

Coq Proof Assistant: Propositions and Proofs

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Minimal Propositional Logic

Basics

Definition

Example

Definition

Demo

Structure

Tactics explenation



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Overview

Minimal Propositional Logic

Basics

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Tactics explenation

Composing tactics



Minimal Propositional Logic

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Definition Demo

Structure



$$(P \rightarrow Q)$$

- Classical logic
- Assign to every variable a denotation true or false
- Formula is valid iff true in all cases
- Question "is the proposition P true?"



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$$(P \rightarrow Q)$$

- Intuitionistic logic
- Obtain a proof of Q from a proof of P
- Arbitrary proof of P constructs a proof of Q
- Question "what are the proof of P (if any)?"





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- Local declaration
- *h* is the name of the hypothesis
- P is its statement
- Synonymous to Variable h:P
- Use Hypotheses or
 - to declare several at a time



Example 0000 0

Hypothesis

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 or
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Section

The section contains all Hypoteses / Variables from the Context

Start section sec1 with Section sec1

End section sec1 with End sec1





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End section sec1 with End sec1



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The section contains all Hypoteses / Variables from the Context Start section sec1 with Section sec1

End section sec1 with End sec1



Axiom x:P

- Global declaration
- Synonymous to Parameter x:P

Environment contains axioms

$$E, \Gamma \vdash \pi : P$$



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- Global declaration
- Synonymous to Parameter x:P

Environment contains axioms

$$E, \Gamma \vdash \pi : P$$



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Goals: what needs to be proven

Goal: $E, \Gamma \vdash P$

Construct a proof of P. Should be a well-formed term t in the environment E and context Γ Term t is called a solution



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Goals: what needs to be proven

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Construct a proof of P. Should be a well-formed term t in the environment E and context Γ Term t is called a *solution*

Tactics: commands to decompose this goal into simpler goals

g ist input goal and $g_1, g_2, ..., g_k$ are output goals Possible to construct a solution of g from the solutions of goals g





Goals and Tactics

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Goals: what needs to be proven

Goal: $E, \Gamma \vdash P$

Construct a proof of P. Should be a well-formed term t in the environment E and context Γ Term t is called a *solution*

Tactics: commands to decompose this goal into simpler goals g ist input goal and $g_1, g_2, ..., g_k$ are output goals Possible to construct a solution of g from the solutions of goals g_i





Goal:
$$(P \rightarrow Q) \rightarrow (Q \rightarrow R) \rightarrow (P \rightarrow R)$$

intros H H' p

- Transform the task of construction a proof into proving R with those hypotheses added
- $H:P\rightarrow Q$
- $H': Q \rightarrow R$ and
- p : P
- New subgoal: R



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Subgoal: R

Hypothesis $H':Q\to R$ and $H:P\to Q$

apply H

- Use the hypothesis H' to advance our proof
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Subgoal: P

Hypothesis p: P

assumption

- Statement to proof is exactly statement of hypothesis p
- Succeeds without generating any new goal

No more subgoals





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Qed

- Saves the theorem's name, statement and proof term
- Displays the sequence of tactics.

```
intros H H' p.
apply H'.
apply H.
assumption.
```

Print theorem-name

```
theorem-name = fun (H:P \rightarrow Q)(H':Q \rightarrow R)(p:P) \Rightarrow H' (H p) : (P \rightarrow Q) \rightarrow (Q \rightarrow R) \rightarrow P \rightarrow R
```





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Transitivity

$$(P \rightarrow Q) \rightarrow (Q \rightarrow R) \rightarrow (P \rightarrow R)$$



Not all the details for the proof is needed

A few automatic tactics are able to solve this goal

```
Theorem transitivity : (P->Q) \rightarrow (Q->R) \rightarrow P \rightarrow R.
```

auto

Qed.



Not all the details for the proof is needed

A few automatic tactics are able to solve this goal

```
Theorem transitivity : (P->Q) \rightarrow (Q->R) \rightarrow P \rightarrow R. Proof.
```

auto

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Not all the details for the proof is needed

A few automatic tactics are able to solve this goal

Theorem transitivity : $(P->Q) \rightarrow (Q->R) \rightarrow P \rightarrow R$. Proof.

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Theorem transitivity : $(P->Q) \rightarrow (Q->R) \rightarrow P \rightarrow R$. Proof.

auto.

Qed.





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```
Theorem transitivity : (P->Q) -> (Q->R) -> P -> R. Proof.
```

auto.

Qed.



The exact tactic takes any term (with right type) as argument

The whole proof could be given as an argument

```
Theorem delta : (P->P->Q) \rightarrow P \rightarrow Q.
Proof.
exact (fun (H:P->P->Q)(p:P) \Rightarrow H p p)
Qed.
```

Or even shorter:

```
Theorem delta : (P\rightarrow P\rightarrow Q) \rightarrow P \rightarrow Q.
Proof (fun (H:P\rightarrow P\rightarrow Q)(p:P) \Rightarrow H p p)
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The exact tactic takes any term (with right type) as argument The whole proof could be given as an argument

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exact

The exact tactic takes any term (with right type) as argument The whole proof could be given as an argument

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Theorem delta : (P->P->Q) \rightarrow P \rightarrow Q.
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```



apply tactic uses the Modus Ponens

$$\mathbf{App} \ \frac{E, \Gamma \vdash t : P \to Q \qquad E, \Gamma \vdash t' : P}{E, \Gamma \vdash tt' : Q}$$

```
Term t: P_1 \rightarrow P_2 \rightarrow ... \rightarrow P_n \rightarrow Q
Goal: P_k \rightarrow P_{k+1} \rightarrow ... \rightarrow P_n \rightarrow Q
```

```
apply t
```

generates k-1 goals with statements $P_1, ..., P_{k-1}$ if new goals have solution $t_1, t_2, ..., t_{k-1}$ solution is $t_1, t_2, ..., t_{k-1}$ for initial goal



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apply tactic uses the Modus Ponens

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generates k-1 goals with statements $P_1, ..., P_{k-1}$ if new goals have solution $t_1, t_2, ..., t_{k-1}$ solution is t t_1 t_2 ... t_{k-1} for initial goal



intros v_1, v_2, ..., v_n

is the same as

intro v_1, intro v_2, ..., intro v_n

intro v_1 takes the first implication as a hypothesis called v_1

Proof Theorem $K: P \rightarrow Q \rightarrow P$

Goal is $P \rightarrow Q \rightarrow P$

intro p.

Hypothesis p:P and new Goal Q o P





```
intros v_1, v_2, ..., v_n is the same as intro v_1, intro v_2, ..., intro v_n intro v_1 takes the first implication as a hypothesis called v_1
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Proof Theorem K : $P \rightarrow Q \rightarrow P$ Goal is $P \rightarrow Q \rightarrow P$

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Hypothesis p: P and new Goal $Q \to P$



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Proof Theorem K : $P \rightarrow Q \rightarrow P$ Goal is $P \rightarrow Q \rightarrow P$

intro p.

Hypothesis p:P and new Goal $Q \rightarrow P$





Show i

Display goal i with complete context Coq displays the goals after each proof step

Undo r

Go back *n* steps and try an alternative if goal can not be solved

Restart

Go back to the beginning of the proof

Abort





Show i

Display goal i with complete context Coq displays the goals after each proof step

Undo n

Go back n steps and try an alternative if goal can not be solved

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Display goal i with complete context Coq displays the goals after each proof step

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Show i

Display goal i with complete context Coq displays the goals after each proof step

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Go back n steps and try an alternative if goal can not be solved

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Combine tactics without stopping at intermediary subgoals

Goal: $P \rightarrow Q \rightarrow (P \rightarrow Q \rightarrow R) \rightarrow R$

intros p q H; apply H; assumption.

Like chess: forsee results of tactics





Combine tactics without stopping at intermediary subgoals

Goal:
$$P \rightarrow Q \rightarrow (P \rightarrow Q \rightarrow R) \rightarrow R$$

intros p q H; apply H; assumption.

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Goal: $P \rightarrow Q \rightarrow (P \rightarrow Q \rightarrow R) \rightarrow R$

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Like chess: forsee results of tactics



Tactics can generate multiple subgoals

```
Goal: (P \to Q \to R) \to (P \to Q) \to (P \to R)
intros H H'p; apply H; [assumption | apply H'; assumption].
Two subgoals P and Q
```



Tactics can generate multiple subgoals

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$$(P \rightarrow Q \rightarrow R) \rightarrow (P \rightarrow Q) \rightarrow (P \rightarrow R)$$

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intros H H' p; apply H; [assumption | apply H'; assumption].

Two subgoals P and Q

First is solved with assumption

Other one first has to apply H' and then use assumption





Tactics can generate multiple subgoals

Goal:
$$(P \rightarrow Q \rightarrow R) \rightarrow (P \rightarrow Q) \rightarrow (P \rightarrow R)$$

intros H H' p; apply H; [assumption | apply H'; assumption].

Two subgoals P and Q



If a tactic fails automatically use another tactic

```
intros H p; apply H; (assumption \mid \mid intro H'). If assumption fails, then intro H' is used
```



If a tactic fails automatically use another tactic intros H p; apply H; (assumption || intro H').

A tactic can be left unchanged to finish every subgoal in one go Goal: $(P \to Q) \to (P \to R) \to (P \to Q \to R \to T) \to P \to T$ intros H H0 H1 p.



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If a tactic fails automatically use another tactic intros H p; apply H; (assumption || intro H'). If assumption fails, then intro H' is used





Tactic that always fails

Goal: $(P \rightarrow Q) \rightarrow (P \rightarrow Q)$

This combination succeeds; there are no more subgoals after "apply X"

Goal:
$$((P \rightarrow P) \rightarrow (Q \rightarrow Q) \rightarrow R) \rightarrow R$$

intro X; apply X; fail.





Tactic that always fails

Goal: $(P \rightarrow Q) \rightarrow (P \rightarrow Q)$

intro X; apply X; fail.

This combination succeeds; there are no more subgoals after "apply X"

Goal:
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Tactic that always fails

Goal: $(P \rightarrow Q) \rightarrow (P \rightarrow Q)$ intro X; apply X; fail.

This combination succeeds; there are no more subgoals after "apply X"

Goal:
$$((P \rightarrow P) \rightarrow (Q \rightarrow Q) \rightarrow R) \rightarrow R$$

intro X; apply X; fail.





Tactic that always fails

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This combination succeeds; there are no more subgoals after "apply X"

Goal:
$$((P \rightarrow P) \rightarrow (Q \rightarrow Q) \rightarrow R) \rightarrow R$$

intro X; apply X; fail.





Tactic that always fails

Goal:
$$(P \rightarrow Q) \rightarrow (P \rightarrow Q)$$

intro X; apply X; fail.

This combination succeeds; there are no more subgoals after "apply X"

Goal:
$$((P \rightarrow P) \rightarrow (Q \rightarrow Q) \rightarrow R) \rightarrow R$$

intro X; apply X; fail.





Tactic that always fails

Goal:
$$(P \rightarrow Q) \rightarrow (P \rightarrow Q)$$

intro X; apply X; fail.

This combination succeeds; there are no more subgoals after "apply X"

Goal:
$$((P \rightarrow P) \rightarrow (Q \rightarrow Q) \rightarrow R) \rightarrow R$$

intro X; apply X; fail.



Combination of tactics that never fail

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Goal: (P \rightarrow Q \rightarrow R \rightarrow T) \rightarrow (P \rightarrow Q) \rightarrow (P \rightarrow R \rightarrow T)
```

apply H; try assumption; apply H'; assumption.

"try tac" behaves like "tac | idtac"



Combination of tactics that never fail

Goal:
$$(P \rightarrow Q \rightarrow R \rightarrow T) \rightarrow (P \rightarrow Q) \rightarrow (P \rightarrow R \rightarrow T)$$

intros H H' p r

apply H; try assumption; apply H'; assumption.

"try tac" behaves like "tac | idtac'





Combination of tactics that never fail

Goal: $(P \rightarrow Q \rightarrow R \rightarrow T) \rightarrow (P \rightarrow Q) \rightarrow (P \rightarrow R \rightarrow T)$ intros H H' p r.

apply H; try assumption; apply H'; assumption.

"try tac" behaves like "tac∥ idtac'



Combination of tactics that never fail

Goal:
$$(P \rightarrow Q \rightarrow R \rightarrow T) \rightarrow (P \rightarrow Q) \rightarrow (P \rightarrow R \rightarrow T)$$

intros H H' p r.

apply H; try assumption; apply H'; assumption.

"try tac" behaves like "tac \parallel idtac"



Combination of tactics that never fail

Goal:
$$(P \rightarrow Q \rightarrow R \rightarrow T) \rightarrow (P \rightarrow Q) \rightarrow (P \rightarrow R \rightarrow T)$$

intros H H' p r.

apply H; try assumption; apply H'; assumption.

"try tac" behaves like "tac || idtac"





There are goals with no solution at all

Even though they are valid in classical logic

Peirce's formula: (((P o Q) o P) o P)



There are goals with no solution at all Even though they are valid in classical logic

Peirce's formula: $(((P \rightarrow Q) \rightarrow P) \rightarrow P)$





There are goals with no solution at all

Even though they are valid in classical logic

Peirce's formula: $(((P \rightarrow Q) \rightarrow P) \rightarrow P)$





There are goals with no solution at all

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Peirce's formula: $(((P \rightarrow Q) \rightarrow P) \rightarrow P)$

