# Robotic Simulation Language
# - Specifications

Primitive Datatypes:

int , float , boolean

Complex(Custom) Datatypes:
Point, Velocity (internal structure same as Point but different units) , Bot

```
struct Point
{
        int x;
        int y;
};

struct Bot
{
        Point position;
        Velocity vel;

        int direction;
        int color;
        boolean active;
}
;
```

Aggregative Datatypes:
- Array of char, int, float
- 2-D arrays supported

- User defined structures supported
- Nested structures supported

Operators:
arithmetic ==> + - / *

unary prefix ==> ++ --

shorthand ==> +=

logical ==> AND(&&) OR( | | ) NOT(!)

relational ==> > < >= <= != ==

array splicing ==> **:** // Eg. b[2:4] = arr[3:5]

addV ==> addV v1, v2 // for adding two velocities
input operator ==> >> // for user input
forward operator ==> fw b1, 5 // to move the bot forward

turn operator ==> rt b1 // to turn the bot right
special assignment ==> := // used for Point, Bot and velocity assignment

Other Features:
static typing

static scoping

weak name equivalence for primitive data types, strong name equivalence for user defined structures

Type conversion, casting : Both implicit and explicit

Precedence in expressions taken care of

Statements:

1. Iteration ==> For Loops

- *for(i=5;i<6;++i;) {}*
- **nested** loops supported

2. Functions

*function <return_type1, return_type2, ....>*
*function_name (params) {*
*// body*

*return val1, val2, val3..;*

*}*

- **Multiple return values supported**

**- Parameters: Name based and Positional matching, Default values on right side**

3. Conditional

if (condition) {

}

else if (condition) {

}

else{

}

5. Assignment

Multiple parallel assignments support

eg. a, d, e = 4, 7, getVal();

4. Declaration

<type> <var_name> = <value>

5. return, break, continue, exit()
- break, continue only allowed inside loops

6. User Input
- readi >> x;
- support for user to input integers