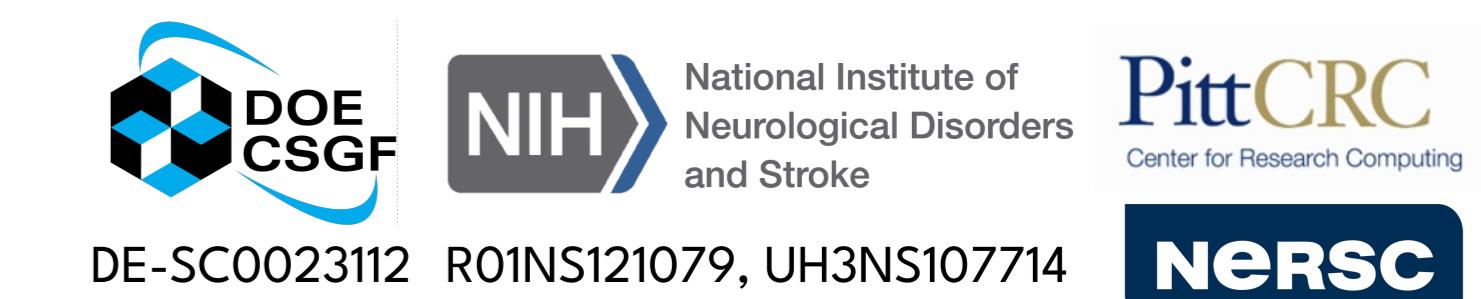


# Neural Data Transformer 3: A Generalist Motor Decoder



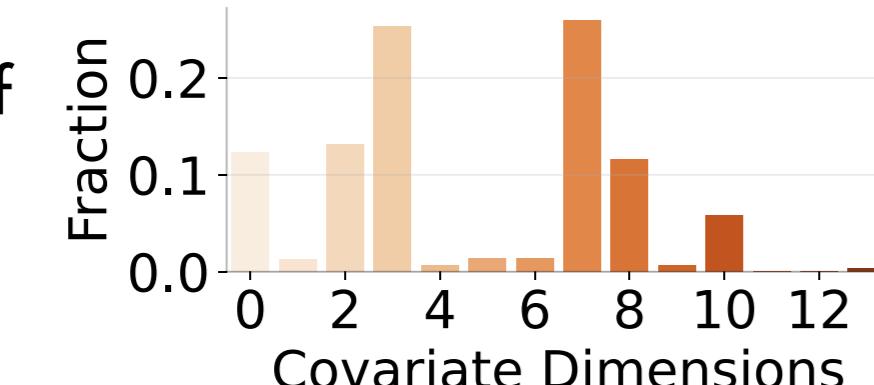
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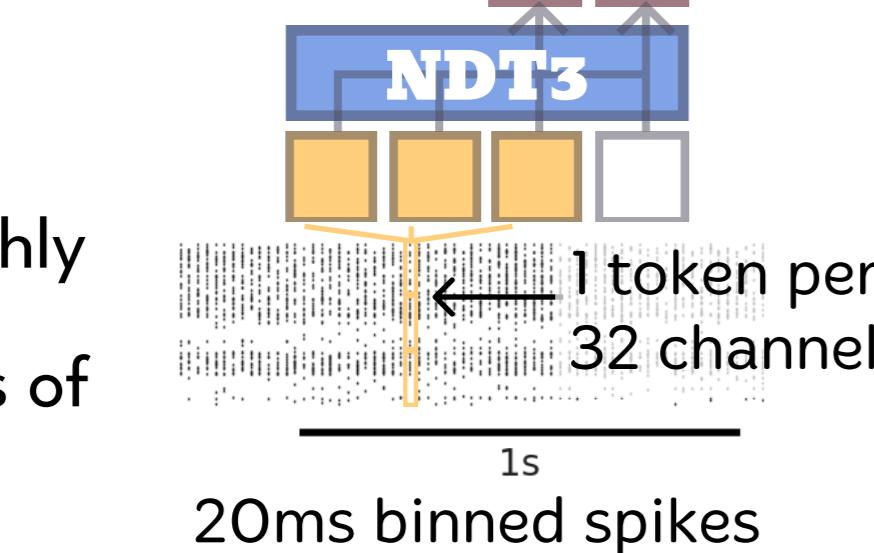
## Methods

### Training on heterogeneous data

Datasets vary in number of recorded neurons and covariates.



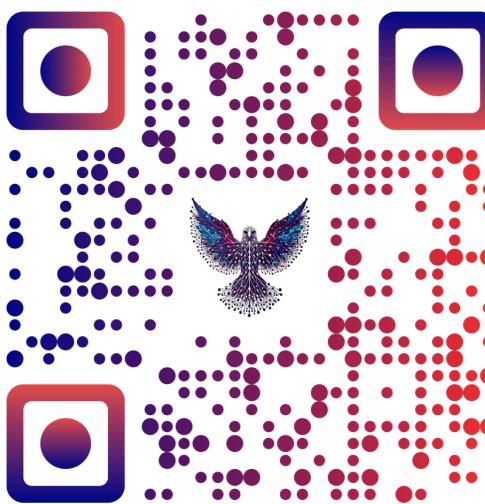
Varied dimensions in data can be converted to a varied number of tokens in a Transformer.



Transformer training is highly parallel. Training 350M parameters on 2000 hours of data uses 20K GPU-hours.

### Evaluating decoding on 8 datasets

FALCON benchmark (Karpowicz 24)

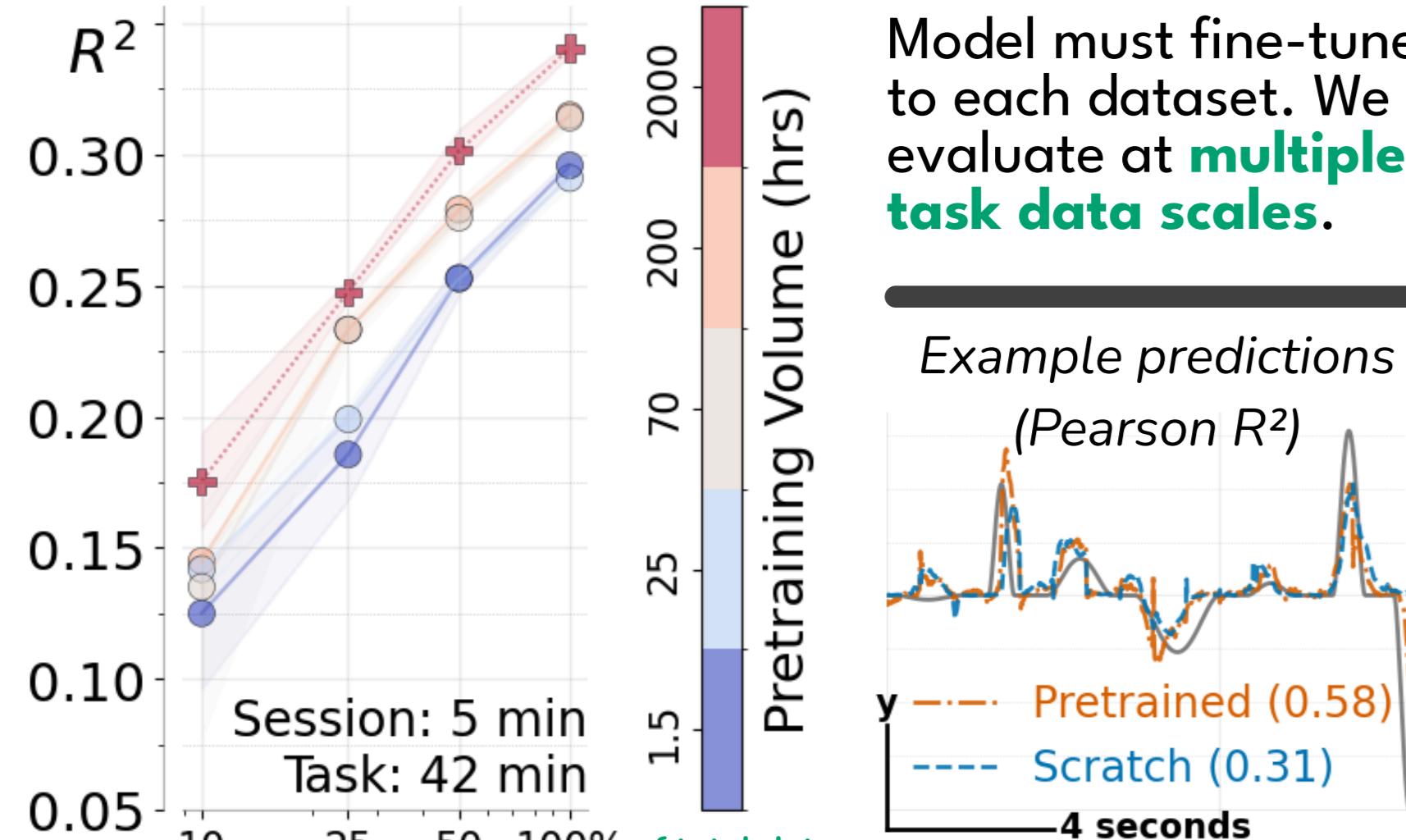


#### Monkey Movement

- 1D Critical Stability Task
- ← 2D Finger Pose
- 2D Self-paced reach
- ← 16D Reach / Grasp EMG

#### Human iBCI (Open-Loop)

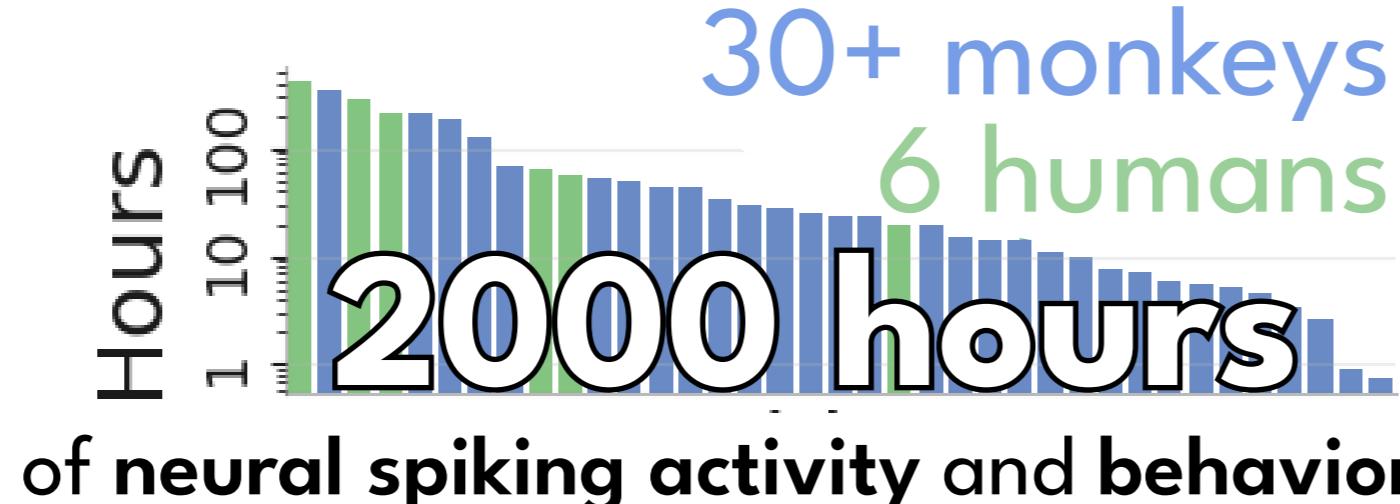
- 1D Grasp Force
- 2D Cursor + Click
- 4D Bimanual Cursor
- ← 7D Reach / Grasp Kinematics



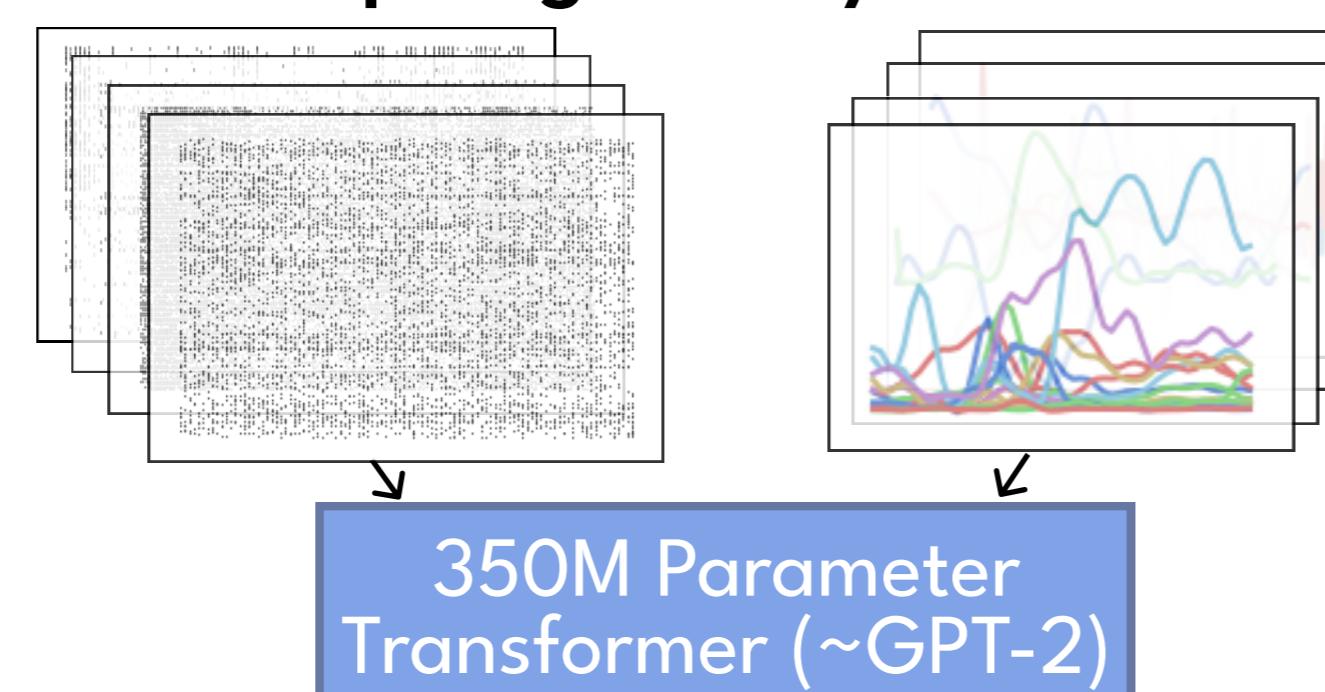
### 1 Can one model provide benefits across individuals and effectors?



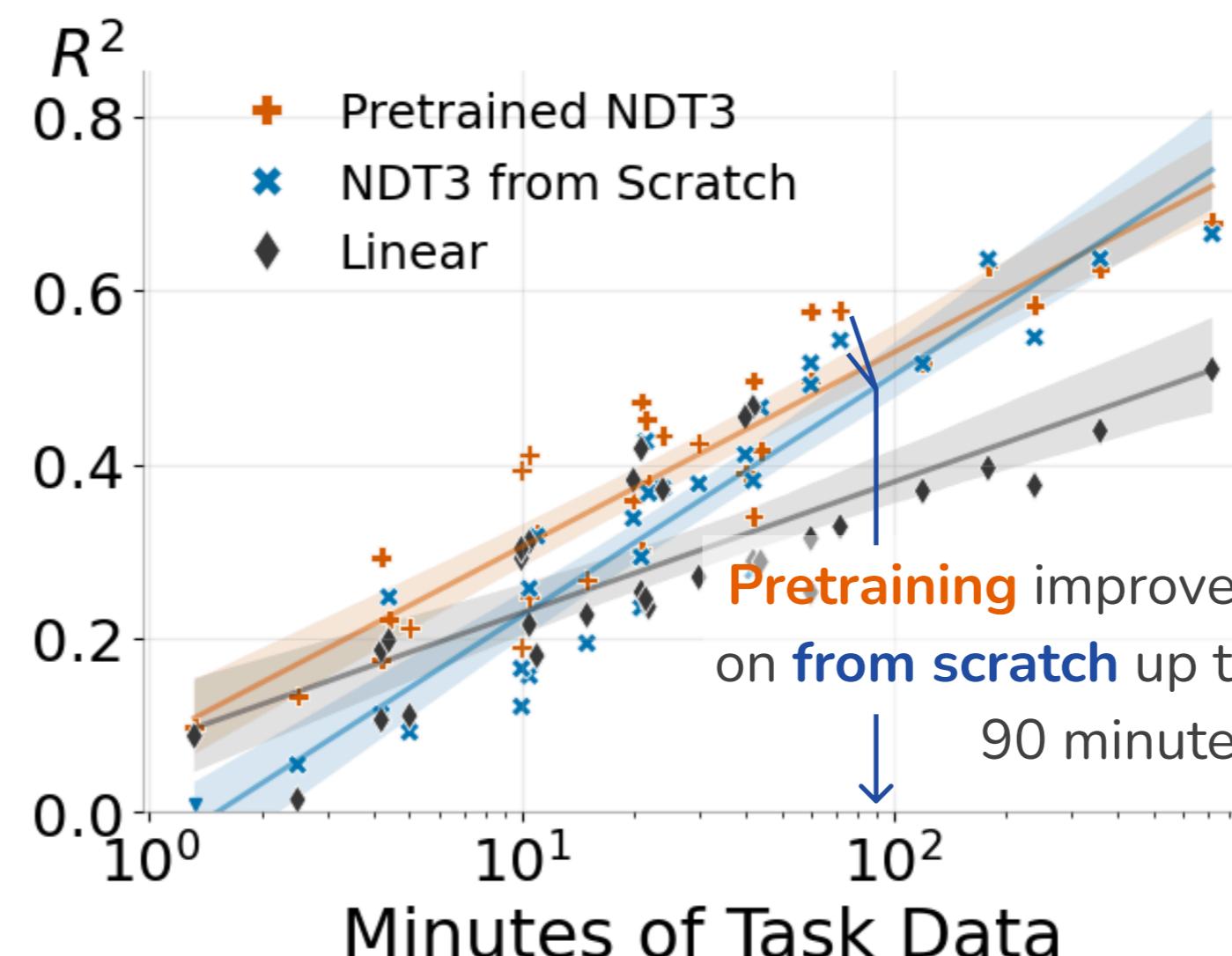
### 2 To do this, we pretrain a deep neural network on 30+ monkeys 6 humans 2000 hours



of neural spiking activity and behavior.



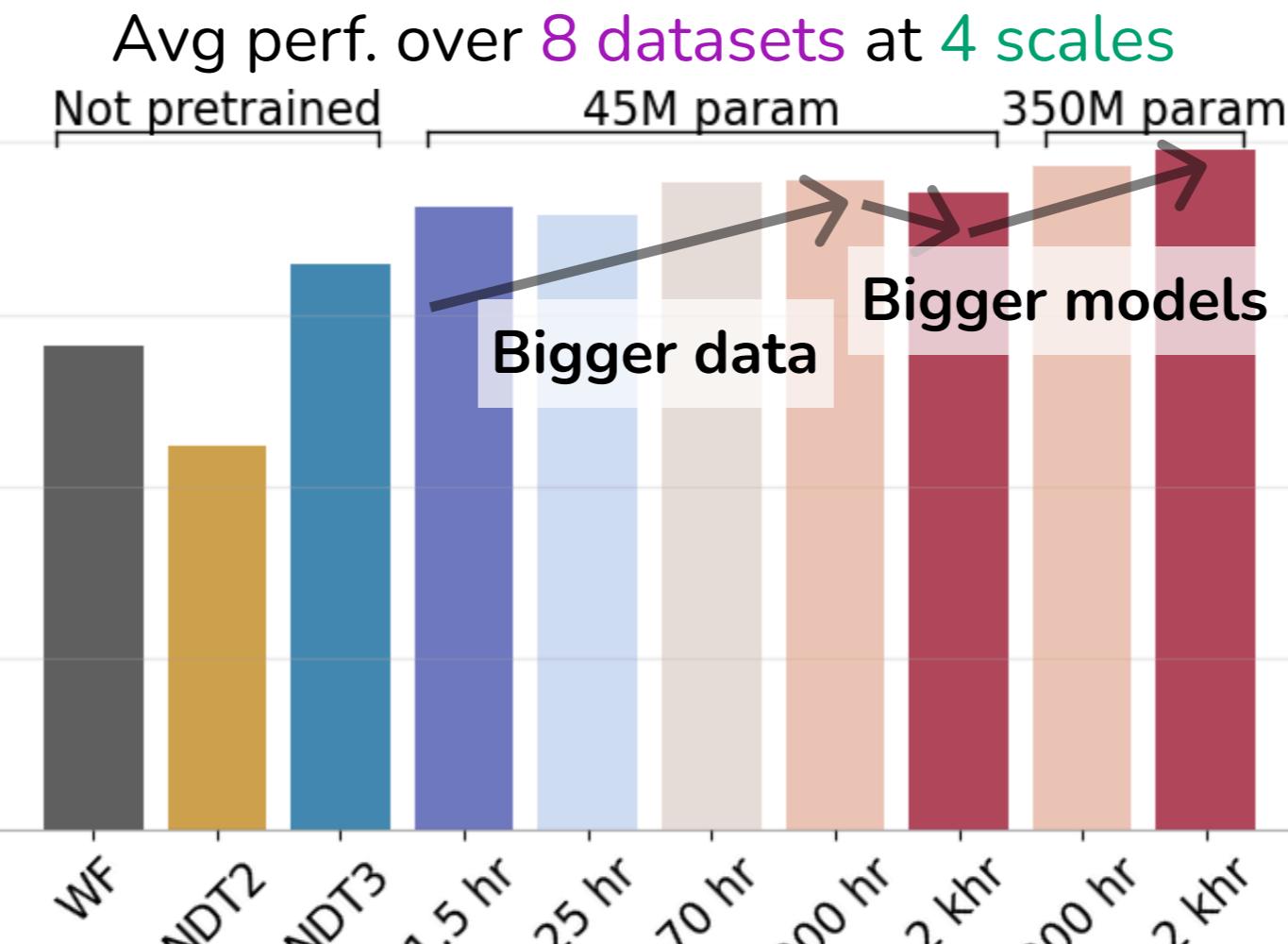
### 3 This improves data efficiency in decoding new behaviors in new individuals.



### 4 Take-Home Message

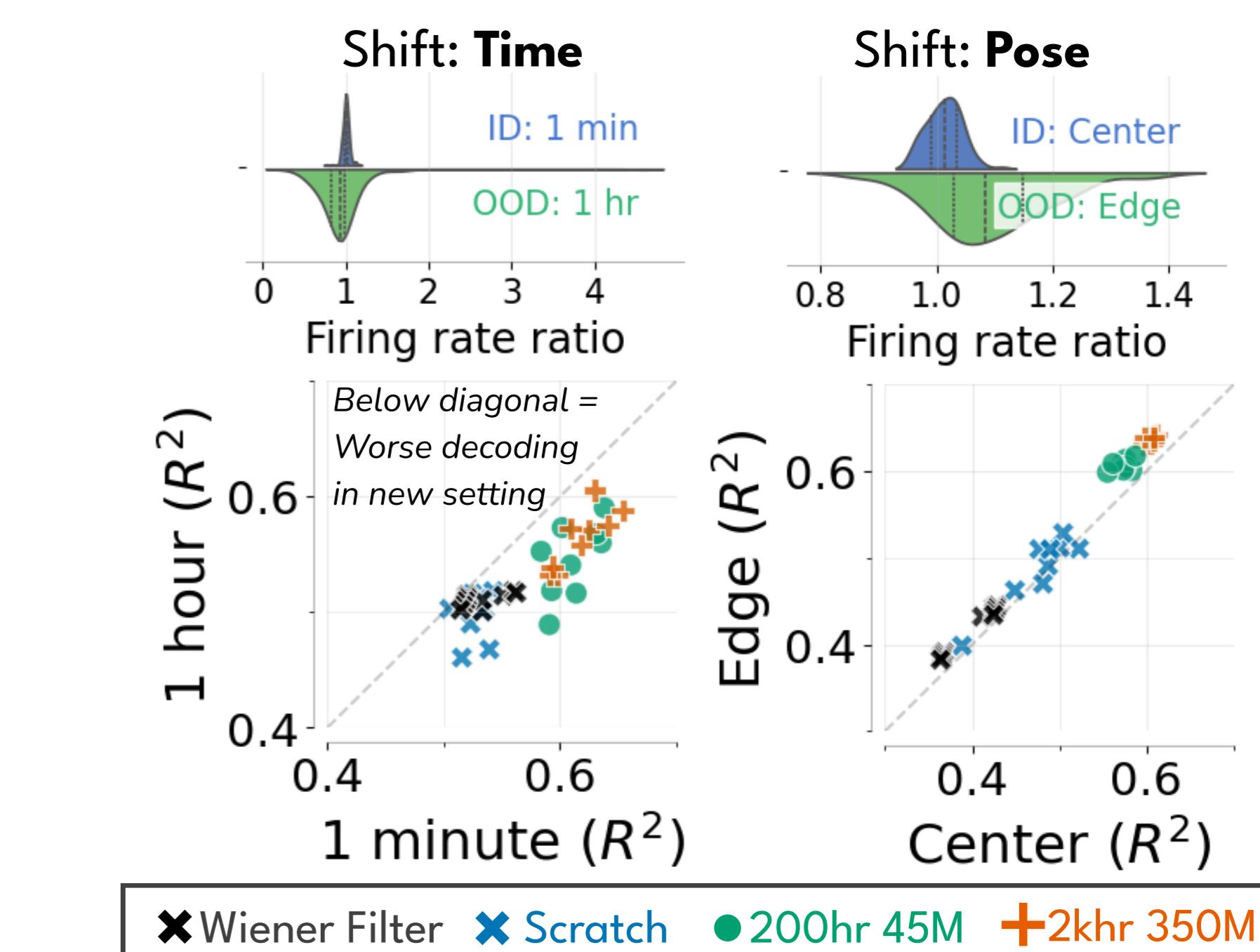
NDT3 benefits low-data decoding on many tasks.

Scaling more may further improve some tasks, but will require larger models.



### Model Benefits

Pretraining gains persist through changes in neural firing patterns in reaching tasks.



### Pretrained NDT3 resists overfit to trial structure

