

Single Molecule Tracking Analysis Documentation

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7.36	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/analysisFunctions/smallestenclosingcircle.py File Reference	268
7.37	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/clusterMethods/blob_detection.py File Reference	269
7.38	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/clusterMethods/clustering_methods.py File Reference	270
7.39	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/ioModule/import_functions.py File Reference	270
7.40	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/ioModule/logging_and_print_util.py File Reference	271
7.41	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/ioModule/pickle_util.py File Reference	271
7.42	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/ioModule/plotting_functions.py File Reference	271
7.43	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/ioModule/SMT_converters.py File Reference	272
7.44	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/misc/decorators.py File Reference	273
7.45	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/misc/diff_mw.py File Reference	273
7.46	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/misc/errors.py File Reference	274
7.47	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/helpers/misc/guassian_fit.py File Reference	274
7.48	/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_↔ Analysis_BP/Matlab/batch_convert_single_fluorescence_BW.m File Reference	275
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Chapter 1

Namespace Index

1.1 Namespace List

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Chapter 2

Hierarchical Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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Chapter 3

Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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Here is a list of all files with brief descriptions:

/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/___init___py	249
/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
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/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
BP/databases/___init___py	249
/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
BP/databases/data_path_container.py	251
/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
BP/databases/structure_storage.py	255
/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
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/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
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/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
BP/databases/thunderSTORM/localization_merger.py	255
/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
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/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔	
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/Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↵ BP/helpers/analysisFunctions/ nucleoid_detection.py	267
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/Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↵ BP/helpers/analysisFunctions/ smallestenclosingcircle.py	268
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Chapter 5

Namespace Documentation

5.1 BP_TRACKING Namespace Reference

Functions

- [main](#) ()
- [tracking_plus_save](#) (directory_path, dir_save, file_path, file_counter)
- [sorted_alphanumeric](#) (data)

Variables

- str [DIRECTORY_MOVIES](#) = "/Volumes/Balijot_HD/SMT_Olympus/RIF_TREATMET_LIVE/20230528/Movie"
- str [MOVIE_BASE_NAME](#) = "nusa_rif"
- str [DIRECTORY_SAVE](#) = "Analysis_new"
- dict [LINKING_PARAMETERS](#)
- dict [LOCALIZATION_PARAMETERS](#)
- dict [FILTERING_PARAMETERS](#)
- dict [OUTPUT_COLUMNS](#)
- list [OUTPUT_COLUMNS_ORDER](#)
- int [PAD_ROWS](#) = 3
- [model](#) = [Model](#)()
- [settings](#) = [Settings](#)(imp)
- [detectorFactory](#)
- [detectorSettings](#)
- [trackerFactory](#)
- [trackerSettings](#)
- [trackmate](#) = [TrackMate](#)([model](#), [settings](#))
- [ok](#) = [trackmate](#).checkInput()
- [ds](#) = [DisplaySettingsIO](#).readUserDefault()
- [selectionModel](#) = [SelectionModel](#)([model](#))
- [displayer](#) = [HyperStackDisplayer](#)([model](#), [selectionModel](#), imp,[ds](#))
- [spt_m](#) = [model](#).getSpots()
- [tracks_found](#) = [model](#).getTrackModel().trackIDs(True)
- [tot_spts](#) = [spt_m](#).getNSpots(True)
- [fm](#) = [model](#).getFeatureModel()
- list [header_row](#) = [header_name for header_name in [OUTPUT_COLUMNS_ORDER](#)]
- list [collection_spots_per_track](#) = [[header_row](#)]

- `track` = `model.getTrackModel().trackSpots(id)`
- `int spot_counter` = 0
- `sid` = `spot.ID()`
- `int spot_label` = `spot_counter`
- `spot_ID` = `sid`
- `track_ID` = `id`
- `spot_quality` = `spot.getFeature('QUALITY')`
- `spot_x` = `spot.getFeature('POSITION_X')`
- `spot_y` = `spot.getFeature('POSITION_Y')`
- `spot_z` = `spot.getFeature('POSITION_Z')`
- `spot_t` = `spot.getFeature('POSITION_T')`
- `spot_frame` = `spot.getFeature('FRAME')`
- `spot_radius` = `spot.getFeature('RADIUS')`
- `spot_visibility` = `spot.getFeature('VISIBILITY')`
- `spot_manual_spot_color` = `spot.getFeature('MANUAL_SPOT_COLOR')`
- `spot_mean_intensity_ch1` = `spot.getFeature('MEAN_INTENSITY_CH1')`
- `spot_median_intensity_ch1` = `spot.getFeature('MEDIAN_INTENSITY_CH1')`
- `spot_min_intensity_ch1` = `spot.getFeature('MIN_INTENSITY_CH1')`
- `spot_max_intensity_ch1` = `spot.getFeature('MAX_INTENSITY_CH1')`
- `spot_total_intensity_ch1` = `spot.getFeature('TOTAL_INTENSITY_CH1')`
- `spot_std_intensity_ch1` = `spot.getFeature('STD_INTENSITY_CH1')`
- `spot_contrast_ch1` = `spot.getFeature('CONTRAST_CH1')`
- `spot_snr_ch1` = `spot.getFeature('SNR_CH1')`
- `writer` = `csv.writer(f,delimiter=',')`
- `start_time` = `time.time()`

5.1.1 Function Documentation

5.1.1.1 `main()`

```
BP_TRACKING.main ()
```

5.1.1.2 `sorted_alphanumeric()`

```
BP_TRACKING.sorted_alphanumeric (
    data)
```

5.1.1.3 `tracking_plus_save()`

```
BP_TRACKING.tracking_plus_save (
    directory_path,
    dir_save,
    file_path,
    file_counter)
```

5.1.2 Variable Documentation

5.1.2.1 `collection_spots_per_track`

```
list BP_TRACKING.collection_spots_per_track = [header_row]
```


5.1.2.2 detectorFactory

```
BP_TRACKING.detectorFactory
```

5.1.2.3 detectorSettings

```
BP_TRACKING.detectorSettings
```

5.1.2.4 DIRECTORY_MOVIES

```
str BP_TRACKING.DIRECTORY_MOVIES = "/Volumes/Baljyot_HD/SMT_Olympus/RIF_TREATMET_LIVE/20230528/Movie"
```

5.1.2.5 DIRECTORY_SAVE

```
str BP_TRACKING.DIRECTORY_SAVE = "Analysis_new"
```

5.1.2.6 displayer

```
BP_TRACKING.displayer = HyperStackDisplayer(model, selectionModel, imp, ds)
```

5.1.2.7 ds

```
BP_TRACKING.ds = DisplaySettingsIO.readUserDefault()
```

5.1.2.8 FILTERING_PARAMETERS

```
dict BP_TRACKING.FILTERING_PARAMETERS
```

Initial value:

```
00001 = {  
00002     "QUALITY": None,  
00003     "MIN_NUMBER_SPOTS_IN_TRACK": None,  
00004     "MAX_NUMBER_SPOTS_IN_TRACK": None  
00005 }
```

5.1.2.9 fm

```
BP_TRACKING.fm = model.getFeatureModel()
```

5.1.2.10 header_row

```
list BP_TRACKING.header_row = [header_name for header_name in OUTPUT_COLUMNS_ORDER]
```

5.1.2.11 LINKING_PARAMETERS

```
dict BP_TRACKING.LINKING_PARAMETERS
```

Initial value:

```
00001 = {
00002     'LINKING_MAX_DISTANCE': 5.0,
00003     'GAP_CLOSING_MAX_DISTANCE': 5.0,
00004     'SPLITTING_MAX_DISTANCE': 0.0,
00005     'MERGING_MAX_DISTANCE': 0.0,
00006     'MAX_FRAME_GAP': 0,
00007     'ALLOW_TRACK_SPLITTING': False,
00008     'ALLOW_TRACK_MERGING': False
00009 }
```

5.1.2.12 LOCALIZATION_PARAMETERS

```
dict BP_TRACKING.LOCALIZATION_PARAMETERS
```

Initial value:

```
00001 = {
00002     "DETECTOR_FACTORY": LogDetectorFactory(),
00003     'DO_SUBPIXEL_LOCALIZATION' : True,
00004     'RADIUS' : 2.0,
00005     'TARGET_CHANNEL' : 1,
00006     'THRESHOLD' : 10.0,
00007     'DO_MEDIAN_FILTERING' : True,
00008 }
```

5.1.2.13 model

```
BP_TRACKING.model = Model()
```

5.1.2.14 MOVIE_BASE_NAME

```
str BP_TRACKING.MOVIE_BASE_NAME = "nusa_rif"
```

5.1.2.15 ok

```
BP_TRACKING.ok = trackmate.checkInput()
```

5.1.2.16 OUTPUT_COLUMNS

```
dict BP_TRACKING.OUTPUT_COLUMNS
```

Initial value:

```
00001 = {
00002     'LABEL':True,
00003     'ID':True,
00004     'TRACK_ID':True,
00005     'QUALITY':True,
00006     'POSITION_X':True,
00007     'POSITION_Y':True,
00008     'POSITION_Z':True,
00009     'POSITION_T':True,
00010     'FRAME':True,
00011     'RADIUS':True,
00012     'VISIBILITY':True,
00013     'MANUAL_SPOT_COLOR':True,
00014     'MEAN_INTENSITY_CH1':True,
00015     'MEDIAN_INTENSITY_CH1':True,
00016     'MIN_INTENSITY_CH1':True,
00017     'MAX_INTENSITY_CH1':True,
00018     'TOTAL_INTENSITY_CH1':True,
00019     'STD_INTENSITY_CH1':True,
00020     'CONTRAST_CH1':True,
00021     'SNR_CH1':True
00022 }
```

5.1.2.17 OUTPUT_COLUMNS_ORDER

```
list BP_TRACKING.OUTPUT_COLUMNS_ORDER
```

Initial value:

```
00001 = [  
00002     'LABEL', 'ID', 'TRACK_ID', 'QUALITY', 'POSITION_X', 'POSITION_Y', 'POSITION_Z', 'POSITION_T',  
        'FRAME',  
00003     'RADIUS', 'VISIBILITY', 'MANUAL_SPOT_COLOR', 'MEAN_INTENSITY_CH1', 'MEDIAN_INTENSITY_CH1',  
        'MIN_INTENSITY_CH1',  
00004     'MAX_INTENSITY_CH1', 'TOTAL_INTENSITY_CH1', 'STD_INTENSITY_CH1', 'CONTRAST_CH1', 'SNR_CH1'  
00005 ]
```

5.1.2.18 PAD_ROWS

```
int BP_TRACKING.PAD_ROWS = 3
```

5.1.2.19 selectionModel

```
BP_TRACKING.selectionModel = SelectionModel(model)
```

5.1.2.20 settings

```
BP_TRACKING.settings = Settings(imp)
```

5.1.2.21 sid

```
BP_TRACKING.sid = spot.ID()
```

5.1.2.22 spot_contrast_ch1

```
BP_TRACKING.spot_contrast_ch1 = spot.getFeature('CONTRAST_CH1')
```

5.1.2.23 spot_counter

```
int BP_TRACKING.spot_counter = 0
```

5.1.2.24 spot_frame

```
BP_TRACKING.spot_frame = spot.getFeature('FRAME')
```

5.1.2.25 spot_ID

```
BP_TRACKING.spot_ID = sid
```

5.1.2.26 spot_label

```
int BP_TRACKING.spot_label = spot_counter
```

5.1.2.27 spot_manual_spot_color

```
BP_TRACKING.spot_manual_spot_color = spot.getFeature('MANUAL_SPOT_COLOR')
```

5.1.2.28 spot_max_intensity_ch1

```
BP_TRACKING.spot_max_intensity_ch1 = spot.getFeature('MAX_INTENSITY_CH1')
```

5.1.2.29 spot_mean_intensity_ch1

```
BP_TRACKING.spot_mean_intensity_ch1 = spot.getFeature('MEAN_INTENSITY_CH1')
```

5.1.2.30 spot_median_intensity_ch1

```
BP_TRACKING.spot_median_intensity_ch1 = spot.getFeature('MEDIAN_INTENSITY_CH1')
```

5.1.2.31 spot_min_intensity_ch1

```
BP_TRACKING.spot_min_intensity_ch1 = spot.getFeature('MIN_INTENSITY_CH1')
```

5.1.2.32 spot_quality

```
BP_TRACKING.spot_quality = spot.getFeature('QUALITY')
```

5.1.2.33 spot_radius

```
BP_TRACKING.spot_radius = spot.getFeature('RADIUS')
```

5.1.2.34 spot_snr_ch1

```
BP_TRACKING.spot_snr_ch1 = spot.getFeature('SNR_CH1')
```

5.1.2.35 spot_std_intensity_ch1

```
BP_TRACKING.spot_std_intensity_ch1 = spot.getFeature('STD_INTENSITY_CH1')
```

5.1.2.36 spot_t

```
BP_TRACKING.spot_t = spot.getFeature('POSITION_T')
```

5.1.2.37 spot_total_intensity_ch1

```
BP_TRACKING.spot_total_intensity_ch1 = spot.getFeature('TOTAL_INTENSITY_CH1')
```

5.1.2.38 spot_visibility

```
BP_TRACKING.spot_visibility = spot.getFeature('VISIBILITY')
```

5.1.2.39 spot_x

```
BP_TRACKING.spot_x = spot.getFeature('POSITION_X')
```

5.1.2.40 spot_y

```
BP_TRACKING.spot_y = spot.getFeature('POSITION_Y')
```

5.1.2.41 spot_z

```
BP_TRACKING.spot_z = spot.getFeature('POSITION_Z')
```

5.1.2.42 spt_m

```
BP_TRACKING.spt_m = model.getSpots()
```

5.1.2.43 start_time

```
BP_TRACKING.start_time = time.time()
```

5.1.2.44 tot_spts

```
BP_TRACKING.tot_spts = spt_m.getNSpots(True)
```

5.1.2.45 track

```
BP_TRACKING.track = model.getTrackModel().trackSpots(id)
```

5.1.2.46 track_ID

```
BP_TRACKING.track_ID = id
```

5.1.2.47 trackerFactory

```
BP_TRACKING.trackerFactory
```

5.1.2.48 trackerSettings

```
BP_TRACKING.trackerSettings
```

5.1.2.49 trackmate

```
BP_TRACKING.trackmate = TrackMate(model, settings)
```

5.1.2.50 tracks_found

```
BP_TRACKING.tracks_found = model.getTrackModel().trackIDs(True)
```

5.1.2.51 writer

```
BP_TRACKING.writer = csv.writer(f, delimiter=',')
```

5.2 localization_merger Namespace Reference

Functions

- `pd.DataFrame` [merge_localization](#) (`pd.DataFrame` tracks, `max_dist=1`, `max_frame_gap=1`)

Variables

- list [COL_NAMES_THUNDERSTORM](#) = ['id', 'frame', 'x [nm]', 'y [nm]', 'sigma [nm]', 'intensity [photon]', 'offset [photon]', 'bkgstd [photon]', 'chi2', 'uncertainty [nm]']
- list [NEW_COL_NAMES](#) = ['id', 'frame', 'x [nm]', 'y [nm]', 'sigma [nm]', 'intensity [photon]', 'offset [photon]', 'bkgstd [photon]', 'chi2', 'uncertainty [nm]', 'merged']

5.2.1 Detailed Description

ThunderSTORM localization merger TODO THIS DOES NOT WORK YET

This module contains the function to merge localizations from ThunderSTORM .csv file.

The structure of the .csv file is the following:

id, frame, x [nm], y [nm], sigma [nm], intensity [photon], offset [photon], bkgstd [photon], chi2, uncertainty [nm]

id: the id of the localization

frame: the frame number

x [nm]: the x coordinate of the localization in nanometers

y [nm]: the y coordinate of the localization in nanometers

sigma [nm]: the sigma of the localization in nanometers

intensity [photon]: the intensity of the localization in photon

offset [photon]: the offset of the localization in photon

bkgstd [photon]: the background standard deviation of the localization in photon

chi2: the chi2 of the localization

uncertainty [nm]: the uncertainty of the localization in nanometers

5.2.2 Function Documentation

5.2.2.1 merge_localization()

```
pd.DataFrame localization_merger.merge_localization (
    pd.DataFrame tracks,
    max_dist = 1,
    max_frame_gap = 1)
```

Merge localizations into one localization given a maximum distance and a maximum frame gap.

The function merge_localization() takes as input a DataFrame containing the localizations to be merged and returns a DataFrame. There is a new column at the end called 'merged' which contains the number of the merged localization produced.

Parameters:

tracks : pandas.DataFrame

DataFrame containing the localizations to be merged. (this is the output of ThunderSTORM .csv file, see doc)

max_dist : float (nm - nanometers, default = 1)

Maximum distance between two localizations to be merged (in nanometers)

max_frame_gap : int (default = 0, no frame gap)

Maximum frame gap between two localizations to be merged (in frames)

Returns:

merged_tracks : pandas.DataFrame

DataFrame containing the merged localizations with a new column 'merged' containing the number of the merged localization produced.

5.2.3 Variable Documentation

5.2.3.1 COL_NAMES_THUNDERSTORM

```
list localization_merger.COL_NAMES_THUNDERSTORM = ['id', 'frame', 'x [nm]', 'y [nm]', 'sigma [nm]', 'intensity [photon]', 'offset [photon]', 'bkgstd [photon]', 'chi2', 'uncertainty [nm]']
```

5.2.3.2 NEW_COL_NAMES

```
list localization_merger.NEW_COL_NAMES = ['id', 'frame', 'x [nm]', 'y [nm]', 'sigma [nm]', 'intensity [photon]', 'offset [photon]', 'bkgstd [photon]', 'chi2', 'uncertainty [nm]', 'merged']
```

5.3 localization_setter Namespace Reference

Classes

- class [mask_localization](#)
- class [path_structure](#)

Variables

- str [RELATIVE_ANALYSIS_FOLDER](#) = "TS_Analysis"
- int [BOUNDING_BOX_EXTRA_BORDER](#) = 2
- list [paths](#)
- ml = [mask_localization](#)(path)

5.3.1 Variable Documentation

5.3.1.1 BOUNDING_BOX_EXTRA_BORDER

```
int localization_setter.BOUNDING_BOX_EXTRA_BORDER = 2
```

5.3.1.2 ml

```
localization_setter.ml = mask\_localization(path)
```

5.3.1.3 paths

```
list localization_setter.paths
```

Initial value:

```
00001 = [
00002     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_rif_fixed/TS",
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_m9_fixed/TS",
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_hex5_fixed_2/TS",
00005     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_hex5_fixed/TS",
00006     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_ez_fixed_2/TS",
00007     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_ez_fixed/TS",
00008     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231017/1l_hex5_fixed/TS",
00009     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/Fixed_100ms/20231015/1l_ez/TS"
00010 ]
```

5.3.1.4 RELATIVE_ANALYSIS_FOLDER

```
str localization_setter.RELATIVE_ANALYSIS_FOLDER = "TS_Analysis"
```


5.4 scale_space_plus_database_tracked Namespace Reference

Classes

- class [segmentation_scale_space](#)

Variables

- int [CORRECTION_FACTOR](#) = 1.
- str [LOCALIZATION_UNIQUE_TYPE](#) = "mean"
- list [cds](#)
- list [t_strings](#)
- dict [blob_parameters](#)
- dict [fitting_parameters](#)
- list [img_dims](#)
- list [rescale_pixel_size](#)
- list [type_analysis_file](#)
- list [total_frames](#)
- list [subframes](#)
- list [pixel_size](#)
- list [loc_error](#)
- list [include_all](#)
- [batch](#)

5.4.1 Variable Documentation

5.4.1.1 batch

`scale_space_plus_database_tracked.batch`

Initial value:

```
00001 = segmentation_scale_space(cds[i],
00002                               t_strings[i],
00003                               blob_parameters,
00004                               fitting_parameters,
00005                               img_dims[i],
00006                               rescale_pixel_size[i],
00007                               type_analysis_file[i],
00008                               total_frames[i],
00009                               subframes[i],
00010                               pixel_size[i],
00011                               loc_error[i],
00012                               include_all[i])
```

5.4.1.2 blob_parameters

`dict scale_space_plus_database_tracked.blob_parameters`

Initial value:

```
00001 = {
00002     "threshold": 3e-2, \
00003     "overlap": 0, \
00004     "median": False, \
00005     "min_sigma": 4/np.sqrt(2), \
00006     "max_sigma": 20/np.sqrt(2), \
00007     "num_sigma": 30, \
00008     "detection": 'bp', \
00009     "log_scale": False
00010 }
```

5.4.1.3 cds

```
list scale_space_plus_database_tracked.cds
```

Initial value:

```
00001 = [  
00002     "/Users/baljyot/Documents/CODE/GitHub_t2/Baljyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/EZ_120min/20190527/rpoc_ez"  
00003 ]
```

5.4.1.4 CORRECTION_FACTOR

```
int scale_space_plus_database_tracked.CORRECTION_FACTOR = 1.
```

5.4.1.5 fitting_parameters

```
dict scale_space_plus_database_tracked.fitting_parameters
```

Initial value:

```
00001 = {  
00002     "mask_size":5,  
00003     "plot_fit":False,  
00004     "fitting_image":"LAP",  
00005     "radius_func":np.mean,#identity,  
00006     "residual_func":residuals_gaus2d,  
00007     "sigma_range":4,  
00008     "centroid_range":3,  
00009     "height_range":1  
00010 }
```

5.4.1.6 img_dims

```
list scale_space_plus_database_tracked.img_dims
```

Initial value:

```
00001 = [  
00002     (290,290)  
00003 ]
```

5.4.1.7 include_all

```
list scale_space_plus_database_tracked.include_all
```

Initial value:

```
00001 = [  
00002     False  
00003 ]
```

5.4.1.8 loc_error

```
list scale_space_plus_database_tracked.loc_error
```

Initial value:

```
00001 = [  
00002     20  
00003 ]
```

5.4.1.9 LOCALIZATION_UNIQUE_TYPE

```
str scale_space_plus_database_tracked.LOCALIZATION_UNIQUE_TYPE = "mean"
```

5.4.1.10 pixel_size

```
list scale_space_plus_database_tracked.pixel_size
```

Initial value:

```
00001 = [
00002     130
00003 ]
```

5.4.1.11 rescale_pixel_size

```
list scale_space_plus_database_tracked.rescale_pixel_size
```

Initial value:

```
00001 = [
00002     10
00003 ]
```

5.4.1.12 subframes

```
list scale_space_plus_database_tracked.subframes
```

Initial value:

```
00001 = [
00002     10
00003 ]
```

5.4.1.13 t_strings

```
list scale_space_plus_database_tracked.t_strings
```

Initial value:

```
00001 = [
00002     "rpoc_ez"
00003 ]
```

5.4.1.14 total_frames

```
list scale_space_plus_database_tracked.total_frames
```

Initial value:

```
00001 = [
00002     5000
00003 ]
```

5.4.1.15 type_analysis_file

```
list scale_space_plus_database_tracked.type_analysis_file
```

Initial value:

```
00001 = [
00002     "new"
00003 ]
```

5.5 scale_space_plus_fixed_palm Namespace Reference

Classes

- class [Reconstruct_Fixed_PALM_DATASETS](#)
- class [Reconstruct_Masked_PALM_DATASETS](#)
- class [Reconstruct_Tracked_PALM_DATASETS_with_mask](#)

Functions

- [load_localizations](#) (localizations_path, skiprows=4)
- [load_localizations_TS](#) (localizations_path, skiprows=0)
- [pd.DataFrame get_unique_localizations](#) (pd.DataFrame localizations_df, str unique_loc_type="first")
- [pd.DataFrame get_unique_localizations_TS](#) (pd.DataFrame localizations_df, str unique_loc_type="first")
- [rescale_scale_space_blob_detection](#) (blobs, callable rescaling_func, **kwargs)

Variables

- int [CORRECTION_FACTOR](#) = 1.
- str [LOCALIZATION_UNIQUE_TYPE](#) = "mean"
- list [XY_NAMES](#) = ['x','y']
- list [global_path](#)
- dict [blob_parameters](#)
- dict [fitting_parameters](#)
- [sm_rec](#)

5.5.1 Detailed Description

Helper script to do the reconstruction and scale space blob detection along with the DBSCAN clustering on fixed scale space blobs. This is different from `scale_space_plus_database_tracked.py` since it enforces a cell mask for each cell in a movie.

```
#####
File structure:
```

```
-----
```

The file structure is as follows:

```
<main_path>
  /Movies
    /Movie_<01>
      /Cell_<cell_number>
        /localizations.csv
        /mask.tif
```

This is the base file structure for the PALM data. The script will look for the localizations and mask files in the following structure:

The localizations file needs to be in the form of TRACKMATE output from the GUI. TODO make it more general.

The objective of this script is to add the following files to the above structure: (new files and directories

```
<main_path>
  /Movies
    /Movie_<01>
      /Cell_<cell_number>
        /localizations.csv
        /mask.tif
        /reconstruction.tif #
        /uniform_reconstruction.tif #
        /normal_scale_projection.tif #
        /reconstruction_parameters.json #
      /Analysis #
        /scale_space_plus_blob_fitted.csv #
        /scale_space_plus_blob_scale.csv #
        /DBSCAN_clusters.csv #
        /analysis_parameters.json #
```

5.5.2 Function Documentation

5.5.2.1 get_unique_localizations()

```
pd.DataFrame scale_space_plus_fixed_palm.get_unique_localizations (
    pd.DataFrame localizations_df,
    str unique_loc_type = "first")
```

For each unique track_ID get the first localization or the mean value of all the localizations

Parameters:

```
localizations_df: pd.DataFrame
    The dataframe of the localizations
unique_loc_type: str
    The type of unique localization to get. Can be either "first" or "mean"
```

5.5.2.2 get_unique_localizations_TS()

```
pd.DataFrame scale_space_plus_fixed_palm.get_unique_localizations_TS (
    pd.DataFrame localizations_df,
    str unique_loc_type = "first")
```

For each unique track_ID get the first localization or the mean value of all the localizations

Parameters:

```
localizations_df: pd.DataFrame
    The dataframe of the localizations
unique_loc_type: str
    The type of unique localization to get. Can be either "first" or "mean"
```

5.5.2.3 load_localizations()

```
scale_space_plus_fixed_palm.load_localizations (
    localizations_path,
    skiprows = 4)
```

Load the localizations from the localizations.csv file

5.5.2.4 load_localizations_TS()

```
scale_space_plus_fixed_palm.load_localizations_TS (
    localizations_path,
    skiprows = 0)
```

Load the localizations from the localizations.csv file (ThunderSTORM format)

5.5.2.5 rescale_scale_space_blob_detection()

```
scale_space_plus_fixed_palm.rescale_scale_space_blob_detection (
    blobs,
    callable rescaling_func,
    ** kwargs)
```

5.5.3 Variable Documentation

5.5.3.1 blob_parameters

```
dict scale_space_plus_fixed_palm.blob_parameters
```

Initial value:

```
00001 = {
00002     "threshold": 2e-1, \
00003     "overlap": 0, \
00004     "median": False, \
00005     "min_sigma": 3/np.sqrt(2), \
00006     "max_sigma": 20/np.sqrt(2), \
00007     "num_sigma": 30, \
00008     "detection": 'bp', \
00009     "log_scale": False
00010 }
```

5.5.3.2 CORRECTION_FACTOR

```
int scale_space_plus_fixed_palm.CORRECTION_FACTOR = 1.
```

5.5.3.3 fitting_parameters

```
dict scale_space_plus_fixed_palm.fitting_parameters
```

Initial value:

```
00001 = {
00002     "mask_size":5,
00003     "plot_fit":False,
00004     "fitting_image":"LAP",
00005     "radius_func":np.mean,#identity,
00006     "residual_func":residuals_gaus2d,
00007     "sigma_range":4,
00008     "centroid_range":2,
00009     "height_range":1
00010 }
```

5.5.3.4 global_path

```
list scale_space_plus_fixed_palm.global_path
```

Initial value:

```
00001 = [  
00002     "/Users/baljyot/Documents/CODE/GitHub_t2/Baljyot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_rif_fixed_2"  
00003 ]
```

5.5.3.5 LOCALIZATION_UNIQUE_TYPE

```
str scale_space_plus_fixed_palm.LOCALIZATION_UNIQUE_TYPE = "mean"
```

5.5.3.6 sm_rec

```
scale_space_plus_fixed_palm.sm_rec
```

Initial value:

```
00001 = Reconstruct_Fixed_PALM_DATASETS(cd = global_path[i],  
00002                                     blob_parameters = blob_parameters,  
00003                                     fitting_parameters = fitting_parameters,  
00004                                     rescale_pixel_size = 10,  
00005                                     pixel_size = 130,  
00006                                     loc_error = 20,  
00007                                     include_all = False)
```

5.5.3.7 XY_NAMES

```
list scale_space_plus_fixed_palm.XY_NAMES = ['x', 'y']
```

5.6 SMT Namespace Reference

Namespaces

- namespace [SMT_Analysis_BP](#)

5.7 SMT.SMT_Analysis_BP Namespace Reference

Namespaces

- namespace [databases](#)
- namespace [helpers](#)
- namespace [Parameter_Store](#)

5.8 SMT.SMT_Analysis_BP.databases Namespace Reference

Namespaces

- namespace [data_path_container](#)
- namespace [directoryManipulator](#)
- namespace [structure_storage](#)
- namespace [trajectory_analysis_script](#)

5.9 SMT.SMT_Analysis_BP.databases.data_path_container Namespace Reference

Variables

- dict [rpoc_ez_paths_keywords](#)
- dict [rpoc_m9_paths_keywords](#)
- dict [rpoc_hex5_paths_keywords](#)
- dict [laci_laco_ez_paths_keywords](#)
- dict [laci_laco_m9_paths_keywords](#)
- dict [laci_laco_hex5_paths_keywords](#)
- dict [rpoc_rif_paths](#)
- dict [rpoc_ez_cluster_tracking_paths](#)
- dict [nusa_ez_paths_keywords](#)
- dict [nusa_m9_paths_keywords](#)
- dict [nusa_hex5_paths_keywords](#)
- dict [nusa_rif_paths_keywords](#)
- list [rpoc](#)
movie paths in volumes
- list [ll](#)

5.9.1 Variable Documentation

5.9.1.1 laci_laco_ez_paths_keywords

dict SMT.SMT_Analysis_BP.databases.data_path_container.laci_laco_ez_paths_keywords

Initial value:

```
00001 = { "LL_EZ":{
00002     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/EZ_120min/20190527/11_ez/
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/EZ_120min/20200217/11_ez/
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/EZ_120min/20200217/11_ez/
00005     }
00006 }
```


5.9.1.2 laci_laco_hex5_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.laci_laco_hex5_paths_keywords
```

Initial value:

```
00001 = {"LL_Hex5":{
00002     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/EZ_5min_5pHex/20200216/1.
00003 "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/EZ_5min_5pHex/20200216/1.
00004 "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/EZ_5min_5pHex/20200216/1.
00005     }
00006 }
```

5.9.1.3 laci_laco_m9_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.laci_laco_m9_paths_keywords
```

Initial value:

```
00001 = {"LL_M9":{
00002     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/M9/20200216/11_m9":{"t_st
00003 "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/M9/20200216/11_m9_2":{"t
00004 "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/LacI_LacO_DATA/M9/20200216/11_m9_3":{"t
00005     }
00006 }
```

5.9.1.4 ll

```
list SMT.SMT_Analysis_BP.databases.data_path_container.ll
```

Initial value:

```
00001 = [
00002     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/20190527/11_ez/Movie",
00003     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/20200217/11_ez/Movie",
00004     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/20200217/11_ez_2/Movie",
00005     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/16/11_m9/Movie",
00006     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/16/11_m9_2/Movie",
00007     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/16/11_m9_3/Movie",
00008     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/16/11_hex5/Movie",
00009     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/16/11_hex5_2/Movie",
00010     "/Volumes/Baljjot_HD/SMT_Olympus/Baljjot_temp/16/11_hex5_3/Movie"
00011 ]
```

5.9.1.5 nusa_ez_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.nusa_ez_paths_keywords
```

Initial value:

```
00001 = {"NUSA_EZ":{
00002     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_120min/20180907/Nusa_ez":{"t
00003 "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_120min/20190305/Nusa_ez":{"t
00004 "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_120min/20230619/Nusa_ez":{"t
00005     }
00006 }
```

5.9.1.6 nusa_hex5_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.nusa_hex5_paths_keywords
```

Initial value:

```
00001 = { "NUSA_Hex5":{
00002
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_5min_5pHex/15/nusa_ez_hex5",
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_5min_5pHex/15/nusa_ez_hex5",
00005     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_5min_5pHex/15/nusa_ez_hex5",
00006     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_5min_5pHex/16/nusa_ez_hex5",
00007     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/EZ_5min_5pHex/16/nusa_ez_hex5",
00008 }
```

5.9.1.7 nusa_m9_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.nusa_m9_paths_keywords
```

Initial value:

```
00001 = { "NUSA_M9":{
00002
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/M9/12/nusa_m9":{"t_string":"n"},
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/M9/12/nusa_m9_2":{"t_string":"n"},
00005     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/M9/20191216/nusa_m9":{"t_string":"n"},
00006     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/M9/20191218/nusa_m9":{"t_string":"n"},
00007 }
```

5.9.1.8 nusa_rif_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.nusa_rif_paths_keywords
```

Initial value:

```
00001 = { "NUSA_RIF":{
00002
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/100ugm1_5min_RIF/20230528/nusa_rif",
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/100ugm1_5min_RIF/20230618/nusa_rif",
00005     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/NUSA_DATA/100ugm1_5min_RIF/20230618/nusa_rif",
00006 }
```

5.9.1.9 rpoc

```
list SMT.SMT_Analysis_BP.databases.data_path_container.rpoc
```

Initial value:

```
00001 = [
00002     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/20190527/rpoc_ez/Movie",
00003     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/20181003/Movie",
00004     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/20180813/RPOC/Movie",
00005     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/20190515/Movie",
00006     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/12/rpoc_m9/Movie",
00007     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/12/rpoc_m9_2/Movie",
00008     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/15/rp_ez_hex5/Movie",
00009     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/15/rp_ez_hex5_2/Movie",
00010     "/Volumes/Baljjyot_HD/SMT_Olympus/Baljjyot_temp/16/rp_ez_hex5/Movie"
00011 ]
```

movie paths in volumes

5.9.1.10 rpoc_ez_cluster_tracking_paths

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_ez_cluster_tracking_paths
```

Initial value:

```
00001 = {"RPOC_EZ_CLUSTER_TRACKING":{
00002     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_CLUSTER_TRACKING/20231009":{"t_str":
00003     }
00004 }
```

5.9.1.11 rpoc_ez_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_ez_paths_keywords
```

Initial value:

```
00001 = {"RPOC_EZ":{
00002     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/EZ_120min/20180813/Other_RPOC":
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/EZ_120min/20181003/RPOC_new":
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/EZ_120min/20190527/rpoc_ez":{
00005     }
00006 }
```

5.9.1.12 rpoc_hex5_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_hex5_paths_keywords
```

Initial value:

```
00001 = {"RPOC_Hex5":{
00002     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/EZ_5min_5pHex/20200215/rp_ez_5p":
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/EZ_5min_5pHex/20200215/rp_ez_5p":
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/EZ_5min_5pHex/20200216/rp_ez_5p":
00005     }
00006 }
```

5.9.1.13 rpoc_m9_paths_keywords

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_m9_paths_keywords
```

Initial value:

```
00001 = {"RPOC_M9":{
00002     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/M9/20200212/rpoc_m9":{"t_str":
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/M9/20200212/rpoc_m9_2":{"t_str":
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/M9/20190515/rpoc_m9":{"t_str":
00005     }
00006 }
```

5.9.1.14 rpoc_rif_paths

```
dict SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_rif_paths
```

Initial value:

```
00001 = {"RPOC_RIF":{
00002     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/100ugm1_5min_RIF/20230528/rpoc_rif":
00003     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/100ugm1_5min_RIF/20230617/rpoc_rif":
00004     "/Users/baljjyot/Documents/CODE/GitHub_t2/Baljjyot_EXP_RPOC/DATA/SMT_FAST_CAPTURE/RPOC_DATA/100ugm1_5min_RIF/20230617/rpoc_rif":
00005     }
00006 }
```

5.10 SMT.SMT_Analysis_BP.databases.directoryManipulator Namespace Reference

Namespaces

- namespace [format_mask_structure](#)
- namespace [tifanal](#)

5.11 SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure Namespace Reference

Classes

- class [movie_mask_directory_structure_manager](#)

Functions

- [read_npy_file](#) ([path](#), [correct_dtype=True](#))
- dict [obtain_masks_npy](#) ([np_output_file](#))
- None [_reorder_file_names](#) ([file_paths](#), [end_string=None](#))

Variables

- list [path](#)
testing
- [mask_dir](#) = [movie_mask_directory_structure_manager](#)([path](#))

5.11.1 Detailed Description

Helper script to find all the masks in a directory and format them into a directory structure

The directory structure is as follows:

```
-parent_dir
  -full_path_to_mask_dir

  -Movies
    -Movie_1
      -IMAGEJ_ROI.zip
      -Cell_1
        -mask.tif
```

This is repeated for each movie defined by the number of mask files found.

The cells are determined by the number of unique masks found in each mask file.

The IMAGEJ_ROI.zip file is the ROI file that works for input into ImageJ for further analysis

5.11.2 Function Documentation

5.11.2.1 _reorder_file_names()

None SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure._reorder_file_names (

```
    file_paths,
    end_string = None) [protected]
```

Reorders the names of the files to start from 1->end.
Given a set of files in the directory, it will reorder them to start from 1->end
so <name>_20.tif will be <name>_1.tif, <name>_21.tif will be <name>_2.tif and so on
This is to rename the file

5.11.2.2 obtain_masks_npy()

dict SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.obtain_masks_npy (

```
    npy_output_file)
```

Obtains the masks from the npy file

5.11.2.3 read_npy_file()

SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.read_npy_file (

```
    path,
    correct_dtype = True)
```

Reads the npy file from the path

5.11.3 Variable Documentation

5.11.3.1 mask_dir

SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.mask_dir = [movie_mask_directory_struct](#)

5.11.3.2 path

list SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.path

Initial value:

```
00001 = [
00002     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231015/1l_ez/TS/gfp",
00003     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231017/1l_hex5_fixed/TS/gfp",
00004     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_ez_fixed/TS/gfp",
00005     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_ez_fixed_2/TS/gfp",
00006     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_hex5_fixed/TS/gfp",
00007     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_hex5_fixed_2/TS/gfp",
00008     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_m9_fixed/TS/gfp",
00009     "/Users/baljjot/Documents/CODE/GitHub_t2/Baljjot_EXP_RPOC/DATA/Fixed_100ms/20231017/rp_rif_fixed/TS/gfp"
00010 ]
```

testing

5.12 SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal Namespace Reference

Variables

- dict [SEGMENT_TYPE](#)
- int [STACK_STEP](#) = 5
- int [CONVERT_NAME](#) = 1
- str [DIR_PATH](#) = "/Volumes/Baljyot_HD/SMT_Olympus/RIF_TREATMET_LIVE/20230528/Movie"
- root = tk.Tk()
- filez = fd.askopenfilenames(parent=[root](#), title='Choose [a](#) file', initialdir=[DIR_PATH](#))
- root_dir = os.path.dirname([filez](#)[0])
- sorted_a_files = sorted([filez](#),key=lambda x: int(x.split("/")[-1].split(".")[0].split("_")[-1]))
- temp_im = io.imread([sorted_a_files](#)[i])
- temp_del = [temp_im](#)[:]
- length = int(len([temp_del](#))/[STACK_STEP](#))
- list hold_img = []
- list hold_name = []
- movie_name = [sorted_a_files](#)[i].split("/")[-1].split(".")[0]
- updated_movie_name = movie_name.split("_")[:-1]

5.12.1 Variable Documentation

5.12.1.1 CONVERT_NAME

```
int SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.CONVERT_NAME = 1
```

5.12.1.2 DIR_PATH

```
str SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.DIR_PATH = "/Volumes/Baljyot_↵
HD/SMT_Olympus/RIF_TREATMET_LIVE/20230528/Movie"
```

5.12.1.3 filez

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.filez = fd.askopenfilenames(parent=root,
title='Choose a file', initialdir=DIR\_PATH)
```

5.12.1.4 hold_img

```
list SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.hold_img = []
```

5.12.1.5 hold_name

```
list SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.hold_name = []
```

5.12.1.6 length

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.length = int(len(temp_del)/STACK_STEP)
```

5.12.1.7 movie_name

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.movie_name = sorted_a_files[i].split("/")[-1].split
```

5.12.1.8 root

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.root = tk.Tk()
```

5.12.1.9 root_dir

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.root_dir = os.path.dirname(filez[0])
```

5.12.1.10 SEGMENT_TYPE

```
dict SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.SEGMENT_TYPE
```

Initial value:

```
00001 = {  
00002     "mean":np.mean,  
00003     "median":np.median,  
00004     "max":np.max,  
00005     "min":np.min,  
00006     "sum":np.sum,  
00007     "std":np.std  
00008 }
```

5.12.1.11 sorted_a_files

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.sorted_a_files = sorted(filez,key=lambda  
x:  int(x.split("/")[-1].split(".")[0].split("_")[-1]))
```

5.12.1.12 STACK_STEP

```
int SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.STACK_STEP = 5
```

5.12.1.13 temp_del

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.temp_del = temp_im[:]
```

5.12.1.14 temp_im

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.temp_im = io.imread(sorted_a_files[i])
```

5.12.1.15 updated_movie_name

```
str SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.updated_movie_name = movie_↵
name.split("_")[:-1]
```

5.13 SMT.SMT_Analysis_BP.databases.structure_storage Namespace Reference

Variables

- dict [SEGMENTATION_FOLDER_TYPES](#)
FOLDER STRUCTURES #####.
- dict [ANALYSIS_FOLDER_TYPES](#)
- dict [LOADING_DROP_BLOB_TYPES](#)

5.13.1 Detailed Description

Collection of structured data for utility. Mainly used within trajectory_analysis_script.py and scale_scale_pl

5.13.2 Variable Documentation

5.13.2.1 ANALYSIS_FOLDER_TYPES

```
dict SMT.SMT_Analysis_BP.databases.structure_storage.ANALYSIS_FOLDER_TYPES
```

Initial value:

```
00001 = {
00002     "TRACKMATE": "Analysis",
00003     "Scale": "Analysis",
00004     "Fitted": "Analysis",
00005     "SCALE_SPACE_PLUS": "Analysis",
00006     "DBSCAN": "Analysis_DBSCAN"
00007 }
```

5.13.2.2 LOADING_DROP_BLOB_TYPES

```
dict SMT.SMT_Analysis_BP.databases.structure_storage.LOADING_DROP_BLOB_TYPES
```

Initial value:

```
00001 = {
00002     "TRACKMATE": True,
00003     "Scale": False,
00004     "Fitted": False,
00005     "SCALE_SPACE_PLUS": True,
00006     "DBSCAN": True
00007 }
```


5.13.2.3 SEGMENTATION_FOLDER_TYPES

```
dict SMT.SMT_Analysis_BP.databases.structure_storage.SEGMENTATION_FOLDER_TYPES
```

Initial value:

```
00001 = {
00002     "TRACKMATE": "Segmented",
00003     "Scale": "Segmented_mean",
00004     "Fitted": "Segmented_mean",
00005     "SCALE_SPACE_PLUS": "segmented_scale_space_plus",
00006     "DBSCAN": "segmented_scale_space_plus"
00007 }
```

FOLDER STRUCTURES #####.

5.14 SMT.SMT_Analysis_BP.databases.trajectory_analysis_script Namespace Reference

Classes

- class [boundary_analysis](#)
- class [Cell](#)
- class [Movie_frame](#)
- class [run_analysis](#)
- class [Trajectory](#)
- class [Trajectory_Drop_Mapping](#)

Variables

- list [TRACK_TYPES](#)

5.14.1 Detailed Description

Documentation for trajectory_analysis_script.py

This script is used to analyse the data from the trajectory analysis script

It does this by reading the data from the trajectory analysis script and then making mappings of the SMT data

The core of the script is the run_analysis class, which is used to analyse a single dataset

Each database in a given experiment is analysed by a separate instance of this class

Each instance of this class is initialised with the working directory and the unique string identifier for the

The mapping of the SMT data to drops and cells is done by the analyse_cell_tracks method among others

The core mapping is as follows:

Movies -> Cells -> Drops -> Trajectories

The class also contains methods to plot the data and to save the data to a .mat file

The script also contains a number of helper functions that are used by the class

These are mostly used to read the data from the trajectory analysis script and to plot the data and make class

The script also contains a number of functions that are used to analyse the data

These are mostly used to analyse the data and to plot the data and make classifications

Classes:

1. run_analysis: class for each dataset to analyse
2. Movie_frame: class for each frame of view in a movie
3. Cell: class for each cell in a frame of view
4. Drop: class for each drop in a cell
5. Trajectory: class for each trajectory in a drop
6. Trajectory_Drop_Mapping: class for each mapping of a trajectory to a drop
7. boundary_analysis: class for each boundary analysis of a dataset

Author: Baljot Singh Parmar

5.14.2 Variable Documentation

5.14.2.1 TRACK_TYPES

```
list SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.TRACK_TYPES
```

Initial value:

```
00001 = [
00002     "IN",
00003     "IO",
00004     "OUT",
00005     "ALL"
00006 ]
```

5.15 SMT.SMT_Analysis_BP.helpers Namespace Reference

Namespaces

- namespace [analysisFunctions](#)
- namespace [clusterMethods](#)
- namespace [ioModule](#)
- namespace [misc](#)

5.16 SMT.SMT_Analysis_BP.helpers.analysisFunctions Namespace Reference

Namespaces

- namespace [Analysis_functions](#)
- namespace [angle_between_vectors](#)
- namespace [bootstrap_util](#)
- namespace [dir_invert_images](#)
- namespace [features_from_mask](#)
- namespace [MSD_Utils](#)
- namespace [NND](#)
- namespace [nucleoid_detection](#)
- namespace [scale_space_plus](#)
- namespace [smallestenclosingcircle](#)

5.17 SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_↵ functions Namespace Reference

Functions

- [non_linear_curvefit](#) (func, xdata, ydata, p0=None, method='lm', bounds=None)
RANDOM FITTING FUNCTIONS #####
- [linear_fitting](#) (xdata, ydata, deg=1)
- [gaus1D](#) (x, a, b, c)
- [gaus2D](#) (x, a, b, c, a1, b1, c1)

- [gaussian_fit](#) (x, p0, p1, p2)
- [Thompson_localization_precision](#) (float psf_sigma, float pixel_size, float|np.ndarray num_photons, float background_photons)
- [rayleigh_corr](#) (x, corr, sigma, A)
- [nnd_correction_rayleigh](#) (x, sigma, xc, w, a1, a2, a3)
- [cum_sum](#) (data, binz=10)

RANDOM UTILITY FUNCTIONS #####

- [rescale](#) (x, a, b)
- [dif_dis](#) (x, y)
- [dist](#) (x, y, c1, c2)
- [d_to_rad](#) (deg_)
- [rad_to_d](#) (rad_)
- [cm_normal](#) (x, y)
- [con_pix_si](#) (data, con_nm=0.130, con_ms=20., which=0)
- float [radius_of_gyration](#) (*args)
- [photon_conversion_from_AUD](#) (float|np.ndarray AUD, float|int photon_conversion_factor, float|int quantum↔_efficiency, float|int dark_offset)
- [bin_ndarray](#) (ndarray, new_shape, operation='sum')
- [bin_img](#) (img, bin=2, operation='sum')
- [convert_3d_to_2d](#) (a)
- [point_inside_circle2D](#) (circle, point)
- [reshape_col2d](#) (arr, permutations)
- [range_distance](#) (a, b)
- [rt_to_xy](#) (r, theta)
- [pad_array](#) (subarray, shape, top_left_coord, pad=0)
- [sorted_alphanumeric](#) (data)
- [subarray2D](#) (arr, mask, full=True, transpose=True)
- [flatten](#) (t)
- [rescale_range](#) (x, min_x, max_x, a, b)
- [dic_union_two](#) (dic_1, dic_2)

MSD calculations for sim data format of dict #####

- [MSD_tavg1](#) (x, y, f, f_inc=False)
- [MSD_tavg](#) (x, y, f, f_inc=False)
- [MSD_tavg_single](#) (x, f, f_inc=False)
- [track_decomp](#) (x, y, f, max_track_decomp)
- [fit_MSD_loc_err](#) (t, p_0, p_1, p_2)
- [fit_MSD](#) (t, p_0, p_1, p_2)
- [fit_MSD_Linear](#) (t, p_0, p_1)
- [find_diffusion_coefficient](#) (time, distance, dim)
- [find_static_localization_error_MSD](#) (sigma, dim)
- [_random_starting_point](#) (start, end)
- [squared_mean_difference](#) (a)
- [point_per_frame_difference](#) (true_points_per_frame, extracted_points_per_frame)

Track percent identity functions #####

- [percent_error](#) (true, estimate, abs=True)
- [_point_identity](#) (point_true, track_estimate, distance_threshold)
- [identity_tracks](#) (track_true, track_estimate, **kwargs)
- [identity_track_matrix](#) (tracks_true, tracks_estimate, verbose=True, **kwargs)
- [point_error_detection](#) (true_points, extracted_points, threshold=0.5)
- [points_per_frame_convert](#) (tracks)
- dict [points_per_frame_bulk_sort](#) (np.ndarray x, np.ndarray y, np.ndarray t)
- [convert_point_pairs](#) (tracks)
- [point_pair_error_detection](#) (true_point_pairs, extracted_point_pairs, threshold=0.5)
- dict [area_points_per_frame](#) (dict points_per_frame, callable area_func=[radius_of_gyration](#))
- [convex_hull_area](#) (points)

5.17.1 Detailed Description

This module contains a collection of functions for analysis

Some of the functions are old and not used anymore, but I am keeping them here for now

Author: Baljyot Singh Parmar

5.17.2 Function Documentation

5.17.2.1 `_point_identity()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions._point_identity (
    point_true,
    track_estimate,
    distance_threshold) [protected]
```

Documentation for `_point_identity`

Parameters:

```
point_true : array
    true point, shape (,2)
track_estimate : array
    estimated track, shape (n,2)
distance_threshold : float
    distance threshold for the point to be considered a match
```

Returns:

```
1 : int
    if the point is within the distance threshold
0 : int
    if the point is not within the distance threshold
```

Notes:

1. Assumes that the tracks and points are formatted as `[[x,y,T],[x,y,T],...,[x,y,T]]` numpy arrays and `[x,y,T]`

5.17.2.2 `_random_starting_point()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions._random_starting_point (
    start,
    end) [protected]
```

5.17.2.3 `area_points_per_frame()`

```
dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.area_points_per_frame (
    dict points_per_frame,
    callable area_func = radius_of_gyration)
```

Parameters:

```
points_per_frame : dict
    dictionary of points per frame, keys are the frame number and the values are the points in that frame of s
area_func : callable
    function to calculate the area of the points per frame, default is radius of gyration
```

Returns:

```
area_per_frame : dict
    dictionary of area per frame, keys are the frame number and the values are the area of the points in that
```

5.17.2.4 bin_img()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.bin_img (
    img,
    bin = 2,
    operation = 'sum')
```

Docstring for bin_img

Parameters:

```
img : numpy array
    The image to be binned
bin : int, optional (default=2)
    The binning factor, this is the number of pixels to be binned together for each axis
operation : str, optional (default='sum')
    The operation to be performed on the pixels, can be 'sum' or 'mean'
```

Returns:

```
numpy array
    The binned image of shape (img.shape[0]//bin,img.shape[1]//bin)
```

5.17.2.5 bin_ndarray()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.bin_ndarray (
    ndarray,
    new_shape,
    operation = 'sum')
```

Docstring for bin_ndarray

Bins an ndarray in all axes based on the target shape, by summing or averaging.

Parameters:

```
ndarray : numpy array
    The array to be binned
new_shape : tuple
    The shape of the output array
operation : str, optional (default='sum')
    The operation to be performed on the pixels, can be 'sum' or 'mean'
```

Returns:

```
numpy array
    The binned array of shape new_shape
```

Raises:

ValueError

If the operation is not 'sum' or 'mean'

ValueError

If the number of dimensions of the input array does not match the length of the new_shape tuple

Examples:

```
>>> m = np.arange(0,100,1).reshape((10,10))
>>> n = bin_ndarray(m, new_shape=(5,5), operation='sum')
>>> print(n)
[[ 22  30  38  46  54]
 [102 110 118 126 134]
 [182 190 198 206 214]
 [262 270 278 286 294]
 [342 350 358 366 374]]
```

5.17.2.6 cm_normal()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.cm_normal (
    x,
    y)
```

5.17.2.7 con_pix_si()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.con_pix_si (
    data,
    con_nm = 0.130,
    con_ms = 20.,
    which = 0)
```

5.17.2.8 convert_3d_to_2d()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.convert_3d_to_2d (
    a)
```

5.17.2.9 convert_point_pairs()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.convert_point_pairs (
    tracks)
```

Docstring for convert_point_pairs

Convert a track dictionary to a point pair dictionary where the keys is a combination of the two frames of the point pairs are defined as consecutive points in a track.

eg: track = [[x1,y1,frame1],[x2,y2,frame2],[x3,y3,frame3]]

point_pairs = {"frame1,frame2":[[x1,y1,frame1],[x2,y2,frame2]], "frame1,frame2":[[x2,y2,frame2],[x3,y3,frame3]]}

Parameters:

tracks : dict, keys are track numbers and values are tracks as defined above

dictionary of tracks where the keys are the track numbers and the values are the tracks

Returns:

point_pairs : dict, keys is a combination of the two frames of the points are point pairs as defined above

dictionary of point pairs where the keys is a combination of the two frames of the points and the values are the point pairs

5.17.2.10 convex_hull_area()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.convex_hull_area (
    points)
```

Docstring for convex_hull_area

Calculate the convex hull area of a set of points

Parameters:

points : numpy array of shape (n,2)

points to calculate the convex hull area

Returns:

hull_points : numpy array of shape (n,2)

convex hull area of the input points

5.17.2.11 cum_sum()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.cum_sum (
    data,
    binz = 10)
```

RANDOM UTILITY FUNCTIONS #####.

5.17.2.12 d_to_rad()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.d_to_rad (
    deg_)
```

5.17.2.13 dic_union_two()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.dic_union_two (
    dic_1,
    dic_2)
```

MSD calculations for sim data format of dict #####.

Documentation for dic_union_two
Find the unique union of two dictionaries, assumes the values are lists

Parameters:

```
-----
dic_1 : dict
        dictionary 1
dic_2 : dict
        dictionary 2
```

Returns:

```
-----
dic_union : dict
            dictionary of the unique union of the two dictionaries
```

Notes:

The values of the dictionaries must be lists for the list concatenation to work properly

This function turns the values of the dictionaries into lists, if arrays are needed then the values must be converted to arrays

5.17.2.14 dif_dis()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.dif_dis (
    x,
    y)
```

5.17.2.15 dist()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.dist (
    x,
    y,
    c1,
    c2)
```

Distance(s) x,y away from a point c1,c2 in 2D

5.17.2.16 find_diffusion_coefficient()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.find_diffusion_coefficient (
    time,
    distance,
    dim)
```

Docstring for find_diffusion_coefficient

This function finds the diffusion coefficient given a time and distance, this is just a simple calculation:
 $D = (1/(2 \cdot \text{dim})) \cdot (\text{distance})^2 / \text{time}$

Parameters:

```
-----
time : array-like or int or float
    The time
distance : array-like or int or float
    The distance
dim : int
    The dimensionality of the system
```

Returns:

```
-----
float or numpy array
    The diffusion coefficient, units are based on the units of the input parameters (time and distance, ie: um
```

5.17.2.17 find_static_localization_error_MSD()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.find_static_localization_↵
error_MSD (
    sigma,
    dim)
```

Docstring for find_static_localization_error_MSD

Given the isotropic gaussian scale (sigma), this function finds the static localization error (sigma_loc) using
 $\text{sigma_loc} = 2n \cdot (\text{sigma})^2$

Parameters:

```
-----
sigma : array-like or int or float
    The isotropic gaussian scale
dim : int
    The dimensionality of the system
```

Returns:

```
-----
float or numpy array
    The static localization error
```

5.17.2.18 fit_MSD()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.fit_MSD (
    t,
    p_0,
    p_1,
    p_2)
```


5.17.2.19 fit_MSD_Linear()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.fit_MSD_Linear (
    t,
    p_0,
    p_1)
```

5.17.2.20 fit_MSD_loc_err()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.fit_MSD_loc_err (
    t,
    p_0,
    p_1,
    p_2)
```

5.17.2.21 flatten()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.flatten (
    t)
```

function to flatten a list of any dimension (arbitrary sublist dimension)

Parameters

t : list
list of any size

Returns

list
flattened list along all dimensions of t.

5.17.2.22 gaus1D()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.gaus1D (
    x,
    a,
    b,
    c)
```

5.17.2.23 gaus2D()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.gaus2D (
    x,
    a,
    b,
    c,
    a1,
    b1,
    c1)
```

5.17.2.24 gaussian_fit()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.gaussian_fit (
    x,
    p0,
    p1,
    p2)
```

5.17.2.25 identity_track_matrix()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.identity_track_matrix (
    tracks_true,
    tracks_estimate,
    verbose = True,
    ** kwargs)
```

Documentation for identity_track_matrix

This creates all unique combinations of tracks and then finds the identity between each pair

Parameters:

tracks_true : dict

dict of true tracks, shape (n,2). Key is the track number, value is the track

tracks_estimate : dict

dict of estimated tracks, shape (m,2). Key is the track number, value is the track

verbose : bool

if True then return all the identity matrices, if False then only return the per track results

Returns:

max_identity : array

array of the maximum identity between each true track and the estimated tracks

length_error : array

array of the percent error between the lengths of each true track and the estimated tracks

identity_matrix : array

matrix of the identity between each pair of tracks

length_error_matrix : array

matrix of the percent error between the lengths of each pair of tracks

Notes:

5.17.2.26 identity_tracks()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.identity_tracks (
    track_true,
    track_estimate,
    ** kwargs)
```

Documentation for identity_tracks

Parameters:

track_true : array

true track, shape (n,2)

track_estimate : array

estimated track, shape (m,2), m can be different than n

threshold : float

distance threshold for the point to be considered a match

Returns:

```
mean_point_identity : float
    mean percent identity between the points in the true track and the estimated track
length_error : float
    percent error between the lengths of the tracks
```

Notes:

1. Assumes that the tracks and points are formatted as `[[x,y,T],[x,y,T],...,[x,y,T]]` numpy arrays and `[x,y,T]`
2. Assumes that the true track is not empty
3. Assumes that the estimated track is not empty

5.17.2.27 linear_fitting()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.linear_fitting (
    xdata,
    ydata,
    deg = 1)
```

Docstring for linear_fitting

This function performs a linear fit to the data using polyfit

Parameters:

```
xdata : numpy array
    The x data
ydata : numpy array
    The y data
deg : int, optional (default=1)
    The degree of the polynomial to be fitted
```

Returns:

```
numpy array with 2 elements
    1. The polynomial coefficients
    2. The covariance matrix
```

5.17.2.28 MSD_tavg()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.MSD_tavg (
    x,
    y,
    f,
    f_inc = False)
```

5.17.2.29 MSD_tavg1()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.MSD_tavg1 (
    x,
    y,
    f,
    f_inc = False)
```

5.17.2.30 MSD_tavg_single()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.MSD_tavg_single (
    x,
    f,
    f_inc = False)
```

5.17.2.31 nnd_correction_rayleigh()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.nnd_correction_rayleigh (
    x,
    sigma,
    xc,
    w,
    a1,
    a2,
    a3)
```

5.17.2.32 non_linear_curvefit()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.non_linear_curvefit (
    func,
    xdata,
    ydata,
    p0 = None,
    method = 'lm',
    bounds = None)
```

RANDOM FITTING FUNCTIONS #####.

Docstring for non_linear_curvefit
This function fits a curve to the data using `scipy.optimize.curve_fit`

Parameters:

```
func : function
    The function to be fitted to the data
xdata : numpy array
    The x data
ydata : numpy array
    The y data
p0 : numpy array, optional (default=None)
    The initial guess for the parameters
method : str, optional (default='lm')
    The method to be used for the curve fitting, can be 'lm' or 'trf' or 'dogbox'
bounds : tuple, optional (default=None)
    The lower and upper bounds for the parameters
```

Returns:

```
tuple
    The fitted parameters and the covariance matrix
```

5.17.2.33 pad_array()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.pad_array (
    subarray,
    shape,
    top_left_coord,
    pad = 0)
```

Parameters

subarray : 2D array-like
array to pad

shape : tuple, list, array-like of length 2
2D shape of the full array

top_left_coord : list, array-like of length 2
coordinate of the top left corner of the subarray in the full array of shape

Returns

array-like 2D
returns the full array of with size shape entries of the subarray are inputted relative to top_left_coord padded with 0s

5.17.2.34 percent_error()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.percent_error (
    true,
    estimate,
    abs = True)
```

Documentation for percent_error

Parameters:

true : float
true value

estimate : float
estimated value

abs : bool (default = True)
if abs == True then the absolute value of the percent error is returned

Returns:

percent_error : float
percent error between the true and estimated values

Notes:

1. Assumes that the true and estimated values are floats
2. Assumes that the true value is not zero
3. Assumes that the true value is not negative
4. Assumes that the true value is not NaN
5. Assumes that the estimated value is not NaN

5.17.2.35 photon_conversion_from_AUD()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.photon_conversion_from_AUD (
    float|np.ndarray AUD,
    float|int photon_conversion_factor,
    float|int quantum_efficiency,
    float|int dark_offset)
```

Converting from AUD to photons for a CMOS camera using the formula:
 $\text{photons} = (\text{AUD} - \text{dark_offset}) * \text{photon_conversion_factor} / \text{quantum_efficiency}$

Parameters:

AUD : float or numpy array

The AUD values

photon_conversion_factor : float or int

The photon conversion factor

quantum_efficiency : float or int

The quantum efficiency at a wavelength for the detector (from 0-1, ie 0% - 100%)

5.17.2.36 point_error_detection()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_error_detection (
    true_points,
    extracted_points,
    threshold = 0.5)
```

Docstring for point_error_detection

Calculate the error between the true points and the extracted points per frame

Parameters:

true_points : dict

dictionary of true points where the keys are the frame numbers and the values are the true points in that

extracted_points : dict

dictionary of extracted points where the keys are the frame numbers and the values are the extracted point

threshold : float

threshold for the distance between the true points and the extracted points

Returns:

percent_detected : float

percent of the true points that are detected

5.17.2.37 point_inside_circle2D()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_inside_circle2D (
    circle,
    point)
```

Check if a point is inside a circle

Parameters:

circle : tuple

(x,y,radius) of the circle

point : tuple

(x,y) of the point

Returns:

bool

True if the point is inside the circle, False otherwise

Raises:

TypeError

If circle or point are not tuples

TypeError

```

    If circle or point are not tuples of length 3 and 2 respectively
TypeError
    If circle or point are not tuples of numbers
ValueError
    If the radius of the circle is not positive

Examples:
-----
>>> point_inside_circle2D((0,0,1),(0,0))
True
>>> point_inside_circle2D((0,0,1),(0,1))
False

Notes:
-----
1. This function is not vectorized, so it will not work with numpy arrays
2. This function is not robust to floating point errors

```

5.17.2.38 point_pair_error_detection()

```

SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_pair_error_detection (
    true_point_pairs,
    extracted_point_pairs,
    threshold = 0.5)

```

Docstring for point_pair_error_detection

Calculate the error between the true point pairs and the extracted point pairs per frame

```
point_pairs = {"frame1,frame2":[[x1,y1,frame1],[x2,y2,frame2]], "frame1,frame2":[[x2,y2,frame2],[x3,y3,frame3]]}
```

Parameters:

```

-----
true_point_pairs : dict, keys is a combination of the two frames of the points are point pairs as defined above
    dictionary of true point pairs where the keys is a combination of the two frames of the points and the value
extracted_point_pairs : dict, keys is a combination of the two frames of the points are point pairs as defined above
    dictionary of extracted point pairs where the keys is a combination of the two frames of the points and the value
threshold : float
    threshold for the distance between the true point pairs and the extracted point pairs

```

Returns:

```

-----
percent_detected : float
    percent of the true point pairs that are detected
mismatch_error : float
    percent of true detected point pairs over the total amount of extracted pairs

```

5.17.2.39 point_per_frame_difference()

```

SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_per_frame_difference (
    true_points_per_frame,
    extracted_points_per_frame)

```

Track percent identity functions #####.

Documentation for point_per_frame_difference

Finds the closest point in the extracted points per frame to the true points per frame and returns the difference for each such point in each frame

Parameters:

```

-----
true_points_per_frame : dict
    dictionary of the true points per frame, key = frame number, value = array of points, shape (n,2)
extracted_points_per_frame : dict
    dictionary of the extracted points per frame, key = frame number, value = array of points, shape (n,2)

```

Returns:

```

-----

```

5.17.2.40 points_per_frame_bulk_sort()

```
dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.points_per_frame_bulk_↵
sort (
    np.ndarray x,
    np.ndarray y,
    np.ndarray t)
```

Utility function, shouldn't be needed.

Sorts points by frame number. The output should be a dict with keys of frame numbers and values of points in t

Parameters:

```
x : np.ndarray
    x coordinates of points
y : np.ndarray
    y coordinates of points
t : np.ndarray
    frame numbers of points
```

Returns:

```
points_per_frame : dict
    dictionary of points per frame where the keys are the frame numbers and the values are the points in that
```

5.17.2.41 points_per_frame_convert()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.points_per_frame_convert (
    tracks)
```

Docstring for points_per_frame_convert

Take a track dictionary and convert it to a points per frame dictionary where the keys are the frame numbers a

Parameters:

```
tracks : dict
    dictionary of tracks where the keys are the track numbers and the values are the tracks
```

Returns:

```
points_per_frame : dict
    dictionary of points per frame where the keys are the frame numbers and the values are the points in that
```

5.17.2.42 rad_to_d()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rad_to_d (
    rad_)
```


5.17.2.43 radius_of_gyration()

```
float SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.radius_of_gyration (
    * args)
```

Determine the radius of gyration of a particle given its *x,y* coordinates.
 If only one argument is given, it is assumed to be a 2D array of *x,y* coordinates.
 If two arguments are given, they are assumed to be *x,y* coordinates.

Parameters:

```
*args : array-like
    if one argument is given, it is assumed to be a 2D array of x,y coordinates. (N,2)
    if two arguments are given, they are assumed to be x,y coordinates. (N,),(N,)
```

Returns:

```
r_g: float
    radius of gyration of particles
```

Raises:

```
ValueError
    if the number of arguments is not 1 or 2
```

5.17.2.44 range_distance()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.range_distance (
    a,
    b)
```

Docstring for range_distance

Parameters:

```
a : float
    The first number
b : float
    The second number
```

Returns:

```
float
    The distance between the two numbers
```

5.17.2.45 rayleigh_corr()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rayleigh_corr (
    x,
    corr,
    sigma,
    A)
```

5.17.2.46 rescale()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rescale (
    x,
    a,
    b)
```

5.17.2.47 rescale_range()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rescale_range (
    x,
    min_x,
    max_x,
    a,
    b)
```

<https://stats.stackexchange.com/questions/281162/scale-a-number-between-a-range>

5.17.2.48 reshape_col2d()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.reshape_col2d (
    arr,
    permutations)
```

Docstring for reshape_col2d

This function reshapes a 2D array by permuting the columns in the order specified by permutations

Parameters:

arr : numpy array

The array to be reshaped

permutations : list of integers

The permutations to be applied to the columns of arr

Returns:

numpy array

The reshaped array

NOTES:

Sometimes this breaks i have no idea why. Use with caution

5.17.2.49 rt_to_xy()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rt_to_xy (
    r,
    theta)
```

Docstring for rt_to_xy

Parameters:

r : float

The radial coordinate

theta : float

The angular coordinate

Returns:

tuple

The x and y coordinates

5.17.2.50 sorted_alphanumeric()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.sorted_alphanumeric (
    data)
```

5.17.2.51 squared_mean_difference()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.squared_mean_difference (
    a)
```

5.17.2.52 subarray2D()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.subarray2D (
    arr,
    mask,
    full = True,
    transpose = True)
```

Gives a new array from a 2D defined by mask. Assumes mask is [n,m]

Parameters

```
-----
arr : 2D numpy array-like
      original array to be zoomed
mask : 2D numpy array-like
      2D mask defining the corners of the box to make the subarray
full : bool
      if True return the full size array with 0 entry anywhere not in the subarray
      else return a new array defined by the mask
transpose : bool
      if true transpose the mask before subindexing
      else use mask as is
```

Returns

```
-----
numpy array-like
      subarray defined using the mask.
      array is same shape as original with 0 values outside subarray if full = True
```

Notes

```
-----
Assumes mask is the same shape or smaller than the input array
```

5.17.2.53 Thompson_localization_precision()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.Thompson_localization_↵
precision (
    float psf_sigma,
    float pixel_size,
    float|np.ndarray num_photons,
    float background_photons)
```

Theory from Thompson et al. 2002 (Precise Nanometer Localization Analysis for Individual Fluorescent Probes)
 For a gaussian PSF, the localization precision is given by:

$$\sigma_{loc}^2 = (\sigma_{psf}^2 + \frac{\text{pixel_size}^2}{12}) / \text{num_photons} + (8\pi\sigma_{psf}^4 \text{background_photons}^2) / (\text{num_photons})$$

This is assuming that the fit of the single molecule localization is done using a least squares fit

Parameters: (all units for the parameters need to be the same)

psf_sigma : float
 The sigma of the PSF
 pixel_size : float
 The size of a pixel
 num_photons : float or numpy array
 The number of photons
 background_photons : float
 The number of background photons

Returns:

float or numpy array
 The localization precision

5.17.2.54 track_decomp()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.track_decomp (
    x,
    y,
    f,
    max_track_decomp)
```

5.18 SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors Namespace Reference

Classes

- class [Angle_Storage](#)
- class [Track_Calculations](#)
- class [Track_Calculations_Individual_Dict](#)

Functions

- dict [Angle_track](#) (dict tracks, conversion_factor=None, tau_conversion_factor=None, min_track_length=3, max_track_length=100, **kwargs)
- np.ndarray [trajectory_angles](#) (np.ndarray trajectory)
- float [asymmetry_metric](#) (np.ndarray angle_distribution, np.ndarray forward_angle_range, np.ndarray backward_angle_range)

5.18.1 Function Documentation

5.18.1.1 Angle_track()

```
dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_track (
    dict tracks,
        conversion_factor = None,
        tau_conversion_factor = None,
        min_track_length = 3,
        max_track_length = 100,
    ** kwargs)
```

Documentation for Angle_track

Parameters:

tracks : dict

dictionary of tracks, key = track ID, value = [[x,y],...] of coordinates

conversion_factor : float (default = None)

if conversion_factor != None then the coordinates are converted to the desired units before the MSD is calculated

tau_conversion_factor : float (default = None)

if tau_conversion_factor != None then the time lags are converted to the desired units before the MSD is calculated. units are for [0->n] (int) -> seconds (1 = 0.02 seconds)

min_track_length : int (default = 2)

the minimum length of a track to be included in the MSD calculation

max_track_length : int (default = 100)

the maximum length of a track to be included in the MSD calculation

Returns:

return_dict : dict

dictionary of angles for each track, key = track ID, value = dictionary of angles of the trajectory at each time lag

This has two keys, "ensemble_angles" and "track_angles" which are the ensemble angles and the angles for each track. Final structure is:

```
return_dict = {
    "ensemble_angles":{time_lag:angles,...},
    "track_angles":{track_ID:{time_lag:angles,...},...}
    "track_storage":{track_ID:[[x,y],...],...}
}
```

5.18.1.2 asymmetry_metric()

```
float SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.asymmetry_metric (
    np.ndarray angle_distribution,
    np.ndarray forward_angle_range,
    np.ndarray backward_angle_range)
```

Calculates the asymmetry metric for the forward and backward angle distributions.

Defined as the difference between the percentage of angles in the forward and backward angle ranges. This metric ranges from -1 and 1, where -1 indicates that all angles are in the backward angle range and 1 indicates that all angles are in the forward angle range.

Parameters:

angle_distribution: 1D array

Array of angles between the vectors of the trajectory

forward_angle_range: 1D array of length 2

Range of angles to consider for the forward angle distribution (in radians)

backward_angle_range: 1D array of length 2

Range of angles to consider for the backward angle distribution (in radians)

Returns:

asymmetry: float

Asymmetry metric for the forward and backward angle distributions

5.18.1.3 trajectory_angles()

```
np.ndarray SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.trajectory_↵
angles (
    np.ndarray trajectory)
```

Calculates the angles between the vectors of a trajectory. (using the cosine rule)

Parameters:

trajectory: 2D array

Array of x and y coordinates of a trajectory (in the form [[x1, y1], [x2, y2], ...])

Returns:

angles: 1D array

Array of angles between the vectors of the trajectory (in radians)

5.19 SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util Namespace Reference

Functions

- [bootstrap_hist](#) (data, bins, n_bootstraps=1000, bootsize=None, bootfunc=np.mean)
- [bootstrap_mean_std](#) (values, n_bootstraps, bootsize, log_values=False)
- [bootstrap_statistic](#) (values, n_bootstraps, bootsize, log_values=False, statistic="mean")

Variables

- list [BOOTSTRAP_PARAMS_NAMES](#)
- list [BOOTSTRAP_PARAMS_DEFAULTS](#)

5.19.1 Detailed Description

Utility functions for bootstrapping different types of data

Containing functions:

1) `bootstrap_hist` = histogram bootstrap with bin selection

2) `bootstrap_mean_std` = bootstrap for the observable of mean and std

3) `bootstrap_statistics` = same as `bootstrap_mean_std` but for a user defined statistic (mean, std, IQR, etc ...)

5.19.2 Function Documentation

5.19.2.1 bootstrap_hist()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.bootstrap_hist (
    data,
    bins,
    n_bootstraps = 1000,
    bootsize = None,
    bootfunc = np.mean)
```

Parameters:

`data` : array-like (1D)
 data to bootstrap
`bins` : int or array-like
 bins to use for the histogram, if int, then the bins are calculated using the histogram function
`n_bootstraps` : int
 number of times to bootstrap the data
`bootsize` : int or float
 number of data points to bootstrap, if float < 0, then the number of data points is calculated as a percent
`bootfunc` : function
 function to use to calculate the mean of the bootstrapped data

Returns:

`hist_mean` : array-like
 mean of the bootstrapped histogram along each bin
`hist_std` : array-like
 std of the bootstrapped histogram along each bin
`bins` : array-like
 bins used for the histogram

5.19.2.2 bootstrap_mean_std()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.bootstrap_mean_std (
    values,
    n_bootstraps,
    bootsize,
    log_values = False)
```

Parameters:

`values` : array-like (1D)
 values to bootstrap
`n_bootstraps` : int
 number of times to bootstrap the data
`bootsize` : int or float
 number of data points to bootstrap, if float < 0, then the number of data points is calculated as a percent
`log_values` : bool
 whether to take the log of the values before bootstrapping

Returns:

`mean` : float
 mean of the bootstrapped values
`std` : float
 std of the bootstrapped values

5.19.2.3 bootstrap_statistic()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.bootstrap_statistic (
    values,
    n_bootstraps,
    bootsize,
    log_values = False,
    statistic = "mean")
```

```

Parameters:
-----
values : array-like (1D)
    values to bootstrap
n_bootstraps : int
    number of times to bootstrap the data
bootsize : int or float
    number of data points to bootstrap, if float < 0, then the number of data points is calculated as a percent
log_values : bool
    whether to take the log of the values before bootstrapping
statistic : str
    statistic to calculate, must be one of ["mean", "median", "std", "var", "min", "max"]

Returns:
-----
value : float
    value of the statistic

```

5.19.3 Variable Documentation

5.19.3.1 BOOTSTRAP_PARAMS_DEFAULTS

```
list SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.BOOTSTRAP_PARAMS_DEFAULTS
```

Initial value:

```

00001 = [
00002     1000,
00003     None,
00004     np.mean,
00005     np.std
00006 ]

```

5.19.3.2 BOOTSTRAP_PARAMS_NAMES

```
list SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.BOOTSTRAP_PARAMS_NAMES
```

Initial value:

```

00001 = [
00002     "n_bootstraps",
00003     "bootsize",
00004     "bootfunc",
00005     "booterrorfunc"
00006 ]

```

5.20 SMT.SMT_Analysis_BP.helpers.analysisFunctions.dir_invert_images ↩ images Namespace Reference

Functions

- [save_invert_images](#) (path, **kwargs)

Variables

- [dir_path](#) = str(sys.argv[1])

5.20.1 Detailed Description

This script takes input at runtime to a directory where images are kept to invert them and save them in a new

Author: Baljyot Singh Parmar

5.20.2 Function Documentation

5.20.2.1 save_invert_images()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.dir_invert_images.save_invert_images (
    path,
    ** kwargs)
```

Makes directory to store inverted images and put files there

Parameters:

path: str

path to the directory holding the images to invert

Keyword Arguments:

invert_path: str

path to the directory to store the inverted images

Returns:

None

5.20.3 Variable Documentation

5.20.3.1 dir_path

```
list SMT.SMT_Analysis_BP.helpers.analysisFunctions.dir_invert_images.dir_path = str(sys.↵
argv[1])
```

5.21 SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask Namespace Reference ↵

Classes

- class [extract_mask_properties](#)

Variables

- str [path](#) = '/Users/baljyot/Documents/SMT_Movies/testing_SM_recon/Movies/Movie_1/Cell_1/mask.tif'
- [mask](#) = io.imread([path](#))
- [prop_obj](#) = [extract_mask_properties](#)([mask](#))
- [fig](#)
- [ax](#)
- [color](#)
- [label](#)

5.21.1 Detailed Description

Module focused on extracting features from a mask image.

Main properties focused on extracting:

- Area
- Bounding Box
- Centroid
- r_offset (bottom left corner of bounding box)

5.21.2 Variable Documentation

5.21.2.1 ax

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.ax
```

5.21.2.2 color

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.color
```

5.21.2.3 fig

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.fig
```

5.21.2.4 label

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.label
```

5.21.2.5 mask

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.mask = io.imread(path)
```

5.21.2.6 path

```
str SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.path = '/Users/baljyot/Documents/SMT↵_Movies/testing_SM_recon/Movies/Movie_1/Cell_1/mask.tif'
```

5.21.2.7 prop_obj

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.prop_obj = extract\_mask\_properties(mask)
```

5.22 SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils Namespace Reference

Classes

- class [Calculation_abc](#)
- class [DatabaseOrderUtil](#)
- class [MSD_Calculations](#)
- class [MSD_Calculations_Track_Dict](#)
- class [MSD_storage](#)

Functions

- [msd_avgerage_utility](#) (dict displacements, bool bootstrap=False, float bootstrap_samples=0.1, float bootstrap_percentile=0.95, bootstrap_num=100, **kwargs)
- [MSD_Tracks](#) (tracks, permutation=True, conversion_factor=None, tau_conversion_factor=None, min_track↵_length=1, max_track_length=10, **kwargs)
- [radius_of_confinement](#) (t, r_sqr, D, loc_msd)
- [radius_of_confinement_xy](#) (t, r_sqr, D, loc_msd_x, loc_msd_y)
- [power_law_xy](#) (t, alpha, D, loc_msd_x, loc_msd_y)
- [power_law](#) (t, alpha, D, loc_msd)
- [linear_MSD_fit](#) (t, a, b)
- [combine_track_dicts](#) (dicts)
- [_msd_tau_utility_all](#) (x, y, tau)
- [_msd_tau_utility_single](#) (x, y, tau)
- [MSD_tau_utility](#) (x, y, tau=1, permutation=True)
- [MSD_tau](#) (x, y, permutation=True)

5.22.1 Function Documentation

5.22.1.1 _msd_tau_utility_all()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils._msd_tau_utility_all (
    x,
    y,
    tau)  [protected]
```

Documentation for _msd_tau_utility_all

Parameters:

```
x : array
    x positions of the data
y : array
    y positions of the data
tau : int
    time lag for the MSD calculation
```

Returns:

```
displacements : array, shape (n,2)
    array of displacements for all possible permutations of the data
```

Notes:

For the theory behind this see https://web.mit.edu/savin/Public/.Tutorial_v1.2/Concepts.html#A1

5.22.1.2 `_msd_tau_utility_single()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils._msd_tau_utility_single (
    x,
    y,
    tau) [protected]
```

5.22.1.3 `combine_track_dicts()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.combine_track_dicts (
    dicts)
```

each dict is going to contain 4 dicts of name "IN","IO","OUT","ALL"
we need to keep this strucutre for the final combined dict

5.22.1.4 `linear_MSD_fit()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.linear_MSD_fit (
    t,
    a,
    b)
```

linear fit function
expects t to be scaled with log10, and returns msd output in log10
b = log10(4*D)
a = alpha
t = log10(tau)

5.22.1.5 `msd_avgerage_utility()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.msd_avgerage_utility (
    dict displacements,
    bool bootstrap = False,
    float bootstrap_samples = 0.1,
    float bootstrap_percentile = 0.95,
    bootstrap_num = 100,
    ** kwargs)
```

Documentation for `_msd_avgerage_utility`

Parameters:

displacements : dict

dictionary of displacements for each time lag, key = time lag, value = array of displacements, shape (n,D)

bootstrap : bool (default = False)

if bootstrap == True then the MSD is calculated for all possible permutations of the data

if bootstrap == False then the MSD is calculated for the data in the order it is given

bootstrap_samples : float (default = 0.1)

the fraction of the data to use for the bootstrap (0.1 = 10%)

bootstrap_percentile : float (default = 0.95)

the percentile to use for the bootstrap (0.95 = 95%)

bootstrap_num : int (default = 100)

the number of bootstrap iterations to perform

Returns:

msd : dict

dictionary of the MSD for each time lag, key = time lag, value = array of MSD values, shape (n,)

error_msd : dict (this is the standard error of the mean of the MSD)

dictionary of the error in the MSD for each time lag, key = time lag, value = array of error in the MSD va

5.22.1.6 MSD_tau()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_tau (
    x,
    y,
    permutation = True)
```

Documentation for MSD_tau

Parameters:

```
x : array
    x positions of the data
y : array
    y positions of the data
permutation : bool
    if permutation == True then the MSD is calculated for all possible permutations of the data
    if permutation == False then the MSD is calculated for the data in the order it is given
```

Returns:

```
displacements : dict
    dictionary of displacements for each time lag, key = time lag, value = array of displacements, shape (n,2)
```

5.22.1.7 MSD_tau_utility()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_tau_utility (
    x,
    y,
    tau = 1,
    permutation = True)
```

Documentation for MSD_tau_utility

Parameters:

```
x : array
    x positions of the data
y : array
    y positions of the data
tau : int
    time lag for the MSD calculation
permutation : bool
    if permutation == True then the MSD is calculated for all possible permutations of the data
    if permutation == False then the MSD is calculated for the data in the order it is given
```

Returns:

```
displacements : array, shape (n,2)
    array of displacements
```

5.22.1.8 MSD_Tracks()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Tracks (
    tracks,
    permutation = True,
    conversion_factor = None,
    tau_conversion_factor = None,
    min_track_length = 1,
    max_track_length = 10,
    ** kwargs)
```

Documentation for MSD_Tracks

Parameters:

tracks : dict

dictionary of tracks, key = track ID, value = [[x,y],...] of coordinates

permutation : bool (default = True, don't change this)

if permutation == True then the MSD is calculated for all possible permutations of the data

if permutation == False then the MSD is calculated for the data in the order it is given

conversion_factor : float (default = None)

if conversion_factor != None then the coordinates are converted to the desired units before the MSD is calculated

tau_conversion_factor : float (default = None)

if tau_conversion_factor != None then the time lags are converted to the desired units before the MSD is calculated

units are for [0->n] (int) -> seconds (1 = 0.02 seconds)

min_track_length : int (default = 1)

the minimum length of a track to be included in the MSD calculation

max_track_length : int (default = 10)

the maximum length of a track to be included in the MSD calculation

KWARGS:

Passed to msd_avgerage_utility() -> (bootstrap:bool=False,bootstrap_samples:float=0.1,bootstrap_percentile:float=0.95)

Returns:

return_dict : dict

dictionary of MSD curves for each track, key = track ID, value = dictionary of displacements for each time lag

Notes:

1. Only implemented sequential tau. If trajectories are missing coordinate values (ex. if using gap linking in SMT) then the MSD is calculated for the non-missing values.

5.22.1.9 power_law()

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.power_law (

t,

alpha,

D,

loc_msd)

5.22.1.10 power_law_xy()

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.power_law_xy (

t,

alpha,

D,

loc_msd_x,

loc_msd_y)

5.22.1.11 radius_of_confinement()

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.radius_of_confinement (

t,

r_sqr,

D,

loc_msd)

5.22.1.12 radius_of_confinement_xy()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.radius_of_confinement_xy (
    t,
    r_sqr,
    D,
    loc_msd_x,
    loc_msd_y)
```

5.23 SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND Namespace Reference

Classes

- class [TestNearestNeighbourDistances2D](#)
- class [TestPairwiseArray](#)

Functions

- [pairwise_array](#) (n)
- [nearest_neighbour_distances_2d](#) (x0, y0, x1, y1, verbose_return=False, conversion_factor=0.13)

5.23.1 Function Documentation

5.23.1.1 nearest_neighbour_distances_2d()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.nearest_neighbour_distances_2d (
    x0,
    y0,
    x1,
    y1,
    verbose_return = False,
    conversion_factor = 0.13)
```

Docstring for nearest_neighbour_distances_2d
finds the nearest neighbour distances for two time points

Parameters:

x0: array-like
x coordinates for the first time point

y0: array-like
y coordinates for the first time point

x1: array-like
x coordinates for the second time point

y1: array-like
y coordinates for the second time point

verbose_return: bool
if True, returns a dictionary with the nearest neighbour distances for x and y

conversion_factor: float
conversion factor to convert to a certain unit. Default is 0.13, which is the conversion factor for the 10

Returns:

```

nearest_neighbour_distances: array-like
    nearest neighbour distances for the two time points
nearest_neighbour_distances_x: array-like
    nearest neighbour distances for the two time points in the x direction
nearest_neighbour_distances_y: array-like
    nearest neighbour distances for the two time points in the y direction

```

Notes:

1. If `verbose_return` is `True`, the function returns a dictionary with the nearest neighbour distances for `x` and `y`.

5.23.1.2 pairwise_array()

```

SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.pairwise_array (
    n)

```

Generates the pairwise array of consecutive integers from 0 to `n-1`.

5.24 SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_↔ detection Namespace Reference

Functions

- [find_nuc](#) (img, str typee, regions=True, **kwargs)
- [get_training_set](#) (img)
- [get_region](#) (image, type=regionprops, connectivity=2, **kawrgs)
- [plot_regions](#) (regions, fig, ax, colorbar_mappable, plot=False)

Variables

- dict [TESTED_DICT](#)

5.24.1 Detailed Description

This module contains the functions used to detect the nucleoids in the images

It uses the Random Forest Classifier to detect the nucleoids in the images and then uses the regionprops function

Author: Baljyot Singh Parmar

5.24.2 Function Documentation

5.24.2.1 find_nuc()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.find_nuc (
    img,
    str typee,
    regions = True,
    **kwargs)
```

Parameters:

```
-----
img : 2D array-like
    image to be segmented
typee : str
    type of image to be segmented. These should have keys in TESTED_DICT. If not then raise error that the "ty
regions : bool, default = True
    if True then return the regionprops of the segmented image
**kwargs : dict
    keyword arguments to be passed to the function. These are:
    connectivity : int, default = 2
        connectivity of the image. This is passed to the regionprops function
    sigma_max : int, default = 10
        maximum sigma value to be used in the multiscale_basic_features function
    sigma_min : int, default = 1
        minimum sigma value to be used in the multiscale_basic_features function
    given_type : dict | str, default = None (dict if passing thresholds, str if passing Cell wise threshold
        dictionary containing the values of the thresholds. If not given then the values are taken from TE
    if str:
        if "Threshold_23" then use a cell wide threshold where nucleoid_threshold = (2/3)*max(img) and
        if "Threshold_12" then use a cell wide threshold where nucleoid_threshold = (1/2)*max(img) and
        if "Threshold_13" then use a cell wide threshold where nucleoid_threshold = (1/3)*max(img) and
        if "Threshold_34" then use a cell wide threshold where nucleoid_threshold = (3/4)*max(img) and
```

Returns:

```
-----
result : 2D array-like
    segmented image. This is a mask with at max 3 values. 2 for background, 1 for nucleoid and 3 for rest of t
region_result : list of RegionProperties
    list of region properties of the segmented image. This is returned only if regions = True
```

5.24.2.2 get_region()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.get_region (
    image,
    type = regionprops,
    connectivity = 2,
    **kwargs)
```

Parameters

```
-----
image : 2D array-like
    binary image (0,1) where 1 indicates the region to fit
type : functional, default = regionprops
    the function type used to fit the image. Default assumes elliptical shapes
```

Returns

```
-----
propertieslist of RegionProperties
    Each item describes one labeled region, and can be accessed using the attributes listed below.
```

Notes

```
-----
```

The following properties can be accessed as attributes or keys:

`area``int`

Number of pixels of the region.

`area_bbox``int`

Number of pixels of bounding box.

`area_convex``int`

Number of pixels of convex hull image, which is the smallest convex polygon that encloses the region.

`area_filled``int`

Number of pixels of the region with all the holes filled in. Describes the area of the `image_filled`.

`axis_major_length``float`

The length of the major axis of the ellipse that has the same normalized second central moments as the region.

`axis_minor_length``float`

The length of the minor axis of the ellipse that has the same normalized second central moments as the region.

`bbox``tuple`

Bounding box (`min_row`, `min_col`, `max_row`, `max_col`). Pixels belonging to the bounding box are in the half-open interval `[min_row, max_row) × [min_col, max_col)`.

`centroid``array`

Centroid coordinate tuple (`row`, `col`).

`centroid_local``array`

Centroid coordinate tuple (`row`, `col`), relative to region bounding box.

`centroid_weighted``array`

Centroid coordinate tuple (`row`, `col`) weighted with intensity image.

`centroid_weighted_local``array`

Centroid coordinate tuple (`row`, `col`), relative to region bounding box, weighted with intensity image.

`coords`(`N`, 2) `ndarray`

Coordinate list (`row`, `col`) of the region.

`eccentricity``float`

Eccentricity of the ellipse that has the same second-moments as the region. The eccentricity is the ratio of the major axis to the minor axis.

`equivalent_diameter_area``float`

The diameter of a circle with the same area as the region.

`euler_number``int`

Euler characteristic of the set of non-zero pixels. Computed as number of connected components subtracted by number of holes.

`extent``float`

Ratio of pixels in the region to pixels in the total bounding box. Computed as `area / (rows * cols)`.

`feret_diameter_max``float`

Maximum Feret's diameter computed as the longest distance between points around a region's convex hull contour.

`image`(`H`, `J`) `ndarray`

Sliced binary region image which has the same size as bounding box.

`image_convex`(`H`, `J`) `ndarray`

Binary convex hull image which has the same size as bounding box.

image_filled(H, J) ndarray

Binary region image with filled holes which has the same size as bounding box.

image_intensityndarray

Image inside region bounding box.

inertia_tensorndarray

Inertia tensor of the region for the rotation around its mass.

inertia_tensor_eigvalstuple

The eigenvalues of the inertia tensor in decreasing order.

intensity_maxfloat

Value with the greatest intensity in the region.

intensity_meanfloat

Value with the mean intensity in the region.

intensity_minfloat

Value with the least intensity in the region.

labelint

The label in the labeled input image.

moments(3, 3) ndarray

Spatial moments up to 3rd order:

$m_{ij} = \sum \{ \text{array}(\text{row}, \text{col}) * \text{row}^i * \text{col}^j \}$

where the sum is over the row, col coordinates of the region.

moments_central(3, 3) ndarray

Central moments (translation invariant) up to 3rd order:

$\mu_{ij} = \sum \{ \text{array}(\text{row}, \text{col}) * (\text{row} - \text{row}_c)^i * (\text{col} - \text{col}_c)^j \}$

where the sum is over the row, col coordinates of the region, and row_c and col_c are the coordinates of the region

moments_hutuple

Hu moments (translation, scale and rotation invariant).

moments_normalized(3, 3) ndarray

Normalized moments (translation and scale invariant) up to 3rd order:

$nu_{ij} = \mu_{ij} / m_{00}^{[(i+j)/2 + 1]}$

where m_00 is the zeroth spatial moment.

moments_weighted(3, 3) ndarray

Spatial moments of intensity image up to 3rd order:

$wm_{ij} = \sum \{ \text{array}(\text{row}, \text{col}) * \text{row}^i * \text{col}^j \}$

where the sum is over the row, col coordinates of the region.

moments_weighted_central(3, 3) ndarray

Central moments (translation invariant) of intensity image up to 3rd order:

$wmu_{ij} = \sum \{ \text{array}(\text{row}, \text{col}) * (\text{row} - \text{row}_c)^i * (\text{col} - \text{col}_c)^j \}$

where the sum is over the row, col coordinates of the region, and row_c and col_c are the coordinates of the region

moments_weighted_hutuple

Hu moments (translation, scale and rotation invariant) of intensity image.

`moments_weighted_normalized(3, 3) ndarray`

Normalized moments (translation and scale invariant) of intensity image up to 3rd order:

`wmu_ij = wmu_ij / wm_00^[(i+j)/2 + 1]`

where `wm_00` is the zeroth spatial moment (intensity-weighted area).

`orientationfloat`

Angle between the 0th axis (rows) and the major axis of the ellipse that has the same second moments as the region.

`perimeterfloat`

Perimeter of object which approximates the contour as a line through the centers of border pixels using a 4-connected neighborhood.

`perimeter_croftonfloat`

Perimeter of object approximated by the Crofton formula in 4 directions.

`slicetuple of slices`

A slice to extract the object from the source image.

`solidityfloat`

Ratio of pixels in the region to pixels of the convex hull image.

Each region also supports iteration, so that you can do:

```
for prop in region:
    print(prop, region[prop])
```

5.24.2.3 get_training_set()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.get_training_set (
    img)
```

5.24.2.4 plot_regions()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.plot_regions (
    regions,
    fig,
    ax,
    colorbar_mappable,
    plot = False)
```

Parameters

`regions` : list, output from `regionprops`
 takes the output of the `regionprops` from `sklearn`
`fig` : `plt.figure` object
 figure object to plot onto
`ax` : axis object
 axis object on which to plot to
`colorbar_mappable` : `colobar mappable`
`colorbar_mappable` opbject

Returns

5.24.3 Variable Documentation

5.24.3.1 TESTED_DICT

dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.TESTED_DICT

5.25 SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus Namespace Reference

Classes

- class [ScaleSpacePlus](#)
- class [SM_reconstruction_image](#)
- class [SM_reconstruction_masked](#)

Functions

- [get_gaussian](#) (mu, sigma, domain=[list(range(10)), list(range(10))])

Variables

- dict [KEY_IMAGE](#)
- int [MASK_VALUE](#) = 255
- int [BOUNDING_BOX_PADDING](#) = 5
- dict [CONVERSION_TYPES](#) = {'RC_to_Original':0,'original_to_RC':1}
- int [RANDOM_SEED](#) = 666

5.25.1 Detailed Description

Suite of functions and classes to perform the scale space plus procedure to create the reconstruction image from

5.25.2 Function Documentation

5.25.2.1 get_gaussian()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.get_gaussian (
    mu,
    sigma,
    domain = [list(range(10)), list(range(10))])
```

Parameters

mu : array-like or float of floats
 center position of gaussian (x,y) or collection of (x,y)
sigma : float or array-like of floats of shape mu
 sigma of the gaussian
domain : array-like, Defaults to 0->9 for x,y
 x,y domain over which this gaussian is over

Returns

array-like 2D
 values of the gaussian centered at mu with sigma across the (x,y) points defined in domain

Notes:

THIS IS IMPORTANT: MAKE SURE THE TYPES IN EACH PARAMETER ARE THE SAME!!!!

5.25.3 Variable Documentation

5.25.3.1 BOUNDING_BOX_PADDING

```
int SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.BOUNDING_BOX_PADDING = 5
```

5.25.3.2 CONVERSION_TYPES

```
dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.CONVERSION_TYPES = {'RC_↔  
to_Original':0, 'original_to_RC':1}
```

5.25.3.3 KEY_IMAGE

```
dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.KEY_IMAGE
```

Initial value:

```
00001 = {  
00002     'png':skimage.io.imsave,  
00003     'jpg':skimage.io.imsave,  
00004     'tif':skimage.io.imsave,  
00005     'svg':skimage.io.imsave  
00006 }
```

5.25.3.4 MASK_VALUE

```
int SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.MASK_VALUE = 255
```

5.25.3.5 RANDOM_SEED

```
int SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.RANDOM_SEED = 666
```

5.26 SMT.SMT_Analysis_BP.helpers.analysisFunctions.↔ smallestenclosingcircle Namespace Reference

Functions

- [make_circle](#) (points)
- [_make_circle_one_point](#) (points, p)
- [_make_circle_two_points](#) (points, p, q)
- [make_diameter](#) (a, b)
- [make_circumcircle](#) (a, b, c)
- [is_in_circle](#) (c, p)
- [_cross_product](#) (x0, y0, x1, y1, x2, y2)

Variables

- [int _MULTIPLICATIVE_EPSILON](#) = 1 + 1e-14

5.26.1 Function Documentation

5.26.1.1 `_cross_product()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._cross_product (
    x0,
    y0,
    x1,
    y1,
    x2,
    y2) [protected]
```

5.26.1.2 `_make_circle_one_point()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._make_circle_one_point (
    points,
    p) [protected]
```

5.26.1.3 `_make_circle_two_points()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._make_circle_two_points
(
    points,
    p,
    q) [protected]
```

5.26.1.4 `is_in_circle()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.is_in_circle (
    c,
    p)
```

5.26.1.5 `make_circle()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.make_circle (
    points)
```

5.26.1.6 `make_circumcircle()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.make_circumcircle (
    a,
    b,
    c)
```

5.26.1.7 `make_diameter()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.make_diameter (
    a,
    b)
```

5.26.2 Variable Documentation

5.26.2.1 `_MULTIPLICATIVE_EPSILON`

```
int SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._MULTIPLICATIVE_↔
EPSILON = 1 + 1e-14 [protected]
```

5.27 `SMT.SMT_Analysis_BP.helpers.clusterMethods` Namespace Reference

Namespaces

- namespace [blob_detection](#)
- namespace [clustering_methods](#)

5.28 `SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection` Namespace Reference

Classes

- class [blob_detection](#)

Functions

- [identity](#) (x)
- [iso_gaus](#) (p, x, y, z)
- [residuals_gaus2d](#) (p, x, y, z, **kwargs)
- [gaussian2D](#) (x, y, cen_x, cen_y, sig_x, sig_y, offset, height, kwargs={})

Variables

- int [FWHM_FACTOR](#) = 2.*(np.log(2.+np.sqrt(3)))

5.28.1 Detailed Description

Documentation for `blob_detection.py`

This file contains the class `blob_detection` which is used to detect blobs in an image. It uses the `skimage.blob` module. It also has the option to fit the blobs with a 2D gaussian function. The class also has the option to fit the blobs with a 2D gaussian function. This is done by using the `lmfit` package. Detection can be done using the `skimage.blob_log()` function or a custom function. The custom function is a module.

Classes:

`blob_detection`: see class docstring for more info, this is the main class that is used to detect blobs in an image.

5.28.2 Function Documentation

5.28.2.1 gaussian2D()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.gaussian2D (
    x,
    y,
    cen_x,
    cen_y,
    sig_x,
    sig_y,
    offset,
    height,
    kwargs = {})
```

2d gaussian anistropic

5.28.2.2 identity()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.identity (
    x)
```

identity function, returns the input

Parameters:

x : any
 input to be returned

Returns:

x : any
 input

Uses:

identity(x) = x

5.28.2.3 iso_gaus()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.iso_gaus (
    p,
    x,
    y,
    z)
```

5.28.2.4 residuals_gaus2d()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.residuals_gaus2d (
    p,
    x,
    y,
    z,
    ** kwargs)
```

Residual calculator for a 2D gaussian for lmfit.minimize

Parameters

```
p : Parameter() object
    Parameters
x : independent variable
    x values
y : independent variable
    y values
z : z = f(x,y)
    function values at x,y. Where function is the one we are trying to fit
```

Returns

```
array-like
    residuals of the function z=f(x,y) (2D gaussian)
```

5.28.3 Variable Documentation

5.28.3.1 FWHM_FACTOR

```
int SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.FWHM_FACTOR = 2.*(np.log(2.+np.sqrt(3)))
```

5.29 SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods Namespace Reference

Functions

- [scale_space_plus_blob_detection](#) (img, blob_parameters, fitting_parameters, show=False)
- [perfrom_DBSCAN_Cluster](#) (localizations, D, minP, show=False)
- [perform_HDBSCAN_Cluster](#) (localizations, min_cluster_size, min_samples, show=False)

5.29.1 Function Documentation

5.29.1.1 perform_HDBSCAN_Cluster()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods.perform_HDBSCAN_Cluster (
    localizations,
    min_cluster_size,
    min_samples,
    show = False)
```

Parameters:

`localizations`: `np.ndarray`
 Numpy array of the localizations in the form `[[x,y],...]`
`min_cluster_size`: `int`
 The minimum size of clusters
`min_samples`: `int`
 The number of samples in a neighborhood for a point to be considered as a core point.
`show`: `bool`
 Whether or not to display a plot of the clusters

Returns:

`cluster_labels`: `np.ndarray`
 Numpy array of the cluster labels in the form `[0,0,1,1,2,2,...]`
`cluster_centers`: `np.ndarray`
 Numpy array of the cluster centers in the form `[[x,y],...]`
`cluster_radii`: `np.ndarray`
 Numpy array of the cluster radii in the form `[r1,r2,...]`
`loc_per_cluster`: `np.ndarray`
 Numpy array of the number of localizations per cluster in the form `[n1,n2,...]`

5.29.1.2 `perfrom_DBSCAN_Cluster()`

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods.perfrom_DBSCAN_Cluster (
    localizations,
    D,
    minP,
    show = False)
```

Parameters:

`localizations`: `np.ndarray`
 Numpy array of the localizations in the form `[[x,y],...]`
`D`: `float`, in the units of the localizations
 The maximum distance between two samples for one to be considered as in the neighborhood of the other
`minP`: `int`
 The number of samples (or total weight) in a neighborhood for a point to be considered as a core point.

Returns:

`cluster_labels`: `np.ndarray`
 Numpy array of the cluster labels in the form `[0,0,1,1,2,2,...]`
`cluster_centers`: `np.ndarray`
 Numpy array of the cluster centers in the form `[[x,y],...]`
`cluster_radii`: `np.ndarray`
 Numpy array of the cluster radii in the form `[r1,r2,...]`
`loc_per_cluster`: `np.ndarray`
 Numpy array of the number of localizations per cluster in the form `[n1,n2,...]`

5.29.1.3 `scale_space_plus_blob_detection()`

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods.scale_space_plus_blob_detection
(
    img,
    blob_parameters,
    fitting_parameters,
    show = False)
```

Wrapper for the `blob_detection` function in the `blob_detection.py` file
 See the `blob_detection.py` file for more details on the parameters

5.30 SMT.SMT_Analysis_BP.helpers.ioModule Namespace Reference

Namespaces

- namespace [import_functions](#)
- namespace [logging_and_print_util](#)
- namespace [pickle_util](#)
- namespace [plotting_functions](#)
- namespace [SMT_converters](#)

5.31 SMT.SMT_Analysis_BP.helpers.ioModule.import_functions Namespace Reference

Functions

- [read_data](#) (path, delimiter=',', skiprow=1, **kwargs)
- [read_file](#) (file_loc)
- [combine_path](#) (root, path)
- [find_image](#) (path, ends_with='.tif', full_path=False)
- [name_sorter](#) (strings, keyword)
- [find_files](#) (path, extension, keyword=None)
- [invert_I16u](#) (img, array=False)
- [invert_img](#) (path)
- [save_img](#) (object, path)

5.31.1 Detailed Description

This file contains most functions used in Input/Output of different files and directories

Author: Baljyot Singh Parmar

5.31.2 Function Documentation

5.31.2.1 `combine_path()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.combine_path (
    root,
    path)
```

Parameters

root : str

path of the root directory

path : str

name of the file or directory to combine with root

Returns

string

combined path given root and path

5.31.2.2 find_files()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.find_files (
    path,
    extension,
    keyword = None)
```

Docstring for find_files

Finds files in a directory with a specific extension and keyword in the name

Parameters:

```
path : str
    path to the directory where the files are located
extension : str
    extension of the files to be found
keyword : str
    keyword to be searched in the file name
```

Returns:

```
files : list
    list of files that match the criteria
```

5.31.2.3 find_image()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.find_image (
    path,
    ends_with = '.tif',
    full_path = False)
```

Docstring for find_image:

Find all files in a directory that end with a certain string

Parameters

```
path : string
    Full path of the directory in which to find the files. Not recursive find!
ends_with : string, default = '.tif'
    Unique string to find files that end with this string
full_path : bool
    if true return the full path of the file, else return just the file name
Returns
-----
list
    list of file paths with the root provided in Parameters with constraints of ends_with
```

5.31.2.4 invert_I16u()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.invert_I16u (
    img,
    array = False)
```

Parameters

```
img : PIL.Image object
    image object to invert
array : bool
    if true return a numpy array of the inverted image, else return a PIL.Image object
```

Returns

```
PIL.Image object or numpy based on the boolean value of array
    inverted image
```

5.31.2.5 invert_img()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.invert_img (
    path)
```

Parameters

path : string
full path of the image to invert

Returns

PIL Image object
to save this image use object.save(new_path)

5.31.2.6 name_sorter()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.name_sorter (
    strings,
    keyword)
```

Docstring for name_sorter:
Find all the strings in a list that contain a keyword

Parameters:

strings : list
list of strings to search through
keyword : string
keyword to search for in the list of strings

Returns:

list
list of strings that contain the keyword

5.31.2.7 read_data()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.read_data (
    path,
    delimiter = ',',
    skiprow = 1,
    ** kwargs)
```

Parameters

path : str
path to the file to be read

delimiter : str
delimiter used in the file to separate individual value

skiprow : int
number of rows to skip from the start of the file before reading

Returns

array-like
array of the loaded data

5.31.2.8 read_file()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.read_file (
    file_loc)
```

Parameters

```
file_loc : str
    path to the file
```

Returns

```
Array-like
    the array is 2D array of the pixel locations
```

5.31.2.9 save_img()

```
SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.save_img (
    object,
    path)
```

Paramteres

```
object : PIL.Image object
    image object
path : str
    path to which this image should be saved
```

5.32 SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util Namespace Reference

Functions

- [beautiful_print](#) (*args, **kwargs)
- [beautiful_print_dict](#) (dict dict_to_print, **kwargs)
- [beautiful_print_list](#) (list list_to_print, **kwargs)

5.32.1 Detailed Description

This is a utility module to house functions and classes involved in logging and printing to the console.

Mainly this is for beautifying the console output and logging to a file if needed

Might just be better to use pprint ([url: https://docs.python.org/3/library/pprint.html](https://docs.python.org/3/library/pprint.html))

5.32.2 Function Documentation

5.32.2.1 `beautiful_print()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util.beautiful_print (
    * args,
    ** kwargs)
```

This function is a wrapper around the print function that adds a line of dashes before and after the print statement.

Parameters:

```
*args: list
    list of arguments to pass to the print function
**kwargs: dict
    dict of keyword arguments to pass to the print function
```

Returns:

None

5.32.2.2 `beautiful_print_dict()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util.beautiful_print_dict (
    dict dict_to_print,
    ** kwargs)
```

This function is a wrapper around the print function that adds a line of dashes before and after the print statement.

Parameters:

```
dict_to_print: dict
    dict to print
**kwargs: dict
    dict of keyword arguments to pass to the print function
```

Returns:

None

5.32.2.3 `beautiful_print_list()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util.beautiful_print_list (
    list list_to_print,
    ** kwargs)
```

This function is a wrapper around the print function that adds a line of dashes before and after the print statement.

Parameters:

```
list_to_print: list
    list to print
**kwargs: dict
    dict of keyword arguments to pass to the print function
```

Returns:

None

5.33 SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util Namespace Reference

Classes

- class [PickleUtil](#)
- class [TestPickleUtil](#)

5.33.1 Detailed Description

Utility functions for pickling and unpickling objects.
Generically, this is used to save and load models with doc specific to the object.

5.34 SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions Namespace Reference

Classes

- class [run_analysis_plotting](#)

Functions

- [circles](#) (x, y, s, c='b', vmin=None, vmax=None, **kwargs)
- [create_circle_obj](#) (dims, fill=False)
- [create_box_plot](#) (box_data, tick_list, y_label="", x_label="", y_lim=(), title="", show=False)
- [read_imag](#) (path, fig=False, ax=False, show=True)
- [contour_intens](#) (img, fig=False, ax=False, show=True, seg=True, perc=95)
- [spacialplot_msd](#) (op, fig=False, ax=False, show=True)
- [other_plot](#) (op, fig=False, ax=False, show=True)
- [animate](#) (i, ax)
- [circular_hist](#) (ax, x, bins=16, density=True, offset=0, gaps=True, **kwargs)
- [create_circular_mask](#) (h, w, center=None, radius=None)
- [plot_stacked_bar](#) (data, series_labels, category_labels=None, show_values=False, value_format="{ }", y_label=None, colors=None, grid=True, reverse=False)

5.34.1 Detailed Description

This script contains all the plotting functions used in the trajectory_analysis_script.py

Author: Baljyot Singh Parmar

5.34.2 Function Documentation

5.34.2.1 animate()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.animate (
    i,
    ax)
```

5.34.2.2 circles()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.circles (
    x,
    y,
    s,
    c = 'b',
    vmin = None,
    vmax = None,
    ** kwargs)
```

Make a scatter of circles plot of x vs y, where x and y are sequence like objects of the same lengths. The size of circles are in data scale.

Parameters

```
-----
x,y : scalar or array_like, shape (n, )
      Input data
s : scalar or array_like, shape (n, )
    Radius of circle in data unit.
c : color or sequence of color, optional, default : 'b'
    'c' can be a single color format string, or a sequence of color
    specifications of length 'N', or a sequence of 'N' numbers to be
    mapped to colors using the 'cmap' and 'norm' specified via kwargs.
    Note that 'c' should not be a single numeric RGB or RGBA sequence
    because that is indistinguishable from an array of values
    to be colormapped. (If you insist, use 'color' instead.)
    'c' can be a 2-D array in which the rows are RGB or RGBA, however.
vmin, vmax : scalar, optional, default: None
    'vmin' and 'vmax' are used in conjunction with 'norm' to normalize
    luminance data. If either are 'None', the min and max of the
    color array is used.
kwargs : '~matplotlib.collections.Collection' properties
    Eg. alpha, edgecolor(ec), facecolor(fc), linewidth(lw), linestyle(ls),
    norm, cmap, transform, etc.
```

Returns

```
-----
paths : '~matplotlib.collections.PathCollection'
```

Examples

```
-----
a = np.arange(11)
circles(a, a, a*0.2, c=a, alpha=0.5, edgecolor='none')
plt.colorbar()
```

License

```
-----
This code is under [The BSD 3-Clause License]
(http://opensource.org/licenses/BSD-3-Clause)
```

5.34.2.3 circular_hist()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.circular_hist (
    ax,
    x,
    bins = 16,
    density = True,
    offset = 0,
    gaps = True,
    ** kwargs)
```

Produce a circular histogram of angles on ax.

Parameters

ax : matplotlib.axes._subplots.PolarAxesSubplot
axis instance created with subplot_kw=dict(projection='polar').

x : array
Angles to plot, expected in units of radians.

bins : int, optional
Defines the number of equal-width bins in the range. The default is 16.

density : bool, optional
If True plot frequency proportional to area. If False plot frequency proportional to radius. The default is True.

offset : float, optional
Sets the offset for the location of the 0 direction in units of radians. The default is 0.

gaps : bool, optional
Whether to allow gaps between bins. When gaps = False the bins are forced to partition the entire $[-\pi, \pi]$ range. The default is True.

****kwargs** : type
Other arguments are passed directly to 'matplotlib.axes.Axes.bar'.

Returns

n : array or list of arrays
The number of values in each bin.

bins : array
The edges of the bins.

patches : '.BarContainer' or list of a single '.Polygon'
Container of individual artists used to create the histogram
or list of such containers if there are multiple input datasets.

5.34.2.4 contour_intens()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.contour_intens (
    img,
    fig = False,
    ax = False,
    show = True,
    seg = True,
    perc = 95)
```

5.34.2.5 create_box_plot()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.create_box_plot (
    box_data,
    tick_list,
    y_label = "",
    x_label = "",
    y_lim = (),
    title = "",
    show = False)
```

5.34.2.6 create_circle_obj()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.create_circle_obj (
    dims,
    fill = False)
```

INPUTS:

```
dims = array-like
    [x,y,r]
    x = x coordinate of center of circle
    y = y coordinate of center of circle
    r = radius of circle
```

RETURNS:

Circle object to be used in `ax.add_artist`

5.34.2.7 create_circular_mask()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.create_circular_mask (
    h,
    w,
    center = None,
    radius = None)
```

h,w are the dimensions of the image

5.34.2.8 other_plot()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.other_plot (
    op,
    fig = False,
    ax = False,
    show = True)
```

5.34.2.9 plot_stacked_bar()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.plot_stacked_bar (
    data,
    series_labels,
    category_labels = None,
    show_values = False,
    value_format = "{}",
    y_label = None,
    colors = None,
    grid = True,
    reverse = False)
```

Plots a stacked bar chart with the data and labels provided.

Keyword arguments:

```
data          -- 2-dimensional numpy array or nested list
                containing data for each series in rows
series_labels -- list of series labels (these appear in
                the legend)
category_labels -- list of category labels (these appear
                on the x-axis)
show_values   -- If True then numeric value labels will
                be shown on each bar
value_format  -- Format string for numeric value labels
                (default is "{}")
y_label       -- Label for y-axis (str)
colors        -- List of color labels
grid          -- If True display grid
reverse       -- If True reverse the order that the
                series are displayed (left-to-right
                or right-to-left)
```

5.34.2.10 read_imag()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.read_imag (
    path,
    fig = False,
    ax = False,
    show = True)
```

5.34.2.11 spacialplot_msd()

```
SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.spacialplot_msd (
    op,
    fig = False,
    ax = False,
    show = True)
```

5.35 SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters Namespace Reference

Classes

- class [IO_run_analysis](#)

Functions

- list [convert_track_data_SMAUG_format](#) (dict track_data)
- list [convert_track_data_NOBIAS_format_global](#) (dict track_data, int max_tau=1)
- [_convert_track_data_NOBIAS_format_tau](#) (displacement_dict, tau, bool include_cor_obs=False)

5.35.1 Function Documentation

5.35.1.1 `_convert_track_data_NOBIAS_format_tau()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters._convert_track_data_NOBIAS_format_tau (
    displacement_dict,
    tau,
    bool include_cor_obs = False) [protected]
```

Docstring for `_convert_track_data_NOBIAS_format_tau`
 This is a utility function for `convert_track_data_NOBIAS_format_global` that formats the track data for a speci

Parameters:

`displacement_dict`: dict
 dict of the form {`track_id`:{`tau`:[[`x1-x0`,`x2-x1`,...],[`y1-y0`,`y2-y1`,...]],...},...}
 This is the output from the `MSD_Tracks` function in `Analysis_functions.py`
`tau`: int
 the tau to use for the NOBIAS analysis
`include_cor_obs`: bool
 whether to include the correlation observations in the output

Returns:

`nobias_dict_out`: dict
 dict of the form {"obs":[[`x1-x0`,`x2-x1`,...],[`y1-y0`,`y2-y1`,...]],`TrID`:[`track_id1`,`track_id1`,...]}
 "obs" is 2 x T where T is the number of frames and 2 is the dimension of the data (x,y)
 "TrID" is a list of track ids that correspond to the displacements in "obs"

Notes:

For the "cor_obs" key, i have no idea what the values for this are and as such i am leaving it out. But can be

5.35.1.2 `convert_track_data_NOBIAS_format_global()`

```
list SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.convert_track_data_NOBIAS_format_↵
global (
    dict track_data,
    int max_tau = 1)
```

Docstring for `convert_track_data_NOBIAS_format_global`
 This should be run in the background to gain all the tau permutations for posterity but the main function shou
 for a single tau. The other funtions will be described later.

Parameters:

`track_data`: dict
 dict of track data in the format {`track_id`:[[`x0`,`y0`,`frame0`],[`x1`,`y1`,`frame1`],...],...}
`max_tau`: int
 the maximum tau to use for the NOBIAS analysis

Returns:

`track_data_NOBIAS`: list of dict
 dict of the form [{"obs":[[`x1-x0`,`x2-x1`,...],[`y1-y0`,`y2-y1`,...]],`TrID`:[`track_id1`,`track_id1`,...]],...]
 Each element in the list is a dict of the displacements for a given tau
 "obs" is 2 x T where T is the number of frames and 2 is the dimension of the data (x,y)
 "TrID" is a list of track ids that correspond to the displacements in "obs"
 For example:
 {"obs":[[`x1-x0`,`x2-x1`,...],[`y1-y0`,`y2-y1`,...]],`TrID`:[1,1,...]}
 this means that the displacements in "obs" are for track id 1

Notes:

This function is used to convert track data in the format {`track_id`:[[`x0`,`y0`,`frame0`],[`x1`,`y1`,`frame1`],...],...}
 to the format required for NOBIAS analysis

5.35.1.3 convert_track_data_SMAUG_format()

```
list SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.convert_track_data_SMAUG_format (
    dict track_data)
```

5.36 SMT.SMT_Analysis_BP.helpers.misc Namespace Reference

Namespaces

- namespace [decorators](#)
- namespace [diff_mw](#)
- namespace [errors](#)
- namespace [guassian_fit](#)

5.37 SMT.SMT_Analysis_BP.helpers.misc.decorators Namespace Reference

Classes

- class [CountCalls](#)

Functions

- [deprecated](#) (reason)
- [timer](#) (func)
- [debug](#) (func)
- [slow_down](#) (_func=None, *, rate=1)
- [repeat](#) (_func=None, *, num_times=2)
- [singleton](#) (cls)
- [cache](#) (func)
- [set_unit](#) (unit)

Variables

- tuple [string_types](#) = (type(b""), type(u""))

5.37.1 Function Documentation

5.37.1.1 cache()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.cache (
    func)
```

Keep a cache of previous function calls

5.37.1.2 debug()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.debug (  
    func)
```

Print the function signature and return value

5.37.1.3 deprecated()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.deprecated (  
    reason)
```

This is a decorator which can be used to mark functions as deprecated. It will result in a warning being emitted when the function is used.

5.37.1.4 repeat()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.repeat (  
    _func = None,  
    * ,  
    num_times = 2)
```

Repeat the function a number of times

Parameters:

num_times : int
 number of times to repeat the function

Returns:

decorator_repeat : function
 decorator function

5.37.1.5 set_unit()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.set_unit (  
    unit)
```

Register a unit on a function

5.37.1.6 singleton()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.singleton (  
    cls)
```

Make a class a Singleton class (only one instance)

5.37.1.7 slow_down()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.slow_down (
    _func = None,
    * ,
    rate = 1)
```

Sleep given amount of seconds before calling the function

5.37.1.8 timer()

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.timer (
    func)
```

Print the runtime of the decorated function

5.37.2 Variable Documentation

5.37.2.1 string_types

```
tuple SMT.SMT_Analysis_BP.helpers.misc.decorators.string_types = (type(b''), type(u''))
```

5.38 SMT.SMT_Analysis_BP.helpers.misc.diff_mw Namespace Reference

Functions

- [mw_to_diff](#) (mw, n, T=310.15, micron=True)

Variables

- int [mw_RPOC](#) = 155160
- int [mw_NUSA](#) = 54871
- int [mw_LACI](#) = 38590
- int [mw_RNAP](#) = 350000
- int [vis_ecoli](#) = 950
- float [vis_cyto_ecoli](#) = 2.82
- [dif_RPOC](#) = [mw_to_diff](#)([mw_RPOC](#),[vis_cyto_ecoli](#))
- [dif_NUSA](#) = [mw_to_diff](#)([mw_NUSA](#),[vis_cyto_ecoli](#))
- [dif_LACI](#) = [mw_to_diff](#)([mw_LACI](#),[vis_cyto_ecoli](#))
- [dif_RNAP](#) = [mw_to_diff](#)([mw_RNAP](#),[vis_cyto_ecoli](#))

5.38.1 Function Documentation

5.38.1.1 mw_to_diff()

```
SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_to_diff (
    mw,
    n,
    T = 310.15,
    micron = True)
```

Documentation:

Given the molecular weight, returns the diffusion coefficient assuming a spherical shape of the molecule wh

From: A Novel Correlation for Protein Diffusion Coefficients Based on Molecular Weight and Radius of Gyration

Parameters:

mw = molecular weight in g*mol⁻¹

n = solution viscosity in c*P

T = Temperature of the solution in K (default is 310.15K = 37C)

```
micron = if True:
    return diffusion coefficient value as um^2*s^-1
if False:
    return diffusion coefficient value as m^2*s^-1
```

Return:

Diffusion Coefficient in m²*s⁻¹ if micron is False

5.38.2 Variable Documentation

5.38.2.1 dif_LACI

```
SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_LACI = mw_to_diff(mw_LACI,vis_cyto_ecoli)
```

5.38.2.2 dif_NUSA

```
SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_NUSA = mw_to_diff(mw_NUSA,vis_cyto_ecoli)
```

5.38.2.3 dif_RNAP

```
SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_RNAP = mw_to_diff(mw_RNAP,vis_cyto_ecoli)
```

5.38.2.4 dif_RPOC

```
SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_RPOC = mw_to_diff(mw_RPOC,vis_cyto_ecoli)
```

5.38.2.5 mw_LACI

```
int SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_LACI = 38590
```

5.38.2.6 mw_NUSA

```
int SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_NUSA = 54871
```

5.38.2.7 mw_RNAP

```
int SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_RNAP = 350000
```

5.38.2.8 mw_RPOC

```
int SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_RPOC = 155160
```

5.38.2.9 vis_cyto_ecoli

```
float SMT.SMT_Analysis_BP.helpers.misc.diff_mw.vis_cyto_ecoli = 2.82
```

5.38.2.10 vis_ecoli

```
int SMT.SMT_Analysis_BP.helpers.misc.diff_mw.vis_ecoli = 950
```

5.39 SMT.SMT_Analysis_BP.helpers.misc.errors Namespace Reference

Classes

- class [InitializationKeys](#)
- class [InitializationValues](#)

5.40 SMT.SMT_Analysis_BP.helpers.misc.guassian_fit Namespace Reference

Classes

- class [SM_Localization_Image](#)
- class [SM_localization_movie](#)

Functions

- [gaussian2D](#) (x, y, cen_x, cen_y, sig_x, sig_y, offset, height, kwargs={})
define some gaussian models for fitting
- [gaussian2D_theta](#) (x, y, cen_x, cen_y, sig_x, sig_y, theta, offset, height, kwargs={})
- [gaussian1D](#) (x, cen_x, sig_x, offset, height, kwargs={})
- [gaussian2D_residual](#) (params, x, y, data, kwargs={})
define some residual functions for fitting
- [gaussian2D_theta_residual](#) (params, x, y, data, kwargs={})
- [gaussian1D_residual](#) (params, x, data, kwargs={})
- [find_peaks](#) (image, **kwargs)
define functions to find candidate peaks in a signal for a 2D signal (image)
- [save_dataframe](#) (pd.DataFrame df, str path)

Variables

- str [path](#) = "/Volumes/Balijot_HD/SMT_Olympus/Balijot_temp/20190527/rpoc_ez/Movie/rpoc_ez_6.tif"
- [image](#) = imread([path](#))
- [sm_localization_movie](#) = [SM_localization_movie](#)([image](#))
- [fit_results_df](#)

5.40.1 Function Documentation

5.40.1.1 find_peaks()

```
SMT.SMT_Analysis_BP.helpers.misc.gaussian_fit.find_peaks (
    image,
    ** kwargs)
```

define functions to find candidate peaks in a signal for a 2D signal (image)

Finds candidate peaks in a 2D image using skimage.feature.peak_local_max

Parameters:

```
image: 2D numpy array
    image to find peaks in
kwargs: dict
    dictionary of keyword arguments to pass to peak_local_max
    See skimage.feature.peak_local_max for more details
    Some useful kwargs:
        min_distance: int
            minimum distance in pixels between peaks
        threshold_abs: int
            minimum intensity of peaks
        exclude_border: int
            number of pixels to exclude from the border of the image
```

5.40.1.2 gaussian1D()

```
SMT.SMT_Analysis_BP.helpers.misc.gaussian_fit.gaussian1D (
    x,
    cen_x,
    sig_x,
    offset,
    height,
    kwargs = {})
```

1d gaussian function

5.40.1.3 gaussian1D_residual()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian1D_residual (
    params,
    x,
    data,
    kwargs = {})

1d gaussian residual function
```

5.40.1.4 gaussian2D()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D (
    x,
    y,
    cen_x,
    cen_y,
    sig_x,
    sig_y,
    offset,
    height,
    kwargs = {})
```

define some gaussian models for fitting

2d gaussian function no theta

5.40.1.5 gaussian2D_residual()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D_residual (
    params,
    x,
    y,
    data,
    kwargs = {})
```

define some residual functions for fitting

2d gaussian residual function

5.40.1.6 gaussian2D_theta()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D_theta (
    x,
    y,
    cen_x,
    cen_y,
    sig_x,
    sig_y,
    theta,
    offset,
    height,
    kwargs = {})
```

2d gaussian function with theta

5.40.1.7 gaussian2D_theta_residual()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D_theta_residual (
    params,
    x,
    y,
    data,
    kwargs = {})
```

2d gaussian residual function with theta

5.40.1.8 save_dataframe()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.save_dataframe (
    pd.DataFrame df,
    str path)
```

Saves a dataframe to a csv file

Parameters:

df: pandas.DataFrame
dataframe to save

path: str
path to save the dataframe to

5.40.2 Variable Documentation

5.40.2.1 fit_results_df

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.fit_results_df
```

Initial value:

```
00001 = sm_localization_movie.fit(
00002     gaussian2D_residual,
00003     {'cen_x':0,'cen_y':0,'sig_x':1,'sig_y':1,'offset':0,'height':1},
00004     {'cen_x':(-np.inf,np.inf),'cen_y':(-np.inf,np.inf),'sig_x':(0,np.inf),'sig_y':(0,np.inf),'offset':(-np.inf,np.inf),'height':(0,np.inf)},
00005     prune_direction={'sig_x':(0.7,2),'sig_y':(0.7,2)})
```

5.40.2.2 image

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.image = imread(path)
```

5.40.2.3 path

```
str SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.path = "/Volumes/Bal jyot_HD/SMT_Olympus/Bal jyot←
_temp/20190527/rpoc_ez/Movie/rpoc_ez_6.tif"
```

5.40.2.4 sm_localization_movie

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.sm_localization_movie = SM_localization_movie(image)
```

5.41 SMT.SMT_Analysis_BP.Parameter_Store Namespace Reference

Namespaces

- namespace [global_params](#)

5.42 SMT.SMT_Analysis_BP.Parameter_Store.global_params Namespace Reference

Variables

- dict [PIXELSIZE](#)
- dict [PHOTON_CONVERSION_FACTORS](#)
- dict [READOUT_NOISE](#)
- dict [DARK_OFFSET](#)
- dict [QUANTUM_EFFICIENCY_561](#)

5.42.1 Detailed Description

This file contains all the global parameters that are used in the code.
These parameters are used in different modules of the code, and may not be useful for the user to change.

Author: Baljyot Singh Parmar
Date: 2023-04-20

5.42.2 Variable Documentation

5.42.2.1 DARK_OFFSET

```
dict SMT.SMT_Analysis_BP.Parameter_Store.global_params.DARK_OFFSET
```

Initial value:

```
00001 = {"olympus_sCMOS_old":100,  
00002         "olympus_sCMOS_new":100,  
00003         "confocal":None}
```

5.42.2.2 PHOTON_CONVERSION_FACTORS

```
dict SMT.SMT_Analysis_BP.Parameter_Store.global_params.PHOTON_CONVERSION_FACTORS
```

Initial value:

```
00001 = {"olympus_sCMOS_old":0.49,  
00002         "olympus_sCMOS_new":0.23,  
00003         "confocal":None}
```

5.42.2.3 PIXELSIZES

```
dict SMT.SMT_Analysis_BP.Parameter_Store.global_params.PIXELSIZES
```

Initial value:

```
00001 = {"olympus_pixel_size":130,
00002      "confocal_pixel_size":79,
00003      "olympus_pixel_size_1x1":65}
```

5.42.2.4 QUANTUM_EFFICIENCY_561

```
dict SMT.SMT_Analysis_BP.Parameter_Store.global_params.QUANTUM_EFFICIENCY_561
```

Initial value:

```
00001 = {"olympus_sCMOS_old":0.71,
00002      "olympus_sCMOS_new":0.95,
00003      "confocal":None}
```

5.42.2.5 READOUT_NOISE

```
dict SMT.SMT_Analysis_BP.Parameter_Store.global_params.READOUT_NOISE
```

Initial value:

```
00001 = {"olympus_sCMOS_old":1.9,
00002      "olympus_sCMOS_new":1.35,
00003      "confocal":None}
```

5.43 testing_new_script Namespace Reference

Variables

- str `dir_tiff` = '/Volumes/Balijot_HD/SMT_Olympus/Balijot_temp/12/rpoc_m9'
- files = glob.glob(`dir_tiff` + '/' + '*seg.tif')
- str `root` = `dir_tiff`
- str `save_analysis_dir` = `dir_tiff` + '/' + 'Analysis_test'
- str `name_fil` = files[z]
- imp = IJ.openImage(`str_name_fil`)
- dims = imp.getDimensions();
- model = Model()
- logger = Logger.IJ_LOGGER
- settings = Settings(imp)
- detectorFactory
- detectorSettings
- trackerFactory
- trackerSettings
- initialSpotFilterValue
- trackmate = TrackMate(model, settings)
- ok = trackmate.checkInput()
- selectionModel = SelectionModel(model)
- displayer = HyperStackDisplayer(model, selectionModel, imp)
- int `go` = 0
- fm = model.getFeatureModel()
- a = model.getSpots().iterator(True)

- `str cd = root`
- `v = fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')`
- `track = model.getTrackModel().trackSpots(id)`
- `sid = spot.ID()`
- `x = spot.getFeature('POSITION_X')`
- `y = spot.getFeature('POSITION_Y')`
- `t = spot.getFeature('FRAME')`
- `rad = spot.getFeature('RADIUS')`
- `q = spot.getFeature('QUALITY')`
- `snr = spot.getFeature('SNR')`
- `mean = spot.getFeature('MEAN_INTENSITY')`
- `str dir_name_save_inten = save_analysis_dir + '/' + files[z][:-4] + '.tif_spots' + '.csv'`
- `spamWriter = csv.writer(f, delimiter=',')`

5.43.1 Variable Documentation

5.43.1.1 a

```
testing_new_script.a = model.getSpots().iterator(True)
```

5.43.1.2 cd

```
str testing_new_script.cd = root
```

5.43.1.3 detectorFactory

```
testing_new_script.detectorFactory
```

5.43.1.4 detectorSettings

```
testing_new_script.detectorSettings
```

5.43.1.5 dims

```
testing_new_script.dims = imp.getDimensions();
```

5.43.1.6 dir_name_save_inten

```
str testing_new_script.dir_name_save_inten = save_analysis_dir + '/' + files[z][:-4] + '.tif←
_spots' + '.csv'
```

5.43.1.7 dir_tiff

```
str testing_new_script.dir_tiff = '/Volumes/Baljyot_HD/SMT_Olympus/Baljyot_temp/12/rpoc_m9'
```

5.43.1.8 **displayer**

```
testing_new_script.displayer = HyperStackDisplayer(model, selectionModel, imp)
```

5.43.1.9 **files**

```
testing_new_script.files = glob.glob(dir_tiff + '/' + '*seg.tif')
```

5.43.1.10 **fm**

```
testing_new_script.fm = model.getFeatureModel()
```

5.43.1.11 **go**

```
int testing_new_script.go = 0
```

5.43.1.12 **imp**

```
testing_new_script.imp = IJ.openImage(str_name_fil)
```

5.43.1.13 **initialSpotFilterValue**

```
testing_new_script.initialSpotFilterValue
```

5.43.1.14 **logger**

```
testing_new_script.logger = Logger.IJ_LOGGER
```

5.43.1.15 **mean**

```
testing_new_script.mean = spot.getFeature('MEAN_INTENSITY')
```

5.43.1.16 **model**

```
testing_new_script.model = Model()
```

5.43.1.17 **ok**

```
testing_new_script.ok = trackmate.checkInput()
```

5.43.1.18 q

```
testing_new_script.q = spot.getFeature('QUALITY')
```

5.43.1.19 rad

```
testing_new_script.rad = spot.getFeature('RADIUS')
```

5.43.1.20 root

```
str testing_new_script.root = dir_tiff
```

5.43.1.21 save_analysis_dir

```
str testing_new_script.save_analysis_dir = dir_tiff + '/' + 'Analysis_test'
```

5.43.1.22 selectionModel

```
testing_new_script.selectionModel = SelectionModel(model)
```

5.43.1.23 settings

```
testing_new_script.settings = Settings(imp)
```

5.43.1.24 sid

```
testing_new_script.sid = spot.ID()
```

5.43.1.25 snr

```
testing_new_script.snr = spot.getFeature('SNR')
```

5.43.1.26 spamWriter

```
testing_new_script.spamWriter = csv.writer(f, delimiter=',')
```

5.43.1.27 str_name_fil

```
testing_new_script.str_name_fil = files[z]
```

5.43.1.28 t

```
testing_new_script.t = spot.getFeature('FRAME')
```

5.43.1.29 track

```
testing_new_script.track = model.getTrackModel().trackSpots(id)
```

5.43.1.30 trackerFactory

```
testing_new_script.trackerFactory
```

5.43.1.31 trackerSettings

```
testing_new_script.trackerSettings
```

5.43.1.32 trackmate

```
testing_new_script.trackmate = TrackMate(model, settings)
```

5.43.1.33 v

```
testing_new_script.v = fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')
```

5.43.1.34 x

```
testing_new_script.x = spot.getFeature('POSITION_X')
```

5.43.1.35 y

```
testing_new_script.y = spot.getFeature('POSITION_Y')
```

5.44 tracking_tif_jpy Namespace Reference

Variables

- `str dir_tiff = '/Users/baljyot/Documents/2019-2020/RNAP_PAPER/Baljyot_EXP_RPOC/DATA/new_↵`
days/20190527/ll_ez/segmented'
- `list files = [fi for fi in files if fi.endswith("seg.tif")]`
- `num_files = len(files)`
- `str save_analysis_dir = dir_tiff + '/' + 'Analysis'`
- `str str_name_fil = root + '/' + files [z]`
- `imp = IJ.openImage(str_name_fil)`
- `model = Model()`
- `settings = Settings()`
- `detectorFactory`
- `detectorSettings`
- `trackerFactory`
- `trackerSettings`
- `trackmate = TrackMate(model, settings)`
- `ok = trackmate.checkInput()`
- `selectionModel = SelectionModel(model)`
- `displayer = HyperStackDisplayer(model, selectionModel, imp)`
- `int go = 0`
- `fm = model.getFeatureModel()`
- `a = model.getSpots().iterator(True)`
- `str cd = "D:\\Baljyot_Experiments\\20190524\\rpoc\\segmented"`
- `x = i.getFeature("POSITION_X")`
- `y = i.getFeature("POSITION_Y")`
- `std = i.getFeature("STANDARD_DEVIATION")`
- `rad = i.getFeature("RADIUS")`
- `ed = i.getFeature("ESTIMATED_DIAMETER")`
- `str dir_name_save_inten = save_analysis_dir + '/' + files[z] + '_' + 'spots' + '.csv'`
- `spamWriter = csv.writer(f, delimiter=',')`

5.44.1 Variable Documentation

5.44.1.1 a

```
tracking_tif_jpy.a = model.getSpots().iterator(True)
```

5.44.1.2 cd

```
str tracking_tif_jpy.cd = "D:\\Baljyot_Experiments\\20190524\\rpoc\\segmented"
```

5.44.1.3 detectorFactory

```
tracking_tif_jpy.detectorFactory
```

5.44.1.4 detectorSettings

```
tracking_tif_jpy.detectorSettings
```

5.44.1.5 dir_name_save_inten

```
str tracking_tif_jpy.dir_name_save_inten = save_analysis_dir + '/' + files[z] + '_' + 'spots' + '.csv'
```

5.44.1.6 dir_tiff

```
str tracking_tif_jpy.dir_tiff = '/Users/baljyot/Documents/2019-2020/RNAP_PAPER/Baljyot_EXP_↵RPOC/DATA/new_days/20190527/1l_ez/segmented'
```

5.44.1.7 displayer

```
tracking_tif_jpy.displayer = HyperStackDisplayer(model, selectionModel, imp)
```

5.44.1.8 ed

```
tracking_tif_jpy.ed = i.getFeature("ESTIMATED_DIAMETER")
```

5.44.1.9 files

```
list tracking_tif_jpy.files = [ fi for fi in files if fi.endswith("seg.tif") ]
```

5.44.1.10 fm

```
tracking_tif_jpy.fm = model.getFeatureModel()
```

5.44.1.11 go

```
int tracking_tif_jpy.go = 0
```

5.44.1.12 imp

```
tracking_tif_jpy.imp = IJ.openImage(str_name_fil)
```

5.44.1.13 model

```
tracking_tif_jpy.model = Model()
```

5.44.1.14 num_files

```
tracking_tif_jpy.num_files = len(files)
```

5.44.1.15 ok

```
tracking_tif_jpy.ok = trackmate.checkInput()
```

5.44.1.16 rad

```
tracking_tif_jpy.rad = i.getFeature("RADIUS")
```

5.44.1.17 save_analysis_dir

```
str tracking_tif_jpy.save_analysis_dir = dir_tiff + '/' + 'Analysis'
```

5.44.1.18 selectionModel

```
tracking_tif_jpy.selectionModel = SelectionModel(model)
```

5.44.1.19 settings

```
tracking_tif_jpy.settings = Settings()
```

5.44.1.20 spamWriter

```
tracking_tif_jpy.spamWriter = csv.writer(f, delimiter=',')
```

5.44.1.21 std

```
tracking_tif_jpy.std = i.getFeature("STANDARD_DEVIATION")
```

5.44.1.22 str_name_fil

```
str tracking_tif_jpy.str_name_fil = root + '/' + files [z]
```

5.44.1.23 trackerFactory

```
tracking_tif_jpy.trackerFactory
```

5.44.1.24 trackerSettings

```
tracking_tif_jpy.trackerSettings
```

5.44.1.25 trackmate

```
tracking_tif_jpy.trackmate = TrackMate(model, settings)
```

5.44.1.26 x

```
tracking_tif_jpy.x = i.getFeature("POSITION_X")
```

5.44.1.27 y

```
tracking_tif_jpy.y = i.getFeature("POSITION_Y")
```

5.45 tracking_tif_jpy_track Namespace Reference

Variables

- str `dir_tiff` = '/Users/baljyot/Documents/2022-2023/PhD Thesis/Random_data'
- list `files` = ['Hurst_0.5_Diff_1e-2_seg.tiff']
- str `root` = `dir_tiff`
- str `save_analysis_dir` = `dir_tiff` + '/' + 'Analysis'
- str `str_name_fil` = `root` + '/' + `files`[z]
- `imp` = `IJ.openImage(str_name_fil)`
- `dims` = `imp.getDimensions()`;
- `model` = `Model()`
- `settings` = `Settings()`
- `detectorFactory`
- `detectorSettings`
- `trackerFactory`
- `trackerSettings`
- `initialSpotFilterValue`
- `trackmate` = `TrackMate(model, settings)`
- `ok` = `trackmate.checkInput()`
- `selectionModel` = `SelectionModel(model)`
- `displayer` = `HyperStackDisplayer(model, selectionModel, imp)`
- int `go` = 0
- `fm` = `model.getFeatureModel()`
- `a` = `model.getSpots().iterator(True)`
- str `cd` = "/Users/baljyot/Documents/2022-2023/PhD Thesis/Random_data"
- `v` = `fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')`
- `track` = `model.getTrackModel().trackSpots(id)`
- `sid` = `spot.ID()`
- `x` = `spot.getFeature('POSITION_X')`
- `y` = `spot.getFeature('POSITION_Y')`
- `t` = `spot.getFeature('FRAME')`
- `rad` = `spot.getFeature('RADIUS')`
- `q` = `spot.getFeature('QUALITY')`
- `snr` = `spot.getFeature('SNR')`
- `mean` = `spot.getFeature('MEAN_INTENSITY')`
- str `dir_name_save_inten` = `save_analysis_dir` + '/' + `files`[z][:-4] + '.tif_spots' + '.csv'
- `spamWriter` = `csv.writer(f, delimiter=',')`

5.45.1 Variable Documentation

5.45.1.1 a

```
tracking_tif_jpy_track.a = model.getSpots().iterator(True)
```

5.45.1.2 cd

```
str tracking_tif_jpy_track.cd = "/Users/baljyot/Documents/2022-2023/PhD Thesis/Random_data"
```

5.45.1.3 detectorFactory

```
tracking_tif_jpy_track.detectorFactory
```

5.45.1.4 detectorSettings

```
tracking_tif_jpy_track.detectorSettings
```

5.45.1.5 dims

```
tracking_tif_jpy_track.dims = imp.getDimensions();
```

5.45.1.6 dir_name_save_inten

```
str tracking_tif_jpy_track.dir_name_save_inten = save_analysis_dir + '/' + files[z][-4] +  
' .tif_spots' + '.csv'
```

5.45.1.7 dir_tiff

```
str tracking_tif_jpy_track.dir_tiff = '/Users/baljyot/Documents/2022-2023/PhD Thesis/Random_  
data'
```

5.45.1.8 displayer

```
tracking_tif_jpy_track.displayer = HyperStackDisplayer(model, selectionModel, imp)
```

5.45.1.9 files

```
list tracking_tif_jpy_track.files = ["Hurst_0.5_Diff_1e-2_seg.tiff"]
```

5.45.1.10 fm

```
tracking_tif_jpy_track.fm = model.getFeatureModel()
```

5.45.1.11 go

```
int tracking_tif_jpy_track.go = 0
```

5.45.1.12 imp

```
tracking_tif_jpy_track.imp = IJ.openImage(str_name_fil)
```

5.45.1.13 initialSpotFilterValue

```
tracking_tif_jpy_track.initialSpotFilterValue
```

5.45.1.14 mean

```
tracking_tif_jpy_track.mean = spot.getFeature('MEAN_INTENSITY')
```

5.45.1.15 model

```
tracking_tif_jpy_track.model = Model()
```

5.45.1.16 ok

```
tracking_tif_jpy_track.ok = trackmate.checkInput()
```

5.45.1.17 q

```
tracking_tif_jpy_track.q = spot.getFeature('QUALITY')
```

5.45.1.18 rad

```
tracking_tif_jpy_track.rad = spot.getFeature('RADIUS')
```

5.45.1.19 root

```
str tracking_tif_jpy_track.root = dir_tiff
```

5.45.1.20 save_analysis_dir

```
str tracking_tif_jpy_track.save_analysis_dir = dir_tiff + '/' + 'Analysis'
```

5.45.1.21 selectionModel

```
tracking_tif_jpy_track.selectionModel = SelectionModel(model)
```

5.45.1.22 settings

```
tracking_tif_jpy_track.settings = Settings()
```

5.45.1.23 sid

```
tracking_tif_jpy_track.sid = spot.ID()
```

5.45.1.24 snr

```
tracking_tif_jpy_track.snr = spot.getFeature('SNR')
```

5.45.1.25 spamWriter

```
tracking_tif_jpy_track.spamWriter = csv.writer(f, delimiter=',')
```

5.45.1.26 str_name_fil

```
str tracking_tif_jpy_track.str_name_fil = root + '/' + files[z]
```

5.45.1.27 t

```
tracking_tif_jpy_track.t = spot.getFeature('FRAME')
```

5.45.1.28 track

```
tracking_tif_jpy_track.track = model.getTrackModel().trackSpots(id)
```

5.45.1.29 trackerFactory

```
tracking_tif_jpy_track.trackerFactory
```

5.45.1.30 trackerSettings

```
tracking_tif_jpy_track.trackerSettings
```

5.45.1.31 trackmate

```
tracking_tif_jpy_track.trackmate = TrackMate(model, settings)
```

5.45.1.32 v

```
tracking_tif_jpy_track.v = fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')
```

5.45.1.33 x

```
tracking_tif_jpy_track.x = spot.getFeature('POSITION_X')
```

5.45.1.34 y

```
tracking_tif_jpy_track.y = spot.getFeature('POSITION_Y')
```

5.46 trackmate_exp Namespace Reference

Variables

- `imp` = `IJ.openImage('/Users/balijot/Desktop/Balijot_EXP_RPOC/Scripts/0.tif')`
- `model` = `Model()`
- `settings` = `Settings()`
- `detectorFactory`
- `detectorSettings`
- `trackerFactory`
- `trackerSettings`
- `initialSpotFilterValue`
- `trackmate` = `TrackMate(model, settings)`
- `ok` = `trackmate.checkInput()`
- `selectionModel` = `SelectionModel(model)`
- `displayer` = `HyperStackDisplayer(model, selectionModel, imp)`
- `fm` = `model.getFeatureModel()`
- `v` = `fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')`
- `track` = `model.getTrackModel().trackSpots(id)`
- `sid` = `spot.ID()`
- `x` = `spot.getFeature('POSITION_X')`
- `y` = `spot.getFeature('POSITION_Y')`
- `t` = `spot.getFeature('FRAME')`
- `q` = `spot.getFeature('QUALITY')`
- `snr` = `spot.getFeature('SNR')`
- `mean` = `spot.getFeature('MEAN_INTENSITY')`

5.46.1 Variable Documentation

5.46.1.1 detectorFactory

```
trackmate_exp.detectorFactory
```

5.46.1.2 detectorSettings

```
trackmate_exp.detectorSettings
```

5.46.1.3 displayer

```
trackmate_exp.displayer = HyperStackDisplayer(model, selectionModel, imp)
```

5.46.1.4 fm

```
trackmate_exp.fm = model.getFeatureModel()
```

5.46.1.5 imp

```
trackmate_exp.imp = IJ.openImage('/Users/baljyot/Desktop/Baljyot_EXP_RPOC/Scripts/0.tif')
```

5.46.1.6 initialSpotFilterValue

```
trackmate_exp.initialSpotFilterValue
```

5.46.1.7 mean

```
trackmate_exp.mean = spot.getFeature('MEAN_INTENSITY')
```

5.46.1.8 model

```
trackmate_exp.model = Model()
```

5.46.1.9 ok

```
trackmate_exp.ok = trackmate.checkInput()
```

5.46.1.10 q

```
trackmate_exp.q = spot.getFeature('QUALITY')
```

5.46.1.11 selectionModel

```
trackmate_exp.selectionModel = SelectionModel(model)
```

5.46.1.12 settings

```
trackmate_exp.settings = Settings()
```

5.46.1.13 sid

```
trackmate_exp.sid = spot.ID()
```

5.46.1.14 snr

```
trackmate_exp.snr = spot.getFeature('SNR')
```

5.46.1.15 t

```
trackmate_exp.t = spot.getFeature('FRAME')
```

5.46.1.16 track

```
trackmate_exp.track = model.getTrackModel().trackSpots(id)
```

5.46.1.17 trackerFactory

```
trackmate_exp.trackerFactory
```

5.46.1.18 trackerSettings

```
trackmate_exp.trackerSettings
```

5.46.1.19 trackmate

```
trackmate_exp.trackmate = TrackMate(model, settings)
```

5.46.1.20 v

```
trackmate_exp.v = fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')
```

5.46.1.21 x

```
trackmate_exp.x = spot.getFeature('POSITION_X')
```

5.46.1.22 y

```
trackmate_exp.y = spot.getFeature('POSITION_Y')
```

5.47 trackmate_scripting Namespace Reference

Variables

- `imp` = `IJ.openImage('https://fiji.sc/samples/FakeTracks.tif')`
- `model` = `Model()`
- `settings` = `Settings(imp)`
- `detectorFactory`
- `detectorSettings`
- `trackerFactory`
- `trackerSettings`
- `initialSpotFilterValue`
- `trackmate` = `TrackMate(model, settings)`
- `ok` = `trackmate.checkInput()`
- `sm` = `SelectionModel(model)`
- `ds` = `DisplaySettingsIO.readUserDefault()`
- `displayer` = `HyperStackDisplayer(model, sm, imp, ds)`
- `fm` = `model.getFeatureModel()`
- `v` = `fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')`
- `track` = `model.getTrackModel().trackSpots(id)`
- `sid` = `spot.ID()`
- `x` = `spot.getFeature('POSITION_X')`
- `y` = `spot.getFeature('POSITION_Y')`
- `t` = `spot.getFeature('FRAME')`
- `q` = `spot.getFeature('QUALITY')`
- `snr` = `spot.getFeature('SNR_CH1')`
- `mean` = `spot.getFeature('MEAN_INTENSITY_CH1')`

5.47.1 Variable Documentation

5.47.1.1 detectorFactory

```
trackmate_scripting.detectorFactory
```

5.47.1.2 detectorSettings

```
trackmate_scripting.detectorSettings
```

5.47.1.3 **displayer**

```
trackmate_scripting.displayer = HyperStackDisplayer( model, sm, imp, ds )
```

5.47.1.4 **ds**

```
trackmate_scripting.ds = DisplaySettingsIO.readUserDefault()
```

5.47.1.5 **fm**

```
trackmate_scripting.fm = model.getFeatureModel()
```

5.47.1.6 **imp**

```
trackmate_scripting.imp = IJ.openImage('https://fiji.sc/samples/FakeTracks.tif')
```

5.47.1.7 **initialSpotFilterValue**

```
trackmate_scripting.initialSpotFilterValue
```

5.47.1.8 **mean**

```
trackmate_scripting.mean = spot.getFeature('MEAN_INTENSITY_CH1')
```

5.47.1.9 **model**

```
trackmate_scripting.model = Model()
```

5.47.1.10 **ok**

```
trackmate_scripting.ok = trackmate.checkInput()
```

5.47.1.11 **q**

```
trackmate_scripting.q = spot.getFeature('QUALITY')
```

5.47.1.12 **settings**

```
trackmate_scripting.settings = Settings(imp)
```


5.47.1.13 sid

```
trackmate_scripting.sid = spot.ID()
```

5.47.1.14 sm

```
trackmate_scripting.sm = SelectionModel( model )
```

5.47.1.15 snr

```
trackmate_scripting.snr = spot.getFeature('SNR_CH1')
```

5.47.1.16 t

```
trackmate_scripting.t = spot.getFeature('FRAME')
```

5.47.1.17 track

```
trackmate_scripting.track = model.getTrackModel().trackSpots(id)
```

5.47.1.18 trackerFactory

```
trackmate_scripting.trackerFactory
```

5.47.1.19 trackerSettings

```
trackmate_scripting.trackerSettings
```

5.47.1.20 trackmate

```
trackmate_scripting.trackmate = TrackMate(model, settings)
```

5.47.1.21 v

```
trackmate_scripting.v = fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')
```

5.47.1.22 x

```
trackmate_scripting.x = spot.getFeature('POSITION_X')
```

5.47.1.23 y

```
trackmate_scripting.y = spot.getFeature('POSITION_Y')
```

5.48 utility_database Namespace Reference

Classes

- class [Counter_start_stop](#)

Variables

- list [ALLOWED_START_TYPES](#) = [int,float]

5.48.1 Variable Documentation

5.48.1.1 ALLOWED_START_TYPES

```
list utility_database.ALLOWED_START_TYPES = [int,float]
```

Chapter 6

Class Documentation

6.1 SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage Class Reference

Public Member Functions

- None `__init__` (self, [name](#), [track_class_type](#), [storage_data](#))
- [ensemble_angles](#) (self)
- [ensemble_angles](#) (self, [ensemble_angles](#))
- [track_angles](#) (self)
- [track_angles](#) (self, [track_angles](#))
- [track_lengths](#) (self)
- [track_lengths](#) (self, [track_lengths](#))
- [track_storage](#) (self)
- [track_storage](#) (self, [track_storage](#))

Public Attributes

- [name](#)
- [track_class_type](#)
- [storage_data](#)

Protected Member Functions

- [_store_data](#) (self)

Protected Attributes

- [_ensemble_angles](#)
- [_track_angles](#)
- [_track_lengths](#)
- [_track_storage](#)

6.1.1 Constructor & Destructor Documentation

6.1.1.1 `__init__()`

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.__↵
init__ (
    self,
    name,
    track_class_type,
    storage_data)
```

6.1.2 Member Function Documentation

6.1.2.1 `_store_data()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage._store_data
(
    self) [protected]
```

6.1.2.2 `ensemble_angles()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.ensemble_↵
angles (
    self)
```

6.1.2.3 `ensemble_angles()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.ensemble_↵
angles (
    self,
    ensemble_angles)
```

6.1.2.4 `track_angles()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.track_angles
(
    self)
```

6.1.2.5 `track_angles()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.track_angles
(
    self,
    track_angles)
```

6.1.2.6 track_lengths() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.track↵  
lengths (  
    self)
```

6.1.2.7 track_lengths() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.track↵  
lengths (  
    self,  
    track_lengths)
```

6.1.2.8 track_storage() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.track↵  
storage (  
    self)
```

6.1.2.9 track_storage() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.track↵  
storage (  
    self,  
    track_storage)
```

6.1.3 Member Data Documentation

6.1.3.1 _ensemble_angles

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage._ensemble↵  
angles [protected]
```

6.1.3.2 _track_angles

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage._track↵  
angles [protected]
```

6.1.3.3 _track_lengths

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage._track↵  
lengths [protected]
```

6.1.3.4 `_track_storage`

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage._track_↵
storage [protected]`

6.1.3.5 `name`

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.name`

6.1.3.6 `storage_data`

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.storage_data`

6.1.3.7 `track_class_type`

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage.track_↵
class_type`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↵
BP/helpers/analysisFunctions/angle_between_vectors.py`

6.2 `SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.↵ blob_detection` Class Reference

Public Member Functions

- `__init__` (self, path, [median](#)=False, [threshold](#)=0.0005, [min_sigma](#)=1.0, [max_sigma](#)=1.5, [num_sigma](#)=500, [overlap](#)=1., [logscale](#)=False, [verbose](#)=False, [exclude_border](#)=False)
- `open_file` (self)
- `detection` (self, type='skimage', **kwargs)
- `blob_logv2` (self, image, [min_sigma](#)=1, [max_sigma](#)=50, [num_sigma](#)=10, [threshold](#)=.2, [overlap](#)=↵
5, [log_scale](#)=False, *, [exclude_border](#)=False, **kwargs)
- `italize_2dgaus` (self, **kwargs)

Public Attributes

- [img](#)
- [median](#)
- [threshold](#)
- [min_sigma](#)
- [max_sigma](#)
- [num_sigma](#)
- [overlap](#)
- [log_scale](#)
- [median_filter_size](#)
- [fitting_parameters](#)
- [verbose](#)

Protected Member Functions

- [_update_fitting_parameters](#) (self, kwargs={})
- [_prune_blobs](#) (self, blobs_array, [overlap](#), *, sigma_dim=1, **kwargs)
- [_update_blob_estimate](#) (self, blobs_pruned, fit_object, radius_func=None)
- [_create_mask](#) (self, [img](#), coords, size, sigma_idx)
- [_gaussian_mesh_helper](#) (self, mesh_2d, initial_xy, sub_arr=[3, 3])

6.2.1 Detailed Description

Parameters TODO

Path : string

Full path of the image to be read

median : bool

if true apply a median filter to the image before blob detection

threshold : float

threshold for the blob detection

min_sigma : float

Minimum value of the gaussian sigma for the blobs

max_sigma : float

Maximum value of the gaussian sigma for the blobs

num_sigma : int

Eqidistant values between min_sigma and max_sigma to consider

overlap : float

Allowed overlap of identified blobs. If 1, full overlap is allowed

Methods TODO

open_file()

opens the file and applied media filter if true

returns an array

detection()

applies blob detection using np.blob_log

returns array of blob attributes or dictionary of blob attributes

Notes

theory: https://www.cse.psu.edu/~rtc12/CSE586/lectures/featureExtractionPart2_6pp.pdf

https://cvgl.stanford.edu/teaching/cs231a_winter1415/lecture/lecture10_detector_descriptors_2015_notes.pdf

6.2.2 Constructor & Destructor Documentation

6.2.2.1 `__init__()`

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.__init__ (

self,

path,

median = False,

threshold = 0.0005,

min_sigma = 1.0,

max_sigma = 1.5,

num_sigma = 500,

overlap = 1.,

logscale = False,

verbose = False,

exclude_border = False)

Initilizes the class object with the parameters for the blob detection

Parameters:

Path : string or 2d array

Full path of the image to be read or the 2d array of the image

median : bool

if true apply a median filter to the image before blog detection

threshold : float

threshold for the blob detection

min_sigma : float

Minimum value of the gaussian sigma for the blobs

max_sigma : float

Maximum value of the gaussian sigma for the blobs

num_sigma : int

Eqidistant values between min_sigma and max_sigma to consider

overlap : float

Allowed overlap of identified blobs. If 1, full overlap is allowed

logscale : bool

if True, use a log scale for the sigma values

verbose : bool

if True, return out the parameters used for the blob detection and fitting

exclude_border : tuple of ints, int, or False, optional, Default is False.

If tuple of ints, the length of the tuple must match the input array's dimensionality. Each element of the tuple will exclude peaks from within 'exclude_border'-pixels of the border of the image along that dimension.

If nonzero int, 'exclude_border' excludes peaks from within

'exclude_border'-pixels of the border of the image.

If zero or False, peaks are identified regardless of their

distance from the border. See method "blob_logv2" for more info

Notes:

1. The blob detection is done using the skimage.blob_log() function or a custom function. The custom function

2. To use the custom function, call the method detection() with the argument type='bp' else the default is 'sk

6.2.3 Member Function Documentation

6.2.3.1 _create_mask()

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection._create_mask (

self,

img,

coords,

size,

sigma_indx) [protected]

mask of the image at the center point of the pixel coordinate. Also applies the fits

TODO make this modular and seperate the mask creation and the fitting to allow better user control.

Parameters

img : 2D array

array defining the image

coords : (N,3) array

array defining the [x,y,radius] of the blobs

size : int

size of the square box around coord[:2] in which to fit

sigma_indx : N array

array defining the index of the sigmas used for each blob in coords

Returns

lmfit.minimize.fit objects in a list: [object, object, ...]

the fit objects created by lmfit.minizie for each coord.


```

Raises
-----
TypeError
    "size needs to an integer value"
Exception
    "simga_indx needs to be same shape as coords"

```

6.2.3.2 _gaussian_mesh_helper()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection._gaussian_mesh_helper
(
```

```

    self,
    mesh_2d,
    initial_xy,
    sub_arr = [3,3]) [protected]

```

takes a 2d_mesh (image data) and a bounding box to return a list of (x,y,z) in that bounding box
box is implimented from the center point of the pixel. this function works similar to Analysis_functions.subar

```
Parameters
-----
```

```

mesh_2d : 2D array
    image data in 2D array format
initial_xy : tuple or array-like of len 2
    [x,y] coordinate of the center point around which to create the subarray
sub_arr : tuple or 1D array, optional
    the grid size from the center to create the mesh, by default [3,3]

```

```
Returns
-----
```

```

1D list
    array containing:
        x,y: the x,y coordinates of the meshgrid
        mesh_view: subarray defined from the original image
        centers: centers of the mesh

```

6.2.3.3 _prune_blobs()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection._prune_blobs (
```

```

    self,
    blobs_array,
    overlap,
    * ,
    sigma_dim = 1,
    ** kwargs) [protected]

```

Eliminated blobs with area overlap. UPDATED: compared to the skimage implimentation this prunes based on the maximum value of the laplacian of the blobs rather than if the blob is bigger or not.

```
Parameters
-----
```

```

blobs_array : ndarray
    A 2d array with each row representing 3 (or 4) values,
    ``(row, col, sigma)`` or ``(pln, row, col, sigma)`` in 3D,
    where ``(row, col)`` or ``(pln, row, col)`` are coordinates of the blob
    and ``sigma`` is the standard deviation of the Gaussian kernel which
    detected the blob.
    This array must not have a dimension of size 0.
overlap : float
    A value between 0 and 1. If the fraction of area overlapping for 2

```

blobs is greater than 'overlap' the smaller blob is eliminated.
sigma_dim : int, optional
The number of columns in ``blobs_array`` corresponding to sigmas rather than positions.

KWARGS

max_lap: N-array

array of values for each blob indicating the max value of the laplacian that created it

sigma_idx: n-array

array of indexes of the sigmas for the blob, this is just inputted for convenience in later calculations. N

Returns

A : ndarray

'array' with overlapping blobs removed.

Notes

Example: blob1 = [100,100,3], blob2 = [101,101,3]

max_lap = [1,2]. If the overlap is larger than the threshold used then blob2 is chosen because it produces a

6.2.3.4 _update_blob_estimate()

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection._update_blob_estimate
(

self,

blobs_pruned,

fit_object,

radius_func = None) [protected]

Using fitted parameters update the estimates of the centroid and sigmas for blob fit

Parameters

blobs_pruned: (ndarray)

output from self._prune_blobs()

fit_object: (lmfit.minimize.fit object)

instances of the .fit object from lmfit's minimize

radius_func: (functional, optional)

Which function to use to remap anisotropic sigmas into isotropic sigma. Defaults to None.

Returns

(N,3) array

first output is [(x,y,s),...] of the blobs updates

(N,3) array

second is the original blobs inputted for comparison

6.2.3.5 _update_fitting_parameters()

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection._update_fitting_↵
parameters (

self,

kwargs = {}) [protected]

Updates the fitting_parameters to be used in each iteration of this class object

Kwargs

```
mask_size: int
    when fitting the image with a function this is size of square round a reference point to use for fit
residual_func: functional
    function to use when defining the residuals for the fitting
fit_method: string, default 'least squares'
    method of the fitting to use
radius_func: functional, default numpy.mean
    function to use as a method to take two sigams and convert to one radius
plot_fit: bool
    if True, plots each fit with the fit statistics
centroid_range: int or float-like
    controls the bounds on the fit for the centroid (x,y). Ie: the min fit is x-centroid_range, and max is x+centroid_range
    same for y.
sigma_range: int or float-like
    controls the bounds on the fit for the sigmas (s_x,s_y). Ie: the min fit is s_x-sigma_range, and max is s_x+sigma_range
    same for y.
fitting_image: string
    if "Original" use the original image to fit function
    else use the Laplacian image created with the sigma that maximized the laplacian
```

Notes

Some of these expect a certain type to work. This is not fully coded yet and might break if you give inputs wh to it.

6.2.3.6 blob_logv2()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.blob_logv2 (
    self,
    image,
    min_sigma = 1,
    max_sigma = 50,
    num_sigma = 10,
    threshold = .2,
    overlap = .5,
    log_scale = False,
    * ,
    exclude_border = False,
    ** kwargs)
```

Finds blobs in the given grayscale image. Adapted from the implimentation of skimage blob-log: https://scikit-image.org/docs/stable/auto_examples/features_detection/plot_blob.html

Blobs are found using the Laplacian of Gaussian (LoG) method [1]_.
For each blob found, the method returns its coordinates and the standard deviation of the Gaussian kernel that detected the blob.

Parameters

```
image : 2D or 3D ndarray
    Input grayscale image, blobs are assumed to be light on dark
    background (white on black).
min_sigma : scalar or sequence of scalars, optional
    the minimum standard deviation for Gaussian kernel. Keep this low to
    detect smaller blobs. The standard deviations of the Gaussian filter
    are given for each axis as a sequence, or as a single number, in
    which case it is equal for all axes.
max_sigma : scalar or sequence of scalars, optional
    The maximum standard deviation for Gaussian kernel. Keep this high to
    detect larger blobs. The standard deviations of the Gaussian filter
    are given for each axis as a sequence, or as a single number, in
```

which case it is equal for all axes.

num_sigma : int, optional
The number of intermediate values of standard deviations to consider between 'min_sigma' and 'max_sigma'.

threshold : float, optional.
The absolute lower bound for scale space maxima. Local maxima smaller than thresh are ignored. Reduce this to detect blobs with less intensities.

overlap : float, optional
A value between 0 and 1. If the area of two blobs overlaps by a fraction greater than 'threshold', the blob with the smaller maximum laplacian value is eliminated. If set to 1, then all overlapping blobs are kept.

log_scale : bool, optional
If set intermediate values of standard deviations are interpolated using a logarithmic scale to the base '10'. If not, linear interpolation is used.

exclude_border : tuple of ints, int, or False, optional
If tuple of ints, the length of the tuple must match the input array's dimensionality. Each element of the tuple will exclude peaks from within 'exclude_border'-pixels of the border of the image along that dimension.
If nonzero int, 'exclude_border' excludes peaks from within 'exclude_border'-pixels of the border of the image.
If zero or False, peaks are identified regardless of their distance from the border.

Returns

A : (n, image.ndim + sigma) ndarray
A 2d array with each row representing 2 coordinate values for a 2D image, and 3 coordinate values for a 3D image, plus the sigma(s) used. When a single sigma is passed, outputs are:
``(r, c, sigma)`` or ``(p, r, c, sigma)`` where ``(r, c)`` or ``(p, r, c)`` are coordinates of the blob and ``sigma`` is the standard deviation of the Gaussian kernel which detected the blob. When an anisotropic gaussian is used (sigmas per dimension), the detected sigma is returned for each dimension.

References

.. [1] https://en.wikipedia.org/wiki/Blob_detection#The_Laplacian_of_Gaussian

Examples

```
>>> from skimage import data, feature, exposure
>>> img = data.coins()
>>> img = exposure.equalize_hist(img) # improves detection
>>> feature.blob_log(img, threshold = .3)
array([[124.      , 336.      , 11.88888889],
       [198.      , 155.      , 11.88888889],
       [194.      , 213.      , 17.33333333],
       [121.      , 272.      , 17.33333333],
       [263.      , 244.      , 17.33333333],
       [194.      , 276.      , 17.33333333],
       [266.      , 115.      , 11.88888889],
       [128.      , 154.      , 11.88888889],
       [260.      , 174.      , 17.33333333],
       [198.      , 103.      , 11.88888889],
       [126.      , 208.      , 11.88888889],
       [127.      , 102.      , 11.88888889],
       [263.      , 302.      , 17.33333333],
       [197.      , 44.       , 11.88888889],
       [185.      , 344.      , 17.33333333],
       [126.      , 46.       , 11.88888889],
       [113.      , 323.      , 1.          ]])
```

Notes

The radius of each blob is approximately $\sqrt{2} \cdot \text{sigma}$ for a 2-D image and $\sqrt{3} \cdot \text{sigma}$ for a 3-D image.

6.2.3.7 detection()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.detection (
    self,
    type = 'skimage',
    ** kwargs)
```

Applies the blob_log scheme to detect blobs in an image using the parameters of this class object
Full list see `__init__().__doc__`

Parameters

type: string

if "bp" use the custom blob_logv2() elif "skimage" use the skimage implimentation of blob_log

Returns

if verbose is True: return type is a dictionary

returns a dictionary of the parameters used for the blob detection and fitting and the fitted objects

else: return type is a numpy array of size 3 tuples

returns the scale space blobs found in the image

Notes:

1. For 2D images the blob radius estimate is the standard deviation of the gaussian fit to the image times sqrt(2)

2. Scale fits are isotropic

3. Fitted fits are anisotropic and are size 4 tuples with simga_x and sigma_y

6.2.3.8 initalize_2dgaus()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.initalize_2dgaus (
    self,
    ** kwargs)
```

initalizes lmfit parameters

Returns

Parameter() class object

class object defining the parameters with bounds for the fit later on

6.2.3.9 open_file()

```
SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.open_file (
    self)
```

Opens and retuns array of the image data

Parameters

self.img: string of a path or path object, or 2D image

if path provided opens the file and reads in image data to apply filter or applies filter is self.img is 2D array

self.median: bool

if True applies a median filter of size self.median_filter_size before returning 2D array

Returns

array-like

2D array of the image data

6.2.4 Member Data Documentation

6.2.4.1 fitting_parameters

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.fitting_parameters

6.2.4.2 img

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.img

6.2.4.3 log_scale

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.log_scale

6.2.4.4 max_sigma

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.max_sigma

6.2.4.5 median

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.median

6.2.4.6 median_filter_size

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.median_filter_size

6.2.4.7 min_sigma

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.min_sigma

6.2.4.8 num_sigma

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.num_sigma

6.2.4.9 overlap

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.overlap

6.2.4.10 threshold

SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.threshold

6.2.4.11 verbose

`SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection.verbose`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/clusterMethods/blob_detection.py`

6.3 SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis Class Reference

Public Member Functions

- None `__init__` (self, **kwargs)
- `directional_displacement_bulk` (self, **kwargs)

Static Public Member Functions

- `directional_displacement` (collection_traj, cell_obj)
- `plot_directional_displacements` (**kwargs)

Public Attributes

- `dataset`

Static Protected Member Functions

- `_xy_angle_from_drop` (collection_traj, cell_obj)
- `_track_to_closest_drop` (x, y, drops)
- `_directional_variableTracks` (x, y, drops)
- `_directional_displacement_utility` (obj)

6.3.1 Detailed Description

```
TODO - make this better
class for storing analysis intermediates and boundary analysis
```

6.3.2 Constructor & Destructor Documentation

6.3.2.1 __init__()

```
None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis.__init__ (
    self,
    ** kwargs)
```

6.3.3 Member Function Documentation

6.3.3.1 `_directional_displacement_utility()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis._directional_↵
displacement_utility (
    obj) [static], [protected]
```

6.3.3.2 `_directional_variableTracks()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis._directional_↵
variableTracks (
    x,
    y,
    drops) [static], [protected]
```

6.3.3.3 `_track_to_closest_drop()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis._track_to_closest_↵
_drop (
    x,
    y,
    drops) [static], [protected]
```

for a track defined by x,y returns the closest circle it is from a collenction of circles `[[d_x,d_y,d_r],...]`

6.3.3.4 `_xy_angle_from_drop()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis._xy_angle_from_drop
(
    collection_traj,
    cell_obj) [static], [protected]
```

6.3.3.5 `directional_displacement()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis.directional_↵
displacement (
    collection_traj,
    cell_obj) [static]
```

6.3.3.6 `directional_displacement_bulk()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis.directional_↵
displacement_bulk (
    self,
    ** kwargs)
```

return the `directional_displacement` vs distance from center with angles

6.3.3.7 plot_directional_displacements()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis.plot_directional_↵
displacements (
    ** kwargs) [static]
```

6.3.4 Member Data Documentation

6.3.4.1 dataset

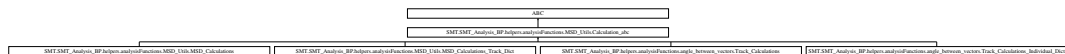
```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis.dataset
```

The documentation for this class was generated from the following file:

- /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↵
BP/databases/trajectory_analysis_script.py

6.4 SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.↵ Calculation_abc Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc:



Public Member Functions

- None `__init__` (self, float `pixel_size`, float `frame_length`, str `pixel_unit`, str `frame_unit`)
- `pixel_size` (self)
- `frame_length` (self)
- `pixel_unit` (self)
- `frame_unit` (self)
- `combined_store` (self)
- `individual_store` (self)

Public Attributes

- `pixel_size`
- `frame_length`
- `pixel_unit`
- `frame_unit`

Protected Member Functions

- `_initialized_print_warning` (self)

Protected Attributes

- [_pixel_size](#)
- [_frame_length](#)
- [_pixel_unit](#)
- [_frame_unit](#)

6.4.1 Detailed Description

Abstract base class for Calculations
Will only inforce pixel size, units and frame length, units

6.4.2 Constructor & Destructor Documentation

6.4.2.1 `__init__()`

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.__init__ (
    self,
    float pixel_size,
    float frame_length,
    str pixel_unit,
    str frame_unit)
```

Reimplemented in [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_Individual_Dict](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations](#), and [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict](#)

6.4.3 Member Function Documentation

6.4.3.1 `_initialized_print_warning()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc._initialized_print_↵
warning (
    self) [protected]
```

6.4.3.2 `combined_store()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.combined_store (
    self)
```

Reimplemented in [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_Individual_Dict](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict](#), and [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict](#)

6.4.3.3 `frame_length()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.frame_length (
    self)
```

6.4.3.4 frame_unit()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.frame_unit (
    self)
```

6.4.3.5 individual_store()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.individual_store (
    self)
```

Reimplemented in [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_Individual_Dict](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations](#), [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict](#), and [SMT.SMT_Analysis_BP.helpers.an](#)

6.4.3.6 pixel_size()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.pixel_size (
    self)
```

6.4.3.7 pixel_unit()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.pixel_unit (
    self)
```

6.4.4 Member Data Documentation

6.4.4.1 _frame_length

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc._frame_length [protected]
```

6.4.4.2 _frame_unit

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc._frame_unit [protected]
```

6.4.4.3 _pixel_size

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc._pixel_size [protected]
```

6.4.4.4 _pixel_unit

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc._pixel_unit [protected]
```

6.4.4.5 frame_length

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.frame_length`

6.4.4.6 frame_unit

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.frame_unit`

6.4.4.7 pixel_size

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.pixel_size`

6.4.4.8 pixel_unit

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc.pixel_unit`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/MSD_Utils.py`

6.5 SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell Class Reference

Public Member Functions

- `__init__` (self, Cell_ID, Cell_Movie_Name, bounding_box=0, r_offset=0, cell_area=0, cell_center=0, cell_long_axis=0, cell_short_axis=0, cell_axis_lengths=0, cell_mask=0, Cell_Nucleoid_Mask=0)
- dict `points_per_frame` (self)
- None `points_per_frame` (self, dict points_per_frame)
- dict `area_of_points_per_frame` (self)
- None `area_of_points_per_frame` (self, dict area_of_points_per_frame)
- dict `density_per_frame` (self)
- float `nucleoid_area` (self)
- None `nucleoid_area` (self, float|int nucleoid_area)

Public Attributes

- [Cell_ID](#)
- [Cell_Movie_Name](#)
- [Cell_Nucleoid_Mask](#)
- [cell_mask](#)
- [cell_area](#)
- [cell_center](#)
- [bounding_box](#)
- [r_offset](#)
- [cell_long_axis](#)
- [cell_short_axis](#)
- [cell_axis_lengths](#)
- [Trajectory_Collection](#)
- [No_Drops_Trajectory_Collection](#)
- [Drop_Collection](#)
- [Drop_Verbose](#)
- [All_Drop_Collection](#)
- [All_Drop_Verbose](#)
- [All_Trajectories](#)
- [raw_tracks](#)
- [sorted_tracks_frame](#)
- [area_of_points_per_frame](#)

Protected Member Functions

- [_convert_viableDrop_list](#) (self, subframes=5)

Protected Attributes

- [_points_per_frame](#)
- [_area_of_points_per_frame](#)
- [_density_per_frame](#)
- [_nucleoid_area](#)

6.5.1 Detailed Description

each cell class is built of two main things:

- 1) A dictionary of drops (x,y,r) identified by a label (0,1,...,n)
- 2) A collection of Trajectory class objects defining the trajectories in that Cell class object

Parameters

`__init__:`

```

    Cell_ID: int
        unique identifier for each cell
    Cell_Movie_Name: string
        name of the movie the cell is in, used to find the movie. This is the name of the movie file!
    bounding_box: list of 4 ints
        coordinates of the bounding box of the cell
    r_offset: list of 2 ints
        coordinate of the top left corner of the bounding box
    cell_area: int
        area of the cell
    cell_center: list of 2 ints
        coordinates of the center of the cell
    cell_long_axis: int

```

```

        length of the long axis of the cell
    cell_short_axis: int
        length of the short axis of the cell
    cell_axis_lengths: list of 2 ints
        lengths of the long and short axis of the cell
    cell_mask: 2D array of bools
        mask of the cell
    Cell_Nucleoid_Mask: 2D array of bools
        mask of the nucleoid in the cell

Methods:
-----
__init__:
    Initialize the Cell class object
_convert_viableDrop_list(self):
    converts the viableDrop_list to a dictionary of viable drops

```

6.5.2 Constructor & Destructor Documentation

6.5.2.1 __init__()

```

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.__init__ (
    self,
    Cell_ID,
    Cell_Movie_Name,
    bounding_box = 0,
    r_offset = 0,
    cell_area = 0,
    cell_center = 0,
    cell_long_axis = 0,
    cell_short_axis = 0,
    cell_axis_lengths = 0,
    cell_mask = 0,
    Cell_Nucleoid_Mask = 0)

```

6.5.3 Member Function Documentation

6.5.3.1 _convert_viableDrop_list()

```

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell._convert_viableDrop_list (
    self,
    subframes = 5) [protected]

```

6.5.3.2 area_of_points_per_frame() [1/2]

```

dict SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.area_of_points_per_frame (
    self)

```

6.5.3.3 area_of_points_per_frame() [2/2]

```

None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.area_of_points_per_frame (
    self,
    dict area_of_points_per_frame)

```

6.5.3.4 density_per_frame()

```
dict SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.density_per_frame (
    self)
```

6.5.3.5 nucleoid_area() [1/2]

```
float SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.nucleoid_area (
    self)
```

6.5.3.6 nucleoid_area() [2/2]

```
None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.nucleoid_area (
    self,
    float|int nucleoid_area)
```

6.5.3.7 points_per_frame() [1/2]

```
dict SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.points_per_frame (
    self)
```

6.5.3.8 points_per_frame() [2/2]

```
None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.points_per_frame (
    self,
    dict points_per_frame)
```

6.5.4 Member Data Documentation**6.5.4.1 _area_of_points_per_frame**

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell._area_of_points_per_frame [protected]
```

6.5.4.2 _density_per_frame

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell._density_per_frame [protected]
```

6.5.4.3 _nucleoid_area

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell._nucleoid_area [protected]
```

6.5.4.4 _points_per_frame

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell._points_per_frame [protected]
```

6.5.4.5 All_Drop_Collection

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.All_Drop_Collection`

6.5.4.6 All_Drop_Verbose

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.All_Drop_Verbose`

6.5.4.7 All_Tracjectories

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.All_Tracjectories`

6.5.4.8 area_of_points_per_frame

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.area_of_points_per_frame`

6.5.4.9 bounding_box

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.bounding_box`

6.5.4.10 cell_area

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.cell_area`

6.5.4.11 cell_axis_lengths

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.cell_axis_lengths`

6.5.4.12 cell_center

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.cell_center`

6.5.4.13 Cell_ID

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.Cell_ID`

6.5.4.14 cell_long_axis

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.cell_long_axis`

6.5.4.15 cell_mask

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.cell_mask

6.5.4.16 Cell_Movie_Name

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.Cell_Movie_Name

6.5.4.17 Cell_Nucleoid_Mask

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.Cell_Nucleoid_Mask

6.5.4.18 cell_short_axis

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.cell_short_axis

6.5.4.19 Drop_Collection

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.Drop_Collection

6.5.4.20 Drop_Verbose

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.Drop_Verbose

6.5.4.21 No_Drops_Trajectory_Collection

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.No_Drops_Trajectory_Collection

6.5.4.22 r_offset

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.r_offset

6.5.4.23 raw_tracks

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.raw_tracks

6.5.4.24 sorted_tracks_frame

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.sorted_tracks_frame

6.5.4.25 Trajectory_Collection

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell.Trajectory_Collection`

The documentation for this class was generated from the following file:

- `/Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/trajectory_analysis_script.py`

6.6 SMT.SMT_Analysis_BP.helpers.misc.decorators.CountCalls Class Reference

Public Member Functions

- `__init__` (self, func)
- `__call__` (self, *args, **kwargs)

Public Attributes

- `func`
- `num_calls`

6.6.1 Detailed Description

Count how many times a function is called

6.6.2 Constructor & Destructor Documentation

6.6.2.1 `__init__()`

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.CountCalls.__init__ (  
    self,  
    func)
```

6.6.3 Member Function Documentation

6.6.3.1 `__call__()`

```
SMT.SMT_Analysis_BP.helpers.misc.decorators.CountCalls.__call__ (  
    self,  
    * args,  
    ** kwargs)
```

6.6.4 Member Data Documentation

6.6.4.1 func

`SMT.SMT_Analysis_BP.helpers.misc.decorators.CountCalls.func`

6.6.4.2 num_calls

`SMT.SMT_Analysis_BP.helpers.misc.decorators.CountCalls.num_calls`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/misc/decorators.py`

6.7 utility_database.Counter_start_stop Class Reference

Public Member Functions

- `__init__` (self, `start`, `increment`=1)
- `__call__` (self)
- `reset` (self)

Public Attributes

- `start`
- `increment`
- `counter`

6.7.1 Constructor & Destructor Documentation

6.7.1.1 __init__()

```
utility_database.Counter_start_stop.__init__ (  
    self,  
    start,  
    increment = 1)
```

6.7.2 Member Function Documentation

6.7.2.1 __call__()

```
utility_database.Counter_start_stop.__call__ (  
    self)
```

6.7.2.2 reset()

```
utility_database.Counter_start_stop.reset (
    self)
```

6.7.3 Member Data Documentation

6.7.3.1 counter

```
utility_database.Counter_start_stop.counter
```

6.7.3.2 increment

```
utility_database.Counter_start_stop.increment
```

6.7.3.3 start

```
utility_database.Counter_start_stop.start
```

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/utilities/utility_database.py↵

6.8 SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil Class Reference↵

Public Member Functions

- `__init__` (self, list|None data_set_RA=None, float pixel_to_um=0.13, float frame_to_seconds=0.02, **kwargs)
- `data_set_RA` (self)
- `data_set_RA` (self, list data_set_RA)
- `data_set_number` (self)
- `data_set_names` (self)
- `data_set_parameters` (self)
- `track_dict_bulk_list` (self)
- `combined_track_dict_bulk` (self)
- `pixel_to_um` (self)
- `pixel_to_um` (self, float pixel_to_um)
- `frame_to_seconds` (self)
- `frame_to_seconds` (self, float frame_to_seconds)

Public Attributes

- `data_set_RA`
- `pixel_to_um`
- `frame_to_seconds`

Protected Member Functions

- [_get_data_RA](#) (self, list dataset)

Protected Attributes

- [_data_set_RA](#)
- [_track_dict_bulk_list](#)
- [_combined_track_dict_bulk](#)
- [_pixel_to_um](#)
- [_frame_to_seconds](#)

6.8.1 Detailed Description

lets create a generic MSD analysis class which will store all the MSD analysis for a single dataset or multiple datasets. using encapsulation we will utilize smaller functions to do the analysis

6.8.2 Constructor & Destructor Documentation

6.8.2.1 __init__()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.__init__ (
    self,
    list|None data_set_RA = None,
    float pixel_to_um = 0.13,
    float frame_to_seconds = 0.02,
    ** kwargs)
```

Parameters:

```
-----
data_set_RA: list
    list of tas.run_analysis objects
pixel_to_um: float
    pixel to um conversion
frame_to_seconds: float
    frame to seconds conversion
```

6.8.3 Member Function Documentation

6.8.3.1 _get_data_RA()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil._get_data_RA (
    self,
    list dataset) [protected]
```

6.8.3.2 combined_track_dict_bulk()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.combined_track_dict_bulk (
    self)
```

6.8.3.3 data_set_names()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.data_set_names (  
    self)
```

6.8.3.4 data_set_number()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.data_set_number (  
    self)
```

6.8.3.5 data_set_parameters()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.data_set_parameters  
(  
    self)
```

6.8.3.6 data_set_RA() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.data_set_RA (  
    self)
```

6.8.3.7 data_set_RA() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.data_set_RA (  
    self,  
    list data_set_RA)
```

6.8.3.8 frame_to_seconds() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.frame_to_seconds (  
    self)
```

6.8.3.9 frame_to_seconds() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.frame_to_seconds (  
    self,  
    float frame_to_seconds)
```

6.8.3.10 pixel_to_um() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.pixel_to_um (  
    self)
```

6.8.3.11 pixel_to_um() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.pixel_to_um (
    self,
    float pixel_to_um)
```

6.8.3.12 track_dict_bulk_list()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.track_dict_bulk_list
(
    self)
```

6.8.4 Member Data Documentation**6.8.4.1 _combined_track_dict_bulk**

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil._combined_track_dict_bulk ↵
dict_bulk [protected]
```

6.8.4.2 _data_set_RA

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil._data_set_RA [protected]
```

6.8.4.3 _frame_to_seconds

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil._frame_to_seconds
[protected]
```

6.8.4.4 _pixel_to_um

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil._pixel_to_um [protected]
```

6.8.4.5 _track_dict_bulk_list

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil._track_dict_bulk_list ↵
list [protected]
```

6.8.4.6 data_set_RA

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.data_set_RA
```

6.8.4.7 frame_to_seconds

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.frame_to_seconds
```

6.8.4.8 pixel_to_um

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil.pixel_to_um

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/[MSD_Utils.py](#)

6.9 SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties Class Reference

Public Member Functions

- None [__init__](#) (self, [masked_image](#), invert_axis)
- [extract_properties](#) (self)
- [__dict__](#) (self)
- [region_properties](#) (self)
- [region_properties](#) (self, region_properties)
- [area](#) (self)
- [bounding_box](#) (self)
- [centroid](#) (self)
- [r_offset](#) (self)
- [longest_axis](#) (self)
- [shortest_axis](#) (self)
- [coordinates](#) (self)
- [orientation](#) (self)

Public Attributes

- [masked_image](#)
- [region_properties](#)
- [area](#)
- [bounding_box](#)
- [centroid](#)
- [r_offset](#)
- [longest_axis](#)
- [shortest_axis](#)
- [coordinates](#)

Protected Member Functions

- [_populate_properties](#) (self)

Protected Attributes

- [_area](#)
- [_bounding_box](#)
- [_centroid](#)
- [_r_offset](#)
- [_longest_axis](#)
- [_shortest_axis](#)
- [_coordinates](#)
- [_orientation](#)
- [_region_properties](#)

6.9.1 Constructor & Destructor Documentation

6.9.1.1 `__init__()`

None SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.[↩](#)
`__init__` (
 self,
 masked_image,
 invert_axis)

Parameters:

masked_image: numpy array
 Masked image
invert_axis: bool
 If True, inverts the axis of the masked image

6.9.2 Member Function Documentation

6.9.2.1 `__dict__()`

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.[↩](#)
`__dict__` (
 self)

6.9.2.2 `_populate_properties()`

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.[↩](#)
`_populate_properties` (
 self) [protected]

6.9.2.3 `area()`

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.[↩](#)
`area` (
 self)

Returns the area of the mask

6.9.2.4 bounding_box()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↵  
bounding_box (   
    self)
```

Returns the bounding box of the mask as a numpy array but in the form of the coordinates of the bounding box (

6.9.2.5 centroid()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↵  
centroid (   
    self)
```

Returns the centroid of the mask

6.9.2.6 coordinates()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↵  
coordinates (   
    self)
```

Returns the coordinates of the mask

6.9.2.7 extract_properties()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↵  
extract_properties (   
    self)
```

6.9.2.8 longest_axis()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↵  
longest_axis (   
    self)
```

Returns the longest axis of the mask

6.9.2.9 orientation()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↵  
orientation (   
    self)
```

Returns the orientation of the mask

6.9.2.10 r_offset()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.r_offset (
    self)
```

Returns the r_offset of the mask

6.9.2.11 region_properties() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.region_properties (
    self)
```

Returns the region properties of the masked image

6.9.2.12 region_properties() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.region_properties (
    self,
    region_properties)
```

6.9.2.13 shortest_axis()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.shortest_axis (
    self)
```

Returns the shortest axis of the mask

6.9.3 Member Data Documentation

6.9.3.1 _area

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._area
[protected]
```

6.9.3.2 _bounding_box

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._bounding_box
[protected]
```

6.9.3.3 `_centroid`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._↵  
centroid [protected]
```

6.9.3.4 `_coordinates`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._↵  
coordinates [protected]
```

6.9.3.5 `_longest_axis`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._↵  
longest_axis [protected]
```

6.9.3.6 `_orientation`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._↵  
orientation [protected]
```

6.9.3.7 `_r_offset`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._r_↵  
offset [protected]
```

6.9.3.8 `_region_properties`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._↵  
region_properties [protected]
```

6.9.3.9 `_shortest_axis`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties._↵  
shortest_axis [protected]
```

6.9.3.10 `area`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.area
```

6.9.3.11 `bounding_box`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↵  
bounding_box
```

6.9.3.12 centroid

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↔
centroid

6.9.3.13 coordinates

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↔
coordinates

6.9.3.14 longest_axis

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↔
longest_axis

6.9.3.15 masked_image

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↔
masked_image

6.9.3.16 r_offset

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.r_↔
offset

6.9.3.17 region_properties

SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↔
region_properties

6.9.3.18 shortest_axis

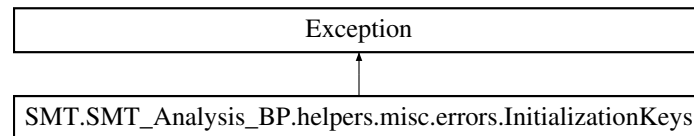
SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties.↔
shortest_axis

The documentation for this class was generated from the following file:

- /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔
BP/helpers/analysisFunctions/features_from_mask.py

6.10 SMT.SMT_Analysis_BP.helpers.misc.errors.InitializationKeys Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.misc.errors.InitializationKeys:



6.10.1 Detailed Description

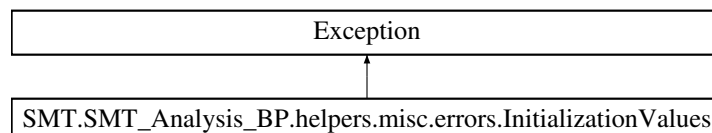
Error class for the initialization keys.

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers\misc\errors.py`

6.11 SMT.SMT_Analysis_BP.helpers.misc.errors.InitializationValues Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.misc.errors.InitializationValues:



6.11.1 Detailed Description

Error class for the initialization values.

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers\misc\errors.py`

6.12 SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.IO_run_analysis Class Reference

Public Member Functions

- `None __init__(self)`

Static Protected Member Functions

- [_save_sptanalysis_data](#) (pp, test)
- [_load_superSegger](#) (cd, _string)

6.12.1 Constructor & Destructor Documentation**6.12.1.1 __init__()**

```
None SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.IO_run_analysis.__init__ (
    self)
```

6.12.2 Member Function Documentation**6.12.2.1 _load_superSegger()**

```
SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.IO_run_analysis._load_superSegger (
    cd,
    _string) [static], [protected]
```

6.12.2.2 _save_sptanalysis_data()

```
SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.IO_run_analysis._save_sptanalysis_data (
    pp,
    test) [static], [protected]
```

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/[SMT_converters.py](#)

6.13 localization_setter.mask_localization Class Reference**Public Member Functions**

- [__init__](#) (self, path)
- [make_loc](#) (self)
- [analysis_folder](#) (self)
- [analysis_loc_files](#) (self)

Public Attributes

- [cd](#)
- [path_structure](#)

Protected Attributes

- [_analysis_loc_files](#)

6.13.1 Constructor & Destructor Documentation

6.13.1.1 __init__()

```
localization_setter.mask_localization.__init__ (  
    self,  
    path)
```

6.13.2 Member Function Documentation

6.13.2.1 analysis_folder()

```
localization_setter.mask_localization.analysis_folder (  
    self)
```

6.13.2.2 analysis_loc_files()

```
localization_setter.mask_localization.analysis_loc_files (  
    self)
```

6.13.2.3 make_loc()

```
localization_setter.mask_localization.make_loc (  
    self)
```

6.13.3 Member Data Documentation

6.13.3.1 _analysis_loc_files

```
localization_setter.mask_localization._analysis_loc_files [protected]
```

6.13.3.2 cd

```
localization_setter.mask_localization.cd
```

6.13.3.3 path_structure

```
localization_setter.mask_localization.path_structure
```

The documentation for this class was generated from the following file:

- [/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/thunderSTORM/localization_setter.py](#)

6.14 SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.[↩](#) Movie_frame Class Reference

Public Member Functions

- [__init__](#) (self, [Movie_ID](#), [Movie_name](#), [Movie_location](#)=0, [nucleoid_location](#)=0)

Public Attributes

- [Movie_ID](#)
- [Movie_name](#)
- [Movie_location](#)
- [Movie_nucleoid](#)
- [Cells](#)

6.14.1 Detailed Description

Frame of reference for one movie

Parameters

[__init__](#):

Movie_ID: int

unique identifier for each movie

Movie_name: string

name of the movie, used to find the movie. This is the name of the movie file!

Movie_location: string or list of strings, optional (size is the number of frames \n (i.e 5 for 5 subframes from a 5000 frame movie with 1000 per subframe))

This is the sub segmented frames of the movie. This is just a list of strings that are the location

nucleoid_location: string, optional

location of the image that shows the nucleoid, by default 0

Cells: dictionary

dictionary of Cell class objects belonging to this Movie, identified by a label (0,1,...,n)

6.14.2 Constructor & Destructor Documentation

6.14.2.1 [__init__](#)()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Movie_frame.__init__ (
    self,
    Movie_ID,
    Movie_name,
    Movie_location = 0,
    nucleoid_location = 0)
```

6.14.3 Member Data Documentation

6.14.3.1 Cells

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Movie_frame.Cells
```

6.14.3.2 Movie_ID

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Movie_frame.Movie_ID`

6.14.3.3 Movie_location

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Movie_frame.Movie_location`

6.14.3.4 Movie_name

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Movie_frame.Movie_name`

6.14.3.5 Movie_nucleoid

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Movie_frame.Movie_nucleoid`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/trajectory_analysis_script.py`

6.15 SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory_structure_manager Class Reference

Public Member Functions

- `None __init__(self, full_path_to_mask_dir)`
- `full_path_to_mask_dir(self)`
- `mask_files(self)`
- `directory_structure_paths(self)`
- `base_files(self)`

Public Attributes

- `full_path_to_mask_dir`
- `mask_files`

Protected Member Functions

- `None _find_mask_files(self)`
- `None _make_directory_structure(self)`

Protected Attributes

- [_full_path_to_mask_dir](#)
- [_base_files](#)
- [_mask_files](#)
- [_directory_structure_paths](#)

6.15.1 Constructor & Destructor Documentation

6.15.1.1 __init__()

```
None SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_↔
directory_structure_manager.__init__ (
    self,
    full_path_to_mask_dir)
```

6.15.2 Member Function Documentation

6.15.2.1 _find_mask_files()

```
None SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_↔
directory_structure_manager._find_mask_files (
    self) [protected]
```

Finds the mask files (right now these are .npy files) in the directory, defined by cellpose output
This sets the mask_files attribute

6.15.2.2 _make_directory_structure()

```
None SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_↔
directory_structure_manager._make_directory_structure (
    self) [protected]
```

Makes the directory structure for the Movies, cells and saves each mask inside it
this follows from the strucure described above

6.15.2.3 base_files()

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory_↔
_structure_manager.base_files (
    self)
```

6.15.2.4 directory_structure_paths()

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory_↔
_structure_manager.directory_structure_paths (
    self)
```

6.15.2.5 full_path_to_mask_dir()

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager.full_path_to_mask_dir (
    self)
```

6.15.2.6 mask_files()

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager.mask_files (
    self)
```

6.15.3 Member Data Documentation

6.15.3.1 _base_files

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager._base_files [protected]
```

6.15.3.2 _directory_structure_paths

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager._directory_structure_paths [protected]
```

6.15.3.3 _full_path_to_mask_dir

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager._full_path_to_mask_dir [protected]
```

6.15.3.4 _mask_files

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager._mask_files [protected]
```

6.15.3.5 full_path_to_mask_dir

```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager.full_path_to_mask_dir
```

6.15.3.6 mask_files

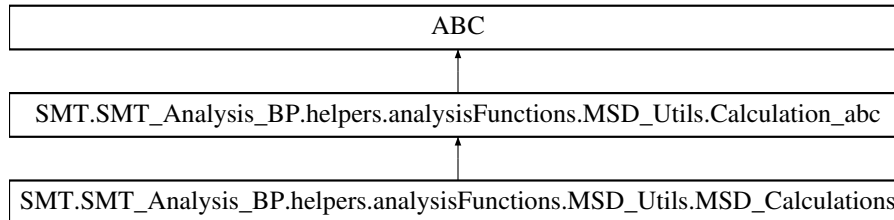
```
SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory↔
_structure_manager.mask_files
```

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔
BP/databases/directoryManipulator/[format_mask_structure.py](#)

6.16 SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations:



Public Member Functions

- None `__init__` (self, list data_set_RA, float pixel_to_um=0.13, float frame_to_seconds=0.02, str frame_units="s", str pixel_units="um", **kwargs)
- `combined_store` (self)
- `combined_store` (self, combined_store)
- `individual_store` (self)
- `individual_store` (self, individual_store)

Public Attributes

- `MSD_dataset`

Protected Member Functions

- `_build_MSD_Tracks_combined` (self, **kwargs)
- `_build_MSD_Tracks_individual` (self, **kwargs)
- `_build_MSD_Tracks` (self, **kwargs)

Protected Attributes

- `_combined_store`
- `_individual_store`

6.16.1 Constructor & Destructor Documentation

6.16.1.1 `__init__()`

```

None SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations.__init__ (
    self,
    list data_set_RA,
    float pixel_to_um = 0.13,
    float frame_to_seconds = 0.02,
    str frame_units = "s",
    str pixel_units = "um",
    ** kwargs)
  
```

Parameters:

data_set_RA: list
list of tas.run_analysis objects
pixel_to_um: float
pixel to um conversion
frame_to_seconds: float
frame to seconds conversion
frame_units: str
frame units
pixel_units: str
pixel units

KWARGS:

min_track_length: int, Default = 1
minimum track length to be considered.
This is passed on to the af.MSD_Tracks() function
max_track_length: int, Default = 1000
maximum track length to be considered.

Passed to af.MSD_Tracks() -> (bootstrap:bool=False,bootstrap_samples:float=0.1,bootstrap_percentile:float=0.95)

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.16.2 Member Function Documentation

6.16.2.1 _build_MSD_Tracks()

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations._build_MSD_Tracks (
self,
** kwargs) [protected]

Parameters:

KWARGS:

Passed to af.MSD_Tracks()

6.16.2.2 _build_MSD_Tracks_combined()

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations._build_MSD_Tracks↵
combined (
self,
** kwargs) [protected]

6.16.2.3 _build_MSD_Tracks_individual()

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations._build_MSD_Tracks↵
individual (
self,
** kwargs) [protected]

6.16.2.4 combined_store() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations.combined_store (
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.16.2.5 combined_store() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations.combined_store (
    self,
    combined_store)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.16.2.6 individual_store() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations.individual_store (
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.16.2.7 individual_store() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations.individual_store (
    self,
    individual_store)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.16.3 Member Data Documentation**6.16.3.1 _combined_store**

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations._combined_store [protected]
```

6.16.3.2 _individual_store

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations._individual_store
[protected]
```

6.16.3.3 MSD_dataset

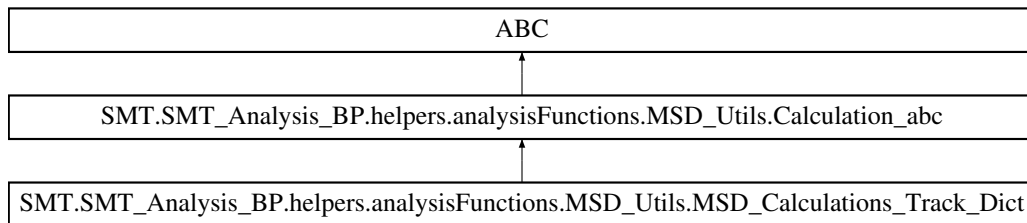
```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations.MSD_dataset
```

The documentation for this class was generated from the following file:

- [/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/MSD_Utils.py](#)

6.17 SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict:



Public Member Functions

- None `__init__` (self, [track_dict](#), **kwargs)
- [combined_store](#) (self)
- [combined_store](#) (self, combined_store)
- [individual_store](#) (self)
- [individual_store](#) (self, individual_store)

Public Attributes

- [track_dict](#)
- [pixel_to_um](#)
- [frame_to_seconds](#)

Protected Member Functions

- [_build_MSD_Tracks](#) (self, **kwargs)

Protected Attributes

- [_storage](#)

6.17.1 Constructor & Destructor Documentation

6.17.1.1 `__init__()`

```

None SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.__init__ (
    self,
    track_dict,
    ** kwargs)
  
```


Parameters:

```

track_dict: dict
    dict of tracks in the form:
    {
        track_ID: [[x,y], ..., [x,y]],
        .
        .
        .
    }
KWARGS:
-----
pixel_to_um: float
    pixel to um conversion
frame_to_seconds: float
    frame to seconds conversion
frame_units: str
    frame units
pixel_units: str
    pixel units
min_track_length: int, Default = 1
    minimum track length to be considered.
max_track_length: int, Default = 1000
    maximum track length to be considered.

```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.17.2 Member Function Documentation

6.17.2.1 _build_MSD_Tracks()

```

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict._build_↵
MSD_Tracks (
    self,
    ** kwargs)    [protected]

```

6.17.2.2 combined_store() [1/2]

```

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.combined_↵
_store (
    self)

```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.17.2.3 combined_store() [2/2]

```

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.combined_↵
_store (
    self,
    combined_store)

```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.17.2.4 individual_store() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.individual↵
_store (
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.17.2.5 individual_store() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.individual↵
_store (
    self,
    individual_store)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.17.3 Member Data Documentation

6.17.3.1 _storage

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict._storage
[protected]
```

6.17.3.2 frame_to_seconds

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.frame_to↵
_seconds
```

6.17.3.3 pixel_to_um

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.pixel_to↵
_um
```

6.17.3.4 track_dict

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict.track_dict
```

The documentation for this class was generated from the following file:

- /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↵
BP/helpers/analysisFunctions/[MSD_Utils.py](#)

6.18 SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage Class Reference

Public Member Functions

- None [__init__](#) (self, [name](#), [track_class_type](#), [storage_data](#))
- [ensemble_MSD](#) (self)
 - ensemble storage*
- [ensemble_MSD](#) (self, [ensemble_MSD](#))
- [ensemble_MSD_error](#) (self)
- [ensemble_MSD_error](#) (self, [ensemble_MSD_error](#))
- [ensemble_displacement](#) (self)
- [ensemble_displacement](#) (self, [ensemble_displacement](#))
- [track_MSD](#) (self)
 - track storage*
- [track_MSD](#) (self, [track_MSD](#))
- [track_MSD_error](#) (self)
- [track_MSD_error](#) (self, [track_MSD_error](#))
- [track_displacement](#) (self)
- [track_displacement](#) (self, [track_displacement](#))
- [track_displacement_r](#) (self)
 - we need to have a datatype which converts the displacement which are (n,d) where d is the dimension to a single r = distance*
- [ensemble_displacement_r](#) (self)
- [track_lengths](#) (self)
- [track_lengths](#) (self, [track_lengths](#))

Public Attributes

- [name](#)
- [track_class_type](#)
- [storage_data](#)

Protected Member Functions

- [_store_data](#) (self)

Protected Attributes

- [_ensemble_MSD](#)
- [_ensemble_MSD_error](#)
- [_ensemble_displacement](#)
- [_track_MSD](#)
- [_track_MSD_error](#)
- [_track_displacement](#)
- [_track_displacement_r](#)
- [_ensemble_displacement_r](#)
- [_track_lengths](#)

6.18.1 Constructor & Destructor Documentation

6.18.1.1 `__init__()`

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.__init__ (
    self,
    name,
    track_class_type,
    storage_data)
```

6.18.2 Member Function Documentation

6.18.2.1 `_store_data()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._store_data (
    self) [protected]
```

6.18.2.2 `ensemble_displacement()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.ensemble_displacement (
    self)
```

6.18.2.3 `ensemble_displacement()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.ensemble_displacement (
    self,
    ensemble_displacement)
```

6.18.2.4 `ensemble_displacement_r()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.ensemble_displacement_r (
    self)
```

6.18.2.5 `ensemble_MSD()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.ensemble_MSD (
    self)
```

ensemble storage

6.18.2.6 `ensemble_MSD()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.ensemble_MSD (
    self,
    ensemble_MSD)
```

6.18.2.7 ensemble_MSD_error() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.ensemble_MSD_error (  
    self)
```

6.18.2.8 ensemble_MSD_error() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.ensemble_MSD_error (  
    self,  
    ensemble_MSD_error)
```

6.18.2.9 track_displacement() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_displacement (  
    self)
```

6.18.2.10 track_displacement() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_displacement (  
    self,  
    track_displacement)
```

6.18.2.11 track_displacement_r()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_displacement_r (  
    self)
```

we need to have a datatype which converts the displacement which are (n,d) where d is the dimension to a single r
= distance

6.18.2.12 track_lengths() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_lengths (  
    self)
```

6.18.2.13 track_lengths() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_lengths (  
    self,  
    track_lengths)
```

6.18.2.14 track_MSD() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_MSD (  
    self)
```

track storage

6.18.2.15 track_MSD() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_MSD (  
    self,  
    track_MSD)
```

6.18.2.16 track_MSD_error() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_MSD_error (  
    self)
```

6.18.2.17 track_MSD_error() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_MSD_error (  
    self,  
    track_MSD_error)
```

6.18.3 Member Data Documentation

6.18.3.1 _ensemble_displacement

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._ensemble_displacement  
[protected]
```

6.18.3.2 _ensemble_displacement_r

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._ensemble_displacement_r  
[protected]
```

6.18.3.3 _ensemble_MSD

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._ensemble_MSD [protected]
```

6.18.3.4 _ensemble_MSD_error

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._ensemble_MSD_error [protected]
```

6.18.3.5 _track_displacement

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._track_displacement [protected]
```

6.18.3.6 _track_displacement_r

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._track_displacement_r [protected]

6.18.3.7 _track_lengths

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._track_lengths [protected]

6.18.3.8 _track_MSD

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._track_MSD [protected]

6.18.3.9 _track_MSD_error

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage._track_MSD_error [protected]

6.18.3.10 name

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.name

6.18.3.11 storage_data

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.storage_data

6.18.3.12 track_class_type

SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage.track_class_type

The documentation for this class was generated from the following file:

- /Users/baljjot/Documents/CODE/GitHub_t2/PHD/Baljjot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/[MSD_Utils.py](#)

6.19 localization_setter.path_structure Class Reference

Public Member Functions

- [__init__](#) (self, [path](#))
- [path](#) (self)
- [path_structure_dict](#) (self)

Public Attributes

- [cd](#)

Protected Attributes

- [_path_structure_dict](#)

6.19.1 Constructor & Destructor Documentation

6.19.1.1 __init__()

```
localization_setter.path_structure.__init__ (  
    self,  
    path)
```

6.19.2 Member Function Documentation

6.19.2.1 path()

```
localization_setter.path_structure.path (  
    self)
```

6.19.2.2 path_structure_dict()

```
localization_setter.path_structure.path_structure_dict (  
    self)
```

6.19.3 Member Data Documentation

6.19.3.1 _path_structure_dict

```
localization_setter.path_structure._path_structure_dict  [protected]
```

6.19.3.2 cd

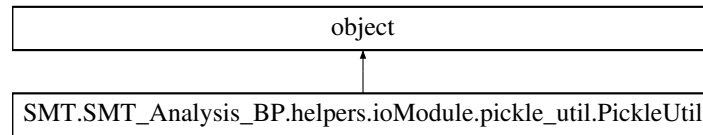
```
localization_setter.path_structure.cd
```

The documentation for this class was generated from the following file:

- [/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/thunderSTORM/localization_setter.py](#)

6.20 SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil:



Public Member Functions

- [__init__](#) (self)
- [save](#) (self, str [path](#), str [name](#), str [docs](#), any [obj](#))
- [obj](#) (self)
- [obj](#) (self, obj)
- [path](#) (self)
- [path](#) (self, path)
- [name](#) (self)
- [name](#) (self, name)
- [docs](#) (self)
- [docs](#) (self, docs)

Static Public Member Functions

- [load](#) (str full_path_to_load)

Public Attributes

- [obj](#)
- [path](#)
- [name](#)
- [docs](#)

Protected Member Functions

- [_update_class_vars](#) (self, [obj](#), [path](#), [name](#), [docs](#))
- [_update_outpkl](#) (self)

Protected Attributes

- [_obj](#)
- [_path](#)
- [_name](#)
- [_docs](#)
- [_outpkl](#)

6.20.1 Constructor & Destructor Documentation

6.20.1.1 `__init__()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.__init__ (
    self)
```

6.20.2 Member Function Documentation

6.20.2.1 `_update_class_vars()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil._update_class_vars (
    self,
    obj,
    path,
    name,
    docs) [protected]
```

6.20.2.2 `_update_outpkl()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil._update_outpkl (
    self) [protected]
```

6.20.2.3 `docs()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.docs (
    self)
```

6.20.2.4 `docs()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.docs (
    self,
    docs)
```

6.20.2.5 `load()`

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.load (
    str full_path_to_load) [static]
```

Docstring:
Load an object from a pickle file. This is the full path to the pickle file.

Parameters:

`full_path_to_load`: str
The full path to the pickle file to load.

Returns:

`obj`: any
The object loaded from the pickle file.

Example:

#create a PickleUtil object if you haven't already
`pickle_util = PickleUtil()`
#load the dict
`dict_loaded = pickle_util.load('C:/Users/JohnDoe/Desktop/my_dict.pkl')`

6.20.2.6 name() [1/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.name (  
    self)
```

6.20.2.7 name() [2/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.name (  
    self,  
    name)
```

6.20.2.8 obj() [1/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.obj (  
    self)
```

6.20.2.9 obj() [2/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.obj (  
    self,  
    obj)
```

6.20.2.10 path() [1/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.path (  
    self)
```

6.20.2.11 path() [2/2]

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.path (  
    self,  
    path)
```

6.20.2.12 save()

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.save (  
    self,  
    str path,  
    str name,  
    str docs,  
    any obj)
```

```

Docstring:
Save an object to a pickle file. The object will be saved to the path/name.pkl file. The docs will be saved to

Parameters:
-----
path: str
    The path to the directory where the object will be saved. This must be the full path to the directory.
name: str
    The name of the pickle file. This should not include the .pkl extension.
docs: str
    A string describing the object. This will be saved to the path/name_docs.txt file.
obj: any
    The object to be saved. This can be any object that can be pickled.

Returns:
-----
None

Example:
-----
#create a PickleUtil object
pickle_util = PickleUtil()
#create a dict to save
dict_to_save = {'a':1, 'b':2}
#save the dict
pickle_util.save(path='C:/Users/JohnDoe/Desktop', name='my_dict', docs='This is a dict I want to save', obj=dict_to_save)

```

6.20.3 Member Data Documentation

6.20.3.1 _docs

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil._docs [protected]
```

6.20.3.2 _name

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil._name [protected]
```

6.20.3.3 _obj

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil._obj [protected]
```

6.20.3.4 _outpkl

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil._outpkl [protected]
```

6.20.3.5 _path

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil._path [protected]
```

6.20.3.6 docs

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.docs
```

6.20.3.7 name

`SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.name`

6.20.3.8 obj

`SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.obj`

6.20.3.9 path

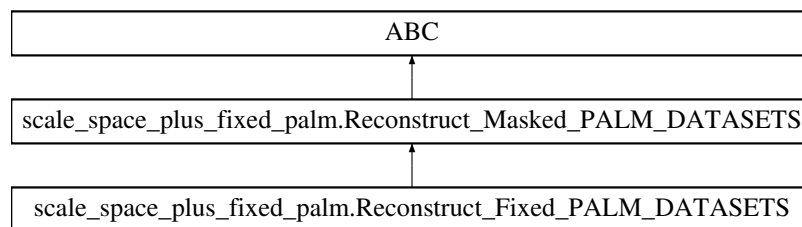
`SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil.path`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/pickle_util.py`

6.21 scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS Class Reference

Inheritance diagram for `scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS`:



Public Member Functions

- `__init__` (self, cd, blob_parameters, fitting_parameters, rescale_pixel_size=10, pixel_size=130, loc_error=30, include_all=True, callable localization_loader=load_localizations, callable unique_localization_getter=get_unique_localizations)

Protected Member Functions

- `_load_localizations` (self, **kwargs)

Protected Attributes

- `_localization_loader`

6.21.1 Constructor & Destructor Documentation

6.21.1.1 `__init__()`

```
scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS.__init__ (
    self,
    cd,
    blob_parameters,
    fitting_parameters,
    rescale_pixel_size = 10,
    pixel_size = 130,
    loc_error = 30,
    include_all = True,
    callable localization_loader = load_localizations,
    callable unique_localization_getter = get_unique_localizations)
```

Reimplemented from [scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS](#).

6.21.2 Member Function Documentation

6.21.2.1 `_load_localizations()`

```
scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS._load_localizations (
    self,
    ** kwargs) [protected]
```

Reimplemented from [scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS](#).

6.21.3 Member Data Documentation

6.21.3.1 `_localization_loader`

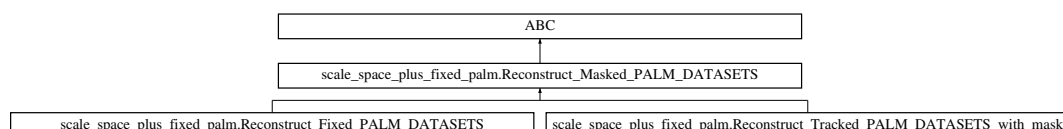
```
scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS._localization_loader [protected]
```

The documentation for this class was generated from the following file:

- /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↵
BP/databases/reconstructionScripts/[scale_space_plus_fixed_palm.py](#)

6.22 `scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_↵ DATASETS` Class Reference

Inheritance diagram for `scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS`:



Public Member Functions

- `__init__` (self, str `cd`, dict `blob_parameters`, dict `fitting_parameters`, `rescale_pixel_size`=10, `pixel_size`=130, `loc_error`=30, `include_all`=True, callable `unique_localization_getter`=`get_unique_localizations`)
- `reconstruct` (self)
- `path_structure_dict` (self)
- `state_parameters` (self)

Public Attributes

- `cd`
- `blob_parameters`
- `fitting_parameters`
- `rescale_pixel_size`
- `pixel_size`
- `loc_error`
- `include_all`

Protected Member Functions

- `_load_localizations` (self)
- `_print_message` (self)
- `_store_parameters` (self)
- None `_save_reconstruction_parameters` (self, str `full_path`)
- None `_check_directory_structure` (self)
- None `_check_if_previous_analysis_has_occured` (self)

Protected Attributes

- `_unique_localization_getter`
- `_state_parameters`
- `_path_structure_dict`

6.22.1 Constructor & Destructor Documentation

6.22.1.1 `__init__()`

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.__init__ (
    self,
    str cd,
    dict blob_parameters,
    dict fitting_parameters,
    rescale_pixel_size = 10,
    pixel_size = 130,
    loc_error = 30,
    include_all = True,
    callable unique_localization_getter = get_unique_localizations)
```

Reimplemented in `scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS`, and `scale_space_plus_fixed_palm.Reconst`

6.22.2 Member Function Documentation

6.22.2.1 `_check_directory_structure()`

None `scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._check_directory_structure (`
 `self) [protected]`

6.22.2.2 `_check_if_previous_analysis_has_occured()`

None `scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._check_if_previous_analysis_↵`
`_has_occured (`
 `self) [protected]`

6.22.2.3 `_load_localizations()`

`scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._load_localizations (`
 `self) [protected]`

Reimplemented in [scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS](#), and [scale_space_plus_fixed_palm.Reconst](#)

6.22.2.4 `_print_message()`

`scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._print_message (`
 `self) [protected]`

6.22.2.5 `_save_reconstruction_parameters()`

None `scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._save_reconstruction_↵`
`parameters (`
 `self,`
 `str full_path) [protected]`

6.22.2.6 `_store_parameters()`

`scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._store_parameters (`
 `self) [protected]`

6.22.2.7 `path_structure_dict()`

`scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.path_structure_dict (`
 `self)`

6.22.2.8 reconstruct()

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.reconstruct (  
    self)
```

Reconstruct the localizations in each cell in each movie

6.22.2.9 state_parameters()

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.state_parameters (  
    self)
```

6.22.3 Member Data Documentation

6.22.3.1 _path_structure_dict

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._path_structure_dict [protected]
```

6.22.3.2 _state_parameters

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._state_parameters [protected]
```

6.22.3.3 _unique_localization_getter

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS._unique_localization_getter [protected]
```

6.22.3.4 blob_parameters

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.blob_parameters
```

6.22.3.5 cd

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.cd
```

6.22.3.6 fitting_parameters

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.fitting_parameters
```

6.22.3.7 include_all

```
scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.include_all
```

6.22.3.8 loc_error

`scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.loc_error`

6.22.3.9 pixel_size

`scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.pixel_size`

6.22.3.10 rescale_pixel_size

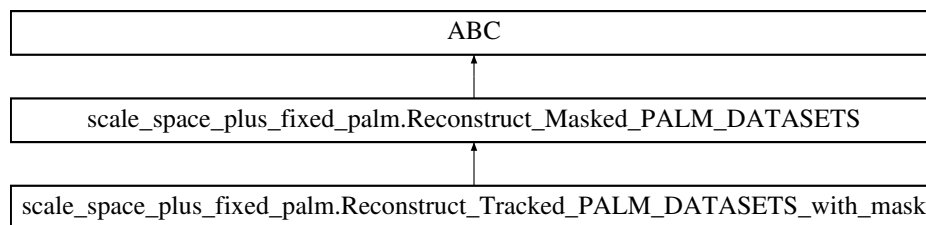
`scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS.rescale_pixel_size`

The documentation for this class was generated from the following file:

- [/Users/baljiyot/Documents/CODE/GitHub_t2/PHD/Baljiyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/reconstructionScripts/scale_space_plus_fixed_palm.py](#)

6.23 scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask Class Reference

Inheritance diagram for `scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask`:



Public Member Functions

- `__init__` (self, `cd`, `blob_parameters`, `fitting_parameters`, `rescale_pixel_size`=10, `pixel_size`=130, `loc_error`=30, `include_all`=True, callable `localization_loader`=[load_localizations](#), callable `unique_localization_getter`=[get_unique_localizations](#))
- `reconstructTime` (self, int `subsample_frequency`=500, int `total_frames`=5000)

Public Attributes

- [include_all](#)

Protected Member Functions

- `_load_localizations` (self, `**kwargs`)

Protected Attributes

- [_localization_loader](#)

6.23.1 Detailed Description

For the masked version of the tracked PALM data, this is different from `scale_space_plus_database_tracked.segm` since it enforces a cell mask for each cell in a movie and also expects a different file structure. (Cellpose File structure is the same as the Fixed cell PALM data.

6.23.2 Constructor & Destructor Documentation

6.23.2.1 `__init__()`

```
scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask.__init__ (
    self,
    cd,
    blob_parameters,
    fitting_parameters,
    rescale_pixel_size = 10,
    pixel_size = 130,
    loc_error = 30,
    include_all = True,
    callable localization_loader = load_localizations,
    callable unique_localization_getter = get_unique_localizations)
```

Reimplemented from [scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS](#).

6.23.3 Member Function Documentation

6.23.3.1 `_load_localizations()`

```
scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask._load_localizations (
    self,
    ** kwargs) [protected]
```

Reimplemented from [scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS](#).

6.23.3.2 `reconstructTime()`

```
scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask.reconstructTime (
    self,
    int subsample_frequency = 500,
    int total_frames = 5000)
```

For each cell we will now make a reconstruction (only, no scale and dbscan analysis) for subsampling

6.23.4 Member Data Documentation

6.23.4.1 `_localization_loader`

`scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask._localization_loader`
[protected]

6.23.4.2 `include_all`

`scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask.include_all`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/reconstructionScripts/scale_space_plus_fixed_palm.py`

6.24 `SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis` Class Reference

Public Member Functions

- `__init__` (self, `wd`, `t_string`, `sim`=False, `unique_name`='')
- `run_flow` (self, `masked_movies`=False)
- `run_flow_sim` (self, `cd`, `t_string`)
- `read_track_data_masked_method` (self, `wd`, `t_string`, **kwargs)
- `read_parameters` (self, `frame_step`=1000, `frame_total`=5000, `t_len_l`=10, `t_len_u`=1000, `MSD_avg_threshold`=0.0001, `upper_bp`=0.99, `lower_bp`=0.50, `max_track_decomp`=1.0, `conversion_p_nm`=130, `minimum_tracks_per_drop`=3, `minimum_percent_per_drop_in`=1.0, `cluster_t_len_l`=7)
- `get_blob_parameters` (self, `threshold`=1e-4, `median`=False, `overlap`=0.5, `num_sigma`=500, `min_sigma`=1, `max_sigma`=3, `log_scale`=False, `detection_name`='bp')
- `get_fitting_parameters` (self, `kwargs`={})
- `type_of_blob` (self)
- `type_of_blob` (self, `value`)
- dict `track_durations` (self)
- bool `isempty` (self)
- dict `parameter_storage` (self)
- `path_structure_dict` (self)

Public Attributes

- [my_name](#)
- [a_file_style](#)
- *LOADING TRACK DATA####.*
- [sim](#)
- [pixel_to_nm](#)
- [pixel_to_um](#)
- [total_experiments](#)
- [wd](#)
- [t_string](#)
- [mat_path_dir](#)
- [frame_step](#)
- [frame_total](#)
- [t_len_l](#)
- [t_len_u](#)
- [blob_t_len_l](#)
- [MSD_avg_threshold](#)
- [upper_bp](#)
- [lower_bp](#)
- [max_track_decomp](#)
- [minimum_tracks_per_drop](#)
- [minimum_percent_per_drop_in](#)
- [frames](#)
- [threshold_blob](#)
- *blob detection parameters*
- [overlap_blob](#)
- [min_sigma_blob](#)
- [max_sigma_blob](#)
- [num_sigma_blob](#)
- [blob_median_filter](#)
- [detection_name](#)
- [log_scale](#)
- [type_of_blob](#)
- [blob_parameters](#)
- [fitting_parameters](#)
- [overwrite_cell_localizations](#)
- *---Load Track Data---##*
- [Movie](#)
- *condensed analysis data Cells in the specific movie being analysed*
- [baljyot_idiot_factor](#)
- *forgot to change scale on some images before trackmate now i need to convert the scale from um to pixel so this all doesn't break*
- [Cells](#)
- *condensed analysis data Cells in the specific movie being analysed*
- [track_collection](#)
- [track_durations](#)

Protected Member Functions

- [_read_track_data_nocells](#) (self, [wd](#), [t_string](#), **kwargs)
- [_read_track_data](#) (self, [wd](#), [t_string](#), **kwargs)
- [_analyse_cell_tracks](#) (self)
- [_map_TrackstoDrops](#) (self, [i](#), [k](#), sorted_tracks)
- [_make_TrueDrop](#) (self, [i](#), [k](#), drop_ID_list, list_drop_track, sorted_tracks)
- [_makeTrackCls](#) (self, temp, which_type, drop_ID, sorted_tracks, kk, l)
- [_analyse_cell_tracks_utility](#) (self, [i](#), [k](#), sorted_tracks)
- [_blob_detection_utility](#) (self, seg_files, movie_ID, plot=False, kwargs={})
- [_read_supersegger](#) (self, sorted_cells)
- [_load_segmented_image_locations](#) (self, pp, cd, [t_string](#), max_tag, min_tag, seg_name="TRACKMATE", analysis_name="TRACKMATE")
- [_load_segmented_image_data](#) (self, drop_files, use_cols=(0, 1, 2), skiprows=0)
- [_get_movie_path](#) (self, movie_ID, frame)
- [_get_frame_cell_mask](#) (self, mask, frame, movie_ID)
- [_get_nucleoid_path](#) (self, movie_ID, cell_ID, full_path=False)
- [_load_track_data](#) (self, track_file, skiprows=4)
- [_load_track_data_as_PD](#) (self, track_file, skiprows=4)
- [_Analysis_path_util](#) (self)
- [_Segmentation_path_util](#) (self)
- [None _check_directory_structure](#) (self)
- [_convert_track_frame](#) (self, track_set, **kwargs)
- [None _convert_track_data_for_cell](#) (self, path, path_structure, cell_ID, movie_ID)
- [_convert_to_track_dict_bulk](#) (self, [Movie](#)=None, track_name_original=True)
- [list _track_collection_utility](#) (self)
- [_store_combined_SMAUG_files](#) (self, combined_dir_name, [Movie](#)=None)
- [None _make_SMAUG_files](#) (self, [Movie](#)=None, dir_name="SMAUG")
- [_store_combined_NOBIAS_files](#) (self, combined_dir_name, [Movie](#)=None)
- [None _make_NOBIAS_files](#) (self, [Movie](#)=None, taus=1, dir_name="NOBIAS")
- [None _pickle_this_object](#) (self)
- [_find_nucleoid](#) (self, movie_ID, cell_ID, img=0)
- [_set_nucleoid_area_bulk](#) (self)
- [_reinitializeVariables](#) (self)

Protected Attributes

- [_type_of_blob](#)
- [_track_durations](#)
- [_parameter_storage](#)
- [_path_structure_dict](#)

6.24.1 Detailed Description

Define a class for each dataset to analyse
Contains multiple frames of view for movies

```
Parameters;
-----
wd : str
    working directory of the stored data
t_string : str
    unique string identifier for dataset
sim : bool
    if True, this is a simulated dataset
```

Methods:

```

get_fitting_parameters(): get the fitting parameters for the dataset
get_blob_parameters(): get the blob detection parameters for the dataset
read_parameters(): read the global parameters for the dataset
run_flow(): run the analysis for the dataset to build the mappings in self.Cells, and self.movie

```

```

_analyse_cell_tracks_utility(): utility function for analyse_cell_tracks
_makeTrackCls(): make the track class for a given trajectory
_make_TrueDrop(): make the true drop class for a given drop
_map_TrackstoDrops(): map the trajectories to the drops
_analyse_cell_tracks(): analyse the cell tracks and make the mappings
_convert_track_frame(): reorder the tracks by subframe rather than the original linking
_find_nucleoid(): find the nucleoid in a given cell
_read_track_data(): read the track data
_load_segmented_image_data(): load the segmented image data
_load_segmented_image_locations(): load the segmented image locations
_read_supersegger(): read the supersegger data
_blob_detection_utility(): utility function for blob detection
_get_nucleoid_path(): get the path to the nucleoid data
_get_frame_cell_mask(): get the cell mask for a given frame
_get_movie_path(): get the path to the movie data
_reinitializeVariables(): reinitialize the variables for a new dataset

```

6.24.2 Constructor & Destructor Documentation

6.24.2.1 __init__()

```

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.__init__ (
    self,
    wd,
    t_string,
    sim = False,
    unique_name = "")

```

Parameters:

```

wd : str
    working directory of the stored data
t_string : str
    unique string identifier for dataset
sim : bool
    if True, this is a simulated dataset

self.Cells : list
    list of cells in the dataset
self.movie : list
    list of movies in the dataset

```

6.24.3 Member Function Documentation

6.24.3.1 _analyse_cell_tracks()

```

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._analyse_cell_tracks (
    self) [protected]

```

Helper function to create mapping of Movie.Cell.Drop.Trajectory

6.24.3.2 `_analyse_cell_tracks_utility()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._analyse_cell_tracks_utility (
    self,
    i,
    k,
    sorted_tracks) [protected]

Main function that:
1) Identifies viable drops
2) Classifies trajecotries based on 1)
```

6.24.3.3 `_Analysis_path_util()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._Analysis_path_util (
    self) [protected]
```

6.24.3.4 `_blob_detection_utility()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._blob_detection_utility
(
    self,
    seg_files,
    movie_ID,
    plot = False,
    kwargs = {}) [protected]

Utility function for the use of blob_dections to find the candidate spots

Parameteres
-----
seg_files : array-like of img locations (str)
    location of the images
plot : bool
    if true plot the images with the circles ontop
    else don't plot and don't print the possible drops
movie_ID : str
    key identifier for the frame of reference, i.e the movie in this whole dataset
kwarg : dict
    keyword arguments for the blob_detection function

KWARGS:
-----
threshold : float
    threshold for the blob detection
overlap : float
    overlap for the blob detection
median : bool
    if true then apply a median filter to the image
min_sigma : float
    minimum sigma for the blob detection
max_sigma : float
    maximum sigma for the blob detection
num_sigma : int
    number of sigmas for the blob detection
detection : str
    which detection method to use
```



```

log_scale : bool
    if true then use a log scale for the blob detection

Returns
-----
array-like
    for each seg_file find the possible blobs and return the center coordinates and radius
    [len(seg_files),# circles identified, 3 ([x,y,r])]

```

6.24.3.5 _check_directory_structure()

None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._check_directory_↵
structure (

self) [protected]

Returns error if Movies is not in the directory structure
Returns True if localizations.csv have been built for all cells
Returns False if localizations.csv have not been built for all cells

6.24.3.6 _convert_to_track_dict_bulk()

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._convert_to_track_dict_↵
_bulk (

self,
Movie = None,
track_name_original = True) [protected]

Docstring for _convert_to_track_dict_bulk

Purpose: convert the Movie object into a dictionary of tracks for the bulk analysis of MSD

Parameters:

Movie: Movie object, default None
Movie object to convert to a dictionary of tracks

Returns:

track_dict: dictionary
dictionary of tracks with keys "IN","OUT","IO","ALL" and values being a dictionary of tracks with

6.24.3.7 _convert_track_data_for_cell()

None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._convert_track_↵
data_for_cell (

self,
path,
path_structure,
cell_ID,
movie_ID) [protected]

Converts the raw data files from TRACKMATE into the same format .csv but now only considering points i

Parameters:

path : str
path to the raw data file from TRACKMATE
path_structure : dict
dictionary of the directory structure (same as self.path_structure, but a copy is passed)
cell_ID : str
key identifier for the cell of interest
movie_ID : str
key identifier for the frame of reference, i.e the movie in this whole dataset

6.24.3.8 `_convert_track_frame()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._convert_track_frame (
    self,
    track_set,
    ** kwargs) [protected]
```

This function preps the data such that the tracks satisfy a length and segregates the data in respect to the frame step.

Parameters

`track_set` : array-like
the set of tracks for one specific frame of reference from TrackMate (unfiltered)
This is a 2D array with the following columns: [track_ID, frame_ID, x, y, intensity]

`**kwargs` : dict

- `frame_total` : int
the total number of frames in the movie
- `frame_step` : int
the step size for the frame
- `track_len_upper` : int
the upper limit of the track length
- `track_len_lower` : int
the lower limit of the track length
- `order` : tuple
the order of the data in track_set
- `conversion` : float
the conversion factor for the data in track_set

Returns

array-like : [track_n, x_n, y_n, i_n, f_n]

- `track_n` : array-like of ints
track_IDs from TrackMate
- `x_n` : array-like of floats
x coordinates of the localization belonging to index of track_ID
- `y_n` : array-like of floats
y coordinates of the localization belonging to index of track_ID
- `i_n` : array-like of floats
intensity of the localization belonging to index of track_ID
- `f_n` : array-like of floats
frame of the movie the localization belonging to index of track_ID

6.24.3.9 `_find_nucleoid()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._find_nucleoid (
    self,
    movie_ID,
    cell_ID,
    img = 0) [protected]
```

This function finds the nucleoid for a given cell. This is done by using the segmented image of the nucleoid and finding the largest blob in the image.

Parameters:

`movie_ID` : int
the movie ID number

`cell_ID` : int
the cell ID number

`img` : array-like
the image to use for nucleoid detection. If not provided, the function will load the image from the Movie object.

Returns:

feature_mask : array-like

the mask of the nucleoid with pixel labels = 1

regions : regionprops object

the regionprops object for the nucleoid detections, see skimage.measure.regionprops and nucleoid.c

6.24.3.10 _get_frame_cell_mask()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._get_frame_cell_mask (
    self,
    mask,
    frame,
    movie_ID) [protected]
```

6.24.3.11 _get_movie_path()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._get_movie_path (
    self,
    movie_ID,
    frame) [protected]
```

Gives the path of the specific time projected frame (0-4) of the movie (reference frame)

Parameters

movie_ID : str

key identifier for the frame of reference, i.e the movie in this whole dataset

frame : int, or array-like of ints

the specific time projected subframe of the movie

Returns

string, or array-like of strings

if frame is a single integer then returns the path to that specific subframe

if frame is a set of integers defining the subframes then array of paths of length frame

Note

This function only works if the run_flow() method has already been applied to an instance of the run_a

6.24.3.12 _get_nucleoid_path()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._get_nucleoid_path (
    self,
    movie_ID,
    cell_ID,
    full_path = False) [protected]
```

Returns the gfp image location or the image used to nucleoid segmentation

6.24.3.13 _load_segmented_image_data()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._load_segmented_image_data (
    self,
    drop_files,
    use_cols = (0,1,2),
    skiprows = 0) [protected]
```

6.24.3.14 _load_segmented_image_locations()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._load_segmented_image_locations (
    self,
    pp,
    cd,
    t_string,
    max_tag,
    min_tag,
    seg_name = "TRACKMATE",
    analysis_name = "TRACKMATE") [protected]
```

6.24.3.15 _load_track_data()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._load_track_data (
    self,
    track_file,
    skiprows = 4) [protected]
```

6.24.3.16 _load_track_data_as_PD()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._load_track_data_as_PD (
    self,
    track_file,
    skiprows = 4) [protected]
```

6.24.3.17 _make_NOBIAS_files()

```
None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._make_NOBIAS_files (
    self,
    Movie = None,
    taus = 1,
    dir_name = "NOBIAS") [protected]
```

6.24.3.18 _make_SMAUG_files()

```
None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._make_SMAUG_files (
    self,
    Movie = None,
    dir_name = "SMAUG") [protected]
```

6.24.3.19 _make_TrueDrop()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._make_TrueDrop (
    self,
    i,
    k,
    drop_ID_list,
    list_drop_track,
    sorted_tracks) [protected]
```

6.24.3.20 _makeTrackCls()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._makeTrackCls (
    self,
    temp,
    which_type,
    drop_ID,
    sorted_tracks,
    kk,
    l) [protected]
```

6.24.3.21 _map_TrackstoDrops()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._map_TrackstoDrops (
    self,
    i,
    k,
    sorted_tracks) [protected]
```

6.24.3.22 _pickle_this_object()

```
None SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._pickle_this_object
(
    self) [protected]
```

6.24.3.23 _read_supersegger()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._read_supersegger (
    self,
    sorted_cells) [protected]
```

Reads the structured cell data from supersegger and returns a nested array with the structure

Parameters

sorted_cells : array-like of strings of directories paths
the directories of the different frames of reference that are segmented

Returns

array-like of structured data for each parameter is read, see below

6.24.3.24 `_read_track_data()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._read_track_data (
    self,
    wd,
    t_string,
    ** kwargs)  [protected]
```

TODO: full explanation

Parameters

wd : str
 directory location of the dataset

t_string : str
 unique identifier string for the dataset. Eg. NUSA, nusA, rpoC, RPOC etc.

Returns

array-like : [tracks,drops,blob_total]
 tracks : array-like
 all raw tracks from the dataset of trajectories from TrackMate

 drops : array-like
 drop statistics from TrackMate on time projected images

 blob_total
 drop statistics from blob_detection on time projected images

Notes

This function does more than just the returns.
It also sets up the class substructure for the Movie.Cell.Drop.Trajectory mapping and updates many of

6.24.3.25 `_read_track_data_nocells()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._read_track_data_nocells
(
    self,
    wd,
    t_string,
    ** kwargs)  [protected]
```

Docstring
Alternative to `_read_track_data` for cases when there is no cell segmentation via the supersegger method

Parameters:

wd : str
 directory location of the dataset

t_string : str
 unique identifier string for the dataset. Eg. NUSA, nusA, rpoC, RPOC etc.

Returns:

array-like : [tracks,drops,blob_total]
 tracks : array-like
 all raw tracks from the dataset of trajectories from TrackMate

 drops : array-like
 drop statistics from TrackMate on time projected images

 blob_total
 drop statistics from blob_detection on time projected images

6.24.3.26 _reinitializeVariables()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._reinitializeVariables (
    self) [protected]
```

6.24.3.27 _Segmentation_path_util()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._Segmentation_path_util
(
    self) [protected]
```

6.24.3.28 _set_nucleoid_area_bulk()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._set_nucleoid_area_bulk
(
    self) [protected]
```

This function sets the nucleoid area for each cell in the movie.

6.24.3.29 _store_combined_NOBIAS_files()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._store_combined_NOBIAS↵
_files (
    self,
    combined_dir_name,
    Movie = None) [protected]
```

Store the NOBIAS style data to a combined directory which will contain data from multiple run_analysis

6.24.3.30 _store_combined_SMAUG_files()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._store_combined_SMAUG↵
_files (
    self,
    combined_dir_name,
    Movie = None) [protected]
```

Store the SMAUG style data to a combined directory which will contain data from multiple run_analysis

Parameters:

combined_dir_name: string, default "SMAUG_COMBINED"
name of the directory to store the combined SMAUG files

Movie: Movie object, default None
Movie object to convert to a dictionary of tracks

6.24.3.31 `_track_collection_utility()`

```
list SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._track_collection←
_utility (
    self) [protected]
```

6.24.3.32 `get_blob_parameters()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.get_blob_parameters (
    self,
    threshold = 1e-4,
    median = False,
    overlap = 0.5,
    num_sigma = 500,
    min_sigma = 1,
    max_sigma = 3,
    log_scale = False,
    detection_name = 'bp')
```

`_summary_`

```
Parameters
-----
threshold : _type_, optional
    _description_, by default 1e-4
median : bool, optional
    _description_, by default False
overlap : float, optional
    _description_, by default 0.5
num_sigma : int, optional
    _description_, by default 500
min_sigma : int, optional
    _description_, by default 1
max_sigma : int, optional
    _description_, by default 3
log_scale : bool, optional
    _description_, by default False
detection_name : str, optional
    _description_, by default 'bp'
```

6.24.3.33 `get_fitting_parameters()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.get_fitting_parameters (
    self,
    kwargs = {})
```

Updates the `fitting_parameters` to be used in each iteration of this class object

Kwargs

```
mask_size: int
    when fitting the image with a function this is size of square round a reference point to use for f
residual_func: functional
    function to use when defining the residuals for the fitting
fit_method: string, default 'least squares'
    method of the fitting to use
radius_func: functional, default numpy.mean
    function to use as a method to take two sigams and convert to one radius
plot_fit: bool
```



```

        if True, plots each fit with the fit statistics
centroid_range: int or float-like
    controls the bounds on the fit for the centroid (x,y). Ie: the min fit is x-centroid_range, and max
    same for y.
sigma_range: int or float-like
    controls the bounds on the fit for the sigmas (s_x,s_y). Ie: the min fit is s_x-sigma_range, and max
    same for y.
fitting_image: string
    if "Original" use the original image to fit function
    else use the Laplacian image created with the sigma that maximized the laplacian

Notes
-----
Some of these expect a certain type to work. This is not fully coded yet and might break if you give it
to it.

```

6.24.3.34 isempty()

```

bool SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.isempty (
    self)

```

6.24.3.35 parameter_storage()

```

dict SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.parameter_storage (
    self)

```

6.24.3.36 path_structure_dict()

```

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.path_structure_dict (
    self)

```

6.24.3.37 read_parameters()

```

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.read_parameters (
    self,
    frame_step = 1000,
    frame_total = 5000,
    t_len_l = 10,
    t_len_u = 1000,
    MSD_avg_threshold = 0.0001,
    upper_bp = 0.99,
    lower_bp = 0.50,
    max_track_decomp = 1.0,
    conversion_p_nm = 130,
    minimum_tracks_per_drop = 3,
    minimum_percent_per_drop_in = 1.0,
    cluster_t_len_l = 7)

```

Reads in the parameters needed for the analysis

Parameters:

frame_step : int

Number of subframes used in the analysis

frame_total : int

Total number of frames in the movies

t_len_l : int

Lower bound for the length of the tracks

t_len_u : int

Upper bound for the length of the tracks

MSD_avg_threshold : float

Lower bound threshold for the MSD average, to determine if the track is a valid track and not auto

upper_bp : float

Upper bound proportion threshold for determining if in_out track or out only.

lower_bp : float

Lower bound proportion threshold for determining if in_out track or out only.

max_track_decomp : float

Maximum track decomposition value

conversion_p_nm : float

Conversion factor from pixels to nanometers

minimum_tracks_per_drop : int

Minimum number of tracks per drop to be considered a valid drop

minimum_percent_per_drop_in : float

Minimum percentage of tracks per drop that are in tracks to be considered a valid drop

cluster_t_len_l : int

Minimum length of track to be used in defining the cluster

Notes:

This function reads in variables and assigns them to the attributed of this class instance

6.24.3.38 read_track_data_masked_method()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.read_track_data_masked←
_method (
```

```
    self,
```

```
    wd,
```

```
    t_string,
```

```
    ** kwargs)
```

This is a repeat of `_read_track_data` but now with integration of masks for each cell and a new directory

The structure needs to be as follows (not counting other files and folders):

```
wd
```

```
  -\gfp
```

```
  -\Movies
```

```
      -\Movie_<movie_ID>
```

```
          -\Cell_<cell_ID>
```

```
              -\mask.tif
```

The analysis or analysis_new folders are as before.

Essentially the movie and cell ID are determined by the folder structure. The mask defines the property

After which we need to determine which spots occur in which cell.

Then the rest of the analysis is the same.

6.24.3.39 run_flow()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.run_flow (
    self,
    masked_movies = False)
```

Controls the flow of this dataset analysis

6.24.3.40 run_flow_sim()

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.run_flow_sim (  
    self,  
    cd,  
    t_string)
```

6.24.3.41 track_durations()

```
dict SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.track_durations (  
    self)
```

6.24.3.42 type_of_blob() [1/2]

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.type_of_blob (  
    self)
```

6.24.3.43 type_of_blob() [2/2]

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.type_of_blob (  
    self,  
    value)
```

6.24.4 Member Data Documentation

6.24.4.1 _parameter_storage

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._parameter_storage [protected]
```

6.24.4.2 _path_structure_dict

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._path_structure_dict  
[protected]
```

6.24.4.3 _track_durations

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._track_durations [protected]
```

6.24.4.4 _type_of_blob

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis._type_of_blob [protected]
```

6.24.4.5 a_file_style

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.a_file_style
```

LOADING TRACK DATA####.

6.24.4.6 baljyot_idiot_factor

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.baljyot_idiot_factor
```

forgot to change scale on some images before trackmate now i need to convert the scale from um to pixel so this all doesn't break

6.24.4.7 blob_median_filter

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.blob_median_filter
```

6.24.4.8 blob_parameters

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.blob_parameters
```

6.24.4.9 blob_t_len_l

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.blob_t_len_l
```

6.24.4.10 Cells

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.Cells
```

condensed analysis data Cells in the specific movie being analysed

6.24.4.11 detection_name

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.detection_name
```

6.24.4.12 fitting_parameters

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.fitting_parameters
```

6.24.4.13 frame_step

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.frame_step
```

6.24.4.14 frame_total

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.frame_total
```

6.24.4.15 frames

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.frames
```

6.24.4.16 log_scale

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.log_scale
```

6.24.4.17 lower_bp

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.lower_bp
```

6.24.4.18 mat_path_dir

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.mat_path_dir
```

6.24.4.19 max_sigma_blob

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.max_sigma_blob
```

6.24.4.20 max_track_decomp

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.max_track_decomp
```

6.24.4.21 min_sigma_blob

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.min_sigma_blob
```

6.24.4.22 minimum_percent_per_drop_in

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.minimum_percent_per_drop_in
```

6.24.4.23 minimum_tracks_per_drop

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.minimum_tracks_per_drop
```

6.24.4.24 Movie

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.Movie
```

condensed analysis data Cells in the specific movie being analysed

6.24.4.25 MSD_avg_threshold

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.MSD_avg_threshold
```

6.24.4.26 my_name

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.my_name
```

6.24.4.27 num_sigma_blob

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.num_sigma_blob
```

6.24.4.28 overlap_blob

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.overlap_blob
```

6.24.4.29 overwrite_cell_localizations

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.overwrite_cell_localizations
```

---Load Track Data---##

6.24.4.30 pixel_to_nm

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.pixel_to_nm
```

6.24.4.31 pixel_to_um

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.pixel_to_um
```

6.24.4.32 sim

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.sim
```

6.24.4.33 t_len_l

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.t_len_l
```

6.24.4.34 t_len_u

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.t_len_u
```

6.24.4.35 t_string

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.t_string
```

6.24.4.36 threshold_blob

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.threshold_blob
```

blob detection parameters

6.24.4.37 total_experiments

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.total_experiments
```

6.24.4.38 track_collection

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.track_collection
```

6.24.4.39 track_durations

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.track_durations
```

6.24.4.40 type_of_blob

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.type_of_blob
```

6.24.4.41 upper_bp

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.upper_bp
```

6.24.4.42 wd

`SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis.wd`

The documentation for this class was generated from the following file:

- `/Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/trajectory_analysis_script.py`

6.25 SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.run_analysis_plotting Class Reference

Public Member Functions

- None `__init__` (self)

Static Public Member Functions

- `draw_item` (which_object, plots=1, all_tracks=False, movie_ID='0', cell_ID=['0', '1'], movie_frame_index=3)
- `plot_img` (which_object, plots=1, movie_ID='0', cell_ID='0', movie_frame_index=3)

6.25.1 Constructor & Destructor Documentation

6.25.1.1 `__init__()`

None SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.run_analysis_plotting.`__init__` (
 self)

6.25.2 Member Function Documentation

6.25.2.1 `draw_item()`

SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.run_analysis_plotting.`draw_item` (
 which_object,
 plots = 1,
 all_tracks = False,
 movie_ID = '0',
 cell_ID = ['0', '1'],
 movie_frame_index = 3) [static]

Plot the projected frame (movie_frame_index) of a movie (movie_ID) with specific cells (cell_ID, can be marray of cells).
 If plots == 1, plot only one subfigure, else plot a hard coded identicle set of subplots (2,3)
 If all_tracks == True use the raw_tracks variable for each cell (all possible localization)

Parameters

```

-----
which_object : run_analysis object from trajectory_analysis_script.py
               eg. rp_ez,nusa_ez,ll_ez
plots : int, tuple (n,m)
        number of total subplots
        if 1 plot only one subplot
        else plot (n,m)
all_tracks : bool
             if true use all raw_tracks localizations
             else use only "viable" tracks
movie_ID : str
           key identifier of the movie in this dataset
cell_ID : str, array-like of str
          key identifier of the cell in this movie
          if array plot multiple cell attributes
movie_frame_index : int
                   the subframe of the movie (usually 0-4 for 5 total subframes)

```

RETURNS

```

-----
Array-like
[x,y,fig,ax]
x : float
   x coordinates of all tracks used
y : float
   y coordinates of all tracks used
fig : figure object
     the figure object which defines the plotting
ax : Axes object
    All the sub_plot ax (if plots == 1, this is a single ax, else it is of shape (n,m))

```

6.25.2.2 plot_img()

```

SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.run_analysis_plotting.plot_img (
    which_object,
    plots = 1,
    movie_ID = '0',
    cell_ID = '0',
    movie_frame_index = 3) [static]

```

Given the location of the image in our dataset, plot it given the plotting rules and return the figure/axis ob

Parameters

```

-----
which_object : run_analysis object from trajectory_analysis_script.py
               eg. rp_ez,nusa_ez,ll_ez
plots : int, tuple (n,m)
        number of total subplots
        if 1 plot only one subplot
        else plot (n,m)
movie_ID : str
           key identifier of the movie in this dataset
cell_ID : str, array-like of str
          key identifier of the cell in this movie
          if array plot multiple cell attributes
movie_frame_index : int
                   the subframe of the movie (usually 0-4 for 5 total subframes)

```

Returns

```

-----
array-like of figure,ax objects
    returns the object of the figure and axis created by the plotting of the image

Notes
-----
squeeze is used in plt.subplots(... ,squeeze) to change the shape of the ax objects created

```

```

squeeze : bool, default: True
    - If True, extra dimensions are squeezed out from the returned
      array of `~matplotlib.axes.Axes`:
    - if only one subplot is constructed (nrows=ncols=1), the
      resulting single Axes object is returned as a scalar.
    - for Nx1 or 1xM subplots, the returned object is a 1D numpy
      object array of Axes objects.
    - for NxM, subplots with N>1 and M>1 are returned as a 2D array.
    - If False, no squeezing at all is done: the returned Axes object is
      always a 2D array containing Axes instances, even if it ends up
      being 1x1.

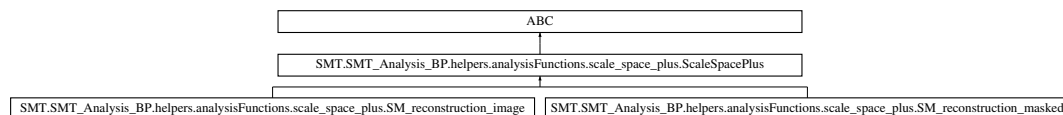
```

The documentation for this class was generated from the following file:

- [/Users/baljiyot/Documents/CODE/GitHub_t2/PHD/Baljiyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/plotting_functions.py](#)

6.26 SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus:



Public Member Functions

- None `__init__` (self)
- [make_reconstruction](#) (self)
- [saving_image](#) (self)
- [print_state](#) (self)

6.26.1 Constructor & Destructor Documentation

6.26.1.1 `__init__`()

```

None SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus.__init__ (
    self)

```

Reimplemented in [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image](#),
and [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked](#).

6.26.2 Member Function Documentation

6.26.2.1 `make_reconstruction()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus.make_reconstruction
(
    self)
```

Reimplemented in [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image](#), and [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked](#).

6.26.2.2 `print_state()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus.print_state (
    self)
```

Reimplemented in [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image](#), and [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked](#).

6.26.2.3 `saving_image()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus.saving_image (
    self)
```

Reimplemented in [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image](#), and [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked](#).

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/scale_space_plus.py`

6.27 `scale_space_plus_database_tracked.segmentation_scale_space` Class Reference

Public Member Functions

- `__init__` (`self`, `cd`, `t_string`, `blob_parameters`, `fitting_parameters`, `img_dim`, `rescale_pixel_size`=10, `type_analysis_file`="new", `total_frames`=5000, `subframes`=5, `pixel_size`=130, `loc_error`=30, `include_all`=True)
- `main_run` (`self`)
- `SMT_Analysis_path` (`self`)
- `segmented_scale_space_plus_path` (`self`)
- `SM_reconstruction_Analysis_path` (`self`)
- `SM_DBSCAN_Analysis_Path` (`self`)

Public Attributes

- [cd](#)
- [t_string](#)
- [blob_parameters](#)
- [fitting_parameters](#)
- [img_dim](#)
- [rescale_pixel_size](#)
- [type_analysis_file](#)
- [total_frames](#)
- [subframes](#)
- [pixel_size](#)
- [loc_error](#)
- [include_all](#)
- [SMT_Analysis_path](#)
- [segmented_scale_space_plus_path](#)

Protected Member Functions

- [_save_parameters](#) (self)

Protected Attributes

- [_SMT_Analysis_path](#)
- [_segmented_scale_space_plus_path](#)
- [_SM_reconstruction_Analysis_path](#)
- [_SM_DBSCAN_Analysis_Path](#)

6.27.1 Constructor & Destructor Documentation**6.27.1.1 __init__()**

```
scale_space_plus_database_tracked.segmentation_scale_space.__init__ (
    self,
    cd,
    t_string,
    blob_parameters,
    fitting_parameters,
    img_dim,
    rescale_pixel_size = 10,
    type_analysis_file = "new",
    total_frames = 5000,
    subframes = 5,
    pixel_size = 130,
    loc_error = 30,
    include_all = True)
```

6.27.2 Member Function Documentation**6.27.2.1 _save_parameters()**

```
scale_space_plus_database_tracked.segmentation_scale_space._save_parameters (
    self) [protected]
```

6.27.2.2 main_run()

```
scale_space_plus_database_tracked.segmentation_scale_space.main_run (  
    self)
```

6.27.2.3 segmented_scale_space_plus_path()

```
scale_space_plus_database_tracked.segmentation_scale_space.segmented_scale_space_plus_path (  
    self)
```

6.27.2.4 SM_DBSCAN_Analysis_Path()

```
scale_space_plus_database_tracked.segmentation_scale_space.SM_DBSCAN_Analysis_Path (  
    self)
```

6.27.2.5 SM_reconstruction_Analysis_path()

```
scale_space_plus_database_tracked.segmentation_scale_space.SM_reconstruction_Analysis_path (  
    self)
```

6.27.2.6 SMT_Analysis_path()

```
scale_space_plus_database_tracked.segmentation_scale_space.SMT_Analysis_path (  
    self)
```

6.27.3 Member Data Documentation

6.27.3.1 _segmented_scale_space_plus_path

```
scale_space_plus_database_tracked.segmentation_scale_space._segmented_scale_space_plus_path  
[protected]
```

6.27.3.2 _SM_DBSCAN_Analysis_Path

```
scale_space_plus_database_tracked.segmentation_scale_space._SM_DBSCAN_Analysis_Path [protected]
```

6.27.3.3 _SM_reconstruction_Analysis_path

```
scale_space_plus_database_tracked.segmentation_scale_space._SM_reconstruction_Analysis_path  
[protected]
```

6.27.3.4 _SMT_Analysis_path

```
scale_space_plus_database_tracked.segmentation_scale_space._SMT_Analysis_path [protected]
```

6.27.3.5 blob_parameters

`scale_space_plus_database_tracked.segmentation_scale_space.blob_parameters`

6.27.3.6 cd

`scale_space_plus_database_tracked.segmentation_scale_space.cd`

6.27.3.7 fitting_parameters

`scale_space_plus_database_tracked.segmentation_scale_space.fitting_parameters`

6.27.3.8 img_dim

`scale_space_plus_database_tracked.segmentation_scale_space.img_dim`

6.27.3.9 include_all

`scale_space_plus_database_tracked.segmentation_scale_space.include_all`

6.27.3.10 loc_error

`scale_space_plus_database_tracked.segmentation_scale_space.loc_error`

6.27.3.11 pixel_size

`scale_space_plus_database_tracked.segmentation_scale_space.pixel_size`

6.27.3.12 rescale_pixel_size

`scale_space_plus_database_tracked.segmentation_scale_space.rescale_pixel_size`

6.27.3.13 segmented_scale_space_plus_path

`scale_space_plus_database_tracked.segmentation_scale_space.segmented_scale_space_plus_path`

6.27.3.14 SMT_Analysis_path

`scale_space_plus_database_tracked.segmentation_scale_space.SMT_Analysis_path`

6.27.3.15 subframes

```
scale_space_plus_database_tracked.segmentation_scale_space.subframes
```

6.27.3.16 t_string

```
scale_space_plus_database_tracked.segmentation_scale_space.t_string
```

6.27.3.17 total_frames

```
scale_space_plus_database_tracked.segmentation_scale_space.total_frames
```

6.27.3.18 type_analysis_file

```
scale_space_plus_database_tracked.segmentation_scale_space.type_analysis_file
```

The documentation for this class was generated from the following file:

- `/Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/reconstructionScripts/scale_space_plus_database_tracked.py`

6.28 SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image Class Reference

Public Member Functions

- `None __init__(self, image, np.ndarray candidate_peaks=None)`
- `fit(self, callable fit_model_residual, dict fit_model_params, dict fit_model_params_bounds, dict prune_direction=None, **kwargs)`
- `image(self)`
- `img_shape(self)`
- `img_background_mean(self)`
- `img_background_std(self)`
- `np.ndarray candidate_peaks(self)`
- `candidate_peaks(self, np.ndarray peaks)`
- `list fit_results(self)`
- `fit_results(self, list fit_results)`
- `lmfit_model(self)`
- `lmfit_model(self, model)`
- `fit_parameters(self)`
- `fit_parameters(self, fit_parameters)`
- `fit_results_df(self)`

Public Attributes

- [plot_fit_results](#)
- [candidate_peaks](#)
- [lmfit_model](#)
- [fit_results](#)
- [img_background_mean](#)
- [fit_parameters](#)

Protected Member Functions

- [_initialize_properties](#) (self, np.ndarray *image*)
- [_update_lmfit_model](#) (self, callable model)
- [_find_candidate_peaks](#) (self, **kwargs)
- [_fit_peaks](#) (self, callable fit_model_residual, dict fit_model_params, dict fit_model_params_bounds)
- [_get_roi_around_peak](#) (self, np.ndarray peak, int roi_size=5)
- [_fit_model_to_roi](#) (self, np.ndarray roi, np.ndarray peak, callable fit_model_residual, dict fit_model_params, dict fit_model_params_bounds)
- [_get_model_params](#) (self, dict fit_model_params, dict fit_model_params_bounds)
- [_get_roi_coordinates](#) (self, np.ndarray roi, np.ndarray peak)
- [_fit_model_to_data](#) (self, callable fit_model_residual, Parameters params, np.ndarray x, np.ndarray y, np.ndarray data)
- [pd.DataFrame _convert_fit_result_pandas](#) (self)
- [_prune_fit_results](#) (self, list params_to_prune, list params_thresholds)

Protected Attributes

- [_image](#)
- [_img_shape](#)
- [_candidate_peaks](#)
- [_fit_results](#)
- [_fit_results_df](#)
- [_image_background_mean](#)
- [_image_background_std](#)
- [_lmfit_model](#)
- [_fit_parameters](#)

6.28.1 Constructor & Destructor Documentation

6.28.1.1 `__init__()`

```
None SMT.SMT_Analysis_BP.helpers.misc.gaussian_fit.SM_Localization_Image.__init__ (
    self,
    image,
    np.ndarray candidate_peaks = None)
```


6.28.2 Member Function Documentation

6.28.2.1 _convert_fit_result_pandas()

```
pd.DataFrame SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._convert_fit_result_pandas (
    self) [protected]
```

Converts the fit results to a pandas dataframe with each row corresponding to a peak, and columns corresponding to the fit parameters and extra columns for the fit errors from the least squares fit

Returns:

```
-----
fit_results_df: pandas.DataFrame
    dataframe of the fit results
```

6.28.2.2 _find_candidate_peaks()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._find_candidate_peaks (
    self,
    ** kwargs) [protected]
```

Private method to find candidate peaks in the image

Parameters:

```
-----
kwargs: dict
    dictionary of keyword arguments to pass to find_peaks
```

Returns:

```
-----
candidate_peaks: numpy array
    array of candidate peaks
```

Keyword Arguments:

```
-----
min_distance: int
    minimum distance in pixels between peaks
threshold_abs: int
    minimum intensity of peaks
exclude_border: int
    number of pixels to exclude from the border of the image
Others are passed to skimage.feature.peak_local_max
```

6.28.2.3 _fit_model_to_data()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._fit_model_to_data (
    self,
    callable fit_model_residual,
    Parameters params,
    np.ndarray x,
    np.ndarray y,
    np.ndarray data) [protected]
```

Fits the passed model to the passed data

Parameters:

`fit_model_residual`: callable
 callable residual function for the model
`params`: Parameters
 parameters for the model
`x`: numpy array
 x coordinates of the data
`y`: numpy array
 y coordinates of the data
`data`: numpy array
 data to fit the model to

Returns:

`fit_results`: `lmfit.minimizer.MinimizerResult`
 results of the fit

6.28.2.4 `_fit_model_to_roi()`

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._fit_model_to_roi (
    self,
    np.ndarray roi,
    np.ndarray peak,
    callable fit_model_residual,
    dict fit_model_params,
    dict fit_model_params_bounds) [protected]
```

Fits the passed model to the passed roi

Parameters:

`roi`: numpy array
 region of interest to fit the model to
`peak`: numpy array
 peak to fit the model to
`fit_model_residual`: callable
 callable residual function for the model
`fit_model_params`: dict
 dictionary of initial parameters for the model
`fit_model_params_bounds`: dict
 dictionary of bounds for the parameters of the model

Returns:

`fit_results`: `lmfit.minimizer.MinimizerResult`
 results of the fit in the form of a `lmfit.MinimizerResult` object

6.28.2.5 `_fit_peaks()`

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._fit_peaks (
    self,
    callable fit_model_residual,
    dict fit_model_params,
    dict fit_model_params_bounds) [protected]
```

Fits the peaks in the image to the passed model

Parameters:

`fit_model_residual`: callable
 callable residual function for the model
`fit_model_params`: dict
 dictionary of initial parameters for the model
`fit_model_params_bounds`: dict
 dictionary of bounds for the parameters of the model

6.28.2.6 `_get_model_params()`

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._get_model_params (
    self,
    dict fit_model_params,
    dict fit_model_params_bounds) [protected]
```

Gets the initial parameters for the model

Parameters:

`fit_model_params`: dict
 dictionary of initial parameters for the model
`fit_model_params_bounds`: dict
 dictionary of bounds for the parameters of the model

6.28.2.7 `_get_roi_around_peak()`

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._get_roi_around_peak (
    self,
    np.ndarray peak,
    int roi_size = 5) [protected]
```

Gets the region of interest around a peak

Parameters:

`peak`: numpy array
 peak to get the roi around

6.28.2.8 `_get_roi_coordinates()`

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._get_roi_coordinates (
    self,
    np.ndarray roi,
    np.ndarray peak) [protected]
```

Gets the x and y coordinates of the roi

Parameters:

`roi`: numpy array
 region of interest to fit the model to
`peak`: numpy array
 peak to fit the model to

6.28.2.9 _initialize_properties()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._initialize_properties (
    self,
    np.ndarray image) [protected]
```

6.28.2.10 _prune_fit_results()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._prune_fit_results (
    self,
    list params_to_prune,
    list params_thresholds) [protected]
```

Prune the fit results based on the passed parameters and thresholds

Parameters:

params_to_prune: list of keys of the parameters to prune

list of parameters to prune

params_thresholds: list of tuples

list of tuples of the form (lower_threshold, upper_threshold) for each parameter in params_to_prune

Returns:

fit_results_pruned: list

list of pruned fit results

Also updates the fit_results property

6.28.2.11 _update_lmfit_model()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._update_lmfit_model (
    self,
    callable model) [protected]
```

6.28.2.12 candidate_peaks() [1/2]

```
np.ndarray SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.candidate_peaks
(
    self)
```

6.28.2.13 candidate_peaks() [2/2]

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.candidate_peaks (
    self,
    np.ndarray peaks)
```

6.28.2.14 fit()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit (
    self,
    callable fit_model_residual,
    dict fit_model_params,
    dict fit_model_params_bounds,
    dict prune_direction = None,
    ** kwargs)
```

Finds candidate peaks in the image and fits them to the passed model, supports only gaussian models for now

Parameters:

```
fit_model_residual: callable
    callable residual function for the model
fit_model_params: dict
    dictionary of initial parameters for the model
fit_model_params_bounds: dict
    dictionary of bounds for the parameters of the model
prune_direction: dict, optional
    dictionary of parameters to prune and the direction to prune them in
    This is a dictionary of the form {parameter_name:prune_direction} where prune_direction is a tuple of the
    the parameter_name is a string matching the key in the fit_model_params dictionary
kwargs: dict
    dictionary of keyword arguments to pass to find_peaks
```

6.28.2.15 fit_parameters() [1/2]

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit_parameters (
    self)
```

6.28.2.16 fit_parameters() [2/2]

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit_parameters (
    self,
    fit_parameters)
```

6.28.2.17 fit_results() [1/2]

```
list SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit_results (
    self)
```

6.28.2.18 fit_results() [2/2]

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit_results (
    self,
    list fit_results)
```

6.28.2.19 fit_results_df()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit_results_df (
    self)
```

6.28.2.20 image()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.image (  
    self)
```

6.28.2.21 img_background_mean()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.img_background_mean (  
    self)
```

6.28.2.22 img_background_std()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.img_background_std (  
    self)
```

6.28.2.23 img_shape()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.img_shape (  
    self)
```

6.28.2.24 lmfit_model() [1/2]

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.lmfit_model (  
    self)
```

6.28.2.25 lmfit_model() [2/2]

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.lmfit_model (  
    self,  
    model)
```

6.28.3 Member Data Documentation

6.28.3.1 _candidate_peaks

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._candidate_peaks [protected]
```

6.28.3.2 _fit_parameters

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._fit_parameters [protected]
```

6.28.3.3 _fit_results

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._fit_results [protected]
```

6.28.3.4 _fit_results_df

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._fit_results_df [protected]

6.28.3.5 _image

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._image [protected]

6.28.3.6 _image_background_mean

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._image_background_mean
[protected]

6.28.3.7 _image_background_std

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._image_background_std
[protected]

6.28.3.8 _img_shape

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._img_shape [protected]

6.28.3.9 _lmfit_model

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image._lmfit_model [protected]

6.28.3.10 candidate_peaks

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.candidate_peaks

6.28.3.11 fit_parameters

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit_parameters

6.28.3.12 fit_results

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.fit_results

6.28.3.13 img_background_mean

SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.img_background_mean

6.28.3.14 lmfit_model

`SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.lmfit_model`

6.28.3.15 plot_fit_results

`SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image.plot_fit_results`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/misc/guassian_fit.py`

6.29 SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie Class Reference

Public Member Functions

- `None __init__(self, movie)`
- `fit(self, callable fit_model_residual, dict fit_model_params, dict fit_model_params_bounds, dict prune_direction=None, List[np.ndarray] candidate_peaks_per_frame=None, **kwargs)`
- `np.ndarray movie(self)`
- `tuple movie_shape(self)`
- `float movie_background_mean(self)`
- `float movie_background_std(self)`
- `dict fit_parameters(self)`
- `list fit_results(self)`
- `pd.DataFrame fit_results_df(self)`

Public Attributes

- `fit_results`
- `fit_results_df`
- `movie`

Protected Member Functions

- `None _initialize_properties(self, np.ndarray movie)`
- `pd.DataFrame _convert_fit_result_pandas(self)`
- `None _save_dataframe(self, str path)`

Protected Attributes

- `_movie`
- `_movie_shape`
- `_fit_results_df`
- `_fit_parameters`
- `_fit_results`
- `_movie_background_mean`
- `_movie_background_std`

6.29.1 Detailed Description

Extension of the SM_Localization_Image class to handle movies in which each frame is a 2D image and is fit to contains utility function to convert to a final pandas dataframe

6.29.2 Constructor & Destructor Documentation

6.29.2.1 __init__()

```
None SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.__init__ (
    self,
    movie)
```

6.29.3 Member Function Documentation

6.29.3.1 _convert_fit_result_pandas()

```
pd.DataFrame SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._convert_fit_result_pandas (
    self) [protected]
```

Converts the fit results to a pandas dataframe with each row corresponding to a peak, and columns corresponding to the fit parameters and extra columns for the fit errors from the least squares fit. We also add 2 more columns for the frame number and a unique peak number in the frame to identify each peak (SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._convert_fit_result_pandas)

Returns:

```
fit_results_df: pandas.DataFrame
    dataframe of the fit results
```

6.29.3.2 _initialize_properties()

```
None SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._initialize_properties (
    self,
    np.ndarray movie) [protected]
```

6.29.3.3 _save_dataframe()

```
None SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._save_dataframe (
    self,
    str path) [protected]
```

Saves the fit results dataframe to a csv file

Parameters:

```
path: str
    path to save the dataframe to (needs to be an absolute path)
```

6.29.3.4 fit()

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.fit (
    self,
    callable fit_model_residual,
    dict fit_model_params,
    dict fit_model_params_bounds,
    dict prune_direction = None,
    List[np.ndarray] candidate_peaks_per_frame = None,
    ** kwargs)
```

Finds candidate peaks in the image and fits them to the passed model, supports only gaussian models for now

Parameters:

```
fit_model_residual: callable
    callable residual function for the model
fit_model_params: dict
    dictionary of initial parameters for the model
fit_model_params_bounds: dict
    dictionary of bounds for the parameters of the model
prune_direction: dict, optional
    dictionary of parameters to prune and the direction to prune them in
    This is a dictionary of the form {parameter_name:prune_direction} where prune_direction is a tuple of the
    the parameter_name is a string matching the key in the fit_model_params dictionary
candidate_peaks_per_frame: numpy array, optional
    numpy array of candidate peaks for each frame, if not passed, the peaks are found using find_peaks
    These need to be [x,y] coordinates
kwargs: dict
    dictionary of keyword arguments to pass to find_peaks
```

6.29.3.5 fit_parameters()

```
dict SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.fit_parameters (
    self)
```

6.29.3.6 fit_results()

```
list SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.fit_results (
    self)
```

6.29.3.7 fit_results_df()

```
pd.DataFrame SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.fit_results←
_df (
    self)
```

6.29.3.8 movie()

```
np.ndarray SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.movie (
    self)
```

6.29.3.9 movie_background_mean()

```
float SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.movie_background_mean (
    self)
```

6.29.3.10 movie_background_std()

```
float SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.movie_background_std (
    self)
```

6.29.3.11 movie_shape()

```
tuple SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.movie_shape (
    self)
```

6.29.4 Member Data Documentation

6.29.4.1 _fit_parameters

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._fit_parameters [protected]
```

6.29.4.2 _fit_results

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._fit_results [protected]
```

6.29.4.3 _fit_results_df

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._fit_results_df [protected]
```

6.29.4.4 _movie

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._movie [protected]
```

6.29.4.5 _movie_background_mean

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._movie_background_mean [protected]
```

6.29.4.6 _movie_background_std

```
SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._movie_background_std [protected]
```

6.29.4.7 `_movie_shape`

`SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie._movie_shape` [protected]

6.29.4.8 `fit_results`

`SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.fit_results`

6.29.4.9 `fit_results_df`

`SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.fit_results_df`

6.29.4.10 `movie`

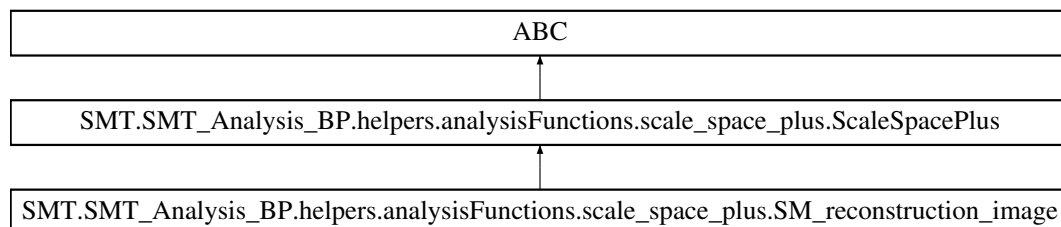
`SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie.movie`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers\misc\guassian_fit.py`

6.30 `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image` Class Reference

Inheritance diagram for `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image`:



Public Member Functions

- `None __init__` (self, tuple|list `img_dims_normal`, int|float `pixel_size_normal`=130, int `rescale_pixel_size`=10)
- `print_state` (self)
- `make_reconstruction` (self, np.ndarray localizations, np.ndarray|float `localization_error`)
- `saving_image` (self, str `full_path`, name, str type)
- `img_dims` (self)
- `img_dims` (self, `img_dims`)
- `img_space` (self)
- `img_space` (self, `img_space`)
- `domain` (self)
- `domain` (self, `domain`)
- `df_localizations` (self)
- `df_localizations` (self, `df_localizations`)
- `total_localizations` (self)

Public Attributes

- [img_dims_normal](#)
- [pixel_size_normal](#)
- [rescale_pixel_size](#)
- [img_dims](#)
- [domain](#)
- [df_localizations](#)
- [img_space](#)

Protected Attributes

- [_img_dims](#)
- [_img_space](#)
- [_domain](#)
- [_df_localizations](#)

6.30.1 Constructor & Destructor Documentation

6.30.1.1 `__init__()`

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.↔
__init__ (
    self,
    tuple|list img_dims_normal,
    int|float pixel_size_normal = 130,
    int rescale_pixel_size = 10)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.30.2 Member Function Documentation

6.30.2.1 `df_localizations()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.df_↔
localizations (
    self)
```

6.30.2.2 `df_localizations()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.df_↔
localizations (
    self,
    df_localizations)
```

6.30.2.3 `domain()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.domain
(
    self)
```

6.30.2.4 domain() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.domain
(
    self,
    domain)
```

6.30.2.5 img_dims() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.img↔
dims (
    self)
```

6.30.2.6 img_dims() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.img↔
dims (
    self,
    img_dims)
```

6.30.2.7 img_space() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.img↔
space (
    self)
```

6.30.2.8 img_space() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.img↔
space (
    self,
    img_space)
```

6.30.2.9 make_reconstruction()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.make↔
reconstruction (
    self,
    np.ndarray localizations,
    np.ndarray|float localization_error)
```

Parameters:

localizations: np.ndarray

Array of localizations in the form of (x,y) in pixels (original scale)

localization_error: np.ndarray or float

Array of localization error in nm or a scalar

Returns:

img_space: np.ndarray

Image space of the reconstruction

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.30.2.10 print_state()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.print←  
_state (  
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.30.2.11 saving_image()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.←  
saving_image (  
    self,  
    str full_path,  
    name,  
    str type)
```

Parameters:

```
-----  
full_path: str  
    Full path to save the image  
name: str  
    Name of the image  
type: str  
    Type of the image. Supported:  
    - png  
    - jpg  
    - tif  
    - svg
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.30.2.12 total_localizations()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.total←  
_localizations (  
    self)
```

6.30.3 Member Data Documentation

6.30.3.1 _df_localizations

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image._df←  
localizations [protected]
```

6.30.3.2 _domain

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image._domain  
[protected]
```

6.30.3.3 `_img_dims`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image._img↵  
dims [protected]
```

6.30.3.4 `_img_space`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image._img↵  
space [protected]
```

6.30.3.5 `df_localizations`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.df↵  
localizations
```

6.30.3.6 `domain`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.domain
```

6.30.3.7 `img_dims`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.img↵  
dims
```

6.30.3.8 `img_dims_normal`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.img↵  
dims_normal
```

6.30.3.9 `img_space`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.img↵  
space
```

6.30.3.10 `pixel_size_normal`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.pixel↵  
_size_normal
```


6.30.3.11 rescale_pixel_size

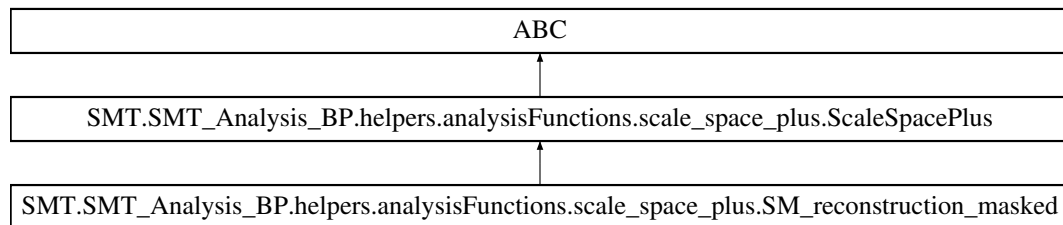
```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image.↔
rescale_pixel_size
```

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔
BP/helpers/analysisFunctions/[scale_space_plus.py](#)

6.31 SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_↔ plus.SM_reconstruction_masked Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_↔
_masked:



Public Member Functions

- None `__init__` (self, tuple|list [img_dims_normal](#), int|float [pixel_size_normal](#)=130, int [rescale_pixel_size](#)=10)
- [print_state](#) (self)
- [make_reconstruction](#) (self, localizations, localization_error, masked_img)
- [make_uniform_reconstruction](#) (self, localizations, localization_error, masked_img)
- [saving_image](#) (self, np.ndarray img, str full_path, str type=None)
- [coordinate_conversion](#) (self, np.ndarray spatial_dim, np.ndarray radius, str conversion_type)
- [masked_img_space](#) (self)
- [img_dims](#) (self)
- [masked_domain](#) (self)
- [bounding_box](#) (self)
- [df_localizations](#) (self)
- [df_localizations](#) (self, df_localizations)

Public Attributes

- [img_dims_normal](#)
- [pixel_size_normal](#)
- [rescale_pixel_size](#)
- [normal_domain](#)
- [df_localizations](#)

Protected Member Functions

- [_get_uniform_localization](#) (self, [masked_domain](#), num_localizations)
- None [_setup_masked_domain](#) (self, int mask_value, np.ndarray [masked_img_space](#))
- None [_setup_bounding_box](#) (self)

Protected Attributes

- [_img_dims](#)
- [_masked_img_space](#)
- [_masked_domain](#)
- [_bounding_box](#)
- [_df_localizations](#)

6.31.1 Constructor & Destructor Documentation

6.31.1.1 __init__()

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
__init__ (
    self,
    tuple|list img_dims_normal,
    int|float pixel_size_normal = 130,
    int rescale_pixel_size = 10)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.31.2 Member Function Documentation

6.31.2.1 _get_uniform_localization()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked._get↔
_uniform_localization (
    self,
    masked_domain,
    num_localizations) [protected]
```

6.31.2.2 _setup_bounding_box()

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
_setup_bounding_box (
    self) [protected]
```

Sets up the bounding box for the reconstruction. This is the bounding box of the masked domain.
Sets:

```
-----
self._bounding_box: np.ndarray
    The bounding box of the masked domain. The format is:
    [[x_min,y_min],[x_max,y_max]]
```

6.31.2.3 _setup_masked_domain()

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
_setup_masked_domain (
    self,
    int mask_value,
    np.ndarray masked_img_space) [protected]
```

Setups the masked domain for the reconstruction. This is the domain of the image space which represents a cell area.
Parameters:

mask_value: int

The value in the masked_img_space which represents the cell area (usually 1)

masked_img_space: np.ndarray

The masked image space. If None then the attribute masked_img_space is used. If the attribute does not exist then the whole image is used.
This is a 2D array defining the frame of view of the whole img

Sets:

self._masked_domain: np.ndarray

The domain of the masked image space which represents the cell area in which the localizations are located

The format is:

[[x,y],[x,y],...,[x,y]] where x,y represent the index and hence the pixel location in the masked image space

6.31.2.4 bounding_box()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
bounding_box (
    self)
```

6.31.2.5 coordinate_conversion()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
coordinate_conversion (
    self,
    np.ndarray spatial_dim,
    np.ndarray radius,
    str conversion_type)
```

Converts the spatial dimension of the reconstruction image to the original image space.

Parameters:

spatial_dim: ndarray

The spatial dimension to convert. This is the dimension of the reconstruction image space.

radius: ndarray

The radius of the reconstruction image space.

conversion_type: str

The type of conversion to perform. Supported:

- RC_to_Original: converts the reconstruction image space to the original image space
- original_to_RC: converts the original image space to the reconstruction image space

Returns:

converted_dim: ndarray

The converted spatial dimension

convert_radius: ndarray

The converted radius

6.31.2.6 df_localizations() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.df↵
localizations (
    self)
```

6.31.2.7 df_localizations() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.df↵
localizations (
    self,
    df_localizations)
```

6.31.2.8 img_dims()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.img↵
dims (
    self)
```

6.31.2.9 make_reconstruction()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.make↵
_reconstruction (
    self,
    localizations,
    localization_error,
    masked_img)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.31.2.10 make_uniform_reconstruction()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.make↵
_uniform_reconstruction (
    self,
    localizations,
    localization_error,
    masked_img)
```

We will now use the number of localizations to uniformly make a reconstruction image on the masked domain.

6.31.2.11 masked_domain()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↵
masked_domain (
    self)
```

6.31.2.12 masked_img_space()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔  
masked_img_space (  
    self)
```

6.31.2.13 print_state()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔  
print_state (  
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.31.2.14 saving_image()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔  
saving_image (  
    self,  
    np.ndarray img,  
    str full_path,  
    str type = None)
```

Save the given image to the full path with the given name and type.

```
Parameters:  
-----  
img: np.ndarray  
    The image to save  
full_path: str  
    Full path to save the image (this includes the name)  
type: str  
    Type of the image. Supported:  
    - png  
    - jpg  
    - tif  
    - svg
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus](#).

6.31.3 Member Data Documentation

6.31.3.1 _bounding_box

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔  
bounding_box [protected]
```

6.31.3.2 _df_localizations

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔  
localizations [protected]
```

6.31.3.3 _img_dims

SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked._img↔
_dims [protected]

6.31.3.4 _masked_domain

SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked._↔
masked_domain [protected]

6.31.3.5 _masked_img_space

SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked._↔
masked_img_space [protected]

6.31.3.6 df_localizations

SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.df↔
localizations

6.31.3.7 img_dims_normal

SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.img↔
dims_normal

6.31.3.8 normal_domain

SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
normal_domain

6.31.3.9 pixel_size_normal

SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
pixel_size_normal

6.31.3.10 rescale_pixel_size

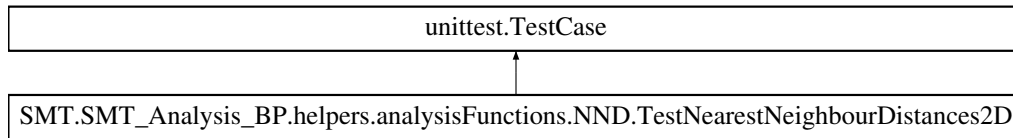
SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked.↔
rescale_pixel_size

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔
BP/helpers/analysisFunctions/[scale_space_plus.py](#)

6.32 SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestNearestNeighbourDistances2D Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestNearestNeighbourDistances2D↩↪:



Public Member Functions

- [test_nearest_neighbour_distances_2d](#) (self)

6.32.1 Member Function Documentation

6.32.1.1 test_nearest_neighbour_distances_2d()

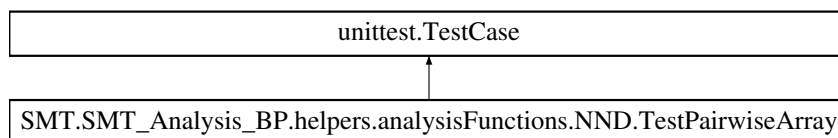
```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestNearestNeighbourDistances2D.test_nearest_neighbour_distances_2d (  
    self)
```

The documentation for this class was generated from the following file:

- /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/[NND.py](#)↩↪

6.33 SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestPairwiseArray Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestPairwiseArray:



Public Member Functions

- [test_pairwise_array](#) (self)

6.33.1 Member Function Documentation

6.33.1.1 test_pairwise_array()

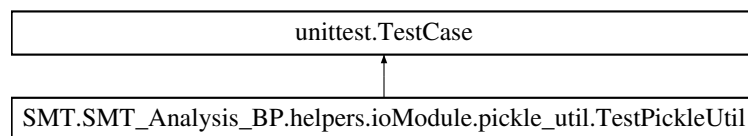
```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestPairwiseArray.test_pairwise_array (
    self)
```

The documentation for this class was generated from the following file:

- [/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/NND.py](#)

6.34 SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.TestPickleUtil Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.TestPickleUtil:



Public Member Functions

- [setUp](#) (self)
- [test_save_and_load](#) (self)
- [tearDown](#) (self)

Public Attributes

- [pickle_util](#)

6.34.1 Member Function Documentation

6.34.1.1 setUp()

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.TestPickleUtil.setUp (
    self)
```

6.34.1.2 tearDown()

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.TestPickleUtil.tearDown (
    self)
```


6.34.1.3 test_save_and_load()

```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.TestPickleUtil.test_save_and_load (
    self)
```

6.34.2 Member Data Documentation

6.34.2.1 pickle_util

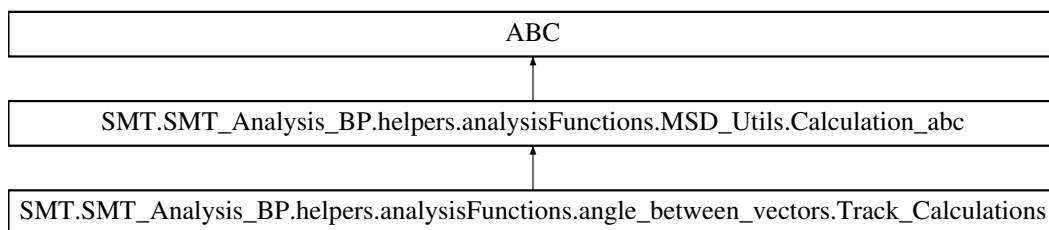
```
SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.TestPickleUtil.pickle_util
```

The documentation for this class was generated from the following file:

- /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/pickle_util.py

6.35 SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations Class Reference

Inheritance diagram for SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations:



Public Member Functions

- None `__init__` (self, list data_set_RA, float pixel_to_um=0.13, float frame_to_seconds=0.02, str frame_units="s", str pixel_units="um", **kwargs)
- `combined_store` (self)
- `combined_store` (self, combined_store)
- `individual_store` (self)
- `individual_store` (self, individual_store)

Public Attributes

- `track_dataset`

Protected Member Functions

- `_build_Tracks_combined` (self, **kwargs)
- `_build_Tracks_individual` (self, **kwargs)
- `_build_Tracks` (self, **kwargs)

Protected Attributes

- [_combined_store](#)
- [_individual_store](#)

6.35.1 Constructor & Destructor Documentation

6.35.1.1 __init__()

None SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations.↵
__init__ (

```
    self,
    list data_set_RA,
    float pixel_to_um = 0.13,
    float frame_to_seconds = 0.02,
    str frame_units = "s",
    str pixel_units = "um",
    ** kwargs)
```

Parameters:

```
-----
data_set_RA: list
    list of tas.run_analysis objects
pixel_to_um: float
    pixel to um conversion
frame_to_seconds: float
    frame to seconds conversion
frame_units: str
    frame units
pixel_units: str
    pixel units
```

KWARGS:

```
-----
min_track_length: int, Default = 1
    minimum track length to be considered.
max_track_length: int, Default = 1000
    maximum track length to be considered.
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.35.2 Member Function Documentation

6.35.2.1 _build_Tracks()

SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._↵
build_Tracks (

```
    self,
    ** kwargs) [protected]
```

Parameters:

```
-----
KWARGS:
-----
Passed to af.MSD_Tracks()
```

6.35.2.2 `_build_Tracks_combined()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._↵
build_Tracks_combined (
    self,
    ** kwargs) [protected]
```

6.35.2.3 `_build_Tracks_individual()`

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._↵
build_Tracks_individual (
    self,
    ** kwargs) [protected]
```

6.35.2.4 `combined_store()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._↵
combined_store (
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.35.2.5 `combined_store()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._↵
combined_store (
    self,
    combined_store)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.35.2.6 `individual_store()` [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._↵
individual_store (
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.35.2.7 `individual_store()` [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._↵
individual_store (
    self,
    individual_store)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.35.3 Member Data Documentation

6.35.3.1 `_combined_store`

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._combined_store` [protected]

6.35.3.2 `_individual_store`

`SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations._individual_store` [protected]

6.35.3.3 `track_dataset`

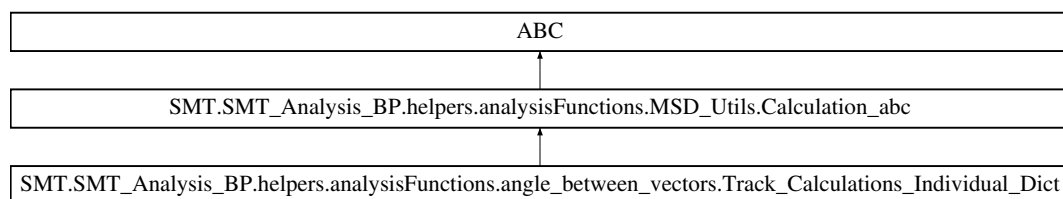
`SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations.track_dataset`

The documentation for this class was generated from the following file:

- `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/angle_between_vectors.py`

6.36 `SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_Individual_Dict` Class Reference

Inheritance diagram for `SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_Individual_Dict`:



Public Member Functions

- `None __init__(self, track_dict, **kwargs)`
- `combined_store(self)`
- `combined_store(self, combined_store)`
- `individual_store(self)`
- `individual_store(self, individual_store)`

Public Attributes

- `track_dict`
- `pixel_to_um`
- `frame_to_seconds`

Protected Member Functions

- [_build_Angle_Tracks](#) (self, **kwargs)

Protected Attributes

- [_storage](#)

6.36.1 Constructor & Destructor Documentation

6.36.1.1 __init__()

```
None SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict.__init__ (
    self,
    track_dict,
    ** kwargs)
```

Parameters:

```
-----
track_dict: dict
    dict of tracks in the form:
    {
        track_ID: [[x,y], ..., [x,y]],
        .
        .
        .
    }
KWARGS:
-----
pixel_to_um: float
    pixel to um conversion
frame_to_seconds: float
    frame to seconds conversion
frame_units: str
    frame units
pixel_units: str
    pixel units
min_track_length: int, Default = 1
    minimum track length to be considered.
max_track_length: int, Default = 1000
    maximum track length to be considered.
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc](#).

6.36.2 Member Function Documentation

6.36.2.1 _build_Angle_Tracks()

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict._build_Angle_Tracks (
    self,
    ** kwargs) [protected]
```

6.36.2.2 combined_store() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict.combined_store (
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utls.Calculation_abc](#).

6.36.2.3 combined_store() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict.combined_store (
    self,
    combined_store)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utls.Calculation_abc](#).

6.36.2.4 individual_store() [1/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict.individual_store (
    self)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utls.Calculation_abc](#).

6.36.2.5 individual_store() [2/2]

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict.individual_store (
    self,
    individual_store)
```

Reimplemented from [SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utls.Calculation_abc](#).

6.36.3 Member Data Documentation**6.36.3.1 _storage**

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict._storage [protected]
```

6.36.3.2 frame_to_seconds

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔
Individual_Dict.frame_to_seconds
```

6.36.3.3 pixel_to_um

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔  
Individual_Dict.pixel_to_um
```

6.36.3.4 track_dict

```
SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_↔  
Individual_Dict.track_dict
```

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↔
BP/helpers/analysisFunctions/[angle_between_vectors.py](#)

6.37 SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.↔ Trajectory Class Reference

Public Member Functions

- `__init__` (self, [Track_ID](#), [Frame_number](#), [X](#), [Y](#), [Classification](#), [Drop_Identifier](#), [Frames](#), [MSD_total_um](#)=None, [**kwargs](#))

Public Attributes

- [Track_ID](#)
- [Frame_number](#)
- [Frames](#)
- [X](#)
- [Y](#)
- [Intensity](#)
- [Classification](#)
- [Drop_Identifier](#)
- [MSD_total_um](#)
- [distance_from_drop](#)

6.37.1 Detailed Description

Trajectory attribute class

Parameters

`__init__` :

```

    Track_ID : int
        unique identifier for each trajectory
    Frame_number : int
        frame number of the trajectory (based on the sub segmented frames) (i.e 0,1,2,3,4 if subframes = 5)
    X : list or np.array
        x coordinates of the trajectory
    Y : list or np.array
        y coordinates of the trajectory
    Classification : str
        "IN" or "OUT" or "IO", for In Drop, Out Drop, In and Out Drop
    Drop_Identifier : str
        ID of the drop that the trajectory belongs to
    Frames : list or np.array
        frame numbers of the trajectory (based on the original frames)
    Intensity : list or np.array
        intensity of the trajectory (same length as X and Y and Frames)
    MSD_total_um : float, default = None
        total MSD of the trajectory

```

Kwargs:

```

distance_from_drop : float
    distance from the drop center to the trajectory

```

6.37.2 Constructor & Destructor Documentation

6.37.2.1 `__init__()`

```

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.__init__ (
    self,
    Track_ID,
    Frame_number,
    X,
    Y,
    Classification,
    Drop_Identifier,
    Frames,
    MSD_total_um = None,
    ** kwargs)

```

6.37.3 Member Data Documentation

6.37.3.1 Classification

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.Classification

6.37.3.2 `distance_from_drop`

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.distance_from_drop

6.37.3.3 Drop_Identifier

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.Drop_Identifier

6.37.3.4 Frame_number

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.Frame_number

6.37.3.5 Frames

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.Frames

6.37.3.6 Intensity

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.Intensity

6.37.3.7 MSD_total_um

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.MSD_total_um

6.37.3.8 Track_ID

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.Track_ID

6.37.3.9 X

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.X

6.37.3.10 Y

SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory.Y

The documentation for this class was generated from the following file:

- /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/trajectory_analysis_script.py↵

6.38 SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory_Drop_Mapping Class Reference↵

Public Member Functions

- [__init__](#) (self, [Drop_ID](#))

Public Attributes

- [Drop_ID](#)
- [IN_Trajectory_Collection](#)
- [OUT_Trajectory_Collection](#)
- [IO_Trajectory_Collection](#)

6.38.1 Detailed Description

create a mapping for each viable drop to store all the Trajectory instances that belong to it in terms of

Parameters

`__init__` :

 Drop_ID : str

 unique identifier for each viable drop (i.e "0,1" for the first drop in the first sub-frame)

 Note that the first number is the sub-frame number and the second number is the drop index in that

 See notes for more information

IN_Trajectory_Collection : dict

 dictionary of all the IN trajectories that belong to the viable drop

OUT_Trajectory_Collection : dict

 dictionary of all the OUT trajectories that belong to the viable drop

IO_Trajectory_Collection : dict

 dictionary of all the IN and OUT trajectories that belong to the viable drop

Notes:

1. Each dictionary is of the form (i,j) -> (frame,trajectory index) where i is the frame number and j is the trajectory index where the above represent the keys, the values are instances of the Trajectory class

2. The frame number is based on the sub segmented frames (i.e 0,1,2,3,4 if subframes = 5)

3. The trajectory index is the index of the trajectory in the raw_tracks list of the Cell class object

4. The viable drop index is the index of the detected drop in the Drop_Collection dictionary of the Cell class object

5. 4) shows that the viable drop index is the same as the drop index in the raw_tracks list of the Cell class object (i.e the drop index is determined by the blob detection. After the viability criterion is applied the non-viable drops are removed. For a collection of drops with IDs (0,1), (0,2), (0,3), if (0,2) is not viable then the viable drops are: (0,1), (0,3)

6.38.2 Constructor & Destructor Documentation

6.38.2.1 `__init__()`

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory_Drop_Mapping.__init__ (
    self,
    Drop_ID)
```

6.38.3 Member Data Documentation

6.38.3.1 Drop_ID

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory_Drop_Mapping.Drop_ID
```

6.38.3.2 IN_Trajectory_Collection

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory_Drop_Mapping.IN_Trajectory_Collection
```

6.38.3.3 IO_Trajectory_Collection

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory_Drop_Mapping.IO_Trajectory↵  
_Collection
```

6.38.3.4 OUT_Trajectory_Collection

```
SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory_Drop_Mapping.OUT_Trajectory↵  
_Collection
```

The documentation for this class was generated from the following file:

- /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_↵
BP/databases/[trajectory_analysis_script.py](#)

Chapter 7

File Documentation

7.1 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔ RPOC/Scripts/SMT/__init__.py File Reference

Namespaces

- namespace [SMT](#)

7.2 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/__init__.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)

7.3 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/databases/__init__.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.databases](#)

7.4 [/Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/directoryManipulator/___init___](#).py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.databases](#)
- namespace [SMT.SMT_Analysis_BP.databases.directoryManipulator](#)

7.5 [/Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/___init___](#).py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)

7.6 [/Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/___init___](#).py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions](#)

7.7 [/Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/clusterMethods/___init___](#).py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.clusterMethods](#)

7.8 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/___init___py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule](#)

7.9 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/misc/___init___py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc](#)

7.10 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/Parameter_Store/___init___py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.Parameter_Store](#)

7.11 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/data_path_container.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.databases](#)
- namespace [SMT.SMT_Analysis_BP.databases.data_path_container](#)

Variables

- dict [SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_ez_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_m9_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_hex5_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.laci_laco_ez_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.laci_laco_m9_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.laci_laco_hex5_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_rif_paths](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.rpoc_ez_cluster_tracking_paths](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.nusa_ez_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.nusa_m9_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.nusa_hex5_paths_keywords](#)
- dict [SMT.SMT_Analysis_BP.databases.data_path_container.nusa_rif_paths_keywords](#)
- list [SMT.SMT_Analysis_BP.databases.data_path_container.rpoc](#)
movie paths in volumes
- list [SMT.SMT_Analysis_BP.databases.data_path_container.ll](#)

7.12 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/databases/directory↔ Manipulator/format_mask_structure.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.movie_mask_directory_structure_manag](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.databases](#)
- namespace [SMT.SMT_Analysis_BP.databases.directoryManipulator](#)
- namespace [SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure](#)

Functions

- [SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.read_npy_file](#) (path, correct↔
_dtype=True)
- dict [SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.obtain_masks_npy](#)
(np_output_file)
- None [SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure._reorder_file_names](#)
(file_paths, end_string=None)

Variables

- list [SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.path](#)
testing
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.format_mask_structure.mask_dir](#) = [movie_mask_directory_structure_r](#)

7.13 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/directoryManipulator/tifanal.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.databases](#)
- namespace [SMT.SMT_Analysis_BP.databases.directoryManipulator](#)
- namespace [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal](#)

Variables

- dict [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.SEGMENT_TYPE](#)
- int [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.STACK_STEP](#) = 5
- int [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.CONVERT_NAME](#) = 1
- str [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.DIR_PATH](#) = "/Volumes/Baljyot_HD/SMT_Olympus/RIF_TREATMET_LIVE/20230528/Movie"
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.root](#) = tk.Tk()
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.filez](#) = fd.askopenfilenames(parent=[root](#), title='Choose a file', initialdir=[DIR_PATH](#))
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.root_dir](#) = os.path.dirname([filez](#)[0])
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.sorted_a_files](#) = sorted([filez](#),key=lambda x: int(x.split("/")[-1].split(".")[0].split("_")[-1]))
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.temp_im](#) = io.imread([sorted_a_files](#)[i])
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.temp_del](#) = [temp_im](#)[:]
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.length](#) = int(len([temp_del](#))/[STACK_STEP](#))
- list [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.hold_img](#) = []
- list [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.hold_name](#) = []
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.movie_name](#) = [sorted_a_files](#)[i].split("/")[-1].split(".")[0]
- [SMT.SMT_Analysis_BP.databases.directoryManipulator.tifanal.updated_movie_name](#) = [movie_name](#).split("_")[:-1]

7.14 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/reconstructionScripts/scale_space_plus_database_tracked.py File Reference

Classes

- class [scale_space_plus_database_tracked.segmentation_scale_space](#)

Namespaces

- namespace [scale_space_plus_database_tracked](#)

Variables

- int `scale_space_plus_database_tracked.CORRECTION_FACTOR` = 1.
- str `scale_space_plus_database_tracked.LOCALIZATION_UNIQUE_TYPE` = "mean"
- list `scale_space_plus_database_tracked.cds`
- list `scale_space_plus_database_tracked.t_strings`
- dict `scale_space_plus_database_tracked.blob_parameters`
- dict `scale_space_plus_database_tracked.fitting_parameters`
- list `scale_space_plus_database_tracked.img_dims`
- list `scale_space_plus_database_tracked.rescale_pixel_size`
- list `scale_space_plus_database_tracked.type_analysis_file`
- list `scale_space_plus_database_tracked.total_frames`
- list `scale_space_plus_database_tracked.subframes`
- list `scale_space_plus_database_tracked.pixel_size`
- list `scale_space_plus_database_tracked.loc_error`
- list `scale_space_plus_database_tracked.include_all`
- `scale_space_plus_database_tracked.batch`

7.15 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_↵ RPOC/Scripts/SMT/SMT_Analysis_BP/databases/reconstruction_↵ Scripts/scale_space_plus_fixed_palm.py File Reference

Classes

- class `scale_space_plus_fixed_palm.Reconstruct_Masked_PALM_DATASETS`
- class `scale_space_plus_fixed_palm.Reconstruct_Fixed_PALM_DATASETS`
- class `scale_space_plus_fixed_palm.Reconstruct_Tracked_PALM_DATASETS_with_mask`

Namespaces

- namespace `scale_space_plus_fixed_palm`

Functions

- `scale_space_plus_fixed_palm.load_localizations` (localizations_path, skiprows=4)
- `scale_space_plus_fixed_palm.load_localizations_TS` (localizations_path, skiprows=0)
- `pd.DataFrame scale_space_plus_fixed_palm.get_unique_localizations` (pd.DataFrame localizations_df, str unique_loc_type="first")
- `pd.DataFrame scale_space_plus_fixed_palm.get_unique_localizations_TS` (pd.DataFrame localizations_df, str unique_loc_type="first")
- `scale_space_plus_fixed_palm.rescale_scale_space_blob_detection` (blobs, callable rescaling_func, **kwargs)

Variables

- int `scale_space_plus_fixed_palm.CORRECTION_FACTOR` = 1.
- str `scale_space_plus_fixed_palm.LOCALIZATION_UNIQUE_TYPE` = "mean"
- list `scale_space_plus_fixed_palm.XY_NAMES` = ['x','y']
- list `scale_space_plus_fixed_palm.global_path`
- dict `scale_space_plus_fixed_palm.blob_parameters`
- dict `scale_space_plus_fixed_palm.fitting_parameters`
- `scale_space_plus_fixed_palm.sm_rec`

7.16 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/structure_storage.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.databases](#)
- namespace [SMT.SMT_Analysis_BP.databases.structure_storage](#)

Variables

- dict [SMT.SMT_Analysis_BP.databases.structure_storage.SEGMENTATION_FOLDER_TYPES](#)
FOLDER STRUCTURES #####.
- dict [SMT.SMT_Analysis_BP.databases.structure_storage.ANALYSIS_FOLDER_TYPES](#)
- dict [SMT.SMT_Analysis_BP.databases.structure_storage.LOADING_DROP_BLOB_TYPES](#)

7.17 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/thunderSTORM/localization_merger.py File Reference

Namespaces

- namespace [localization_merger](#)

Functions

- `pd.DataFrame` [localization_merger.merge_localization](#) (`pd.DataFrame` tracks, `max_dist=1`, `max_frame_gap=1`)

Variables

- list [localization_merger.COL_NAMES_THUNDERSTORM](#) = ['id', 'frame', 'x [nm]', 'y [nm]', 'sigma [nm]', 'intensity [photon]', 'offset [photon]', 'bkgstd [photon]', 'chi2', 'uncertainty [nm]']
- list [localization_merger.NEW_COL_NAMES](#) = ['id', 'frame', 'x [nm]', 'y [nm]', 'sigma [nm]', 'intensity [photon]', 'offset [photon]', 'bkgstd [photon]', 'chi2', 'uncertainty [nm]', 'merged']

7.18 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/databases/thunderSTORM/localization_setter.py File Reference

Classes

- class [localization_setter.path_structure](#)
- class [localization_setter.mask_localization](#)

Namespaces

- namespace [localization_setter](#)

Variables

- str [localization_setter.RELATIVE_ANALYSIS_FOLDER](#) = "TS_Analysis"
- int [localization_setter.BOUNDING_BOX_EXTRA_BORDER](#) = 2
- list [localization_setter.paths](#)
- [localization_setter.ml](#) = [mask_localization](#)(path)

7.19 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/databases/trajectory_↔ analysis_script.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.run_analysis](#)
- class [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Movie_frame](#)
- class [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Cell](#)
- class [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory_Drop_Mapping](#)
- class [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.Trajectory](#)
- class [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.boundary_analysis](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.databases](#)
- namespace [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script](#)

Variables

- list [SMT.SMT_Analysis_BP.databases.trajectory_analysis_script.TRACK_TYPES](#)

7.20 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/databases/utilities/utility_↔ database.py File Reference

Classes

- class [utility_database.Counter_start_stop](#)

Namespaces

- namespace [utility_database](#)

Variables

- list `utility_database.ALLOWED_START_TYPES` = [int,float]

7.21 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/fiji/BP_TRACKING.py File Reference

Namespaces

- namespace `BP_TRACKING`

Functions

- `BP_TRACKING.main()`
- `BP_TRACKING.tracking_plus_save` (directory_path, dir_save, file_path, file_counter)
- `BP_TRACKING.sorted_alphanumeric` (data)

Variables

- str `BP_TRACKING.DIRECTORY_MOVIES` = "/Volumes/Baljyot_HD/SMT_Olympus/RIF_TREATMET_LIVE/20230528/Movie" ↩
- str `BP_TRACKING.MOVIE_BASE_NAME` = "nusa_rif"
- str `BP_TRACKING.DIRECTORY_SAVE` = "Analysis_new"
- dict `BP_TRACKING.LINKING_PARAMETERS`
- dict `BP_TRACKING.LOCALIZATION_PARAMETERS`
- dict `BP_TRACKING.FILTERING_PARAMETERS`
- dict `BP_TRACKING.OUTPUT_COLUMNS`
- list `BP_TRACKING.OUTPUT_COLUMNS_ORDER`
- int `BP_TRACKING.PAD_ROWS` = 3
- `BP_TRACKING.model` = Model()
- `BP_TRACKING.settings` = Settings(imp)
- `BP_TRACKING.detectorFactory`
- `BP_TRACKING.detectorSettings`
- `BP_TRACKING.trackerFactory`
- `BP_TRACKING.trackerSettings`
- `BP_TRACKING.trackmate` = TrackMate(model, settings)
- `BP_TRACKING.ok` = trackmate.checkInput()
- `BP_TRACKING.ds` = DisplaySettingsIO.readUserDefault()
- `BP_TRACKING.selectionModel` = SelectionModel(model)
- `BP_TRACKING.displayer` = HyperStackDisplayer(model, selectionModel, imp, ds)
- `BP_TRACKING.spt_m` = model.getSpots()
- `BP_TRACKING.tracks_found` = model.getTrackModel().trackIDs(True)
- `BP_TRACKING.tot_spts` = spt_m.getNSpots(True)
- `BP_TRACKING.fm` = model.getFeatureModel()
- list `BP_TRACKING.header_row` = [header_name for header_name in `OUTPUT_COLUMNS_ORDER`]
- list `BP_TRACKING.collection_spots_per_track` = [header_row]
- `BP_TRACKING.track` = model.getTrackModel().trackSpots(id)
- int `BP_TRACKING.spot_counter` = 0
- `BP_TRACKING.sid` = spot.ID()

- `int BP_TRACKING.spot_label = spot_counter`
- `BP_TRACKING.spot_ID = sid`
- `BP_TRACKING.track_ID = id`
- `BP_TRACKING.spot_quality = spot.getFeature('QUALITY')`
- `BP_TRACKING.spot_x = spot.getFeature('POSITION_X')`
- `BP_TRACKING.spot_y = spot.getFeature('POSITION_Y')`
- `BP_TRACKING.spot_z = spot.getFeature('POSITION_Z')`
- `BP_TRACKING.spot_t = spot.getFeature('POSITION_T')`
- `BP_TRACKING.spot_frame = spot.getFeature('FRAME')`
- `BP_TRACKING.spot_radius = spot.getFeature('RADIUS')`
- `BP_TRACKING.spot_visibility = spot.getFeature('VISIBILITY')`
- `BP_TRACKING.spot_manual_spot_color = spot.getFeature('MANUAL_SPOT_COLOR')`
- `BP_TRACKING.spot_mean_intensity_ch1 = spot.getFeature('MEAN_INTENSITY_CH1')`
- `BP_TRACKING.spot_median_intensity_ch1 = spot.getFeature('MEDIAN_INTENSITY_CH1')`
- `BP_TRACKING.spot_min_intensity_ch1 = spot.getFeature('MIN_INTENSITY_CH1')`
- `BP_TRACKING.spot_max_intensity_ch1 = spot.getFeature('MAX_INTENSITY_CH1')`
- `BP_TRACKING.spot_total_intensity_ch1 = spot.getFeature('TOTAL_INTENSITY_CH1')`
- `BP_TRACKING.spot_std_intensity_ch1 = spot.getFeature('STD_INTENSITY_CH1')`
- `BP_TRACKING.spot_contrast_ch1 = spot.getFeature('CONTRAST_CH1')`
- `BP_TRACKING.spot_snr_ch1 = spot.getFeature('SNR_CH1')`
- `BP_TRACKING.writer = csv.writer(f, delimiter=',')`
- `BP_TRACKING.start_time = time.time()`

7.22 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_↵ RPOC/Scripts/SMT/SMT_Analysis_BP/fiji/OLD_METHODS/testing_↵ new_script.py File Reference

Namespaces

- namespace `testing_new_script`

Variables

- `str testing_new_script.dir_tiff = '/Volumes/Balijyot_HD/SMT_Olympus/Balijyot_temp/12/rpoc_m9'`
- `testing_new_script.files = glob.glob(dir_tiff + '/' + '*seg.tif')`
- `str testing_new_script.root = dir_tiff`
- `str testing_new_script.save_analysis_dir = dir_tiff + '/' + 'Analysis_test'`
- `testing_new_script.str_name_fil = files[z]`
- `testing_new_script.imp = IJ.openImage(str_name_fil)`
- `testing_new_script.dims = imp.getDimensions();`
- `testing_new_script.model = Model()`
- `testing_new_script.logger = Logger.IJ_LOGGER`
- `testing_new_script.settings = Settings(imp)`
- `testing_new_script.detectorFactory`
- `testing_new_script.detectorSettings`
- `testing_new_script.trackerFactory`
- `testing_new_script.trackerSettings`
- `testing_new_script.initialSpotFilterValue`
- `testing_new_script.trackmate = TrackMate(model, settings)`
- `testing_new_script.ok = trackmate.checkInput()`
- `testing_new_script.selectionModel = SelectionModel(model)`

- `testing_new_script.displayer` = HyperStackDisplayer(`model`, `selectionModel`, `imp`)
- `int testing_new_script.go` = 0
- `testing_new_script.fm` = `model.getFeatureModel()`
- `testing_new_script.a` = `model.getSpots().iterator(True)`
- `str testing_new_script.cd` = `root`
- `testing_new_script.v` = `fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')`
- `testing_new_script.track` = `model.getTrackModel().trackSpots(id)`
- `testing_new_script.sid` = `spot.ID()`
- `testing_new_script.x` = `spot.getFeature('POSITION_X')`
- `testing_new_script.y` = `spot.getFeature('POSITION_Y')`
- `testing_new_script.t` = `spot.getFeature('FRAME')`
- `testing_new_script.rad` = `spot.getFeature('RADIUS')`
- `testing_new_script.q` = `spot.getFeature('QUALITY')`
- `testing_new_script.snr` = `spot.getFeature('SNR')`
- `testing_new_script.mean` = `spot.getFeature('MEAN_INTENSITY')`
- `str testing_new_script.dir_name_save_inten` = `save_analysis_dir + '/' + files[z][-4] + '.tif_spots' + '.csv'`
- `testing_new_script.spamWriter` = `csv.writer(f, delimiter=',')`

7.23 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/fiji/OLD_METHODS/tracking_tif_jpy.py File Reference

Namespaces

- namespace `tracking_tif_jpy`

Variables

- `str tracking_tif_jpy.dir_tiff` = `"/Users/baljyot/Documents/2019-2020/RNAP_PAPER/Baljyot_EXP_RPOC/DATA/new_days/20190527/ll_ez/segmented"`
- `list tracking_tif_jpy.files` = `[fi for fi in files if fi.endswith("seg.tif")]`
- `tracking_tif_jpy.num_files` = `len(files)`
- `str tracking_tif_jpy.save_analysis_dir` = `dir_tiff + '/' + 'Analysis'`
- `str tracking_tif_jpy.str_name_fil` = `root + '/' + files [z]`
- `tracking_tif_jpy.imp` = `IJ.openImage(str_name_fil)`
- `tracking_tif_jpy.model` = `Model()`
- `tracking_tif_jpy.settings` = `Settings()`
- `tracking_tif_jpy.detectorFactory`
- `tracking_tif_jpy.detectorSettings`
- `tracking_tif_jpy.trackerFactory`
- `tracking_tif_jpy.trackerSettings`
- `tracking_tif_jpy.trackmate` = `TrackMate(model, settings)`
- `tracking_tif_jpy.ok` = `trackmate.checkInput()`
- `tracking_tif_jpy.selectionModel` = `SelectionModel(model)`
- `tracking_tif_jpy.displayer` = `HyperStackDisplayer(model, selectionModel, imp)`
- `int tracking_tif_jpy.go` = 0
- `tracking_tif_jpy.fm` = `model.getFeatureModel()`
- `tracking_tif_jpy.a` = `model.getSpots().iterator(True)`
- `str tracking_tif_jpy.cd` = `"D:\\Baljyot_Experiments\\20190524\\rpoc\\segmented"`
- `tracking_tif_jpy.x` = `i.getFeature("POSITION_X")`
- `tracking_tif_jpy.y` = `i.getFeature("POSITION_Y")`
- `tracking_tif_jpy.std` = `i.getFeature("STANDARD_DEVIATION")`
- `tracking_tif_jpy.rad` = `i.getFeature("RADIUS")`
- `tracking_tif_jpy.ed` = `i.getFeature("ESTIMATED_DIAMETER")`
- `str tracking_tif_jpy.dir_name_save_inten` = `save_analysis_dir + '/' + files[z] + '_' + 'spots' + '.csv'`
- `tracking_tif_jpy.spamWriter` = `csv.writer(f, delimiter=',')`

7.24 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_↵ RPOC/Scripts/SMT/SMT_Analysis_BP/fiji/OLD_METHODS/tracking_↵ _tif_jpy_track.py File Reference

Namespaces

- namespace [tracking_tif_jpy_track](#)

Variables

- str [tracking_tif_jpy_track.dir_tiff](#) = '/Users/baljyot/Documents/2022-2023/PhD Thesis/Random_data'
- list [tracking_tif_jpy_track.files](#) = ["Hurst_0.5_Diff_1e-2_seg.tiff"]
- str [tracking_tif_jpy_track.root](#) = [dir_tiff](#)
- str [tracking_tif_jpy_track.save_analysis_dir](#) = [dir_tiff](#) + '/' + 'Analysis'
- str [tracking_tif_jpy_track.str_name_fil](#) = [root](#) + '/' + [files](#)[z]
- [tracking_tif_jpy_track.imp](#) = [IJ.openImage\(str_name_fil\)](#)
- [tracking_tif_jpy_track.dims](#) = [imp.getDimensions\(\)](#);
- [tracking_tif_jpy_track.model](#) = [Model\(\)](#)
- [tracking_tif_jpy_track.settings](#) = [Settings\(\)](#)
- [tracking_tif_jpy_track.detectorFactory](#)
- [tracking_tif_jpy_track.detectorSettings](#)
- [tracking_tif_jpy_track.trackerFactory](#)
- [tracking_tif_jpy_track.trackerSettings](#)
- [tracking_tif_jpy_track.initialSpotFilterValue](#)
- [tracking_tif_jpy_track.trackmate](#) = [TrackMate\(model, settings\)](#)
- [tracking_tif_jpy_track.ok](#) = [trackmate.checkInput\(\)](#)
- [tracking_tif_jpy_track.selectionModel](#) = [SelectionModel\(model\)](#)
- [tracking_tif_jpy_track.displayer](#) = [HyperStackDisplayer\(model, selectionModel, imp\)](#)
- int [tracking_tif_jpy_track.go](#) = 0
- [tracking_tif_jpy_track.fm](#) = [model.getFeatureModel\(\)](#)
- [tracking_tif_jpy_track.a](#) = [model.getSpots\(\).iterator\(True\)](#)
- str [tracking_tif_jpy_track.cd](#) = "/Users/baljyot/Documents/2022-2023/PhD Thesis/Random_data"
- [tracking_tif_jpy_track.v](#) = [fm.getTrackFeature\(id, 'TRACK_MEAN_SPEED'\)](#)
- [tracking_tif_jpy_track.track](#) = [model.getTrackModel\(\).trackSpots\(id\)](#)
- [tracking_tif_jpy_track.sid](#) = [spot.ID\(\)](#)
- [tracking_tif_jpy_track.x](#) = [spot.getFeature\('POSITION_X'\)](#)
- [tracking_tif_jpy_track.y](#) = [spot.getFeature\('POSITION_Y'\)](#)
- [tracking_tif_jpy_track.t](#) = [spot.getFeature\('FRAME'\)](#)
- [tracking_tif_jpy_track.rad](#) = [spot.getFeature\('RADIUS'\)](#)
- [tracking_tif_jpy_track.q](#) = [spot.getFeature\('QUALITY'\)](#)
- [tracking_tif_jpy_track.snr](#) = [spot.getFeature\('SNR'\)](#)
- [tracking_tif_jpy_track.mean](#) = [spot.getFeature\('MEAN_INTENSITY'\)](#)
- str [tracking_tif_jpy_track.dir_name_save_inten](#) = [save_analysis_dir](#) + '/' + [files](#)[z][:4] + '.tif_spots' + '.csv'
- [tracking_tif_jpy_track.spamWriter](#) = [csv.writer\(f, delimiter=','\)](#)

7.25 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_↵ RPOC/Scripts/SMT/SMT_Analysis_BP/fiji/OLD_↵ METHODS/trackmate_exp.py File Reference

Namespaces

- namespace [trackmate_exp](#)

Variables

- `trackmate_exp.imp` = `IJ.openImage('/Users/balijyot/Desktop/Balijyot_EXP_RPOC/Scripts/0.tif')`
- `trackmate_exp.model` = `Model()`
- `trackmate_exp.settings` = `Settings()`
- `trackmate_exp.detectorFactory`
- `trackmate_exp.detectorSettings`
- `trackmate_exp.trackerFactory`
- `trackmate_exp.trackerSettings`
- `trackmate_exp.initialSpotFilterValue`
- `trackmate_exp.trackmate` = `TrackMate(model, settings)`
- `trackmate_exp.ok` = `trackmate.checkInput()`
- `trackmate_exp.selectionModel` = `SelectionModel(model)`
- `trackmate_exp.displayer` = `HyperStackDisplayer(model, selectionModel, imp)`
- `trackmate_exp.fm` = `model.getFeatureModel()`
- `trackmate_exp.v` = `fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')`
- `trackmate_exp.track` = `model.getTrackModel().trackSpots(id)`
- `trackmate_exp.sid` = `spot.ID()`
- `trackmate_exp.x` = `spot.getFeature('POSITION_X')`
- `trackmate_exp.y` = `spot.getFeature('POSITION_Y')`
- `trackmate_exp.t` = `spot.getFeature('FRAME')`
- `trackmate_exp.q` = `spot.getFeature('QUALITY')`
- `trackmate_exp.snr` = `spot.getFeature('SNR')`
- `trackmate_exp.mean` = `spot.getFeature('MEAN_INTENSITY')`

7.26 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/fiji/OLD_METHODS/trackmate_scripting.py File Reference

Namespaces

- namespace `trackmate_scripting`

Variables

- `trackmate_scripting.imp` = `IJ.openImage('https://fiji.sc/samples/FakeTracks.tif')`
- `trackmate_scripting.model` = `Model()`
- `trackmate_scripting.settings` = `Settings(imp)`
- `trackmate_scripting.detectorFactory`
- `trackmate_scripting.detectorSettings`
- `trackmate_scripting.trackerFactory`
- `trackmate_scripting.trackerSettings`
- `trackmate_scripting.initialSpotFilterValue`
- `trackmate_scripting.trackmate` = `TrackMate(model, settings)`
- `trackmate_scripting.ok` = `trackmate.checkInput()`
- `trackmate_scripting.sm` = `SelectionModel(model)`
- `trackmate_scripting.ds` = `DisplaySettingsIO.readUserDefault()`
- `trackmate_scripting.displayer` = `HyperStackDisplayer(model, sm, imp, ds)`
- `trackmate_scripting.fm` = `model.getFeatureModel()`
- `trackmate_scripting.v` = `fm.getTrackFeature(id, 'TRACK_MEAN_SPEED')`
- `trackmate_scripting.track` = `model.getTrackModel().trackSpots(id)`

- `trackmate_scripting.sid` = `spot.ID()`
- `trackmate_scripting.x` = `spot.getFeature('POSITION_X')`
- `trackmate_scripting.y` = `spot.getFeature('POSITION_Y')`
- `trackmate_scripting.t` = `spot.getFeature('FRAME')`
- `trackmate_scripting.q` = `spot.getFeature('QUALITY')`
- `trackmate_scripting.snr` = `spot.getFeature('SNR_CH1')`
- `trackmate_scripting.mean` = `spot.getFeature('MEAN_INTENSITY_CH1')`

7.27 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_↵ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/↵ Analysis_functions.py File Reference

Namespaces

- namespace `SMT`
- namespace `SMT.SMT_Analysis_BP`
- namespace `SMT.SMT_Analysis_BP.helpers`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions`

Functions

- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.non_linear_curvefit` (`func`, `xdata`, `ydata`, `p0=None`, `method='lm'`, `bounds=None`)
RANDOM FITTING FUNCTIONS #####
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.linear_fitting` (`xdata`, `ydata`, `deg=1`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.gaus1D` (`x`, `a`, `b`, `c`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.gaus2D` (`x`, `a`, `b`, `c`, `a1`, `b1`, `c1`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.gaussian_fit` (`x`, `p0`, `p1`, `p2`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.Thompson_localization_precision` (`float psf_sigma`, `float pixel_size`, `float|np.ndarray num_photons`, `float background_photons`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rayleigh_corr` (`x`, `corr`, `sigma`, `A`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.nnd_correction_rayleigh` (`x`, `sigma`, `xc`, `w`, `a1`, `a2`, `a3`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.cum_sum` (`data`, `binz=10`)
RANDOM UTILITY FUNCTIONS #####
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rescale` (`x`, `a`, `b`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.dif_dis` (`x`, `y`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.dist` (`x`, `y`, `c1`, `c2`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.d_to_rad` (`deg_`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rad_to_d` (`rad_`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.cm_normal` (`x`, `y`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.con_pix_si` (`data`, `con_nm=0.130`, `con_ms=20.`, `which=0`)
- `float SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.radius_of_gyration` (`*args`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.photon_conversion_from_AUD` (`float|np.ndarray AUD`, `float|int photon_conversion_factor`, `float|int quantum_efficiency`, `float|int dark_offset`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.bin_ndarray` (`ndarray`, `new_shape`, `operation='sum'`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.bin_img` (`img`, `bin=2`, `operation='sum'`)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.convert_3d_to_2d` (`a`)

- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_inside_circle2D (circle, point)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.reshape_col2d (arr, permutations)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.range_distance (a, b)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rt_to_xy (r, theta)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.pad_array (subarray, shape, top_left↵_coord, pad=0)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.sorted_alphanumeric (data)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.subarray2D (arr, mask, full=True, transpose=True)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.flatten (t)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.rescale_range (x, min_x, max_x, a, b)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.dic_union_two (dic_1, dic_2)

MSD calculations for sim data format of dict #####

- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.MSD_tavg1 (x, y, f, f_inc=False)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.MSD_tavg (x, y, f, f_inc=False)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.MSD_tavg_single (x, f, f_inc=False)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.track_decomp (x, y, f, max_track↵_decomp)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.fit_MSD_loc_err (t, p_0, p_1, p_2)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.fit_MSD (t, p_0, p_1, p_2)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.fit_MSD_Linear (t, p_0, p_1)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.find_diffusion_coefficient (time, dis↵tance, dim)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.find_static_localization_error_MSD (sigma, dim)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions._random_starting_point (start, end)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.squared_mean_difference (a)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_per_frame_difference (true↵_points_per_frame, extracted_points_per_frame)

Track percent identity functions #####

- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.percent_error (true, estimate, abs=True)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions._point_identity (point_true, track↵_estimate, distance_threshold)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.identity_tracks (track_true, track↵_estimate, **kwargs)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.identity_track_matrix (tracks_true, tracks_estimate, verbose=True, **kwargs)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_error_detection (true_points, extracted_points, threshold=0.5)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.points_per_frame_convert (tracks)
- dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.points_per_frame_bulk_sort (np.ndarray x, np.ndarray y, np.ndarray t)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.convert_point_pairs (tracks)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.point_pair_error_detection (true↵_point_pairs, extracted_point_pairs, threshold=0.5)
- dict SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.area_points_per_frame (dict points_per_frame, callable area_func=radius_of_gyration)
- SMT.SMT_Analysis_BP.helpers.analysisFunctions.Analysis_functions.convex_hull_area (points)

7.28 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysis↔ Functions/angle_between_vectors.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_Storage](#)
- class [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations](#)
- class [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Track_Calculations_Individual_Dict](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors](#)

Functions

- dict [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.Angle_track](#) (dict tracks, conversion_factor=None, tau_conversion_factor=None, min_track_length=3, max_track_length=100, **kwargs)
- np.ndarray [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.trajectory_angles](#) (np.ndarray trajectory)
- float [SMT.SMT_Analysis_BP.helpers.analysisFunctions.angle_between_vectors.asymmetry_metric](#) (np.↔ ndarray angle_distribution, np.ndarray forward_angle_range, np.ndarray backward_angle_range)

7.29 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysis↔ Functions/bootstrap_util.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.bootstrap_hist](#) (data, bins, n_bootstraps=1000, bootsize=None, bootfunc=np.mean)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.bootstrap_mean_std](#) (values, n_bootstraps, bootsize, log_values=False)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.bootstrap_statistic](#) (values, n_bootstraps, bootsize, log_values=False, statistic="mean")

Variables

- list [SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.BOOTSTRAP_PARAMS_NAMES](#)
- list [SMT.SMT_Analysis_BP.helpers.analysisFunctions.bootstrap_util.BOOTSTRAP_PARAMS_DEFAULTS](#)

7.30 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers/analysisFunctions/dir_invert_images.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions.dir_invert_images](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.dir_invert_images.save_invert_images](#) (path, **kwargs)

Variables

- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.dir_invert_images.dir_path](#) = str(sys.argv[1])

7.31 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers/analysisFunctions/features_from_mask.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.extract_mask_properties](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask](#)

Variables

- str `SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.path` = `'/Users/balijot/Documents/SMT_↵_Movies/testing_SM_recon/Movies/Movie_1/Cell_1/mask.tif'`
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.mask` = `io.imread(path)`
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.prop_obj` = `extract_mask_properties(mask)`
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.fig`
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.ax`
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.color`
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.features_from_mask.label`

7.32 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↵RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/↵MSD_Utils.py File Reference

Classes

- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.Calculation_abc`
- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.DatabaseOrderUtil`
- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_storage`
- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations`
- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Calculations_Track_Dict`

Namespaces

- namespace `SMT`
- namespace `SMT.SMT_Analysis_BP`
- namespace `SMT.SMT_Analysis_BP.helpers`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils`

Functions

- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.msd_avgerage_utility` (dict displacements, bool bootstrap=False, float bootstrap_samples=0.1, float bootstrap_percentile=0.95, bootstrap_num=100, **kwargs)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_Tracks` (tracks, permutation=True, conversion_factor=None, tau_conversion_factor=None, min_track_length=1, max_track_length=10, **kwargs)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.radius_of_confinement` (t, r_sqr, D, loc_msd)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.radius_of_confinement_xy` (t, r_sqr, D, loc_↵msd_x, loc_msd_y)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.power_law_xy` (t, alpha, D, loc_msd_x, loc_↵msd_y)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.power_law` (t, alpha, D, loc_msd)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.linear_MSD_fit` (t, a, b)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.combine_track_dicts` (dicts)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils._msd_tau_utility_all` (x, y, tau)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils._msd_tau_utility_single` (x, y, tau)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_tau_utility` (x, y, tau=1, permuta-
tion=True)
- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.MSD_Utils.MSD_tau` (x, y, permutation=True)

7.33 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/NND.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestPairwiseArray](#)
- class [SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.TestNearestNeighbourDistances2D](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.pairwise_array](#) (n)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.NND.nearest_neighbour_distances_2d](#) (x0, y0, x1, y1, verbose_return=False, conversion_factor=0.13)

7.34 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysisFunctions/nucleoid_detection.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions](#)
- namespace [SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.find_nuc](#) (img, str typee, regions=True, **kwargs)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.get_training_set](#) (img)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.get_region](#) (image, type=regionprops, connectivity=2, **kawrgs)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.plot_regions](#) (regions, fig, ax, colorbar_mappable, plot=False)

Variables

- dict [SMT.SMT_Analysis_BP.helpers.analysisFunctions.nucleoid_detection.TESTED_DICT](#)

7.35 `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysis_ Functions/scale_space_plus.py` File Reference

Classes

- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.ScaleSpacePlus`
- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_image`
- class `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.SM_reconstruction_masked`

Namespaces

- namespace `SMT`
- namespace `SMT.SMT_Analysis_BP`
- namespace `SMT.SMT_Analysis_BP.helpers`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus`

Functions

- `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.get_gaussian` (`mu`, `sigma`, `domain`=`[list(range(10)), list(range(10))]`)

Variables

- dict `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.KEY_IMAGE`
- int `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.MASK_VALUE` = 255
- int `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.BOUNDING_BOX_PADDING` = 5
- dict `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.CONVERSION_TYPES` = `{'RC_
to_Original':0,'original_to_RC':1}`
- int `SMT.SMT_Analysis_BP.helpers.analysisFunctions.scale_space_plus.RANDOM_SEED` = 666

7.36 `/Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/analysis_ Functions/smallestenclosingcircle.py` File Reference

Namespaces

- namespace `SMT`
- namespace `SMT.SMT_Analysis_BP`
- namespace `SMT.SMT_Analysis_BP.helpers`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions`
- namespace `SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle`

Functions

- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.make_circle](#) (points)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._make_circle_one_point](#) (points, p)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._make_circle_two_points](#) (points, p, q)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.make_diameter](#) (a, b)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.make_circumcircle](#) (a, b, c)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle.is_in_circle](#) (c, p)
- [SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._cross_product](#) (x0, y0, x1, y1, x2, y2)

Variables

- [int SMT.SMT_Analysis_BP.helpers.analysisFunctions.smallestenclosingcircle._MULTIPLICATIVE_EPSILON](#) = 1 + 1e-14

7.37 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers\clusterMethods/blob_detection.py File Reference

Classes

- [class SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.blob_detection](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.clusterMethods](#)
- namespace [SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.identity](#) (x)
- [SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.iso_gaus](#) (p, x, y, z)
- [SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.residuals_gaus2d](#) (p, x, y, z, **kwargs)
- [SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.gaussian2D](#) (x, y, cen_x, cen_y, sig_x, sig_y, offset, height, kwargs={})

Variables

- [int SMT.SMT_Analysis_BP.helpers.clusterMethods.blob_detection.FWHM_FACTOR](#) = 2.*(np.log(2.+np.sqrt(3)))

7.38 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/cluster↔ Methods/clustering_methods.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.clusterMethods](#)
- namespace [SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods.scale_space_plus_blob_detection](#) (img, blob_parameters, fitting_parameters, show=False)
- [SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods.perfrom_DBSCAN_Cluster](#) (localizations, D, minP, show=False)
- [SMT.SMT_Analysis_BP.helpers.clusterMethods.clustering_methods.perform_HDBSCAN_Cluster](#) (localizations, min_cluster_size, min_samples, show=False)

7.39 /Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/import_↔ functions.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.read_data](#) (path, delimiter=',', skiprow=1, **kwargs)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.read_file](#) (file_loc)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.combine_path](#) (root, path)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.find_image](#) (path, ends_with='.tif', full_↔ path=False)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.name_sorter](#) (strings, keyword)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.find_files](#) (path, extension, keyword=None)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.invert_l16u](#) (img, array=False)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.invert_img](#) (path)
- [SMT.SMT_Analysis_BP.helpers.ioModule.import_functions.save_img](#) (object, path)

7.40 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/logging_and_print_util.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util.beautiful_print](#) (*args, **kwargs)
- [SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util.beautiful_print_dict](#) (dict dict_to_print, **kwargs)
- [SMT.SMT_Analysis_BP.helpers.ioModule.logging_and_print_util.beautiful_print_list](#) (list list_to_print, **kwargs)

7.41 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/pickle_util.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.PickleUtil](#)
- class [SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util.TestPickleUtil](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule.pickle_util](#)

7.42 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/plotting_functions.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.run_analysis_plotting](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.circles](#) (x, y, s, c='b', vmin=None, vmax=None, **kwargs)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.create_circle_obj](#) (dims, fill=False)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.create_box_plot](#) (box_data, tick_list, y_label="", x_label="", y_lim=(), title="", show=False)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.read_imag](#) (path, fig=False, ax=False, show=True)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.contour_intens](#) (img, fig=False, ax=False, show=True, seg=True, perc=95)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.spacialplot_ms](#) (op, fig=False, ax=False, show=True)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.other_plot](#) (op, fig=False, ax=False, show=True)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.animate](#) (i, ax)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.circular_hist](#) (ax, x, bins=16, density=True, offset=0, gaps=True, **kwargs)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.create_circular_mask](#) (h, w, center=None, radius=None)
- [SMT.SMT_Analysis_BP.helpers.ioModule.plotting_functions.plot_stacked_bar](#) (data, series_labels, category←_labels=None, show_values=False, value_format="{ }", y_label=None, colors=None, grid=True, reverse=False)

7.43 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_↵ RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/ioModule/SMT_↵ converters.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.IO_run_analysis](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule](#)
- namespace [SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters](#)

Functions

- list [SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.convert_track_data_SMAUG_format](#) (dict track_data)
- list [SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters.convert_track_data_NOBIAS_format_global](#) (dict track_data, int max_tau=1)
- [SMT.SMT_Analysis_BP.helpers.ioModule.SMT_converters._convert_track_data_NOBIAS_format_tau](#) (displacement_dict, tau, bool include_cor_obs=False)

7.44 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers/misc/decorators.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.misc.decorators.CountCalls](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc.decorators](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.misc.decorators.deprecated](#) (reason)
- [SMT.SMT_Analysis_BP.helpers.misc.decorators.timer](#) (func)
- [SMT.SMT_Analysis_BP.helpers.misc.decorators.debug](#) (func)
- [SMT.SMT_Analysis_BP.helpers.misc.decorators.slow_down](#) (_func=None, *, rate=1)
- [SMT.SMT_Analysis_BP.helpers.misc.decorators.repeat](#) (_func=None, *, num_times=2)
- [SMT.SMT_Analysis_BP.helpers.misc.decorators.singleton](#) (cls)
- [SMT.SMT_Analysis_BP.helpers.misc.decorators.cache](#) (func)
- [SMT.SMT_Analysis_BP.helpers.misc.decorators.set_unit](#) (unit)

Variables

- tuple [SMT.SMT_Analysis_BP.helpers.misc.decorators.string_types](#) = (type(b''), type(u''))

7.45 /Users/balijyot/Documents/CODE/GitHub_t2/PHD/Balijyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP\helpers/misc/diff_mw.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc.diff_mw](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_to_diff](#) (mw, n, T=310.15, micron=True)

Variables

- int [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_RPOC](#) = 155160
- int [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_NUSA](#) = 54871
- int [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_LACI](#) = 38590
- int [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.mw_RNAP](#) = 350000
- int [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.vis_ecoli](#) = 950
- float [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.vis_cyto_ecoli](#) = 2.82
- [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_RPOC](#) = [mw_to_diff\(mw_RPOC,vis_cyto_ecoli\)](#)
- [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_NUSA](#) = [mw_to_diff\(mw_NUSA,vis_cyto_ecoli\)](#)
- [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_LACI](#) = [mw_to_diff\(mw_LACI,vis_cyto_ecoli\)](#)
- [SMT.SMT_Analysis_BP.helpers.misc.diff_mw.dif_RNAP](#) = [mw_to_diff\(mw_RNAP,vis_cyto_ecoli\)](#)

7.46 [/Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔](#) RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/misc/errors.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.misc.errors.InitializationKeys](#)
- class [SMT.SMT_Analysis_BP.helpers.misc.errors.InitializationValues](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc.errors](#)

7.47 [/Users/balijot/Documents/CODE/GitHub_t2/PHD/Balijot_EXP_↔](#) RPOC/Scripts/SMT/SMT_Analysis_BP/helpers/misc/guassian_fit.py File Reference

Classes

- class [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_Localization_Image](#)
- class [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.SM_localization_movie](#)

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.helpers](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc](#)
- namespace [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit](#)

Functions

- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D](#) (x, y, cen_x, cen_y, sig_x, sig_y, offset, height, kwargs={})
define some gaussian models for fitting
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D_theta](#) (x, y, cen_x, cen_y, sig_x, sig_y, theta, offset, height, kwargs={})
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian1D](#) (x, cen_x, sig_x, offset, height, kwargs={})
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D_residual](#) (params, x, y, data, kwargs={})
define some residual functions for fitting
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian2D_theta_residual](#) (params, x, y, data, kwargs={})
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.gaussian1D_residual](#) (params, x, data, kwargs={})
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.find_peaks](#) (image, **kwargs)
define functions to find candidate peaks in a signal for a 2D signal (image)
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.save_dataframe](#) (pd.DataFrame df, str path)

Variables

- str [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.path](#) = "/Volumes/Baljyot_HD/SMT_Olympus/Baljyot_←_temp/20190527/rpoc_ez/Movie/rpoc_ez_6.tif"
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.image](#) = imread(path)
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.sm_localization_movie](#) = [SM_localization_movie](#)(image)
- [SMT.SMT_Analysis_BP.helpers.misc.guassian_fit.fit_results_df](#)

7.48 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_←RPOC/Scripts/SMT/SMT_Analysis_BP/Matlab/batch_convert_←single_fluorescence_BW.m File Reference

Functions

- [imwrite](#) (rd2{i, 1}, filename, 'WriteMode', 'append')

Variables

- clear [a](#) = which('rp_ez_fixed_01.vsi')
- give it an initial file to start with [filelist](#) = dir([fileparts([a](#)) filesep 'rp_ez_fixed_*.vsi'])
- [fileNames](#) = {filelist.name}
- [number_of_files](#) =100
- pick the number of files to convert mkdir Movie mkdir gfp for [k](#)
- [rd2](#) =rd{1,1}
- for [i](#)

7.48.1 Function Documentation

7.48.1.1 imwrite()

```
imwrite (
    rd2{i, 1} ,
    filename ,
    'WriteMode' ,
    'append' )
```

7.48.2 Variable Documentation

7.48.2.1 a

```
clear a = which('rp_ez_fixed_01.vsi')
```

7.48.2.2 fileList

```
give it an initial file to start with fileList = dir([fileparts(a) filesep 'rp_ez_fixed_↵
*.vsi'])
```

7.48.2.3 fileNames

```
fileNames = {filelist.name}
```

7.48.2.4 i

```
for i
```

Initial value:

```
=1:length(rd2(:,1))
```

```
filename=sprintf('rp_ez_fixed_%d.tif',k)
```

7.48.2.5 k

```
pick the number of files to convert mkdir Movie mkdir gfp for k
```

Initial value:

```
=1:1:number_of_files
```

```
rd=bfopen(fileNames{k})
```

7.48.2.6 number_of_files

```
number_of_files =100
```


7.48.2.7 rd2

```
rd2 =rd{1,1}
```

7.49 /Users/baljyot/Documents/CODE/GitHub_t2/PHD/Baljyot_EXP_RPOC/Scripts/SMT/SMT_Analysis_BP/Parameter_Store/global_params.py File Reference

Namespaces

- namespace [SMT](#)
- namespace [SMT.SMT_Analysis_BP](#)
- namespace [SMT.SMT_Analysis_BP.Parameter_Store](#)
- namespace [SMT.SMT_Analysis_BP.Parameter_Store.global_params](#)

Variables

- dict [SMT.SMT_Analysis_BP.Parameter_Store.global_params.PIXELSIZES](#)
- dict [SMT.SMT_Analysis_BP.Parameter_Store.global_params.PHOTON_CONVERSION_FACTORS](#)
- dict [SMT.SMT_Analysis_BP.Parameter_Store.global_params.READOUT_NOISE](#)
- dict [SMT.SMT_Analysis_BP.Parameter_Store.global_params.DARK_OFFSET](#)
- dict [SMT.SMT_Analysis_BP.Parameter_Store.global_params.QUANTUM_EFFICIENCY_561](#)

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