Examples of Adaptive MCMC

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Introduction

- Adaptive MCMC (Markov Chain Monte Carlo) can be ideal to sample complicated high-dimensional distributions (e.g statistical inference).
- Those strategies can be very successful at finding good parameter values with little user intervention.
- However adaptive MCMC algorithms will not always are stationary of the target distribution.

Theorem

Theorem 1.1: Ergodicity Adaptive MCMC

Consider an adaptive MCMC algorithm on a state space χ , with adaptation index Y, so $\pi(.)$ is stationary for each kernel P_{γ} for $\gamma \in Y$. Under the following conditions, the adaptive algorithm is ergodic.

- (Simultaneous uniform ergodicity) For all $\epsilon > 0$, there exists $N = N(\epsilon) \in \mathbb{N}$ such that $||P_{\gamma}^{N}(x,.) \phi(.)|| \le \epsilon$ for all $x \in \chi$ and $\gamma \in Y$.
- (Diminishing adaptation) $\lim_{n\to\infty} D_n = 0$ in probability where

$$D_n = \sup_{x \in \chi} ||P_{\Gamma_{n+1}}(x,.) - P_{\Gamma_n}(x,.)||$$

is a measurable random variable (depending on the random values Γ_n and Γ_{n+1}

Conditions

Adaptive MCMC do not always preserve stationarity of the target distribution $\pi(.)$

- Diminishing Adaptation
 - Two successive transitions kernels are similar.

$$\lim_{n\to\infty} \sup_{x\in X} ||P_{\Gamma_{n+1}}(x,.) - P_{\Gamma_n}(x,.)|| = 0$$
 (1)

- Bounded Convergence
 - Ergodicity of transition kernels.

$$\{M_{\epsilon}(X_n, \Gamma_n)\}_{n=0}^{\infty}, \quad \epsilon > 0$$
 (2)

Assuming those conditions the Asymptotic convergence and WLLN (Weak law of large numbers) are satisfied.

Adaptive Metropolis (AM)

Haario, Saksman, and Tamminen (2001) proposed a version of the AM algorithm.

$$Q_n(x,.) = \begin{cases} N(x,(0.1)^2I_d/d), & \text{if } n \leq 2d \\ (1-\beta)N(x,(2.38)^2\Sigma_n/d) + \beta N(x,(0.1)^2I_d/d), & \text{otherwise} \end{cases}$$
 (3)

where

 $\pi(,)$ is a d-dimensional target distribution Σ_n is the current empirical estimate of the covariance of the target distribution

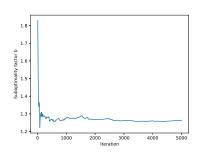
- ightharpoonup eta is a small positive constant to ensure *Boundary Convergence* (eta=0.05).
- ▶ Empirical estimates change at the nth iteration by only O(1/n), Diminishing Adaptation is satisfied.

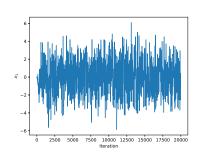
Adaptive Metropolis (AM)- Experimental validation

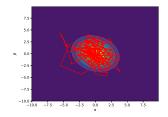
- ► The previously proposal was tested with $\pi(.) = N(0, MM^t)$, where $M \in \Re^{d \times d}$, $\{M_{ij}\}_{i,j=1}^d$ i.i.d $\sim N(0,1)$.
- ➤ This target model was configured with 2 and 100 dimensions, each one with 100 and 1'000'000 iterations correspondingly.
- The performance of the algorithm can be measured with a suboptimality factor Eqn. (4) where λ_i are the eigenvalues of $\Sigma_p^{\frac{1}{2}}\Sigma^{-\frac{1}{2}}$.

$$b = d \frac{\sum_{i=1}^{d} \lambda_i^{-2}}{(\sum_{i=1}^{d} \lambda_i^{-1})_2}$$
 (4)

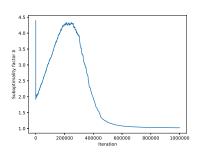
Adaptive Metropolis (AM)- Experimental validation

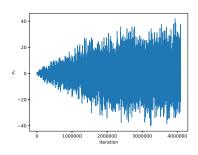






Adaptive Metropolis (AM)- Experimental validation

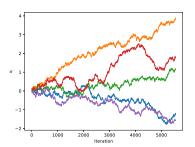




Adaptive Metropolis (AM)- An Irregularly Shaped Example

- AM can work well on target densities which density elliptical contours.
- ► Target distribution: $f_B = f_d \circ \Phi_B$, where $f_d = N(\mathbf{0}, diag(100, 1, ..., 1))$, $\Phi_B(x_1, ..., x_d) = (x_1, x_2 + Bx_1^2 100B, x_3, ..., x_d)^2$.
- ► Taking into account 50 variables and 100'000 iterations.

$$f_B(x_1,...,x_d) \propto exp[-x_1^2/200 - \frac{1}{2}(x_2 + Bx_1^2 - 100B)^2 - \frac{1}{2}(x_3^2 + x_4^2 + ... + x_d^2)]$$
 (5)



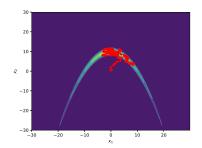
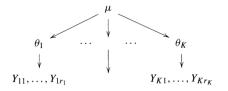


Figure 1: First five variables with 100'000 iterations and 50 variables (left side). Two dimensional contour with 1'000 iterations (right side).

Consider the following model:



where

$$\theta_{i} \sim Cauchy(\mu, A) \quad [1 \leq i \leq K]$$

$$Y_{ij} \sim N(\theta_{i}, V) \quad [1 \leq j \leq r_{i}]$$

$$priors:$$

$$\mu \sim N(0, 1), \quad A, V \sim IG(1, 1)$$
(6)

IG is the inverse gamma distribution with density proportional to $e^{-b}x^{-(a+1)}$, and Cauchy distribution is proportional to $[1 + ((x-m)/s)^2]^{-1}$.

- ▶ This model gives rise to a posterior distribution $\pi(.)$ on the (K+3)-dimensional vector $(A, V, \mu, \theta_1, ..., \theta_k)$ conditional on the observed data $\{Y_{ij}\}$.
- ▶ We take r_i randomly from $\{5, 2, 3, 1\}$ and K = 10.
- ► The Cauchy distribution destroys conjugacy, thus classical Gibbs is infeasible.
- ▶ Test data $Y_{ij} \sim N(i-1, 10^2)$, $1 \le i \le K$ and $1 \le j \le r_i$.

The poster distribution can be efficient-computed taking into account the logarithm.

$$f(A, V, \mu, \theta_1, ..., \theta_K) \propto \left[\prod_{i=1}^K \prod_{j=1}^{r_i} N(Y_{ij}) \theta_i V \right) \times Cauchy(\mu, A; \theta_1, ...m \theta_K) \right] \times N(\mu_0, \sigma_0) \times IG(A; a_1, b_1) \times IG(V; a_2, b_2)$$

$$(7)$$

$$log(f(A, V, \mu, \theta_1, ..., \theta_K)) \propto$$

$$\left[\sum_{i=1}^{K} \left(-\log(1 + ((\theta_i - \mu)/A)^2) + \sum_{j=1}^{r_i} [-\log(V^{0.5}) - \frac{1}{2V} (Y_{ij} - \theta_i)^2] \right) \right] - \log(\sigma_0) - \frac{1}{2\sigma_0^2} (\mu - \mu_0)^2 - \frac{b_1}{A} - (a_1 + 1)\log(A) - \frac{b_2}{V} - (a_2 + 1)\log(V) \right]$$
(8)

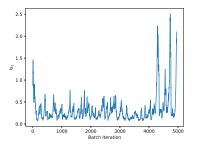
- 1: For each variable i $[i \le i \le K+3]$, create a variable ls_i giving the logarithm of the standard deviation.
- 2: Begin with unit variance $ls_i = 0 \ \forall i \in K$.
- 3: After n^{th} batch of 50 iterations update each ls_i

$$ls_i = \begin{cases} +\delta(n), & \text{if } Acceptance \quad rate \quad batch > 0.44 \\ -\delta(n), & \text{otherwise} \end{cases} \tag{9}$$

- 4: Choose a $\delta(n) \to 0$ to satisfy Diminishing Adaptation condition (e.g. $\delta(n) = min(0.001, n^{-0.5})$).
- 5: Restrict each $ls_i \in [-M, M]$ to satisfy Boundary Convergence condition.

Experimental Validation - Adaptive Metropolis-Within-Gibbs

- ▶ We take r_i randomly from $\{5, 2, 3, 1\}$ and K = 10.
- ▶ Batch size = 50, Batch iterations = 5000
- ► Test data $Y_{ij} \sim N(i-1, 10^2)$, $1 \le i \le K$ and $1 \le j \le r_i$.



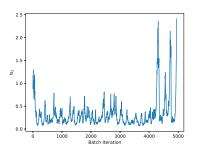
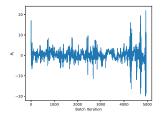


Figure 2: Log variance of the first two variables ls_1, ls_2 .

Experimental Validation - Adaptive Metropolis-Within-Gibbs



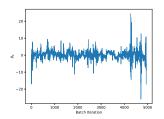


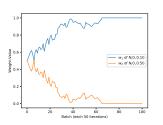
Figure 3: Values of the first two variables θ_1, θ_2 .

Variable	Adaptive	Fixed
θ_1	4.27	9.98
θ_2	4.08	9.73
θ_3	4.69	10.74
θ_4	4.27	10.75
θ_5	4.31	9.63

Table 1: Avr sq. dist.

Proposal - Adaptive Weights Hybrid with Kernels

- ▶ Target distribution $\pi(.) = N(0, MM^t)$, where $M \in \Re^{d \times d}$, $\{M_{ij}\}_{i=1}^d$ i.i.d $\sim N(0,1)$.
- Proposal $\epsilon_t = w_1 N_2(0, (0.1 * I)) + w_2 N_2(0, (0.5 * I)).$
- ▶ To have more difficult $x_0 \sim U(0.0, 500.0)$.
- Each weight is implemented taking into account the acceptance ratio.
- ► The batch-size was set to 1000 and the number of iterations to 10'000.



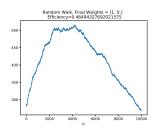


Figure 4: Weight values and states of the first variable.

Conclusions

- Adaptive MCMC provide promising results for finding good values for proposal variance, especially in cases of high dimension when it is unreasonable to do by hand.
- Adaptive strategy is too greedy in that it tries to adapt too closely to initial information from the output, such algorithms can take considerable time to recover from misleading initial information.
- More work should be done to design robust adaptive algorithms.
- Avoidance of frankenstein in the designing of adaptive algorithms is fundamental.

Acknowledgements

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