# Stat 102C HW3: Answer Key

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#### Problem 1

```
> SAW = function(n = 5){
   map = matrix(FALSE, nrow = 2*n+1, ncol = 2*n+1)
    r = c = n+1
   w = 1
    for (i in 1:n) {
     map[r, c] = TRUE
      opt = c('up', 'right', 'down', 'left')
      # if up is occupied, delete "1" in options
      if (map[r-1, c] == TRUE) opt = opt[-which(opt == 'up')]
      if (map[r, c+1] == TRUE) opt = opt[-which(opt == 'right')]
      if (map[r+1, c] == TRUE) opt = opt[-which(opt == 'down')]
      if (map[r, c-1] == TRUE) opt = opt[-which(opt == 'left')]
     nopt = length(opt)
      if (nopt == 0) {
        w = 0
       break
     }
     w = w * nopt
     dir = sample(opt, 1)
     if (dir == 'up'){
       r = r - 1
     } else if (dir == 'right'){
       c = c + 1
     } else if (dir == 'down'){
       r = r + 1
      } else {
        c = c - 1
   pathlength = sum(map)
   res = list("w" = w, "length" = pathlength)
    return(res)
+ }
```

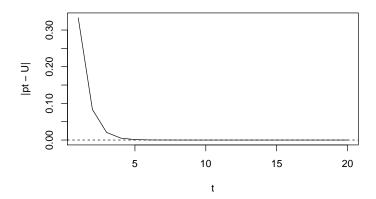
```
> res = replicate(1e5, SAW(10))
> mean(unlist(res[1,]))
[1] 44034.72
```

[1] 0.3333333 0.3333333 0.3333333

#### Problem 2

```
> RW3 = function(t = 1e2, p = c(1, 0, 0), k11 = 0.5, k12 = 0.25,
                  k13 = 0.25, k21 = 0.25, k22 = 0.5, k23 = 0.25,
                  k31 = 0.25, k32 = 0.25, k33 = 0.5) {
    states = c(1, 2, 3)
    K = matrix(c(k11, k12, k13, k21, k22, k23, k31, k32, k33), 3)
    if(!(sum(K[, 1]) == 1 \& sum(K[, 2]) == 1 \& sum(K[, 3]) == 1)) {
      print('Row sum is not 1!')
      break
    }
    for (i in 1:t) {
      p1 = sum(p * K[1,])
      p2 = sum(p * K[2, ])
      p3 = sum(p * K[3, ])
      p = c(p1, p2, p3)
    return(p)
We can set different p^{(0)} as (1, 0, 0), (0, 1, 0), (0, 0, 1). The results are shown as
below. We find that no matter what p^{(0)} is, p^{(t)} is always close to the uniform
distribution.
> RW3(p = c(1, 0, 0))
[1] 0.3333333 0.3333333 0.3333333
> RW3(p = c(0, 1, 0))
```

```
+  }
+  diff = apply(z, 1, FUN = function(x){sum(abs(x - 1/3))})
+  return(diff)
+ }
> t = 20
> abdiff = RW3Unif(t)
> plot(1:t, abdiff, type = 'l', xlab = 't', ylab = '|pt - U|')
> abline(h = 0, lty = 2)
```



The result below suggets that  $p^{(t)}$  will be close to another distribution if you change the transition matrix.

```
> RW3(t = 1e2, k12 = 1/6, k13 = 1/3, k31 = 1/12,
+ k32 = 1/6, k33 = 3/4)
```

[1] 0.2142857 0.2500000 0.5357143

## Problem 3

```
# get the number of people at 1
     n1 = sum(people == 1)
     n2 = sum(people == 2)
     n3 = sum(people == 3)
      # get the index of people at 1
      index1 = which(people == 1)
      index2 = which(people == 2)
      index3 = which(people == 3)
      # draw the next states for those at 1
     move1 = sample(states, n1, replace = TRUE, prob = K[1, ])
     move2 = sample(states, n2, replace = TRUE, prob = K[2, ])
     move3 = sample(states, n3, replace = TRUE, prob = K[3, ])
     people[index1] = move1
     people[index2] = move2
     people[index3] = move3
   p1 = sum(people == 1)/M
   p2 = sum(people == 2)/M
   p3 = sum(people == 3)/M
   p = c(p1, p2, p3)
   return(p)
The estimated p^{(t)} is shown as below.
> RWM(t = 1e2, M = 1e5)
[1] 0.33140 0.33268 0.33592
The estimated p^{(t)} will be different if we change the transition probabilities.
> RWM(t = 1e2, M = 1e5, k12 = 1/6, k13 = 1/3, k31 = 1/12,
     k32 = 1/6, k33 = 3/4)
[1] 0.35631 0.38619 0.25750
```