Chapter 6: Object Oriented Programming

Object oriented programming (OOP) is a method that defines reusable structures which posess their own variables and functionality. These structures are then declared in specific instances when needed. Objects offer an effective way to operate on data using data types that are not inherent to Fortran. The basic property of Fortran that allows object-oriented programming is the ability to define new *data types*.

5.1 Derived Types

We have already learned that we are not limited to the intrinsic functions that Fortran offers; that is, you can create your own functions. The same is true of data types. You are not limited to the intrinsic data types such as integer, real, or character; you can create your own with the type declaration. For the following examples, new data types and functions that operate on them will be created modules, and these modules will be used by programs.

The following program illustrates how to declare, modify, and operate on a new data type called point that represents a 3D point.

```
_type.f95
1 module pointmodule
2 implicit none
    ! define a new data type called point
    type point
       real :: x(3)
5
    end type point
6
7 contains
  ! define a function that operates on points
    function magnitude(pt)
9
       type(point), intent(in) :: pt
10
       real :: magnitude
11
       magnitude=sqrt(sum(pt%x**2))
    end function magnitude
13
14 end module pointmodule
16 program typeex
17 use pointmodule
18 implicit none
    ! declare a point
    type(point) :: pt
20
21
    ! set the values of 'x' in 'pt'
22
   pt%x(1)=1.
   pt%x(2)=2.
24
    pt%x(3)=3.
25
    ! print point and magnitude
26
    write(*,*) pt
    write(*,*) magnitude(pt)
29 end program typeex
```

- The new data type is created with the type TYPE_NAME ...end type TYPE_NAME tags. All variables that the new type contains are declared within these tags.
- After a new data type is created, an instance of it can be delcared with type(TYPE_NAME) ::

VAR_NAME where VAR_NAME is a named instance of the new data type. As a recognized data type, functions can be created whose arguments may be of the new data type.

• The variables of a derived data type can be accessed with the % symbol. For example, the variable x within an instance pt of the derived data type point is accessed by pt%x.

```
gfortran type.f95 -o type
./type
1.00000000 2.00000000 3.00000000
3.74165750
```

The following program creates a matrix data type as well as some subroutines and functions that operate on the derived data type. The subroutines are designed to initialize a matrix as zeros, print a matrix, or free up the memory that a matrix occupies. The function is designed to compute the ∞ -norm of a matrix.

```
_ matrix.f95 _
1 module matrixmodule
2 implicit none
     ! define a new data type called matrix
     type matrix
        real, allocatable :: element(:,:)
5
     end type matrix
6
7 contains
    ! initialize matrix with zeros
8
     subroutine matrix_zeros(m, n, mat)
9
        integer, intent(in) :: m, n
10
        type(matrix), intent(out) :: mat
11
        integer :: i, j
12
        ! allocate memory for matrix
13
        allocate(mat%element(m,n))
14
15
        do i=1, m
           do j=1,n
16
              mat%element(i,j)=0.
17
           end do
18
        end do
19
     end subroutine matrix_zeros
20
21
     ! compute matrix inf-norm
22
     function matrix_infnorm(mat)
        type(matrix), intent(in) :: mat
24
        real :: matrix_infnorm
25
        integer :: m, i
26
27
        ! count number of rows
28
        m=size(mat%element(:,1))
29
        ! find maximum absolute row sum
30
        matrix_infnorm=0.
31
        do i=1, m
32
           matrix_infnorm=max(matrix_infnorm,sum(abs(mat%element(i,:))))
33
        end do
     end function matrix_infnorm
35
36
     ! print matrix
37
     subroutine matrix_print(mat)
38
39
        type(matrix) :: mat
        integer :: m, i
40
41
        ! count number of rows
```

```
m=size(mat%element(:,1))
43
        ! print one row at a time
44
45
        do i=1, m
           print*, mat%element(i,:)
46
        end do
47
     end subroutine matrix_print
48
     ! destroy matrix
50
     subroutine matrix_destroy(mat)
51
        type(matrix) :: mat
52
        deallocate(mat%element)
     end subroutine matrix_destroy
55 end module matrixmodule
57 program matrixex
58 use matrixmodule
59 implicit none
    ! declare a matrix
     type(matrix) :: mat
     integer :: m=2, n=2, i, j
62
63
    ! initialize matrix as zeros
     call matrix_zeros(m,n,mat)
     write(*,*) '2x2 zero matrix: '
66
     call matrix_print(mat)
67
    ! assign elements of matrix
     do i=1, m
69
70
        do j=1,n
           mat%element(i,j)=real(i**j)
71
        end do
72
     end do
73
     write(*,*) 'new 2x2 matrix: '
74
     call matrix_print(mat)
75
     write(*,*) 'The inf-norm of the last matrix is ', matrix_infnorm(mat)
     ! destroy matrix
77
     call matrix_destroy(mat)
78
79
80 end program matrixex
```

Exercise

1. Use the Thomas Algorithm (see Quateroni Section 3.7.1) to solve the system

$$\begin{bmatrix} 2 & \frac{1}{2} & & & & \\ \frac{1}{2} & 2 & \frac{1}{2} & & & \\ & \frac{1}{2} & 2 & \frac{1}{2} & & & \\ & & \ddots & \ddots & \ddots & \\ & & & \frac{1}{2} & 2 & \frac{1}{2} \\ & & & & \frac{1}{2} & 2 \end{bmatrix} \begin{bmatrix} s_0 \\ s_1 \\ s_2 \\ \vdots \\ s_{n-2} \\ s_{n-1} \\ s_n \end{bmatrix} = 6 \begin{bmatrix} 0 \\ f[x_0, x_1, x_2] \\ f[x_1, x_2, x_3] \\ \vdots \\ f[x_{n-3}, x_{n-2}, x_{n-1}] \\ f[x_{n-2}, x_{n-1}, x_n] \\ 0 \end{bmatrix}$$

for $s = (s_0, \ldots, s_n)^T$ where n = 10, $f(x) = 1/(1 + e^x)$ and $x_i = -1 + 2i/n$ for $i = 0, \ldots, n$. Note $f[x_{i-1}, x_i, x_{i+1}]$ is the second-order Newton divided difference on nodes x_{i-1}, x_i, x_{i+1} . Report the s that you found as well as the number of computations and the number of storage locations used to compute s.