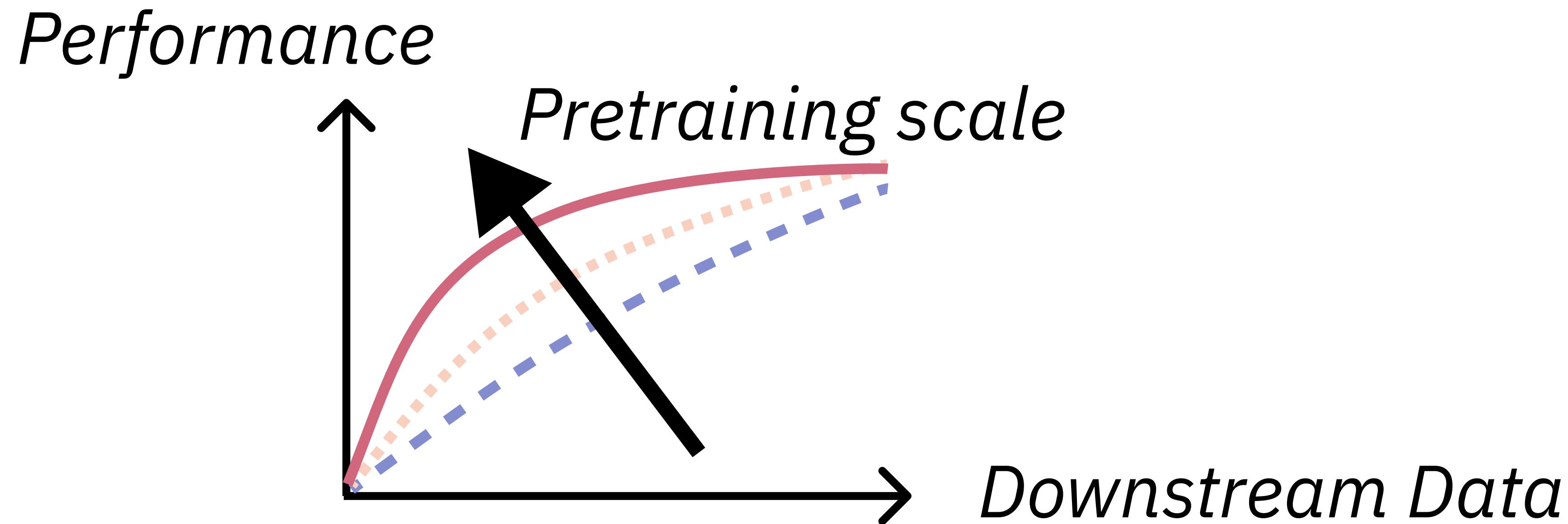


## Scaled pretraining shows weak pragmatic (cross-subject) transfer

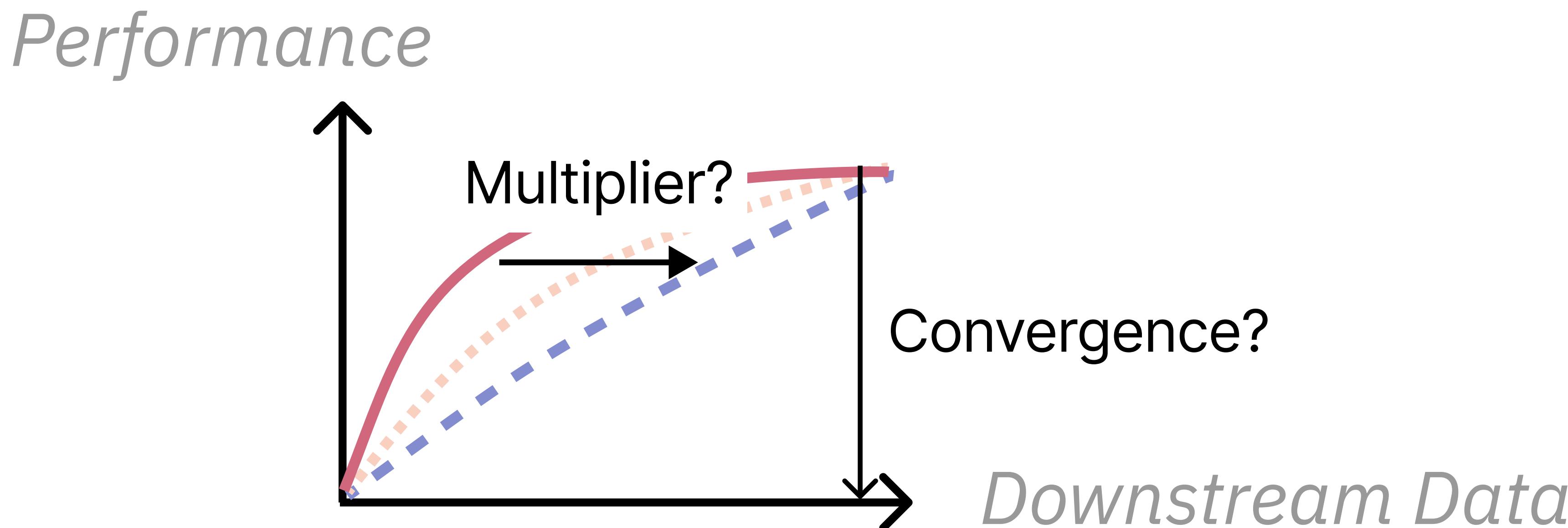


**A cost to our ambition, for no gain?**

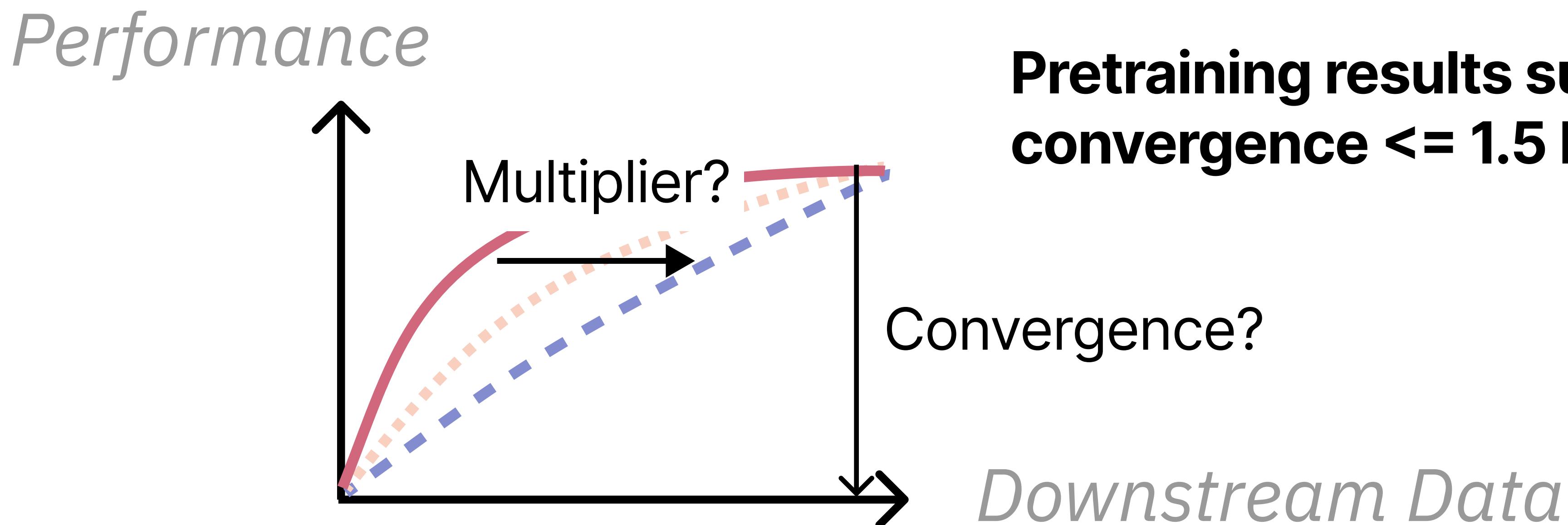
## Quantifying downstream scaling gains



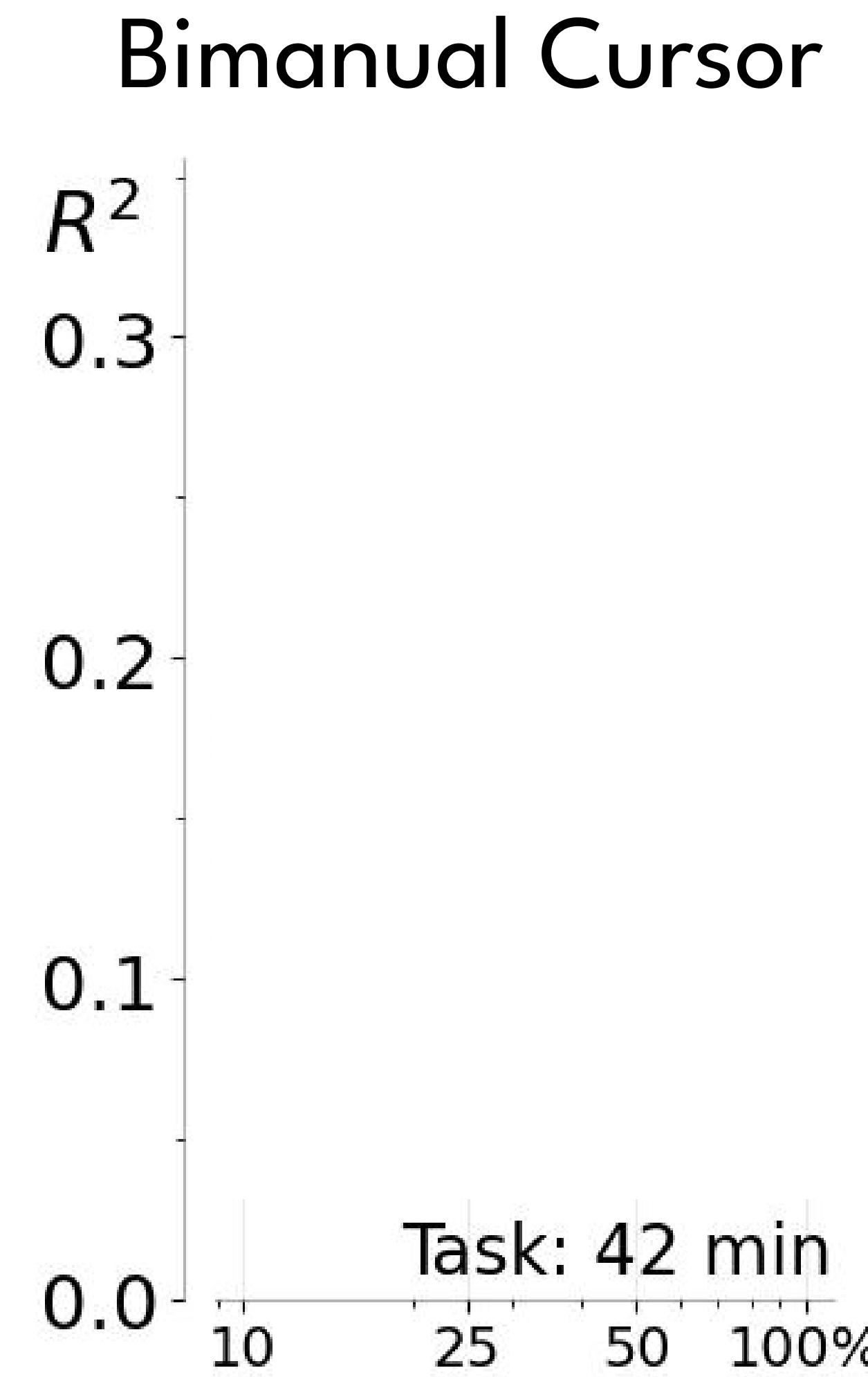
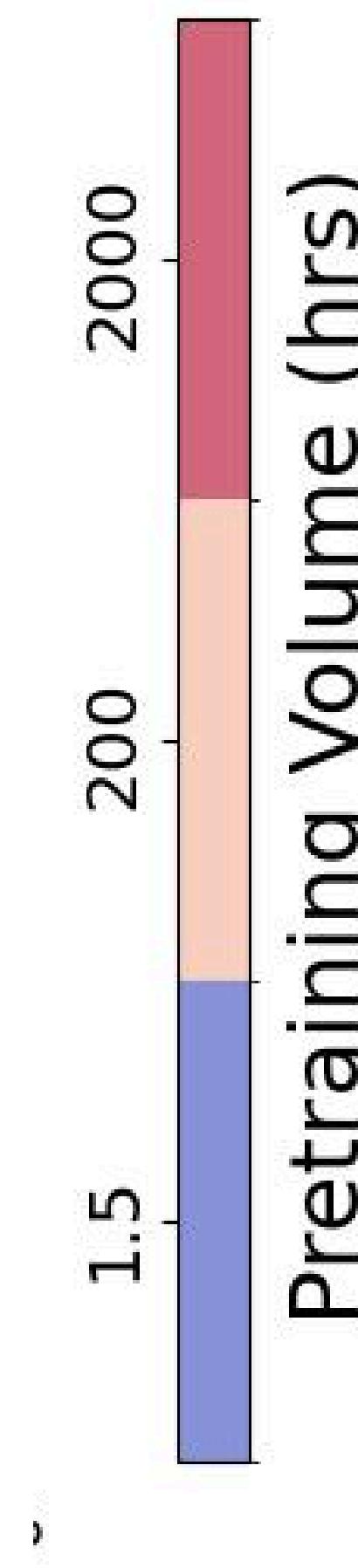
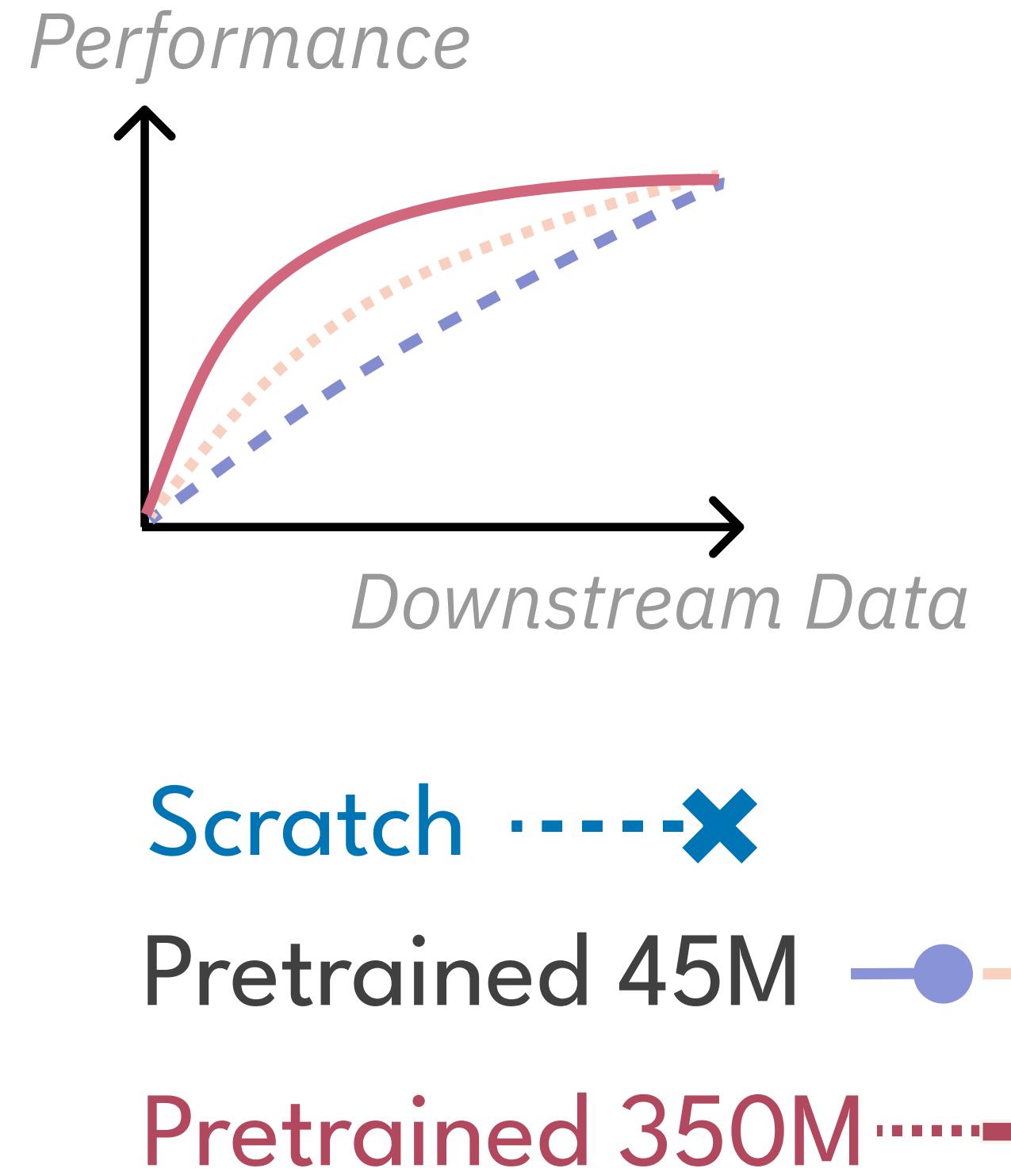
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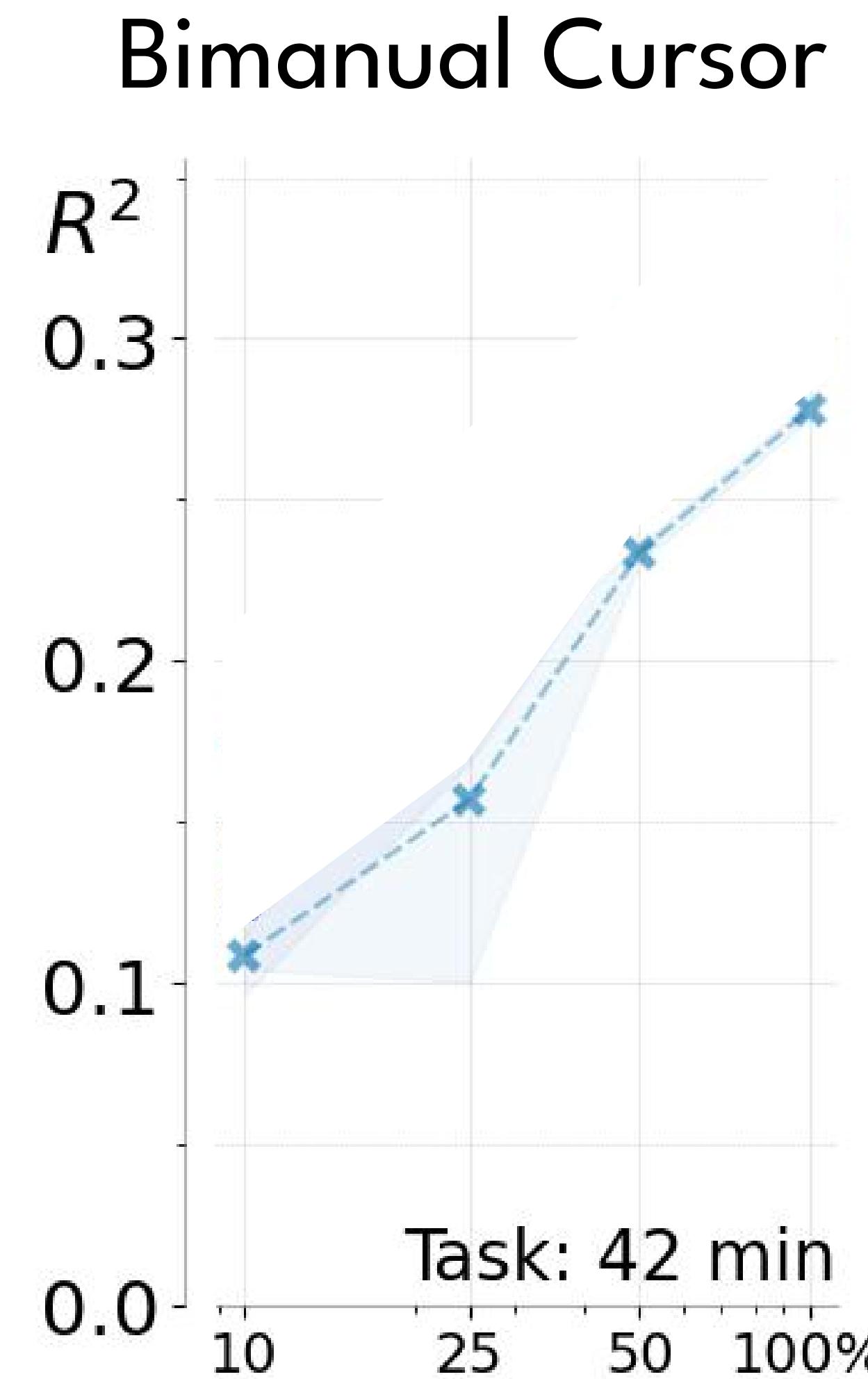
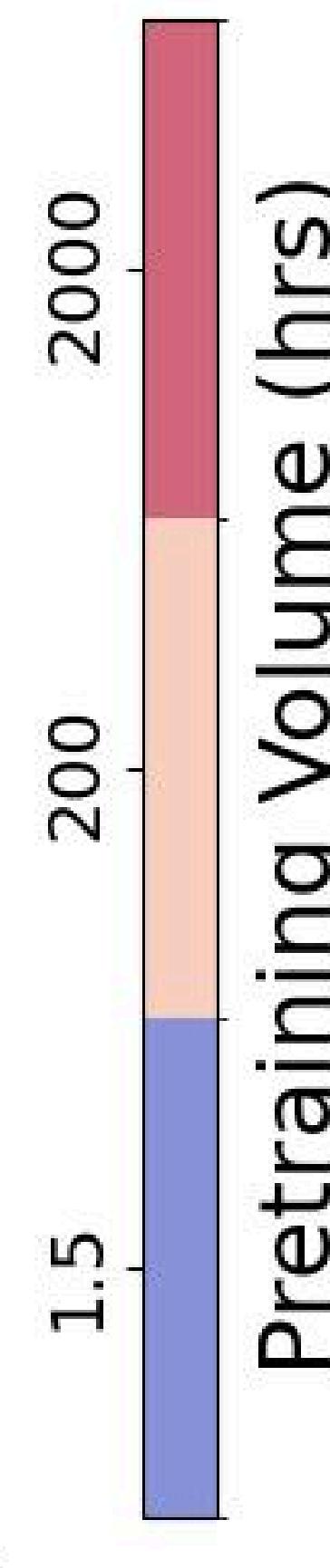
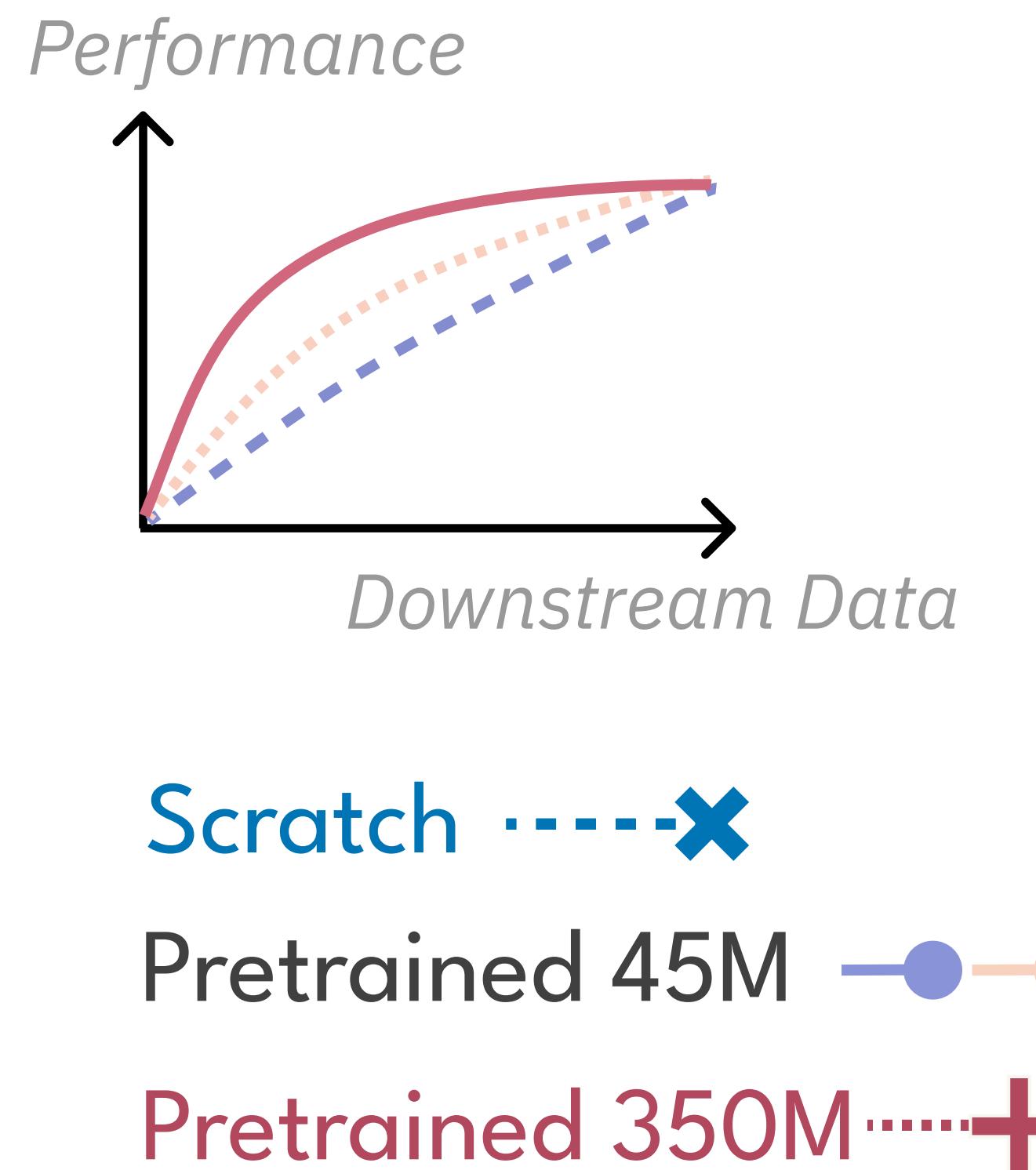
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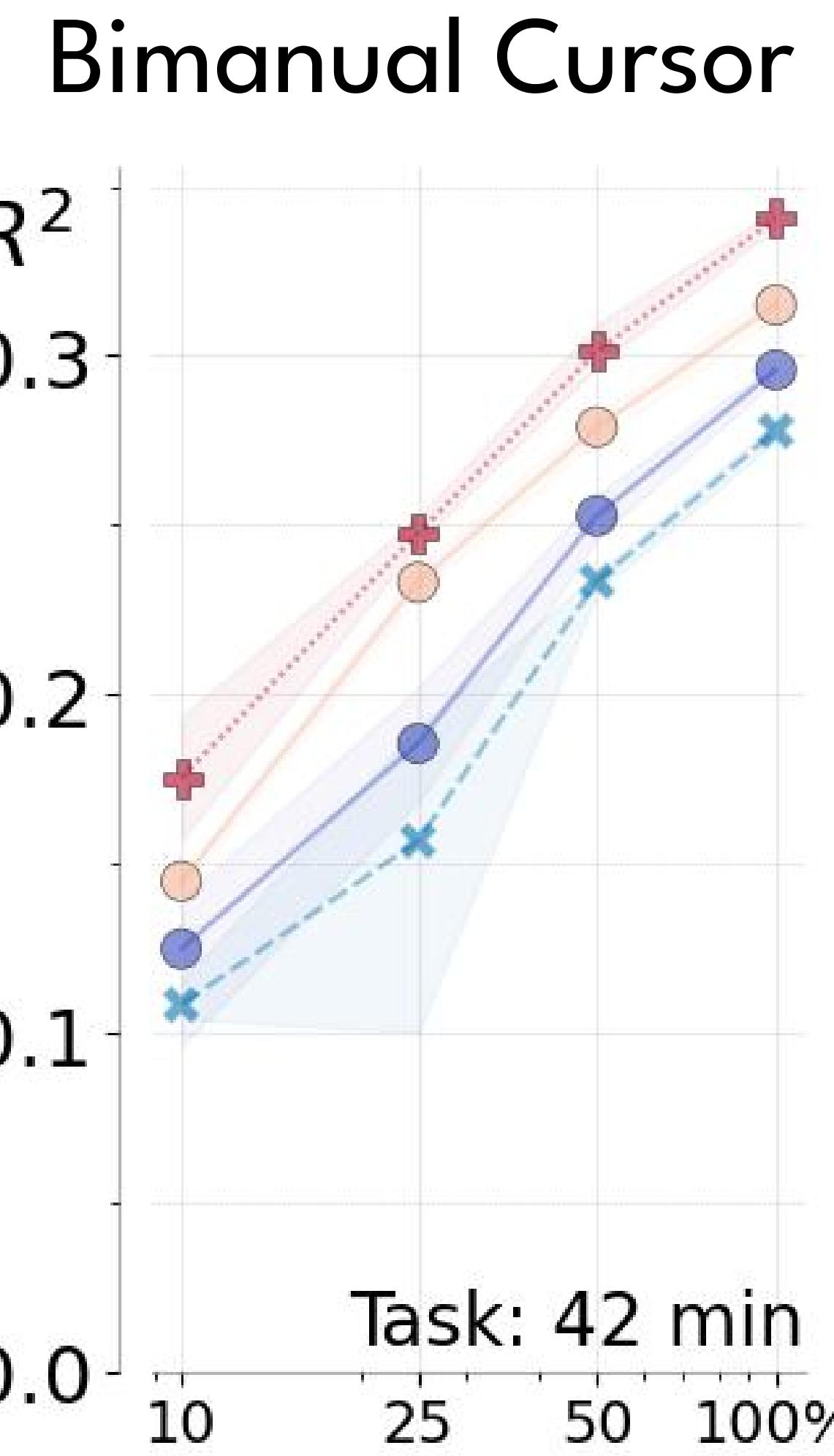
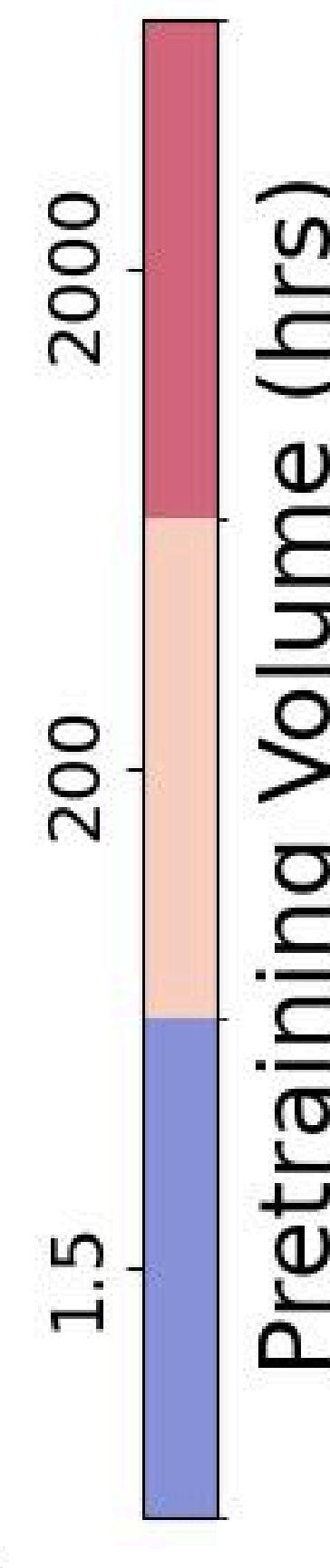
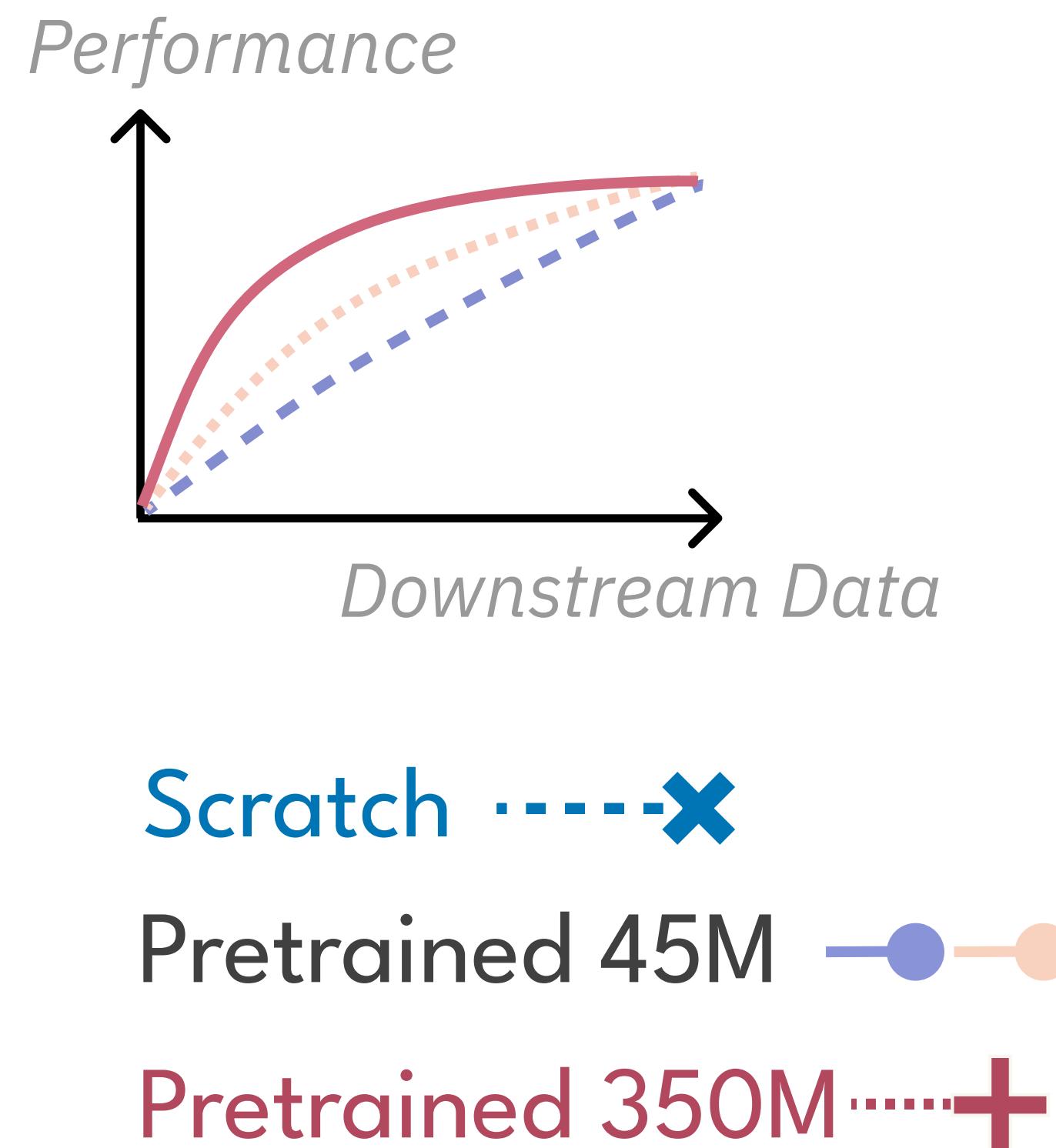
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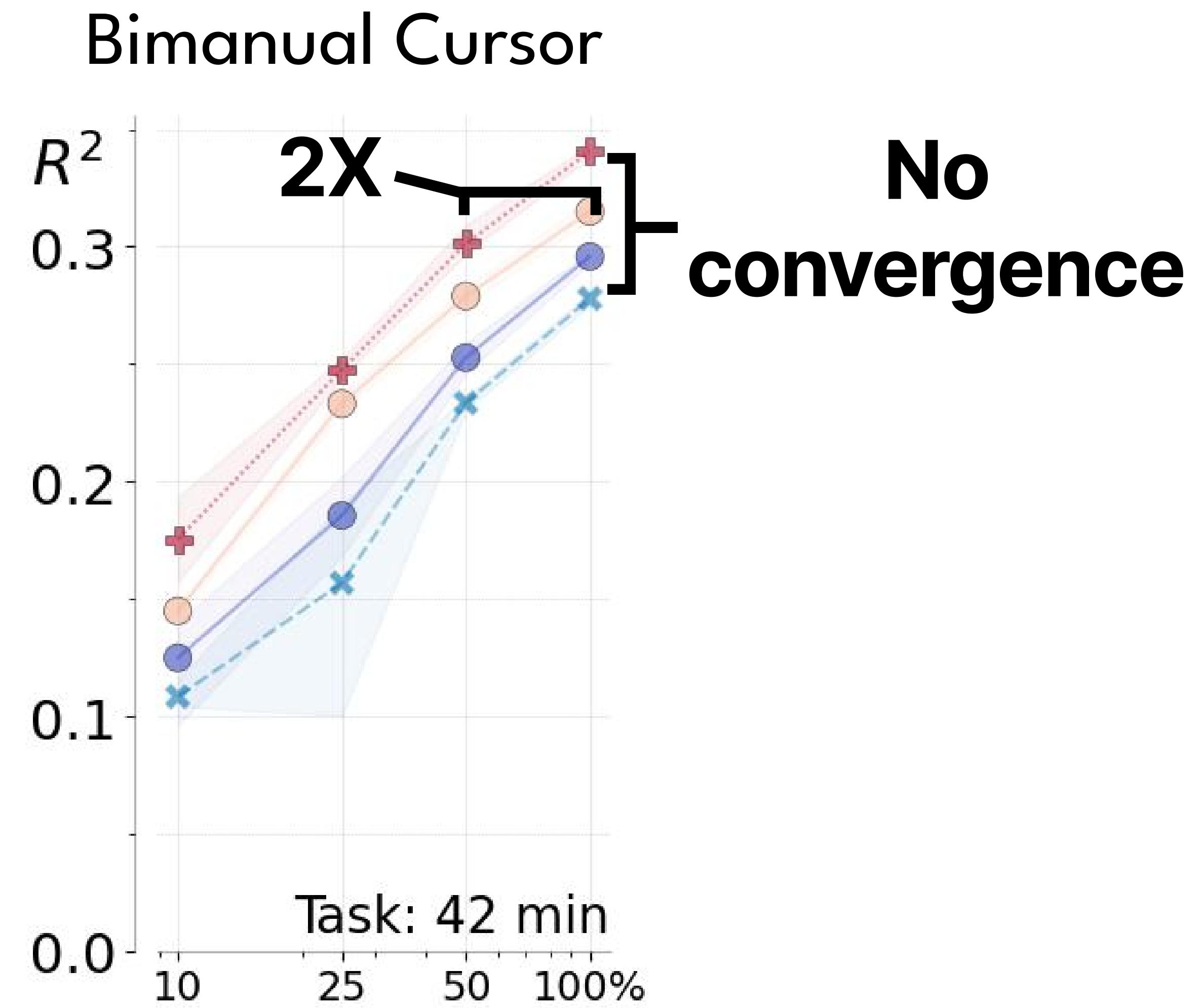
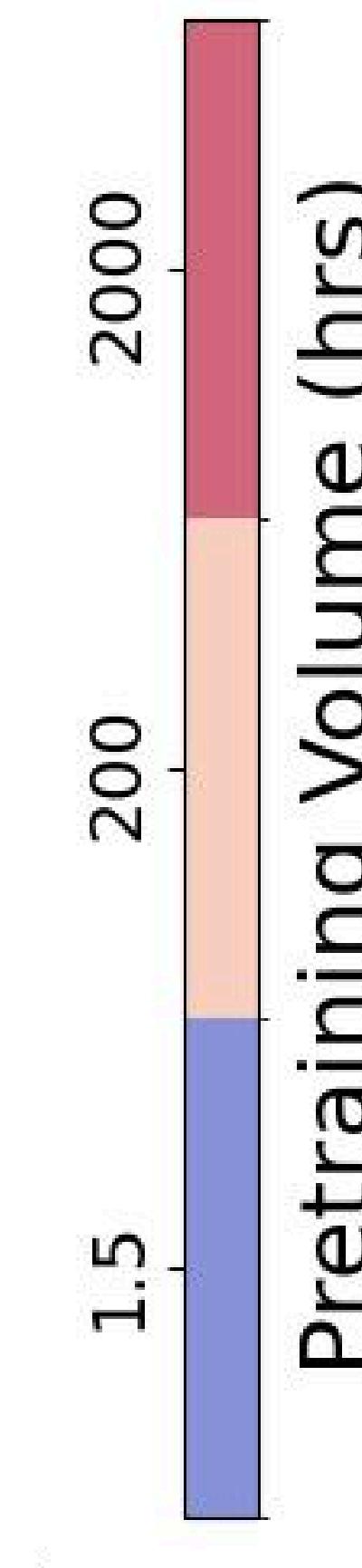
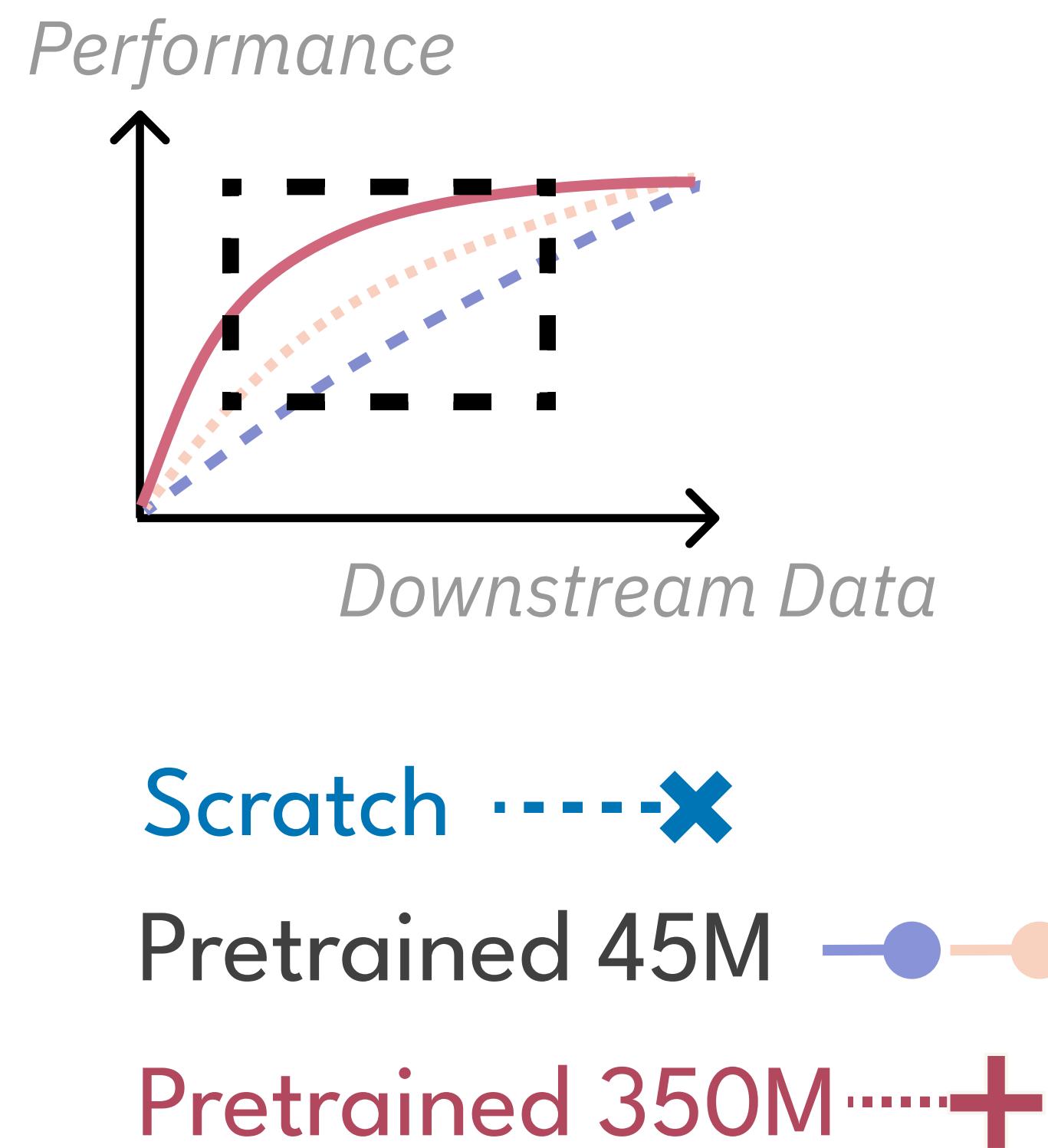
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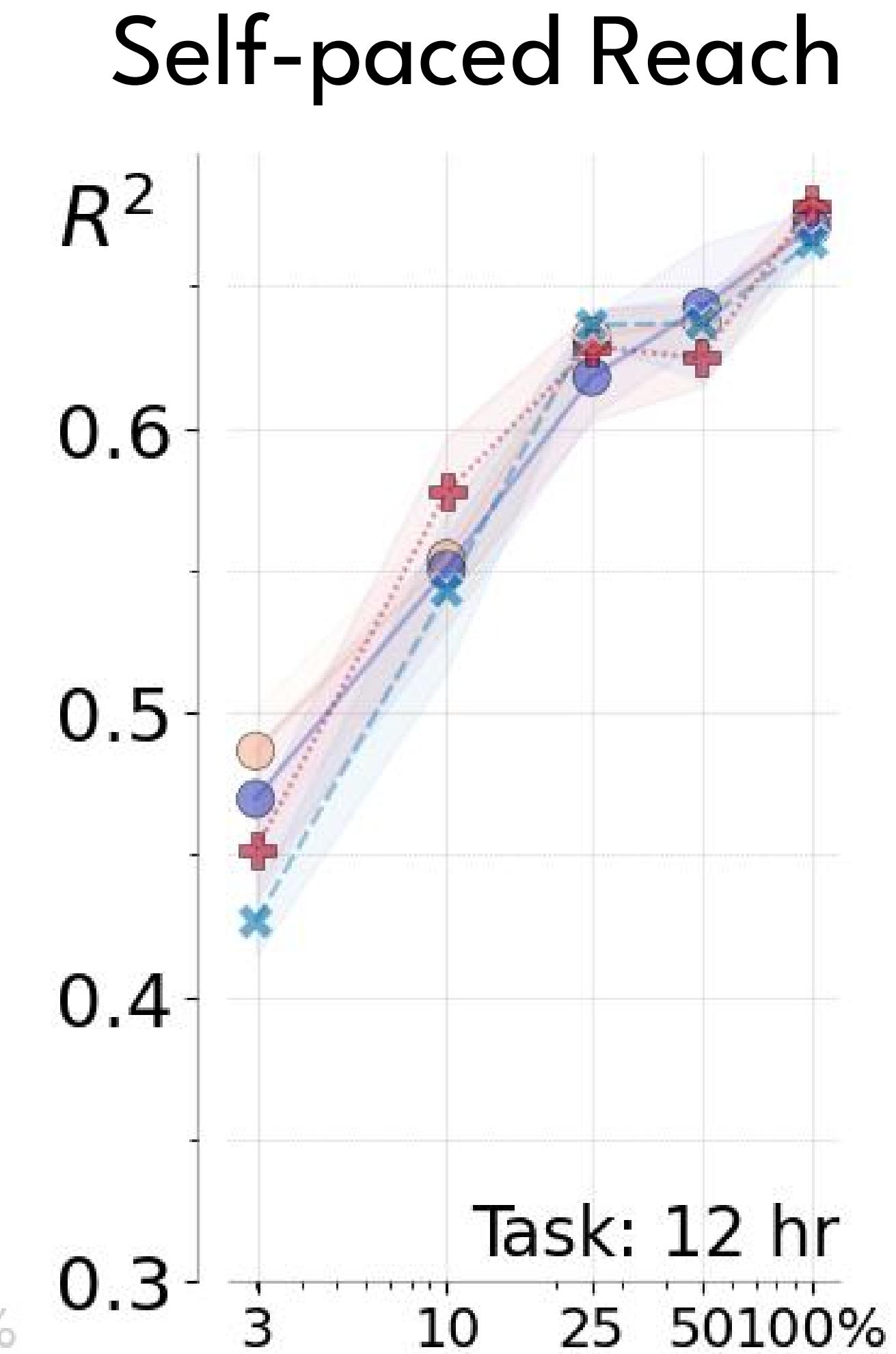
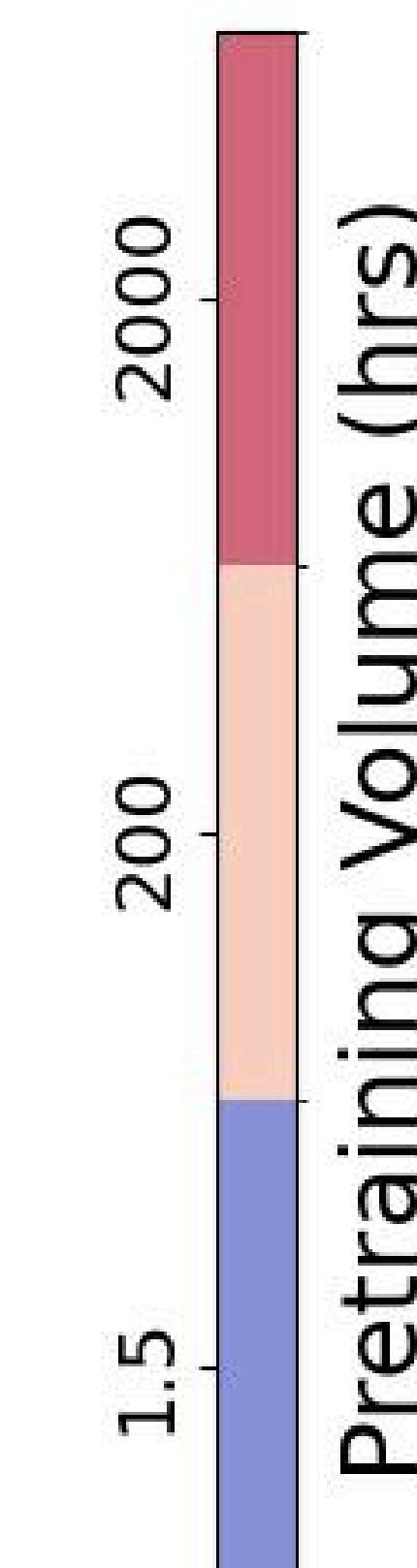
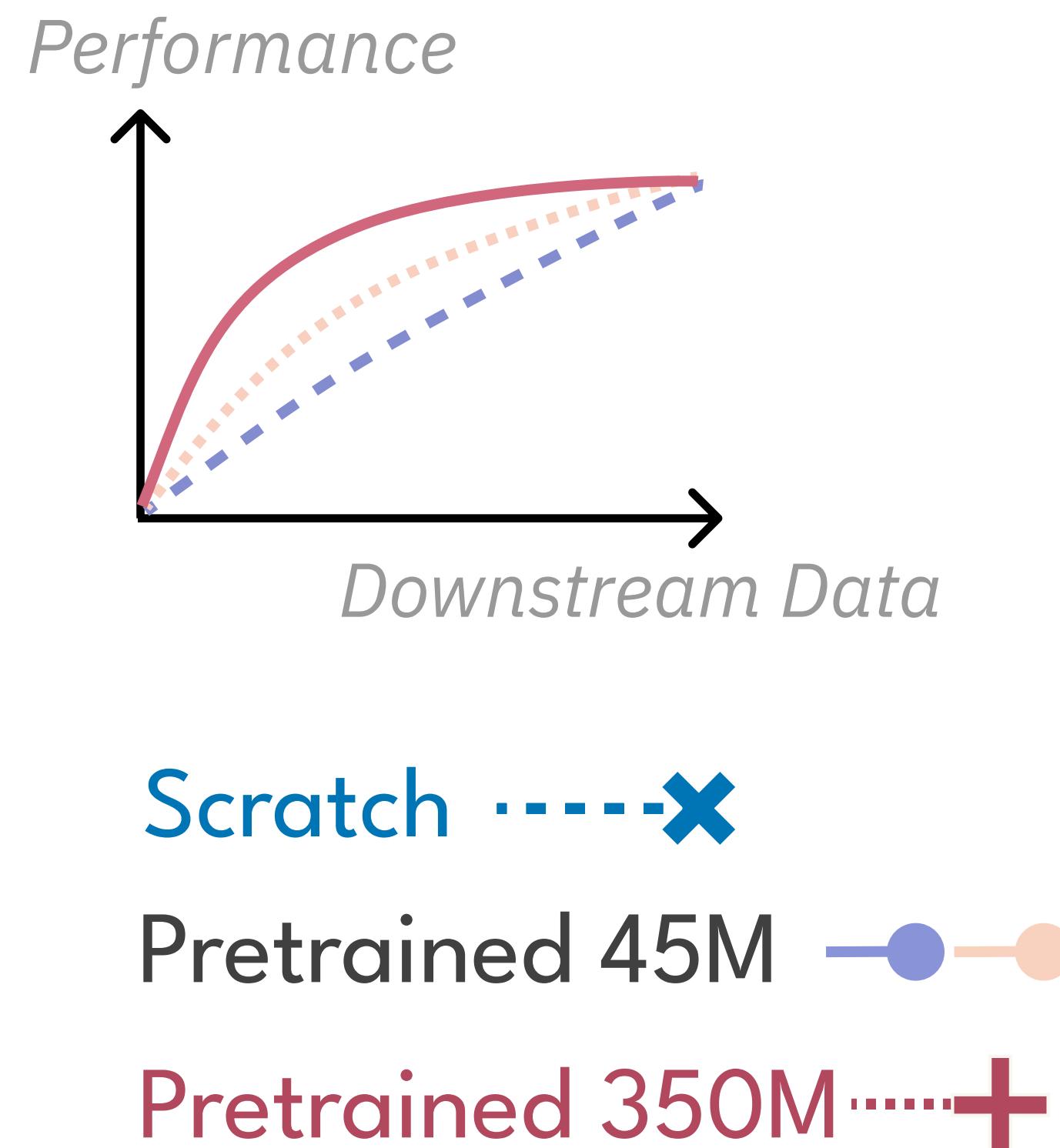
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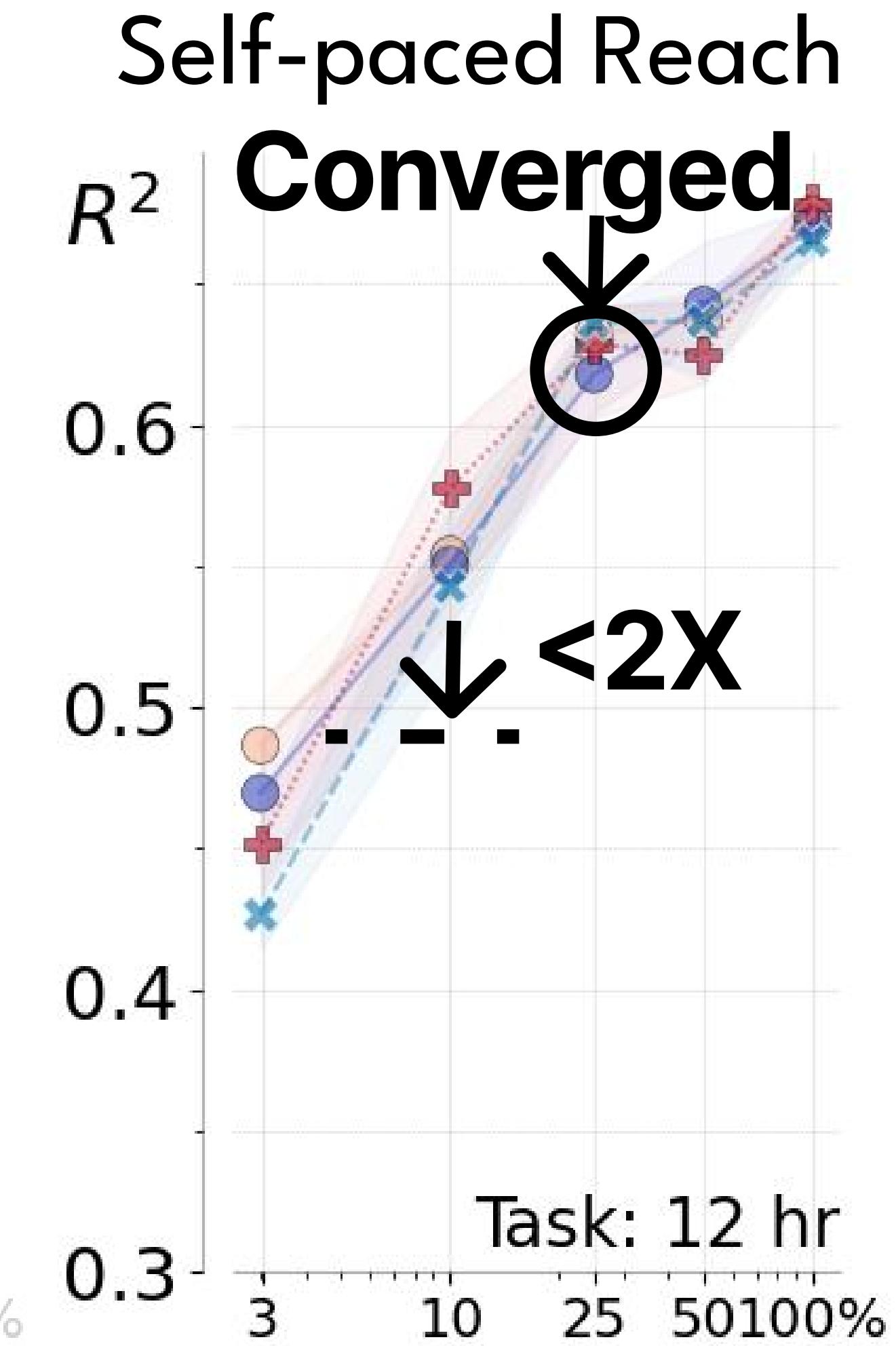
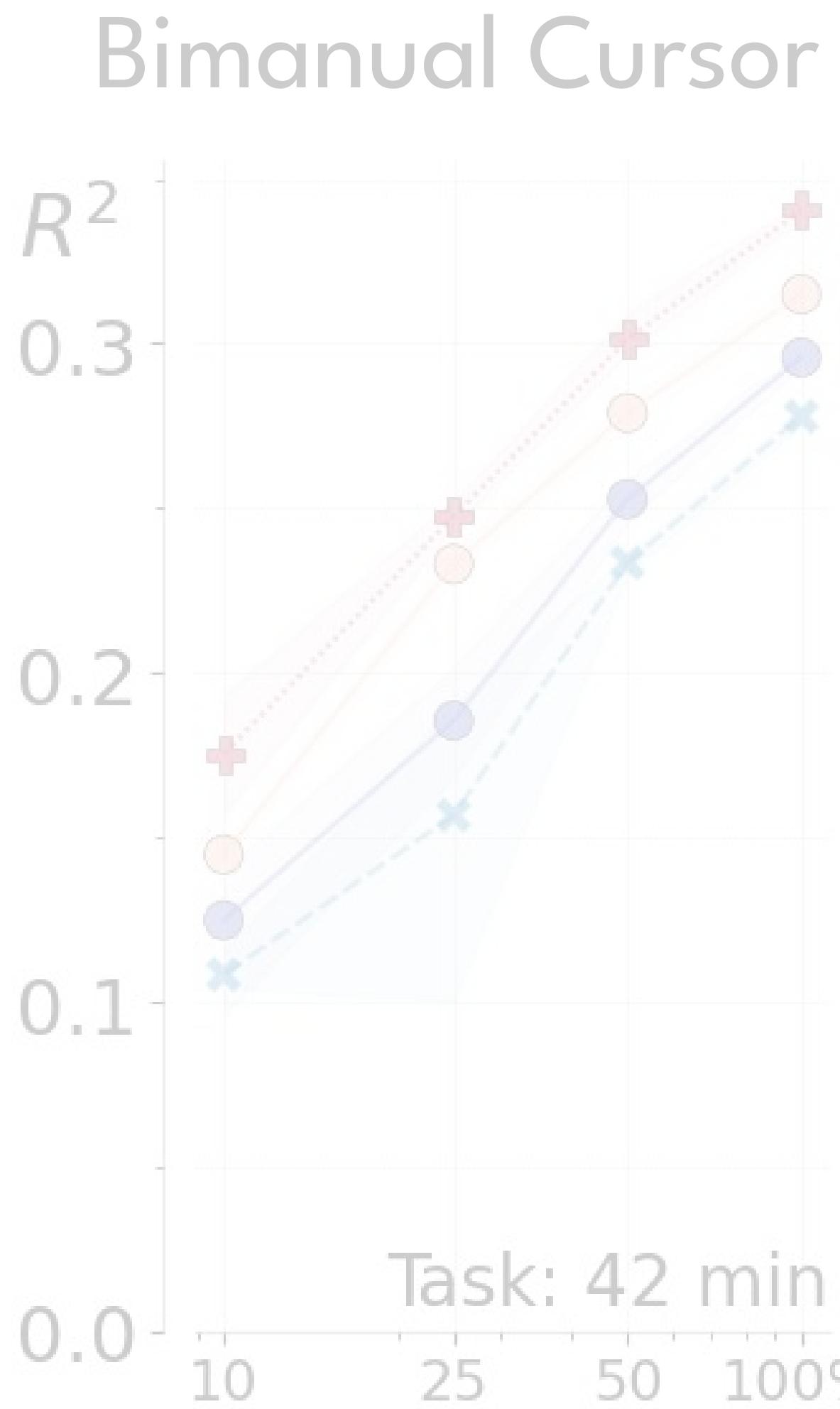
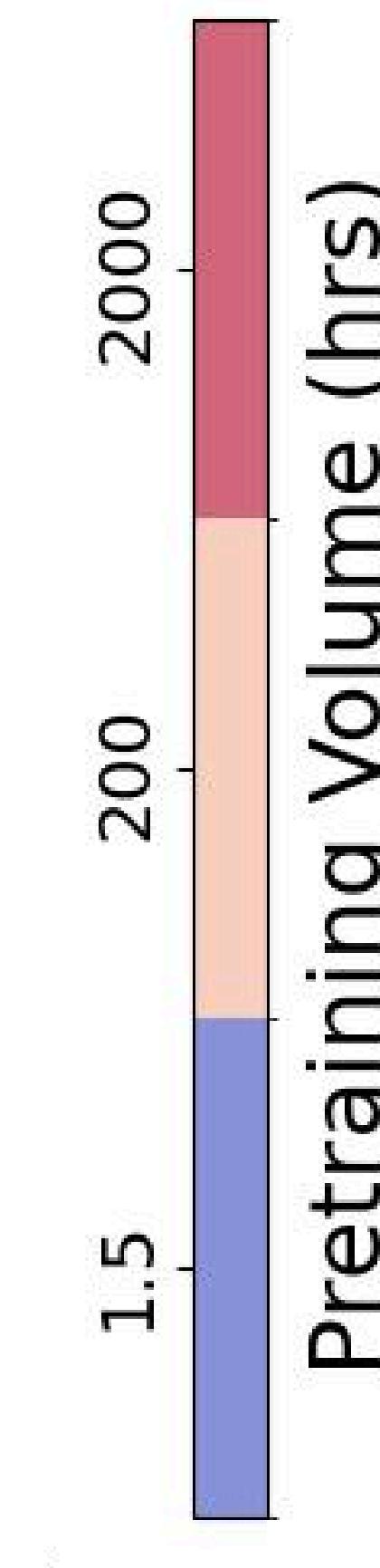
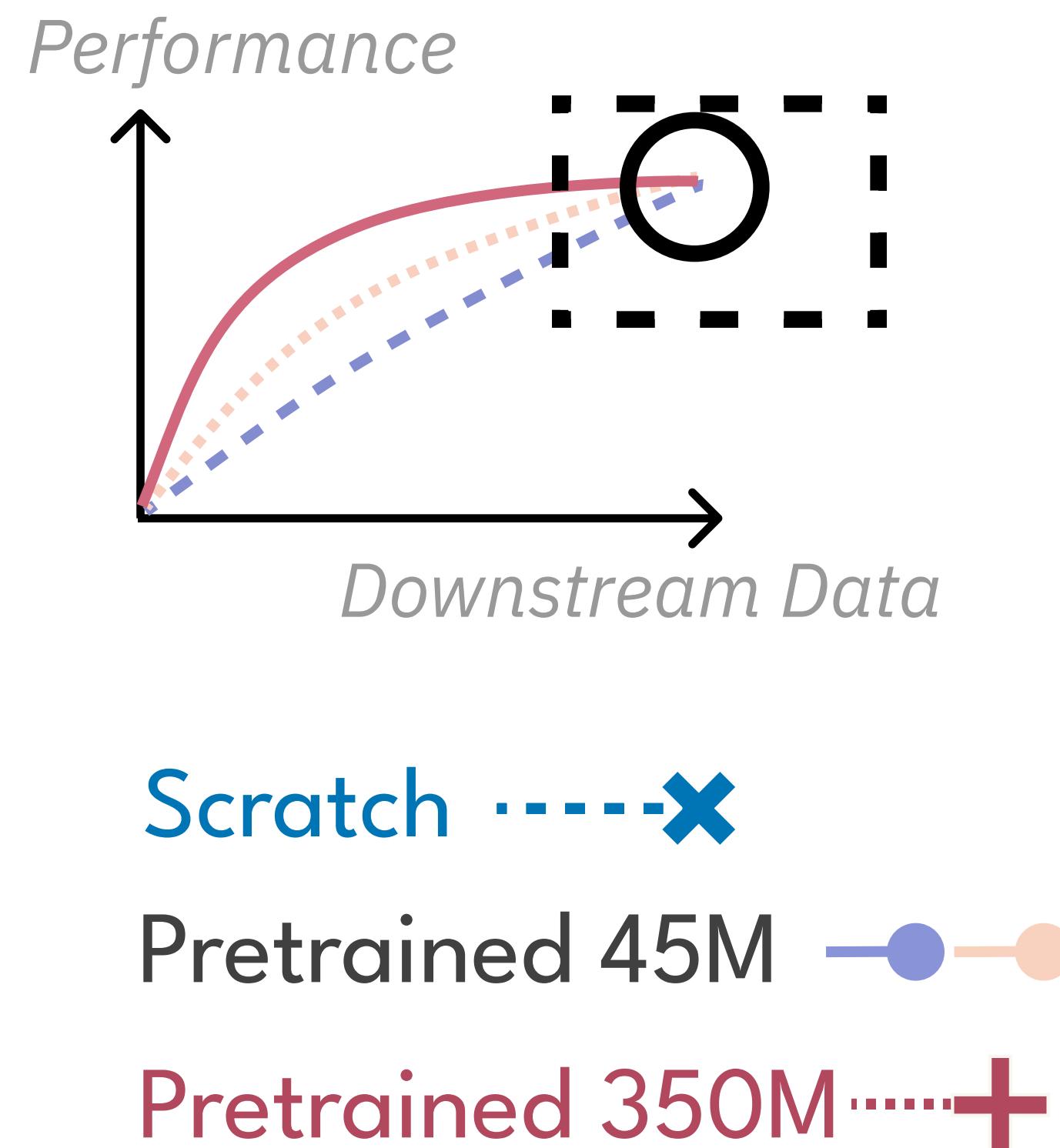
## Quantifying downstream scaling gains



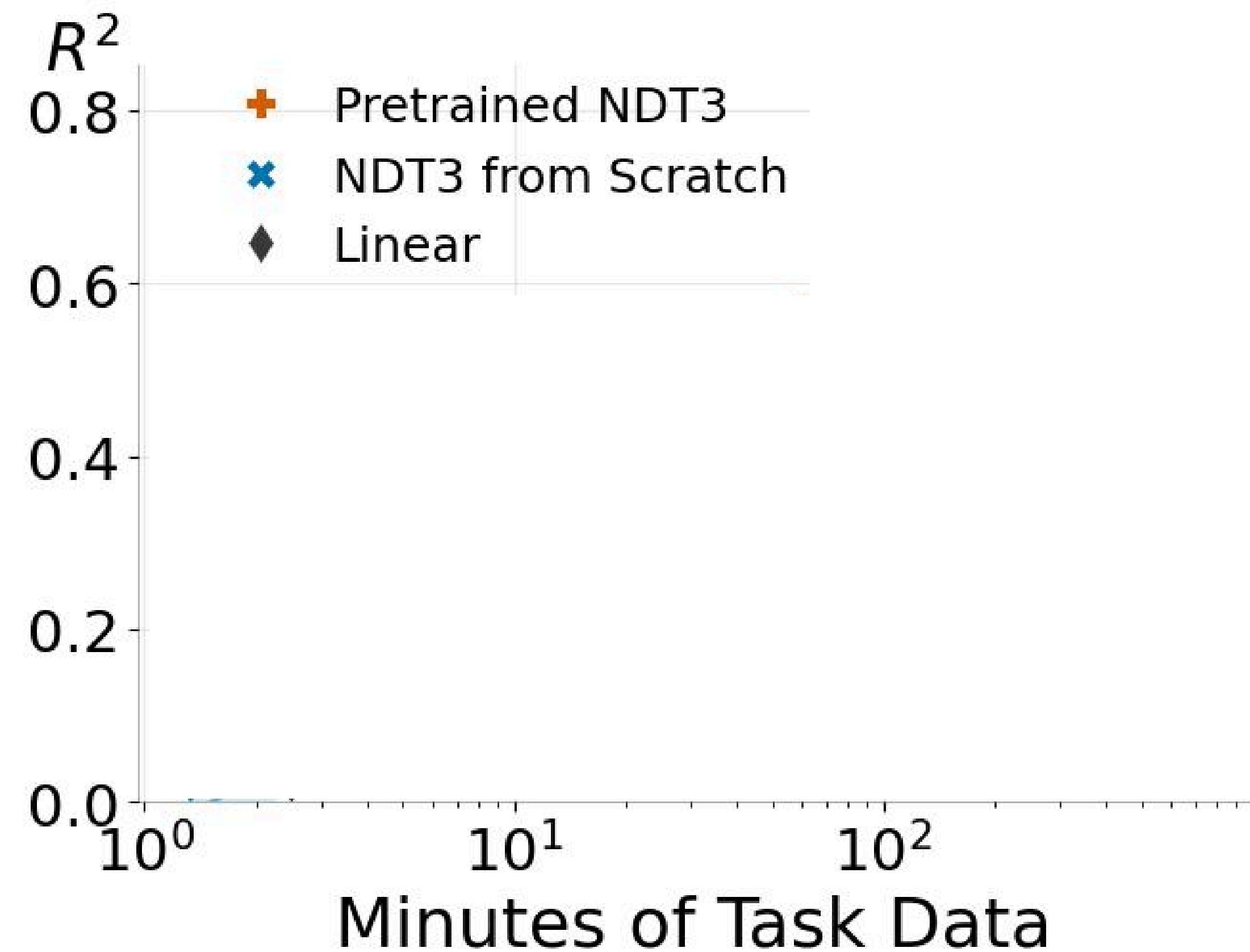
# Quantifying downstream scaling gains **across tasks**



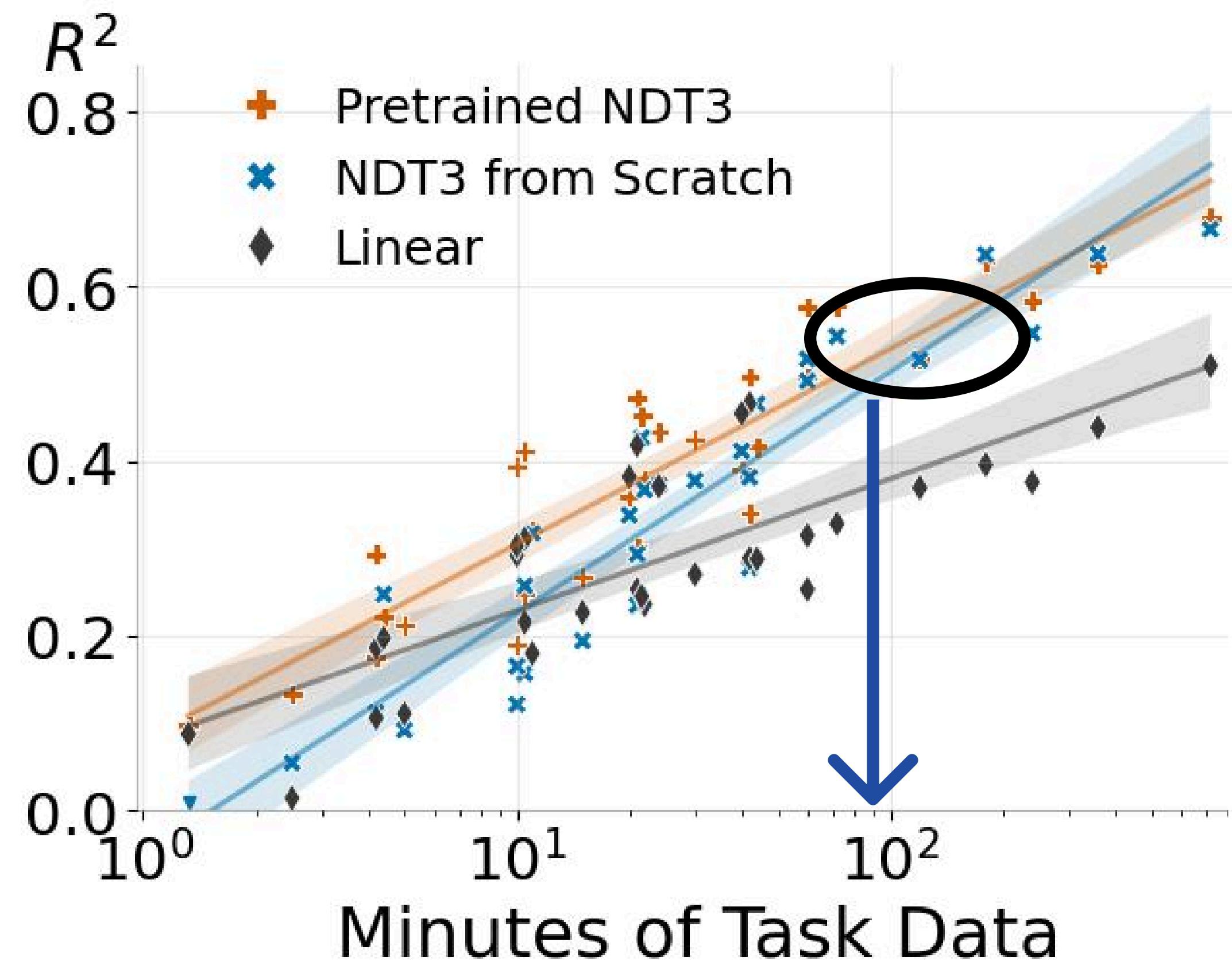
## Quantifying downstream scaling gains **across tasks**



## Quantifying downstream scaling gains **on 8 datasets**

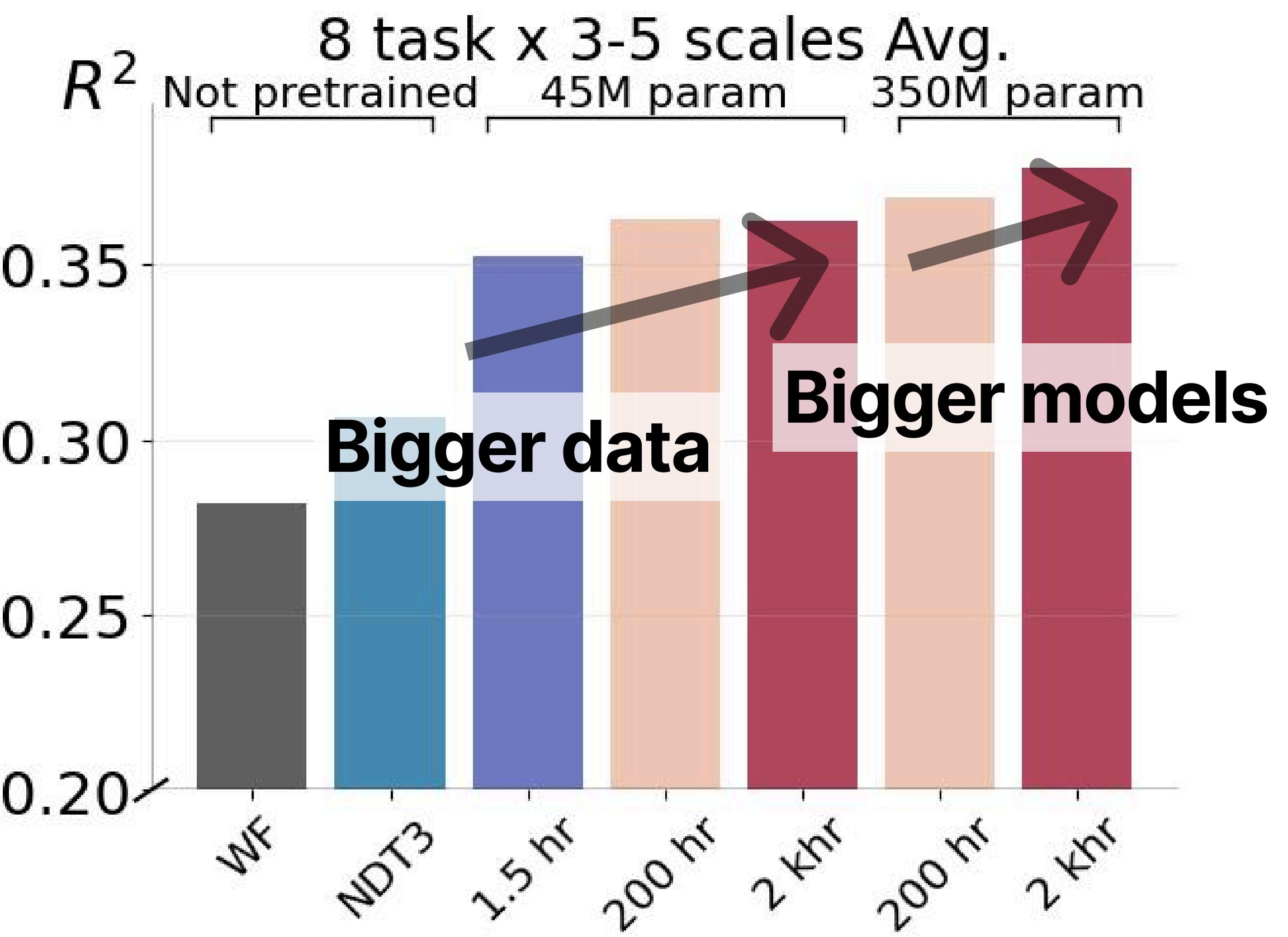
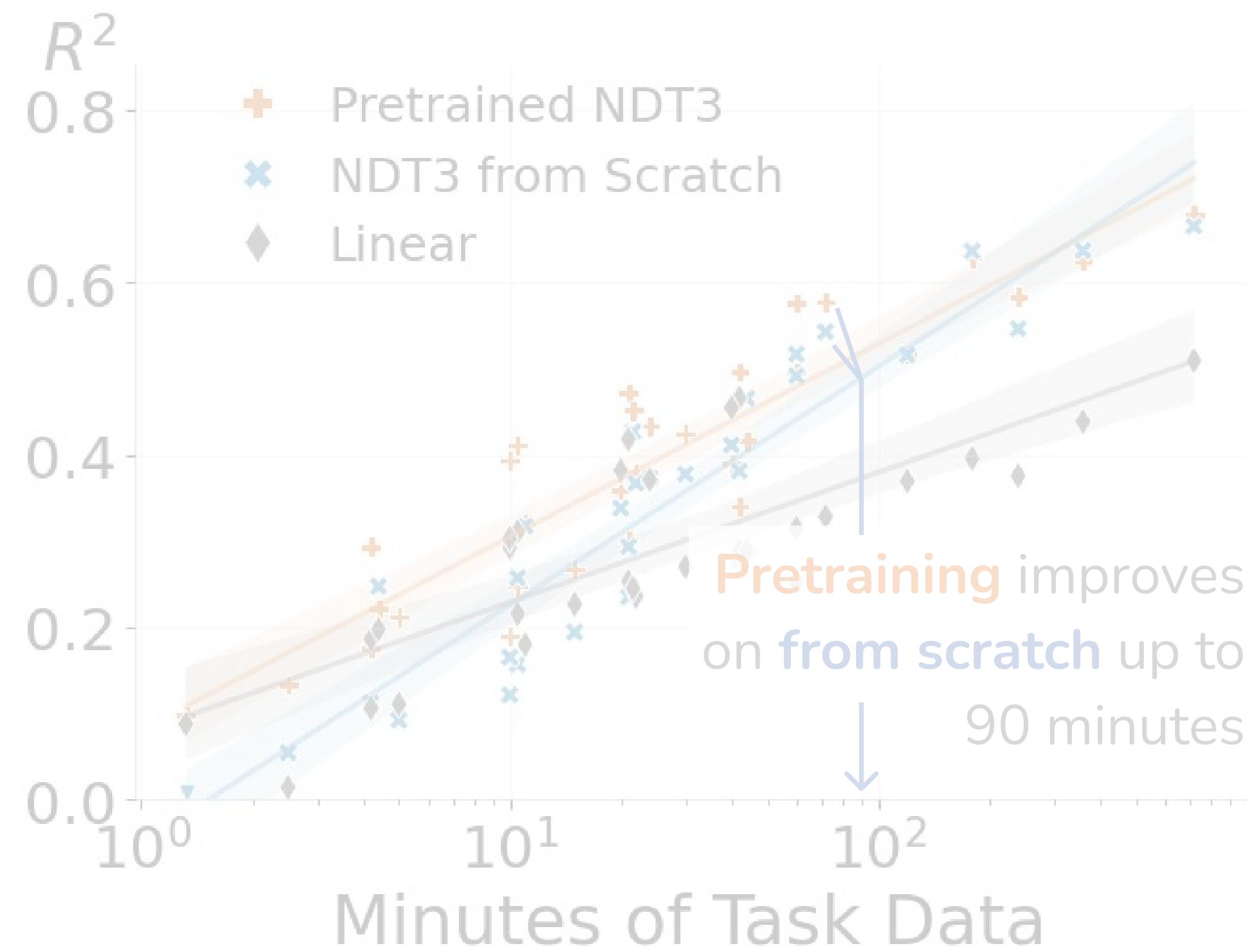


## Quantifying downstream scaling gains **on 8 datasets**

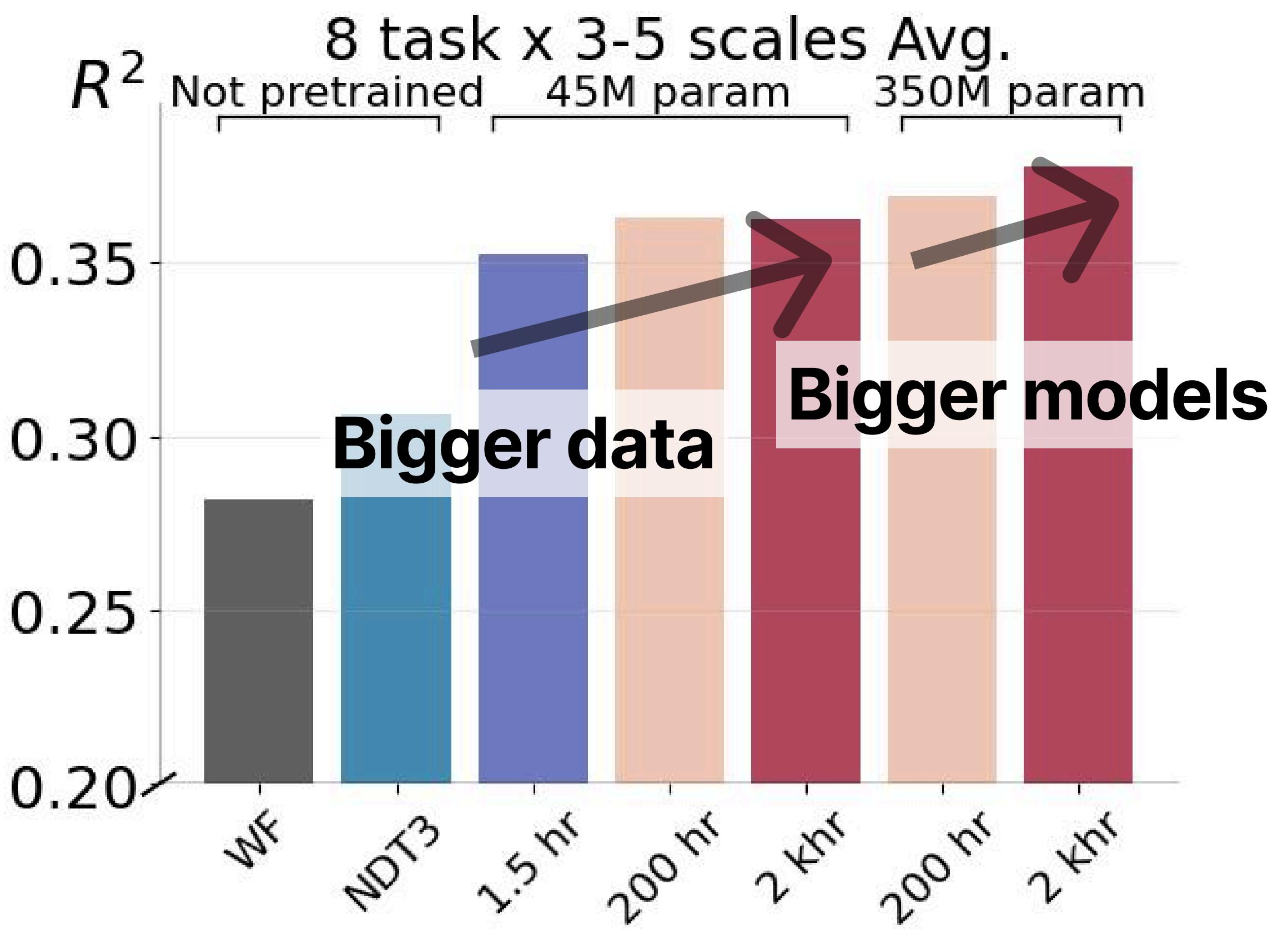
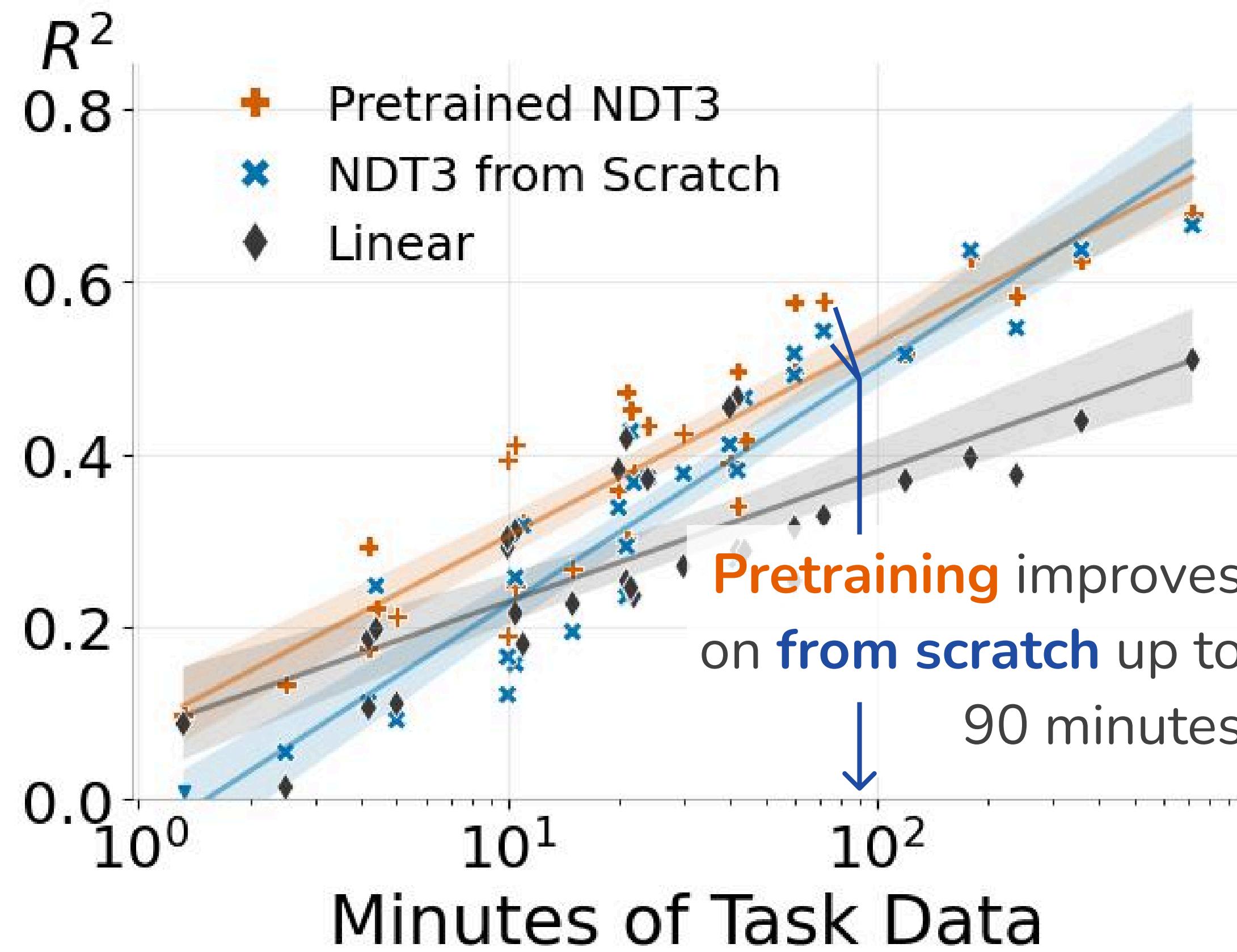


**Pretraining** improves  
on **from scratch** up to  
90 minutes

## Quantifying downstream scaling gains on 8 datasets



**NDT has modest practical value for BCI, and scaling likely won't change this.**



**1. Evaluating\* for pragmatics (is hard)**

**2. Evaluating for generalization**

**Neural foundation models need evaluations to progress.**

## 1. Evaluating for pragmatics

## 2. Evaluating for generalization

**Pretrain** → **Tune A** → **Evaluate B**

- Ecological covariate shifts
- Angular attractors
- Cursor control

**Neural foundation models need evaluations to progress.**

**Pretrain** → **Tune A** → **Evaluate B**

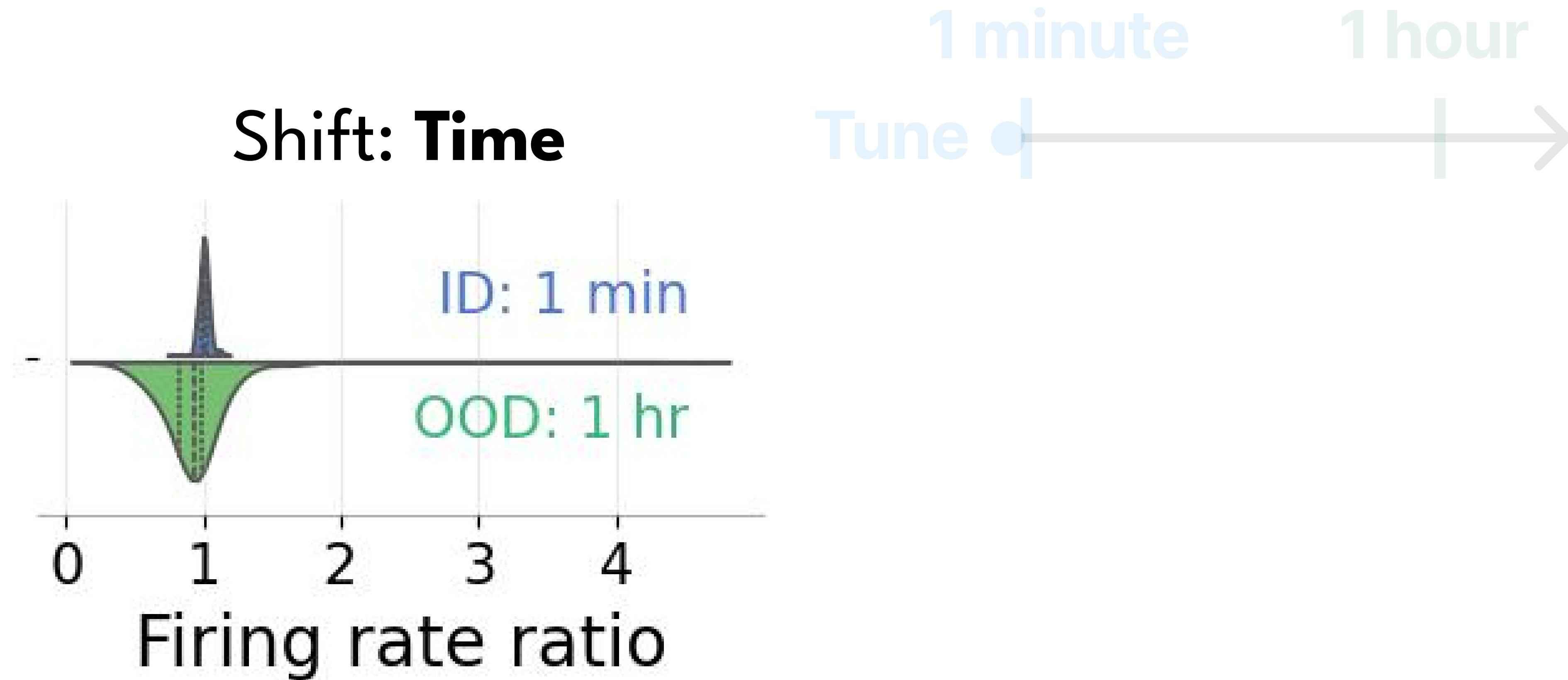
## **Ecological covariate shifts**

**Shift: Time**



**Pretrain** → **Tune A** → **Evaluate B**

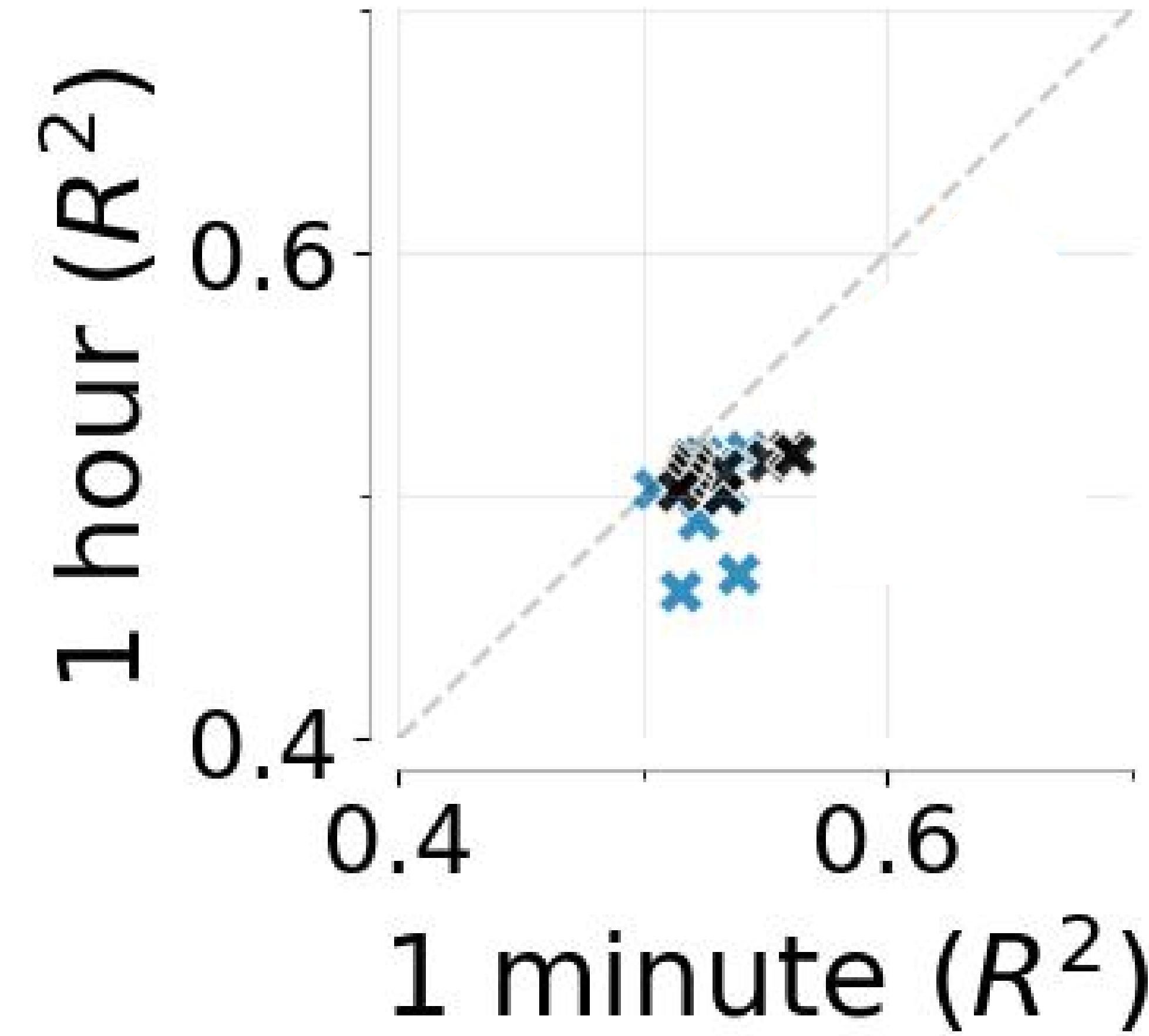
## Ecological covariate shifts



Pretrain → Tune A → Evaluate B

## Ecological covariate shifts

Shift: Time



✖ Wiener Filter

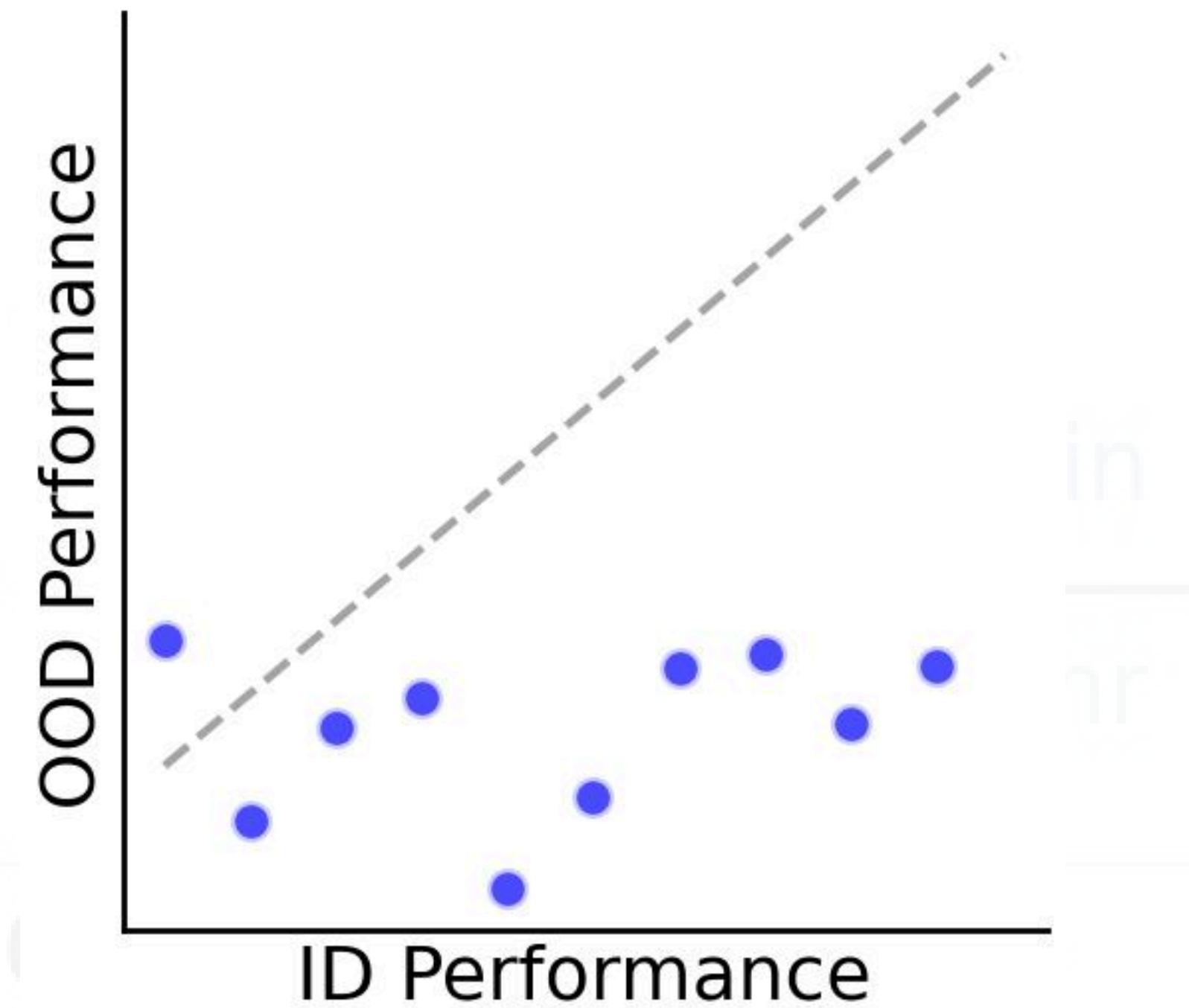
✖ Scratch

● 200hr 45M

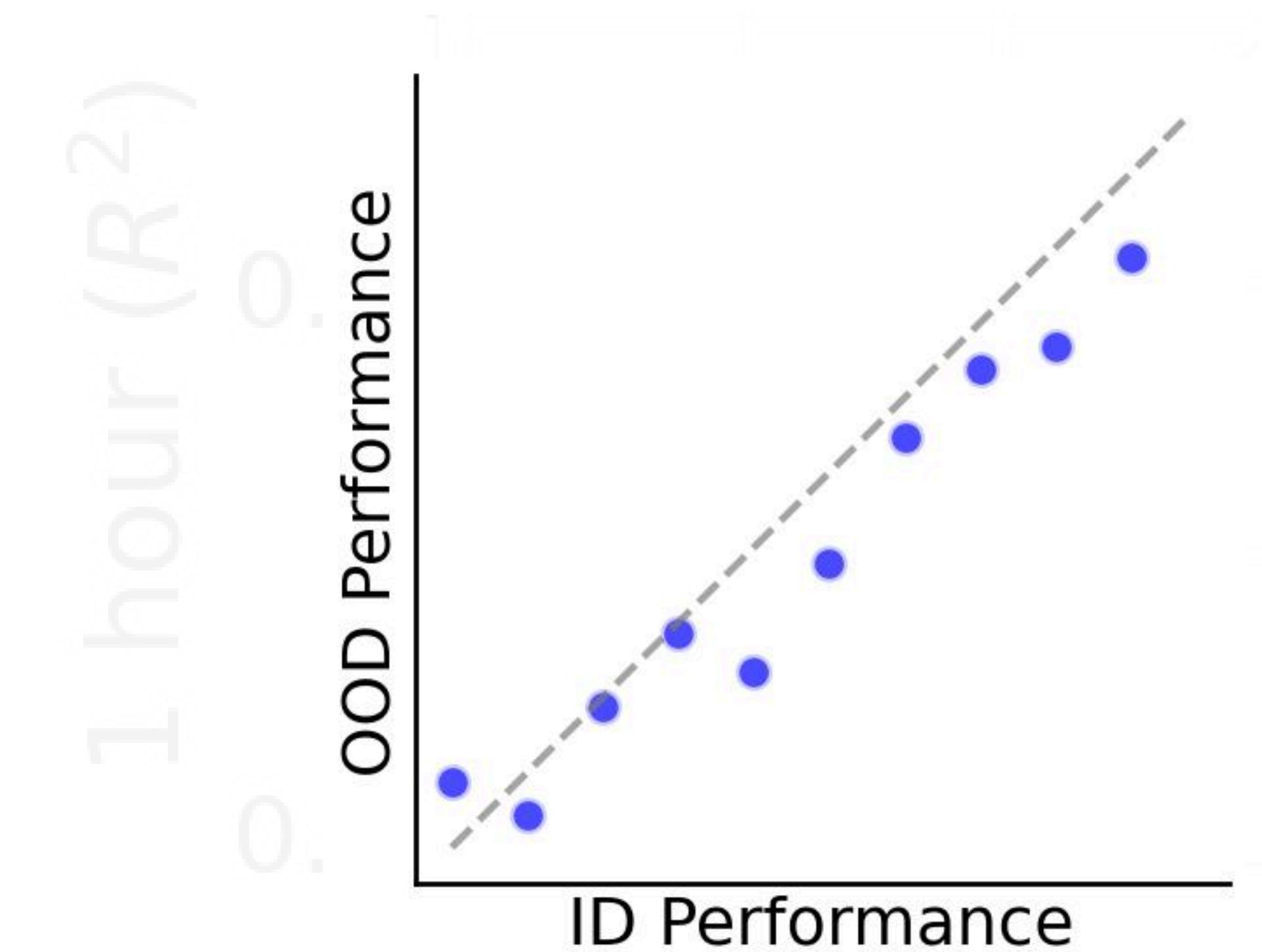
✚ 2khr 350M

Pretrain → Tune A → Evaluate B

## Ecological covariate shifts



**Hypothesis 1: Fragile features**



**Hypothesis 2: Robust gains**

Wiener Filter

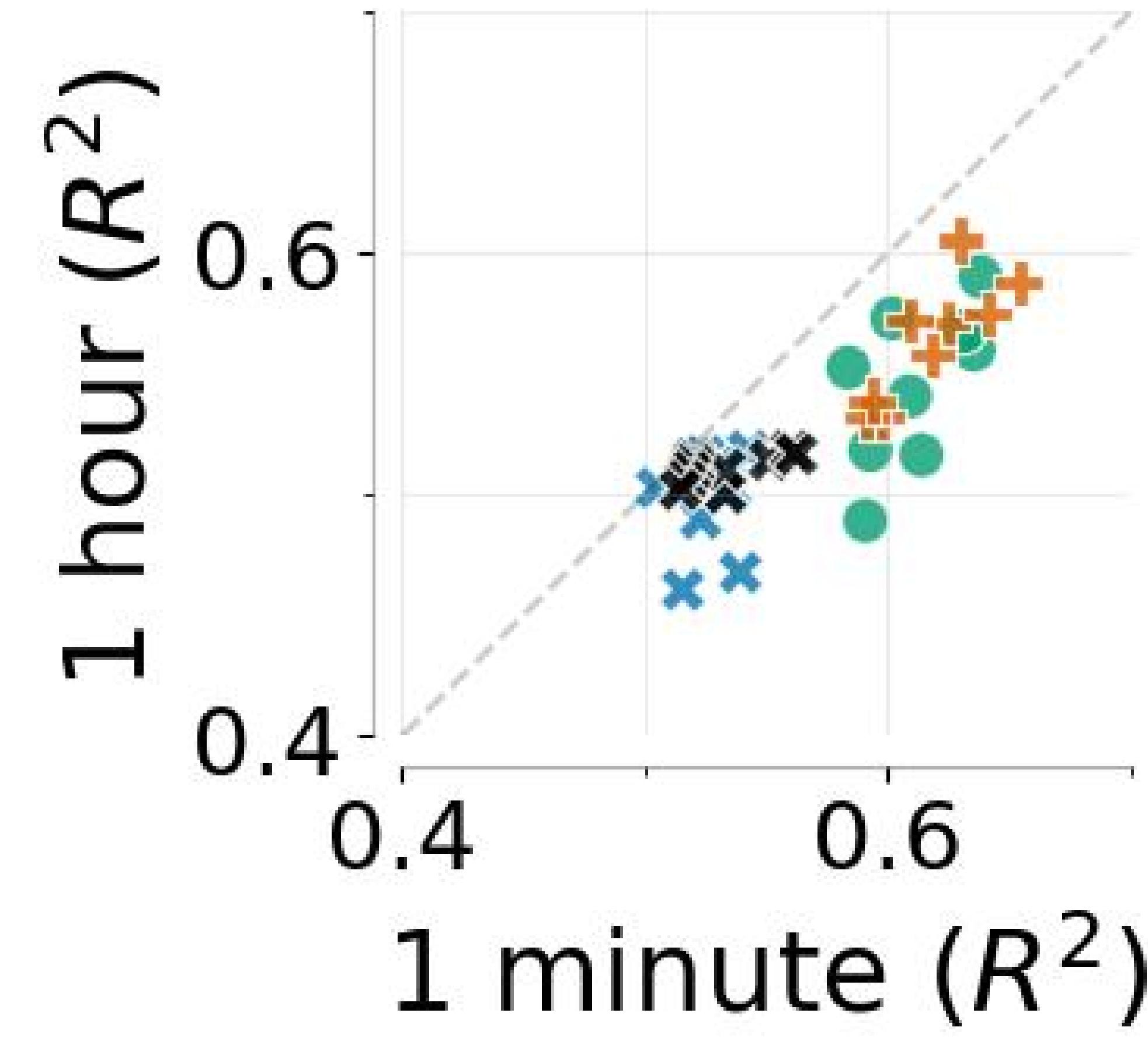
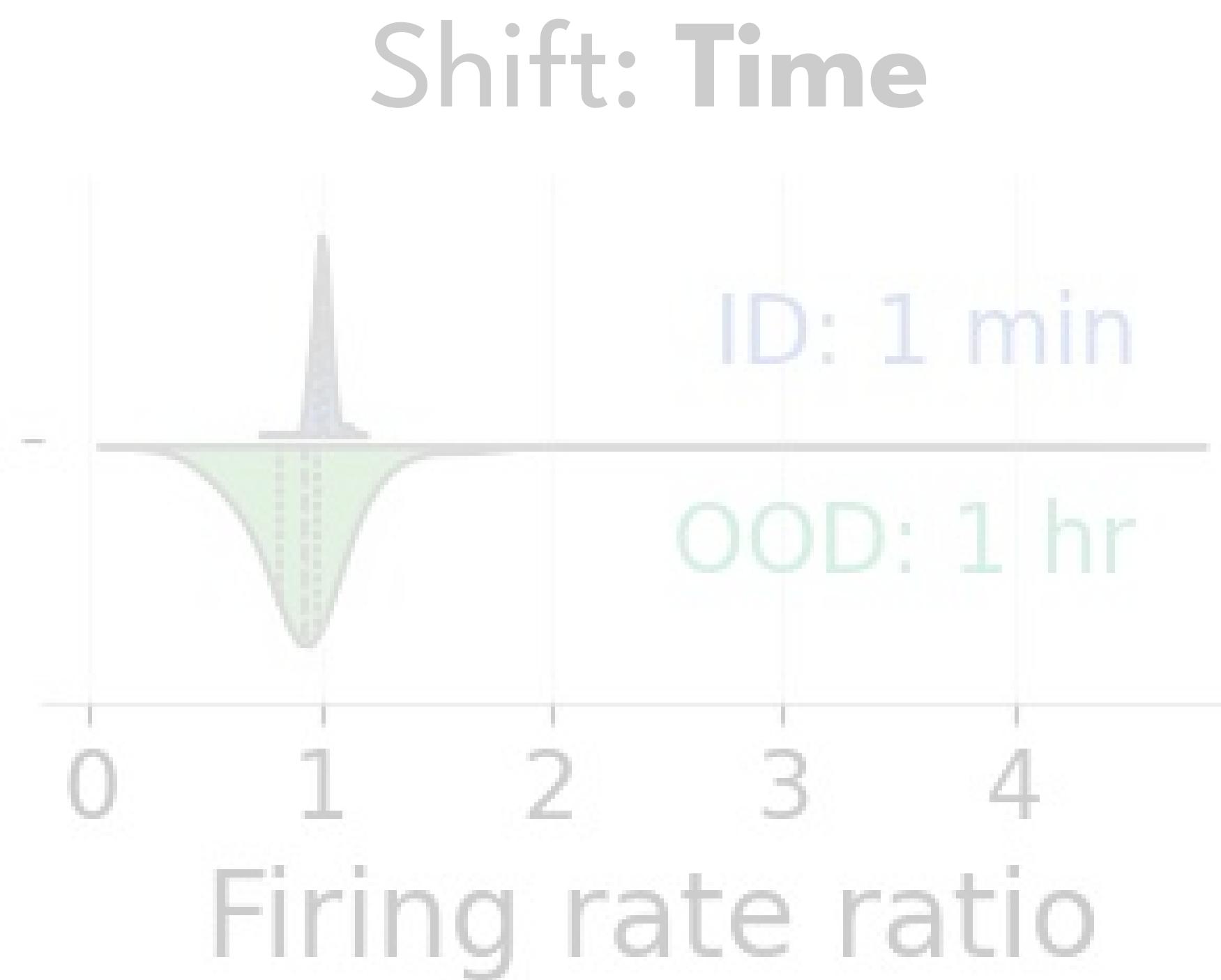
Scratch

200hr 45M

+2khr 350M

Pretrain → Tune A → Evaluate B

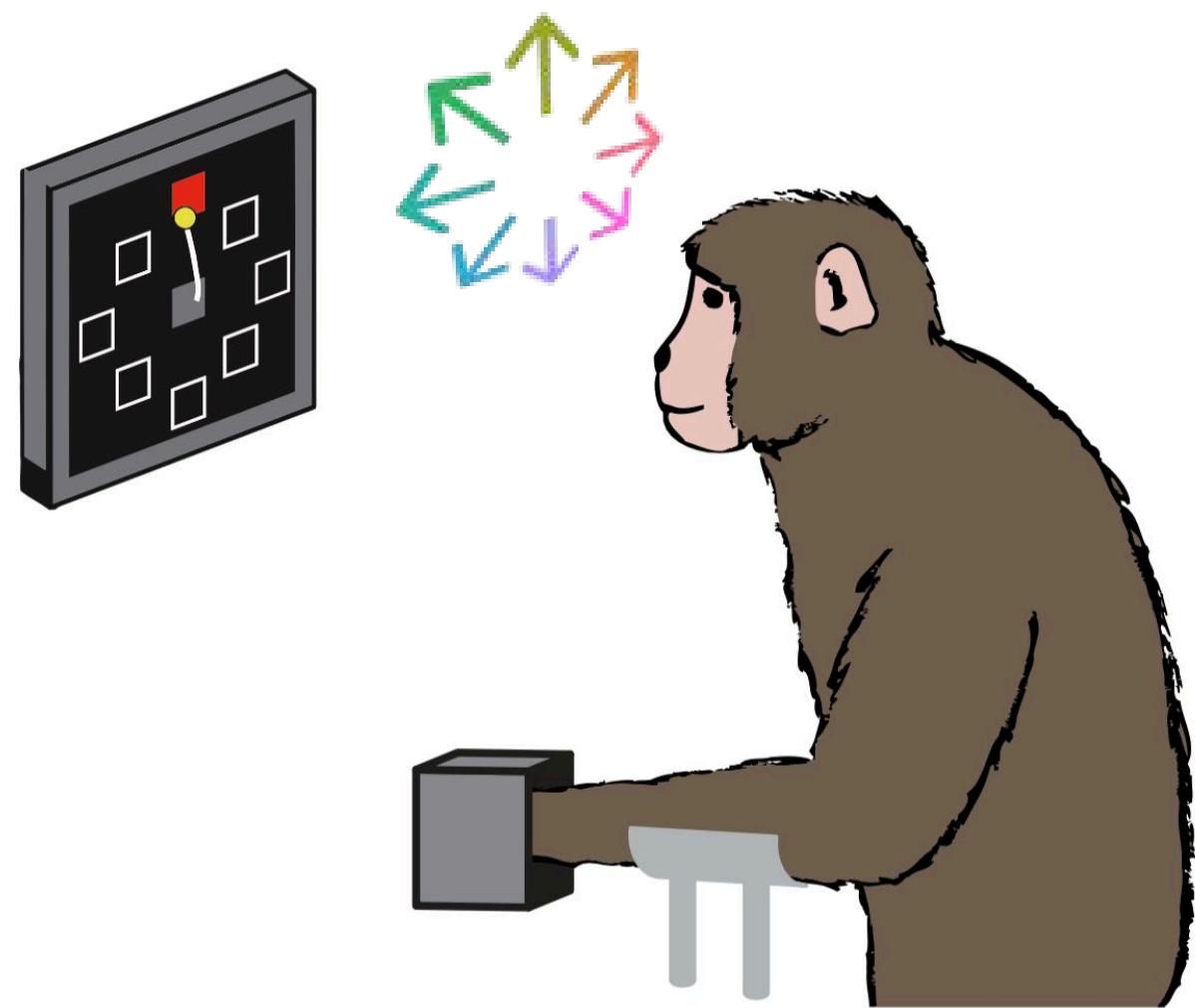
## Ecological covariate shifts



✖ Wiener Filter   ✖ Scratch   ● 200hr 45M   + 2khr 350M

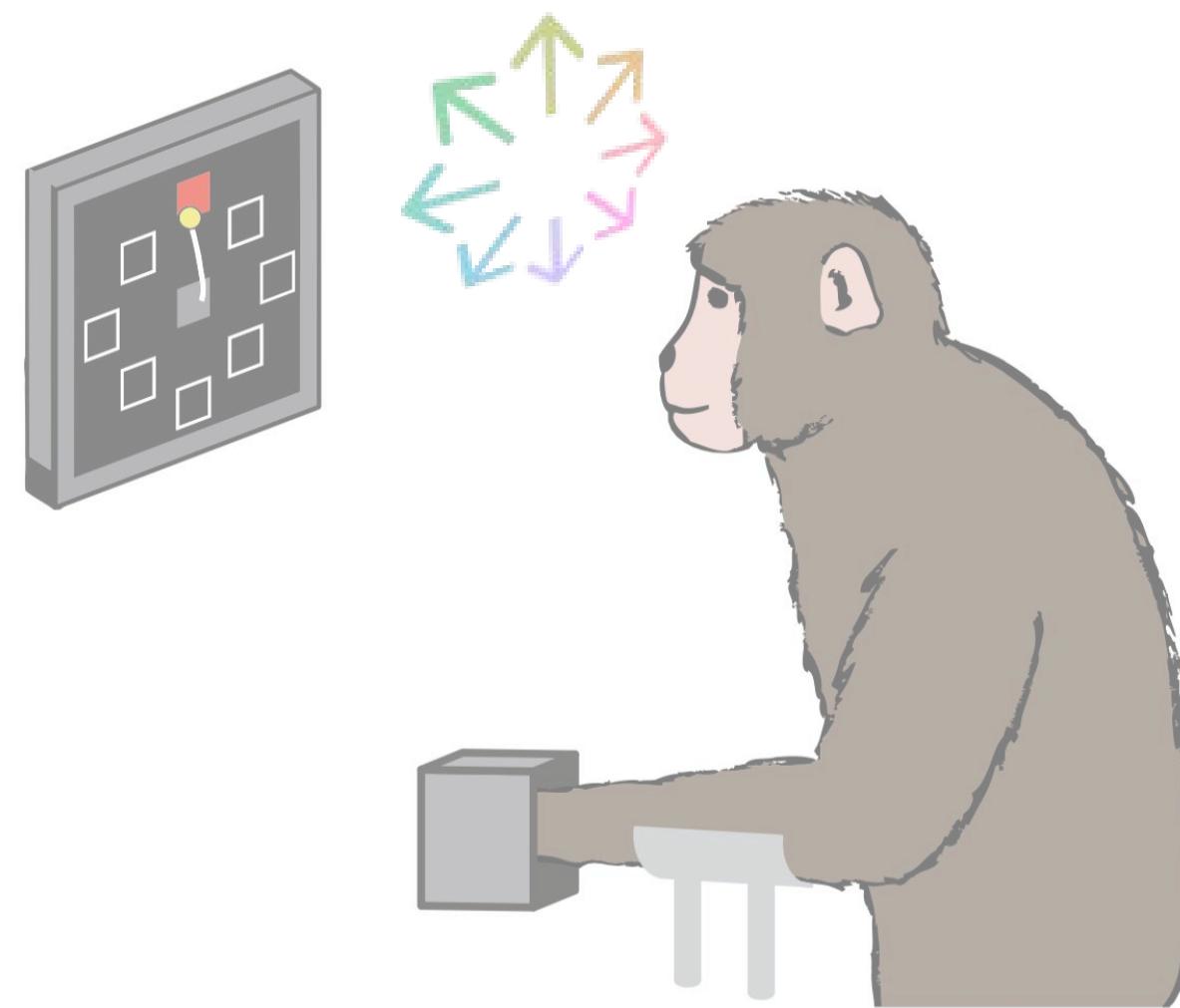
**Pretrain** → **Tune A** → **Evaluate B**

## **Angular attractors: Probing for “qualitative priors”**

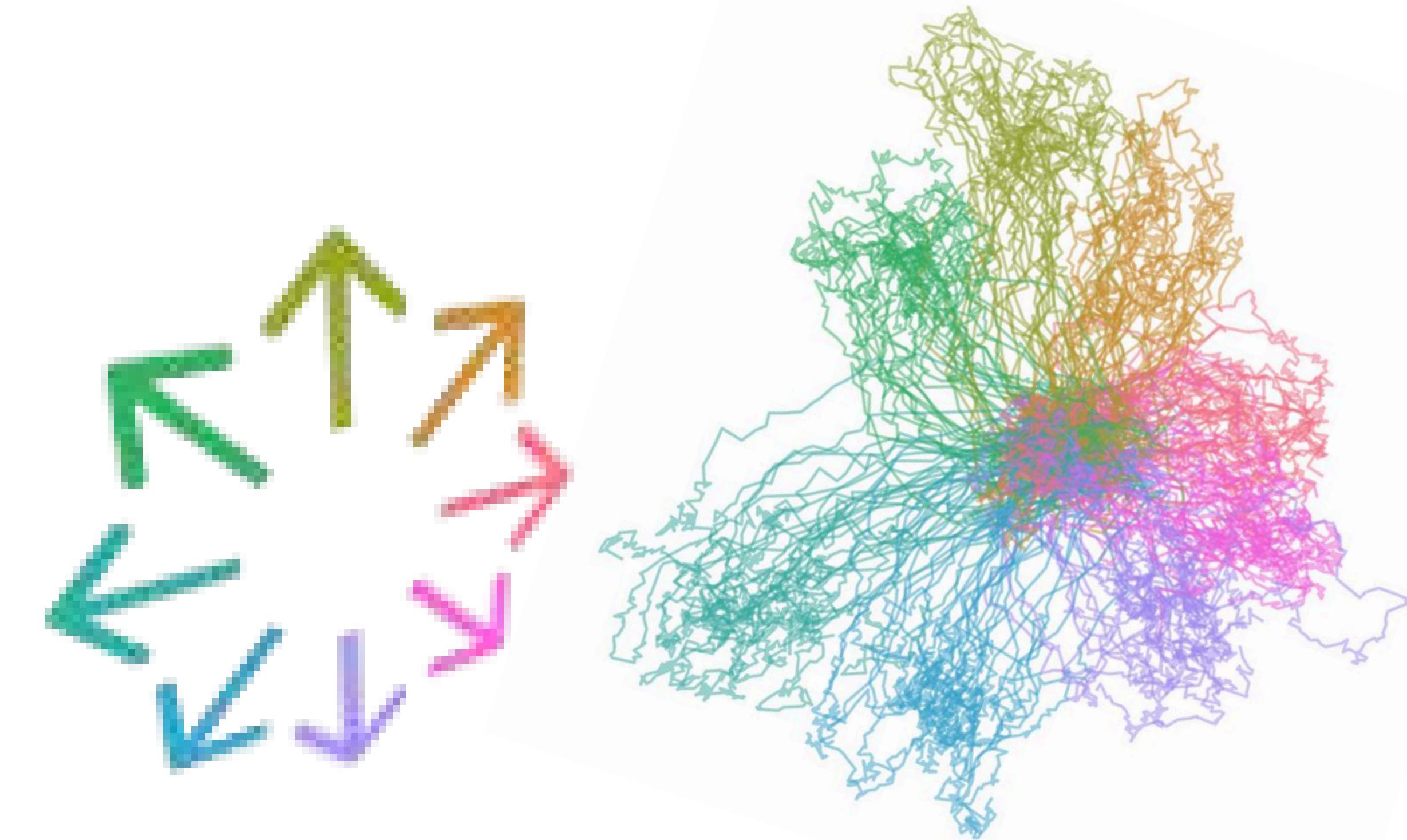


**Pretrain** → **Tune A** → **Evaluate B**

## Angular attractors

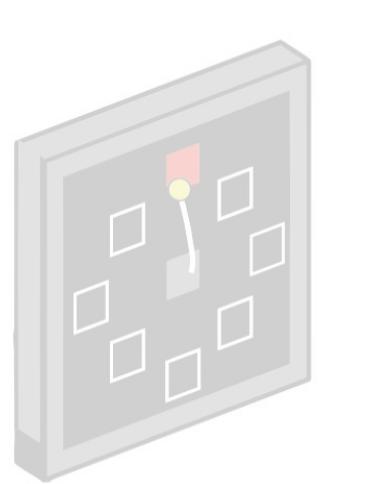


## PCA + LDA Trajectories



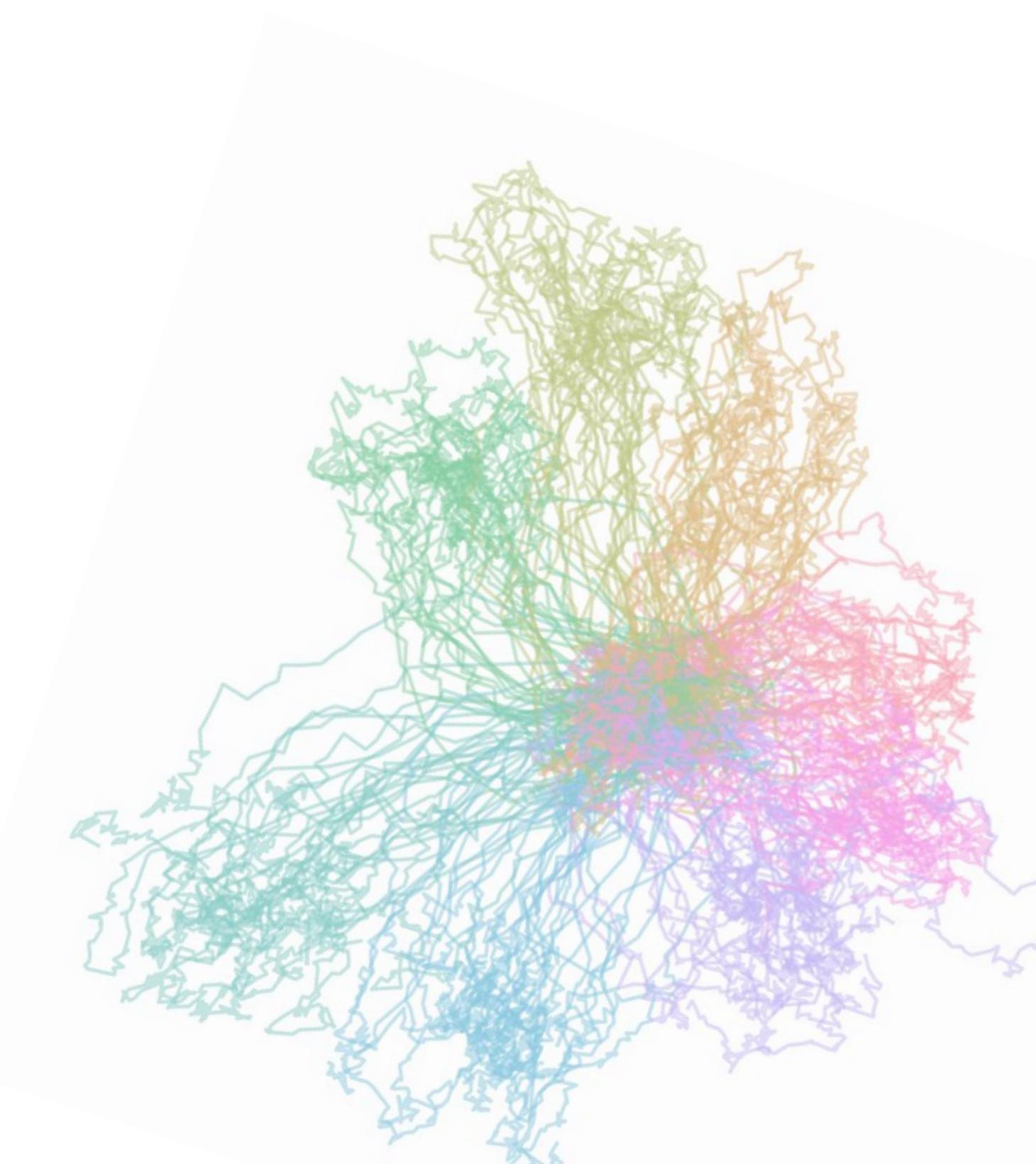
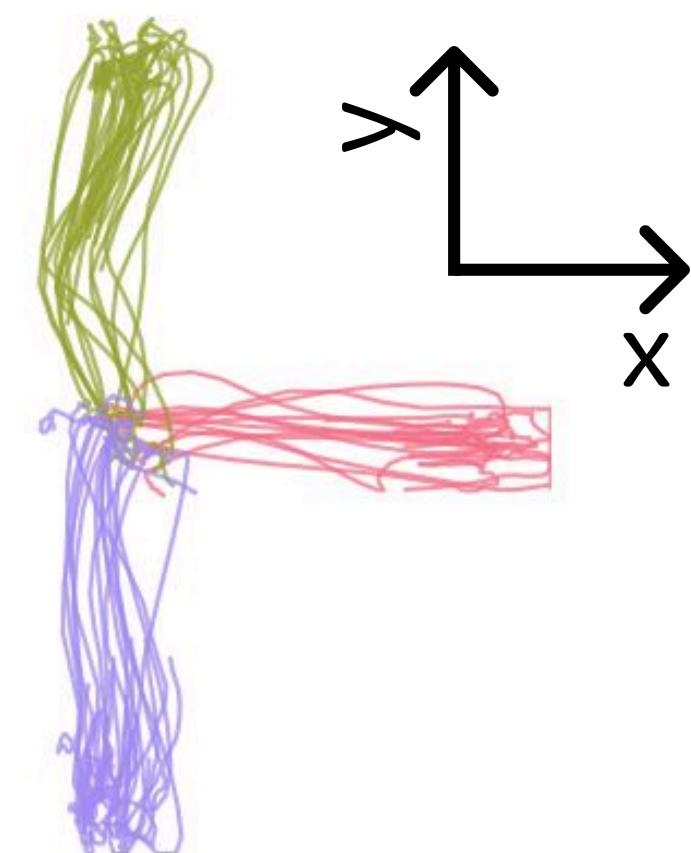
Pretrain → Tune A → Evaluate B

## Angular attractors



Train angles

Behavior

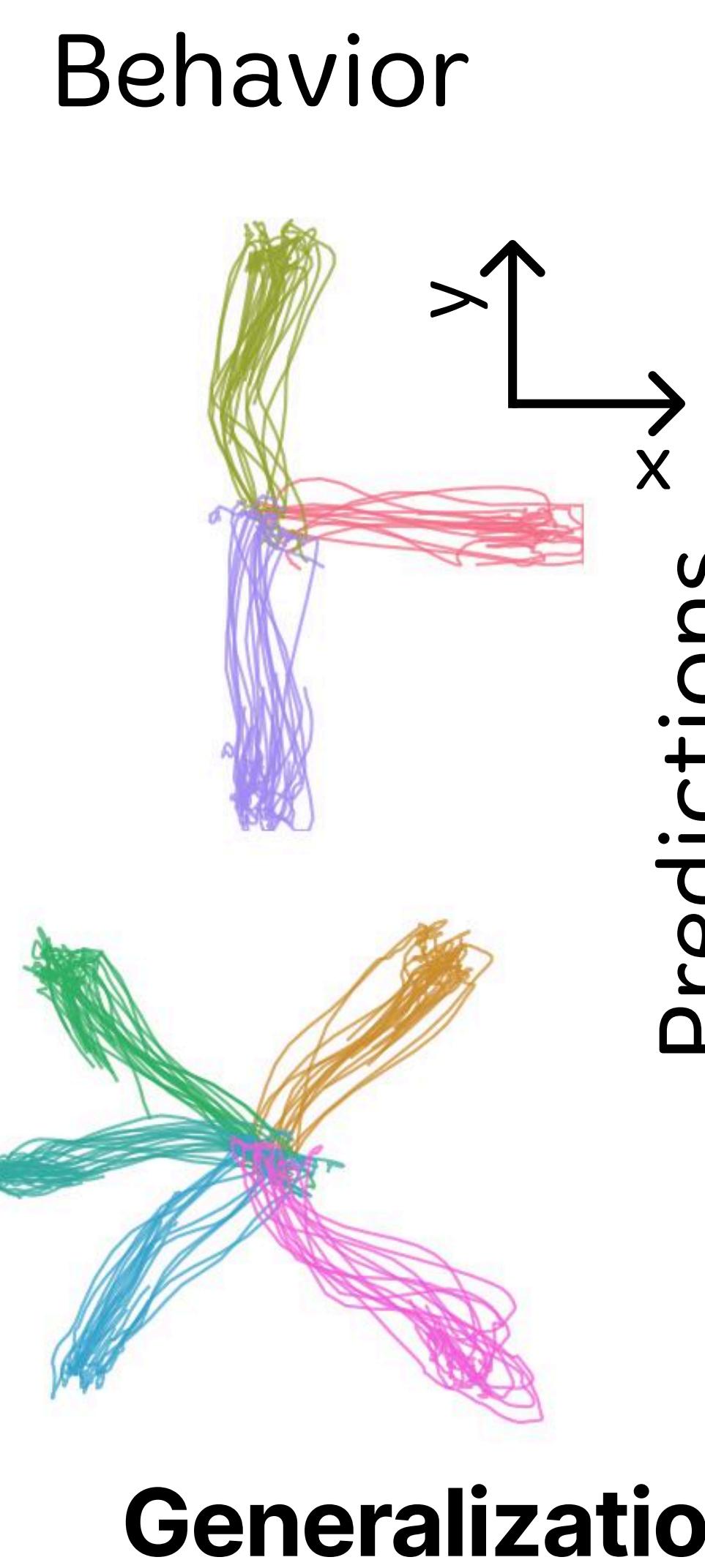


**Pretrain** → **Tune A** → **Evaluate B**

## Angular attractors



Train angles

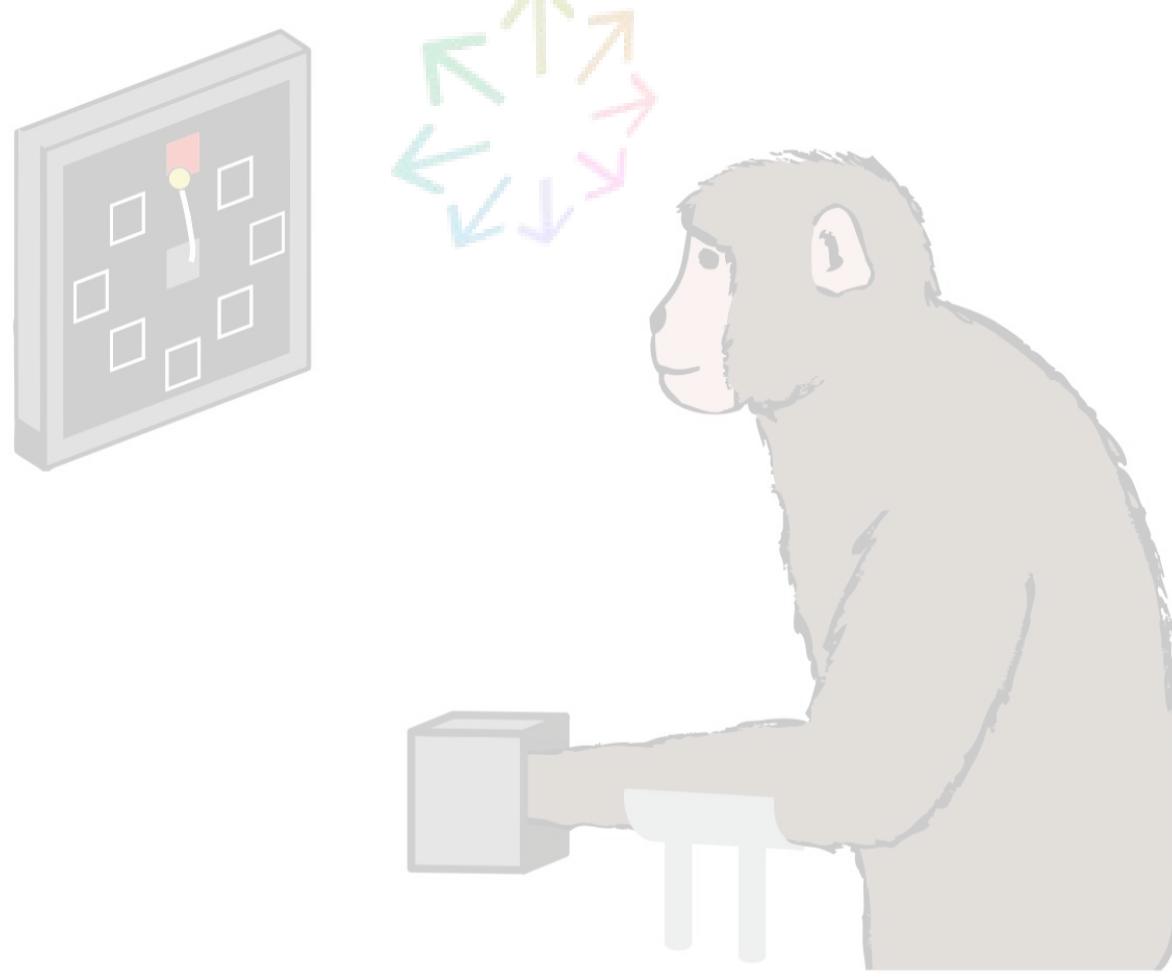


Linear  
(PCA-LDA)

Predictions

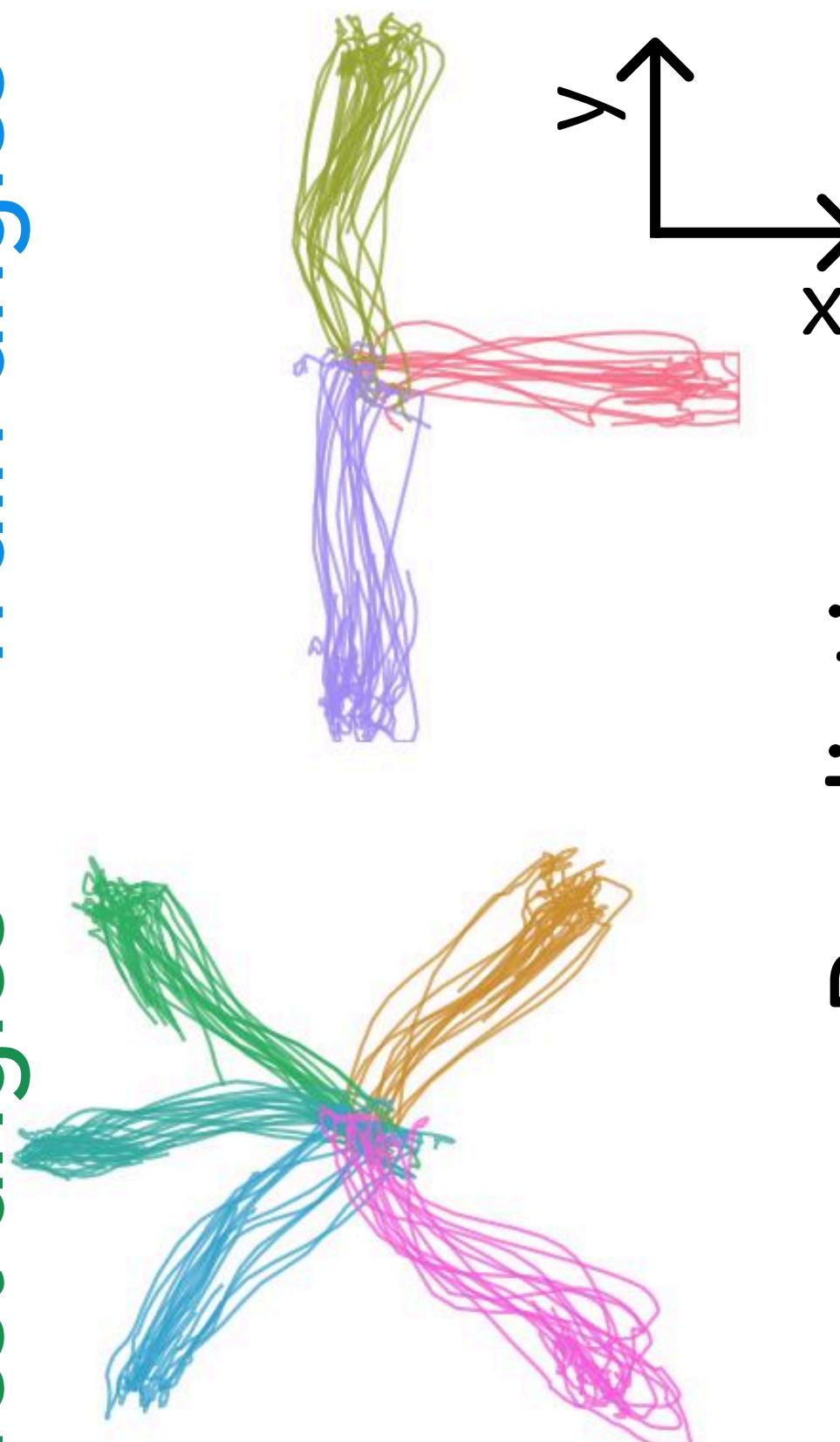
**Pretrain** → **Tune A** → **Evaluate B**

## Angular attractors



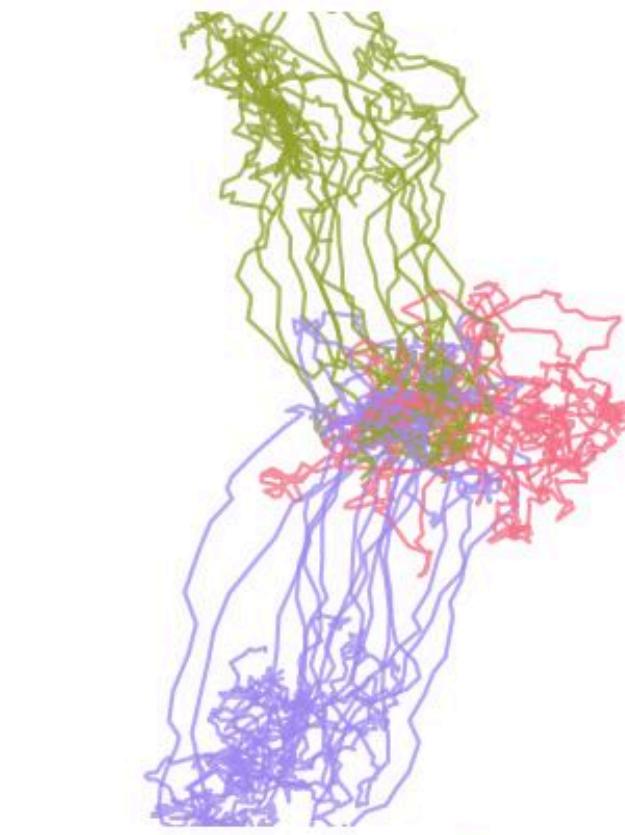
Train angles

Behavior

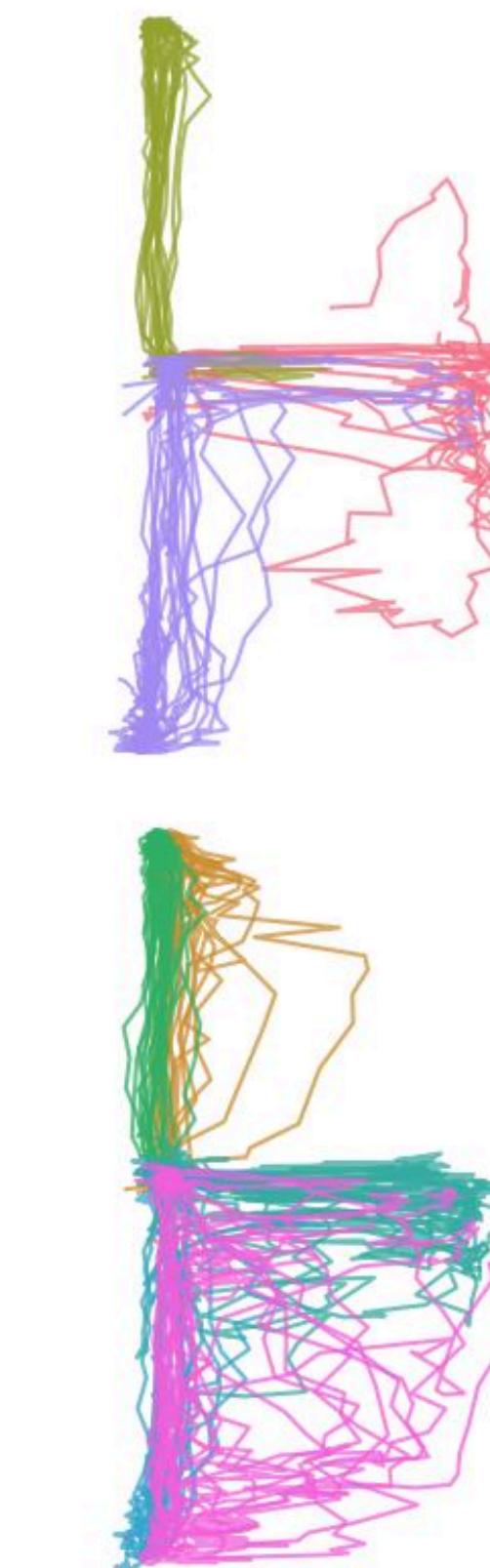


Predictions

Linear  
(PCA-LDA)



NDT3  
Scratch

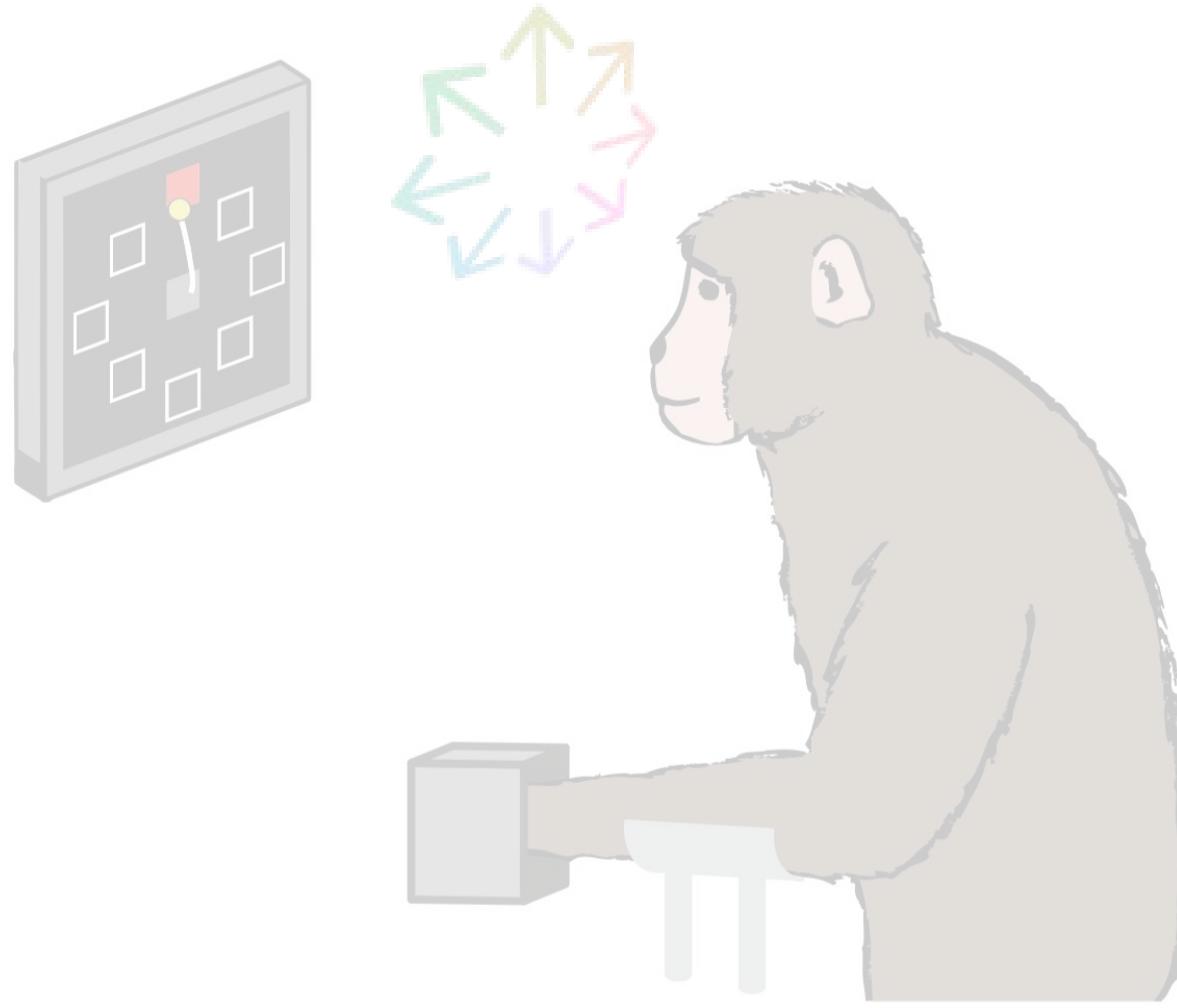


Generalization

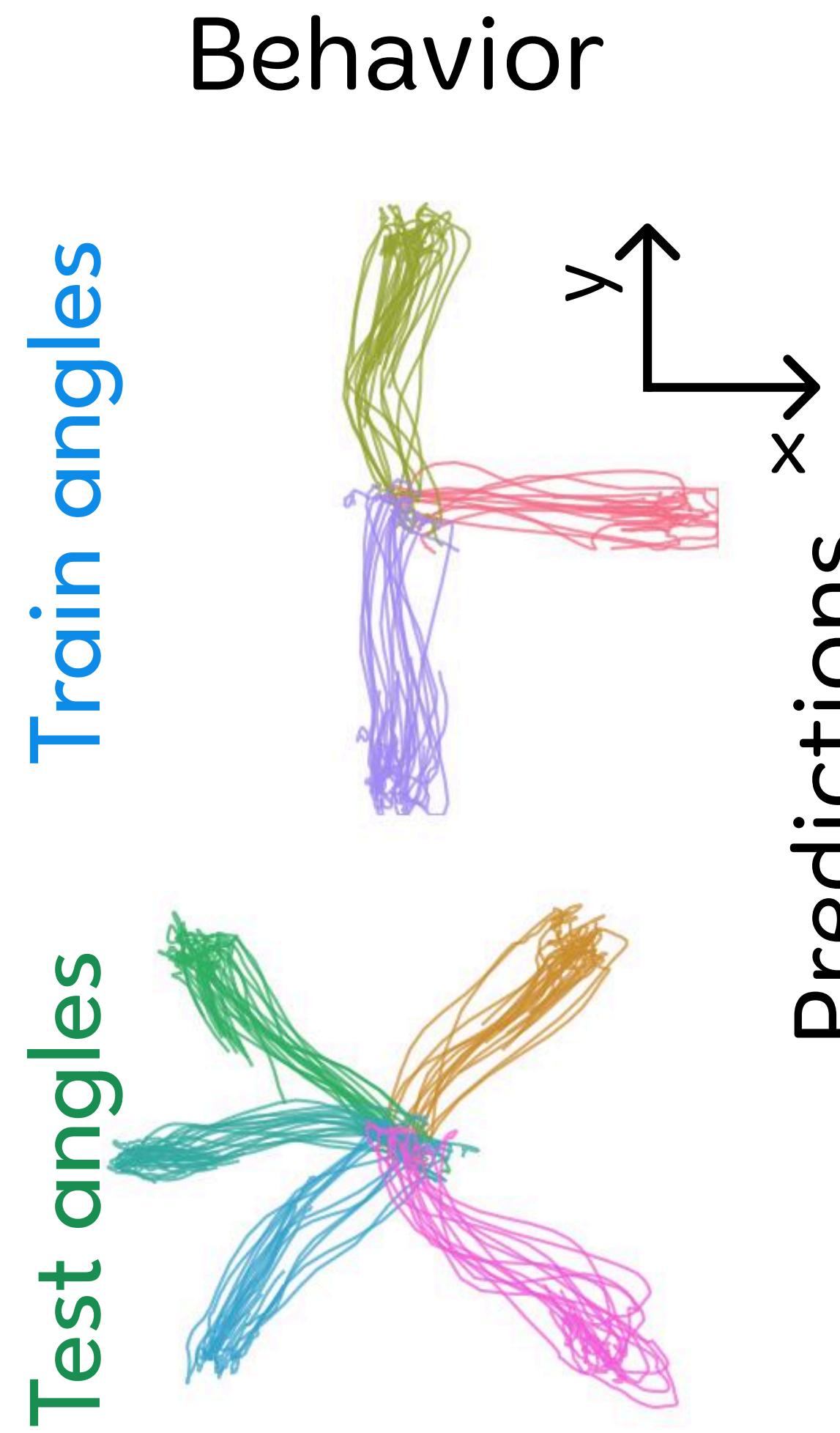


**Pretrain** → **Tune A** → **Evaluate B**

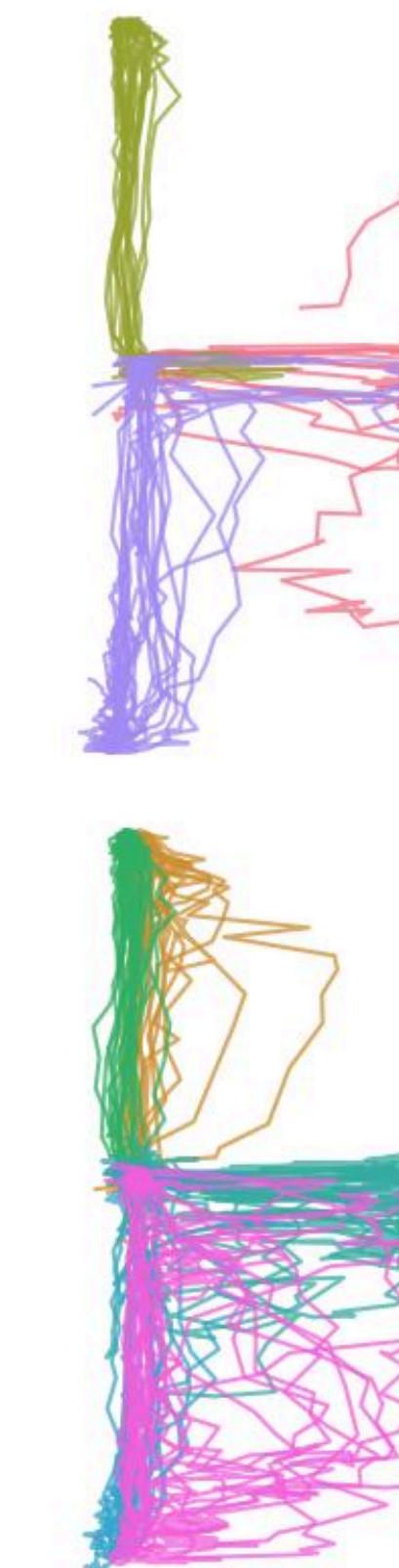
## Angular attractors



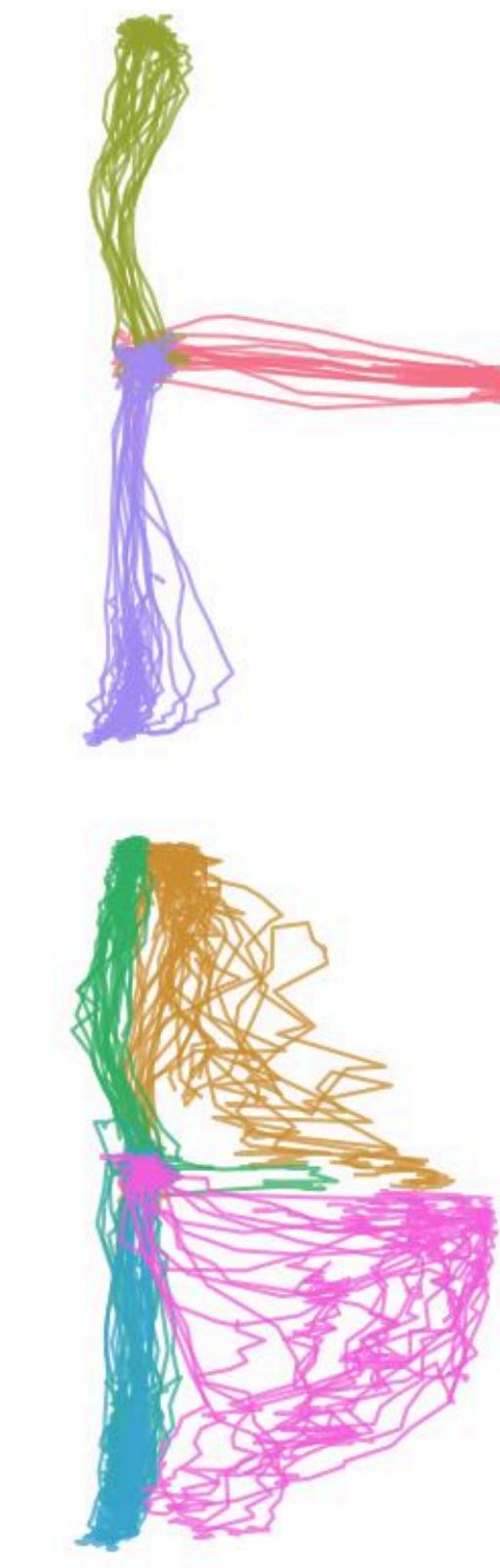
Train angles



NDT3  
Scratch



NDT3  
350M 2 khr



Pretrain → Tune A → Evaluate B

## Angular attractors

- Either:
  - Model has failed to learn prior
  - Fine-tuning alone **fails to surface** priors (Post-training?)



**Pretrain** → **Tune A** → **Evaluate B**

## **Cursor control**

**Tune A**

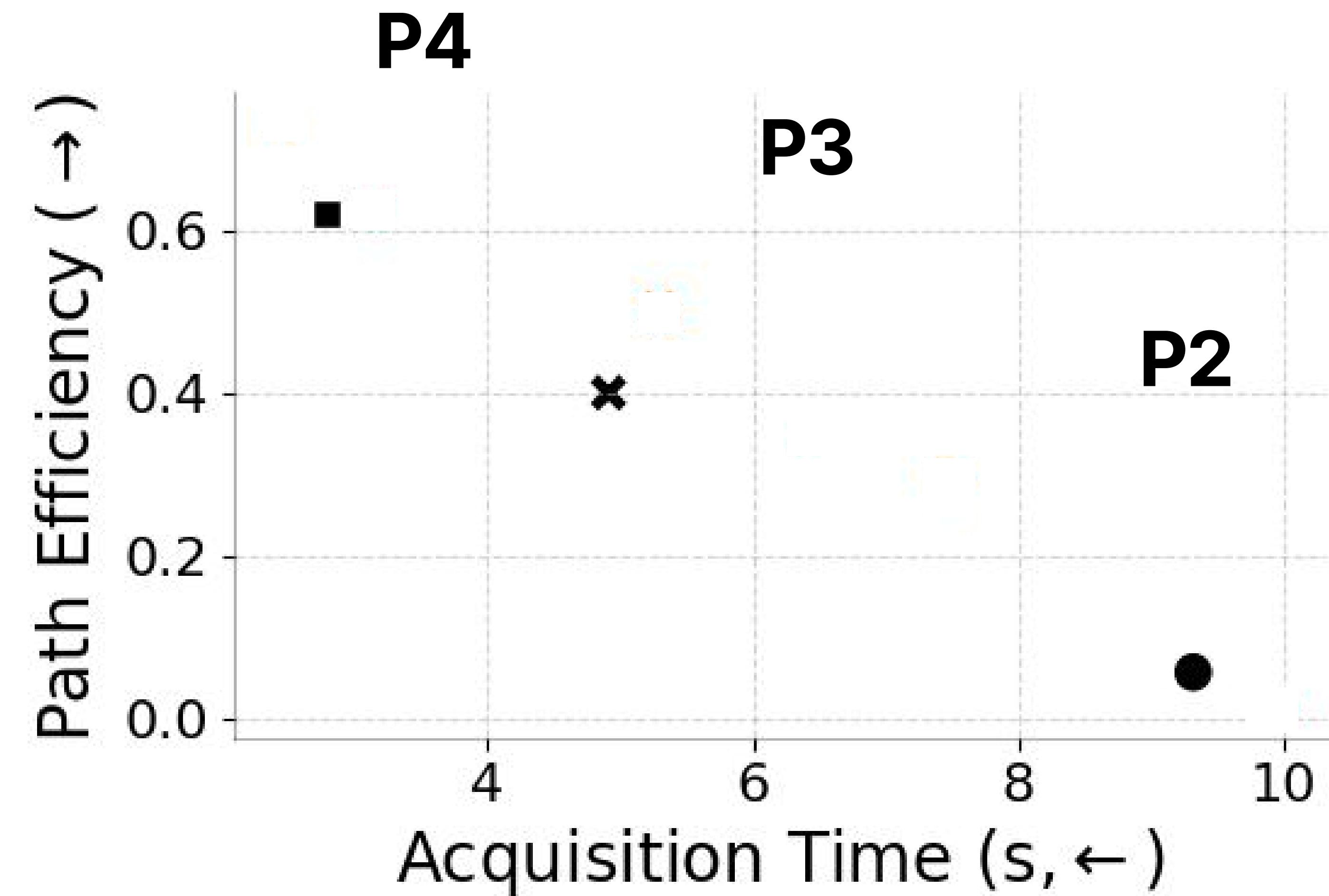
**Open loop calibration**  
**(~1 minute)**

**Evaluate B (Control)**

Pretrain → Tune A → Evaluate B

## Cursor control

Linear (iOLE)



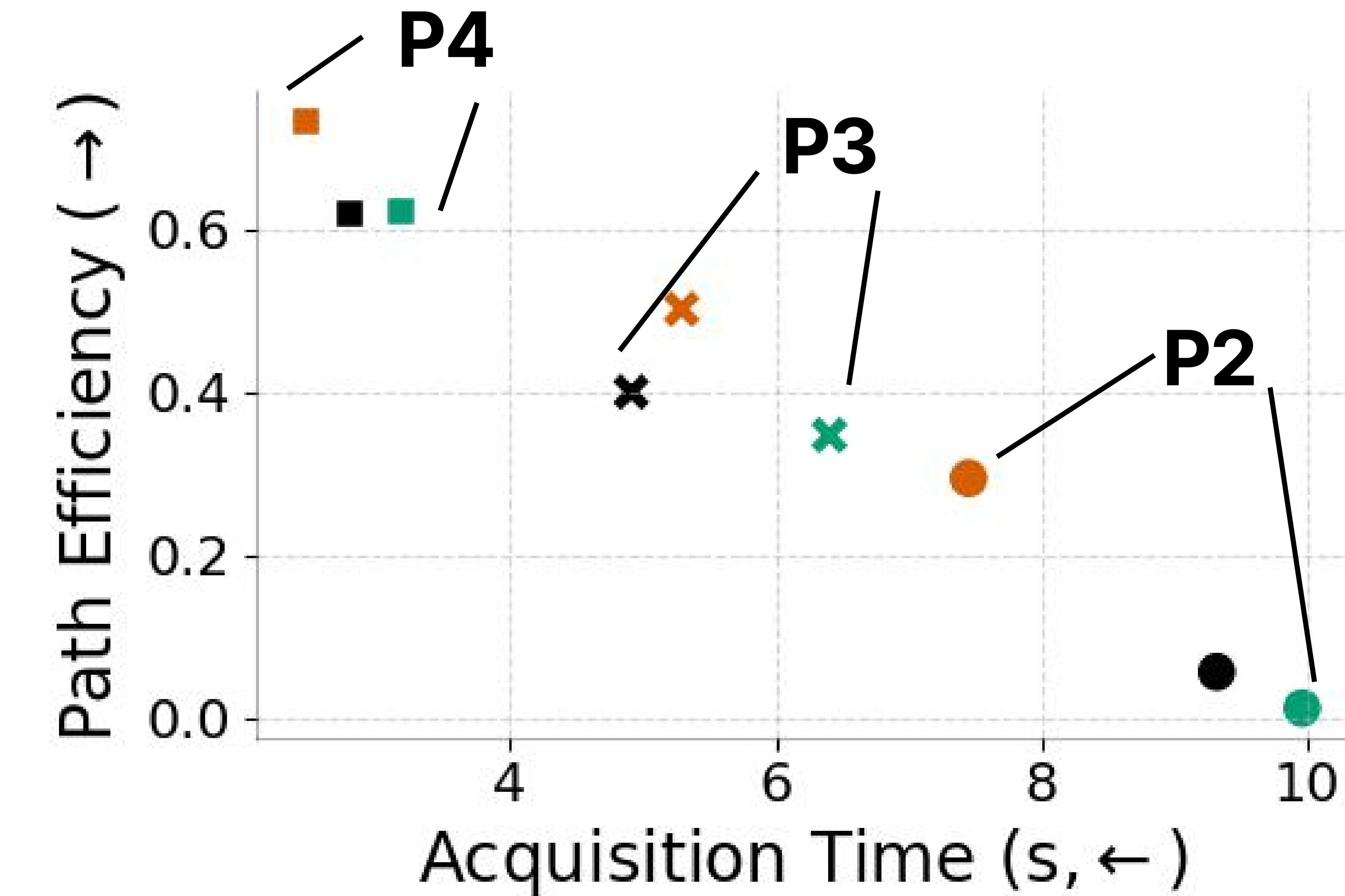
Pretrain → Tune A → Evaluate B

## Cursor control

Linear (iOLE)

NDT Base (200hr 45M)

NDT Big (2khr 350M)



**Evaluation will drive progress in neural foundation models.**

**Pragmatics**

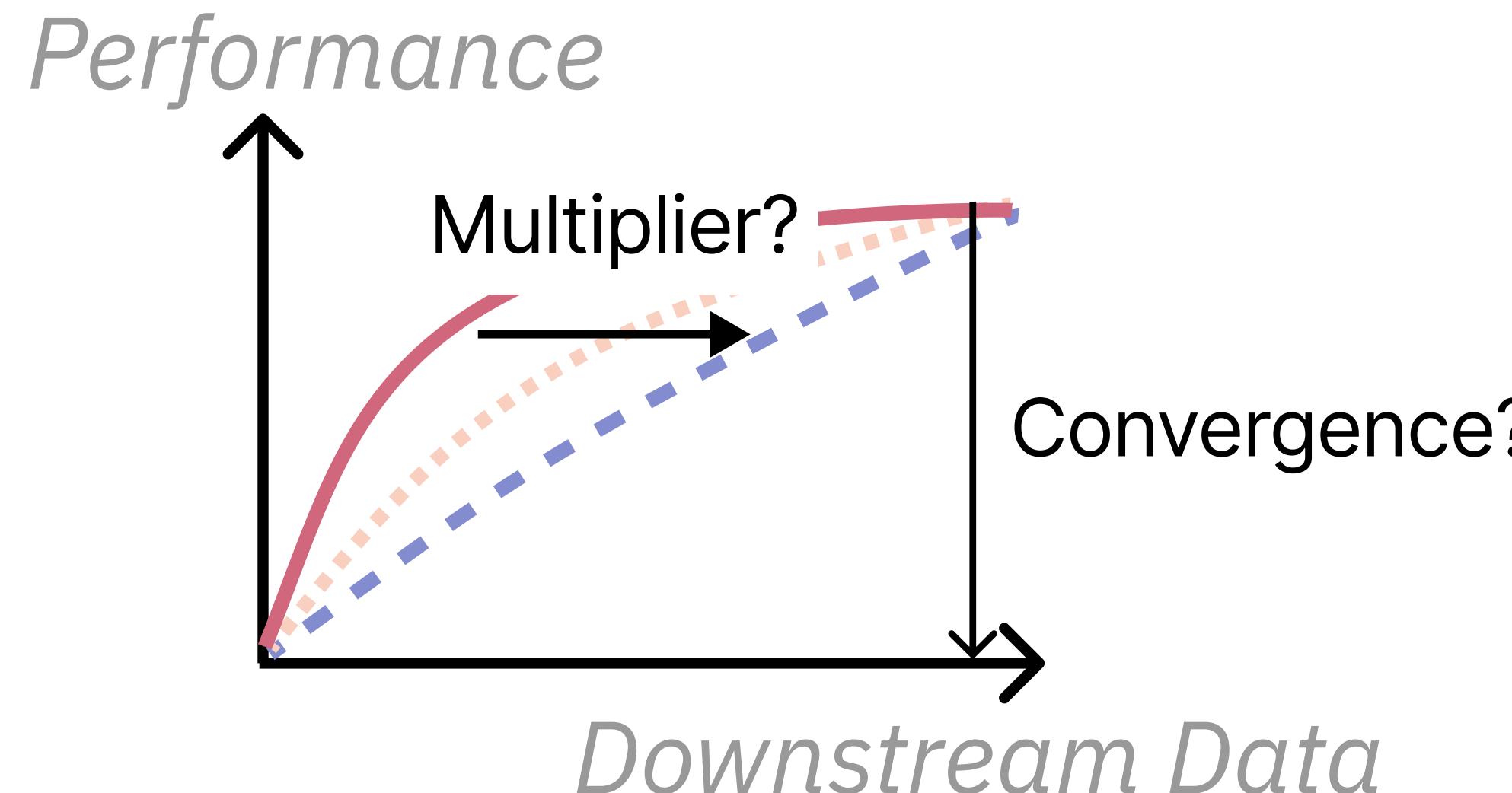
**Generalization**

# Evaluation will drive progress in neural foundation models.

## Pragmatics

- Pretraining gain should be measured over realistic ranges

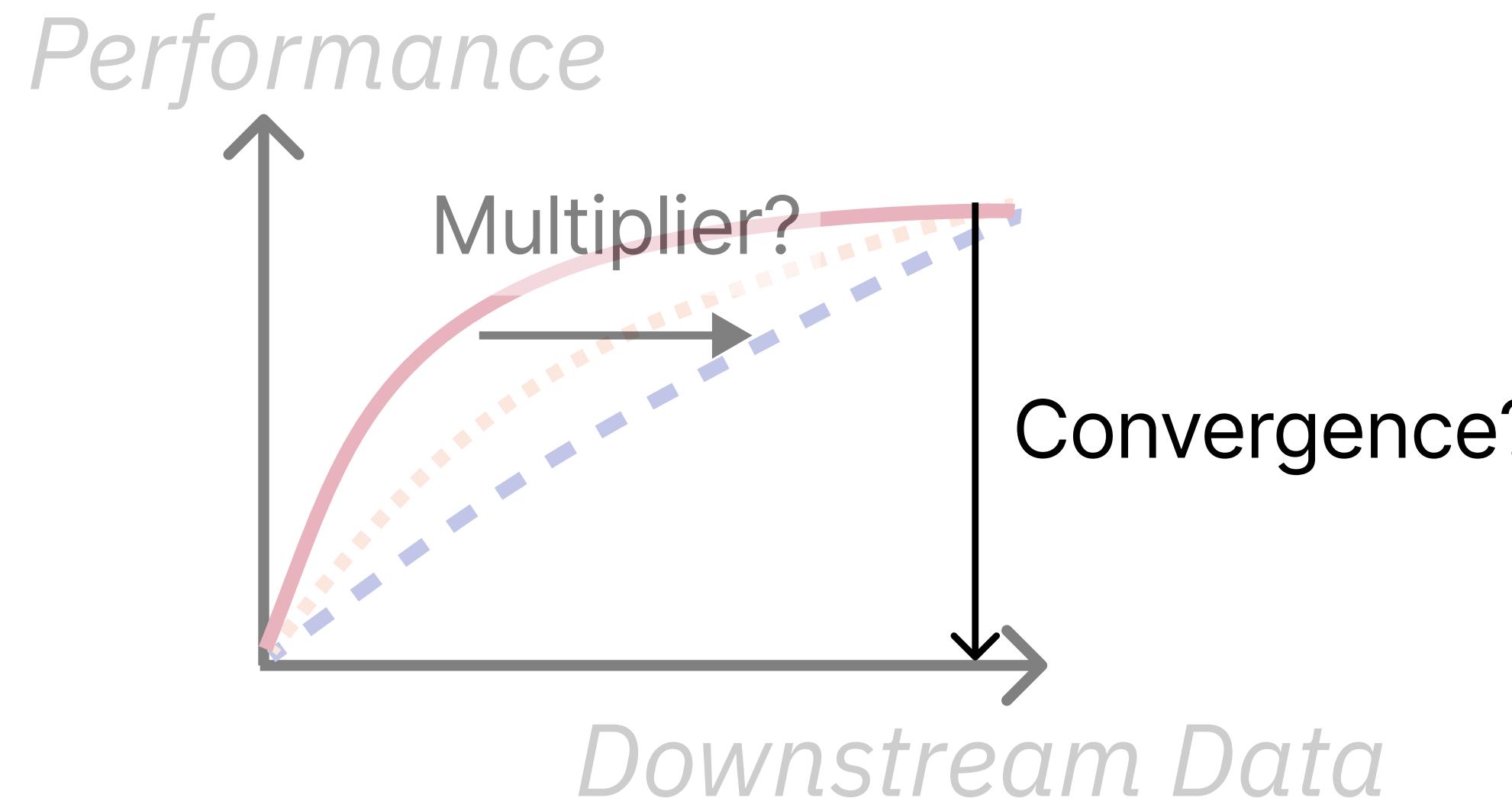
## Generalization



# Evaluation will drive progress in neural foundation models.

## Pragmatics

- Pretraining gain should be measured over realistic ranges



## Generalization

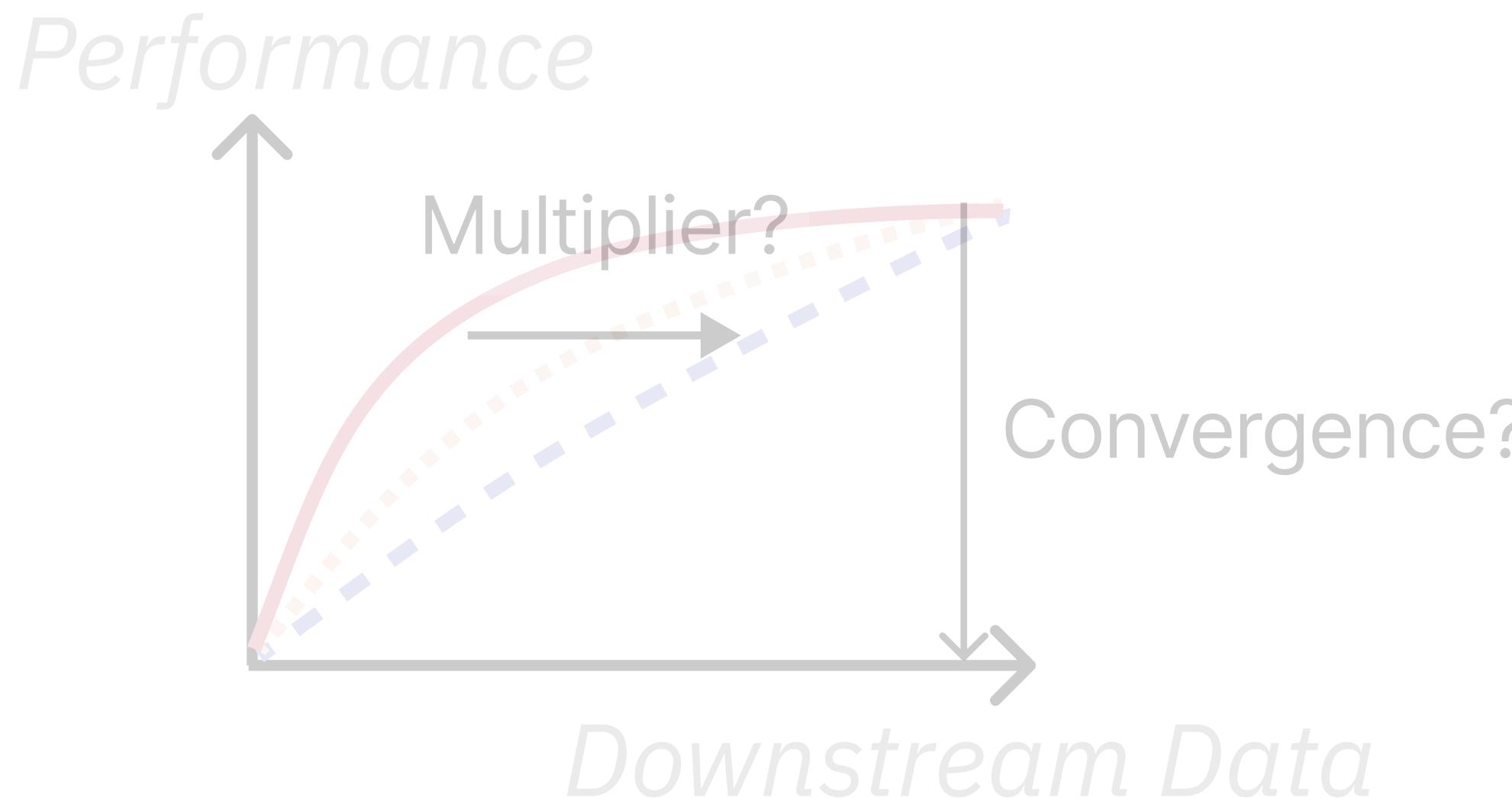
- Downstream often needs generalization
- Targeted probes can surface challenges that scaling will not resolve.

**Pretrain → Tune A → Evaluate B**

Pragmatics

Generalization

# Evaluations define progress in neural foundation models.



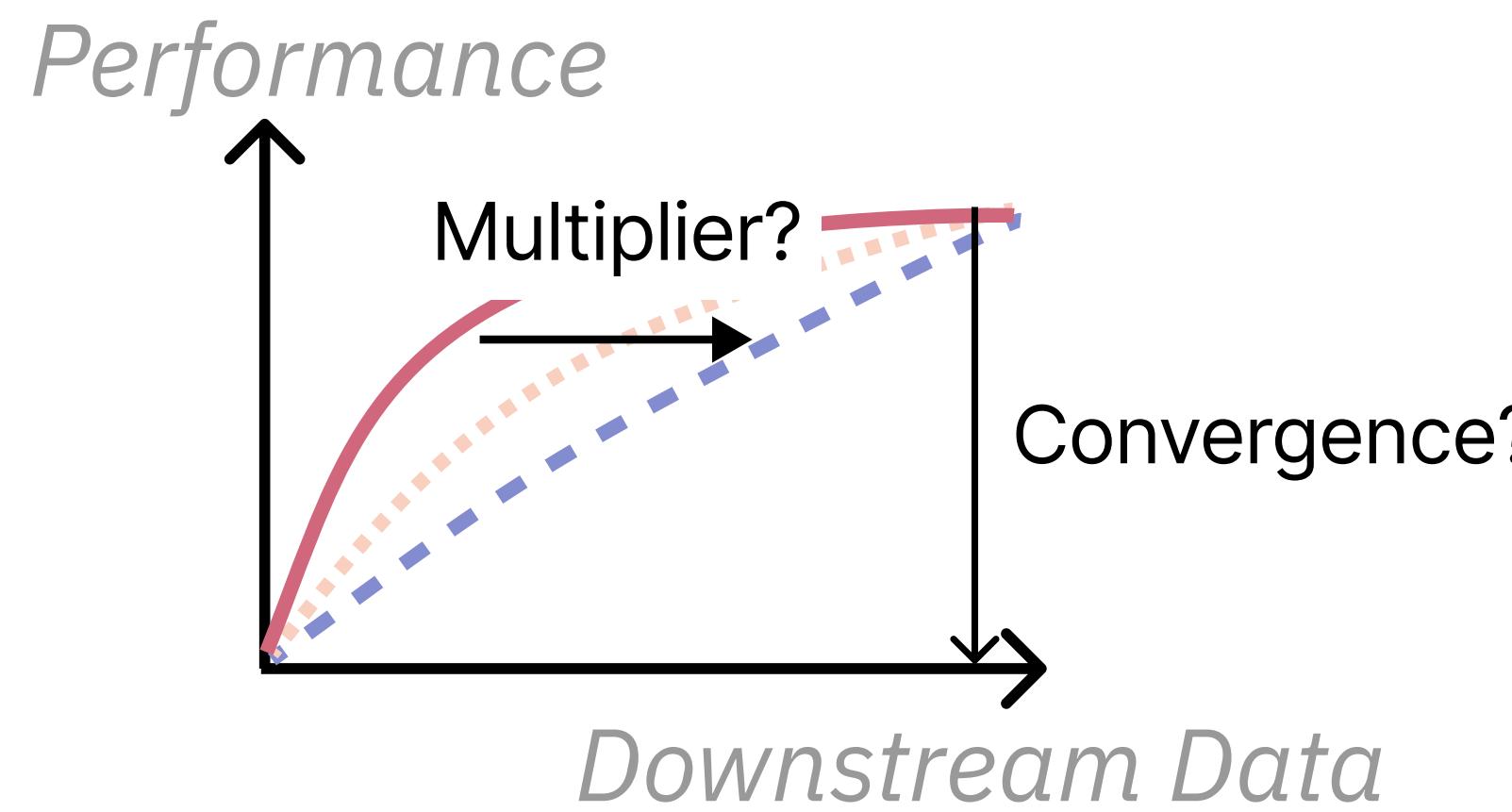
resolve.

Pretrain → Tune A → Evaluate B

# Evaluation will drive progress in neural foundation models.

## Pragmatics

- Pretraining gain should be measured over realistic ranges



## Generalization

- Downstream will need generalization
- Targeted probes can surface challenges that scaling will not resolve.

**Pretrain** → **Tune A** → **Evaluate B**

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Mellon  
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**RNEL**  
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