Answers/Solutions of Questions 1-14 of Exercise 3 (Version: October 3, 2016)

1.
$$\boldsymbol{u} = (1, \sqrt{3}), \ \boldsymbol{v} = (-\sqrt{3}, -1), \ \boldsymbol{u} + \boldsymbol{v} = (1 - \sqrt{3}, -1 + \sqrt{3}), \ 3\boldsymbol{u} - 2\boldsymbol{v} = (3 + 2\sqrt{3}, 2 + 3\sqrt{3}).$$

- 2. See Question 1 of Tutorial 5.
- 3. A = B = C = F and A, D, E are all different.
- 4. (a) U and V contains the origin but W does not.

(b)
$$\begin{cases} 2x - y + 3z = 0 \\ 3x + 2y - z = 0 \end{cases} \Leftrightarrow \begin{cases} x = -\frac{5}{7}t \\ y = \frac{11}{7}t \text{ where } t \in \mathbb{R} \\ z = t \end{cases}$$
So $U \cap V = \{ (-\frac{5}{7}t, \frac{11}{7}t, t) \mid t \in \mathbb{R} \}.$

$$\begin{cases} 3x + 2y - z = 0 \\ x - 3y - 2z = 1 \end{cases} \Leftrightarrow \begin{cases} x = \frac{1}{11}(2 + 7t) \\ y = \frac{1}{11}(-3 - 5t) \text{ where } t \in \mathbb{R} \\ z = t \end{cases}$$

So $V \cap W = \{ (\frac{2+7t}{11}, \frac{-3-5t}{11}, t) \mid t \in \mathbb{R} \}.$

- 5. (a) A is a line joining the points (1,1,1) and (2,3,4).
 - (b) Let $B = \{(x, y, z) \mid x + y z = 1 \text{ and } x 2y + z = 0\}$. Since x + y z = 1 and x + y z = 1 are two non-parallel lines, B is the line of intersection of the two planes. To show that A = B, it suffices to show that the line A lies on both planes. This is true because (1 + t) + (1 + 2t) (1 + 3t) = 1 and (1 + t) 2(1 + 2t) + (1 + 3t) = 0 for all $t \in \mathbb{R}$.

(c) For example,
$$\mathbf{M} = \begin{pmatrix} 1 & 1 & -1 \\ 1 & -2 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$
 and $\mathbf{b} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$.

6. Since

$$\begin{vmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ a & b & c & d \end{vmatrix} = \begin{vmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ b & c & d \end{vmatrix} - 0 + \begin{vmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ a & b & d \end{vmatrix} - 0 = a + b - d - c,$$

 $V = \{(a, b, c, d) \mid a + b - d - c = 0\} = \{(x, y, z, w) \mid x + y - z - w = 0\} = T.$ On the other hand, $S \neq T$ because $(1, -1, 0, 0) \in T$ but $(1, -1, 0, 0) \notin S$.

- 7. (a) For example, $P = \{(1 + s t, s, t) \mid s, t \in \mathbb{R}\}.$
 - (b) A lies in P because a a + 1 = 1. Since both B and C pass through (0,0,0) and $(0,0,0) \notin P$, B and C does not lies in P.
 - (c) B intersects P at one point, (1,0,0).
 - (d) The plane x y + z = 0 contains C but not A and B.
 - (e) No. By Discussion 1.4.11, the solution set of a consistent nonzero linear system in three variables represents a point, a line or a plane in \mathbb{R}^3 . Suppose we have a nonzero linear system whose solution set contains both B and C. Then the solution set must be a plane. However, the plane containing both B and C is the xz-plane which does not contain A. So the solution set cannot contain A.
- 8. (2,3,-7,3), (0,0,0,0) and (-4,6,-13,4) are vectors in span $\{u_1,u_2,u_3\}$ while (1,1,1,1) is not.
- 9. S_4 and S_6 span \mathbb{R}^3 while S_1 , S_2 , S_3 and S_5 do not span \mathbb{R}^3 .
- 10. (a) Since (1, 1, 0) and (5, 2, 3) satisfy the equation x y z = 0, (1, 1, 0), $(5, 2, 3) \in V$ and hence span $(S) \subseteq V$.

Note that a general solution of x - y - z = 0 is x = s + t, y = s, z = t where $s, t \in \mathbb{R}$. Let (s + t, s, t) be any vector in V. Consider the following equation:

$$a(1,1,0) + b(5,2,3) = (s+t,s,t) \Leftrightarrow \begin{cases} a+5b = s+t \\ a+2b = s \\ 3b = t. \end{cases}$$

Since

$$\begin{pmatrix} 1 & 5 & s+t \\ 1 & 2 & s \\ 0 & 3 & t \end{pmatrix} \xrightarrow{\text{Gaussian}} \begin{pmatrix} 1 & 5 & s+t \\ 0 & 3 & t \\ 0 & 0 & 0 \end{pmatrix},$$
Elimination

the system is consistent for all $s, t \in \mathbb{R}$. So $V \subseteq \text{span}(S)$.

We have shown that span $\{(1,1,0), (5,2,3)\} = V$.

(b) Since

$$\begin{pmatrix} 1 & 5 & 0 \\ 1 & 2 & 0 \\ 0 & 3 & 1 \end{pmatrix} \xrightarrow{\text{Gaussian}} \begin{pmatrix} 1 & 5 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

by Discussion 3.2.5, span $\{(1,1,0), (5,2,3), (0,0,1)\} = \mathbb{R}^3$.

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11. (a)
$$\begin{pmatrix} 1 & 0 & 2 \\ -1 & 1 & -2 \\ -5 & 1 & 0 \end{pmatrix}$$
 Gaussian $\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 10 \end{pmatrix}$

Since $u_2 \notin \text{span}\{v_1, v_2\}$, $\text{span}\{u_1, u_2, u_3\} \neq \text{span}\{v_1, v_2\}$.

(b)
$$\begin{pmatrix} 1 & 2 & -1 & 1 & 0 \\ 6 & 4 & 2 & -2 & 8 \\ 4 & -1 & 5 & -5 & 9 \end{pmatrix}$$
 Gaussiann $\begin{pmatrix} 1 & 2 & -1 & 1 & 0 \\ 0 & -8 & 8 & -8 & 8 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$

The systems are consistent and thus span $\{v_1, v_2\} \subseteq \text{span}\{u_1, u_2, u_3\}$.

$$\begin{pmatrix} 1 & 0 & 1 & 2 & -1 \\ -2 & 8 & 6 & 4 & 2 \\ -5 & 9 & 4 & -1 & 5 \end{pmatrix} \xrightarrow{\text{Gaussian}} \begin{pmatrix} 1 & 0 & 1 & 2 & -1 \\ 0 & 8 & 8 & 8 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$
Elimination

The systems are consistent and thus span $\{u_1, u_2, u_3\} \subseteq \text{span}\{v_1, v_2\}$.

So span $\{v_1, v_2\} = \text{span}\{u_1, u_2, u_3\}.$

12. (a)
$$\begin{pmatrix} -1 & 3 & 0 & -4 & 1 \\ 2 & 1 & 1 & 3 & 0 \\ 1 & 4 & 1 & -1 & 2 \\ 0 & 0 & 3 & 6 & 5 \end{pmatrix}$$
Gaussian
$$\rightarrow$$
Elimination
$$\begin{pmatrix} -1 & 3 & 0 & -4 & 1 \\ 0 & 7 & 1 & -5 & 2 \\ 0 & 0 & 3 & 6 & 5 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Since $u_2 \notin \text{span}\{v_1, v_2, v_3, v_4\}$, $\text{span}\{u_1, u_2, u_3, u_4\} \not\subseteq \text{span}\{v_1, v_2, v_3, v_4\}$.

(b)
$$\begin{pmatrix} 2 & 1 & 0 & 1 & | & -1 & | & 3 & | & 0 & | & -4 \\ 0 & 0 & 3 & 1 & | & 2 & | & 1 & | & 1 & | & 3 \\ 2 & 2 & 6 & 2 & | & 1 & | & 4 & | & | & -1 \\ 0 & 5 & 9 & -1 & | & 0 & | & 0 & | & 3 & | & 6 \end{pmatrix} \xrightarrow{\text{Gaussian}} \begin{pmatrix} 2 & 1 & 0 & 1 & | & -1 & | & 3 & | & 0 & | & -4 \\ 0 & 1 & 6 & 1 & | & 2 & | & 1 & | & 1 & | & 3 \\ 0 & 0 & 3 & 1 & | & 2 & | & 1 & | & 1 & | & 3 \\ 0 & 0 & 0 & 1 & | & 4 & | & 2 & | & 5 & | & 12 \end{pmatrix}$$

The systems are consistent and thus $\operatorname{span}\{v_1,v_2,v_3,v_4\}\subseteq \operatorname{span}\{u_1,u_2,u_3,u_4\}.$

- (c) span $\{u_1, u_2, u_3, u_4\} = \mathbb{R}^4$.
- (d) span $\{v_1, v_2, v_3, v_4\} \neq \mathbb{R}^4$.
- 13. For S_1 , S_2 and S_3 , see Question 5 of Tutorial 5. Both S_4 and S_5 span \mathbb{R}^3 .
- 14. (a) True. Let $\mathbf{u} = (u)$ for $u \neq 0$. Then for any $(c) \in \mathbb{R}^1$, $(c) = \frac{c}{u}\mathbf{u}$.
 - (b) False. For example, let u = (1, 1), v = (2, 2).
 - (c) False. For example, let $S_1 = \{(1,0), (0,1)\}, S_2 = \{(1,0), (0,2)\}.$
 - (d) False. For example, let $S_1 = \{(1,0)\}, S_2 = \{(0,1)\}.$