

Numerical Analysis Qualifier

prepared by

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INSTRUCTIONS: Do any (and only) 8 of the following 10 problems.

1. (Mathematical Conditioning)

Consider the approximate evaluation of the function $\tan x$ in finite precision.

- (a) Calculate the *condition number* (amplification factor with respect to relative error) of this function.
- (b) For what values of x is this function “ill conditioned?”
- (c) Near which of the values below would you expect the finite-precision approximate evaluation of $\tan x$ to be close to full machine-precision accuracy?
 - i. $x = 0$
 - ii. $x = (2n + 1)\pi/2$
 - iii. $x = n\pi$, $n \neq 0$

Here n is an integer.

2. (Asymptotic Expansions, Numerical Benchmarking)

Many numerical procedures (such as quadrature rules, numerical solutions of differential equations, ...) admit asymptotic error expansions of the form

$$T(h) = \tau_0 + \tau_1 h^{p_1} + \tau_2 h^{p_2} + \cdots, \quad \text{as } h \rightarrow 0.$$

Here $T(h)$ denotes an approximation depending on h (the “discretization parameter”); τ_0 is the true/exact/limiting value; τ_1, τ_2, \dots are constants that do *not* depend on h ; and the exponents satisfy $0 < p_1 < p_2 < \cdots$. One can attempt to verify or determine the “order of convergence” p_1 by *numerical experiment*.

- (a) Assuming that you have a test problem for which you *know* τ_0 , how could you determine p_1 from a numerical experiment?

- (b) Could you similarly determine p_1 for a situation in which you *don't* know an exact value for τ_0 ? If so, how; if not, why not.
3. (Quadrature Rules, Change of Interval, Composite Rules)
Consider a basic n -point quadrature rule defined for the standard interval $[-1, 1]$:

$$\int_{-1}^1 f \approx \sum_{i=1}^n w_i f(x_i). \quad (1)$$

- (a) Determine the *weights* and *abscissae* (or *nodes* or *knots*) of an associated quadrature rule for the general interval $[a, b]$:

$$\int_a^b f \approx \sum_{i=1}^n \tilde{w}_i f(\tilde{x}_i).$$

- (b) Does the quadrature rule on $[a, b]$ have the same (or possibly different) “polynomial order” (highest degree polynomial family for which the rule is *exact*) as the original one on $[-1, 1]$? Justify your answer.
- (c) Construct the associated *composite quadrature rule* based upon a uniform partition of the general interval $[a, b]$ into N equal-length sub-intervals.
4. (Gaussian Quadrature Rules)
The basic n -point Gaussian quadrature rule on the standard interval $[-1, 1]$ is of the form (??) above. It can be viewed as an “interpolatory quadrature rule,” with abscissae specified as the zeros of the n -th *Legendre polynomial*, constructed to be exact on Π_{n-1} (the family of polynomials of degree at most $n - 1$). Given this, prove that in fact the rule is exact on Π_{2n-1} .
5. (Polynomial Interpolation)
We wish to tabulate equally spaced values of $f(x) = \cos x$ on the interval $[0, \pi/2]$ so that *local linear interpolation* gives 3 accurate decimal places.
- (a) What is the minimum number of entries needed?
- (b) How accurate must the entries in the table be?
6. (LLS Problems)
Describe and explain

- (a) the normal equations,
- (b) the orthogonalization method

for solving the linear least square problem

$$\min_{x \in \mathbb{R}^n} \|y - Ax\|_2, \quad A \in \mathbb{R}^{m \times n}, \quad y \in \mathbb{R}^m.$$

Briefly discuss (dis)advantages of the two methods.

7. (Matrices and Matrix Norms)

Let $A = [a_{ij}] \in \mathbb{C}^{n \times n}$ and let $\alpha > 0$ and $\beta > 0$, where

$$\alpha = \min_{1 \leq k \leq n} (|a_{kk}| - \sum_{\substack{j=1 \\ j \neq k}}^n |a_{kj}|),$$

$$\beta = \min_{1 \leq k \leq n} (|a_{kk}| - \sum_{\substack{i=1 \\ i \neq k}}^n |a_{ik}|).$$

Show that

- (a) A is nonsingular,
- (b) $\|A^{-1}\|_{\infty}^{-1} = \inf_{x \neq 0} \frac{\|Ax\|_{\infty}}{\|x\|_{\infty}},$
- (c) $\|A^{-1}\|_{\infty} \leq \frac{1}{\alpha},$
- (d) $\|A^{-1}\|_1 \leq \frac{1}{\beta}.$

8. (Approximate Inverse)

Let A and B be two nonsingular matrices, such that B approximates A^{-1} . Let $\|\cdot\|$ be a subordinate matrix norm.

- (a) If $0 < \|I - AB\| < 1$, show that $C := B + B(I - AB)$ is a “better” approximation to A^{-1} in the sense that

$$\|I - AC\| < \|I - AB\|.$$

(b) Show that

$$\frac{\|B - A^{-1}\|}{\|B\|} \leq \text{cond}(A) \frac{\|A - B^{-1}\|}{\|A\|}.$$

9. (Eigenvalue Computation)

Let A be a matrix whose eigenvalues satisfy

$$\lambda_1 = -\lambda_2, \quad |\lambda_1| > |\lambda_3| \geq \cdots \geq |\lambda_n|$$

and let $y^k = A^k y^0$, $k = 1, 2, \dots$, for some vector y^0 . Show that with a large k , y_i^{2k+2}/y_i^{2k} can be used to find λ_1 , provided certain assumptions hold true (state those assumptions). Then show that $y^k \pm \lambda_1 y^{k-1}$ approximate the eigenvectors corresponding to $\pm \lambda_1$.

10. (Gershgorin Circles)

Let A and B be two $n \times n$ matrices and let λ be an eigenvalue of A , which is not an eigenvalue of B . Prove that

$$1 \leq \|(\lambda I - B)^{-1}(A - B)\| \leq \|(\lambda I - B)^{-1}\| \|A - B\|.$$

Then use this result with a special choice of B and $\|\cdot\|$ to derive the Gershgorin statement about the row-circles.