Joel Gallant

Cell: 403-826-5534 Email: joel@joelgallant.me

Driven, detail oriented, self taught and a candid software developer - with specialization in making the complex simple. I work hard and fast without sacrificing quality.

Skills	<u>Advanced</u>	<u>Intermediate</u>	<u>Familiar</u>
	• Java 6/7	Node.js	 Ruby on Rails
	• C++11	Python	 Scala
	 CMake & Make 	 OpenCV & dlib 	• Rust
		 HTML5 & Javascript 	CSS / Sass
Tools	 Version Control (git) Github, Bitbucket, etc.	 Continuous Integration & Deployment 	SSH and common unix toolsWindows 7/8/10
	• vim / tmux / zsh	Unit Testing (gtest)IDE Tools (netbeans, eclipse)	 Solidworks

Experience

Renoworks

Software Developer (Jan 2017 - Present)

Developing software for frontend and backend portions of Renoworks' core products. Improving rendering engine, researching auto-masking and developing novel computer vision techniques.

Draganfly UAV & Trace

Computer Vision Technologist (Apr 2015 - Dec 2016)

Responsible for developing, testing and integrating embedded Linux computer vision tracking software. Working with the state-of-the art short term general object trackers, high speed detection, machine learning classification and gesture control. Advancing techniques and integrating them into a low power system to control cameras and UAVs.

Tracking software developed controls an autonomous UAV, target assists in public safety situations, and is adaptable to any type of target.

FIRST Robotics

FIRST Senior Mentor - 2014-2015

Supporting, recruiting and mentoring students & coaches for FIRST Robotics teams in Alberta.

My work had an impact on over 750 students across Alberta, giving them an opportunity to work hands-on with technology and engineering.

Interests

Free Software, Open Source, Linux

I have always been passionate about the moral and practical missions of free software **Electronics & Robotics**

I have worked with a good amount of electronics and competed in 5 years of robotics competitions

Active Living

I'm passionate about staying healthy through hiking, basketball, weightlifting and cycling

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Education

Bishop Carroll Self-Directed High School

High School Diploma, 2014

Achievements & Projects

Trace Visual Intelligence

I joined the software team for Trace to create a fast target tracker onboard UAVs. My proprietary work outperformed the best available options in accuracy and performance.

FIRST Robotics

I was a founding student member and continue to mentor with <u>Team 4334</u>. In 2014, I led the team to a World Championship division semi-final, and the Chairman's award.

- Chairman's award for broad inpact in and out of STEM
- · Over 15 official awards within 6 years of competing
- World division winner, the highest stage of competition

ATAlibj

In high school, I collaborated with members from other teams to develop a high quality Java library for use in FRC robots, generalizing many of the common approaches and problems faced.

Gordian Scripting Language

In my grade 11 year, I wrote an interpreter for a python-like scripting language that was run onboard an FRC robot. It used no external libraries and had a prototypical object model.

High School Robotics Curriculum

I was honored in my grade 11 and 12 years to write curriculum for online high school courses that were taken by over 50 students.

Find me





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