Bayesian Optimization Tutorial

Why Go Beyond Traditional Optimization?

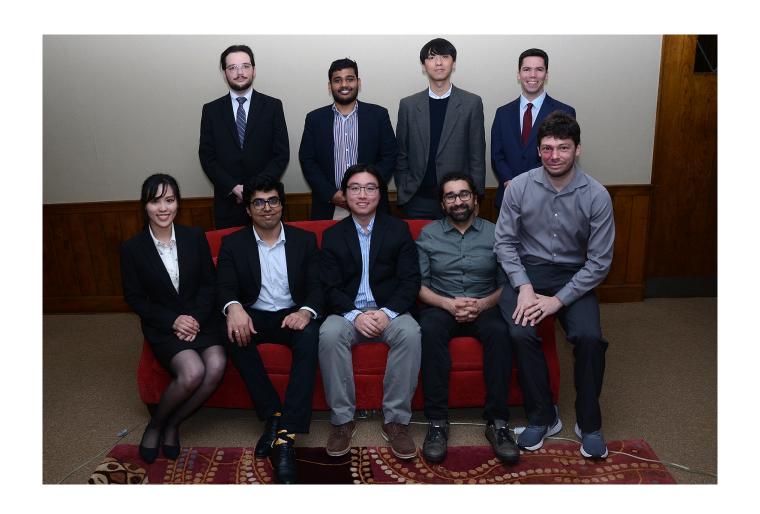
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Great Lakes PSE Student Workshop, 2023

For copies of slides & code, see https://github.com/joelpaulson/Great_Lakes_PSE_Workshop_2023

Thank you to My Group for Help Developing Materials! (Especially the Code for the Modules)



What is an Optimization Problem?

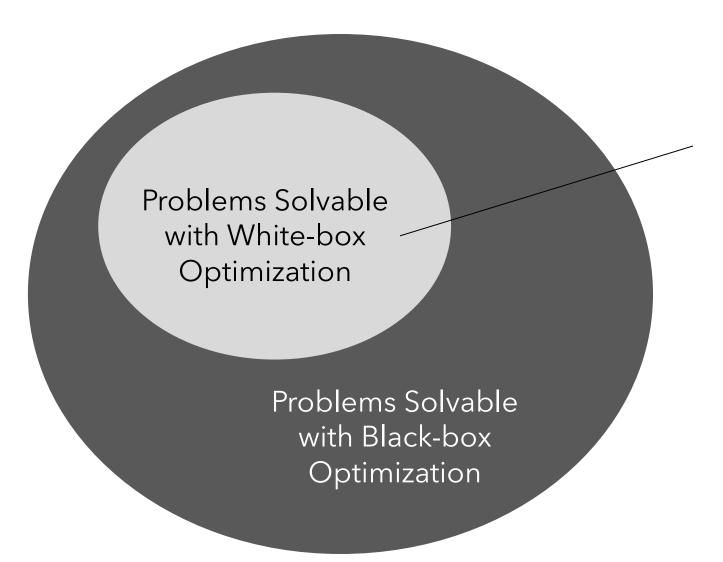
decision (design)
$$\underbrace{ \begin{array}{c} \min \\ x \end{array} } f(x) \Big \} - \underbrace{ \begin{array}{c} \text{objective function} \\ \text{s.t.} \end{array} } x \in \Omega \Big \} - \underbrace{ \begin{array}{c} \text{constraints} \\ \text{(feasible region)} \end{array} }$$

- Optimization problems are **pervasive** in every application domain
 - differentiate problems based on characteristics \rightarrow determine what solver to use
- There are a huge number of available optimization algorithms; difficult to a priori know the best one but we can eliminate some options

How to Classify Optimization Algorithms?

- A simple way to "partition" the algorithms into two major buckets are "white-box" and "black-box" (i.e., not white box)
- White-box means that we need an "equation-oriented model" of the system so that the mathematical structure of f(x) and Ω satisfy certain important assumptions
 - The exact assumptions depend on the method, but they will typically require the functions to be differentiable and/or easy to build relaxations of them
- Any method that only requires evaluations of f(x) and $x \in \Omega$ at specific points can then be classified as "black box"

How to Classify Optimization Algorithms?



Since white-box algorithms make stronger assumptions, they can only be used to tackle a subset of problems when compared to black-box algorithms

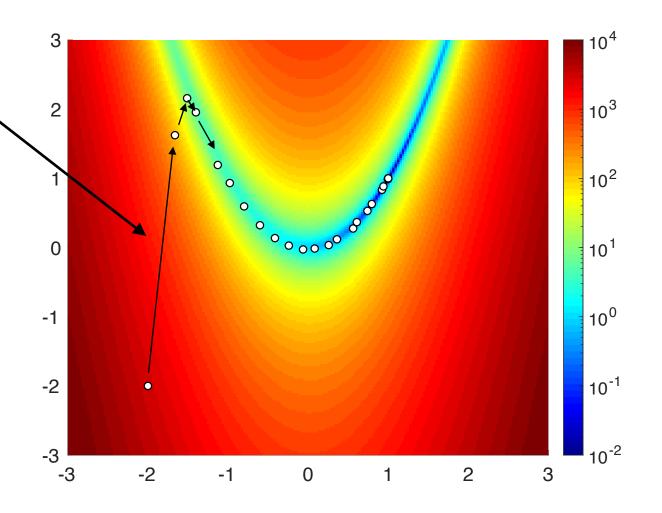
→ The main value of black-box methods are their generality (not necessarily efficient)

Example of White-Box Optimization: Newton's Method

Use derivatives to take step toward reducing objective, i.e.,

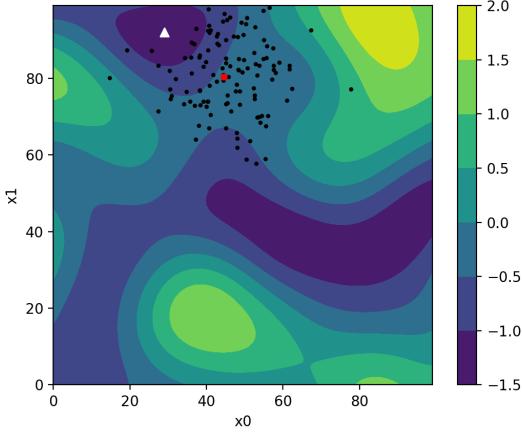
$$x_{k+1} = x_k - \alpha_k (\nabla^2 f(x_k))^{-1} \nabla f(x_k)$$

This type of algorithm is "local" (requires initial guess) & requires ability to compute derivatives (expensive when the structure of the function is unknown)



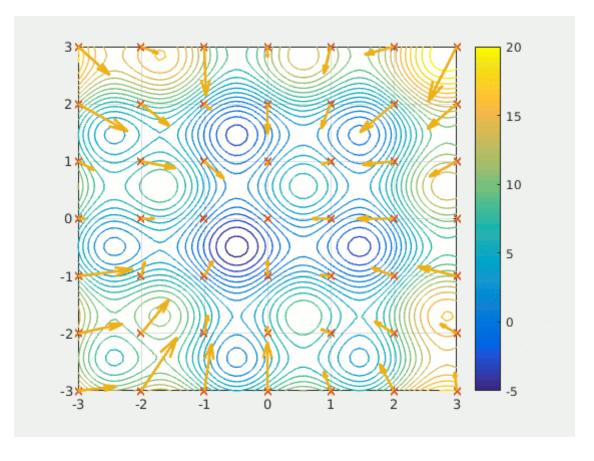
Examples of Black-Box (Derivative-Free) Optimization

Covariance Matrix Adaptive Evolutionary Strategy (CMA-ES)



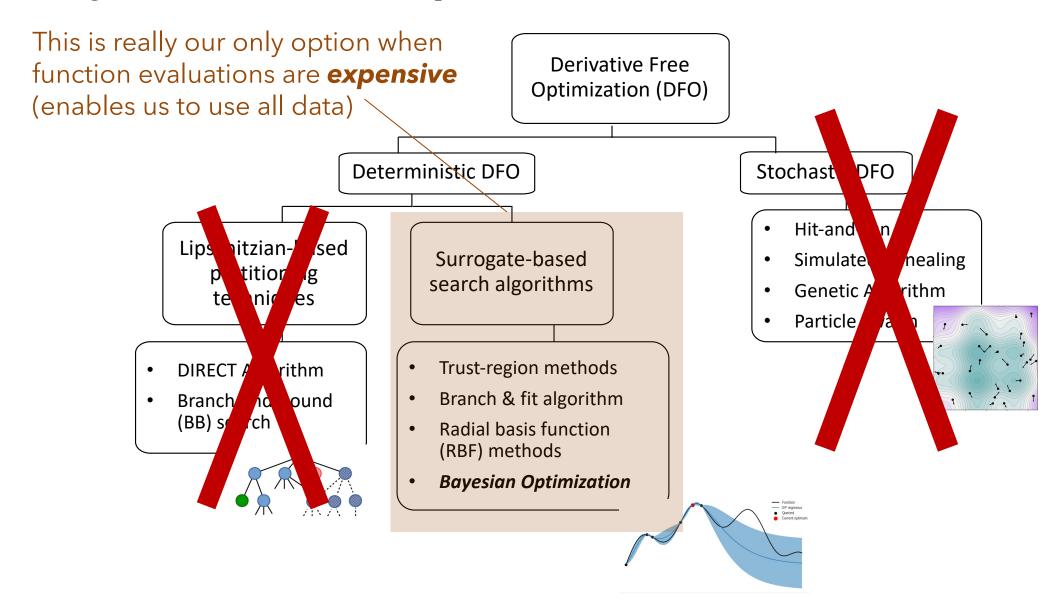
https://thurinj.github.io/CMA-ES.html

Particle Swarm Optimization (PSO)

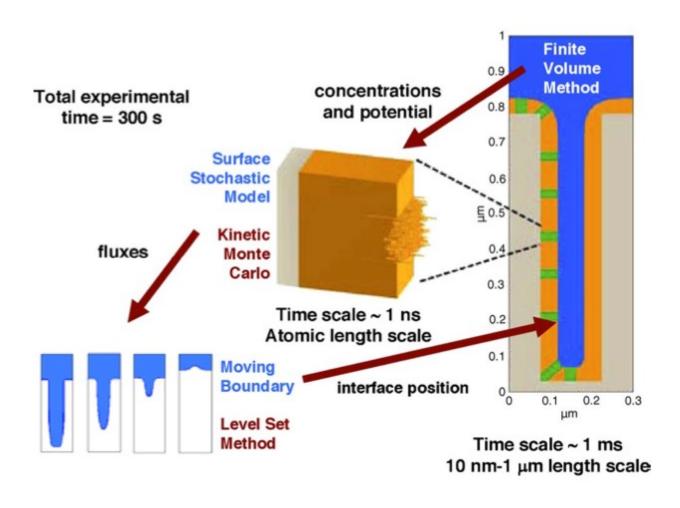


https://en.wikipedia.org/wiki/Particle_swarm_optimization

Many derivative-free optimization methods, which to choose?



Optimizing multi-scale simulation models



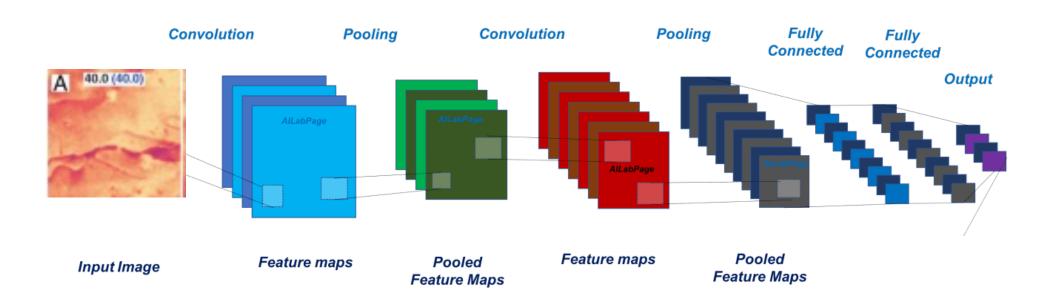
Objective:

Minimize surface roughness

Design variables:

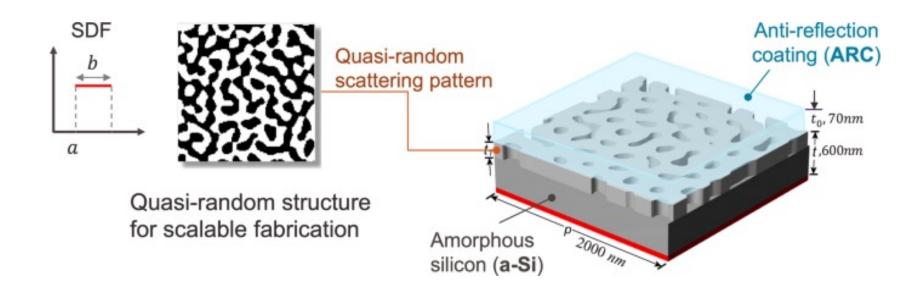
Chemical additive concentrations & reaction temperature

Automated machine learning



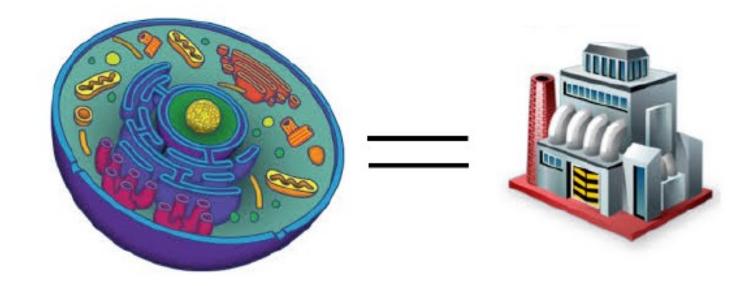
- Objective: Maximize classification accuracy for image-based chemical sensor
- **Design variables:** Number of layers, number of nodes per layer, learning rates, regularization penalties, activation functions, etc.

Material and drug discovery



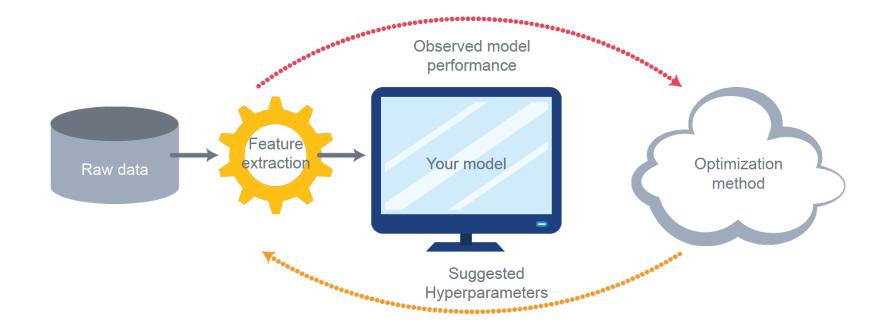
- Objective: Maximize light adsorption in quasi-random solar cell
- **Design variables:** Type of amorphous silicon (a-Si), light trapping pattern for fabrication, & overall thickness

Design of experiments: Gene optimization



- **Objective:** Maximize efficiency of the cell factory to make product (e.g., proteins)
- **Design variables:** Gene sequence (e.g., ATTGGTUGA...) & culture conditions (e.g., pH)

Tuning hyperparameters in optimization codes



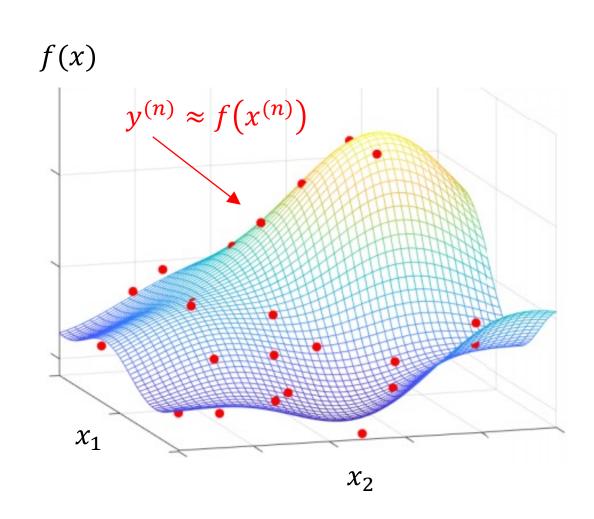
- Objective: Minimize solution time for family of scheduling/planning problems
- Design variables: Algorithmic parameters in solver (e.g., CPLEX has 76 design parameters)

Many other problems:

- Robotics, aerospace, control, reinforcement learning
- Tuning websites with A/B testing
- Calibrating expensive simulators to experimental data
- etc....

Standard Goal in Bayesian Optimization:

Optimize functions $f: \mathbb{R}^d \to \mathbb{R}$ that are:

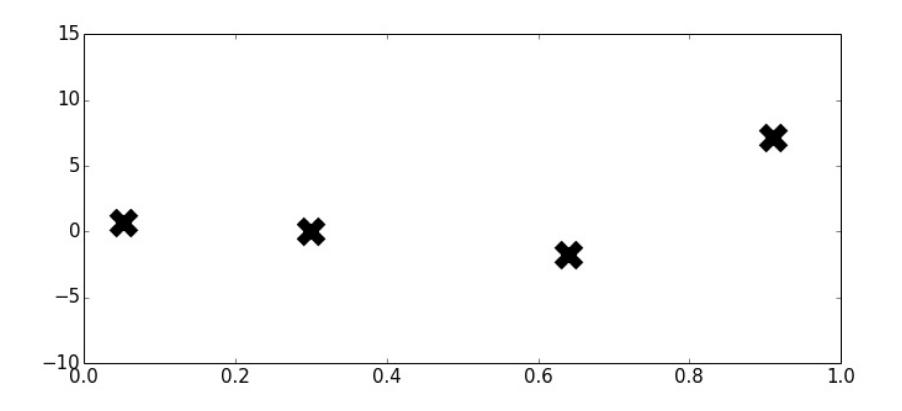


*We will deal with black-box constraints later

- f(·) is explicitly <u>unknown</u> & <u>non-convex</u>
 - lacks known special structure, e.g., convexity
- f(⋅) is <u>derivative-free</u>
 - cannot simply get gradients
- $f(\cdot)$ is expensive to evaluate
 - # of evaluations is severely limited
- $f(\cdot)$'s evaluations may be <u>noisy</u>
 - noise independent & ~normally distributed,
 but unknown variance

Illustrative example to build some intuition

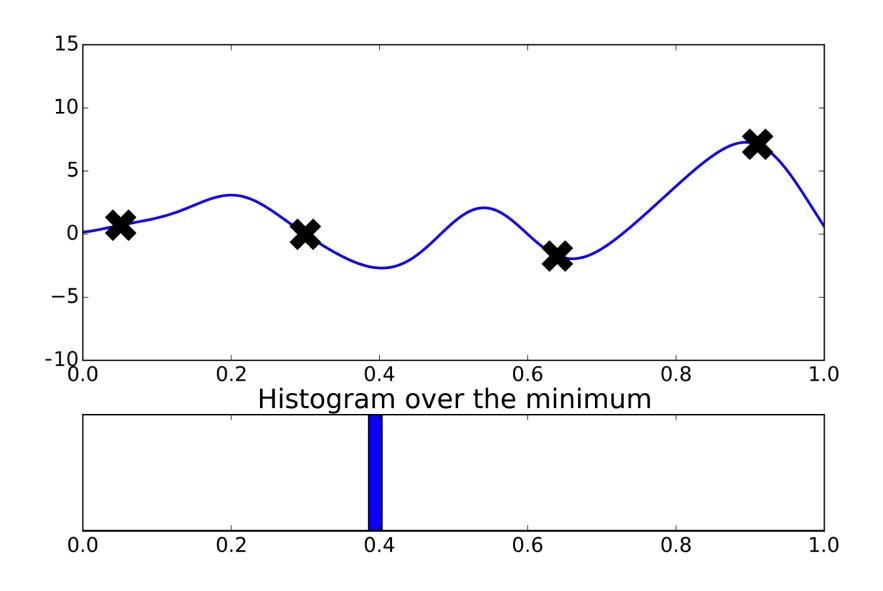
We have four function evaluations



- Where is the minimum of the function $f(\cdot)$?
- Where should we take our next evaluation?

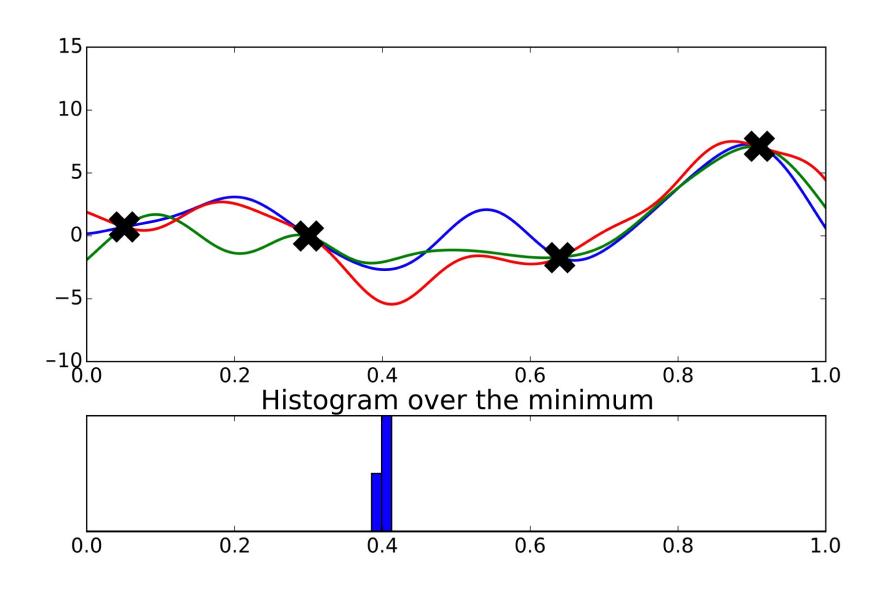
Intuitive solution, fit a surrogate model

One curve; which one should we select?



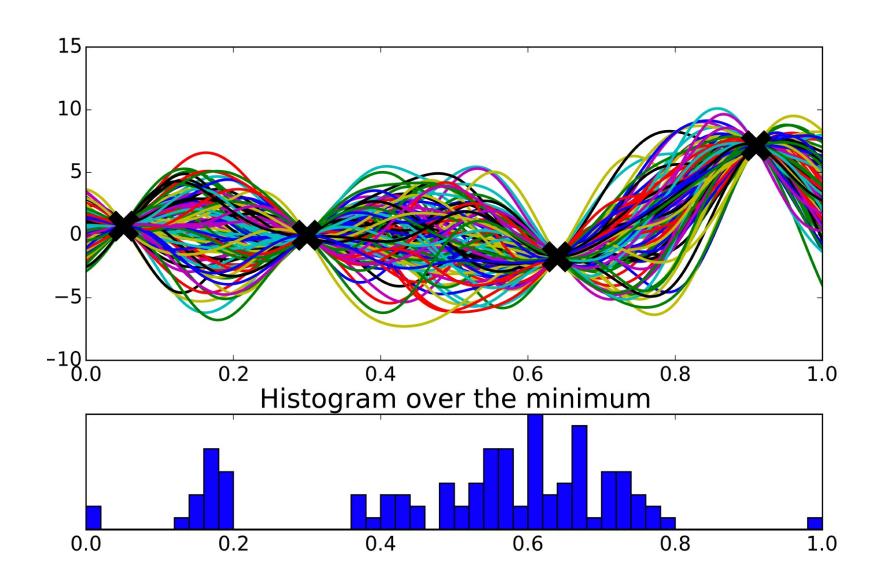
Intuitive solution, fit a surrogate model

Three curves



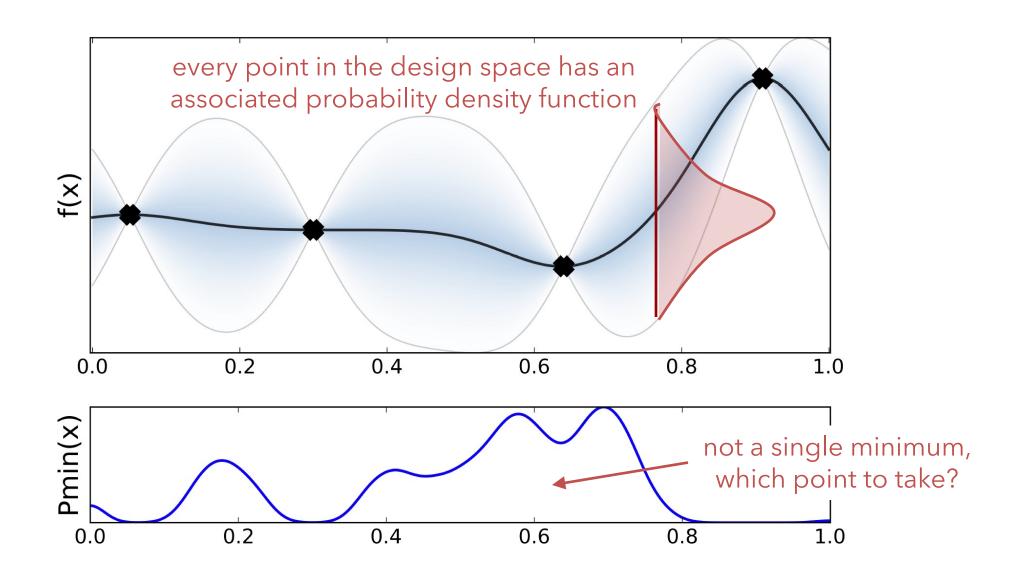
Intuitive solution, fit a surrogate model

One hundred curves



Intuitive solution, fit a surrogate model Infinite curves

(Need the help of information theory to properly define models + metrics)



Bird's-eye View of Bayesian Optimization

Module 3

while {budget not exhausted}

Module 1

Fit a Bayesian machine learning model (usually Gaussian process regression) to observations $\{x, f(x)\}$

Find x that maximizes acquisition(x, posterior)

Sample x & then observe f(x)

Module 2

end

More Information

Workshop Schedule

Introduction: Why Go Beyond Traditional Optimization?
Module 1: Probabilistic Surrogate Modeling*
Break
Module 2: Quantifying the Value of Information*
Module 3: The BO Feedback Loop*
Break
Module 4: Beyond Bayesian Optimization

^{*}module includes Python code review / exercises